

# Assignment 1

## Convex Optimization SS 2018

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**Submission:** Upload your solution as a PDF to the TeachCenter. You can also use your scanned hand-written manuscript.

**Deadline:** April 16<sup>th</sup>, 2018 at 23:55h.

### Convex Sets (13 points)

1. Let  $C \subseteq \mathbb{R}^n$  be a convex set,  $x_1, \dots, x_k \in C$  and let  $\theta_1, \dots, \theta_k \in \mathbb{R}$  be factors that satisfy  $\theta_i \geq 0$  and sum up to one  $\sum_{i=1}^k \theta_i = 1$ . Show that any combination of points  $\theta_1 x_1 + \dots + \theta_k x_k$  is also element of the set  $C$ . Hint: Use induction on the definition of convexity.
2. Calculate the distance between two parallel hyperplanes  $\{x \in \mathbb{R}^n \mid a^T x = b_1\}$  and  $\{x \in \mathbb{R}^n \mid a^T x = b_2\}$ . You can derive this geometrically. Draw a picture!
3. Prove or disprove the convexity of the following sets:
  - a) The set  $\{x \in \mathbb{R} \mid x \geq 1/2, x \leq -1/2\}$ .
  - b) The set of points closer to one set than another, i.e.,  $\{x \mid \text{dist}(x, S) \leq \text{dist}(x, T)\}$  with  $S, T \subseteq \mathbb{R}^n$  (not necessarily convex) and  $\text{dist}(x, S) = \inf\{\|x - z\|_2 \mid z \in S\}$ .
  - c) A *hyperrectangle*:  $\{x \in \mathbb{R}^n \mid a_i \leq x_i \leq b_i, i = 1, \dots, n\}$ .
  - d) A *wedge*, i.e., a set of form  $\{x \in \mathbb{R}^n \mid a_1^T x \leq b_1, a_2^T x \leq b_2\}$ . What happens if  $b_1 = b_2 = 0$ ?
4. Let  $x_0, x_1, \dots, x_k \in \mathbb{R}^n$ . The set of points closer to a given point  $x_0$  than the other points  $x_1, \dots, x_k$

$$\{x \in \mathbb{R} \mid \|x - x_0\|_2 \leq \|x - x_i\|_2, \quad i = 1, \dots, k\} \quad (1)$$

is called a *Voronoi region* around  $x_0$  with respect to the points  $x_1, \dots, x_k$ .

- a) Show that (1) is a convex set.
- b) Equation (1) can be expressed in terms of a polyhedron. Rewrite (1) in the form  $\{x \mid Ax \preceq b\}$ .
- c) Consider the case  $k = 1$ . Show that the set of all points closer to  $x_0$  than to  $x_1$  is a halfspace,  $x_0 \neq x_1$ . Hint: Recall the definition of a halfspace  $\{x \mid a^T x \leq b\}$ . Draw a picture!

### Convex Functions (12 points)

1. Prove or disprove the convexity/concavity of the geometric mean

$$f(x) = \left( \prod_{i=1}^k x_i \right)^{\frac{1}{k}}$$

on  $\mathbb{R}_{++}^n$ .

2. Let  $f : \mathbb{R}^n \rightarrow [-\infty, +\infty]$ . Show that the perspective of  $f$  defined via

$$g(x, y) = yf(x/y), \quad x \in \mathbb{R}^n, y \in \mathbb{R}_+$$

is convex if and only if  $f(x)$  is a convex function.

3. Prove or disprove the convexity/concavity of the following functions:

- a)  $f(x) = \log(x)$  for  $x \in \mathbb{R}_{++}$
- b)  $f(x) = |a|x| - x^2$  for  $a, x \in \mathbb{R}$
- c)  $f(x_1, x_2, x_3) = -e^{(-x_1+x_2-2x_3)^2}$  for  $x \in \mathbb{R}^3$
- d)  $f(x) = \ln(e^{x_1} + e^{x_2} + \dots + e^{x_n})$  for  $x \in \mathbb{R}^n$

## Convex Sets

### 1) Proof by induction

$$\underline{n=1}: \quad \theta_1 \cdot x_1 \in C \quad \sum_i \theta_i = 1$$

$$\underline{n=2}: \quad \theta_1 x_1 + \theta_2 x_2 \in C \quad \sum_i \theta_i = 1$$

$$\theta_1 x_1 + (1-\theta_1) x_2 \in C \quad \checkmark$$

$$\underline{n=k}: \quad \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_k x_k \in C$$

