Decompositions of Graphs

(DFS/BFS, DAG, SCC, Bicomp)

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June 12, 2019



John Hopcroft



Robert Tarjan

"For fundamental achievements in the design and analysis of algorithms and data structures."

— Turing Award, 1986

SIAM J. COMPUT. Vol. 1, No. 2, June 1972

DEPTH-FIRST SEARCH AND LINEAR GRAPH ALGORITHMS*

ROBERT TARJAN†

Abstract. The value of depth-first search or "backtracking" as a technique for solving problems is illustrated by two examples. An improved version of an algorithm for finding the strongly connected components of a directed graph and an algorithm for finding the biconnected components of an undirect graph are presented. The space and time requirements of both algorithms are bounded by $k_1V + k_2E + k_3$ for some constants k_1, k_2 , and k_3 , where V is the number of vertices and E is the number of edges of the graph being examined.

Key words. Algorithm, backtracking, biconnectivity, connectivity, depth-first, graph, search, spanning tree, strong-connectivity.

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"DFS is a powerful technique with many applications."

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Power of DFS:

Graph Traversal \implies Graph Decomposition

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Structure! Structure! Structure!



Graph *structure* induced by DFS:

states of v

types of u v

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types of \underbrace{u} \underbrace{v}

life time of $\stackrel{(v)}{\smile}$:

v : d[v], f[v]

d[v]: BICOMP

f[v]: Toposort, SCC

Definition (Classifying edges)

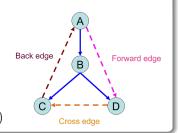
Given a DFS traversal \implies DFS tree:

Tree edge: \rightarrow child

Back edge: \rightarrow ancestor

Forward edge: $\rightarrow nonchild$ descendant

Cross edge: \rightarrow (\neg ancestor) \land (\neg descendant)



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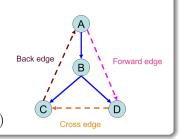
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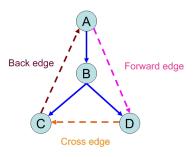
Back edge: \rightarrow ancestor

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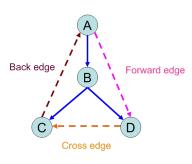
Cross edge: \rightarrow (\neg ancestor) \land (\neg descendant)



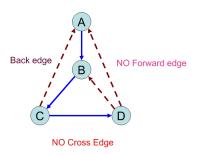
Also applicable to BFS



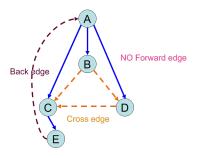
DFS on directed graph



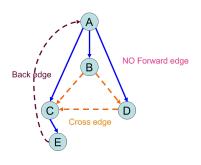
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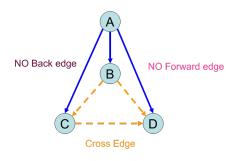
DFS on undirected graph



BFS on directed graph



BFS on directed graph



BFS on undirected graph

Coloring

Coloring

 $\xrightarrow{\text{Tree Edge}} v$

Coloring



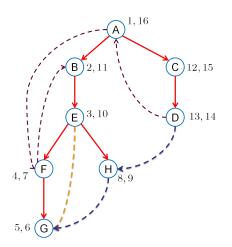
Coloring



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Life time of vertices in DFS



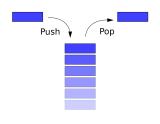
Theorem (Disjoint or Contained (Problem 4.2:(1)&(2)))

$$\forall u,v: [_{u}\]_{u}\cap [_{v}\]_{v}=\emptyset\bigvee\left([_{u}\]_{u}\subset [_{v}\]_{v}\vee [_{v}\]_{v}\subset [_{u}\]_{u}\right)$$

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Proof.



$$\forall u \rightarrow v$$
:

- tree/forward edge: $[u \ [v \]v \]u$
- ▶ back edge: $[v \ [u \]u \]v$
- ightharpoonup cross edge: $\begin{bmatrix} v \end{bmatrix}_v \begin{bmatrix} u \end{bmatrix}_u$

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$$\sharp \text{ cycle } \Longrightarrow \left| u \to v \iff f[v] < f[u] \right|$$



