Decompositions of Graphs

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June 12, 2018



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John Hopcroft



Robert Tarjan



John Hopcroft



Robert Tarjan

"For fundamental achievements in the design and analysis of algorithms and data structures."

— Turing Award, 1986

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SIAM J. COMPUT. Vol. 1, No. 2, June 1972

DEPTH-FIRST SEARCH AND LINEAR GRAPH ALGORITHMS*

ROBERT TARJAN†

Abstract. The value of depth-first search or "backtracking" as a technique for solving problems is illustrated by two examples. An improved version of an algorithm for finding the strongly connected components of a directed graph and an algorithm for finding the biconnected components of an undirect graph are presented. The space and time requirements of both algorithms are bounded by $k_1V + k_2E + k_3$ for some constants k_1, k_2 , and k_3 , where V is the number of vertices and E is the number of edges of the graph being examined.

Key words. Algorithm, backtracking, biconnectivity, connectivity, depth-first, graph, search, spanning tree, strong-connectivity.

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"DFS is a powerful technique with many applications."

▶ "Depth-First Search And Linear Graph Algorithms" by Robert Tarjan.

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Power of DFS:

Graph Traversal \implies Graph Decomposition

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Power of DFS:

Graph Traversal ⇒ Graph Decomposition

Structure! Structure! Structure!



Graph structure induced by DFS:

states of v

types of \overbrace{u} v

Graph structure induced by DFS:

states of v

types of \underbrace{u} \underbrace{v}

life time of v:

 $v:\mathsf{d}[v],\mathsf{f}[v]$

f[v]: DAG, SCC

d[v]: biconnectivity

Definition (Classifying edges)

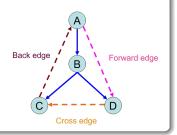
Given a DFS traversal \implies DFS tree:

Tree edge: \rightarrow child

Back edge: \rightarrow ancestor

Forward edge: → *nonchild* descendant

Cross edge: \rightarrow (\neg ancestor) \land (\neg descendant)



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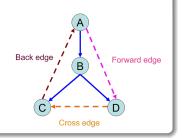
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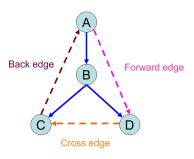
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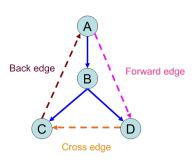
Cross edge: \rightarrow (¬ancestor) \land (¬descendant)



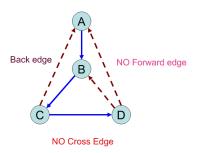
- also applicable to BFS
- w.r.t. DFS/BFS trees



DFS on directed graph

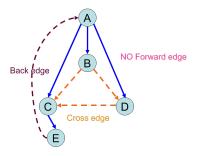


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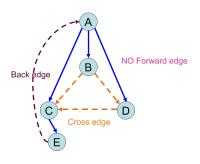


DFS on undirected graph

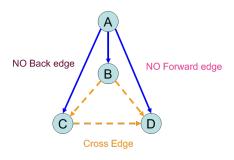
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BFS on directed graph



BFS on directed graph



BFS on undirected graph

Undirected connected graph $G = (V, E), v \in V$

DFS tree T from $v \equiv BFS$ tree T' from v

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Proof.

$$G_{\mathsf{DFS}}$$
: tree + back vs. G_{BFS} : tree + cross



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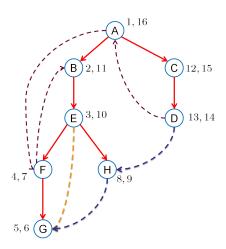
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Q: What if G is a digraph?



Lift time of vertices in DFS



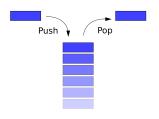
Theorem (Disjoint or Contained (Problem 4.2: (1) & (2)))

$$\forall u,v: [_u\]_u\cap [_v\]_v=\emptyset\bigvee\left([_u\]_u\subsetneqq [_v\]_v\vee [_v\]_v\subsetneqq [_u\]_u\right)$$

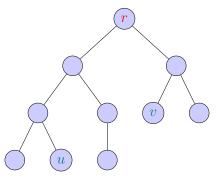
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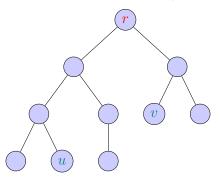


Preprocessing for ancestor/descendant relation (Problem 5.23)



Q: Is u an ancestor of v? O(1)

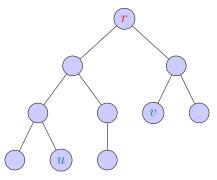
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 $v: \mathsf{d}[v], \mathsf{f}[v]$

Q: # of descendants of any v?

$$\forall u \rightarrow v$$
:

- ▶ tree/forward edge: $\begin{bmatrix} u & v \end{bmatrix}_v$
- ▶ back edge: $\begin{bmatrix} v & u \end{bmatrix} u \end{bmatrix} v$
- ightharpoonup cross edge: $\begin{bmatrix} v \end{bmatrix}_v \begin{bmatrix} u \end{bmatrix}_u$

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$$\mathsf{f}[v] < \mathsf{d}[u] \iff \qquad \mathsf{edge}$$

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$$\nexists \mathsf{ cycle } \implies \boxed{u \to v \iff \mathsf{ f}[v] < \mathsf{ f}[u]}$$



- $\blacktriangleright \ \operatorname{height} \ H(T) \ \operatorname{in} \ O(n)$
- ▶ diameter D(T) in O(n)

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$$\begin{cases} H(T) = \max(H(L_T), H(R_T)) + 1, \end{cases}$$

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Binary tree T=(V,E) with $\lvert V \rvert = n$ and the root r

Binary tree T = (V, E) with |V| = n and the root r

Q: Diameter of a $\it tree \ without$ a designated root

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Your Job: Prove it!

