

# STATISTICAL MODELING AND CAUSAL INFERENCE WITH R

## Week 9: Panel Data

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# Recap

A powerful way to achieve causal identification: leverage multiple observations over time.

The DiD estimator manages to do this with 2 observations in time: prior to and after a treatment was applied.

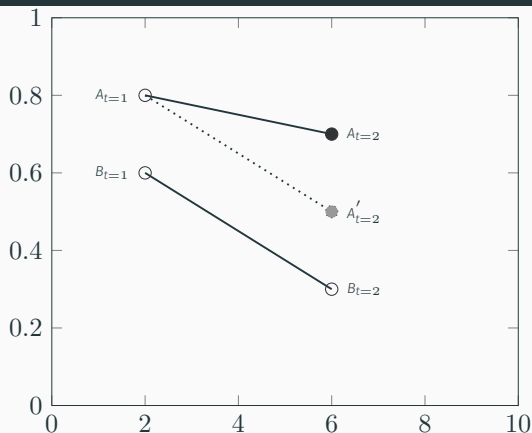
Excellent at ensuring that unobserved time-invariant confounders don't bias estimates (comparisons happen within-units).

Assumption: **parallel trends**. Had there been no treatment, temporal dynamics for treatment group would have been the same as for control group.

# Parallel trends

Effect:  $Y_{t=2}^A - Y_{t=2}^{A'}$

Not mandatory to have same units over time—works for pooled cross-sections too.



$$\beta = (Y_{t=2}^A - Y_{t=2}^B) - (Y_{t=1}^A - Y_{t=1}^B)$$

# Today's plan

Extend this design to cases with more than 2 time points:

- ✓ Features of 2 “pure” designs: cross-sectional and temporal;
- ✓ Panel data as a mix of CS and T;
- ✓ Estimation: *FE* vs. *RE*
- ✓ Assumptions implicit in strategies

## Cross-sectional and temporal designs

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# Types of data structures

**Cross-section:** sample of countries, firms, regions, schools, employees ... all measured at same time point,  $t$ .

Measurements on  $(Y_i; X_i)$  for  $i = 1, 2, \dots, N$  at time  $t$ .

**Time-series:** same unit (country, school, firm, child) measured over multiple time points.

Measurements on  $(Y_t; X_t)$  for  $t = 1, 2, \dots, T$  for same unit.

# Types of data structures

**Panel data:** multiple units measured over multiple time points.

Measurements on  $(Y_{it}; X_{it})$  for  $i = 1, 2, \dots, N$ , and  $t = 1, 2, \dots, T$ .

“Pure” CS or TS designs have weaknesses in terms of ability to estimate a causal effect.

Panel data can (theoretically) overcome these weaknesses.

## Short didactic example

Card and Krueger (1994) examine whether a minimum price increase influences unemployment.

Treatment: increase in minimum wage in NJ (but not in PA) in Apr. 1992.

Same restaurants over time—Feb. 1992 and Nov.-Dec. 1992.



# Static-group comparison

$$\begin{aligned}Y_{i1}^0 &= \theta_i^0 + \delta_1 + v_{i1}^0 \\Y_{i1}^1 &= \tau + \theta_i^1 + \delta_1 + v_{i1}^1\end{aligned}$$

$\theta_i$ : time-invariant unit-specific effect.

$\delta_t$ : time period effect (identical for all units here:  $\delta_1$ ).

$$E[Y_{i1}^1 - Y_{i1}^0] = \tau + E[\theta_i^1 - \theta_i^0] + E[v_{i1}^1 - v_{i1}^0] \quad (1)$$

$\delta_1$  disappears—unobserved time-varying factors don't bias the estimate.

## Assumptions made

**Exogeneity:** mean of error is independent of the treatment.

$$E[v_i^1] = E[v_i^0] \Rightarrow E[v_i^1 - v_i^0] = 0 \quad (2)$$

**Random effects:** unobserved unit heterogeneity is independent of the treatment.

$$E[\theta_i^1] = E[\theta_i^0] \Rightarrow E[\theta_i^1 - \theta_i^0] = 0 \quad (3)$$

## Effect of wage increase: static comparison

If we're willing to make the two assumptions, a static comparison can recover treatment effect.

