# bootfs - Bootstrapped feature selection

Christian Bender \*

November 27, 2012

This document describes the package 'bootfs' for robust feature selection in classification problems from high-throughput data, such as genomic or proteomic screening data. Several methods for classification are combined, in order to derive a robust estimation of the importance of each feature used for classification.

## 1 Using bootfs

This section contains the basic steps for analysis of high-throughput data, consisting of a number of samples to classify (such as patients) and a number of features, such as genes or proteins. Samples originate in two sample groups, for instance healthy versus sick patients. The aim is to find the most important features discriminating the two classes of patients.

The usage of the package is illustrated for three classification algorithms: pamr (Prediction analysis for Microarrays, [3], implementation in pamr-R-package),  $rf_-boruta$  (Random forests with the Boruta algorithm for feature selection, [2], implementation in Boruta-R-package) and scad (Support Vector Machines with Smoothly Clipped Absolute Deviation feature selection, [4], implementation in the penalizedSVM R-package [1]). Also available feature selection methods (through penalizedSVM package) are 1norm for L1-penalisation (LASSO), scad+L2 for Elastic-SCAD and DrHSVM for Elastic Net. First of all load the package:

#### > library(bootfs)

<sup>\*</sup>Translational Oncology (TRON) Mainz, Germany. eMail: christian.bender@tronmainz.de

#### 1.1 Simulating data

Data can be simulated using a built in function simDataSet. This samples a data matrix with nsam samples and ngen genes, as well as a grouping vector defining two sample groups.

```
> set.seed(1234)
> data <- simDataSet(nsam=30, ngen=100, sigma=1.5, plot=TRUE)
> logX <- data$logX
> groupings <- data$groupings</pre>
```

#### 1.2 Assessing performance of the classifiers

The first step is to verify, if the feature selection algorithms perform sufficienctly on the given data set. For this, a crossvalidation of different classification algorithms is run:

The above command uses the classification methods PAMR, SCAD-SVM and RF-Boruta and performs a 5-fold (ncv=5) crossvalidation on the training data, repeating the crossvalidation 2 times with different training/test set assignments. Classification methods and k-fold for the CV can be easily exchanged by setting the appropriate parameters. The results of the crossvalidation are summarised as ROC (Receiver operator characteristic) curves together with the corresponding AUC (area under the curve), shown in figures 1, 2 and 3.

#### 1.3 Do the feature selection and importance ranking

If the performance is of sufficient quality, as seen in the ROC curves generated during the cross-validation, the bootstrapping approach for deriving the most important features for this classification task can be done. Again, we select the three algorithms from above and perform bootstrapping on the input data. For each bootstrapping data set the feature selections are done using each algorithm.

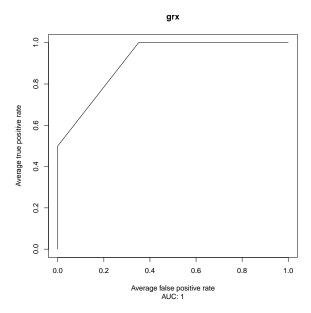


Figure 1: Receiver Operator Characteristic (ROC) curve for the PAM algorithm cross-validation. Input data were the simulated data matrix and grouping vectore for 30 samples and 100 features.

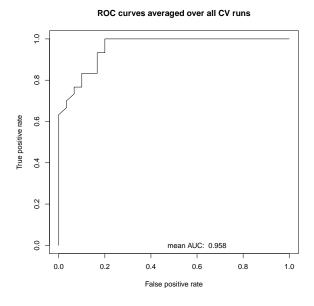


Figure 2: Receiver Operator Characteristic (ROC) curve for the random forest RF-Boruta algorithm cross-validation. Input data were the simulated data matrix and grouping vectore for 30 samples and 100 features.

#### ROC curves averaged over all CV runs

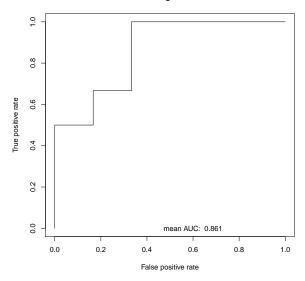


Figure 3: Receiver Operator Characteristic (ROC) curve for the SCAD-SVM algorithm cross-validation. Input data were the simulated data matrix and grouping vectore for 30 samples and 100 features.

Here, 15 bootstrap sample sets are drawn (bstr=15) and feature Selection is done for each sample set. The group proportions are kept constant during the sample selection. Now, for each method, a separate importance graph can be generated:

```
> ## show an importance ranking for a single
> ## classification method
> bsres <- makeIG(retBS[[1]], SUBDIR=NULL, prob=.9)</pre>
```

This might be useful to inspect the selected features for each method separately. The parameter prob=.9 is used to define the cutoff value, how often a feature at least must co-occur with another feature, in which case an edge

is drawn between them. However, the general ranking of the importance of the features is done by generating the combined importance graph from all selected methods:

```
> ## create the combined importance graph for all methods
> ## and export the adjacency matrix containing the
> ## numbers of occuerrences of the features, as well
> ## as the top hits.
> res <- resultBS(retBS, DIR="bs", vlabel.cex = 3, filter = 8, saveres = FALSE)</pre>
```

There are several arguments which customise the look of the importance graph. In this call, the *vlabel.cex* argument defines the magnification factor of the node labels (each node corresponds to one feature). The argument *filter* can be used to specify, how often a feature must co-occur with another, such that an edge is drawn between the two features. Figure 4 shows the result of the above call.