Suppose, we know have  $k-1$  elements in ~~are~~  $\exists$

$$\lambda = \sum_{i=1}^{k-1} \theta_i$$

$$\theta'_i = \frac{\theta_i}{\lambda}$$

$$p := \sum_{i=1}^{k-1} \theta'_i x_i \in C \quad \text{Point } p \text{ is still in the convex set.}$$

Thus, by convexity of  $C$ :

$$\lambda \cdot p + (1-\lambda) \cdot x_k \in C$$

$$= \cancel{\lambda} \cdot \sum_{i=1}^{k-1} \theta'_i x_i + \cancel{\lambda} \cdot \theta_k x_k$$

$$= \sum_{i=1}^k \theta_i x_i \quad \square$$

2) Distance between 2 hyperplanes:  $\{x \in \mathbb{R}^n \mid \bar{a}^T x = b_1\}$

If I draw a line orthogonal through one hyperplane, then it will also intersect the 2nd hyperplane orthogonal.

$\rightarrow$  Distance is minimal, if the line intersects orthogonal.

$$\begin{aligned}\bar{a}^T x_i = b_i \mid a \quad \{i=1..2\} \\ \bar{a}^T a x_i = b_i \cdot a \quad ; \quad \bar{a}^T a \Leftrightarrow \|a\|_2^2 \\ x_i = \frac{b_i}{\|a\|_2^2} a\end{aligned}$$

$$\|x_1 - x_2\|_2 = \frac{|b_1 - b_2|}{\|a\|_2}$$

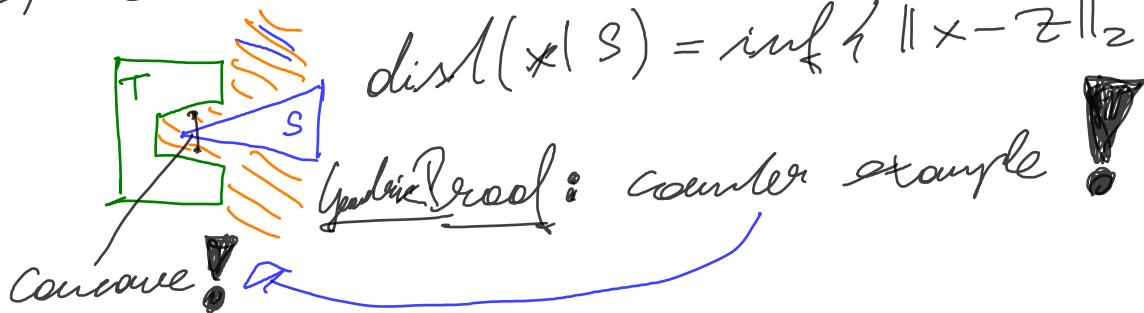
3) a) set  $\{x \in \mathbb{R} \mid x \geq \frac{1}{2}, x \leq -\frac{1}{2}\}$

Proof: by definition  $\rightarrow$  convex

Answer: An empty set is a convex set.

b)  $\{x \mid \text{dist}(x, S) \leq \text{dist}(x, T)\}$  with  $S, T \subseteq \mathbb{R}^n$ .

$$\text{dist}(x, S) = \inf \{ \|x - z\|_2 \mid z \in S \}$$



Analytical Proof:

$\{x \mid \text{dist}(x, S) \leq \text{dist}(x, T)\}$  with  $S = \{-1, 1\}$

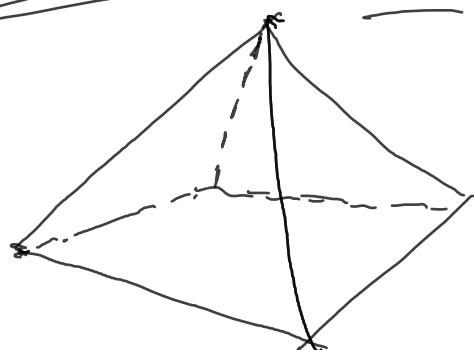
$$\text{and } T = \{0\}$$

$\Rightarrow$  is not convex  $\forall x$ , e.g.  $x \in \mathbb{R}: x \leq -\frac{1}{2}$

