

# How To Write Fast Numerical Code

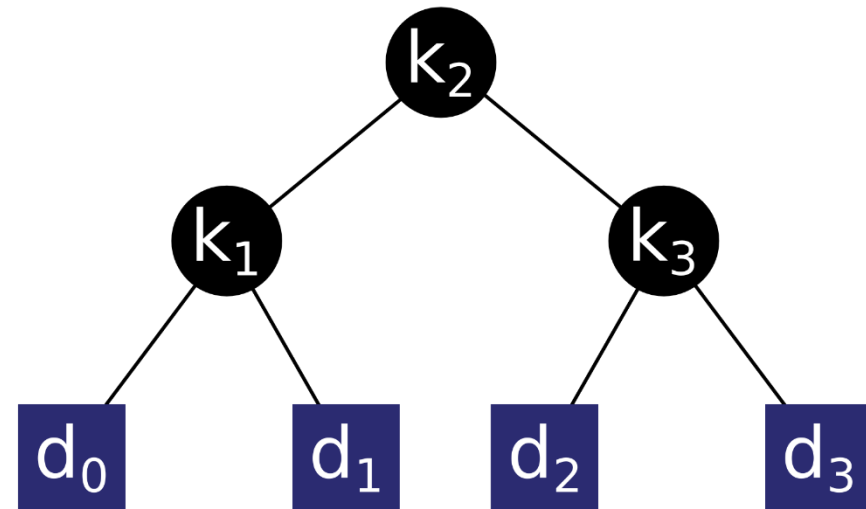
# Optimal Binary Search Trees

Team 16: Jeremia Bär, Stefan Dietiker

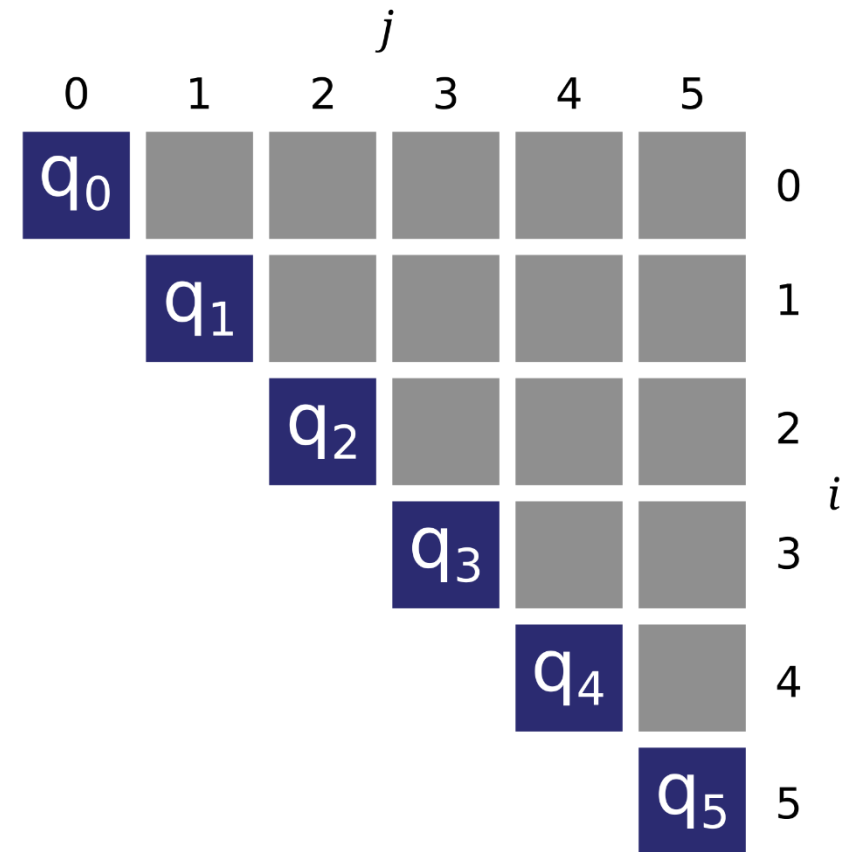
May 20<sup>th</sup>, 2014

# Problem Description

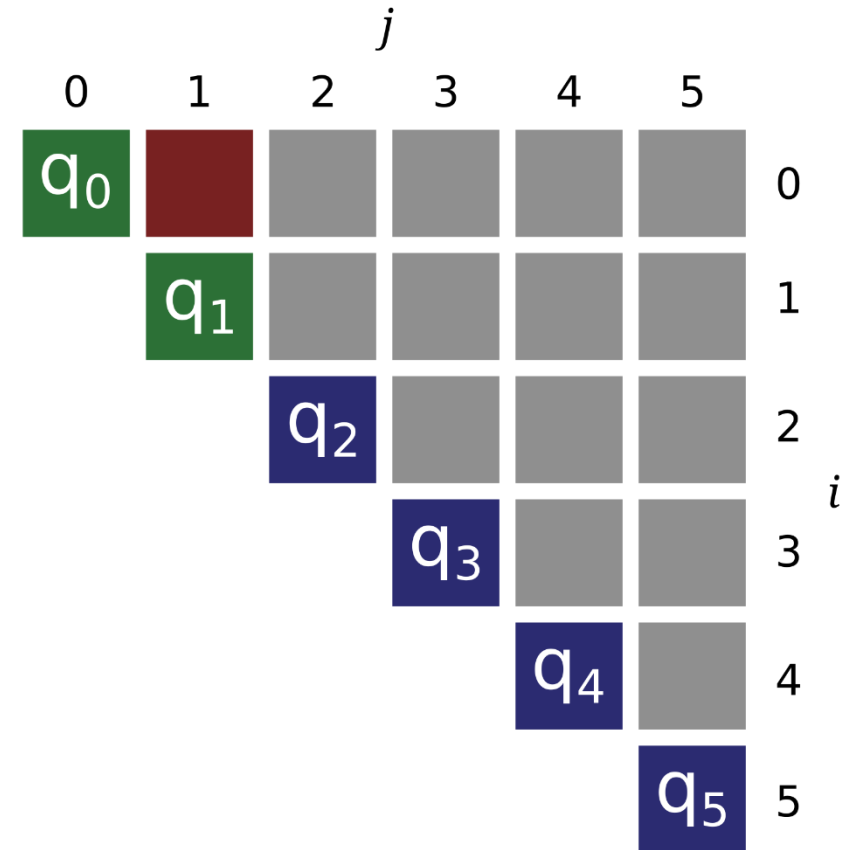
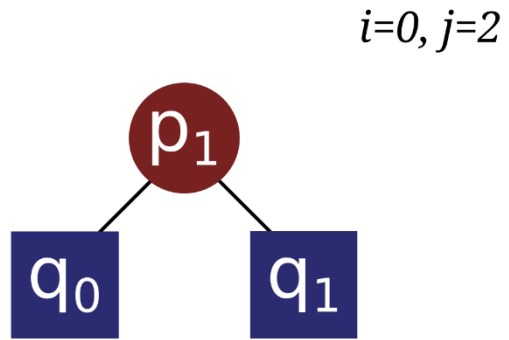
- Given:
  - Key Weights  $p_1, \dots, p_n$
  - Dummy Weights  $q_0, \dots, q_n$
- Required:
  - Minimize Expected Lookup Cost
  - $\sum h(k_i) \cdot p_i + \sum h(d_j) \cdot q_j$



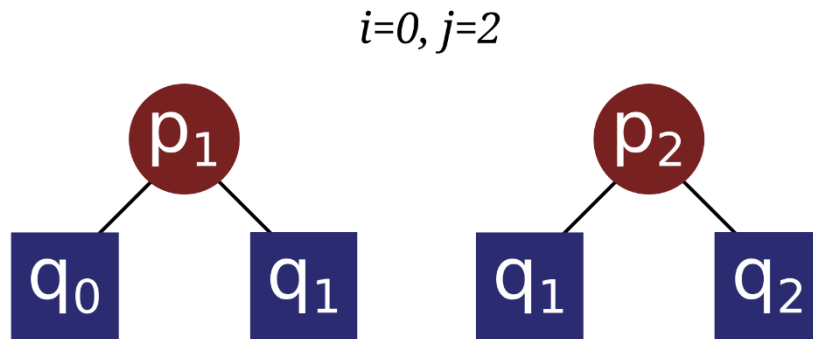
# Algorithm: Dynamic Programming



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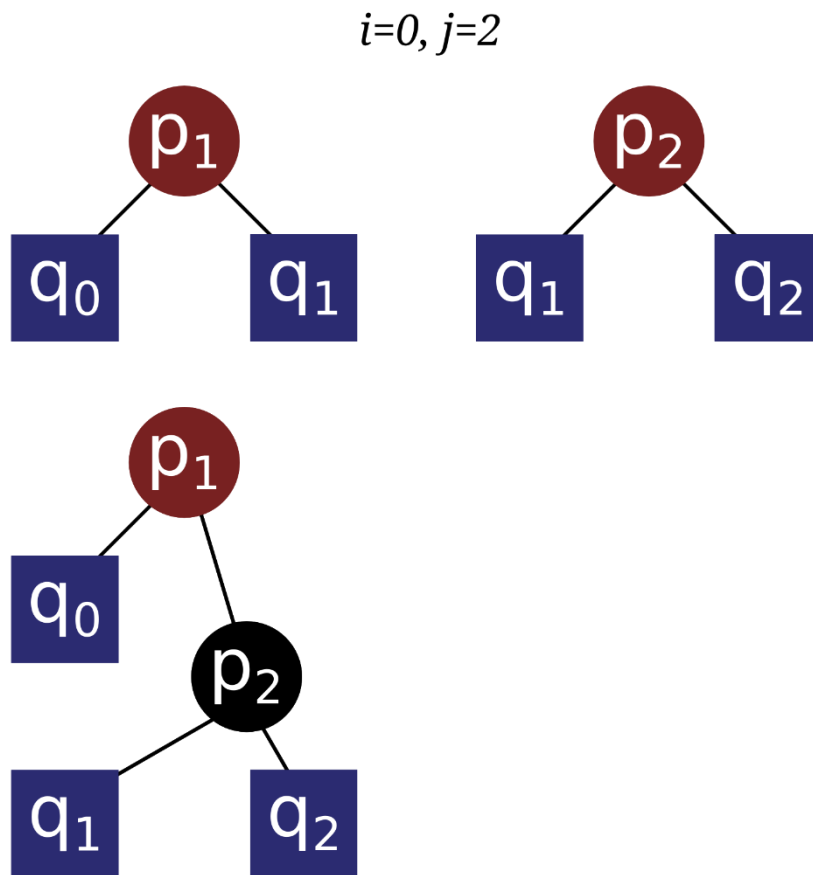
# Algorithm: Dynamic Programming



$j$						
0	1	2	3	4	5	
0	$q_0$					0
1	$q_1$					1
2						2
3						3
4						4
5						5

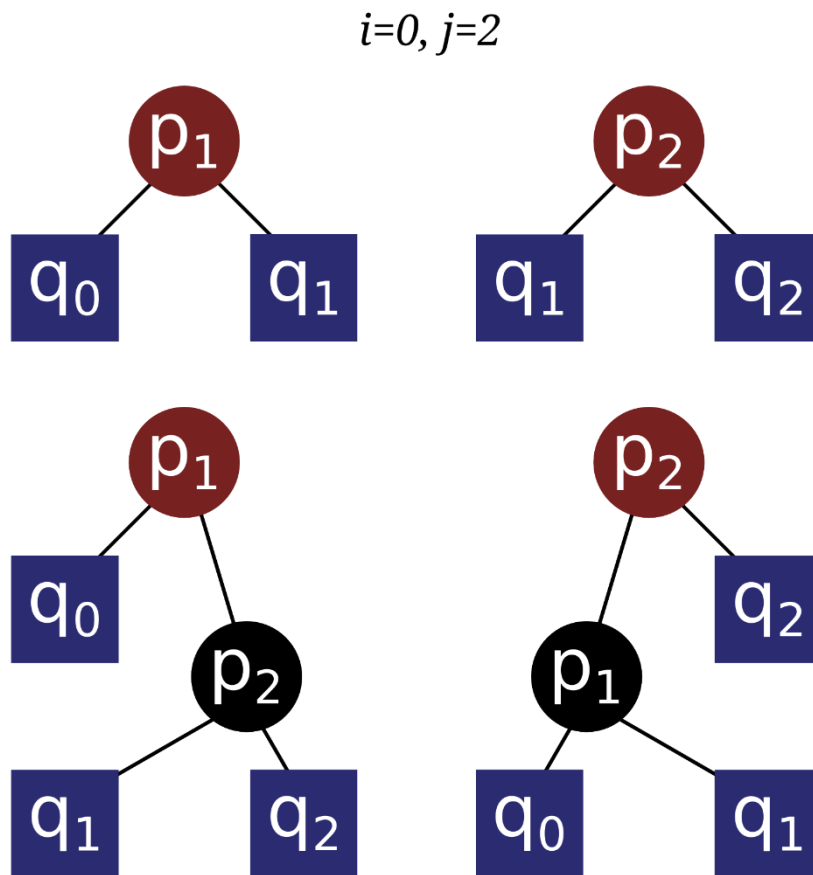
$i$

# Algorithm: Dynamic Programming



$j$						
0	1	2	3	4	5	
$q_0$						0
	$q_1$					1
		$q_2$				2
			$q_3$			3
				$q_4$		4
					$q_5$	5
						$i$

