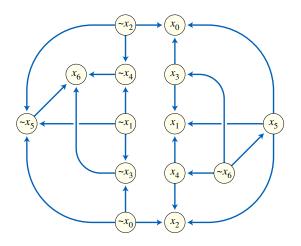
Implication graph



An implication graph representing the 2-satisfiability instance $(x_0 \lor x_2) \land (x_0 \lor \neg x_3) \land (x_1 \lor \neg x_3) \land (x_1 \lor \neg x_4) \land (x_2 \lor \neg x_4) \land (x_0 \lor \neg x_5) \land (x_1 \lor \neg x_5) \land (x_2 \lor \neg x_5) \land (x_3 \lor x_6) \land (x_4 \lor x_6) \land (x_5 \lor x_6).$

In mathematical logic, an **implication graph** is a skew-symmetric directed graph G(V, E) composed of vertex set V and directed edge set E. Each vertex in V represents the truth status of a Boolean literal, and each directed edge from vertex u to vertex v represents the material implication "If the literal u is true then the literal v is also true". Implication graphs were originally used for analyzing complex Boolean expressions.

1 Applications

A 2-satisfiability instance in conjunctive normal form can be transformed into an implication graph by replacing each of its disjunctions by a pair of implications. For example, the statement $(x_0 \vee x_1)$ can be rewritten as the pair $(\neg x_0 \to x_1), (\neg x_1 \to x_0)$. An instance is satisfiable if and only if no literal and its negation belong to the same strongly connected component of its implication graph; this characterization can be used to solve 2-satisfiability instances in linear time. [1]

In CDCL SAT-solvers, unit propagation can be naturally associated with an implication graph that captures all possible ways of deriving all implied literals from decision literals, [2] which is then used for clause learning.

2 References

[1] Aspvall, Bengt; Plass, Michael F.; Tarjan, Robert E. (1979). "A linear-time algorithm for testing the truth of

- certain quantified boolean formulas". *Information Processing Letters*. **8** (3): 121–123. doi:10.1016/0020-0190(79)90002-4.
- [2] Paul Beame; Henry Kautz; Ashish Sabharwal (2003). Understanding the Power of Clause Learning (PDF). IJ-CAI. pp. 1194–1201.

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3.1 Text

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