Counting shortest paths (Problem 5.26)

Counting # of shortest paths in (un)directed graphs using BFS.

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Counting # of shortest paths in (un)directed graphs using BFS.

Maybe in the next class...

	Digraph	Undirected graph
DFS		
BFS		

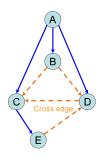
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DFS	back edge \iff cycle	
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	cycle → back edge	cross edge \longleftrightarrow cycle

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$$\mathsf{Evasiveness} \ \triangleq \ \mathsf{check} \ \binom{n}{2} \ \mathsf{edges} \ (\mathsf{adjacency} \ \mathsf{matrix})$$

Evasiveness
$$\triangleq$$
 check $\binom{n}{2}$ edges (adjacency matrix)

Q: Is acyclicity evasive?

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By Adversary Argument.



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Adversary A:







Algorithm \mathbb{A} :

CHECKEDGE(u, v)

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Algorithm A:

CHECKEDGE(u, v)

Hint: Kruskal

←□ → ←□ → ←□ → □ → ○ へ ○ □ → ←□ → ←□ → ←□ → □ → □ → ○





$$\begin{array}{c} \text{CheckEdge}(u,v) \leftarrow \overbrace{u} \\ \Longleftrightarrow \\ \\ & \\ \end{array} \\ \begin{array}{c} \text{cycle} \ \in G + \overbrace{u} \\ \end{array} \\ \end{array}$$

 $Q: \mathsf{Why} \ \mathsf{adjacency} \ \mathsf{matrix}?$



After-class Exercise: Evasiveness of connectivity of undirected graphs

Evasiveness
$$\triangleq$$
 check $\binom{n}{2}$ edges (adjacency matrix)

Q: Is connectivity evasive?

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Hint: Anti-Kruskal

- ightharpoonup undirected (connected) graph G
- ▶ edges oriented *s.t.*

$$\forall v, \mathsf{in}[v] \geq 1$$

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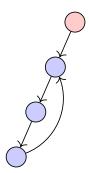
DFS from
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DFS from $v \in C$



Shortest cycle of undirected graph (Problem 4.12)

A WRONG DFS-based algorithm:

$$\forall v : \mathsf{level}[v]$$

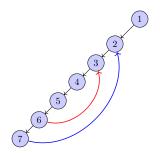
Back edge
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Shortest cycle of digraph (Problem 4.12)

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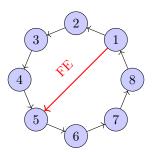
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 $\frac{1}{2} \text{ back edge} \iff \text{DAG} \iff \exists \text{ topo. ordering}$

$$\nexists$$
 back edge \iff DAG \iff \exists topo. ordering

TOPOSORT by Tarjan (probably), 1976

$$\sharp \operatorname{cycle} \implies \boxed{u \to v \iff \operatorname{f}[v] < \operatorname{f}[u]}$$

$$\frac{1}{2} \text{ back edge} \iff \text{DAG} \iff \exists \text{ topo. ordering}$$

TOPOSORT by Tarjan (probably), 1976

Sort vertices in *decreasing* order of their *finish* times.

Kahn's TOPOSORT algorithm (1962; Problem 4.16)

- ▶ Queue Q for source vertices (in[v] = 0)
- ▶ Repeat: DEQUEUE $(u \in Q)$, delete u and $u \to v$ from Q, output u, ENQUEUE(v) if $\ln[v] = 0$

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Lemma (Correctness of Kahn's TOPOSORT)

Every DAG has at least one source (and at least one sink vertex).

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Lemma (Correctness of Kahn's TOPOSORT)

Every DAG has at least one source (and at least one sink vertex).

Q: What if G is not a DAG?

Taking courses in few semesters (Problem 5.14)

- ightharpoonup n courses
- ▶ m of $c_1 \rightarrow c_2$: prerequisite
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Critical path *OR* Longest path using DFS in O(n+m)

For general digraph, LONGEST-PATH is NP-hard.

Line up (Problem 4.22)

- 1. i hates j: $i \succ j$
- 2. i hates j: #i < #j

Toposort

Critical path

HP: path visiting each vertex once

 $Q: \exists \ \mathsf{HP} \ \mathsf{in} \ \mathsf{a} \ \mathsf{DAG} \ \mathsf{in} \ O(n+m)$

HP: path visiting each vertex once

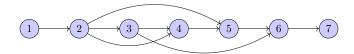
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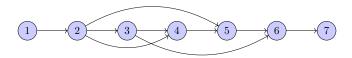
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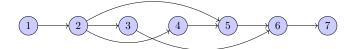
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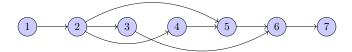
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Tarjan's TOPOSORT + Check edges (v_i, v_{i+1})

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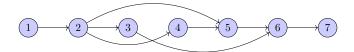


Tarjan's TOPOSORT + Check edges (v_i, v_{i+1})



Kahn's TOPOSORT (Problem 4.16)

Tarjan's TOPOSORT + Check edges (v_i, v_{i+1})



Kahn's TOPOSORT (Problem 4.16)

$$|Q| \leq 1$$