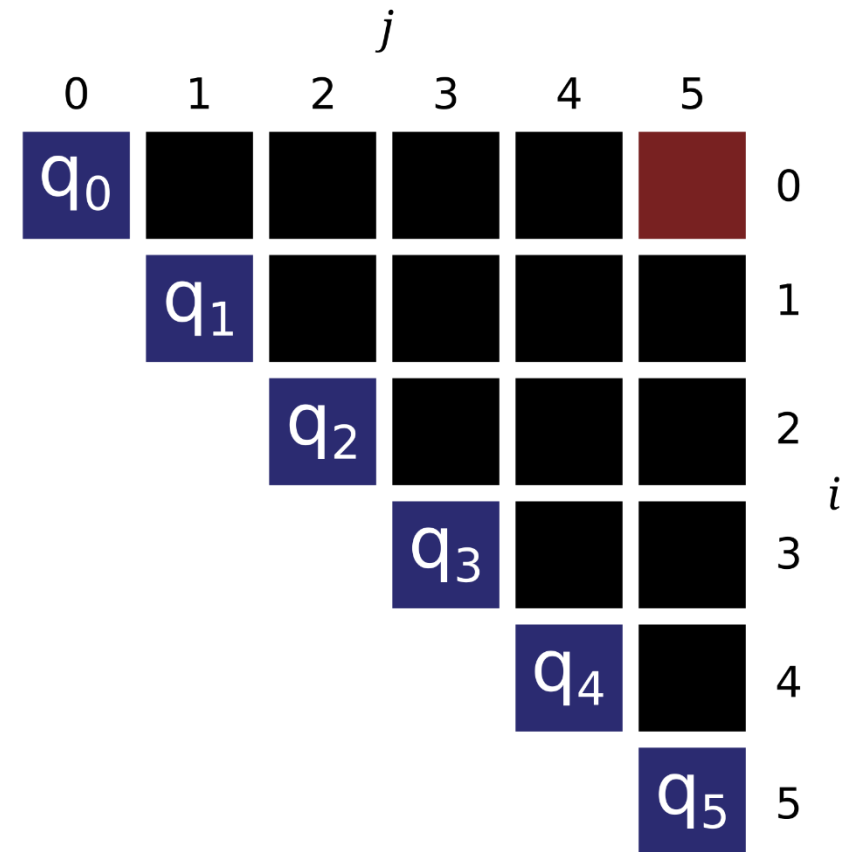
# Algorithm: Dynamic Programming



$j$						
0	1	2	3	4	5	
$q_0$						0
	$q_1$					1
		$q_2$				2
			$q_3$			3
				$q_4$		4
					$q_5$	5

$i$

# Algorithm: Dynamic Programming

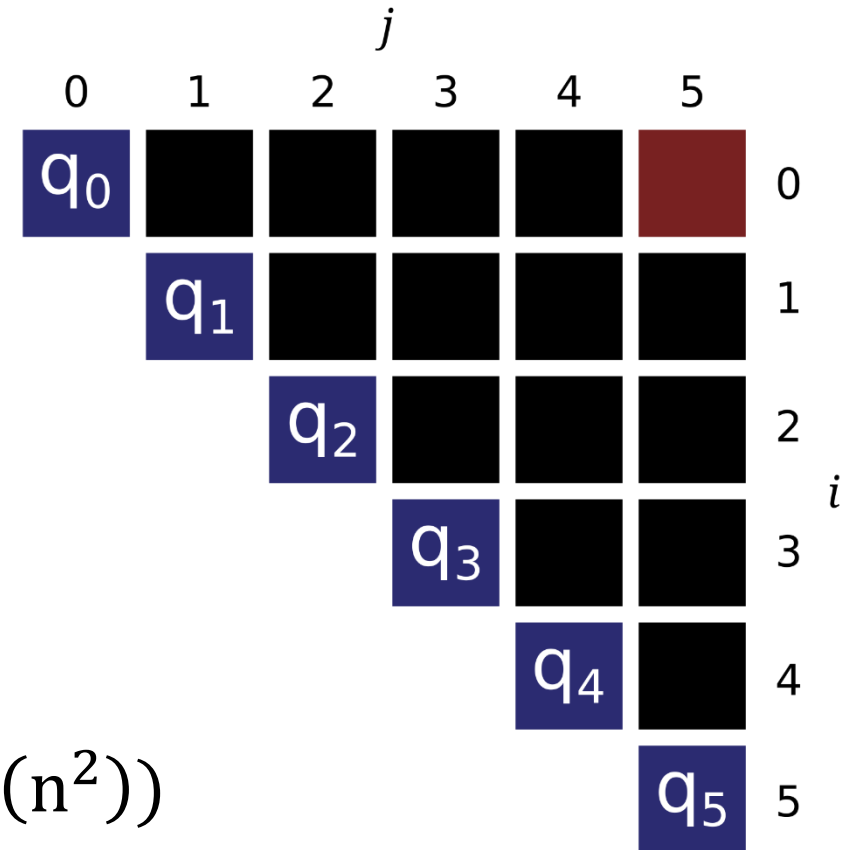




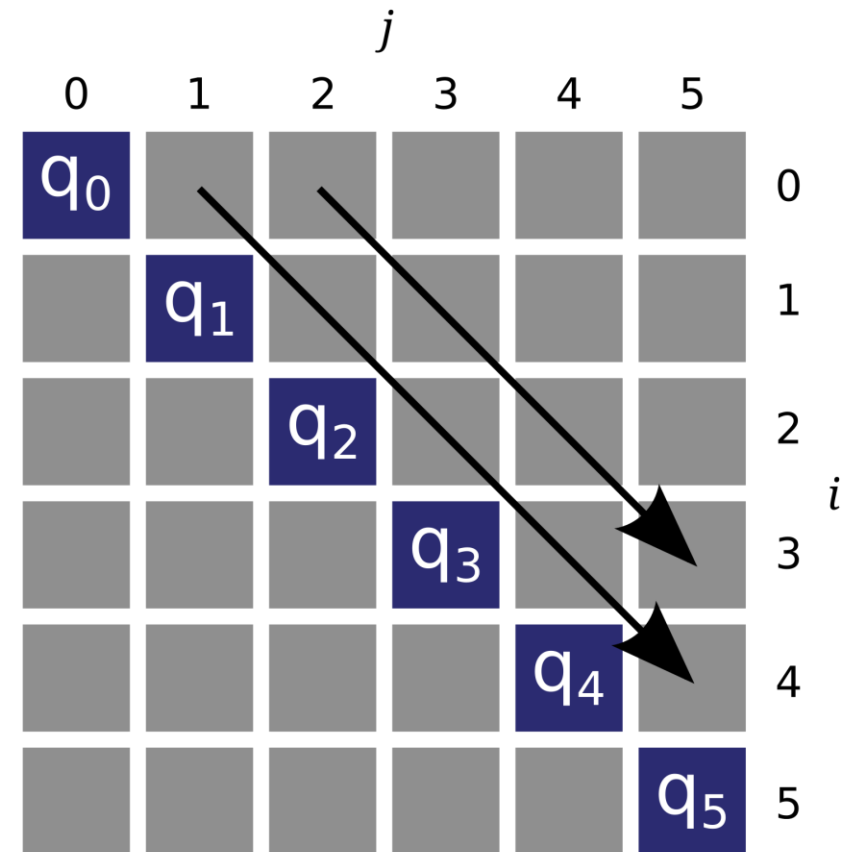
# Algorithm: Dynamic Programming

- per entry
  - $h$  additions
  - $h$  comparisons
- $O(n^2)$  entries

- $C(\text{add}, \text{cmp}) = C(\frac{1}{3}n^3 + O(n^2), \frac{1}{6}n^3 + O(n^2))$



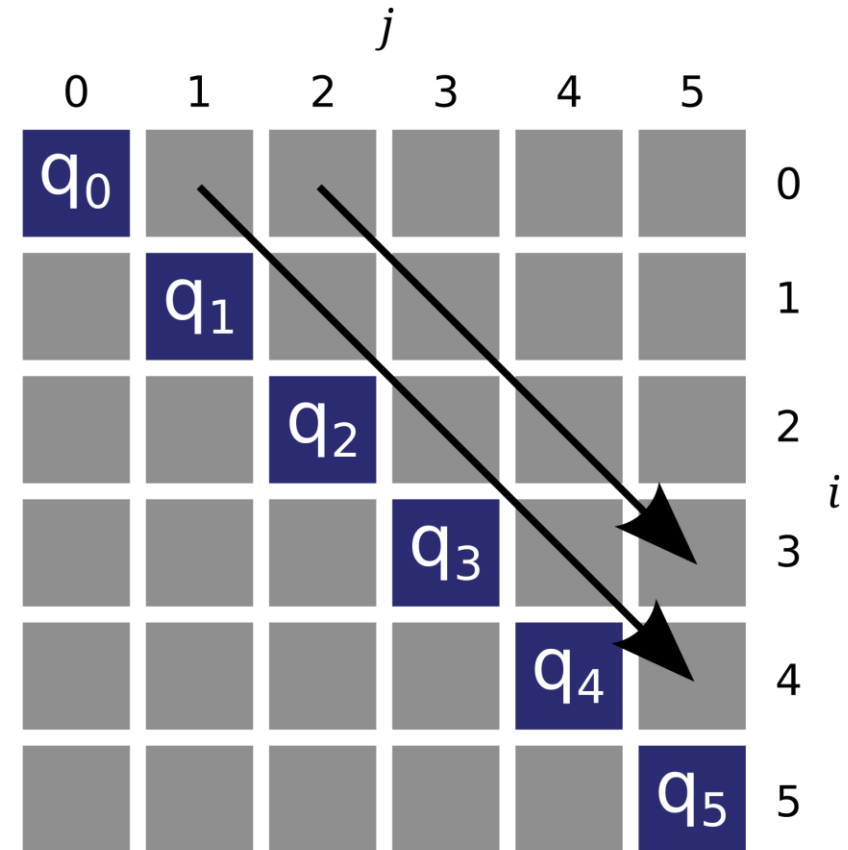
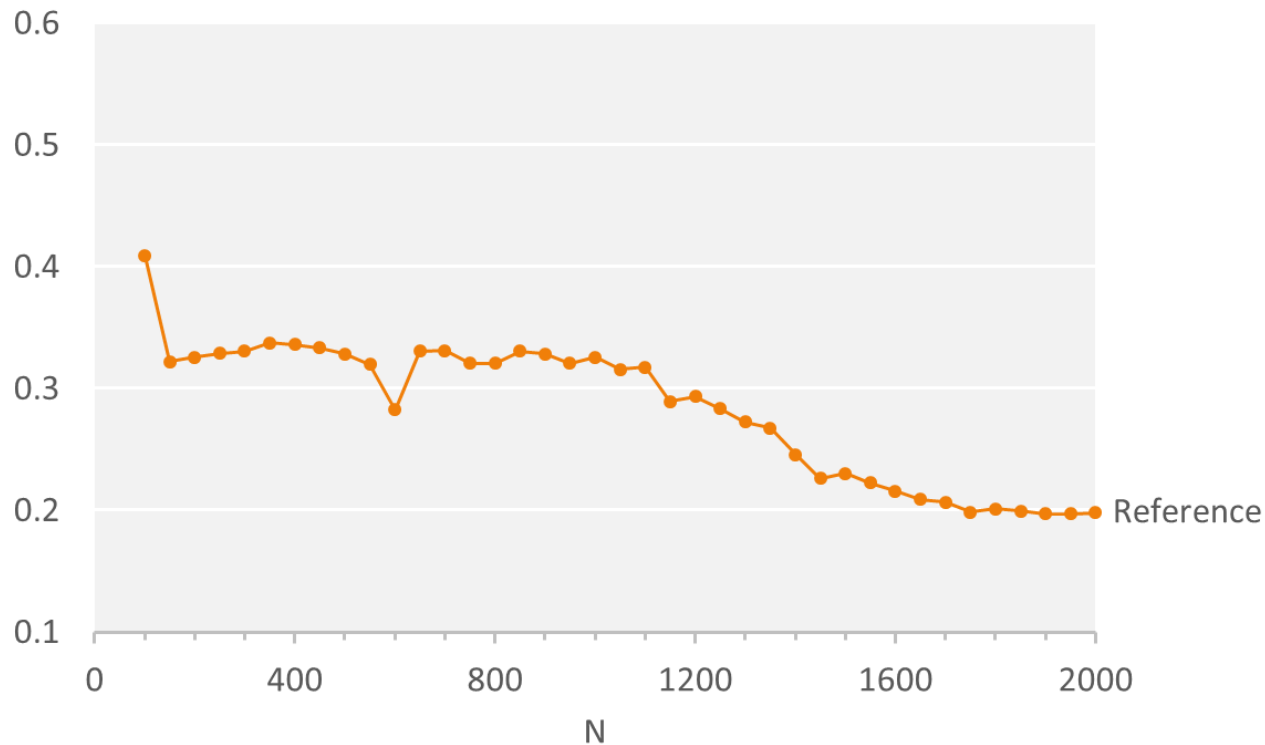
# Reference Implementation



