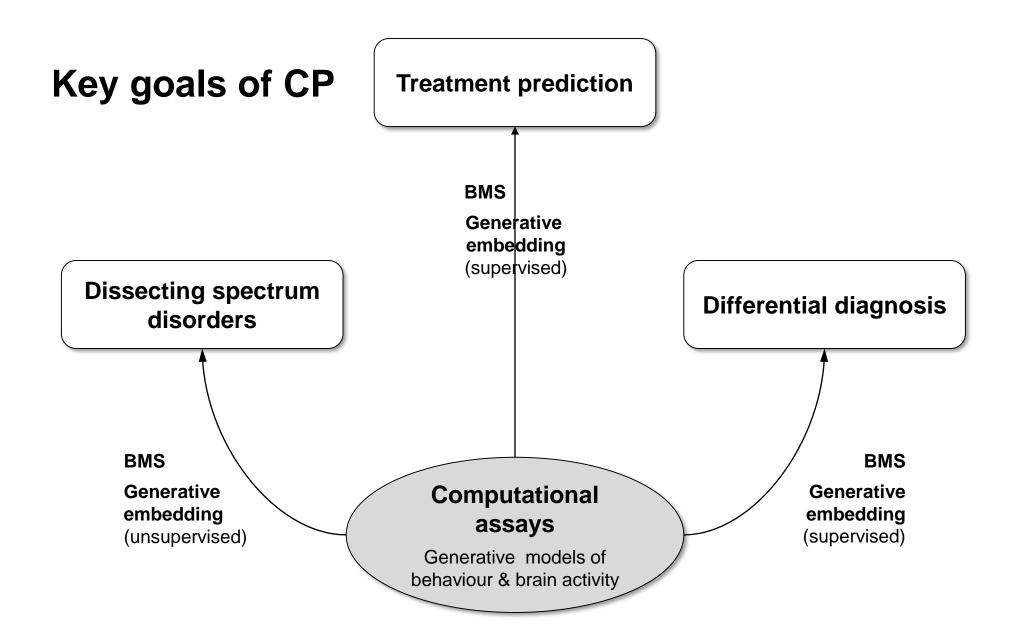
Bayesian model selection (BMS)

Klaas Enno Stephan



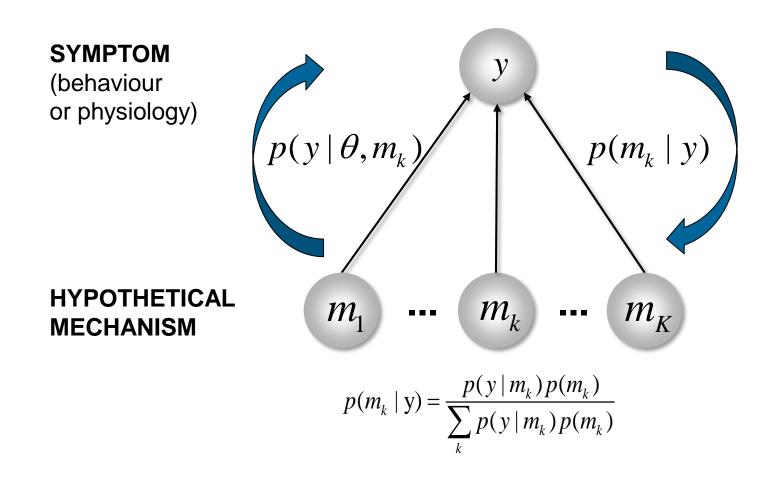




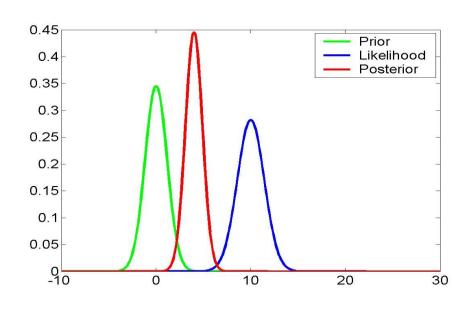


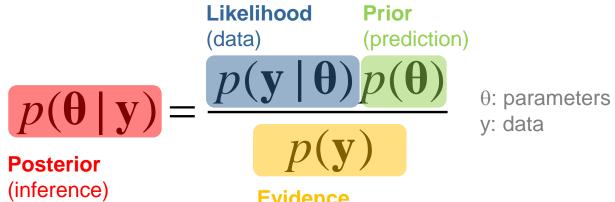
adapted from: Stephan & Mathys 2014, *Curr. Opin. Neurobiol.*

BMS for differential diagnosis



Reminder: Bayes' rule





Evidence

(normalisation term)

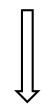
The Reverend Thomas Bayes (1702-1761)

"... the theorem expresses how a ... degree of belief should rationally change to account for availability of related evidence."

