

Computational topology: Lecture 12

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May 2, 2019

- 1 Symbolic debugger
- 2 Symbolic debugging in Julia
- 3 Rebugger tutorial
- 4 Restart our debugging session

Symbolic debugger

Introduction

I can't recommend **too strongly** that you learn how to **use a debugger**

- If your programs **assemble and link properly** **but do not work**, you will remain in the dark about the reason for this, **until you watch** them **working under debugger control**
- **Often**, one debugging session will **show up an error instantly** and can **save hours** of time **trying** out various different things

What is a debugger?

A **debugger** is **able to run another program** (the “debuggee”) in **closely controlled conditions**

- This enables you to **single step** through the **debuggee's code**: the processor will execute a **single instruction at a time**, and you can **watch the effect** of this on the debuggee's **registers** and **flags**, **stack** and **memory areas**
- Usually a debugger **allows** you to **choose** whether to **trace into CALLS** or **execute but jump** over them
- A debugger will also allow you to **set breakpoints** where you can **stop execution** and proceed from there, **or to run the debuggee** until something **goes wrong**.

What is a symbolic debugger?

A symbolic debugger **knows the addresses** of the **symbols** and is able to **display** them in the **disassembly**.

- Data references in the disassembly are shown by **data label**
- A symbolic debugger may also use the code labels to allow the user to **establish breakpoints**, and **may display the contents of memory** by reference to data labels
- The **symbols are known** to the debugger either because the **symbol information is embedded in the executable**, or **kept in a separate file**
- This is **done at link-time** and is achieved by the linker, which if asked, will sort the labels in the object files and **put them in the executable file** (or in a separate file) to be **read by the debugger** as symbols.

Retrace the steps prior to the bug

Try to **note** the **sequence of events** leading up to the **bug** each time the fault occurs

- Then **carry out that sequence** again to check that the fault then occurs
- **Try to isolate the fault** by removing some of the steps or by taking other steps
- Get the **sequence as short as you can**
- This process will **help to find** the **most likely culprit** for the fault, and **reduce** the procedures that **you need to check**

Symbolic debugging in Julia

A Julia interpreter and debugger

A Julia interpreter and debugger

- Step into functions and manually walk through your code while inspecting its state
- Set breakpoints and trap errors, allowing you to discover what went wrong at the point of trouble
- Interactively update and replace existing code to rapidly fix bugs in place without restarting
- Use the full-featured IDE in Juno to bundle all these features together in an easy to use graphical interface

Juno

- The `Juno.@run` macro interprets your code and drops you in a debugging session if it hits a breakpoint
- `Juno.@enter` allows you to step through starting from the first line.

The screenshot displays the Juno IDE interface with the following components:

- Editor (promotion.jl):**

```

483  (==)(x::T, y::T) where {T<:Number} = x == y
484  (<)(x::T, y::T) where {T<:Real} = no_op_err("<", T)
485  (<=)(x::T, y::T) where {T<:Real} = no_op_err("<=", T)
486
487  rem(x::T, y::T) where {T<:Real} = no_op_err("rem", T)
488  mod(x::T, y::T) where {T<:Real} = no_op_err("mod", T)
489
490  min(x::Real) = x
491  max(x::Real) = x
492  minmax(x::Real) = (x, x)
493
494  max(x::T, y::T) where {T<:Real} = ifelse(y < x, x, y)
495  > min(x::T, y::T) where {T<:Real} = ifelse(y < x, y, x) | <(0, 1)
496  minmax(x::T, y::T) where {T<:Real} = y < x ? (y, x) : (x, y)
497
498  flpsign(x::T, y::T) where {T<:Signed} = no_op_err("flpsign", T)
499

```
- REPL:**

```

julia> Juno.@run gcd(2,3)
debug> x
1
debug> y
0
debug> T
Int64

```
- Debugger:**
 - Buttons: Step into Function, Step over, Step out, Run, Stop, Close.
 - Current state: `> <(0, 1) Debug: Step into Function`
 - Code being debugged:

```

minmax(x::Real) = (x, x)

max(x::T, y::T) where {T<:Real} = ifelse(y < x, x,
min(x::T, y::T) where {T<:Real} = ifelse(y < x, y,
minmax(x::T, y::T) where {T<:Real} = y < x ? (y, x)

flpsign(x::T, y::T) where {T<:Signed} = no_op_err/

```
 - Callstack:

```

1 min(x::T, y::T) promotion.jl:415
0 gcd(a::T, b::T) intfuncs.jl:35