# Reference Implementation

## Scalar Performance

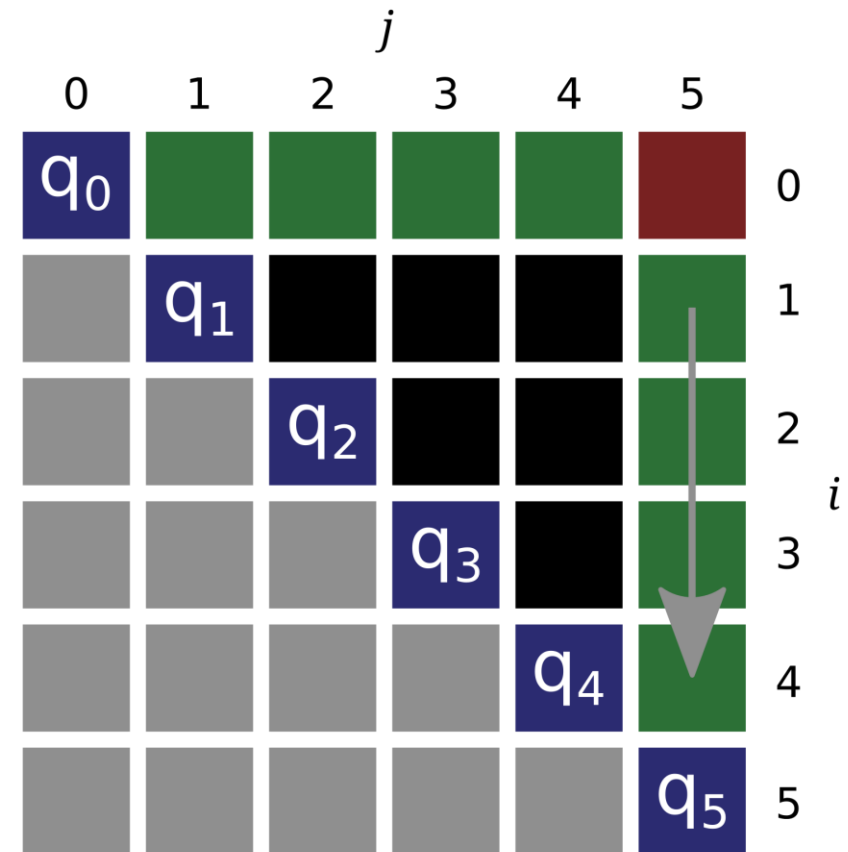
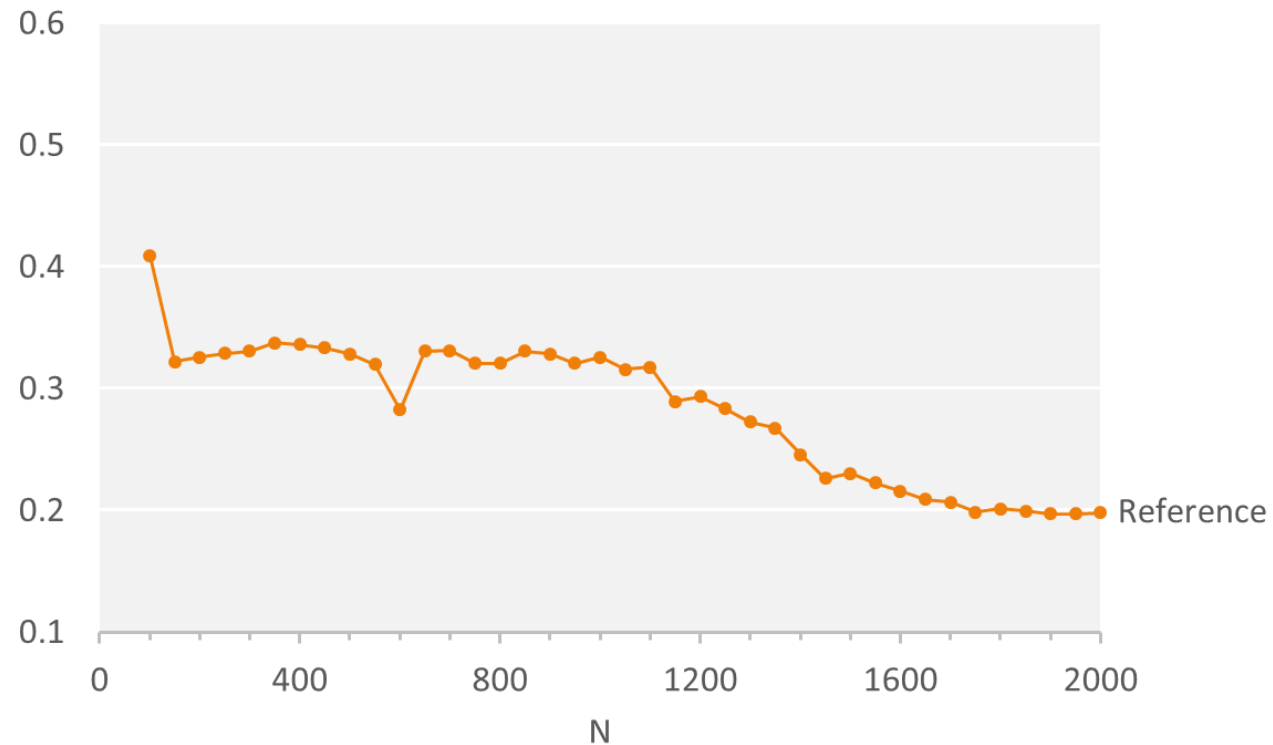
[flops/cycle]



# Reference Issues

## Scalar Performance

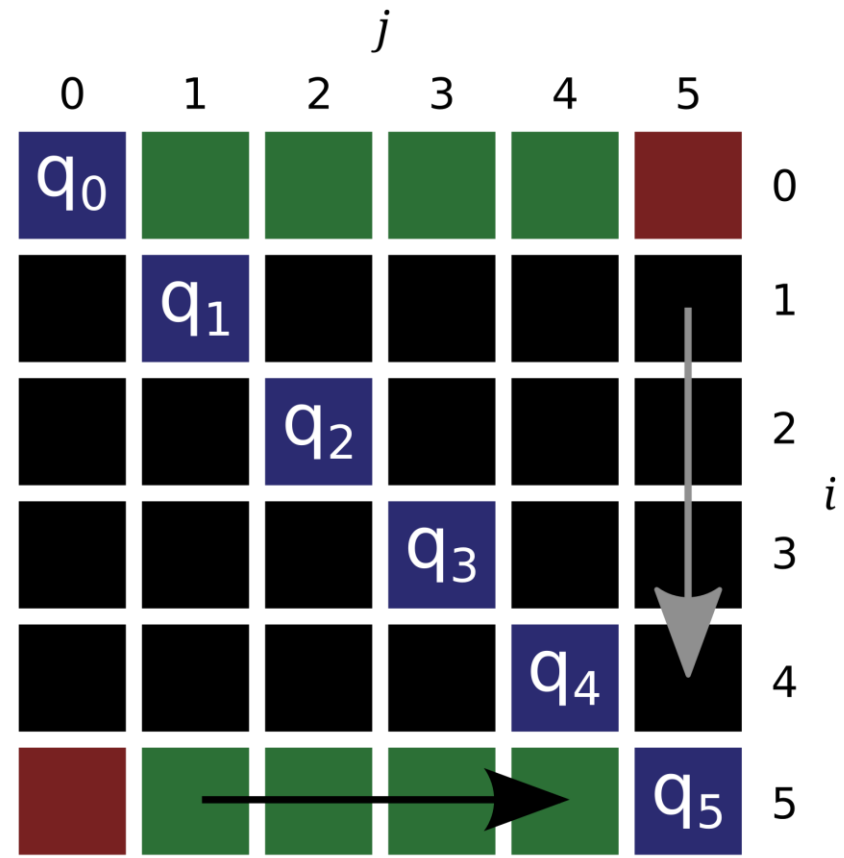
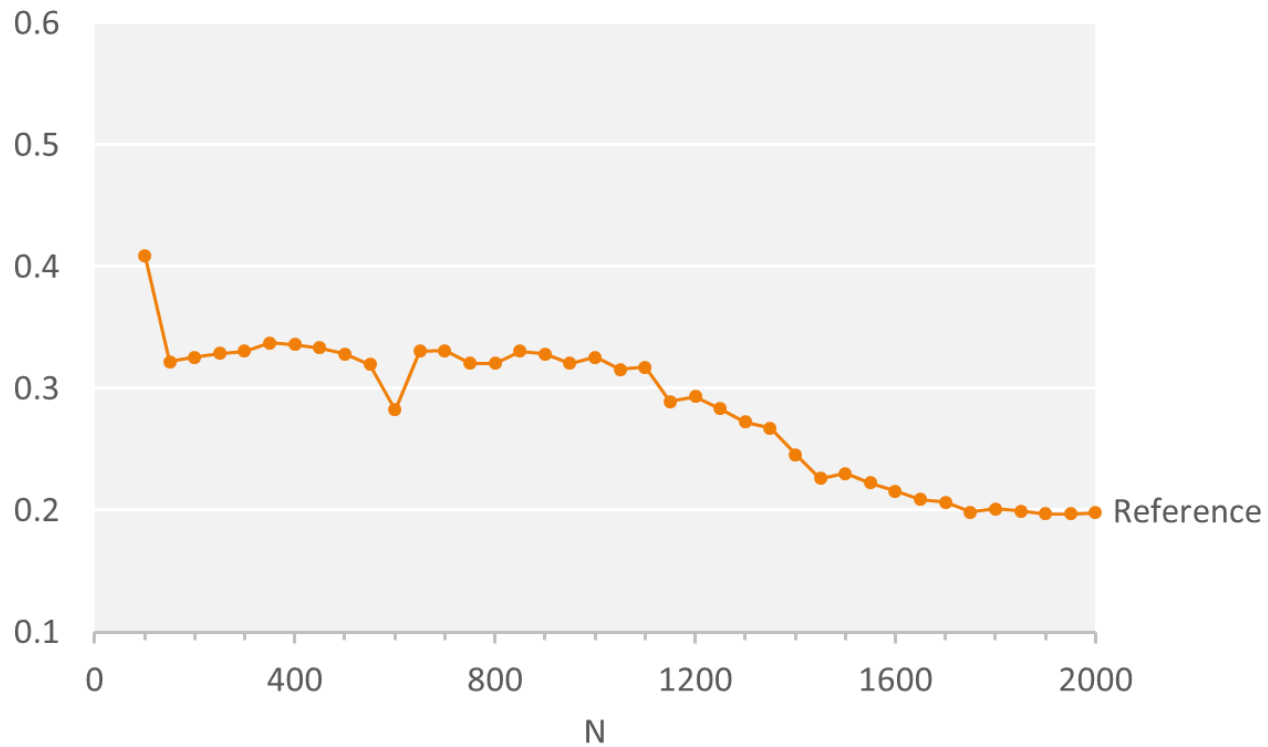
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# Transposed

## Scalar Performance

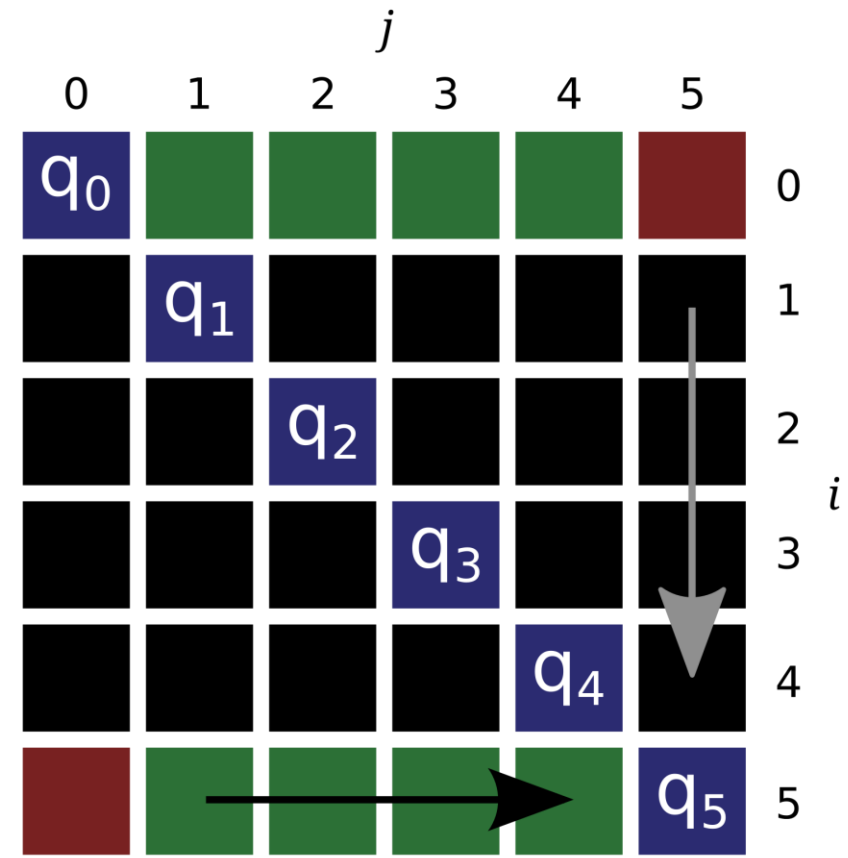
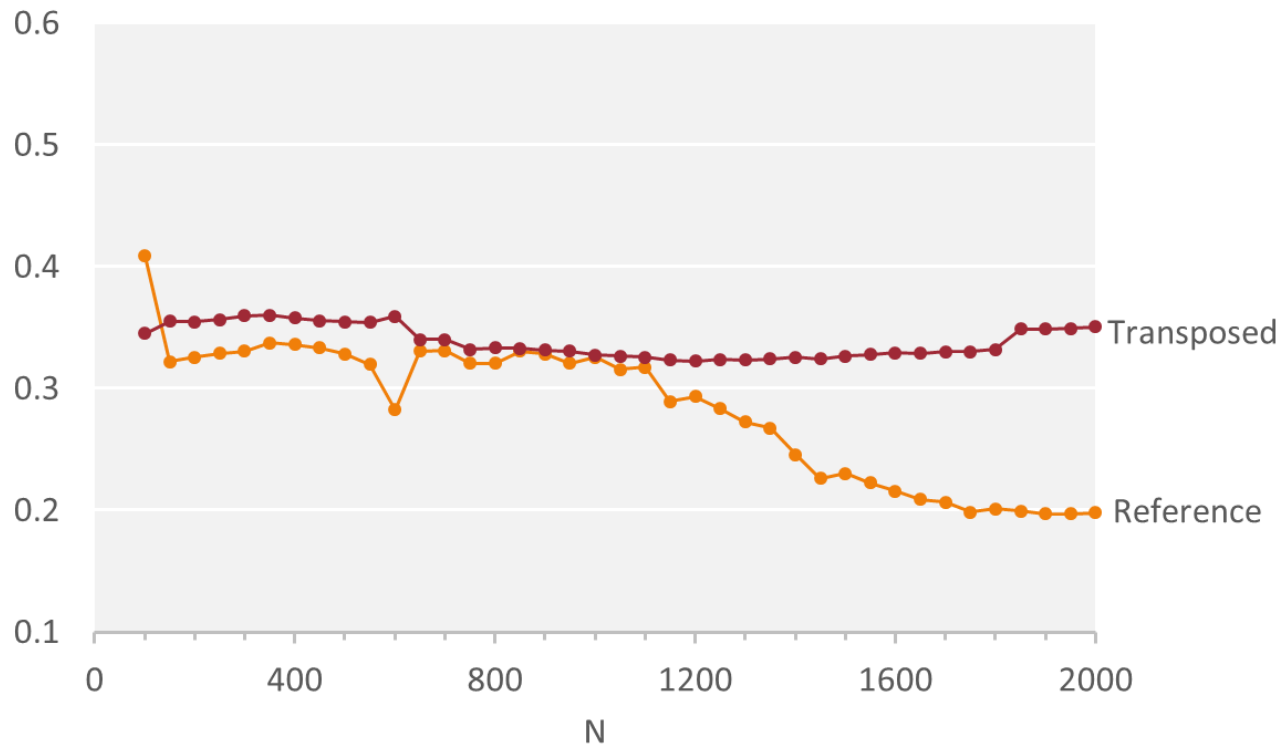
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# Transposed

