

$$\dot{\underline{x}} = \underline{A} \underline{x} + \underline{B} u$$

$$\underline{y} = \underline{C} \underline{x} + d u$$

$$\underline{A} = \begin{bmatrix} -6 & -5 \\ 1 & 0 \end{bmatrix} \quad \underline{B} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\underline{y} = \begin{bmatrix} 3 & 1 \end{bmatrix}$$

Controllability

$$\underline{B} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \underline{A} = \begin{bmatrix} -6 & -5 \\ 1 & 0 \end{bmatrix}$$

$$\underline{A} \underline{B} = \begin{bmatrix} -6 & -5 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} -6 \\ 1 \end{bmatrix}$$

$$CM = \begin{bmatrix} 1 & -6 \\ 0 & 1 \end{bmatrix} \quad \left[\underline{B} \mid \underline{A} \underline{B} \right]$$

$$\det \begin{bmatrix} 1 & -6 \\ 0 & 1 \end{bmatrix} \neq 0$$

$$1 - (-6 \times 0) = \underline{\underline{1}}$$

Observability

$$C^T = \begin{bmatrix} 3 \\ 1 \end{bmatrix} \quad A^T C^T = \begin{bmatrix} -6 & 1 \\ -5 & 0 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} -17 \\ -15 \end{bmatrix}$$

$$OM = \begin{bmatrix} 3 & -17 \\ 1 & -15 \end{bmatrix}$$

$$\det(OM) = -28 \neq 0$$

Use diagonalization to
confirm result.