## 1 Routings in transformation program

```
input: program, program to be processed; ast, abstact syntax tree of the program
   output: new_program, processed program
1 new_program \leftarrow \emptyset
 2 foreach block \in program do
       \mathsf{new\_block} \leftarrow \emptyset
3
       pointers[] \leftarrow \emptyset
 4
       eval_prog 
— Construct a random evaluation program from the evaluation templates
 5
       block ← Mix_Program(block, eval_prog)
 6
       constant\_pool \leftarrow [All constants in the block]
       CT ← build_constant_trees(constant_pool, pointers[])
 8
       CT_val \leftarrow decode(CT)
 9
       append(new_block, dynamic_build_constant_tree(CT_val))
10
       foreach statement \in block do
11
          if have_constant(statement, ast) then
12
              for each constant \in statement do
13
                  pointer \leftarrow \texttt{locate\_subtree}(pointers[\ ], \ constant)
14
                  substutite(statement, constant, decode(pointer))
15
              end
16
           end
17
           val \leftarrow left value of the statement
18
           append(new_block, statement)
19
           append(new_block, update_graph(CT, val))
20
21
       append(new_program, new_block)
22
23 end
24 return new_program
```

**Algorithm 1**: Overview

Algorithm 2: Locate subtree

```
input : constant_pool, a set of constants used in the block;
             pointers[], a set of pointers used to point to the
             root of the subgraphs representing the constant
   output: CT, the root of the constant tree
 1 CT ← Root of init_tree
 \mathbf{2} for each constant \in constant_pool \mathbf{do}
       subtree\_root \leftarrow build\_const\_tree(constant)
3
       node ← locate_subtree(pointers[], constant)
 4
       if node == NULL then //if cannot find one, construct one
5
          node \leftarrow random\_node(CT)
 6
          merge_tree(node, subtree_root)
 7
       else//if find one, make a duplication in probability
 8
          toss a coin
 9
          if head is up then
10
              node \leftarrow random\_node(CT)
11
              merge_tree(node, subtree_root)
12
13
          end
       end
14
       pointers[].join((node, constant ))
15
16 end
17 return CT
```

Algorithm 3: Build Constant Trees

## 2 Routings in watermarked program

```
input : CT, the root of the constant tree; val, value update refers to
    output: None
 1 node ← find_upgradable_node(CT)
 \mathbf{2} if node == node \rightarrowparent \rightarrowleft \mathbf{then}
        parent\_point \leftarrow \&node \rightarrow parent \rightarrow left
 4 else
        \mathsf{parent\_point} \leftarrow \&\mathsf{node} \rightarrow \!\!\mathsf{parent} \rightarrow \!\!\mathsf{right}
 5
 6 end
 7 if val is odd then //left rotate
        switch rotate case do
 9
             case 1 left_rotate_1()
             case 2 left_rotate_2()
10
             case 3 left_rotate_3()
11
             case 4 left_rotate_4()
12
        end
13
    else
14
        switch rotate case do
15
             case 1 right_rotate_1()
16
17
             case 2 right_rotate_2()
             case 3 right_rotate_3()
18
             case 4 right_rotate_4()
19
20
        end
21 end
22 if CT \rightarrow left \neq CT \rightarrow right then //update the child pointers of the root
        \mathsf{CT} \to \mathsf{right} \leftarrow \mathsf{CT} \to \mathsf{left}
24 end
```

Algorithm 4: UpdateGraph

```
*parent_point \leftarrow node \rightarrowright;

node \rightarrowright \rightarrowparent \leftarrow node \rightarrowparent;

node \rightarrowparent \leftarrow node \rightarrowleft;

node \rightarrowright \leftarrow node \rightarrowparent \rightarrowleft;

node \rightarrowparent \rightarrowleft \rightarrowparent \leftarrow node;

node \rightarrowparent \rightarrowleft \leftarrow node;
```

#### Algorithm 5: Left rotate case 1

```
allocate(new_node);

new_node →left ← node →right →left;

new_node →right ← node →right →right;

node →right →left →parent ← new_node;

node →right →right →parent ← new_node;

node →right →right ← new_node;

node →right →left ← node;

node →right →parent ← node →parent;

*parent_point ← node →right;

node →parent ← node →right;

allocate(another_new_node);

node →right ← another_new_node;

pointers[].update(node →parent, node →parent →right);
```