	Digraph	Undirected graph
DFS		
BFS		

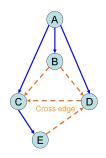
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DIS	$cycle \implies back edge$	cross edge \rightarrow cycle



Evasiveness of acyclicity of undirected graphs (Problem 5.8 - 2)

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$$\triangleq$$
 check $\binom{n}{2}$ edges (adjacency matrix)

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Algorithm \mathbb{A} :

CheckEdge(u, v)

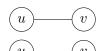
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CHECKEDGE(u, v)

Hint: Kruskal



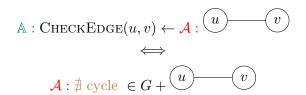


$$\mathbb{A}: \mathsf{CheckEdge}(u,v) \leftarrow \underline{\mathcal{A}}: \underbrace{u} \underbrace{v}$$

$$\Longleftrightarrow$$

$$\underline{\mathcal{A}}: \nexists \; \mathsf{cycle} \; \in G + \underbrace{u} \underbrace{v}$$





Q: Why adjacency matrix?

On digraphs:

 \nexists back edge \iff DAG \iff \exists topo. ordering

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Toposort by Tarjan (probably), 1976

$$\nexists \text{ cycle } \Longrightarrow \boxed{u \to v \iff f[v] < f[u]}$$

Sort vertices in *decreasing* order of their *finish* times.

HP: path visiting each vertex once

 $Q: \exists \text{ HP in a DAG in } O(n+m)$

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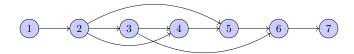
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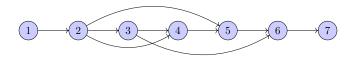
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DAG: \exists HP \iff \exists ! topo. ordering

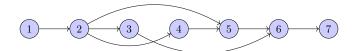
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Tarjan's Toposort + Check edges (v_i, v_{i+1})

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Theorem (Digraph as DAG (Problem 4.6))

Every digraph is a dag of its SCCs.

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Two tiered structure of digraphs:

 $digraph \equiv a dag of SCCs$

SCC: equivalence class over reachability

$$v:v \leadsto^? \forall u$$

$$\exists ? \ v : v \leadsto \forall u$$

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SCC

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 $\exists!$ source vertex $v \iff v \leadsto \forall u$

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SCC

 $\exists!$ source vertex $v \iff v \rightsquigarrow \forall u$

 $\Leftarrow=:\exists!$ source

 \implies : By contradiction.

 $\exists u : v \not \rightsquigarrow u \land \text{in}[u] > 0 \implies \exists \text{ cycle}$

$$\mathrm{impact}(v) = |\{w \neq v : v \leadsto w\}|$$

- ightharpoonup arg min_v impact(v)
- $\blacktriangleright \ \operatorname{arg\,max}_v \operatorname{impact}(v)$

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 $Q: \forall v, \text{ computing impact}(v)$

$$I: (x_1 \vee \overline{x_2}) \wedge (\overline{x_1} \vee \overline{x_3}) \wedge (x_1 \vee x_2) \wedge (\overline{x_3} \vee x_4) \wedge (\overline{x_1} \vee x_4)$$

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$$\alpha \vee \beta \equiv \overline{\alpha} \to \beta \equiv \overline{\beta} \to \alpha$$

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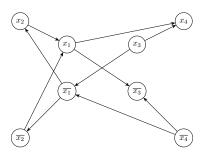
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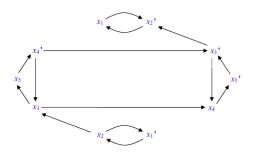
Implication graph G_I .

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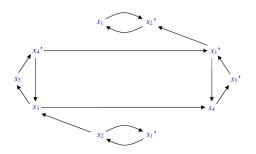
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Theorem (2SAT)

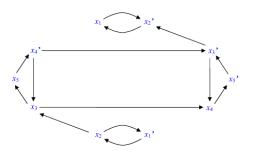
 $\exists \ SCC \ \exists x : v_x \in SCC \land v_{\overline{x}} \in SCC \iff I \ is \ not \ satisfiable.$



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"A Linear-time Algorithm for Testing the Truth of Certain Quantified Boolean Formulas", Bengt Aspvall, Michael Plass, Robert Tarjan, 1979





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