(Re)introduction to x86 Assembly

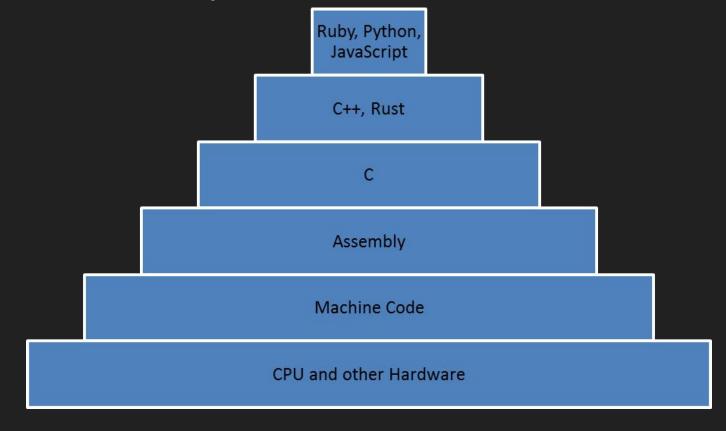
MST - 1/26

What is Assembly?

What and why

- Lowest level language we're concerned about directly writing
- Translates almost 1:1 into machine code for the CPU
- We focus on 32-bit x86 assembly in this class, common on Intel and AMD processors
 - Many other variants including ARM, RISC, AVR, etc
- Understanding assembly will help you learn what your computer is really doing
- Initial learning curve can be difficult, but stick with it

What is Assembly?



Basic Syntax

x86 Key Concepts

- Understanding assembly is crucial to low-level exploitation
- Instructions are the main unit of code
- Many instructions use registers, which are built-in named temporary variables
- Two main forms: Intel and AT&T syntax

Intel: mov eax, 12345

AT&T: movl \$12345, %eax

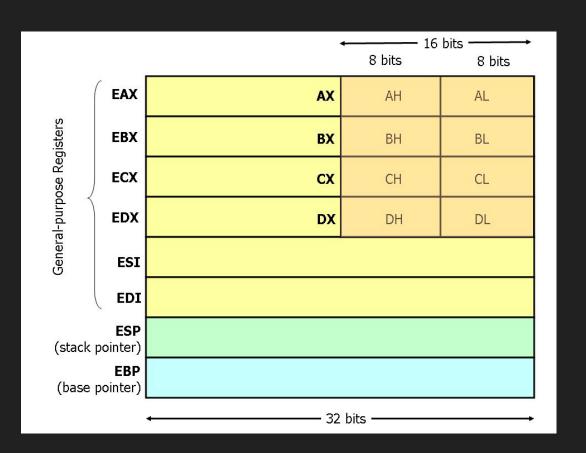
 May take multiple instructions to perform one higher-level "operation"

```
0000000000040057d <main>:
55
                                rbp
48 89 e5
                                rbp, rsp
48 83 ec 10
                                rsp,0x10
bf 44 06 40 00
                                edi,0x400644
e8 c1 fe ff ff
                         call
                                400450 <puts@plt>
c7 45 fc 05 00 00 00
                                DWORD PTR [rbp-0x4],0x5
                                DWORD PTR [rbp-0x4],0x1
83 45 fc 01
                         add
                                eax, DWORD PTR [rbp-0x4]
8b 45 fc
89 c6
                                esi,eax
bf 50 06 40 00
                                edi,0x400650
b8 00 00 00 00
                                eax.0x0
e8 b2 fe ff ff
                         call
                                400460 <printf@plt>
b8 00 00 00 00
                                eax.0x0
с3
                        ret
```

```
$ gcc hello.c
$ ./a.out
Hello World
6
```

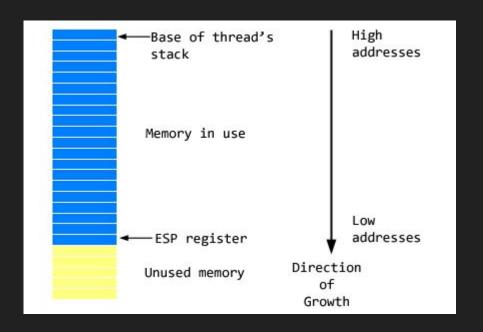
Registers

- EAX, EBX, ECX, EDX
 - Common general purpose registers
- ESP
 - Points to the "top" of the current stack frame
- EBP
 - Stack base pointer, points to the "bottom" of the current stack frame
- EIP
 - Points to the location of the current instruction in memory
- EFLAGS
 - Contains flag bits (zero flag, carry flag, sign flag, etc)