Model for employment change (Nov. 1992 data)

DV: No. full-time	
(Intercept)	7.56*** (0.91)
State (NJ)	0.88 (1.01)
R <sup>2</sup>	0.00
Adj. R <sup>2</sup>	−0.00
Num. obs.	398
*** $p < 0.001$ ; ** $p < 0.01$ ; * $p < 0.05$	

Heroic random effects assumption—even with controls, hard to make it convincing.

# Longitudinal comparison

$$Y_{i0}^0 = \delta_0^0 + \theta_i + v_{i0}^0$$

$$Y_{i1}^1 = \tau + \delta_1^1 + \theta_i + v_{i1}^1$$

$\theta_i$ : time-invariant unit-specific effect (identical for all units here).

$\delta_t$ : time period effect.

$$E[Y_{i1}^1 - Y_{i0}^0] = \tau + E[\delta_1^1 - \delta_0^0] + E[v_{i1}^1 - v_{i0}^0] \quad (4)$$

$\theta_i$  disappears—unobserved time-invariant unit-specific effect don't bias estimate.

## Assumptions made

**Exogeneity:**  $E[v_{i1}^1] = E[v_{i0}^0]$ .

**Temporal stability:** no impact of unobserved time-varying factors.

$$E[\delta_1^1] = E[\delta_0^0] \quad (5)$$

Time-invariant factors ( $\theta_i$ ) don't matter, because the units compared are the same.

# Effect of wage increase: temporal comparison

Model for employment change (NJ data)

	DV: No. full-time
(Intercept)	7.72*** (0.44)
Time (Nov. 1992)	0.72 (0.62)
R <sup>2</sup>	0.00
Adj. R <sup>2</sup>	0.00
Num. obs.	647
*** $p < 0.001$ ; ** $p < 0.01$ ; * $p < 0.05$	

Heroic temporal stability assumption.

## Panel Data

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Partly addresses the unit heterogeneity and temporal instability problems.

Relies on a weaker exogeneity assumption.

$$E[Y_{i1}^1 - Y_{i1}^0] - E[Y_{i0}^1 - Y_{i0}^0] = \tau + E[\epsilon_{i1}^1 - \epsilon_{i1}^0] - E[\epsilon_{i0}^1 - \epsilon_{i0}^0] \quad (6)$$

You saw this in previous class: DiD estimator was applied to a specific type of panel data.

Extending the lessons of DiD to instances with  $t > 2$  and where, typically,  $N \gg T$ .



$$Y_{it} = \beta_0 + \beta_1 D_{it} + \underbrace{\theta_i + \delta_t + v_{it}}_{\epsilon_{it}} \quad (7)$$

Error term components:

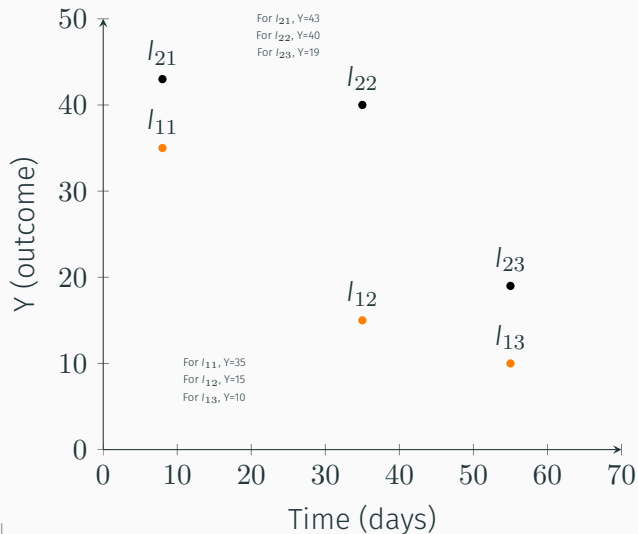
- ✓  $\theta_i$ : unit fixed effect—captures influence of time-invariant features
- ✓  $\delta_t$ : time fixed effect—captures influence of time-varying features (affect all units)
- ✓  $\epsilon_{it}$ : “classical” error term

$$Y_{it} = \beta_0 + \beta_1 D_{it} + \underbrace{\theta_i + \delta_t + v_{it}}_{\epsilon_{it}} \quad (8)$$

Normally, in this setup, **homogeneity** assumption is violated:  $\text{Cov}(D_{it}, \theta_i) \neq 0$ .