The graph can be customised more flexibly using the *importance\_igraph* function directly:

```
> ## plot the importance graph directly. Gives more
> ## flexibility to adjust the graph
>
> ig <- importance_igraph(res$adj, main = "my test",
+ highlight = NULL, layout="layout.ellipsis",
+ pdf=NULL, pointsize=12, tk=FALSE,
+ node.color="grey", node.filter=NULL,
+ vlabel.cex=2, vlabel.cex.min=0.5, vlabel.cex.max=4,
+ max_node_cex=8,
+ edge.width=2, filter=8, max_edge_cex=4, ewprop=8 )</pre>
```

Figure 5 shows the importance graph generated with the above call. Arguments vlabel.cex, vlabel.cex.min and vlabel.cex.max can be used to adjust the overall, minimum and maximum expansion factor for the node labels. max\_node\_cex controls the maximum expansion factor of the node size. The size of the nodes is always proportional to the absolute occurrence of the feature in the bstr bootstrapping sample sets. edge.width and max\_edge\_cex are used for setting the edge width and expansion factor for the edges, respectively, while ewprop is a proportionality factor controlling the decrease of edge width with decreasing frequency. A higher value of ewprop means a fast reduction of edge width and thus a less densly packed importance graph plot. Also consider the help pages for the respective functions, to learn about the remaining function arguments.

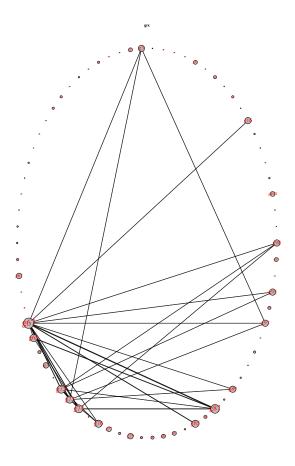


Figure 4: Importance graph generated by *resultBS*. Node width is proportional to the absolute frequency of occurrence of a feature across all bootstrap feature selections. Edge width is proportional to the frequency of co-occurrence of the two adjacent nodes.

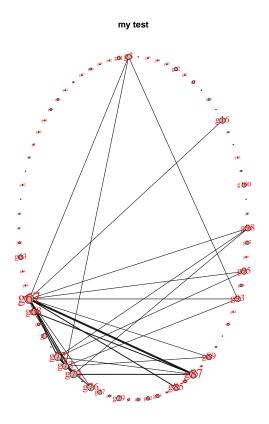


Figure 5: Importance graph generated by call to  $importance\_igraph$  directly. Note how the edge widths are thicker but decreasing more rapidly as in figure 4, achieved by setting  $max\_edge\_cex$  and ewprop appropriately. Besides, the node label sizes are adjusted using vlabel.cex.

### **Session Information**

The version number of R and packages loaded for generating the vignette were:

- R version 2.15.2 Patched (2012-11-26 r61166),
   x86\_64-unknown-linux-gnu
- Locale: LC\_CTYPE=en\_US.UTF-8, LC\_NUMERIC=C,
  LC\_TIME=en\_US.UTF-8, LC\_COLLATE=C, LC\_MONETARY=en\_US.UTF-8,
  LC\_MESSAGES=en\_US.UTF-8, LC\_PAPER=C, LC\_NAME=C, LC\_ADDRESS=C,
  LC\_TELEPHONE=C, LC\_MEASUREMENT=en\_US.UTF-8,
  LC\_IDENTIFICATION=C
- Base packages: base, datasets, grDevices, graphics, methods, stats, utils
- Loaded via a namespace (and not attached): tools 2.15.2

#### References

- [1] Natalia Becker, Grischa Toedt, Peter Lichter, and Axel Benner. Elastic scad as a novel penalization method for svm classification tasks in high-dimensional data. *BMC Bioinformatics*, 12:138, 2011.
- [2] Miron B. Kursa and Witold R. Rudnicki. Feature selection with the boruta package. *Journal of Statistical Software*, 36(11):1–13, 9 2010.
- [3] Robert Tibshirani, Trevor Hastie, Balasubramanian Narasimhan, and Gilbert Chu. Diagnosis of multiple cancer types by shrunken centroids of gene expression. *Proc Natl Acad Sci U S A*, 99(10):6567–6572, May 2002.
- [4] Hao Helen Zhang, Jeongyoun Ahn, Xiaodong Lin, and Cheolwoo Park. Gene selection using support vector machines with non-convex penalty. *Bioinformatics*, 22(1):88–95, Jan 2006. SCAD paper.