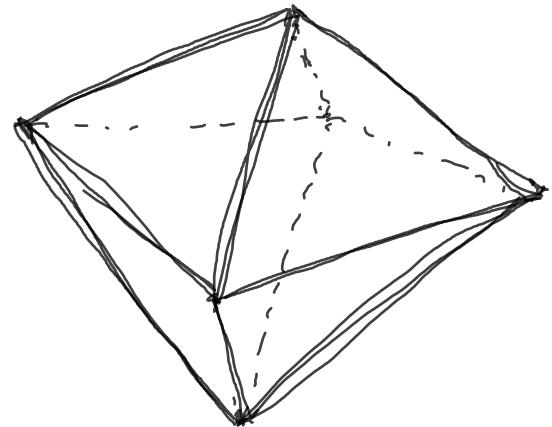
c) hyper rectangle  $\{x \in \mathbb{R}^n \mid a_i \leq x_i \leq b_i, i=1..n\}$

- ↳
  - Rectangle for higher dimensions.
  - Cartesian product of intervals.

$n > 2$



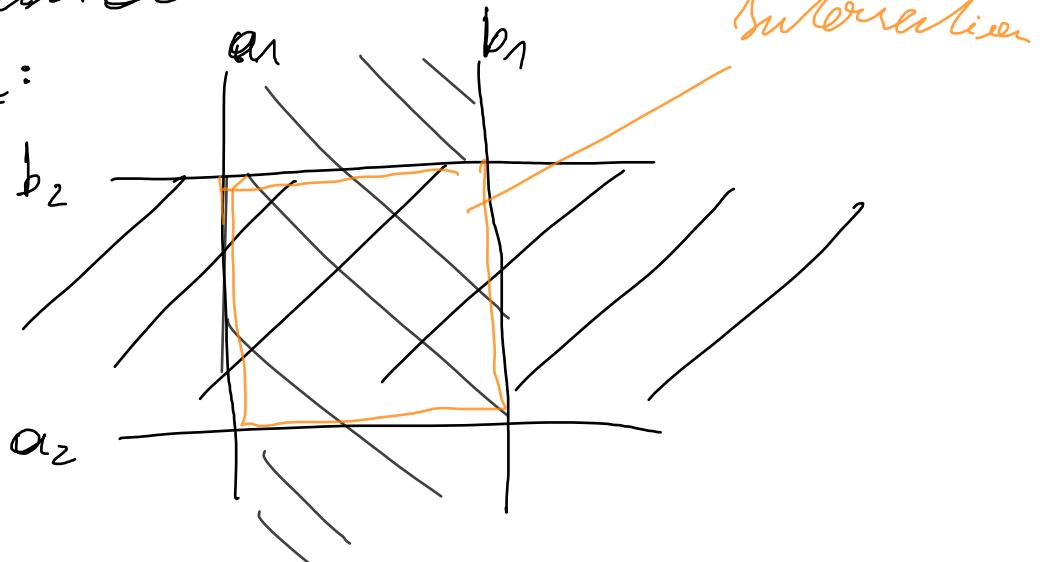
or:



Rectangle is a convex set by definition.  
whereas a rectangle of dimensions  $n > 2$  is called hyperrectangle

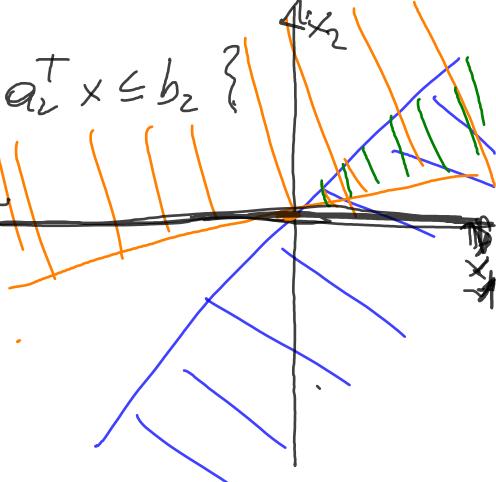
Halfspaces are convex by definition.  
If we intersect halfspaces, the intersection  
is again convex set.

2D case:



d) wedge:  $\{x \in \mathbb{R}^n \mid a_1^T x \leq b_1, a_2^T x \leq b_2\}$   
 What happens  $b_1 = b_2 = 0$ ?

- A wedge is an intersection of 2 halfspaces  $\Rightarrow$  convex.



- $b_1 = b_2 = 0 \Rightarrow$  cone  
 That the intersection is at the origin.