The Stack

- LIFO data structure used for local variables and function calls
- A stack frame is the portion of the stack used by the current function
- ESP stores the lowest address, which is the top of the stack
- EBP stores the highest address, which is the bottom of the current stack frame



Side note: Hexadecimal and Binary

- Both hex and binary are widely used in assembly and low-level exploitation
- Addresses are almost always expressed in hexadecimal
 - o 134524739 = 0x0804af43
- Useful to know ASCII representation of common characters in hex as well
 - \circ 'A' = 0x41, 'B' = 0x42,
- Understanding binary operations quickly can also be helpful
 - o AND, OR, XOR, NOT, etc

Side note: Little Endian vs Big Endian

- x86 is a little endian architecture, which refers to the order of bytes in memory for multi-byte data
- This matters only if you access specific bytes of a larger data type otherwise, it will be transparently handled for you

	0x100	0x101	0x102	0x103	200000
Big Endian	01	23	45	67	
	0x100	0x101	0x102	0x103	
Little Endian	67	45	23	01	

Common Instructions

Arithmetic Instructions

```
    add eax, 0x123

    \circ eax = eax + 0x123
• sub eax, 0x456
    \circ eax = eax - 0x456
and eax, ebx
    \circ eax = eax | ebx
not ecx
    \circ ecx = \simecx
• inc edx
    o edx++
```

```
• shl ecx, al
    \circ ecx = ecx << al
  mul ecx
    (edx:eax) = ecx * eax
div ecx
    o eax = (edx:eax) / ecx
      edx = (edx:eax) \% ecx
```

MOV Instructions

```
mov eax, ebx
      eax = ebx
  mov eax, 123
      eax = 123
 mov eax, DWORD PTR [0x123456]
      eax = *(0x123456)
  mov eax, DWORD PTR [edx+esi*4]
       eax = *(edx + esi * 4)
• lea esi, [ebp - 16]
      esi = ebp - 16
       Commonly used for pointer
       manipulations
```

Addressing Modes

```
[ebx]
[ebx - 4]
[ebx + eax]
[ebx + eax*4]
[ebx-eax]; Invalid
        (Can only add registers)
[ebx + eax + ecx]; Invalid
        (Can only use 2 registers)
```

Size Directives

```
BYTE PTR [edx]
WORD PTR [edx]
DWORD PTR [edx]
```

Control Flow Instructions

- jmp eax
 - Unconditional jump
- jz \$my_location
 - Jump if zero flag set
- jnz \$my_location
 - Jump if zero flag not set
- jg \$my_location
 - Jump if greater
- jb \$my_location
 - Jump if below

EFLAGS register

- Stores bit flags to indicate the results of operations
 - Carry Flag
 - Zero Flag
 - Sign Flag
- Implicitly set after certain instructions

```
mov eax, 5
cmp eax, 4
jg $cool_place
jz $also_cool
```

PUSH, POP, CALL, RET

- Mainly used for calling functions and saving registers
- push ebp
 - Puts EBP on the top of the stack and decrements ESP
- pop ebp
 - Loads the top of the stack into ESP and increments ESP
- call 400460 <printf@plt>
 - Pushes the address of the next instruction to the stack and jumps to 400460
- ret
 - Pulls the top of the stack into EIP and continues execution

Calling Conventions

- When compilers generate x86 from C, they use the cdecl calling convention
- cdecl specifies what to do with registers and the stack
 - Which registers have to be saved before calling a function?
 - How are arguments passed?
 - How do we handle saving and updating EBP and ESP?
 - Which function should handle cleanup?
- Since all relevant C compilers for x86 use cdecl, their code can interoperate

cdecl

- Function arguments are pushed to the stack in reverse order before the call
- EBP is set to the top of the stack at the beginning of the function
- EBP is restored at the bottom of a function
- Caller is responsible for
 - Cleaning up the stack after a call
 - Saving EAX, ECX, and EDX registers
- Callee is responsible for
 - Putting the return value in EAX
 - Preserving all other registers

callee(1, 2, 3);

```
caller:
    ; push call arguments
    push 3
    push 2
    push 1
    ; call subroutine 'callee'
    call callee
    ; remove arguments from frame
    add
        esp, 12
    ; use subroutine result
    cmp eax, 6
```

```
callee:
    ; make new call frame
            ebp
    push
           ebp, esp
    mov
    ; use arguments to set result
    mov eax, [ebp+0x8]
    mov edx, [ebp+0xc]
    mov ecx, [ebp+0x10]
    add eax, edx
    add eax, ecx
    ; restore old call frame
            ebp
    pop
    ; return to caller
    ret
```