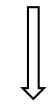
Wikipedia

Model comparison and selection

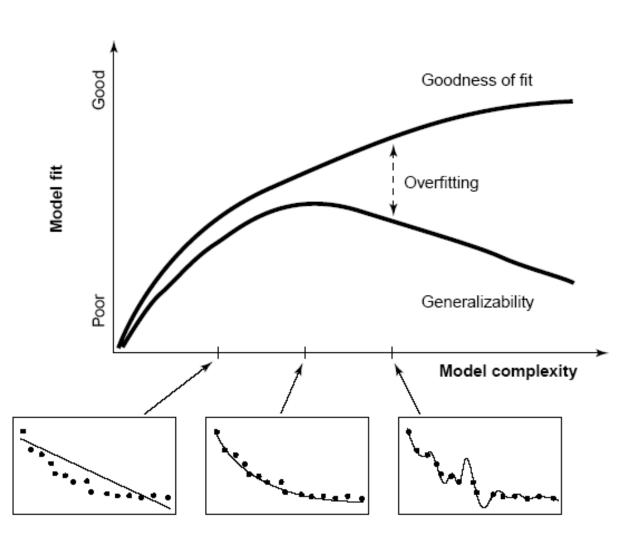
Given competing hypotheses on structure & functional mechanisms of a system, which model is the best?



Which model represents the best balance between model fit and model complexity?



For which model m does p(y|m) become maximal?



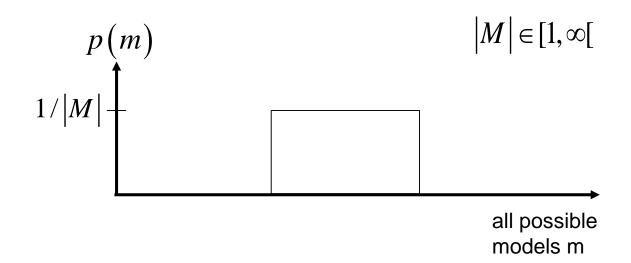
Pitt & Miyung (2002) TICS

Bayesian model selection (BMS)

- A major goal of generative modeling: comparing competing hypotheses about the mechanisms underlying observed data
 - a priori definition of hypothesis set (model space) is crucial
- BMS = selecting the model (within the pre-specified model space) that has the highest probability of having generated the data
- Model selection is not equal to model validation and only allows one to compare the relative goodness of competing hypotheses within the prespecified model space!
- Model validation requires external criteria (external to the measured data).

BMS: Defining the model space

- The model space M comprises all models m that are deemed plausible a priori. This is the researcher's hypothesis space.
- Defining M is equivalent to defining a prior over models, p(m), such that a finite set of models has non-zero prior probability.
- Usually, all models in M are assigned equal prior probability.



BMS: Applying Bayes' rule to models

 We wish to select the model that has the highest posterior probability given the data:

$$p(m_i \mid y) = \frac{p(y \mid m_i) p(m_i)}{p(y)} = \frac{p(y \mid m_i) p(m_i)}{\sum_{j=1}^{|M|} p(y \mid m_j) p(m_j)}$$

Under uniform priors over models, all prior model probabilities are identical:

$$p(m_i \mid y) = \frac{p(y \mid m_i)}{\sum_{j=1}^{|M|} p(y \mid m_j)}$$
 identical for all models

We can thus use the model evidence to compare and select models.

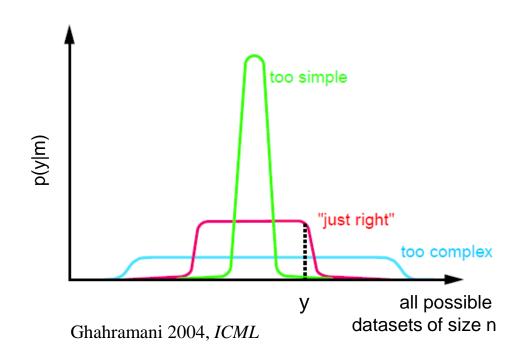
Model evidence: How can it be interpreted?

Model evidence = marginal likelihood:

$$p(y | m) = \int p(y | \theta, m) p(\theta | m) d\theta$$

randomly selected parameters from the prior would generate the observed data

log evidence accounts for both accuracy and complexity of the model



Overly simple models are unlikely to generate the given data.

Overly complex models can generate many possible datasets and are thus unlikely to have generated the specific dataset that is given.

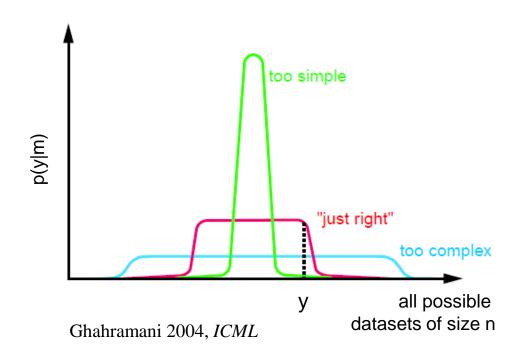
Model evidence: How can it be interpreted?

Model evidence = marginal likelihood:

$$p(y | m) = \int p(y | \theta, m) p(\theta | m) d\theta$$

"If I randomly sampled from my prior and plugged the resulting value into the likelihood function, how close would the predicted data be – on average – to my observed data?"

log evidence accounts for both accuracy and complexity of the model



Overly simple models are unlikely to generate the given data.