```
 - Breakpoints:
 - Toggle All: On
 - Break on Exception: Off
 - Breakpoint list:
 - min (active)
 - mpfr.jl:693
 - missing.jl:102
 - math.jl:579
 - promotion.jl:410
 - promotion.jl:415

Debugger and Rebugger

If you have a **different favorite editor** than **Atom**—or via remote sessions through a **console**—you can alternatively perform **debugging via the REPL**

- There are **two REPL interfaces**:
 - **Debugger** offers a “**step, next, continue**” interface similar to debuggers like **gdb**,
 - **Rebugger** aims to provide a console interface that is reminiscent of an IDE

Debugger and Rebugger

If you have a **different favorite editor** than **Atom**—or via remote sessions through a **console**—you can alternatively perform **debugging via the REPL**

- There are **two REPL interfaces**:
 - **Debugger** offers a “**step, next, continue**” interface similar to debuggers like **gdb**,
 - **Rebugger** aims to provide a console interface that is reminiscent of an IDE
- Debugger has some capabilities that none of the other interfaces offer, so it should be your choice for particularly difficult cases

Debugger session example

```
julia> @enter closestpair([[0, -0.3], [1., 1.], [1.5, 2], [2, 2], [3, 3]])
In closestpair(P) at /mnt/c/Users/Kristoffer/Debugging/closest_pair.jl
>4 N = length(P)
5 if N < 2 return (Inf, ()) end
6 mindst = norm(P[1] - P[2])
7 minpts = (P[1], P[2])
●8 for i in 1:N-1, j in i+1:N

About to run: (length)(Array{Float64,1}[[0.0, -0.3], [1.0, 1.0], [1.5, 2.0], [2.0, 2.0], [3.0, 3.0]])
1|debug> c
Hit breakpoint:
In closestpair(P) at /mnt/c/Users/Kristoffer/Debugging/closest_pair.jl
4 N = length(P)
5 if N < 2 return (Inf, ()) end
6 mindst = norm(P[1] - P[2])
7 minpts = (P[1], P[2])
> 8 for i in 1:N-1, j in i+1:N
9     tmpdst = norm(P[1] - P[j])
10     if tmpdst < mindst
11         mindst = tmpdst
12         minpts = (P[i], P[j])

About to run: (-)(5, 1)
1|debug> fr
[1] closestpair(P) at /mnt/c/Users/Kristoffer/Debugging/closest_pair.jl
| P::Array{Array{Float64,1},1} = Array{Float64,1}[[0.0, -0.3], [1.0, 1.0], [1.5, 2.0], [2.0, 2.0], [3.0, 3.0]]
| N::Int64 = 5
| mindst::Float64 = 1.6401219466856727
| minpts::Tuple{Array{Float64,1},Array{Float64,1}} = ([0.0, -0.3], [1.0, 1.0])
| T::DataType = Float64
1|julia> norm(P[2] - P[1])
1.6401219466856727
```

Rebugger

Rebugger enters calls via a **key binding**

- To try it, type `gcd(10, 20)` and without hitting enter type **Meta-i** (**Esc-i**, **Alt-i**, or **option-i**)
- After a short pause the display should update; **type ?** to see the **possible actions**:

JuliaInterpreter

Contains the logic needed to evaluate and inspect running Julia code

- An interpreter lends itself naturally to step-wise code evaluation and the implementation of breakpoints

```
using JuliaInterpreter  
A = rand(1:10, 5)  
@interpret sum(A)
```

JuliaInterpreter gained the ability to interpret “top-level code”, for example the code used to define packages and create test suites

JuliaInterpreter

JuliaInterpreter gained support for **breakpoints**

- While not strictly a feature of interpreters, **they are necessary** to build a capable debugger and can be viewed as an **additional form of control-flow within the interpreter** itself
- These breakpoints **can be set manually** with functions **breakpoint** and a macro **@breakpoint**, manipulated in Juno, Rebugger, or Debugger, or **added directly** to code with the **@bp** macro
- Existing breakpoints can be **disabled**, **enabled**, or **removed**
- We support setting of breakpoints **at specific source lines** or on **entry** to a **specific method**, conditional and unconditional breakpoints, and can automatically trap errors as if they were manually-set breakpoints

CodeTracking

`CodeTracking` won't do anything useful unless the user is **also running `Revise`**, because `Revise` will be responsible for updating `CodeTracking`'s **internal variables**

