Introduction to Functions

Lab 4

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Problem

The purpose of this lab was to create a program which took data from the Esplora and made calculations and outputted it to the display. The program must use several functions and those functions must have prototypes before the main () method. The program must also use data that comes from the Esplora via the given explore.exe program. The objective of this lab is to create functions, learn how GCC compiles and executes these functions, practice mod and integer division expressions and to practice formatting various types of output.

Analysis

The problem must be solved by creating prototype functions before the main() function and then giving that function functionality after the main() function. The program must scan data from the explore.exe program using the pipe command. This data may come in the form of 4 columns of floating point numbers representing accelerometer values, or five columns of integers representing the state of each of the Esplora's buttons.

The output of the program in the case of the accelerometer input is text followed by four columns of data. The first column is an integer representing the time in milliseconds formatted to an eight character area with three digits of precision. The second, third and fourth columns of data represented the x, y, and z accelerations (respectively) of the Esplora's accelerometer each formatted to a 7 character area with four digits of precision. These values are each specially formatted outputs of the same values as the inputs.

In the case of the button input, the output is an integer representing the number of buttons pressed simultaneously followed by some text. The outputted integer is the sum of all five columns of input.

Design

In order to get the lab4.c program to read data from the Esplora, explore.exe must be piped through the lab4.c compiled program. When this happens, lab4.c will be able to use scanf() to assign data from the Esplora to variables. Once the data has been assigned to their respective variables, the values can be formatted and reprinted to the console in a way that is more readable as well as perform calculations to extend the meaning of the data.

One of these calculations is the magnitude of the acceleration of the Esplora. To do this, a function **mag** is written that takes three double inputs (one for each x, y and z acceleration) and returns a double representing the magnitude of acceleration. The function uses the formula $\sqrt{x^2+y^2+z^2}$ to calculate the magnitude. The time in milliseconds and magnitude is printed to the console using **printf()**.

Another calculation made is converting time in milliseconds to time in minutes, seconds and milliseconds. Three functions are used to accomplish this conversion. One calculates the number of whole minutes elapsed, one calculates the number of whole minutes left and the last calculates the number of milliseconds left. Each function does not report time that has already been reported. For example, if 63230 milliseconds have elapsed, minutes (63230) will return 1 and the time remaining is 3230 milliseconds. seconds (63230) will return 3 seconds because only 3 whole seconds remained after the number of minutes reported was subtracted leaving 230 milliseconds remaining. millis (63230) will return 230 milliseconds because 230 milliseconds remain after 1 minute 3 seconds have been reported.

The last calculation made is the number of buttons simultaneously pressed on the Esplora. Using different flags while executing **explore**. **exe** will return five columns of

integers. Each column is a 1 or 0 representing whether or not the respective button is currently pressed. To return the total number of buttons simultaneously pressed, <code>explore.exe</code> is piped through lab4-4.c. The data is scanned from <code>explore.exe</code> via <code>scanf()</code> and each column's value is assigned to a variable. The program returns the sum of the values of these variables (an integer representing the total number of buttons pressed) followed by some text explaining what the number means. No functions are needed for this task.

Testing

To test the mag(x, y, z) function, we plugged in the Esplora, found the board's COM port number, and piped explore.exe with the appropriate flags through the compiled lab4 program. To verify our results, we did several tests. The first was to leave the Esplora flat on the table to see if two of the three acceleration components were about 0 and the third about -9.8 (the acceleration due to gravity). We then picked up the board and shook it in a single direction. We saw that the harder we shook the board, the larger the respective component value and the larger the acceleration magnitude was. This confirmed that our mag(x, y, z) function worked correctly.

To test the minute(), second() and millis() functions, we piped explore.exe through our program while the Esplora was plugged in and watched each value as time elapsed. We compared the elapsed time calculated by our program to a stopwatch on our phones to confirm our results.

To test the **lab4-4**.**c**, we piped **explore**.**exe** through our program and pressed any combination of buttons. Since the numbers of buttons that we were pressing matched the integer printed to the console in every situation, we knew our program was correct.

