

Computational topology: Lecture 7

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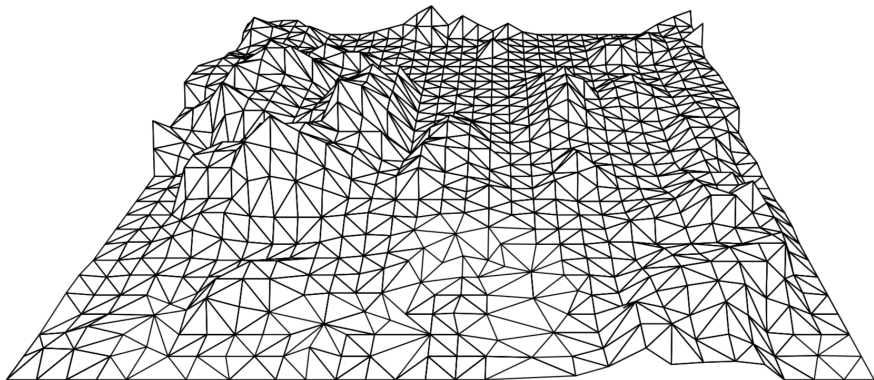
¹from: de Berg, Otfried Cheong, van Kreveld, Overmars: [Computational Geometry, Algorithms and Applications](#), Third Edition, Springer.

²idem.

Delaunay triangulations³

³from: de Berg, Otfried Cheong, van Kreveld, Overmars: [Computational Geometry, Algorithms and Applications](#), Third Edition, Springer.

Triangulation example (terrain map)



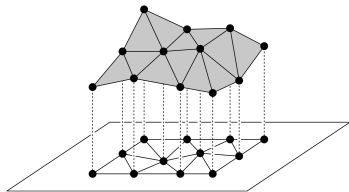
Triangulation example (terrain map)

We first determine a **triangulation** of P : a **planar subdivision** whose bounded faces are **triangles** and whose **vertices** are the points of P .

We then lift each sample point to its height, **mapping every triangle** in the triangulation **to a triangle in 3-space**

We get is a **polyhedral terrain**, the **graph** of a **piecewise linear continuous function**

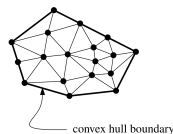
The polyhedral terrain as an **approximation** of the original terrain.



Triangulations of Planar Point Sets

Let $P := \{p_1, p_2, \dots, p_n\}$ be a set of points in the plane. To be able to formally define a triangulation of P , we first define a *maximal planar subdivision* as a subdivision \mathcal{S} such that no edge connecting two vertices can be added to \mathcal{S} without destroying its planarity. In other words, any edge that is not in \mathcal{S} intersects one of the existing edges. A *triangulation* of P is now defined as a maximal planar subdivision whose vertex set is P .

Theorem 9.1 Let P be a set of n points in the plane, not all collinear, and let k denote the number of points in P that lie on the boundary of the convex hull of P . Then any triangulation of P has $2n - 2 - k$ triangles and $3n - 3 - k$ edges.

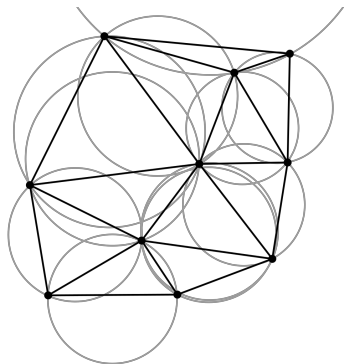


The Delaunay Triangulation

Definition

Delaunay triangulation for a **set P of discrete points** in a plane is a triangulation $DT(P)$ such that no point in P is inside the circumcircle of any triangle in $DT(P)$

Delaunay triangulations **maximize the minimum angle** of all the angles of the triangles in the triangulation; they tend to **avoid sliver triangles**.



Delaunay Triangulation properties

The **Delaunay triangulation** is a triangulation which is **equivalent to the nerve** of the cells in a **Voronoi diagram**,

it is the triangulation of the convex hull of the points in the diagram in which every circumcircle of a triangle is an empty circle

an **edge is illegal** if we can **locally increase the smallest angle** by **flipping that edge**.