Calling Conventions

- You don't have to use cdecl when writing in assembly...
- ...but you won't be able to call 32-bit C library functions!
- Also, it's good to get practice for later when we are reading compiler-generated assembly

Basic x86 example

What does this code do?

```
my function:
    push ebp
    mov ebp, esp
    mov eax, [ebp+0x4]
    mov edx, [ebp+0x8]
body:
    mov ecx, [eax]
    cmp ecx, edx
    jz found
    cmp ecx, 0
    jz notfound
    inc eax
    jmp body
```

```
found:
    mov ecx, [ebp+0x4]
    sub eax, ecx
    jmp done
notfound:
    xor eax, eax
done:
    pop ebp
    ret
```

What does this code do?

```
my function:
    push ebp ; function prologue
    mov ebp, esp
    mov eax, [ebp+0x4]
    mov edx, [ebp+0x8]
body: ; loop body
    mov ecx, [eax]
    cmp ecx, edx ; what is ecx? edx?
    jz found
    cmp ecx, 0
    iz notfound
    inc eax
    jmp body
```

```
found: ; success case
    mov ecx, [ebp+0x4]
    sub eax, ecx
    jmp done
notfound: ; error case
    xor eax, eax
done: ; function epilogue
    pop ebp
    ret
```

x86 -> C

```
my function:
    push ebp
    mov ebp, esp
    mov eax, [ebp+0x4]
    mov edx, [ebp+0x8]
body:
    mov ecx, [eax]
    cmp ecx, edx
    jz found
    cmp ecx, 0
    jz notfound
    inc eax
    jmp body
( rest omitted )
```

```
int my function(char *d, char ch)
    int x = 0;
    while (d[x] != 0) {
        if (d[x] == ch)
            return x;
        X++;
    return 0;
```

Creating Executables

Using GCC as an assembler

```
$ gcc -m32 -o simple simple.s

$ ./simple

$ .globl main

main:

main:

mov eax, 1

ret
```

Calling C functions

```
$ gcc -m32 -o hello hello.s
$ ./hello
Hello World!
```

```
.intel syntax noprefix
.data
message:
.string "Hello World!"
.text
.globl main
main:
mov ecx, offset message
push ecx
call puts
pop ecx
mov eax, 0
ret
```

Print an argument

```
$ gcc -m32 -o arg arg.s
$ ./arg ayyy
ayyy
```

```
.intel_syntax noprefix
.text
.globl main
main:
push ebp
mov ebp, esp
mov ecx, [ebp+0xc]
mov ecx, [ecx+0x4]
push ecx
call puts
pop ecx
mov eax, ∅
pop ebp
ret
```

Homework

Homework: Print out a file backwards

 Write a script that accepts a filename, reads in the file, and prints it out backwards

```
$ cat hello_world.txt
Hello World!
$ ./your_program hello_world.txt
!dlroW olleH
```

Write code only in 32-bit x86 assembly, but no other restrictions

Homework grading

- Submit your assembly code file to <u>cm7bv@virginia.edu</u> with the subject "MST Assignment 1 <YOUR_UVA_ID>"
 - eg: "MST Assignment 1 cm7bv"
- Also, include a brief (1-paragraph) description of what you did and how it went
- We've included a simple grading script you can test your program against in the GitHub repository (check the folder for today's class)

Homework tips

- You will need to use dynamic memory management (with malloc/free) handle command line arguments
- Don't overthink it or worry about performance. Only consider correctness.
- You can use gcc to assemble your code into a program
 - eg: gcc my_code.s
- Become familiar with <u>man pages</u>, they are invaluable
- Syscalls may be easier than the C standard library in many cases
- Don't be afraid to ask questions either via Slack or email!

Good Resources

Resources

https://en.wikibooks.org/wiki/X86_Assembly

https://www.nayuki.io/page/a-fundamental-introduction-to-x86-assembly-programming

https://www.cs.virginia.edu/~evans/cs216/guides/x86.html

General bash and terminal practice: http://overthewire.org/wargames/bandit/