Comments

During this lab, I learned about how the GCC compiler looks at functions and how prototypes allow the developer more flexibility in the way the code is written and ordered. I also learned about how it is important to keep the functionality of all other functions in mind when developing a function. For example, when developing the **second()** and **millis()** functions, I had to remember what kind of result **minute()** would produce and how that output related to the problem I was working on.

```
/* Lab 4 Wrapper Program */
#include <stdio.h>
#include <math.h>
#define TRUE 1
/* Put your function prototypes here */
int main(void) {
    int t;
    double ax, ay, az;
    while (TRUE) {
        scanf("%d,%lf,%lf,%lf", &t, &ax, &ay, &az);
/* CODE SECTION 0 */
        printf("Echoing output: %5.3d, %3.4lf, %3.4lf, %3.4lf\n", (t / 1000), ax, ay, az); */
/* CODE SECTION 1
        printf("At %d ms, the acceleration's magnitude was: %lf\n",
            t, mag(ax, ay, az)); */
/* CODE SECTION 2
        printf("At %d minutes, %d seconds, and %d milliseconds it was: %lf\n",
        minutes(t), seconds(t), millis(t), mag(ax,ay,az)); */
    }
return 0;
}
/* Put your functions here */
```

```
Echoing output:
                  407, 0.0527, 0.0357, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
                  407, 0.0527, 0.0357, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9705
Echoing output:
                  407, 0.0464, 0.0357, 0.9705
Echoing output:
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
                  407, 0.0527, 0.0418, 0.9705
Echoing output:
                  407, 0.0527, 0.0357, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9705
Echoing output:
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
                  407, 0.0527, 0.0357, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
Echoing output:
Echoing output:
                  407, 0.0464, 0.0357, 0.9705
                  407, 0.0464, 0.0418, 0.9766
Echoing output:
Echoing output:
                  407, 0.0527, 0.0357, 0.9766
Echoing output:
                  407, 0.0527, 0.0357, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9705
                  407, 0.0401, 0.0357, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9705
Echoing output:
Echoing output:
                  407, 0.0401, 0.0357, 0.9705
Echoing output:
                  407, 0.0464, 0.0357, 0.9705
                  407, 0.0464, 0.0357, 0.9705
Echoing output:
                  407, 0.0464, 0.0418, 0.9766
Echoing output:
                  407, 0.0527, 0.0357, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9828
Echoing output:
                  407, 0.0527, 0.0357, 0.9766
Echoing output:
Echoing output:
                  407, 0.0527, 0.0357, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9705
                  407, 0.0527, 0.0357, 0.9705
Echoing output:
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
Echoing output:
                  407, 0.0527, 0.0357, 0.9766
                  407, 0.0464, 0.0357, 0.9705
Echoing output:
                  407, 0.0464, 0.0357, 0.9705
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
Echoing output:
Echoing output:
                  407, 0.0464, 0.0418, 0.9766
                  407, 0.0464, 0.0357, 0.9705
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
Echoing output:
Echoing output:
                  407, 0.0527, 0.0357, 0.9828
Echoing output:
                  407, 0.0527, 0.0295, 0.9828
                  407, 0.0527, 0.0357, 0.9828
Echoing output:
                  407, 0.0527, 0.0357, 0.9828
Echoing output:
Echoing output:
                  407, 0.0527, 0.0357, 0.9766
                  407, 0.0527, 0.0357, 0.9705
Echoing output:
Echoing output:
                  407, 0.0464, 0.0295, 0.9705
                  407, 0.0464, 0.0295, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
Echoing output:
                  407, 0.0527, 0.0357, 0.9766
Echoing output:
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
                  407, 0.0464, 0.0357, 0.9766
Echoing output:
                  407, 0.0464, 0.0357, 0.9766