4) Voronoi

$$\{x \in \mathbb{R}^n \mid \|x - x_0\|_2 \leq \|x - x_i\|_2, i=1 \dots k\} \quad (1)$$

$x_0, \dots, x_k \in \mathbb{R}^n$  closer to  $x_0$  than

$x_1, \dots, x_k$

a) At (b) we showed it can be a Polyhedron, which is convex by definition.

b) Rewrite in the form of  $\{x \mid Ax \leq b\}$

Rule:  $\|x\|_2 = \sqrt{x^T x}$

$$\|x - x_0\|_2 \leq \|x - x_i\|_2$$

$$\Leftrightarrow \sqrt{(x - x_0)^T (x - x_0)} \leq \sqrt{(x - x_i)^T (x - x_i)}$$

$$\Leftrightarrow (x - x_0)^T (x - x_0) \leq (x - x_i)^T (x - x_i)$$

anförmig & linear

$$\Leftrightarrow x^T x - x_0^T x_0 - x_0^T x + x^T x_0 \leq x^T x - x_i^T x_i - x_i^T x + x_i^T x_i$$

$$\Leftrightarrow -2x^T x_0 + x_0^T x_0 \leq -2x^T x_i + x_i^T x_i$$

$$\Leftrightarrow -2x^T x_0 + 2x^T x_i \leq x_i^T x_i - x_0^T x_0$$

$$\Leftrightarrow 2x^T (x_i - x_0) \leq \underbrace{x_i^T x_i}_{b} - \underbrace{x_0^T x_0}_{A}$$

$$A = 2$$

$$\begin{bmatrix} x_1 - x_0 \\ x_2 - x_0 \\ \vdots \\ x_k - x_0 \end{bmatrix}$$

$$b = \begin{bmatrix} x_1^T x_1 - x_0^T x_0 \\ x_2^T x_2 - x_0^T x_0 \\ \vdots \\ x_k^T x_k - x_0^T x_0 \end{bmatrix}$$

c) Case:  $b_i = 1$ . Set of all points closer to  $x_0$  than to  $x_1$  is a halfspace,  $x_0 \neq x_1$

halfspace:  $\{x \mid a^T x \leq b\}$

$$\mathbb{R}^{B_{X_0}} \quad \mathbb{R}^n \quad \mathbb{R}^k$$

$$\begin{array}{c} \text{A matrix } A \in \mathbb{R}^{n \times k} \\ \text{A vector } x \in \mathbb{R}^n \\ \text{A vector } b \in \mathbb{R}^k \end{array} \quad \begin{array}{c} n \\ \downarrow \\ \begin{matrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \end{matrix} \end{array} \quad \begin{array}{c} n \\ \downarrow \\ \begin{matrix} x_1 \\ x_2 \end{matrix} \end{array} \quad \begin{array}{c} k \\ \downarrow \\ \begin{matrix} b_1 \\ b_2 \\ b_3 \end{matrix} \end{array}$$

Any point  $x_0 \in A x \leq b$  we can choose  
the mirror image of  $x_0$  w.r.t.  $x_i = x_0 + \lambda a_i$   
*Geradengleichung*

$\lambda$  must be chosen, so that  
the distance of  $x_i$  to the hyperplane  
fulfills:  $a_i^T x = b_i \Leftrightarrow$  distance of  $x_0$  to the hyperplane

$$b_i - a_i^T x_0 = a_i^T x_i - b_i$$

$$b_i - a_i^T x_0 = a_i^T (x_0 + \lambda a_i) - b_i$$

$$b_i - a_i^T x_0 = a_i^T x_0 + a_i^T \lambda a_i - b_i$$

$$2b_i - 2a_i^T x_0 = a_i^T x_0 + a_i^T \lambda a_i$$

$$2(b_i - a_i^T x_0) = a_i^T a_i \lambda$$

$$\lambda = \frac{2(b_i - a_i^T x_0)}{\|a_i\|_2^2}$$

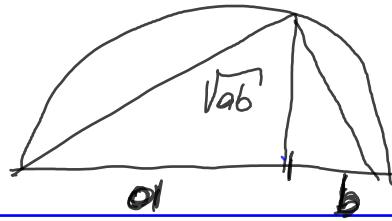
Set  $\lambda$  in the beginning term:

