

# Computational topology: Lecture 3

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March 7, 2019

- 1 Line segment intersection
- 2 Introduction to LAR (Linear Algebraic Representation)

# Line segment intersection

# Logic and data structures: segments, events, sweep-line

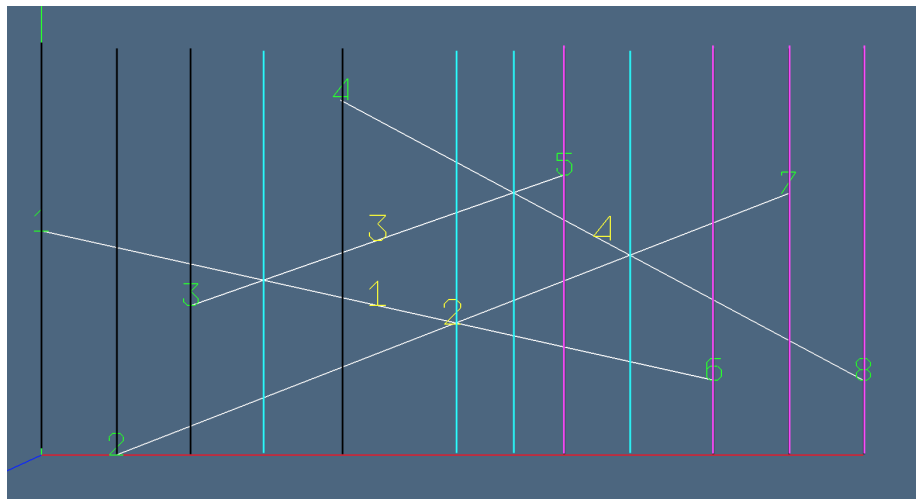


Figure 1: A simple example

# Test data preparation

Same as the original article

```
# EXAMPLE 0
```

```
# data generation
```

```
lines = [[[1,3],[10,5]], [[2,6],[11,2.5]],  
          [[3,4],[8,2.25]], [[5,1.25],[12,5]]]
```

```
V,EV = lines2lar(lines)
```

```
Plasm.view(Plasm.numbering(2.)((V,[[[k] for k=1:size(V,2)], EV
```

```
# data sorting
```

```
V = Plasm.normalize(V,flag=true)
```

```
W,EW = presorted(V,EV)
```

```
Plasm.view(Plasm.numbering(.25)((W,[[[k] for k=1:size(W,2)], E
```

# Pseudocode

```

Initialize event queue  $\xi$  = all segment endpoints;
Sort  $\xi$  by increasing x and y;
Initialize sweep line  $SL$  to be empty;
Initialize output intersection list  $\Lambda$  to be empty;

While ( $\xi$  is nonempty) {
  Let E = the next event from  $\xi$ ;
  If (E is a left endpoint) {
    Let segE = E's segment;
    Add segE to  $SL$ ;
    Let segA = the segment above segE in  $SL$ ;
    Let segB = the segment below segE in  $SL$ ;
    If (I = Intersect( segE with segA) exists)
      Insert I into  $\xi$ ;
    If (I = Intersect( segE with segB) exists)
      Insert I into  $\xi$ ;
  }
  Else If (E is a right endpoint) {
    Let segE = E's segment;
    Let segA = the segment above segE in  $SL$ ;
    Let segB = the segment below segE in  $SL$ ;
    Remove segE from  $SL$ ;
    If (I = Intersect( segA with segB) exists)
      If (I is not in  $\xi$  already) Insert I into  $\xi$ ;
  }
  Else { // E is an intersection event
    Add E to the output list  $\Lambda$ ;
    Let segE1 above segE2 be E's intersecting segments in  $SL$ ;
    Swap their positions so that segE2 is now above segE1;
    Let segA = the segment above segE2 in  $SL$ ;
    Let segB = the segment below segE1 in  $SL$ ;
    If (I = Intersect(segE2 with segA) exists)
      If (I is not in  $\xi$  already) Insert I into  $\xi$ ;
    If (I = Intersect(segE1 with segB) exists)
      If (I is not in  $\xi$  already) Insert I into  $\xi$ ;
  }
  remove E from  $\xi$ ;
}
return  $\Lambda$ ;

```

# Algorithm bootstrap

"docs/algorithm.jl"

[docs/algorithm.jl](#)

Same structure than pseudocode, but data structures already chosen

# Data structures

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## DataStructures.jl

latest

Search docs

» DataStructures.jl

[Edit on GitHub](#)

## DataStructures.jl

This package implements a variety of data structures, including

- Deque (based on block-list)
- CircularBuffer
- CircularDeque (based on a circular buffer)
- Stack
- Queue
- Priority Queue
- Accumulators and Counters
- Disjoint Sets
- Binary Heap
- Mutable Binary Heap
- Ordered Dicts and Sets
- Dictionaries with Defaults
- Trie
- Linked List
- Sorted Dict, Sorted Multi-Dict and Sorted Set
- DataStructures.IntSet