Echoing output:
                  408, 0.0527, 0.0418, 0.9766
Echoing output:
                  408, 0.0527, 0.0418, 0.9766
Echoing output:
Echoing output:
                  408, 0.0464, 0.0357, 0.9766
                  408, 0.0527, 0.0357, 0.9828
Echoing output:
Echoing output:
                  408, 0.0464, 0.0418, 0.9828
                  408, 0.0527, 0.0418, 0.9766
Echoing output:
Echoing output:
                  408, 0.0464, 0.0418, 0.9766
Echoing output:
                  408, 0.0464, 0.0418, 0.9705
```

```
/* Lab 4 Wrapper Program */
#include <stdio.h>
#include <math.h>
#define TRUE 1
/* Put your function prototypes here */
double mag (double x, double y, double z);
int main(void) {
    int t;
    double ax, ay, az;
    while (TRUE) {
        scanf("%d,%lf,%lf,%lf", &t, &ax, &ay, &az);
/* CODE SECTION 0
        printf("Echoing output: %5.3d, %3.4lf, %3.4lf, %3.4lf\n", (t / 1000), ax, ay, az); */
   CODE SECTION 1 */
        printf("At %d ms, the acceleration's magnitude was: %lf\n",
            t, mag(ax, ay, az));
   CODE SECTION 2
        printf("At %d minutes, %d seconds, and %d milliseconds it was: %lf\n",
        minutes(t), seconds(t), millis(t), mag(ax,ay,az)); */
    }
return 0;
}
/* Put your functions here */
double mag (double x, double y, double z) {
    double magnitude = sqrt(pow(x, 2) + pow(y, 2) + pow(z, 2));
    return magnitude;
}
```

```
At 218909 ms, the acceleration's magnitude was: 0.973009
At 218911 ms, the acceleration's magnitude was: 0.987251
At 218913 ms, the acceleration's magnitude was: 0.960301
At 218916 ms, the acceleration's magnitude was: 0.991983
At 218918 ms, the acceleration's magnitude was: 0.999988
At 218920 ms, the acceleration's magnitude was: 1.087952
At 218924 ms, the acceleration's magnitude was: 1.100086
At 218926 ms, the acceleration's magnitude was: 1.110186
At 218928 ms, the acceleration's magnitude was: 1.155636
At 218931 ms, the acceleration's magnitude was: 1.124562
At 218933 ms, the acceleration's magnitude was: 1.100616
At 218935 ms, the acceleration's magnitude was: 1.100545
At 218937 ms, the acceleration's magnitude was: 1.137576
At 218940 ms, the acceleration's magnitude was: 1.154926
At 218942 ms, the acceleration's magnitude was: 1.156570
At 218944 ms, the acceleration's magnitude was: 1.178695
At 218947 ms, the acceleration's magnitude was: 1.200629
At 218949 ms, the acceleration's magnitude was: 1.166326
At 218951 ms, the acceleration's magnitude was: 1.189078
At 218954 ms, the acceleration's magnitude was: 1.232474
At 218956 ms, the acceleration's magnitude was: 1.252648
At 218958 ms, the acceleration's magnitude was: 1.252380
At 218960 ms, the acceleration's magnitude was: 1.258532
At 218963 ms, the acceleration's magnitude was: 1.264386
At 218966 ms, the acceleration's magnitude was: 1.300710
At 218968 ms, the acceleration's magnitude was: 1.282040
At 218971 ms, the acceleration's magnitude was: 1.324639
At 218973 ms, the acceleration's magnitude was: 1.290505
At 218975 ms, the acceleration's magnitude was: 1.284073
At 218977 ms, the acceleration's magnitude was: 1.276134
At 218980 ms, the acceleration's magnitude was: 1.224283
At 218982 ms, the acceleration's magnitude was: 1.215235
At 218984 ms, the acceleration's magnitude was: 1.170462
At 218987 ms, the acceleration's magnitude was: 1.134349
At 218989 ms, the acceleration's magnitude was: 1.107572
At 218991 ms, the acceleration's magnitude was: 1.071345
At 218993 ms, the acceleration's magnitude was: 1.012673
At 218996 ms, the acceleration's magnitude was: 0.986218
At 218998 ms, the acceleration's magnitude was: 0.930937
At 219000 ms, the acceleration's magnitude was: 0.898207
At 219003 ms, the acceleration's magnitude was: 0.890244
At 219005 ms, the acceleration's magnitude was: 0.867655
At 219008 ms, the acceleration's magnitude was: 0.867655
At 219011 ms, the acceleration's magnitude was: 0.875184
At 219013 ms, the acceleration's magnitude was: 0.944117
At 219015 ms, the acceleration's magnitude was: 0.982212
At 219017 ms, the acceleration's magnitude was: 1.165264
At 219020 ms, the acceleration's magnitude was: 1.104431