$$x_i = x_0 + \frac{2(b_i - a_i^T x_0)}{\|a_i\|_2^2} a_i$$

# Convex functions

1) Proof by concavity of geometric mean

Properties :- geometric mean  $\leq$  arithmetic mean  
ratio



Prove: 2nd derivative of  $f(x)'' > 0$

Version  $\nabla^2 f(x)$  is given:

$$\frac{\partial}{\partial x_k} \left( \prod_{i=1}^k x_i \right)^{\frac{1}{k}} = \frac{1}{k} \left( \frac{1}{k} - 1 \right) \left( \prod_{i=1}^k x_i \right)^{\frac{1}{k}-2} \cdot \left( \prod_{\substack{i=1 \\ i \neq k}}^k x_i \right)^2$$

$$= \frac{1}{k^2} (1-k) \left( \prod_{i=1}^k x_i \right)^{\frac{1}{k}} \cdot \frac{1}{x_k}$$

$$\frac{\partial}{\partial x_k} = \frac{1}{k} \left( \prod_{i=1}^k x_i \right)^{\frac{1}{k}} \cdot \frac{1}{x_k}$$

$$\frac{\partial}{\partial x_l \partial x_k} = \frac{1}{k^2} \left( \prod_{i=1}^k x_i \right)^{\frac{1}{k}} \cdot \frac{1}{x_l x_k}$$

$$H = \begin{bmatrix} \frac{\partial^2}{\partial x_k^2} & \frac{\partial^2}{\partial x_k \partial x_e} \\ \frac{\partial^2}{\partial x_e \partial x_k} & \frac{\partial^2}{\partial x_e^2} \end{bmatrix} \Rightarrow \omega^T \nabla^2 f(x) \omega \leq 0$$

$$H = -\frac{\prod_{i=1}^k x_i^{\frac{1}{k}}}{k^2} \cdot \left( n \cdot \begin{bmatrix} \frac{1}{x_1^{\frac{1}{k}}} & \frac{1}{x_1^{\frac{1}{k}}} & \dots & \frac{1}{x_1^{\frac{1}{k}}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{1}{x_n^{\frac{1}{k}}} & \frac{1}{x_n^{\frac{1}{k}}} & \dots & \frac{1}{x_n^{\frac{1}{k}}} \end{bmatrix} - \begin{bmatrix} 1 & 1 & \dots & 1 \\ x_1 & x_2 & \dots & x_k \end{bmatrix} \begin{bmatrix} 1 & 1 & \dots & 1 \\ x_1^2 & x_2^2 & \dots & x_k^2 \end{bmatrix}^{-1} \right)$$

To show that, we use  $\omega^T H \omega \leq 0$ ,  $H \omega$ .

$$\nabla^T H \phi = -\frac{\nabla \times_i}{B^2} \left( n \sum_{i=1}^n \left( \frac{(\phi_i)^2}{x_i} \right) - \left( \sum_{i=1}^n 1 \cdot \frac{\phi_i}{x_i} \right)^2 \right) \leq 0$$

Hölder's Inequality:  $\left( \sum_{k=1}^n a_k b_k \right)^2 \leq \left( \sum_{k=1}^n a_k^2 \right) \left( \sum_{k=1}^n b_k^2 \right)$

$$a = 1$$

$$b = \frac{\phi}{x}$$

$\Rightarrow$  This  $f(x)$  is concave.

2)  $f: \mathbb{R}^n \rightarrow [-\infty, +\infty]$ . Note:  $\mathbb{R}$  is usually exclusive "∞" by definition.  
 $f(x)$  is convex.

$$g(x) = y f\left(\frac{x}{y}\right) \quad x \in \mathbb{R}^n, y \in \mathbb{R}_{++}$$

Perspective of a function  $P: \mathbb{R}^{n+1} \rightarrow \mathbb{R}^n$ , with domain  $\mathbb{R}_{++}$  as  $P(z, t) = z/t$ .

It scales or normalizes vectors so the last component is one, and removes the last component.  
e.g.: Pinhole Camera from 3D to 2D.

The domain is a convex set for  $(x, t), (y, s) \in \text{dom } g$ , and  $\theta \in [0, 1]$ , then

$$g(\theta x + (1-\theta)y, \theta t + (1-\theta)s) \leq \theta g(x, t) + (1-\theta)g(y, s).$$

Proof via epi:

For  $t > 0$ : we have

$$(x, t, s) \in \text{epi } g \iff t f(x/t) \leq s \quad \text{if } t$$

$$\iff f(x/t) \leq s/t$$

$$\iff (x/t, s/t) \in \text{epi } f$$

$\text{epi } g$  is the inverse mapping of  $\text{epi } f$

The  $\text{epi } g$  is convex, so the function  $g$  is convex.