However, we can partial out  $\theta_i$  from  $\epsilon_{it}$  (it's constant in longitudinal data) by “taking out” unit means in the outcome.

## Partialling out $\theta_i$



## Partialling out $\theta_i$

For group 1,  $\bar{Y}=20$ . For group 2,  $\bar{Y}=35$ .

	Y raw	$\theta_i$ partialled out
$l_{11}$	35	15
$l_{12}$	15	-5
$l_{13}$	10	-10
$l_{21}$	43	8
$l_{22}$	40	5
$l_{23}$	19	-16

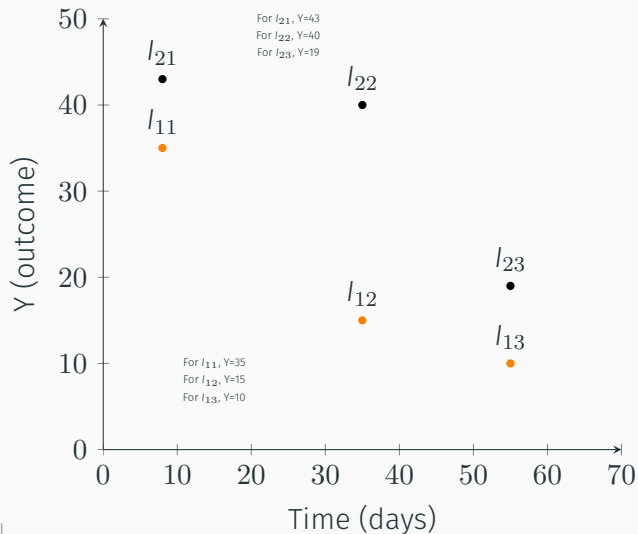
Remaining variance is the relative position of units within a group, e.g. the distance between  $l_{11}$  and  $l_{12}$  is still 20.

$$Y_{it} = \beta_0 + \beta_1 D_{it} + \underbrace{\theta_i + \delta_t + v_{it}}_{\epsilon_{it}} \quad (9)$$

Temporal stability assumption is violated as well:  $\text{Cov}(D_{it}, \delta_t) \neq 0$ .

We can partial out  $\delta_t$  from  $\epsilon_{it}$  (it's constant in cross-sectional) by “taking out” period means in the outcome.

## Same panel setup



## Partialling out $\delta_t$

$$\bar{Y}_{period\ 1} = 39 \mid \bar{Y}_{period\ 2} = 27.5 \mid \bar{Y}_{period\ 3} = 14.5.$$

	Y raw	$\delta_t$ partialled out
$l_{11}$	35	-4
$l_{21}$	43	4
$l_{12}$	15	-12.5
$l_{22}$	40	12.5
$l_{13}$	10	-4.5
$l_{23}$	19	4.5

Remaining variance is the relative position of units within a time period, e.g. the distance between  $l_{11}$  and  $l_{21}$  is still 8.

We will cover the mechanics of partialling out  $\theta_i$  and  $\delta_t$  in the next section:  
*Estimation.*

See how similar this is to the **DiD** framework!

$$Y_{ct} = \alpha + \beta D_c + \gamma Post_t + \tau(D_c \times Post_t) + v_{ct} \quad (10)$$

$D_c$ : partials out unit heterogeneity.

$Post_t$ : partials out temporal instability.



$$Employment_{it} = \alpha + \underbrace{\beta State_i}_{\theta_i} + \underbrace{\gamma Time_t}_{\delta_t} + \tau(State_i \times Time_t) + v_{it} \quad (11)$$

$State_i \times Time_t$  is an indicator for the treatment:

$$State_i \times Time_t = \begin{cases} 1, & \text{if NJ **AND** Nov. 1992} \\ 0, & \text{if PA **OR** Feb. 1992} \end{cases} \quad (12)$$

## Model for employment change

DV: No. full-time	
(Intercept)	10.21*** (0.94)
State (NJ)	-2.48* (1.04)
Time (Nov.)	-2.64* (1.33)
State x Time	3.36* (1.48)
R <sup>2</sup>	0.01
Adj. R <sup>2</sup>	0.00
Num. obs.	802

\*\*\*  $p < 0.001$ ; \*\*  $p < 0.01$ ; \*  $p < 0.05$

Covariates ( $X_{it}$ ) need to be added before jumping to interpretations, but fundamentals are the same.