Overly complex models can generate many possible datasets and are thus unlikely to have generated the specific dataset that is given.

Model evidence: How can it be computed?

Analytically:

only possible in rare cases (e.g. linear Gaussian models)

By approximation:

- Akaike Information Criterion (AIC)
- Bayesian Information Criterion (BIC)
- Variational Bayes (VB)
 - negative free energy as lower bound approximation to the log evidence
- Sampling-based methods
 - prior arithmetric mean estimator
 - posterior harmonic mean estimator
 - thermodynamic integration (TI)

AIC/BIC approximations to the model evidence

- Generally:
 - For numerical reasons, we typically approximate the log evidence (the logarithm is a strictly monotonic function).
 - The log evidence (and its approximations) can be decomposed into accuracy and complexity terms:

$$\log p(y \mid m) = accuracy(m) - complexity(m)$$

$$= \log p(y \mid \theta, m) - complexity(m)$$
No. of parameters

Akaike Information Criterion: $AIC = \log p(y \mid \theta, m) - p$
No. of data points

Akaike Information Criterion: $AIC = \log p(y \mid \theta, m) - p$ Bayesian Information Criterion: $BIC = \log p(y \mid \theta, m) - \frac{p}{2} \log N$

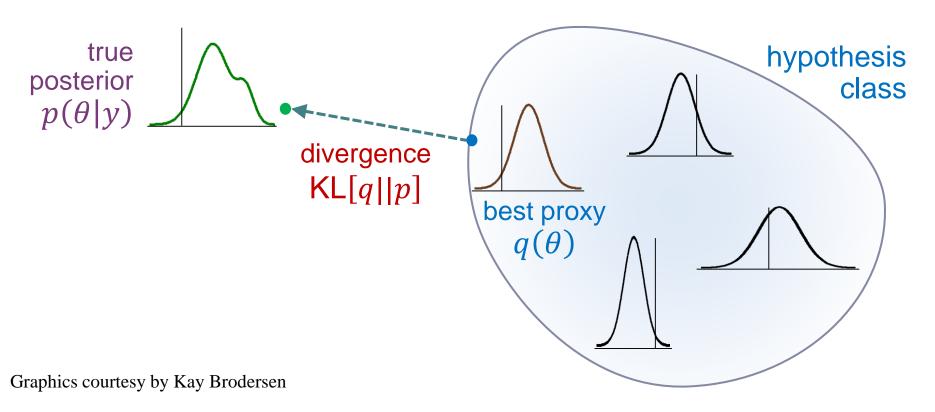
Pros and cons of AIC/BIC

- easy and fast to compute
 - only the MLE of the parameters and counting (parameters and data points) is needed.
- but: a limited concept of model complexity
 - all parameters contribute equally to complexity, regardless of how they can affect the data
 - e.g. do not take into account dependencies amongst parameters
- a richer concept of model complexity is provided by the negative free energy (aka "evidence lower bound", ELBO)

Recap: Variational Bayes (VB)

Basic idea of VB: find an approximate density $q(\theta)$ that is maximally similar to the true posterior $p(\theta|y)$.

This is often done by assuming a particular form for q (fixed form VB) and then optimising its sufficient statistics.



Recap: Variational Bayes

$$\ln p(y) = \text{KL}[q||p] + F(q,y)$$

$$\text{divergence neg. free}$$

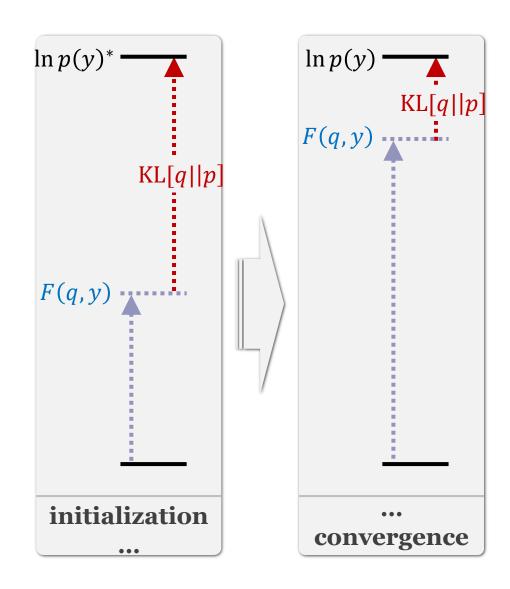
$$\geq 0 \quad \text{energy}$$

$$\text{(unknown) (easy to evaluate for a given } q)$$

F(q, y) is a functional wrt. the approximate posterior $q(\theta)$.

Maximizing F(q, y) is equivalent to:

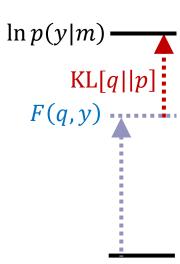
- minimizing KL[q||p],
- making $q(\theta)$ the best possible estimate of the posterior,
- tightening F(q, y) as a lower bound to the log model evidence.