## Scalar Performance

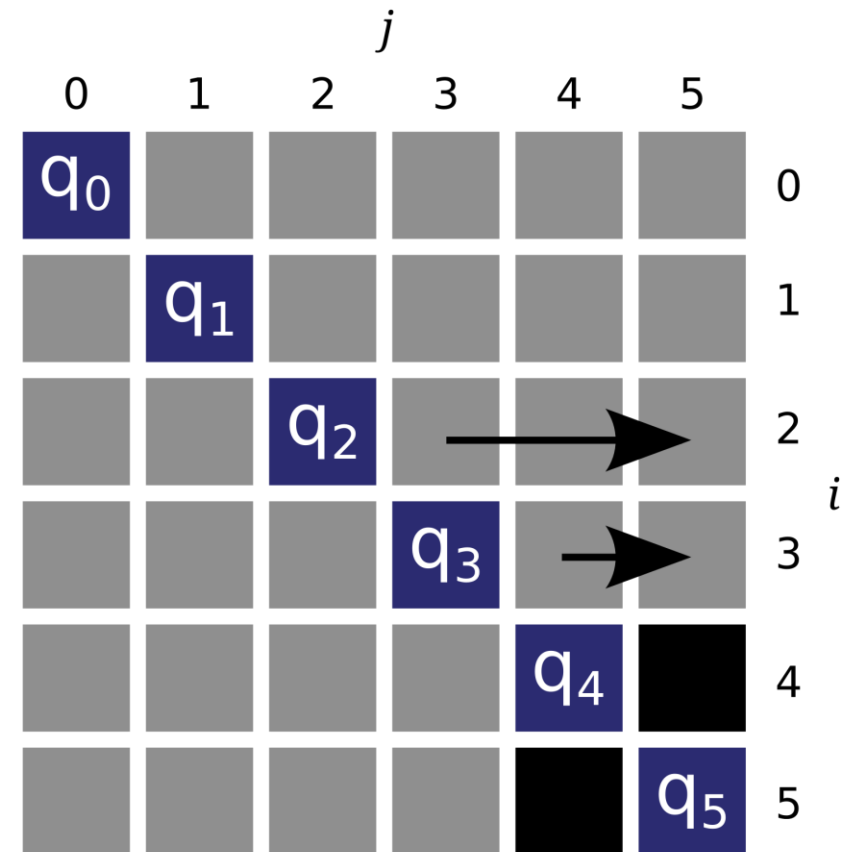
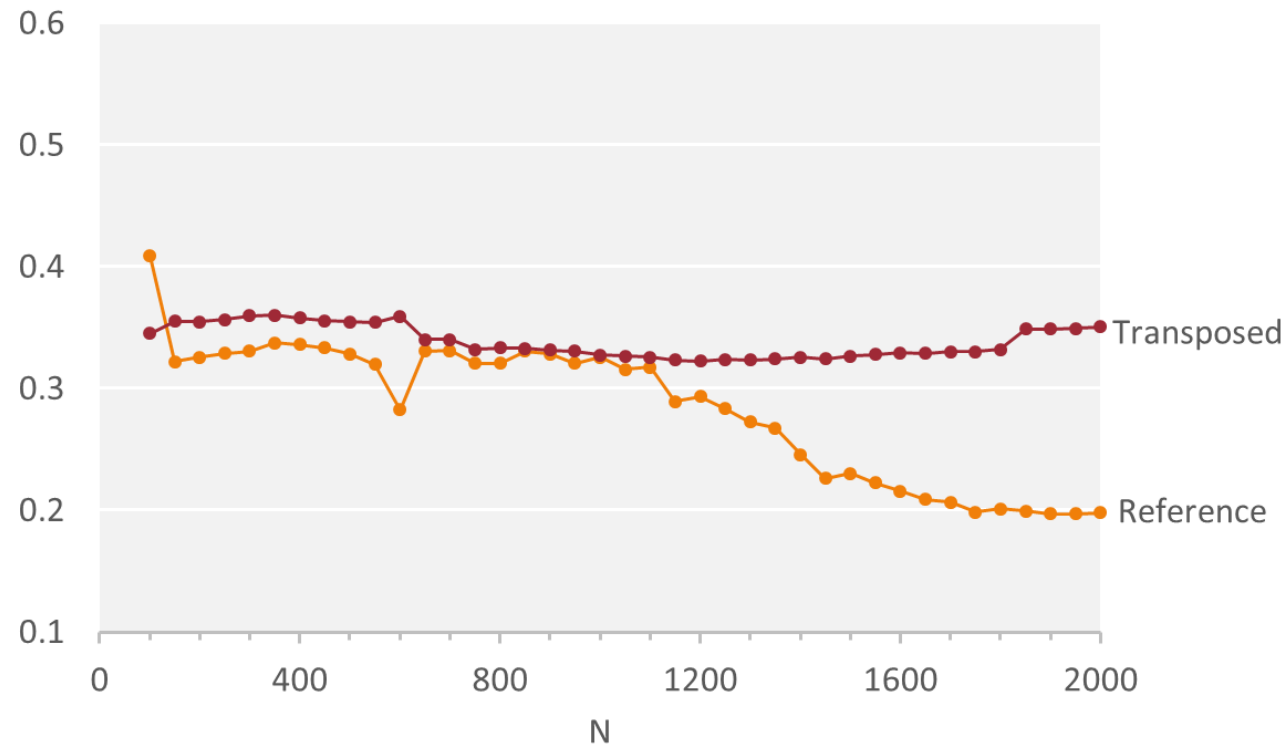
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# Bottom Up

## Scalar Performance

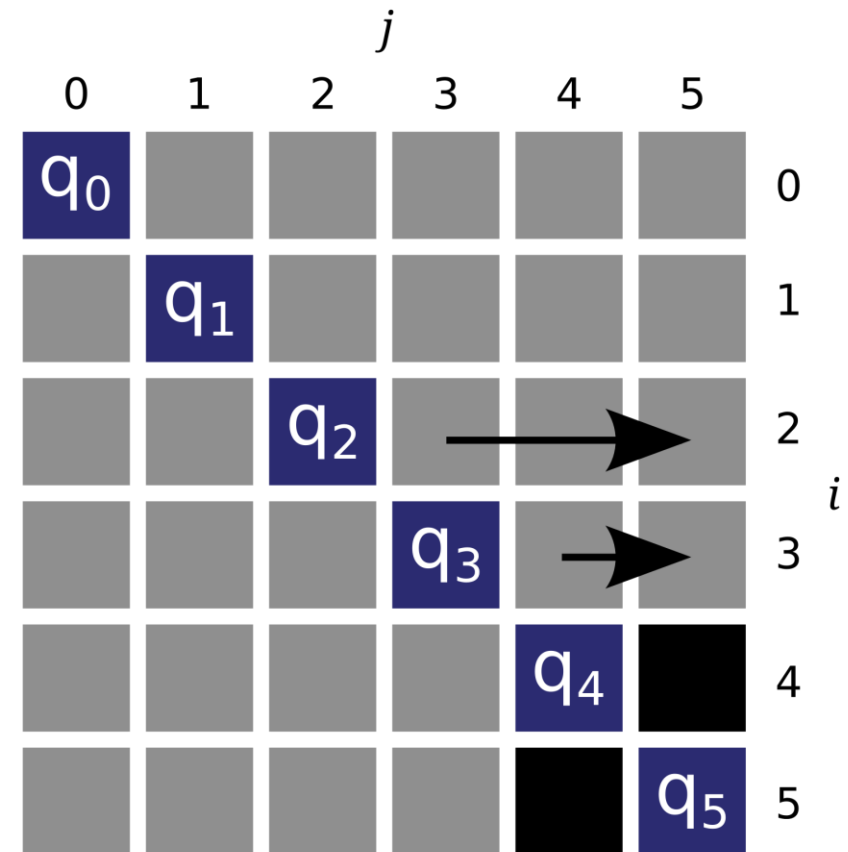
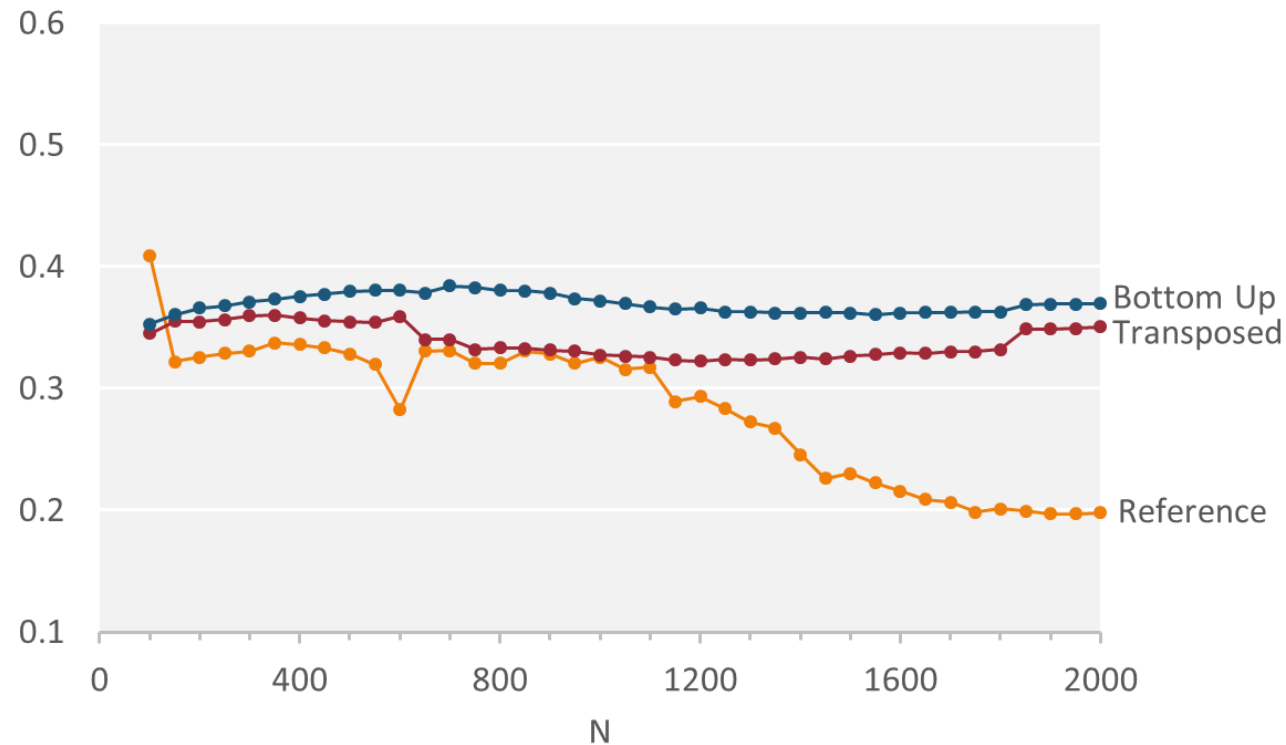
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# Bottom Up

## Scalar Performance

[flops/cycle]

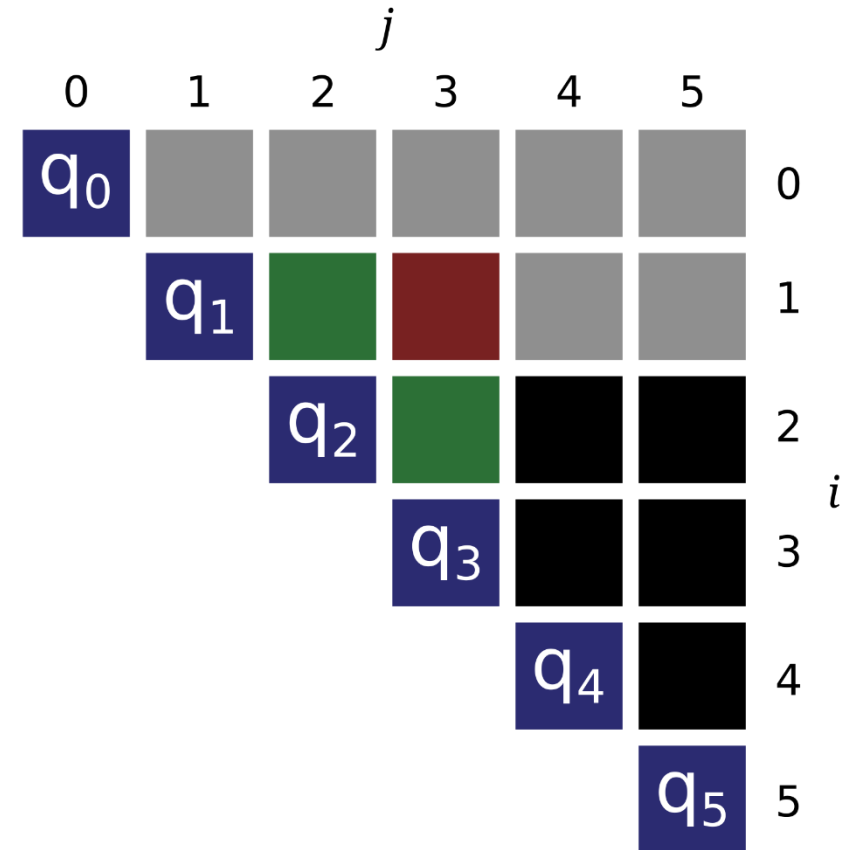
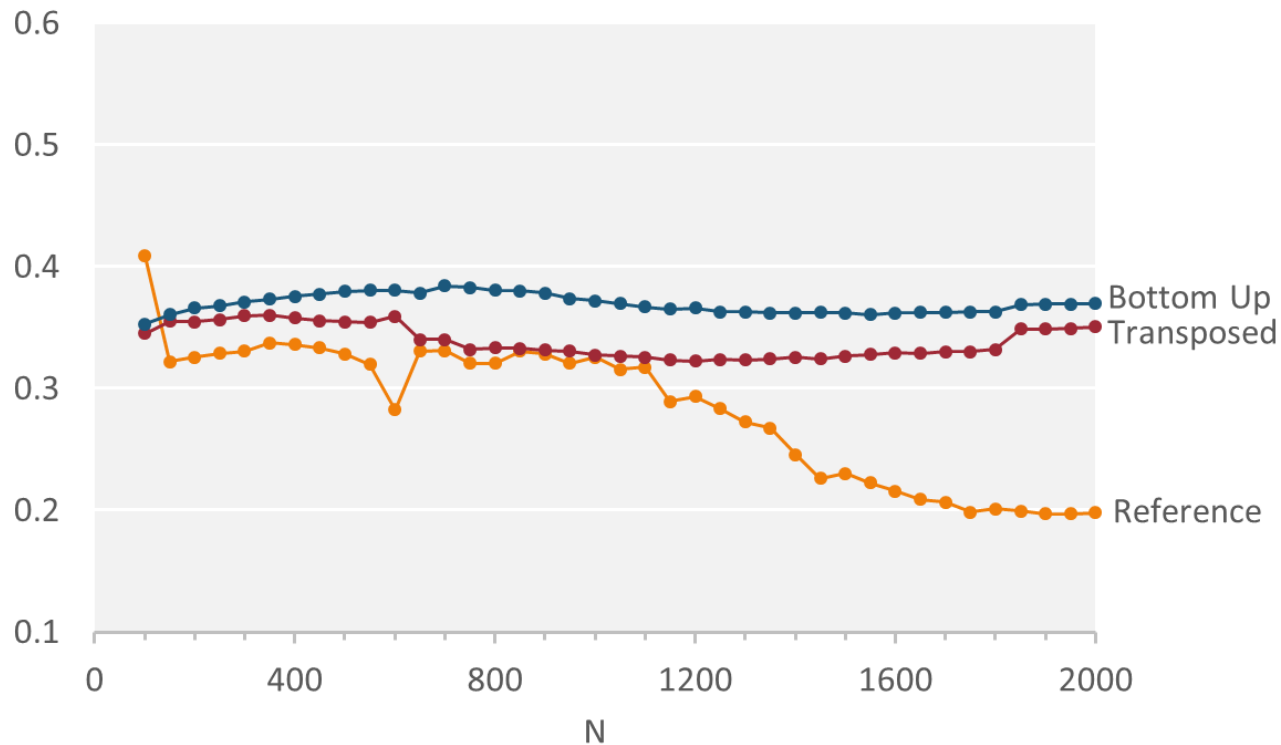