A **Delaunay triangulation is unique** iff the **circumcircle** of every triangle contains **exactly three points** on its circumference: the vertices of the triangle.

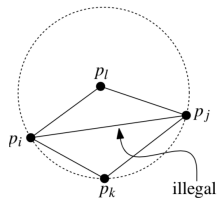
For instance, the Delaunay diagram of the four vertices of a **square** is a square, and **can be converted into a triangulation** in **two different ways**

Computing the Delaunay Triangulation

Observation 9.3 Let \mathcal{T} be a triangulation with an illegal edge e . Let \mathcal{T}' be the triangulation obtained from \mathcal{T} by flipping e . Then $A(\mathcal{T}') > A(\mathcal{T})$.

It turns out that it is not necessary to compute the angles $\alpha_1, \dots, \alpha_6, \alpha'_1, \dots, \alpha'_6$ to check whether a given edge is legal. Instead, we can use the simple criterion stated in the next lemma. The correctness of this criterion follows from Thales's Theorem.

Lemma 9.4 Let edge $\overline{p_i p_j}$ be incident to triangles $p_i p_j p_k$ and $p_i p_j p_l$, and let C be the circle through p_i, p_j , and p_k . The edge $\overline{p_i p_j}$ is illegal if and only if the point p_l lies in the interior of C . Furthermore, if the points p_i, p_j, p_k, p_l form a convex quadrilateral and do not lie on a common circle, then exactly one of $\overline{p_i p_j}$ and $\overline{p_k p_l}$ is an illegal edge.



Computing the Delaunay Triangulation

We define a *legal triangulation* to be a triangulation that does not contain any illegal edge. From the observation above it follows that any angle-optimal triangulation is legal. Computing a legal triangulation is quite simple, once we are given an initial triangulation. We simply flip illegal edges until all edges are legal.

Algorithm LEGALTRIANGULATION(\mathcal{T})

Input. Some triangulation \mathcal{T} of a point set P .

Output. A legal triangulation of P .

1. **while** \mathcal{T} contains an illegal edge $\overline{p_i p_j}$
2. **do** (* Flip $\overline{p_i p_j}$ *)
3. Let $p_i p_j p_k$ and $p_i p_j p_l$ be the two triangles adjacent to $\overline{p_i p_j}$.
4. Remove $\overline{p_i p_j}$ from \mathcal{T} , and add $\overline{p_k p_l}$ instead.
5. **return** \mathcal{T}

Computing the Delaunay Triangulation: Divide and conquer

Recursively draws a line to split the vertices into two sets

The Delaunay triangulation is computed for each set, and then the two sets are merged along the splitting line.

A divide and conquer paradigm to performing a triangulation in d dimensions is presented in “DeWall: A fast divide and conquer Delaunay triangulation algorithm in E^d ” by P. Cignoni, C. Montani, R. Scopigno.

Delaunay triangulations rely on fast operations for detecting if a point is within a triangle's circumcircle and an efficient data structure for storing triangles and edges (LAR is OK?)

In 2D, wheater point D lies in the circumcircle of A, B, C is tested by evaluating a 3×3 determinant

Voronoi complexes¹³

¹³idem.

Convex polygons

To test if a **polygon is convex**, every point of the polygon should be level with or behind each line segment

Consider **each set of three points** along the polygon. If every angle is $\leq \pi$ you have a **convex polygon**

Definition and Basic Properties

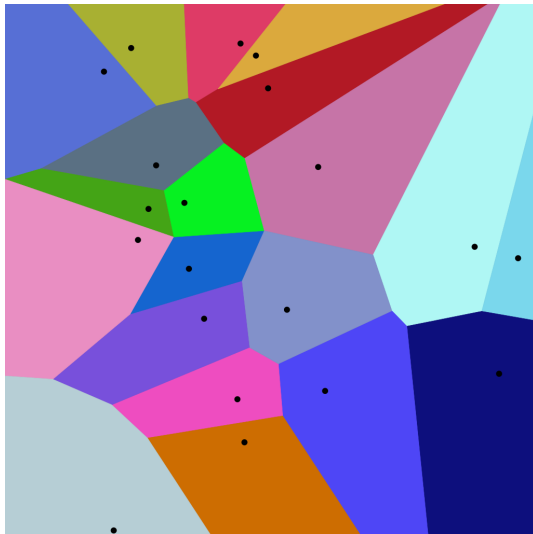
Voronoi diagram is a partitioning of a plane into regions based on distance to points in a specific subset of the plane.