Example

$f(x) = x^T x$  on  $\mathbb{R}^n$ , convex in  $(x, t)$  for  $t > 0$ .

$$g(x, t) = t (x/t)^T (x/t) = \frac{x^T x}{t} \quad (\text{is convex for } t > 0)$$

↳ much lower, little  $\triangleright$ .

Proof via Jensen's inequality:

Suppose  $\frac{x}{t} > 0$ ,  $\frac{x}{t} \in \text{dom } f$ ,  $\frac{y}{s} \in \text{dom } f$ :

$$\begin{aligned} q(\theta x + (1-\theta)y, \theta t + (1-\theta)s) \\ = (\theta t + (1-\theta)s) f\left(\frac{(\theta x + (1-\theta)y)}{\theta t + (1-\theta)s}\right) \\ = (\theta t + (1-\theta)s) f\left(\frac{\theta t\left(\frac{x}{t}\right) + (1-\theta)s\left(\frac{y}{s}\right)}{\theta t + (1-\theta)s}\right) \\ \leq \theta t f\left(\frac{x}{t}\right) + (1-\theta)s f\left(\frac{y}{s}\right) \quad \blacksquare \end{aligned}$$

We showed that  $(x, t), (y, s) \in \text{dom } g$  and  
g is convex set.

3) a)  $f(x) = \log(x)$  for  $x \in \mathbb{R}_{++}$

Proof: 2nd derivative must be  $> 0$ .  $\rightarrow$  convex

$$f'(x) = \frac{1}{x} = x^{-1}$$

$$f''(x) = -1 \cdot x^{-2} = -x^{-2} = -\frac{1}{x^2} \dots \text{is negative}$$

for all  $x \in \mathbb{R}_{++} \rightarrow$  convex

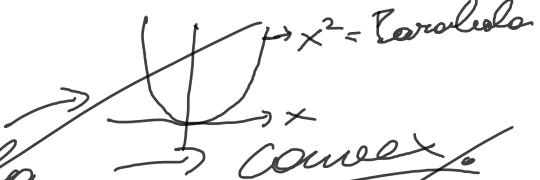
b)  $f(x) = |\alpha|x| - x|^2$  for  $\alpha, x \in \mathbb{R}$

$$f(x) = \begin{cases} |\alpha x - x|^2 \Rightarrow |x(\alpha - 1)|^2 \Rightarrow x^2(\alpha - 1)^2 & x > 0 \\ |\alpha x - x|^2 \Rightarrow |x(-\alpha - 1)|^2 \Rightarrow x^2(-\alpha - 1)^2 & x < 0 \\ 0 & \text{else} \end{cases}$$

$$f'(x) = \begin{cases} 2x(\alpha - 1) & x < 0 \\ 2x(-\alpha - 1) & x > 0 \end{cases}$$

$$f''(x) = \begin{cases} 2(\alpha - 1)^2 & x < 0 \\ 2(-\alpha - 1)^2 & x > 0 \\ 0 & x = 0 \end{cases}$$

$\left. \begin{array}{l} \text{is convex, because } f''(x) \\ \text{is always } \geq 0. \end{array} \right\}$



Case  $\alpha \in \mathbb{R} \setminus \{-1, 1\}$ :

Both cases are Parabola  $\rightarrow$  convex.

Case  $\alpha \in \{-1, 1\}$ :

One part is 0 and the other part is a parabola.  $\rightarrow f$  is convex.

c)  $f(x_1, x_2, x_3) = -e^{-(x_1 + x_2 - 2x_3)^2}$  for  $x \in \mathbb{R}^3$

Proof:  $\nabla^2 f = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \frac{\partial^2 f}{\partial x_1 \partial x_3} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \frac{\partial^2 f}{\partial x_2 \partial x_3} \\ \frac{\partial^2 f}{\partial x_3 \partial x_1} & \frac{\partial^2 f}{\partial x_3 \partial x_2} & \frac{\partial^2 f}{\partial x_3^2} \end{bmatrix} \geq 0$  to be convex.  $\nabla$