# Swap Loops: Triangle

## Scalar Performance

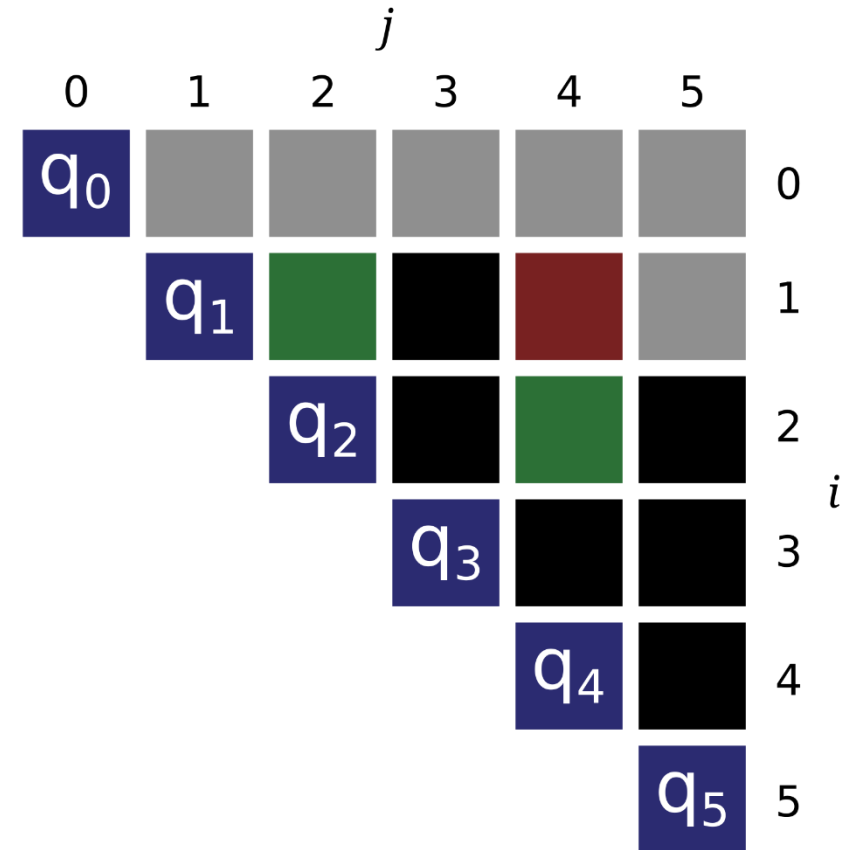
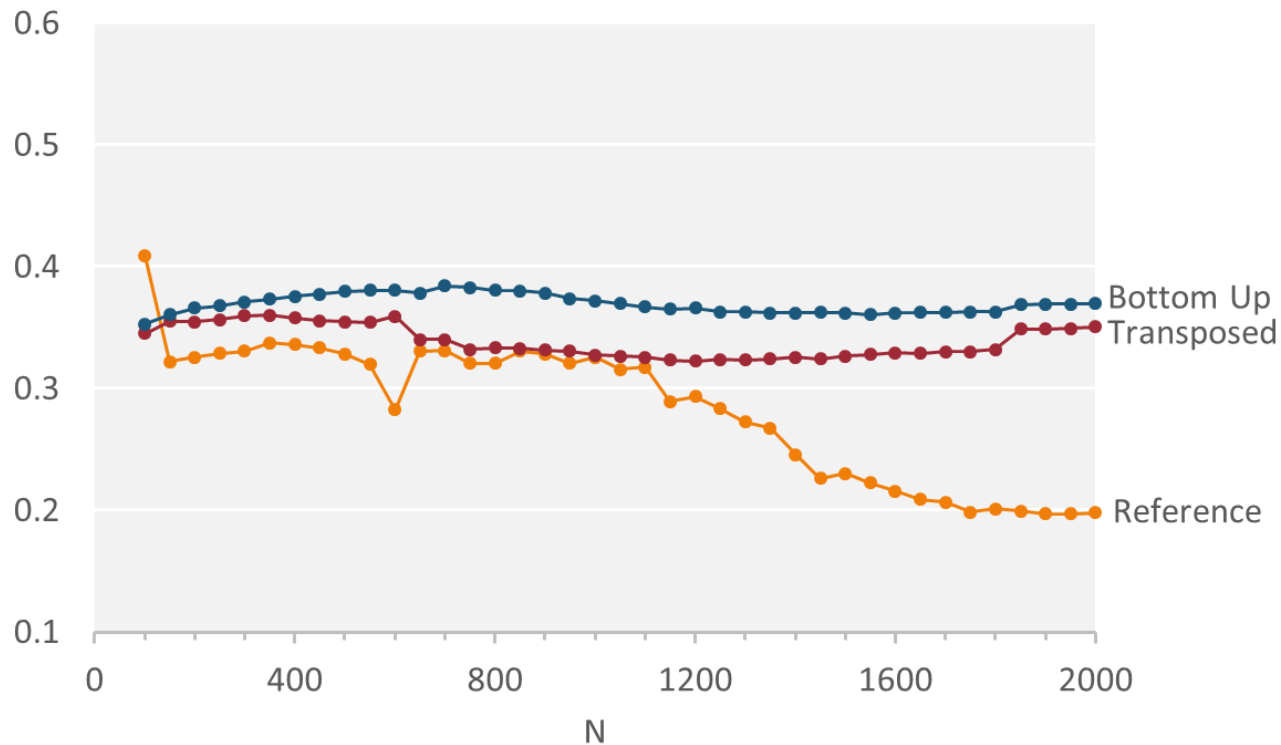
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# Swap Loops: Triangle

## Scalar Performance

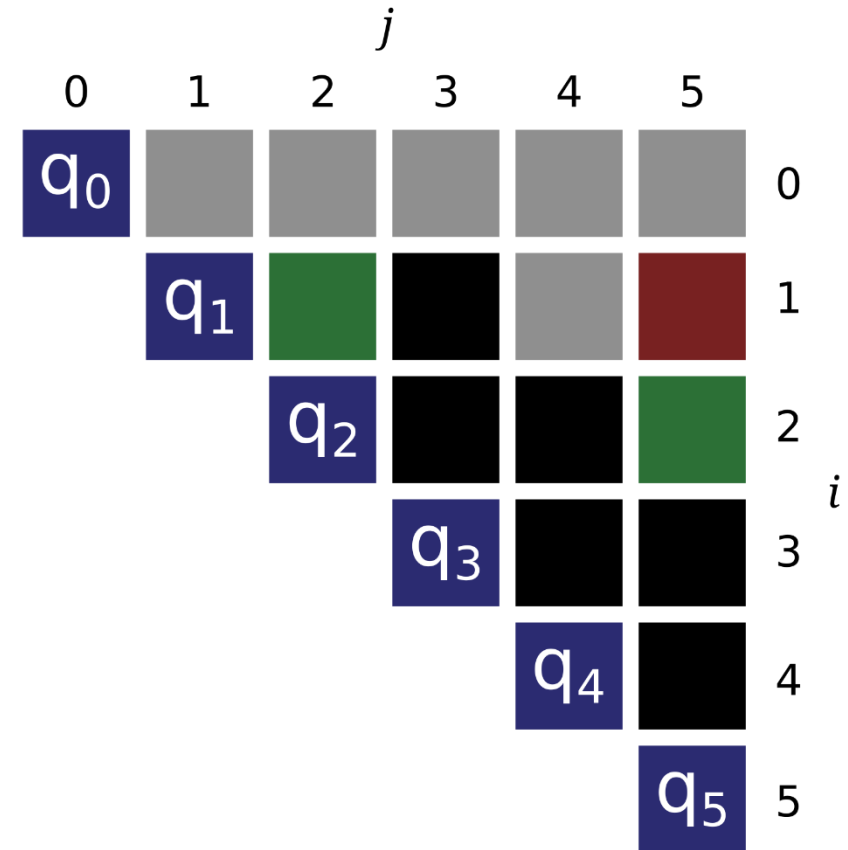
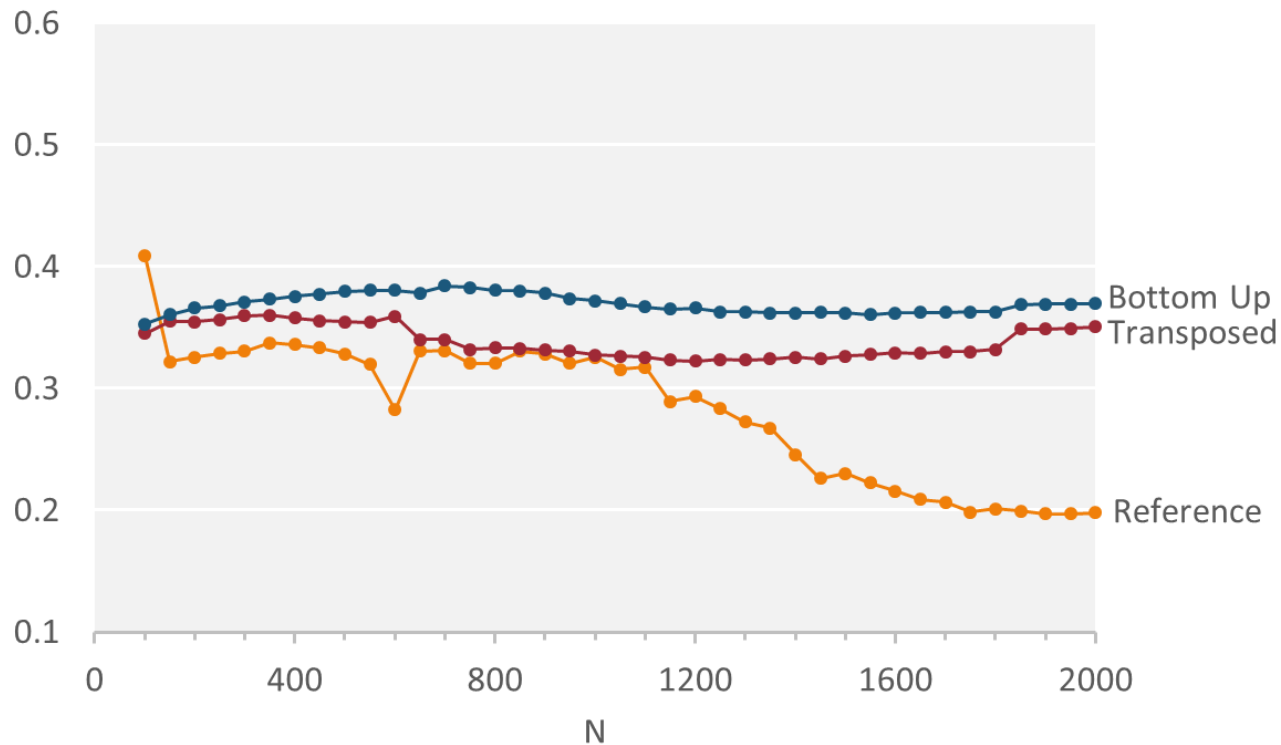
[flops/cycle]