That set of points (called **seeds**, **sites**, or **generators**) is specified beforehand, and **for each seed** there is a corresponding **region** consisting of **all points closer to that seed** than to any other.

These regions are called **Voronoi cells**.

The Voronoi diagram of a set of points is dual to its Delaunay triangulation.

Voronoi diagrams



Voronoi properties

The **dual graph** for a Voronoi diagram (in the case of a Euclidean space with point sites) corresponds to the **Delaunay triangulation** for the same set of points

The **closest pair of points** corresponds to **two adjacent cells** in the Voronoi diagram

Then **two points are adjacent** on the **convex hull** if and only if their Voronoi cells share an **infinitely long side**

Computing the Voronoi Diagram

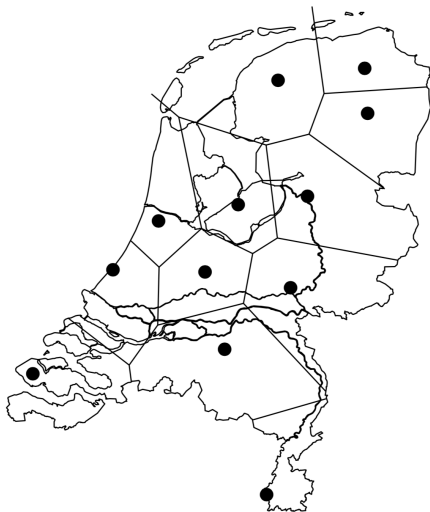
Fortune's algorithm, an $O(n \log(n))$ algorithm for generating a **Voronoi diagram** from a set of points in a plane

Lloyd's algorithm and its generalization via the Linde–Buzo–Gray algorithm (aka k -means clustering), utilize **Voronoi tessellations** in **spaces of arbitrary dimension** to iteratively converge towards a specialized form of the Voronoi diagram, called **Centroidal Voronoi tessellation**, where **each site** is also the **geometric center** (barycenter) of its cell

Starting with a Delaunay triangulation (obtain the dual):

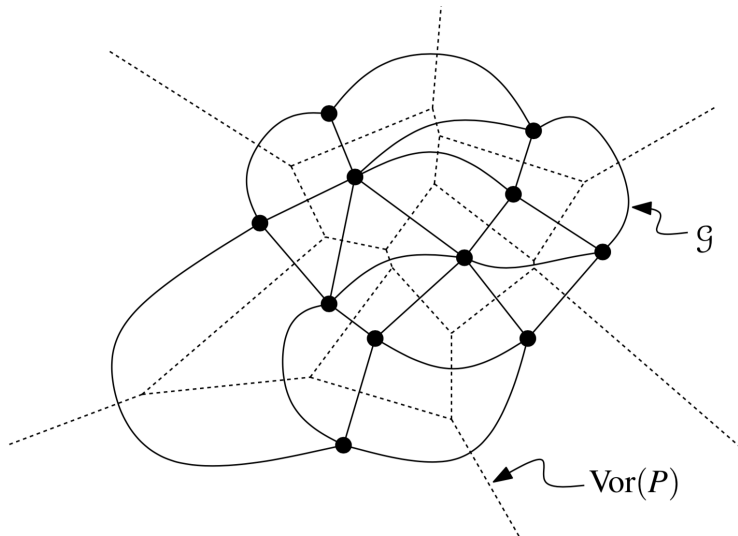
Bowyer–Watson algorithm, an $O(n \log(n))$ to $O(n^2)$ algorithm for generating a **Delaunay triangulation** in **any number of dimensions**, from which the Voronoi diagram can be obtained