# Estimation

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## Simplified set-up

Let's assume period effects are not a problem (simplifies notation) for now, as it will make the presentation less cumbersome.

We're only concerned about unit heterogeneity,  $\theta_i$ .

$$Y_{it} = \beta_0 + \beta_1 X_{it} + \theta_i + v_{it} \quad (13)$$

Three strategies to estimate:

- ✓ first differences (FD)
- ✓ fixed effects (FE)
- ✓ random effects (RE)

## First differences (FD)

$$Y_{it} = \beta_0 + \beta_1 X_{it} + \theta_i + v_{it} \quad (14)$$

$$Y_{i(t-1)} = \beta_0 + \beta_1 X_{i(t-1)} + \theta_i + v_{i(t-1)} \quad (15)$$

Though  $\theta_i$  is a problem, we can eliminate it by differencing.

$$Y_{it} - Y_{i(t-1)} = \beta_1 X_{it} - \beta_1 X_{i(t-1)} + v_{it} - v_{i(t-1)} \quad (16)$$

$$\Delta Y_{it} = \beta_1 \Delta X_{it} + \Delta v_{it} \quad (17)$$

## Fixed effects (FE)

Alternative is to “de-mean” variables, by subtracting their mean across time points.

$$Y_{it} = \beta_0 + \beta_1 X_{it} + \theta_i + v_{it} \quad (18)$$

$$\bar{Y}_i = \beta_0 + \beta_1 \bar{X}_i + \bar{\theta}_i + \bar{v}_i \quad (19)$$

Keeping in mind that  $\bar{\theta}_i = \frac{\sum_{t=1}^T \theta_i}{T} = \frac{T * \theta_i}{T} = \theta_i$ ,

$$Y_{it} - \bar{Y}_i = \beta_1 (X_{it} - \bar{X}_i) + (v_{it} - \bar{v}_i) \quad (20)$$

## Dummy variables (LSDV)

FE and FD will be mathematically identical *only* in instances with 2 time points.

Related to FE: Least Squares Dummy Variable (LSDV) regression.

Logic: use  $i - 1$  dummy indicators for units, which capture *all* between-unit heterogeneity.

$$Y_{it} = \beta_0 + \beta_1 X_{it} + \underbrace{\beta_2 U_1 + \beta_3 U_2 + \cdots + \beta_i U_{i-1}}_{\text{unit dummies}} + v_{it} \quad (21)$$

LSDV and FE will be mathematically identical.

## Fixed effects (FE)

FE (or LSDV) won't allow the use of time-invariant predictors of  $Y_{it}$ . They have the same fate as  $\theta_i$ : de-meaning absorbs them.

FE can be expanded to also incorporate time-period fixed-effects  $\Rightarrow$  **two-way fixed effects**.

Two-way FE models don't allow for purely time-invariant or purely time-varying predictors; only  $X_{it}$  work.



## Random effects (RE)

One challenge with LSDV is the large number of parameters estimate (all those unit dummies!).

Degrees of freedom are:  $n * T - n - k$ , with  $n$  designating units,  $T$  time periods, and  $k$  covariates; problematic if  $T$  is small.

$$Y_{it} = \beta_0 + \beta_1 X_{it} + \theta_i + v_{it} \quad (22)$$

*Solution:* avoid estimating  $n - 1$  coefficients by making a simplifying assumption about distribution of  $\theta_i$ .

## Random effects (RE)

Usually, this assumption is that  $\theta_i \sim iid(0, \sigma_\theta^2)$ .

In this case, we only estimate a variance (of this distribution).

Not so much correcting for heterogeneity bias, but *modeling* it.

However, using the RE estimator requires one strong assumption:  $Cov(X_{it}, \theta_i) = 0$ , which is encountered rarely in practice.