# Swap Loops: Triangle

## Scalar Performance

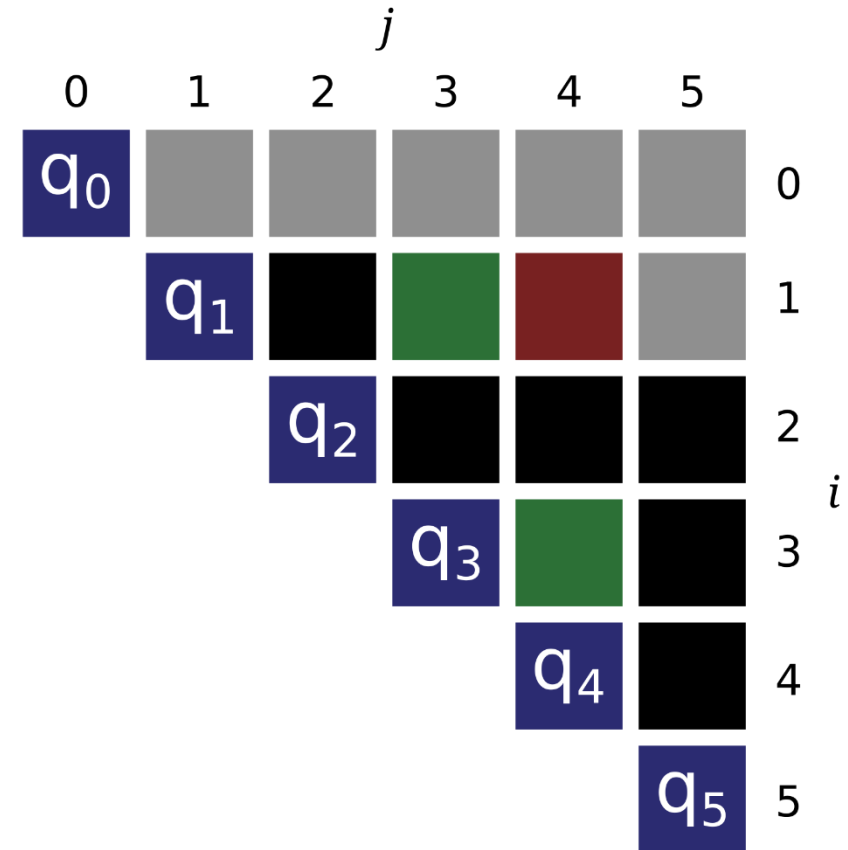
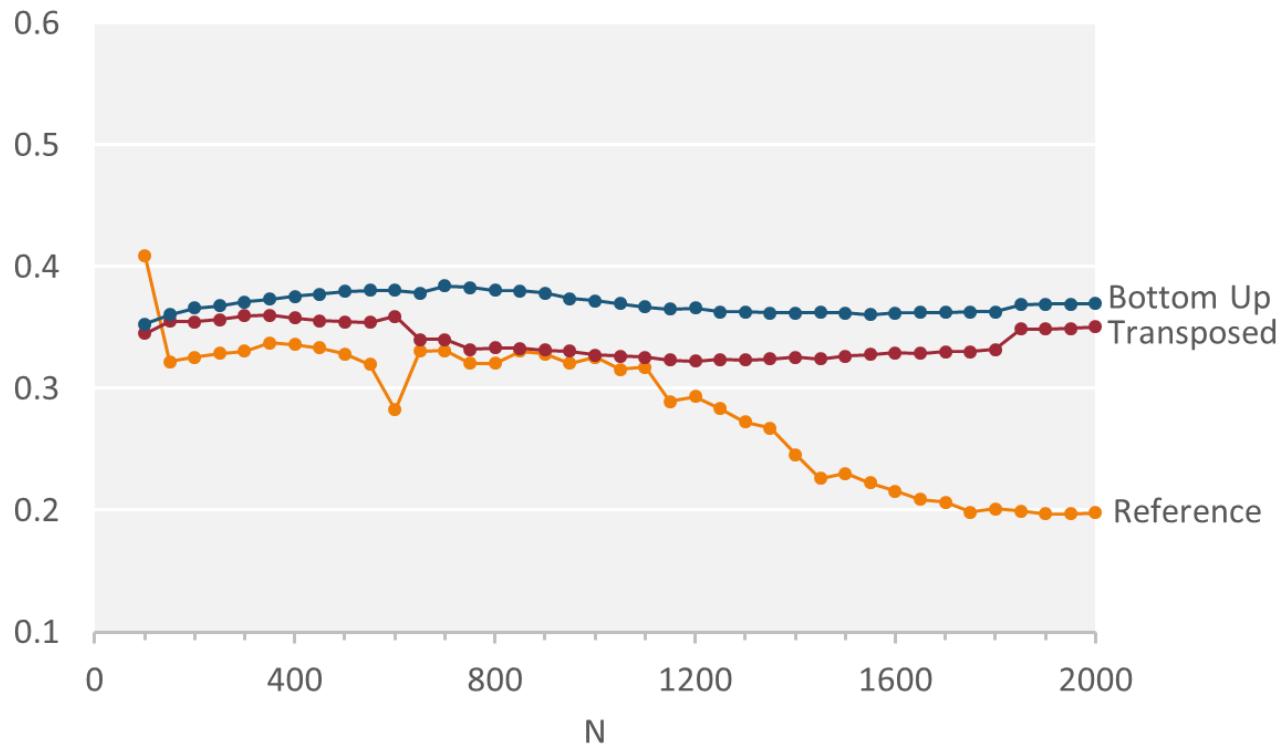
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# Swap Loops: Triangle

## Scalar Performance

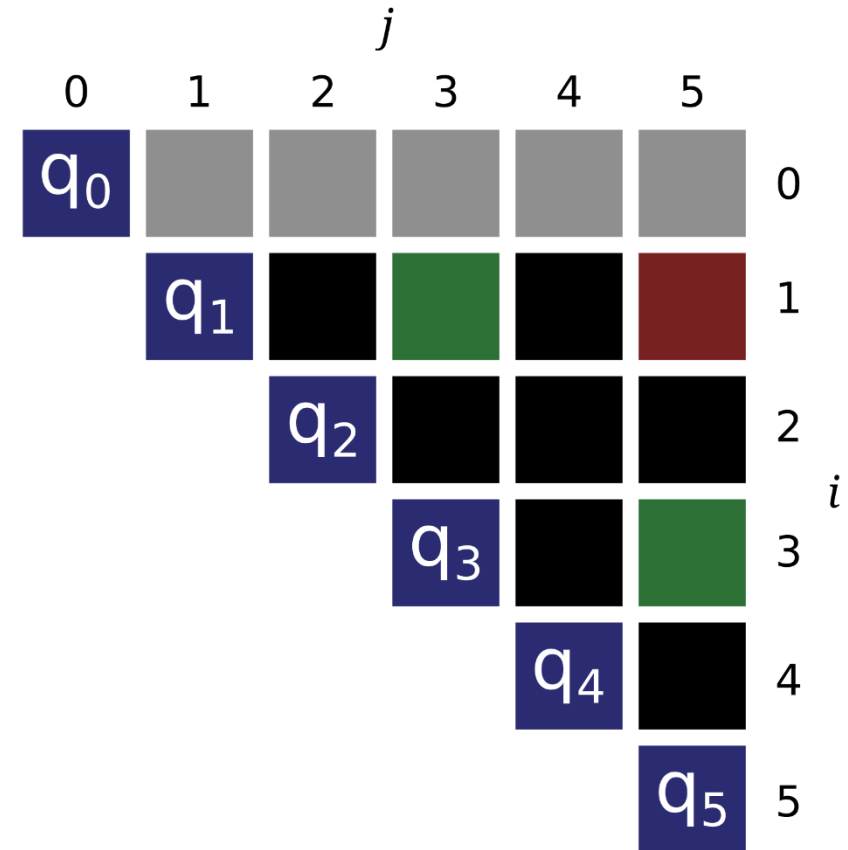
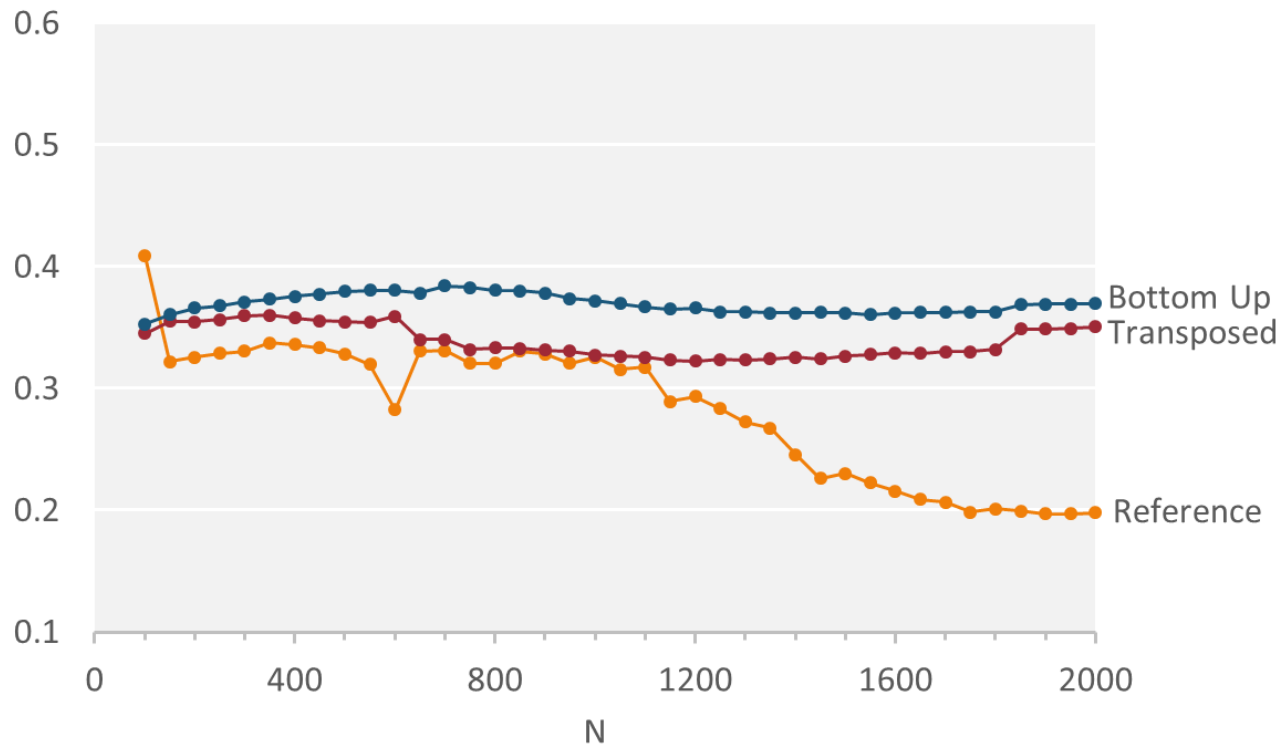
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# Swap Loops: Triangle

## Scalar Performance

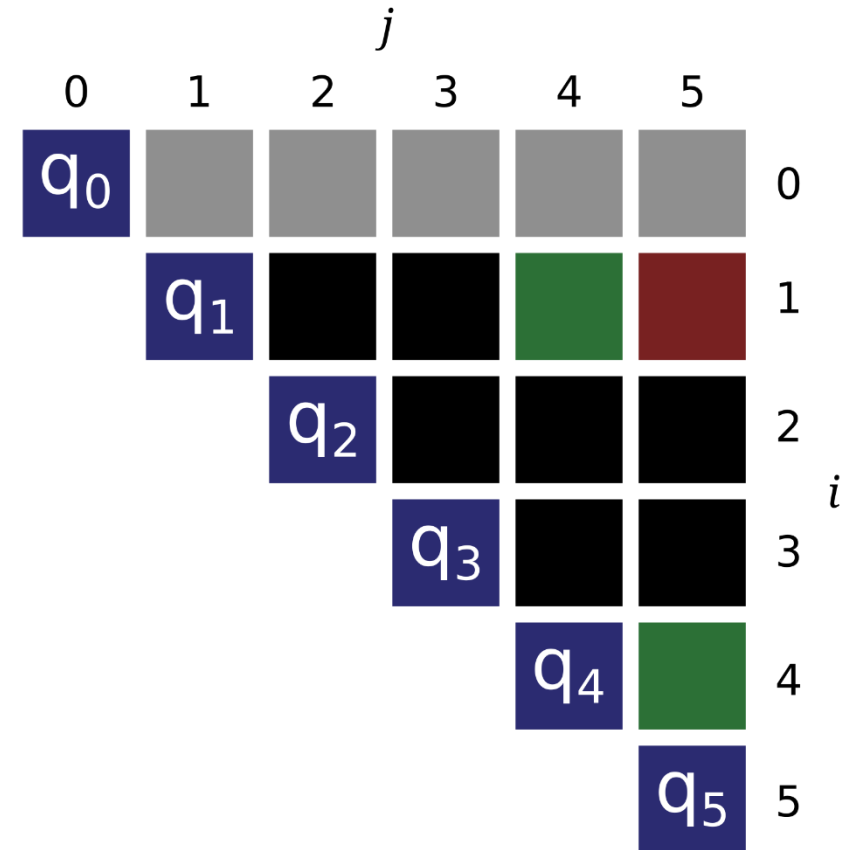
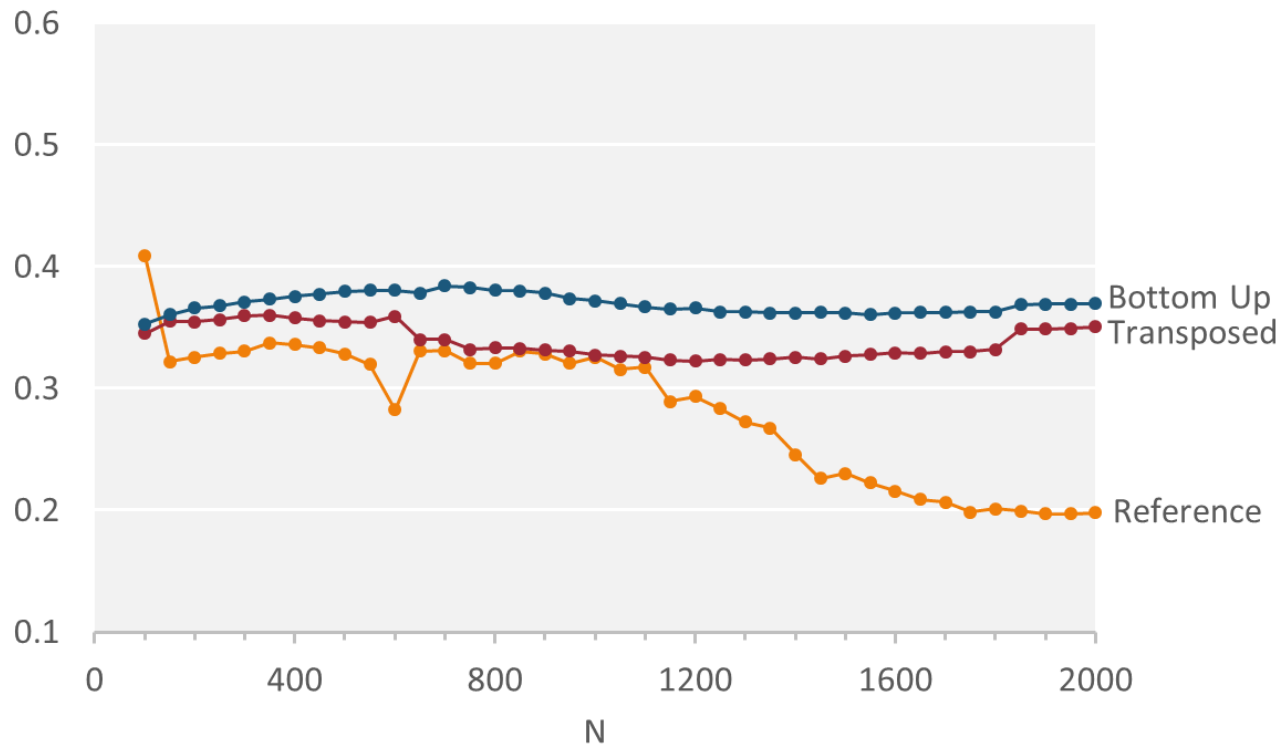
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# Swap Loops: Triangle