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However, `Revise` is a fairly large (and fairly complex) package, and currently it's not easy to discover how to extract particular kinds of information from its internal storage

- `CodeTracking` is designed to be the new “query” part of `Revise.jl`
- The aim is to have a very simple API that developers can learn in a few minutes and then incorporate into their own packages; its lightweight nature means that they potentially gain a lot of functionality without being forced to take a big hit in startup time

Rebugger tutorial

Rebugger tutorial

Rebugger is an expression-level debugger for Julia

- It has no ability to interact with or manipulate call stacks (see Gallium), but it can trace execution via the manipulation of Julia expressions

The name “Rebugger” has 3 meanings:

- 1 it is a REPL-based debugger (more on that in the documentation)
- 2 it is the Revise-based debugger
- 3 it supports repeated-execution debugging

Rebugger tutorial

clone locally the package <https://github.com/timholly/Rebugger.jl>
compile the docs
start from `build/index.html`

Restart our debugging session

Our 3D test example: here is OK

```
using LinearAlgebraicRepresentation, Plasm
Lar = LinearAlgebraicRepresentation
```

```
function twocubes()
```

```
    #V, (VV,EV,FV,CV) = Lar.cuboid([0.5,0.5,0.5],true,[-0.5,-0.5,-0.5])
```

```
    V, (VV,EV,FV,CV) = Lar.cuboidGrid([1,1,1],true)
```

```
    mybox = (V,CV,FV,EV)
```

```
    #twocubes = Lar.Struct([ mybox , Lar.t(0.3,0.4,0.5), Lar.r(pi/5,0,0), Lar.r(0,0,pi/12), mybox ])
```

```
    twocubes = Lar.Struct([ mybox , Lar.t(0.3,0.4,0.5), Lar.r(pi/3,0,0), Lar.r(0,0,pi/6), mybox ])
```

```
    V,CV,FV,EV = Lar.struct2lar(twocubes)
```

```
    Plasm.view(V,CV)
```

```
    cop_EV = Lar.coboundary_0(EV::Lar.Cells);
```

```
    cop_EW = convert(Lar.ChainOp, cop_EV);
```

```
    cop_FE = Lar.coboundary_1(V, FV::Lar.Cells, EV::Lar.Cells);
```

```
    W = convert(Lar.Points, V');
```

```
    V, copEV, copFE, copCF = Lar.Arrangement.spatial_arrangement( W::Lar.Points, cop_EW::Lar.ChainOp, cop_FE::Lar.ChainOp)
```

```
    EV = Lar.cop2lar(copEV)
```

```
    FE = [findnz(copFE[k,:])[1] for k=1:size(copFE,1)]
```

```
    FV = [collect(Set(cat(EV[e] for e in FE[f]))) for f=1:length(FE)]
```

```
    FV = convert(Lar.Cells, FV)
```

```
    W = convert(Lar.Points, V')
```

```
    Plasm.view(Plasm.numbering(0.25)((W,[[[k] for k=1:size(W,2)],EV,FV]]))
```

```
    triangulated_faces = Lar.triangulate(V, [copEV, copFE])
```

```
    FVs = convert(Array{Lar.Cells}, triangulated_faces)
```

```
    V = convert(Lar.Points, V')
```

```
    Plasm.viewcolor(V::Lar.Points, FVs::Array{Lar.Cells})
```

Our 3D test example: here is KO ...

```
using LinearAlgebraicRepresentation, Plasm
Lar = LinearAlgebraicRepresentation

function twocubes()
    V,(VV,EV,FV,CV) = Lar.cuboid([0.5,0.5,0.5],true,[-0.5,-0.5,-0.5])
    #V,(VV,EV,FV,CV) = Lar.cuboidGrid([1,1,1],true)
    mybox = (V,CV,FV,EV)

    #twocubes = Lar.Struct([ mybox , Lar.t(0.3,0.4,0.5), Lar.r(pi/5,0,0), Lar.r(0,0,pi/12), mybox ])
    twocubes = Lar.Struct([ mybox , Lar.t(0.3,0.4,0.5), Lar.r(pi/3,0,0), Lar.r(0,0,pi/6), mybox ])
    V,CV,FV,EV = Lar.struct2lar(twocubes)
    Plasm.view(V,CV)
```

Loops...

```
sigma = 67
sigma = 68
sigma = 69
sigma = 70
sigma = 71
sigma = 72
0%
```

aaaaaa

aaaaaa