# Assumptions

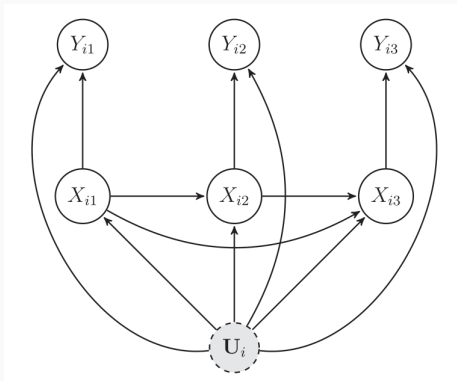
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Imai and Kim (2019) refer to the same model, though notation is more complex:

$$\hat{\beta}_{LIN-FE} = \underset{\beta}{\operatorname{argmin}} \sum_{i=1}^N \sum_{t=1}^T \{(Y_{it} - \bar{Y}_i) - \beta(X_{it} - \bar{X}_i)\}^2 \quad (23)$$

This specification come at the cost of assuming away the possibility of dynamic temporal relationships.

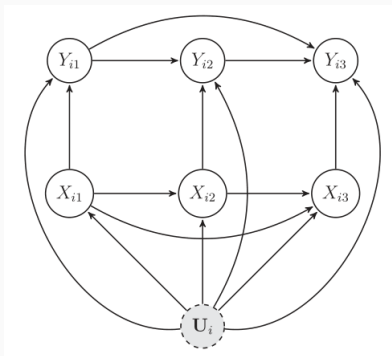
# Assumptions of standard FE



1. No unobserved time-varying confounders
2. Past outcomes don't influence current ones
3. Past outcomes don't influence current treatment
4. Past treatment doesn't influence current outcome

# Relaxing assumptions I

Not much can be done for assumption #1.

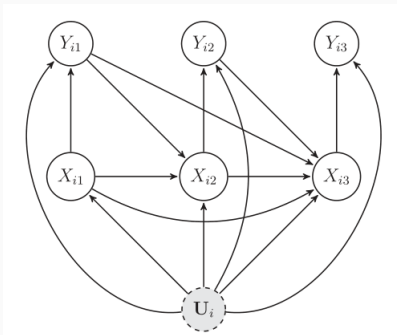


Assumption #2:

$Outcome_{t-1} \nrightarrow Outcome_t$ . Can be relaxed without biasing  $\tau$ .

$$Y_{it} = \alpha_i + \beta_1 X_{it} + \beta_2 X_{i(t-1)} + \epsilon_{it}$$

## Relaxing assumptions II



Assumption #3:

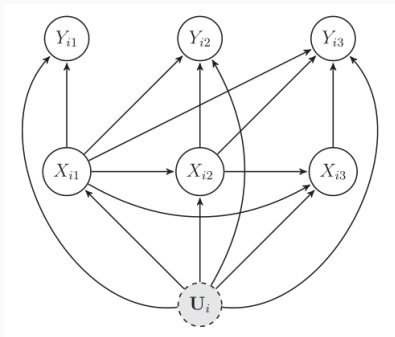
$Outcome_{t-1} \nrightarrow Treatment_t$ .

$$Y_{it} = \alpha_i + \beta X_{it} + \rho Y_{i(t-1)} + \epsilon_{it}$$

Standard OLS isn't good here (can bias downwards other  $\beta$ s) (Achen, 2000).

IV-based approach using  $X_{i1}$ ,  $X_{i2}$  and  $Y_{i1}$  as instruments and controlling for  $U_i$  and  $Y_{i2}$  (Arellano & Bond, 1991).

## Relaxing assumptions III



Assumption #4:

$Treatment_{t-1} \nrightarrow Outcome_t$ .

$$Y_{it} = \alpha_i + \beta_1 X_{it} + \beta_2 X_{i(t-1)} + \epsilon_{it}$$

Also dealt with lagged values of predictors (usually 1-period lag).



## Summary

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Very common type of data, allowing researchers to easily control for confounders.

Offer some leverage over causal inference, given the temporal ordering of observations.

Gives leverage over both within-unit change, and across-unit differences.

However, keeping heterogeneity bias and temporal instability in check comes at the expense of dynamic relationships.

Solutions have been found for estimating dynamic and long-run effects, but estimation is not straightforward.

New strategies are still being proposed:

[\*https://papers.ssrn.com/sol3/papers.cfm?abstract\\_id=3555463\*](https://papers.ssrn.com/sol3/papers.cfm?abstract_id=3555463).

Remaining challenges: (1) settings where  $T$  is long; (2) how to handle “sluggish” variables (see

[\*https://papers.ssrn.com/sol3/papers.cfm?abstract\\_id=622581\*](https://papers.ssrn.com/sol3/papers.cfm?abstract_id=622581)).

Thank **you** for the kind attention!

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