The negative free energy approximation ${\it F}$

F is a lower bound on the log model evidence:

$$\log p(y | m) = F + KL[q(\theta), p(\theta | y, m)]$$



Like AIC/BIC, F is an accuracy/complexity tradeoff:

$$F = \underbrace{\langle \log p(y \mid \theta, m) \rangle}_{accuracy} - \underbrace{KL[q(\theta), p(\theta \mid m)]}_{complexity}$$

The complexity term in *F*

In contrast to AIC & BIC, the complexity term of the negative free energy F
accounts for parameter interdependencies.

Under Gaussian assumptions about the posterior (Laplace approximation):

$$KL[q(\theta), p(\theta \mid m)] = \frac{1}{2} \ln |C_{\theta}| - \frac{1}{2} \ln |C_{\theta|y}| + \frac{1}{2} (\mu_{\theta|y} - \mu_{\theta})^T C_{\theta}^{-1} (\mu_{\theta|y} - \mu_{\theta})$$

- The complexity term of F is higher
 - the more independent the prior parameters (↑ effective DFs)
 - the more dependent the posterior parameters
 - the more the posterior mean deviates from the prior mean

Bayes factors

To compare two models, we could just compare their log evidences.

But the log evidence is just some number – not very intuitive!

A more intuitive interpretation of model comparisons is made possible by Bayes factors:

$$B_{12} = \frac{p(y | m_1)}{p(y | m_2)}$$

positive value, [0; ∞[

Kass & Raftery classification:

B ₁₂	$p(m_1 y)$	Evidence
1 to 3	50-75%	weak
3 to 20	75-95%	positive
20 to 150	95-99%	strong
≥ 150	≥ 99%	Very strong

Fixed effects BMS at group level

Group Bayes factor (GBF) for 1... K subjects:

$$GBF_{ij} = \prod_{k} BF_{ij}^{(k)}$$

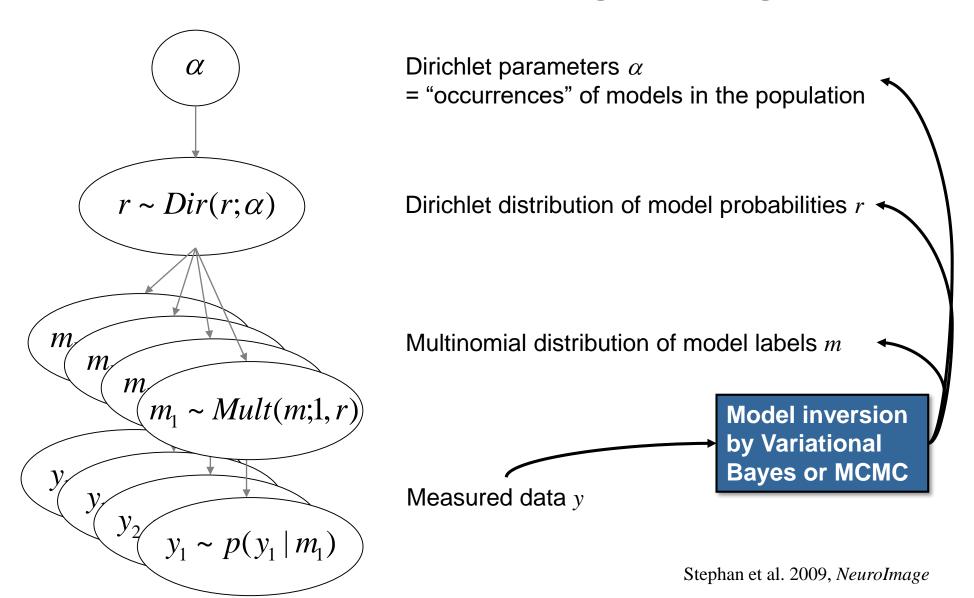
Average Bayes factor (ABF):

$$ABF_{ij} = \sqrt[K]{\prod_{k} BF_{ij}^{(k)}}$$

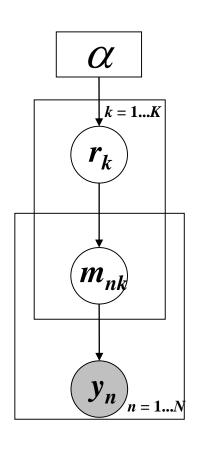
Problems:

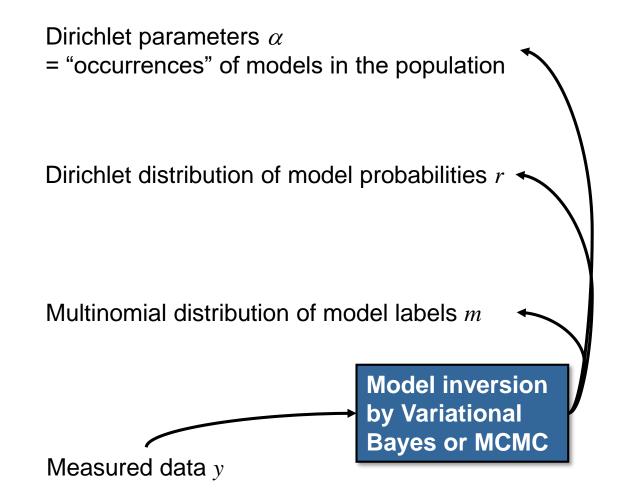
- blind with regard to group heterogeneity
- sensitive to outliers