### Algorithm 6: Left rotate case 2

```
*parent_point ← node →left;

node →left →parent ← node →parent;

node →parent ← node →right;

node →left ← node →parent →right;

node →parent →right →parent ← node;

node →parent →right ← node;
```

**Algorithm 7**: Right rotate case 1

```
allocate(new_node);

new_node →left ← node →right →left;

new_node →right ← node →right →right;

node →right →left →parent ← new_node;

node →right →right →parent ← new_node;

node →right →right ← new_node;

node →right →left ← node;

node →right →parent ← node →parent;

*parent_point ← node →right;

node →parent ← node →right;

allocate(another_new_node);

node →right ← another_new_node;

pointers[].update(node →parent, node →parent →right);
```

**Algorithm 8**: Right rotate case 2

# 3 Routings shared in both parts

Algorithm 9: Build Constant Tree

Algorithm 10: decode

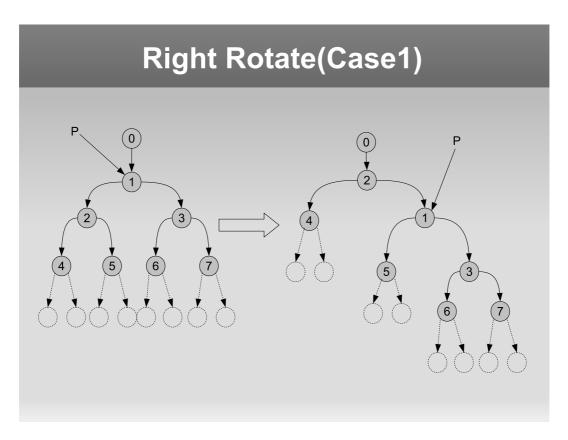


Figure 1: Right Rotate Case 1

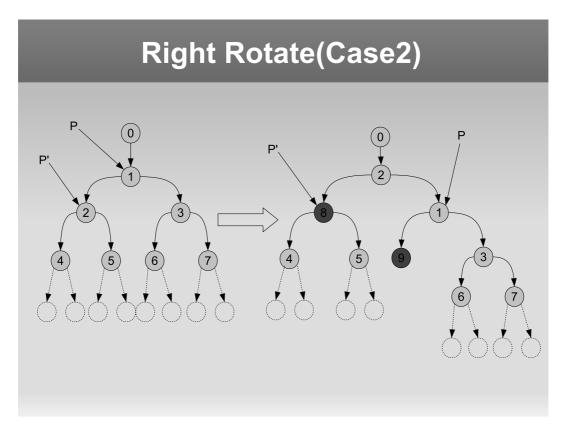


Figure 2: Right Rotate Case 2

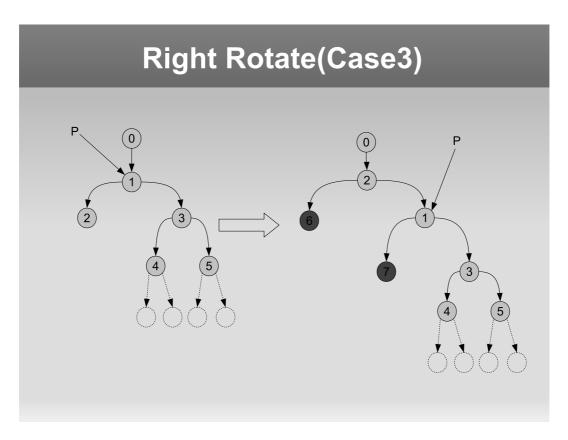


Figure 3: Right Rotate Case 3

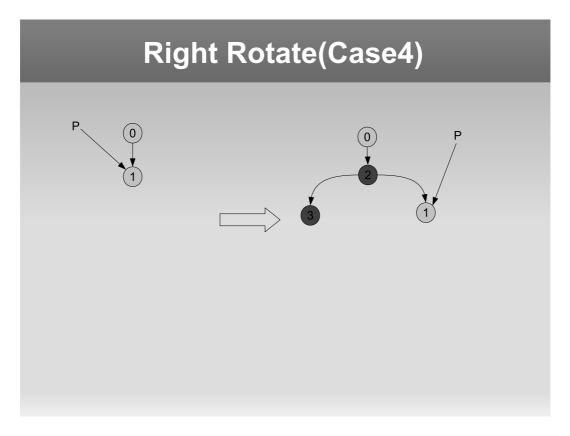


Figure 4: Right Rotate Case 4