$$\frac{\partial f(x)}{\partial x} = \begin{bmatrix} \frac{\partial f(x)}{\partial x_1} \\ \frac{\partial f(x)}{\partial x_2} \\ \frac{\partial f(x)}{\partial x_3} \end{bmatrix} = \begin{bmatrix} 2(-x_1 + x_2 - 2x_3) \cdot e^{(-x_1 + x_2 - 2x_3)^2} \\ -2(-x_1 + x_2 - 2x_3) \cdot e^{(-x_1 + x_2 - 2x_3)^2} \\ 4(-x_1 + x_2 - 2x_3) \cdot e^{(-x_1 + x_2 - 2x_3)^2} \end{bmatrix}$$

$$f(x_1, x_2, x_3) = -e^{\underbrace{(-x_1 + x_2 - 2x_3)^2}_{\vartheta}} \quad || \quad \vartheta = -x_1 + x_2 - 2x_3$$

Auxiliary calculation (AC):

$$\begin{aligned} \frac{\partial}{\partial x_1} (-e^{\vartheta^2}) &= \frac{\partial}{\partial x_1} \vartheta^2 \cdot (-e^{\vartheta^2}) = -2\vartheta(1)e^{\vartheta^2} = \underline{\underline{2\vartheta e^{\vartheta^2}}} \\ \frac{\partial}{\partial x_2} (-e^{\vartheta^2}) &= = -2\vartheta(1)e^{\vartheta^2} = \underline{\underline{-2\vartheta e^{\vartheta^2}}} \\ \frac{\partial}{\partial x_3} (-e^{\vartheta^2}) &= = -2\vartheta(-2)e^{\vartheta^2} = \underline{\underline{4\vartheta e^{\vartheta^2}}} \end{aligned}$$

$$\frac{\partial^2 f(x)}{\partial x^2} = H =$$

$$\begin{bmatrix} \frac{\partial^2 f(x)}{\partial x_1^2} & \frac{\partial^2 f(x)}{\partial x_1 \partial x_2} & \frac{\partial^2 f(x)}{\partial x_1 \partial x_3} \\ \frac{\partial^2 f(x)}{\partial x_2 \partial x_1} & \frac{\partial^2 f(x)}{\partial x_2^2} & \frac{\partial^2 f(x)}{\partial x_2 \partial x_3} \\ \frac{\partial^2 f(x)}{\partial x_3 \partial x_1} & \frac{\partial^2 f(x)}{\partial x_3 \partial x_2} & \frac{\partial^2 f(x)}{\partial x_3^2} \end{bmatrix} \quad \text{Hessian is symmetric!}$$

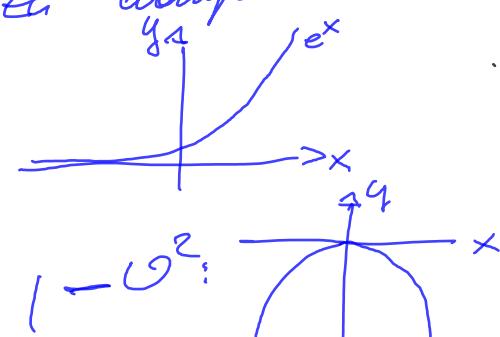
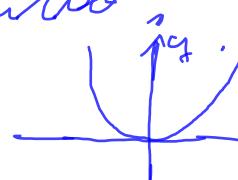
AC:

$$\begin{aligned} \frac{\partial^2 f(x)}{\partial x_1^2} &= 2 \cdot (-1) \cdot e^{\vartheta^2} + 2\vartheta \cdot (2\vartheta(-1)) \cdot e^{\vartheta^2} = -2e^{\vartheta^2} - 4\vartheta^2 e^{\vartheta^2} \\ \frac{\partial^2 f(x)}{\partial x_1 \partial x_2} &= 2 \cdot (1) \cdot e^{\vartheta^2} + 2\vartheta \cdot (2\vartheta \cdot 1 e^{\vartheta^2}) = 2e^{\vartheta^2} + 4\vartheta^2 e^{\vartheta^2} \\ \frac{\partial^2 f(x)}{\partial x_1 \partial x_3} &= 2(-2) \cdot e^{\vartheta^2} + 2\vartheta \cdot (2\vartheta \cdot (-2) \cdot e^{\vartheta^2}) = -4e^{\vartheta^2} - 8\vartheta^2 e^{\vartheta^2} \\ \frac{\partial^2 f(x)}{\partial x_3 \partial x_3} &= 6 \cdot (-2) e^{\vartheta^2} + 4\vartheta (2\vartheta(-2) \cdot e^{\vartheta^2}) = -8e^{\vartheta^2} - 16\vartheta^2 e^{\vartheta^2} \end{aligned}$$

Man könnte Min/Max berechnen indem man  $f'(x) = 0$  setzt und nach x auflöst  $\Rightarrow$  viel zu kompliziert.  
Besser: grafisch!