Post office problem



Planar graphs

V, E, F one-to-one to F, E, V

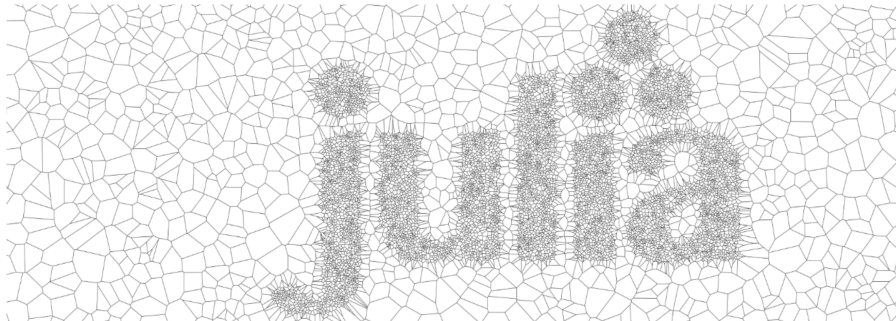


Julia Packages

<https://github.com/JuliaGeometry/VoronoiDelaunay.jl>

VoronoiDelaunay.jl

build passing Julia v0.6 v0.2.0 Tests Pass coverage 73%



Fast, robust construction of 2D Delaunay and Voronoi tessellations on generic point types. Implementation follows algorithms described in the [Arepo paper](#) and used (for e.g.) in the [Illustris Simulation](#). License: MIT. Bug reports welcome!

Read the source !!

Look and enjoy the coding style ...

728 lines (641 sloc) | 22.8 KB

[Raw](#)
[Blame](#)
[History](#)


```

1  module VoronoiDelaunay
2
3  # Fast, robust 2D Voronoi/Delaunay tessellation
4  # Implementation follows algorithms described in http://arxiv.org/abs/0901.4107
5  # and used (for e.g.) in the Illustris Simulation
6  # http://www.illustris-project.org/
7  #
8  # Author: Ariel Keselman (skariel@gmail.com)
9  # License: MIT
10 # Bug reports welcome!
11
12 export
13   DelaunayTessellation, DelaunayTessellation2D, sizehint!, isexternal,
14   min_coord, max_coord, locate, movea, moveb, movec,
15   delaunayedges, voronoiedges, voronoiedgeswithoutgenerators,
16   iterate, findindex, push!,
17   Point, Point2D, AbstractPoint2D, getx, gety, geta, getb, getc,
18   getgena, getgenb, getplotxy
19
20 using GeometricalPredicates
21 import GeometricalPredicates: geta, getb, getc
22

```

Examples and implementation

Exercise

- 1 generate a set of random points within $[0, 1]^2$

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- ① generate a set of random points within $[0, 1]^2$
- ② generate a Delaunay tessellation with
`JuliaGeometry/VoronoiDelaunay.jl`

Exercise

- ① generate a **set of random points** within $[0, 1]^2$
- ② generate a **Delaunay tessellation** with
`JuliaGeometry/VoronoiDelaunay.jl`
- ③ **import the result** in `cvdlab/LinearAlgebraicRepresentation.jl`
aka `Lar`

Exercise

- 1 generate a **set of random points** within $[0, 1]^2$
- 2 generate a **Delaunay tessellation** with
`JuliaGeometry/VoronoiDelaunay.jl`
- 3 **import the result** in `cvdlab/LinearAlgebraicRepresentation.jl`
aka `Lar`
- 4 **visualize** with `cvdlab/Plasm.jl`

Exercise

- 1 generate a **set of random points** within $[0, 1]^2$
- 2 generate a **Delaunay tessellation** with
JuliaGeometry/VoronoiDelaunay.jl
- 3 **import the result** in cvdlab/LinearAlgebraicRepresentation.jl
aka Lar
- 4 **visualize** with cvdlab/Plasm.jl
- 5 as above: **generate**, **export** and **visualize** the corresponding **Voronoi complex**