Random effects BMS for heterogeneous groups



Random effects BMS: plate notation





Four equivalent options for reporting model ranking by random effects BMS

1. Dirichlet parameter estimates

 α

2. **expected posterior probability** of obtaining the k-th model for any randomly selected subject

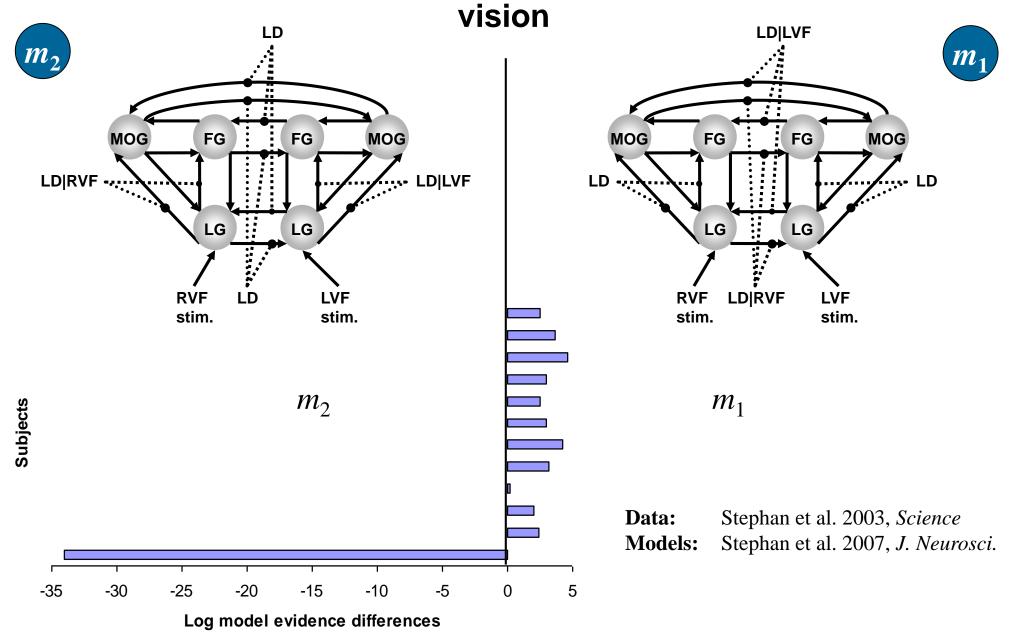
$$\langle r_k \rangle_q = \alpha_k / (\alpha_1 + \ldots + \alpha_K)$$

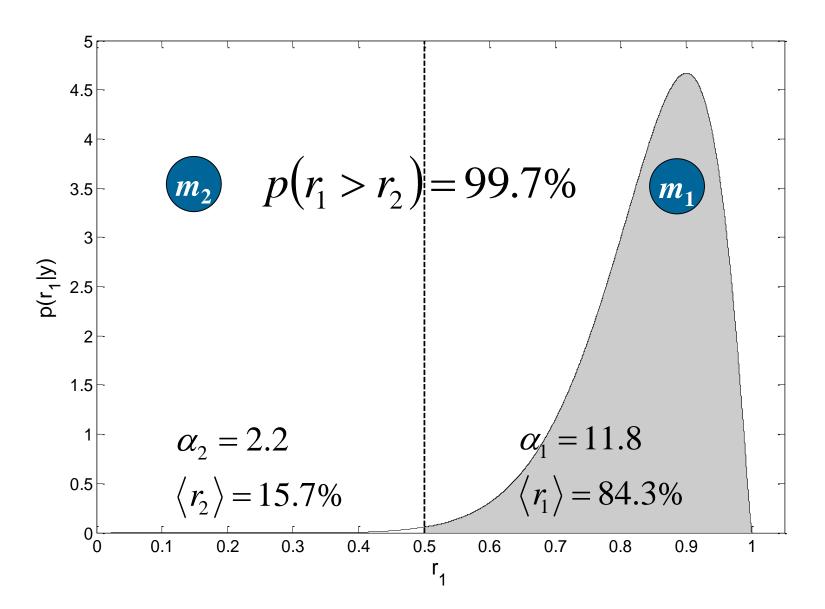
3. **exceedance probability (XP)** that a particular model *k* is more likely than any other model (of the *K* models tested), given the group data

$$\exists k \in \{1...K\}, \forall j \in \{1...K \mid j \neq k\}:$$
$$\varphi_k = p(r_k > r_j \mid y; \alpha)$$

 protected exceedance probability (PXP): see Rigoux et al. (2014) and below

Example: Hemispheric interactions during





Protected exceedance probability: Using BMA to protect against chance findings

- XPs express our confidence that the posterior probabilities of models are different under the hypothesis H_1 that models differ in probability: $r_k \neq 1/K$
- does not account for the possibility of the "null hypothesis" H_0 : $r_k=1/K$
- protected exceedance probability:

Bayesian model averaging (BMA, see below) over H₀ and H₁:

$$PXP = P(r_k \ge r_{k'=k} \mid y)$$

$$= P(r_k \ge r_{k'=k} \mid y, H_1) P(H_1 \mid y) + P(r_k \ge r_{k'=k} \mid y, H_0) P(H_0 \mid y)$$

Example: DA effects on strial connectivity

- task-free fMRI with 2x2 pharmacological design (sulpiride, bromocriptin, ON/OFF)
- stochastic DCM
- DA drug effects on the striatum vary widely across individuals and might average to zero
- BMS: identifies where DA drugs alter intrastriatal connectivity, even when the sign of this effect was not consistent across participants

intra-striatal connectivity dopaminergic modulation DAP DAP A₁ B₀ A2 **B1 A3 B2** A4 **B3 A5 B4 B5**





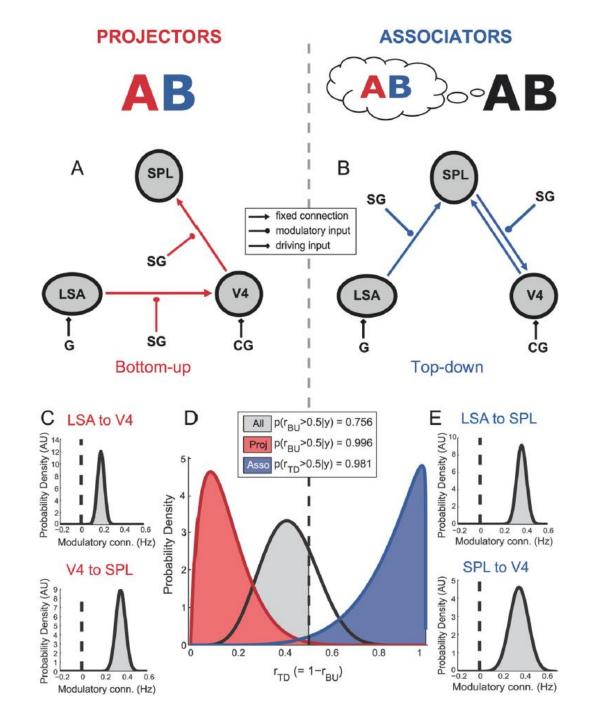
winning model

VS: ventral striatum

DCN: dorsal caudate nucleus DAP: dorsal anterior putamen

Example: Synaesthesia

- "projectors" experience color externally colocalized with a presented grapheme
- "associators" report an internally evoked association
- across all subjects: no evidence for either model
- but BMS results map precisely onto projectors (bottom-up mechanisms) and associators (top-down)



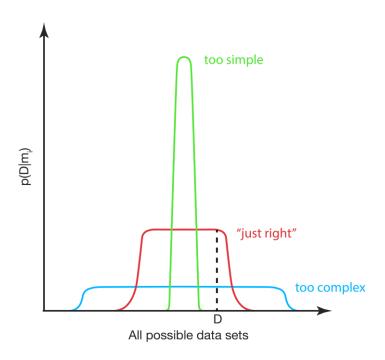
Overfitting at the level of models

Common question:

There is an infinite number of possible models for a given dataset. Should we not strive for a "brute force" search and compare as many models as possible?

Not necessarily.

The more models are included in the model space, the risk of overfitting (at the level of models) increases, too.



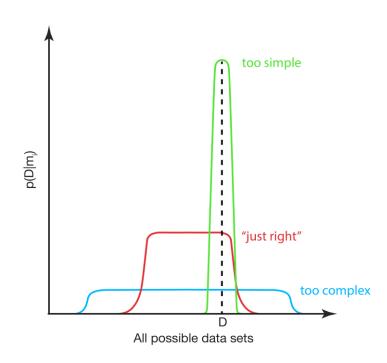
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Not necessarily.

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Overfitting at the level of models

In brief: \uparrow #models \Rightarrow \uparrow risk of overfitting

Three solutions in the context of BMS:

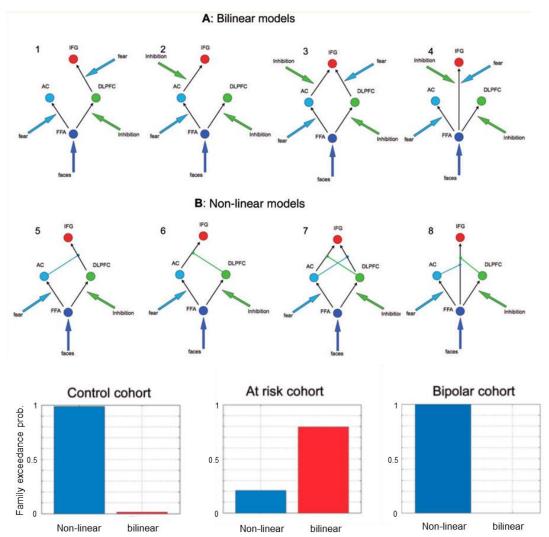
- Regularisation: choosing priors over models p(m) such that model space is small
- Pamily-level BMS
- Bayesian model averaging (BMA)