$e^{\vartheta^2}$  is always positive

$\vartheta^2$  is a parabola:



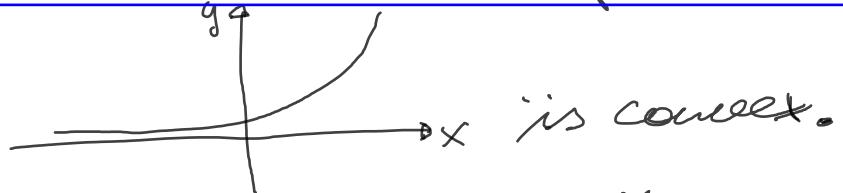
Result:

$$H = \begin{bmatrix} - & + & - \\ - & + & \\ - & - & \end{bmatrix}$$

Concave! because note all entries are convex!  
 Notation: + convex, - concave

d)  $f(x) = \ln(e^{x_1} + e^{x_2} + \dots + e^{x_n})$  for  $x \in \mathbb{R}^n$

Def:  $e^x$ :



Rule:  $C_1 + C_2 = C \Rightarrow e^{x_1} + \dots + e^{x_n} = e^x \in C$

Simplify:  $f(x) = \ln(e^x) = x$

- Properties:
- $f(x) = \exp(ax)$  on  $\mathbb{R}$ ,  $a \in \mathbb{R} \Rightarrow$  convex
  - $f(x) = \log(x)$  on  $\mathbb{R}^+$   $\Rightarrow$  concave

Proof by:  $v^T H v \geq 0$   $v \neq 0, v \in \mathbb{R}^n$

$$\frac{\partial f(x)}{\partial x_i} = \frac{e^{x_i}}{\sum_{k=1}^n e^{x_k}} \quad i = 1, \dots, n$$

$$\frac{\partial^2 f(x)}{\partial x_i \partial x_j} = \left\{ \begin{array}{l} \frac{-e^{x_i} e^{x_j}}{\sum_{k=1}^n e^{x_k}} \quad i \neq j \\ -\frac{e^{x_i} e^{x_j}}{\left(\sum_{k=1}^n e^{x_k}\right)^2} + \frac{e^{x_i}}{\sum_{k=1}^n e^{x_k}} \quad i = j \end{array} \right.$$

$$H = \left[ \begin{array}{cccc} \frac{1}{\sum_{k=1}^n e^{x_k}} & & & \\ & \ddots & & \\ & & \frac{1}{\sum_{k=1}^n e^{x_k}} & \\ & & & \ddots \\ & & & & \frac{1}{\sum_{k=1}^n e^{x_k}} \end{array} \right] + \left[ \begin{array}{cccc} & & & \\ & \ddots & & \\ & & \frac{x_1 \dots x_n}{\sum_{k=1}^n e^{x_k}} & \\ & & & \ddots \\ & & & & \frac{x_n}{\sum_{k=1}^n e^{x_k}} \end{array} \right]$$

$$H = \text{diag}(u) - uu^T$$

$$u = \frac{e^{x_i}}{\sum_{j=1}^n e^{x_j}}$$

Now, we have to prove the positive definiteness.

$$v^T H v = \sum_{i=1}^n u_i v_i^2 - (v^T u)^2$$

Cauchy-Schwarz's of  $\downarrow$

$$l_i = \sqrt{u_i} v_i, \quad t_i = \sqrt{u_i} \quad i = 1..n$$

$$(v^T u)^2 = (l^T t)^2 \stackrel{(*)}{\leq} \|s\|^2 \|t\|^2 =$$

$$= \left( \sum_{i=1}^n u_i v_i^2 \right) \left( \sum_{i=1}^n u_i \right) = \sum_{i=1}^n u_i v_i^2$$

$\sum$   
1, because  $\frac{\sum_{i=1}^n e^{x_i}}{\sum_{k=1}^n e^{x_k}} = 1$

□

$H$  is positive semidefinite, since  $v^T H v \geq 0$  and the inequality  $(*)$  holds for every  $v \in \mathbb{R}^n$ . Thus  $f(x)$  is convex.