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- Overview
- 2 1D DP
- 3 2D DP
- 4 DP on Graphs
- 5 The Knapsack Problem

What is DP?

 $\label{eq:DP} DP \approx \text{``brute force''} \\ DP \approx \text{``smart scheduling of subproblems''} \\ DP \approx \text{``shortest/longest paths in some DAG''}$

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$$\label{eq:defDP} \begin{split} \mathsf{DP} \approx \text{``smarter brute force''} \\ \mathsf{DP} \approx \text{``smart scheduling of subproblems''} \\ \mathsf{DP} \approx \text{``shortest/longest paths in some DAG''} \end{split}$$

What is not DP?

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Programming \neq Coding (Richard Bellman, 1940s)

Steps for applying DP

- 1. Define subproblems
 - # of subproblems
- 2. Set the goal
- 3. Define the recurrence
 - ▶ larger subproblem ← # smaller subproblems
 - init. conditions
- 4. Write pseudo-code: fill "table" in topo. order
- 5. Analyze Time/Space complexity
- 6. Extract the optimal sulution



1D subproblems:

```
Input: x_1, x_2, \ldots, x_n (array, sequence, string) Subproblems: x_1, x_2, \ldots, x_i (prefix/suffix) #: \Theta(n)
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 $\#: \Theta(n)$

Examples: Fib, Maximum-sum subarray, Longest increasing subsequence, Highway restaurants, Text justification

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2D subproblems:

```
1. Input: x_1, x_2, ..., x_m; y_1, y_2, ..., y_n
Subproblems: x_1, x_2, ..., x_i; y_1, y_2, ..., y_j
#: \Theta(mn)
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Examples: Edit distance, Longest common subsequence

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2. Input: x_1, x_2, \dots, x_n
Subproblems: x_i, \dots, x_j
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Examples: Edit distance, Longest common subsequence

```
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```

Examples: Matrix chain multiplication, Optimal BST

3D subproblems:

► Floyd-Warshall algorithm

$$\mathsf{d}(i,j,k) = \min \{ \mathsf{d}(i,j,k-1), \mathsf{d}(i,k,k-1) + \mathsf{d}(k,j,k-1) \}$$

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DP on graphs:

1. On rooted tree

Subproblems: rooted subtrees

2. On DAG

Subproblems: nodes after/before in the topo. order

3D subproblems:

Floyd-Warshall algorithm

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DP on graphs:

1. On rooted tree

Subproblems: rooted subtrees

2. On DAG

Subproblems: nodes after/before in the topo. order

Knapsack problem:

Subset sum problem, change-making problem



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And Others . . .



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