Family-level BMS

- rests on partitioning model space into K subsets or families: $M = \{f_1, ..., f_K\}$
- pooling information over all models in these subsets allows one to compute the probability of a model family, given the data
- effectively removes uncertainty about any aspect of model structure, other than the attribute of interest (which defines the partition)
- the uniform prior over models is replaced with a uniform prior over families:
 - For **FFX**, this means family prior $p(f) = \frac{1}{K}$ and model prior $p(m) = \frac{1}{KN_k}$.
 - For **RFX**, fair priors over families are achieved by setting $\alpha_{prior}(m) = \frac{1}{N_k}$.

Example application of family-level BMS: Bipolar disorder

- Go/No-Go task to emotional faces with bipolar patients, at-risk individuals, healthy controls
- DCM used to explain interaction of motor inhibition and fear processing during this task.
- Family-level BMS showed differences in general model structure (bilinear vs. nonlinear models) between at-risk group vs. healthy controls and bipolar patients.



Bayesian Model Averaging (BMA)

- abandons dependence of parameter inference on a single model and takes into account model uncertainty
- uses the entire model space considered (or an optimal family of models)
- averages parameter estimates, weighted by posterior model probabilities
- represents a particularly useful alternative
 - when none of the models (or model subspaces) considered clearly outperforms all others
 - when comparing groups for which the optimal model differs

single-subject BMA:

$$p(\theta | y)$$

$$= \sum_{m} p(\theta | y, m) p(m | y)$$

group-level BMA:

$$p(\theta_n | y_{1..N})$$

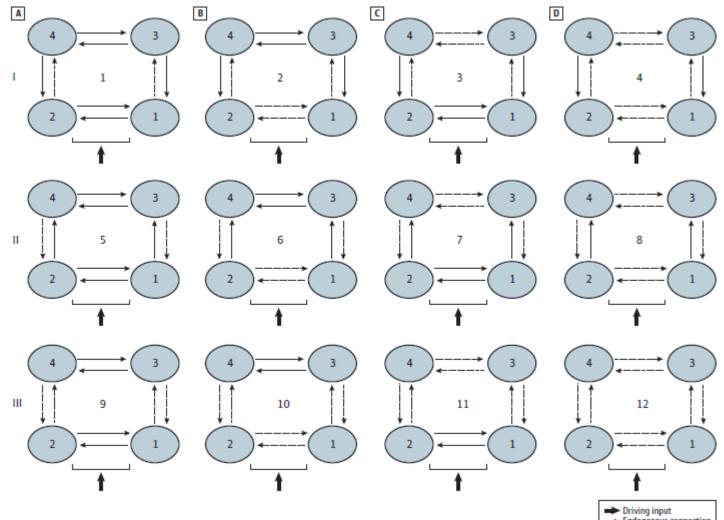
$$= \sum_{m} p(\theta_n | y_n, m) p(m | y_{1..N})$$

NB: $p(m|y_{1..N})$ can be obtained by either FFX or RFX BMS

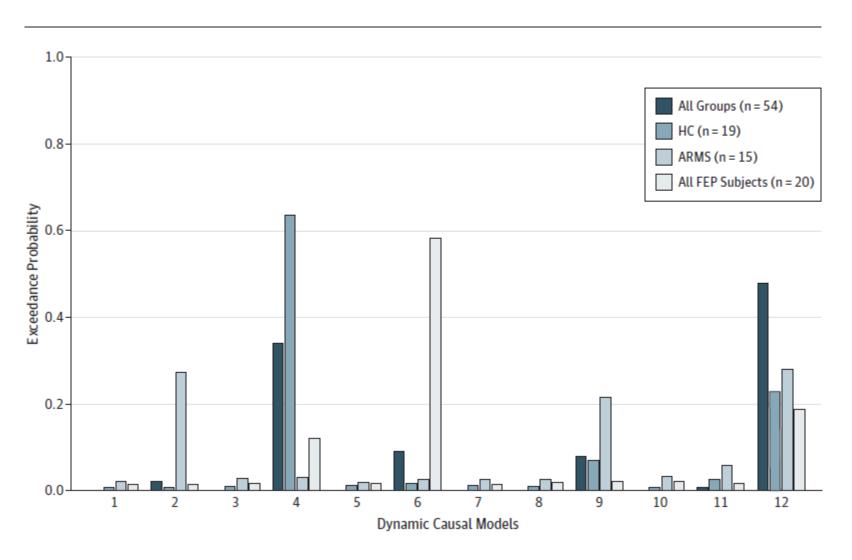


Prefrontal-parietal connectivity during working memory in schizophrenia

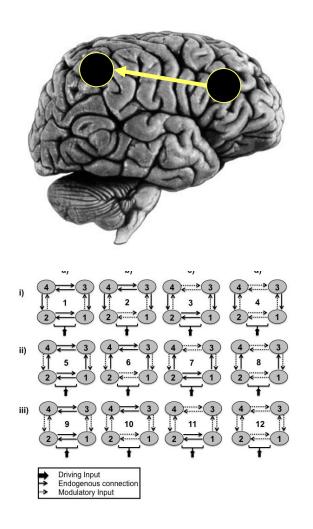
- 17 at-risk mental state (ARMS) individuals
- 21 first-episode patients (13 non-treated)
- 20 controls