At 219022 ms, the acceleration's magnitude was: 1.048972
At 219024 ms, the acceleration's magnitude was: 1.115735
At 219027 ms, the acceleration's magnitude was: 0.981664
At 219029 ms, the acceleration's magnitude was: 1.118547
At 219031 ms, the acceleration's magnitude was: 1.143507
At 219033 ms, the acceleration's magnitude was: 1.078236
At 219036 ms, the acceleration's magnitude was: 1.069490
At 219038 ms, the acceleration's magnitude was: 1.038928
At 219040 ms, the acceleration's magnitude was: 0.900870
At 219043 ms, the acceleration's magnitude was: 0.862764
At 219045 ms, the acceleration's magnitude was: 0.867357
At 219047 ms, the acceleration's magnitude was: 0.765146
At 219051 ms, the acceleration's magnitude was: 0.827998
```

```
/* Lab 4 Wrapper Program */
#include <stdio.h>
#include <math.h>
#define TRUE 1
/* Put your function prototypes here */
double mag (double x, double y, double z);
int minutes (int millis);
int seconds (int millis);
int millis (int millis);
int main(void) {
    int t;
    double ax, ay, az;
    while (TRUE) {
        scanf("%d,%lf,%lf,%lf", &t, &ax, &ay, &az);
/* CODE SECTION 0
        printf("Echoing output: %5.3d, %3.4lf, %3.4lf, %3.4lf\n", t, ax, ay, az);
   CODE SECTION 1
        printf("At %d ms, the acceleration's magnitude was: %lf\n",
            t, mag(ax, ay, az)); */
   CODE SECTION 2 */
        printf("At %d minutes, %d seconds, and %d milliseconds it was: %lf\n",
        minutes(t), seconds(t), millis(t), mag(ax,ay,az));
        fflush(stdout);
    }
return 0;
}
/* Put your functions here */
double mag (double x, double y, double z) {
    double magnitude = sqrt(pow(x, 2) + pow(y, 2) + pow(z, 2));
    return magnitude;
}
int minutes (int time) {
    int minsLeft = time / 60 / 1000; // Converts ms to minutes
    return minsLeft;
}
int seconds (int time) {
    int secsLeft = time / 1000;
    int minsUsed = minutes(time) * 60; // Converts minutes already used to seconds
    secsLeft -= minsUsed; // Discounts time already reported
    return secsLeft;
```

```
int millis (int time) {
   int msLeft = time;
   int minsUsed = minutes(msLeft) * 60 * 1000; // Converts minutes already reported to
   milliseconds
   msLeft -= minsUsed; // Discounts time already reported
   int secsUsed = seconds(msLeft) * 1000; // Converts seconds already reported to milliseconds
   msLeft -= secsUsed; // Discounts time already reported
   return msLeft;
}
```

```
At 2 minutes, 45 seconds, and 136 milliseconds it was: 0.955535
At 2 minutes, 45 seconds, and 138 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 141 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 143 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 145 milliseconds it was: 0.955962
At 2 minutes, 45 seconds, and 147 milliseconds it was: 0.955962
At 2 minutes, 45 seconds, and 150 milliseconds it was: 0.955962
At 2 minutes, 45 seconds, and 152 milliseconds it was: 0.955535
At 2 minutes, 45 seconds, and 154 milliseconds it was: 0.949381
At 2 minutes, 45 seconds, and 157 milliseconds it was: 0.949334
At 2 minutes, 45 seconds, and 159 milliseconds it was: 0.948901
At 2 minutes, 45 seconds, and 161 milliseconds it was: 0.948901
At 2 minutes, 45 seconds, and 164 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 167 milliseconds it was: 0.961644
At 2 minutes, 45 seconds, and 169 milliseconds it was: 0.961644
At 2 minutes, 45 seconds, and 171 milliseconds it was: 0.955962
At 2 minutes, 45 seconds, and 174 milliseconds it was: 0.949334
At 2 minutes, 45 seconds, and 176 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 178 milliseconds it was: 0.955962
At 2 minutes, 45 seconds, and 181 milliseconds it was: 0.949810
At 2 minutes, 45 seconds, and 183 milliseconds it was: 0.949805
At 2 minutes, 45 seconds, and 185 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 187 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 190 milliseconds it was: 0.962113
At 2 minutes, 45 seconds, and 192 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 194 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 197 milliseconds it was: 0.955962