## Scalar Performance

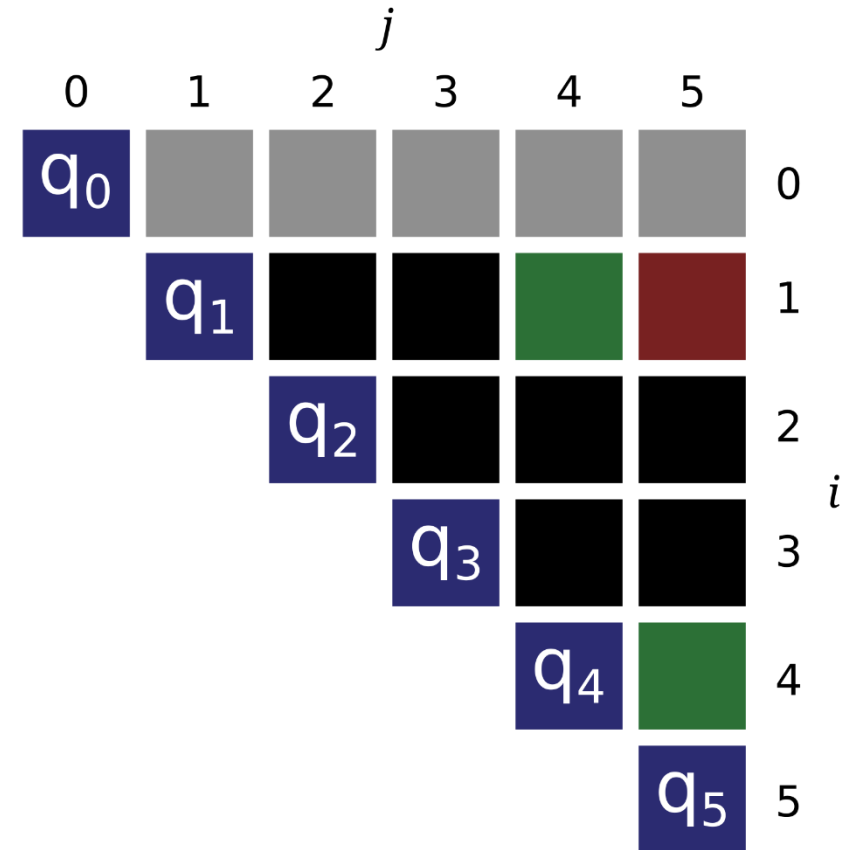
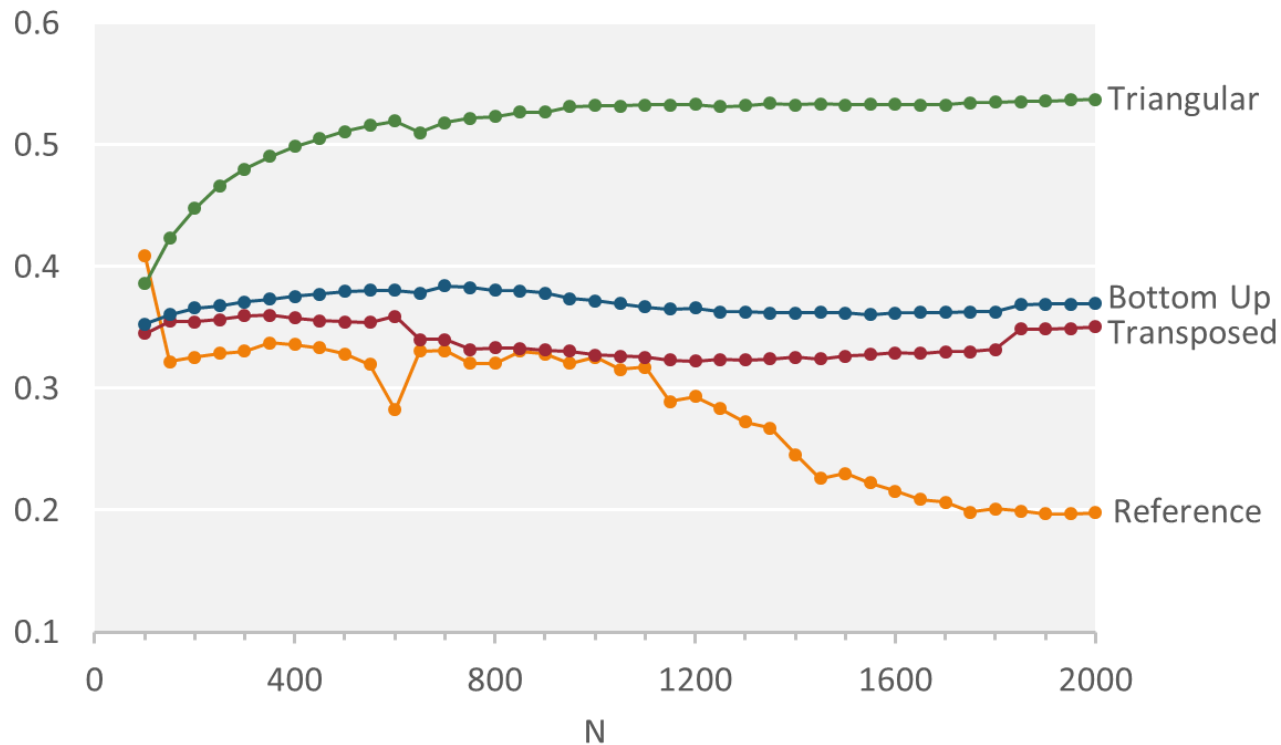
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# Swap Loops: Triangle

## Scalar Performance

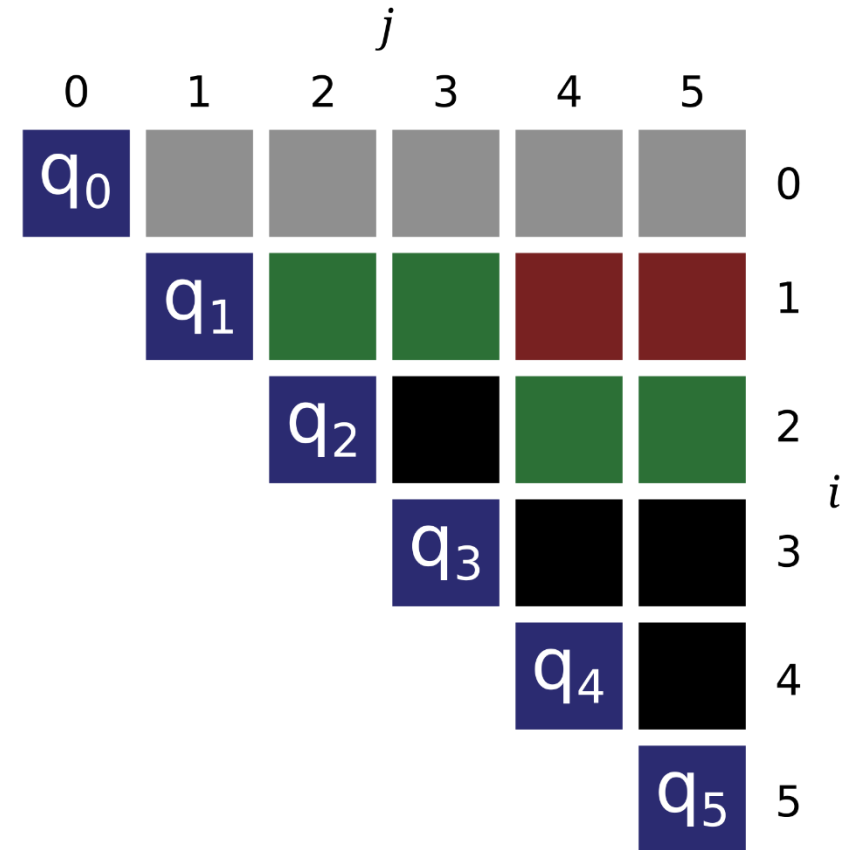
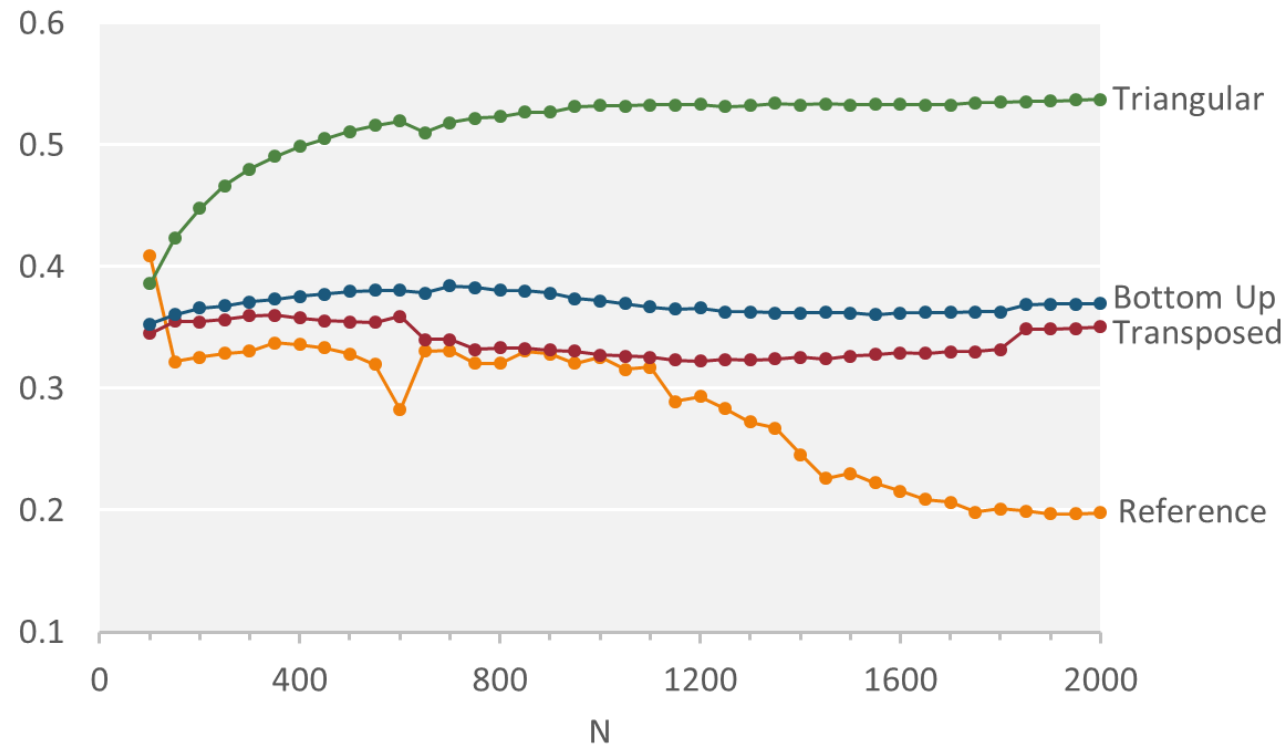
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# Blocking

## Scalar Performance

[flops/cycle]

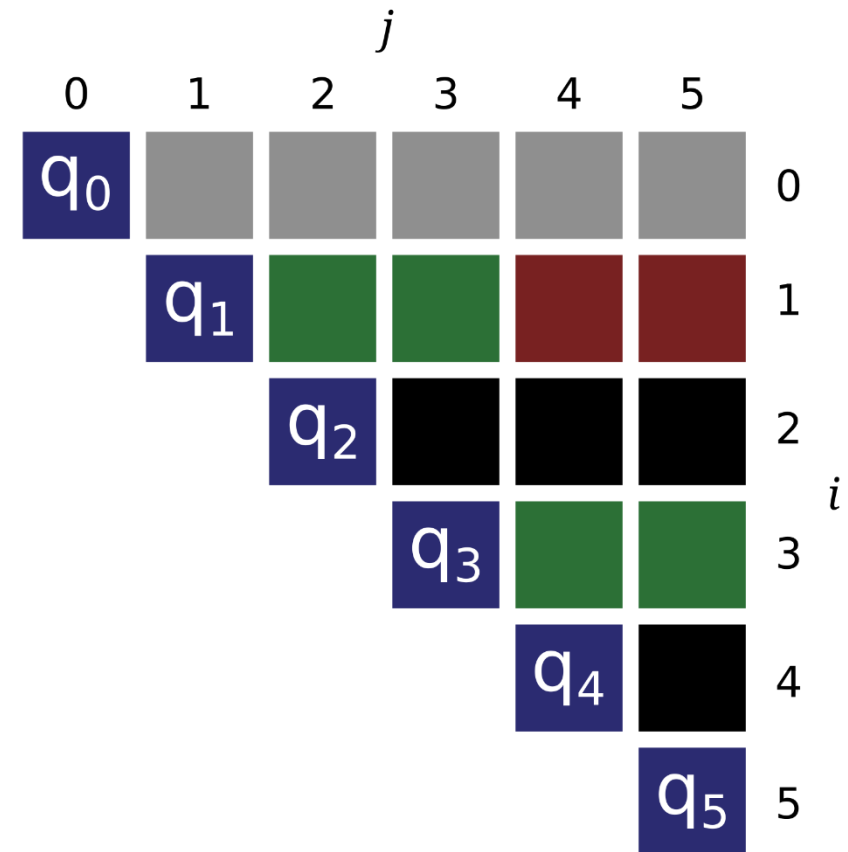
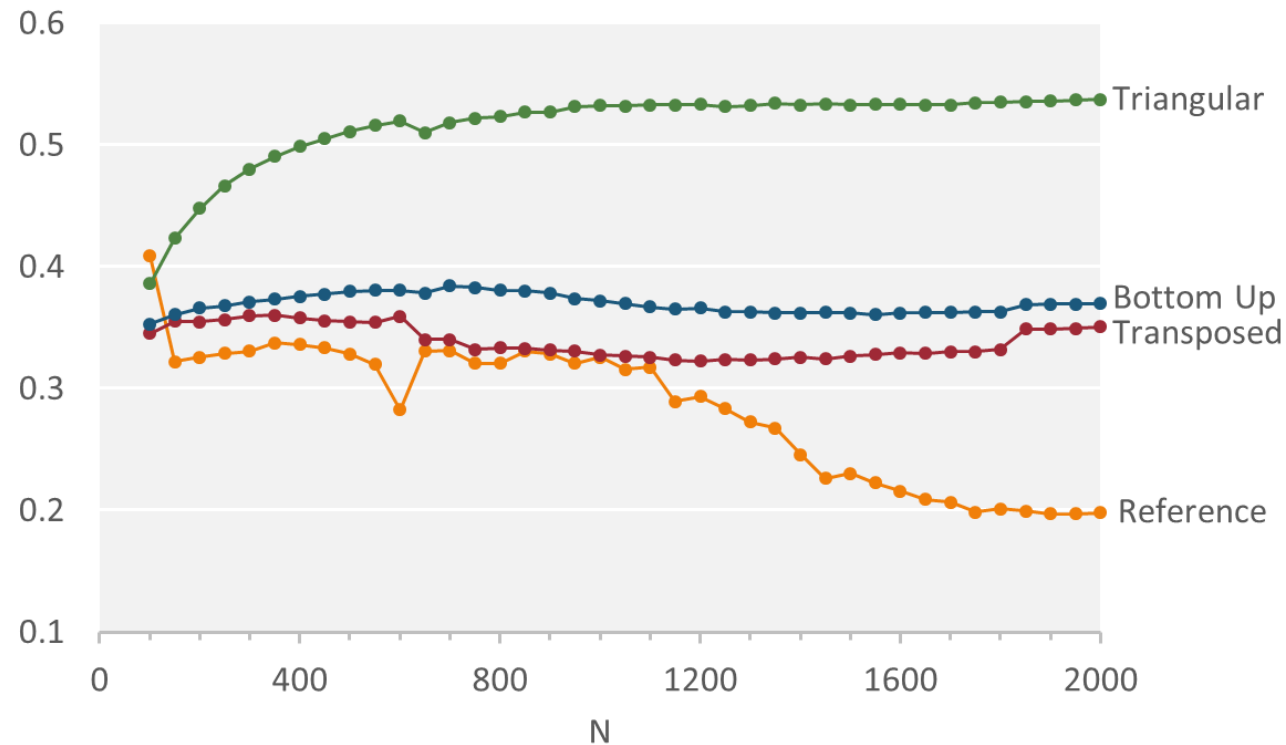