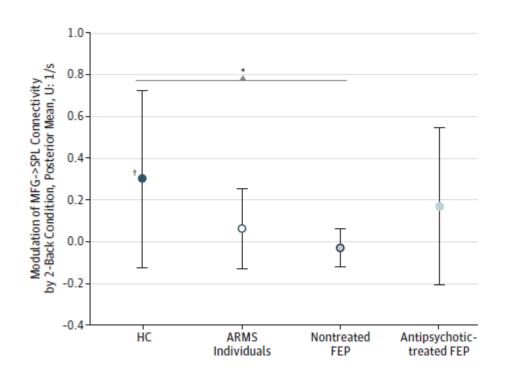


BMS results for all groups

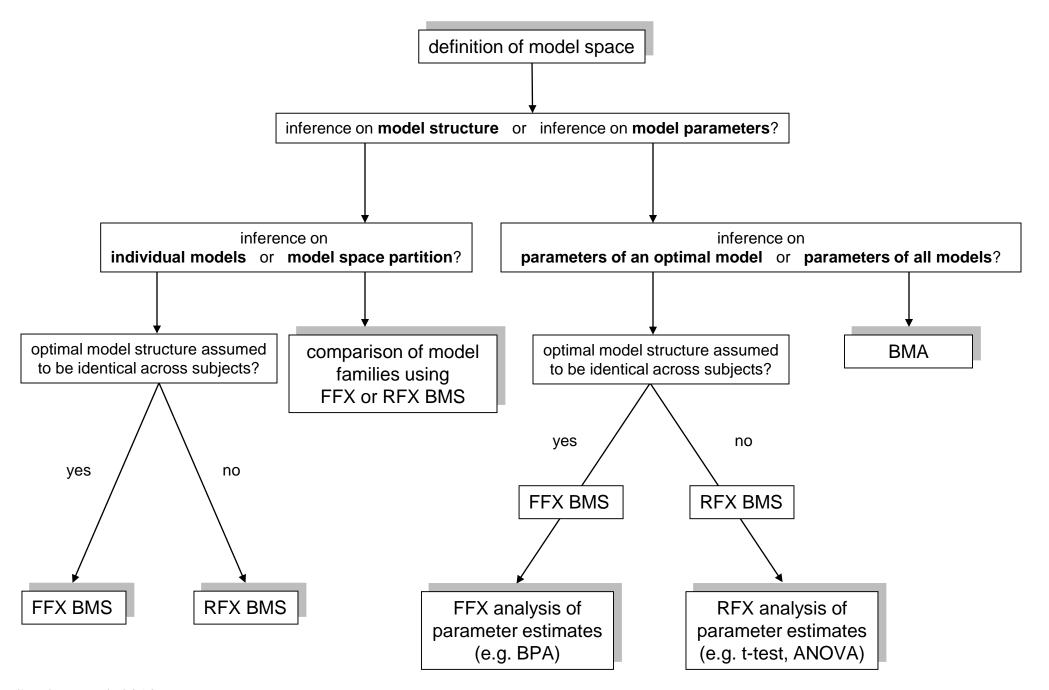


BMA results: PFC → PPC connectivity





17 ARMS, 21 first-episode (13 non-treated), 20 controls



Important topics I have not covered in this talk

- Bayesian model reduction
 - an efficient alternative to RFX-BMS (applicable to nested models only)
 - see:
 Friston KJ et al. (2016) Neurolmage 128:413-431
 https://www.sciencedirect.com/science/article/pii/S105381191501037X
- estimating the model evidence with sampling-based methods, such as thermodynamic integration
 - for a tutorial review, see:
 Aponte, Yao et al. (2021) Cognitive Neurodynamics
 https://link.springer.com/article/10.1007/s11571-021-09696-9

Further reading

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- Penny WD, Stephan KE, Daunizeau J, Joao M, Friston K, Schofield T, Leff AP (2010) Comparing Families of Dynamic Causal Models. PLoS Computational Biology 6: e1000709.
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 Neuroimage 59: 319-330.
- Rigoux L, Stephan KE, Friston KJ, Daunizeau J (2014) Bayesian model selection for group studies revisited. NeuroImage 84: 971-985.
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- Stephan KE, Schlagenhauf F, Huys QJM, Raman S, Aponte EA, Brodersen KH, Rigoux L, Moran RJ, Daunizeau J, Dolan RJ, Friston KJ, Heinz A (2017) Computational Neuroimaging Strategies for Single Patient Predictions. NeuroImage 145: 180-199.

Thank you