At 2 minutes, 45 seconds, and 199 milliseconds it was: 0.956007
At 2 minutes, 45 seconds, and 201 milliseconds it was: 0.949381
At 2 minutes, 45 seconds, and 204 milliseconds it was: 0.949810
At 2 minutes, 45 seconds, and 207 milliseconds it was: 0.949810
At 2 minutes, 45 seconds, and 209 milliseconds it was: 0.949381
At 2 minutes, 45 seconds, and 211 milliseconds it was: 0.948947
At 2 minutes, 45 seconds, and 214 milliseconds it was: 0.949381
At 2 minutes, 45 seconds, and 216 milliseconds it was: 0.949334
At 2 minutes, 45 seconds, and 218 milliseconds it was: 0.955535
At 2 minutes, 45 seconds, and 221 milliseconds it was: 0.949381
At 2 minutes, 45 seconds, and 223 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 225 milliseconds it was: 0.955535
At 2 minutes, 45 seconds, and 227 milliseconds it was: 0.961216
At 2 minutes, 45 seconds, and 230 milliseconds it was: 0.961644
At 2 minutes, 45 seconds, and 232 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 234 milliseconds it was: 0.948896
At 2 minutes, 45 seconds, and 237 milliseconds it was: 0.955058
At 2 minutes, 45 seconds, and 239 milliseconds it was: 0.961644
At 2 minutes, 45 seconds, and 241 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 244 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 246 milliseconds it was: 0.949334
At 2 minutes, 45 seconds, and 249 milliseconds it was: 0.949805
At 2 minutes, 45 seconds, and 251 milliseconds it was: 0.949330
At 2 minutes, 45 seconds, and 254 milliseconds it was: 0.955962
At 2 minutes, 45 seconds, and 256 milliseconds it was: 0.955962
At 2 minutes, 45 seconds, and 258 milliseconds it was: 0.949381
At 2 minutes, 45 seconds, and 261 milliseconds it was: 0.949810
At 2 minutes, 45 seconds, and 263 milliseconds it was: 0.949856
At 2 minutes, 45 seconds, and 265 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 267 milliseconds it was: 0.955535
At 2 minutes, 45 seconds, and 270 milliseconds it was: 0.949334
At 2 minutes, 45 seconds, and 272 milliseconds it was: 0.955489
At 2 minutes, 45 seconds, and 274 milliseconds it was: 0.949334
```

```
/* Lab 4 Wrapper Program */
#include <stdio.h>
#include <math.h>

#define TRUE 1

/* Put your function prototypes here */
int main(void) {
    int a, b, x, y, joystick, buttonsPressed;

    while (TRUE) {
        scanf("%d, %d, %d, %d, %d, %d, ", &a, &y, &x, &b, &joystick);
        buttonsPressed = (a + b + x + y + joystick);
        printf("%d buttons are being pressed\n", buttonsPressed);
        fflush(stdout);
    }

    return 0;
}

/* Put your functions here */
```

```
1 buttons are being pressed
```

```
1 buttons are being pressed
```

```
1 buttons are being pressed
```

```
1 buttons are being pressed
```

```
1 buttons are being pressed
```

```
1 buttons are being pressed
```

```
1 buttons are being pressed
```

```
1 buttons are being pressed
2 buttons are being pressed
```

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2 buttons are being pressed
```

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2 buttons are being pressed
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2 buttons are being pressed
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2 buttons are being pressed
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2 buttons are being pressed
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2 buttons are being pressed
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2 buttons are being pressed
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2 buttons are being pressed
3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
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3 buttons are being pressed
2 buttons are being pressed
2 buttons are being pressed
1 buttons are being pressed
0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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0 buttons are being pressed
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- 0 buttons are being pressed
- 0 buttons are being pressed
 0 buttons are being pressed
- 0 buttons are being pressed
 0 buttons are being pressed
- 0 buttons are being pressed