## Contents

### DataStructures.jl

#### Contents

Deque

CircularBuffer

CircularDeque

Stack and Queue

Priority Queue

Accumulators and Counters

Disjoint Sets

Heaps

OrderedDicts and OrderedSets

DefaultDict and DefaultOrderedDict

Trie

Linked List

DataStructures.IntSet

Sorted Containers



# Data structures

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# Current status

aaaaa

# Current status execution

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# Introduction to LAR (Linear Algebraic Representation)

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With increased complexity of geometric data, topological models play an increasingly important role beyond boundary representations, assemblies, finite elements, image processing, and other traditional modeling applications. While many graph- and index-based data structures have been proposed, no standard representation has emerged as of now. Furthermore, such representations typically do not deal with representations of mappings and functions and do not scale to support parallel processing, open source, and client-based architectures. We advocate that a proper mathematical model for all topological structures is a (co)chain complex: a sequence of (co)chain spaces and (co)boundary mappings. This in turn implies all topological structures may be represented by a collection of sparse matrices. We propose a Linear Algebraic Representation (LAR) scheme for mod 2 (co)chain complexes using CSR matrices and show that it supports a variety of topological computations using standard matrix algebra, without any overhead in space or running time. A full open source implementation of LAR is available and is being used for a variety of applications.

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Figure 3: Some examples

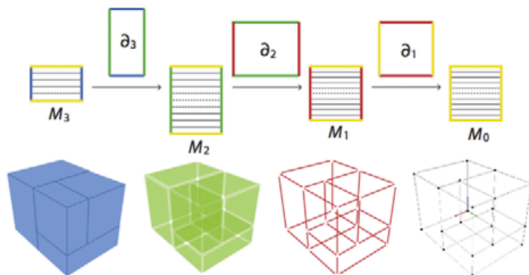
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A **complex**  $C$  is a sequence  $\cdots \longrightarrow C_{d+1} \xrightarrow{\partial_{d+1}} C_d \xrightarrow{\partial_d} C_{d-1} \longrightarrow \cdots$

## Chain and cochain complex

A **chain complex**  $C$  is a complex of **chain spaces** and **boundary maps**:



**Unit  $d$ -chains** (single  $d$ -cell subsets), are the **standard bases** ( $M_d$  rows) of  **$d$ -chain** :

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linear spaces  $C_d$  and linear boundary maps  $\partial_d$ , where  $\partial_{d+1} \circ \partial_d = 0$ , for all  $d$

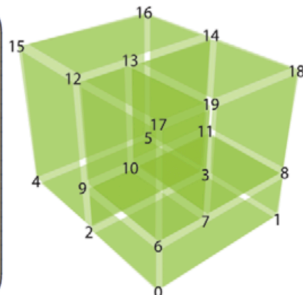
## Characteristic matrices in CSR matrix form

$$M_3 = \begin{pmatrix} 00111100001111111000 \\ 11110011111100000000 \\ 00000011011011000101 \\ 00000001101101100011 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 3 & 4 & 5 & 9 & 10 & 11 & 12 & 13 & 14 & 15 & 16 \\ 0 & 1 & 2 & 3 & 6 & 7 & 8 & 9 & 10 & 11 \\ 6 & 7 & 9 & 10 & 12 & 13 & 17 & 19 \\ 7 & 8 & 10 & 11 & 13 & 14 & 18 & 19 \end{pmatrix}$$

$$M_2 = \begin{pmatrix} 11110000000000000000 \\ 11000011100000000000 \\ 10100010010000000000 \\ 01010000100100000000 \\ 00111100000000000000 \\ 00110000011100000000 \\ 00101000010010010000 \\ 00010100000100101000 \\ 00001100000000011000 \\ 00000011011000000000 \\ 00000011000000000101 \\ 00000010010010000100 \\ 00000001101100000000 \\ 00000001100000000011 \\ 00000001001001000001 \\ 00000000100100100010 \\ 00000000011011000000 \\ 00000000001101100000 \\ 00000000000011111000 \\ 00000000000011000101 \\ 00000000000001100011 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 & 2 & 3 \\ 0 & 1 & 6 & 7 & 8 \\ 0 & 2 & 6 & 9 \\ 1 & 3 & 8 & 11 \\ 2 & 3 & 4 & 5 \\ 2 & 3 & 9 & 10 & 11 \\ 2 & 4 & 9 & 12 & 15 \\ 3 & 5 & 11 & 14 & 16 \\ 4 & 5 & 15 & 16 \\ 6 & 7 & 9 & 10 \\ 6 & 7 & 17 & 19 \\ 6 & 9 & 12 & 17 \\ 7 & 8 & 10 & 11 \\ 7 & 8 & 18 & 19 \\ 7 & 10 & 13 & 19 \\ 8 & 11 & 14 & 18 \\ 9 & 10 & 12 & 13 \\ 10 & 11 & 13 & 14 \\ 12 & 13 & 14 & 15 & 16 \\ 12 & 13 & 17 & 19 \\ 13 & 14 & 18 & 19 \end{pmatrix}$$



aces  $d$ -cells as subsets of vertices

CSR form of a binary matrix

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