# Blocking

## Scalar Performance

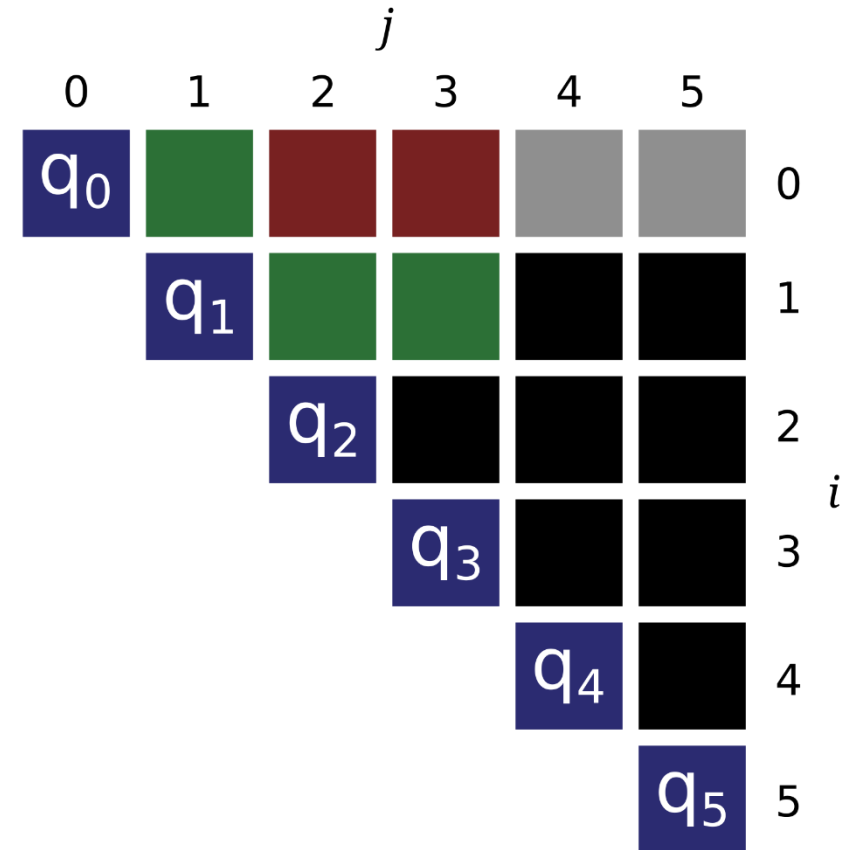
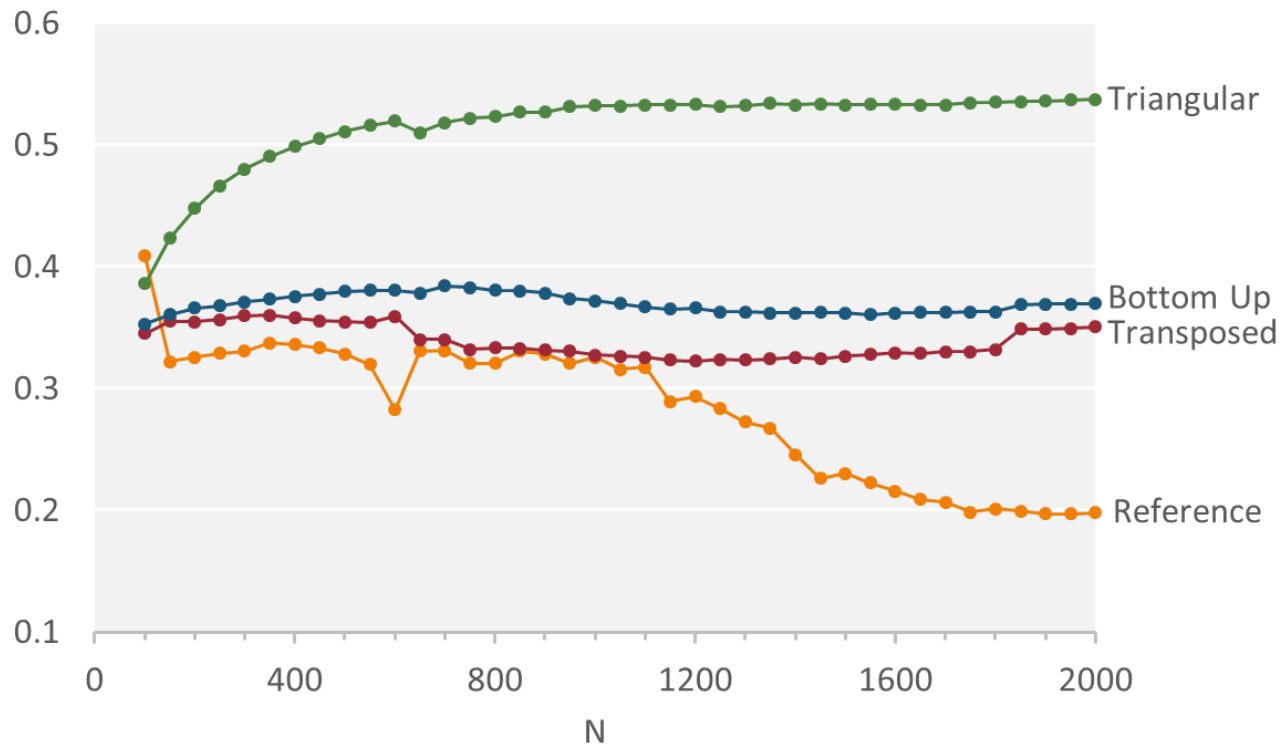
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# Vectorization

## Scalar Performance

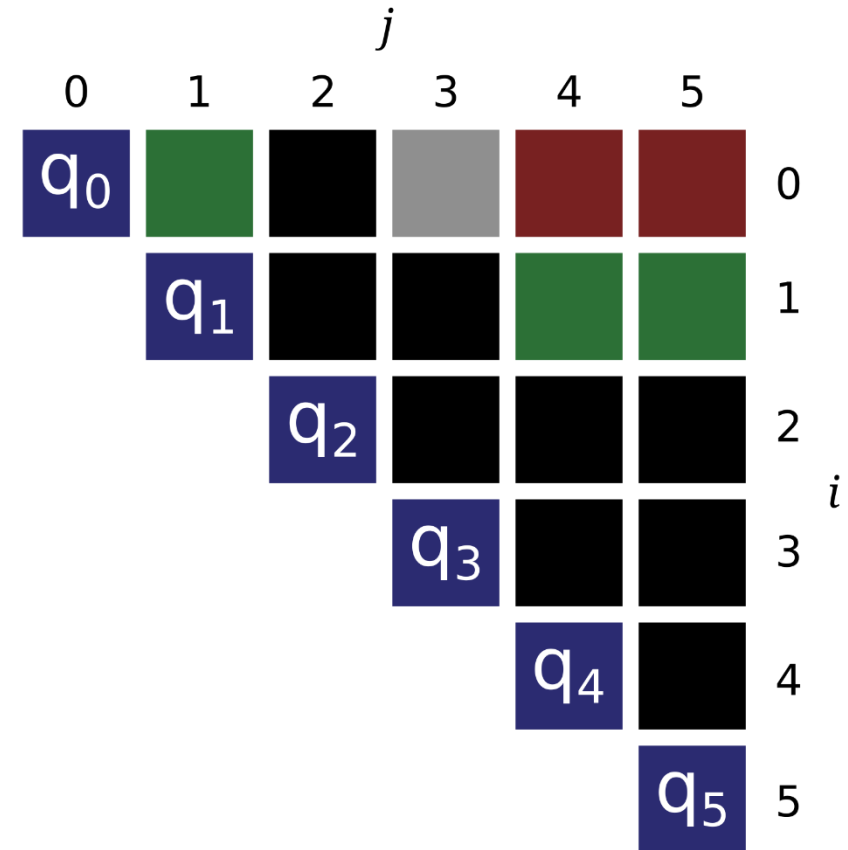
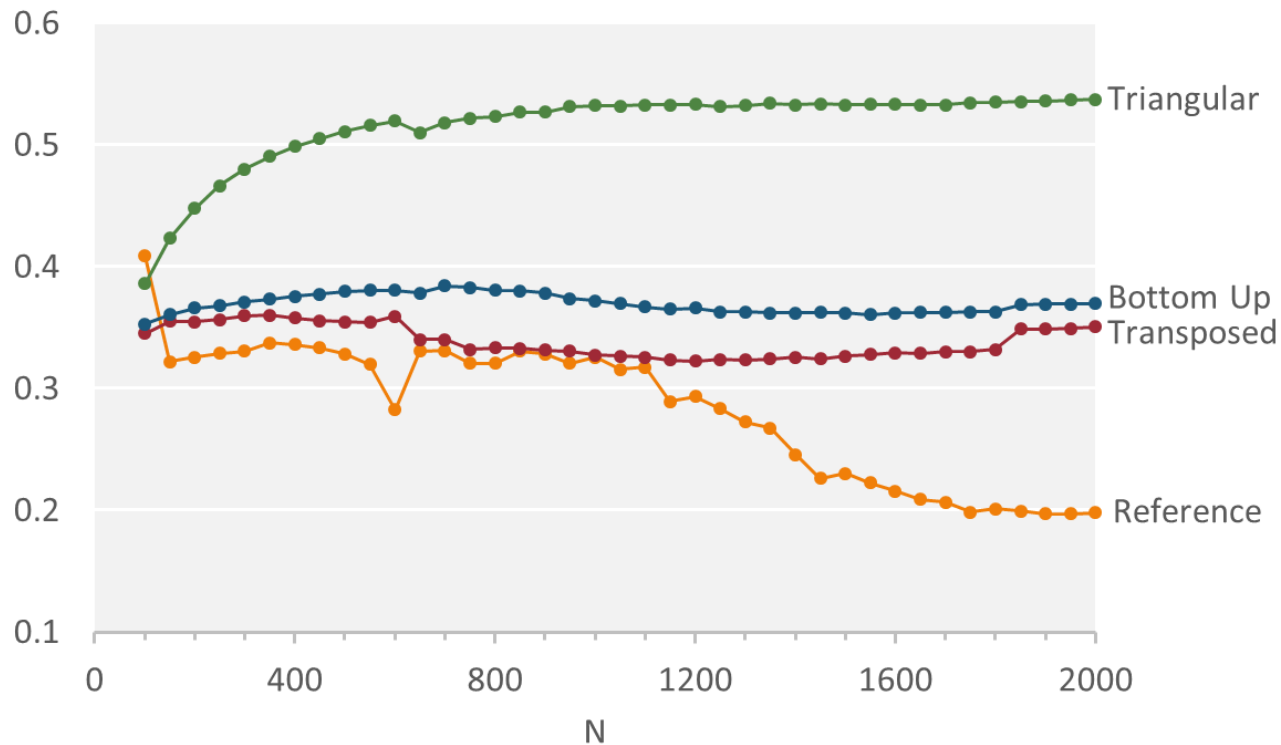
[flops/cycle]



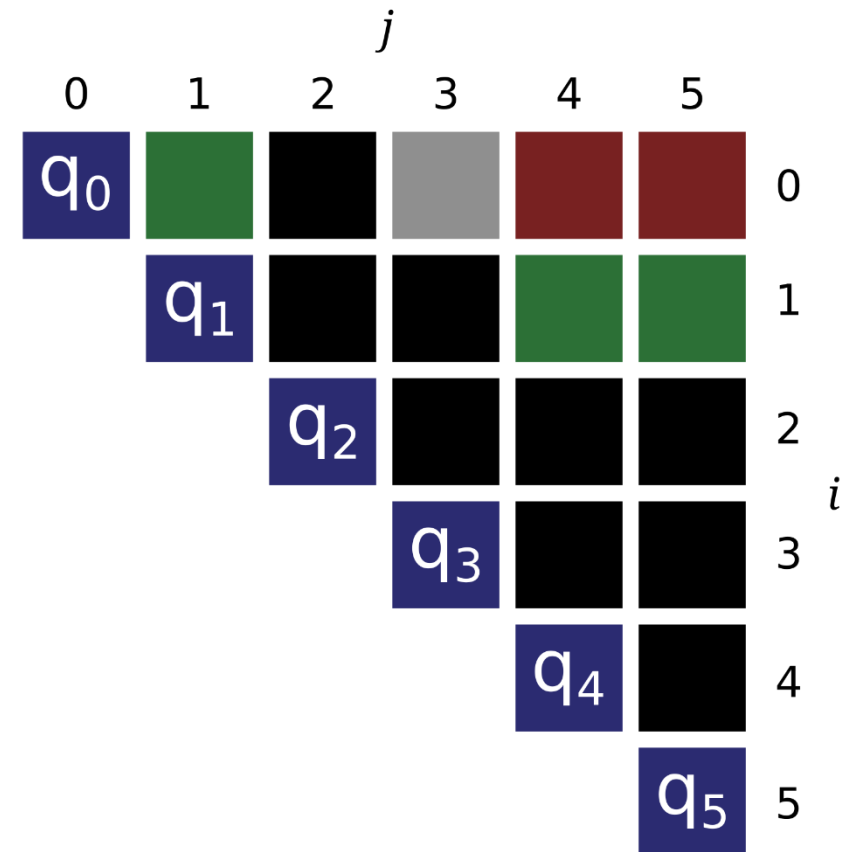
# Vectorization

## Scalar Performance

[flops/cycle]



# Vectorization



# Vectorization Issues: Scheduling

## Standard

`a = load()`

`b = load()`

`c = load()`

`d = load()`

`e = add(a,b)`

`f = add(c,d)`

`g = add(e,f)`

`store(g)`

# Vectorization Issues: Scheduling

## Standard

`a = load()`

`b = load()`

`c = load()`

`d = load()`

`e = add(a,b)`

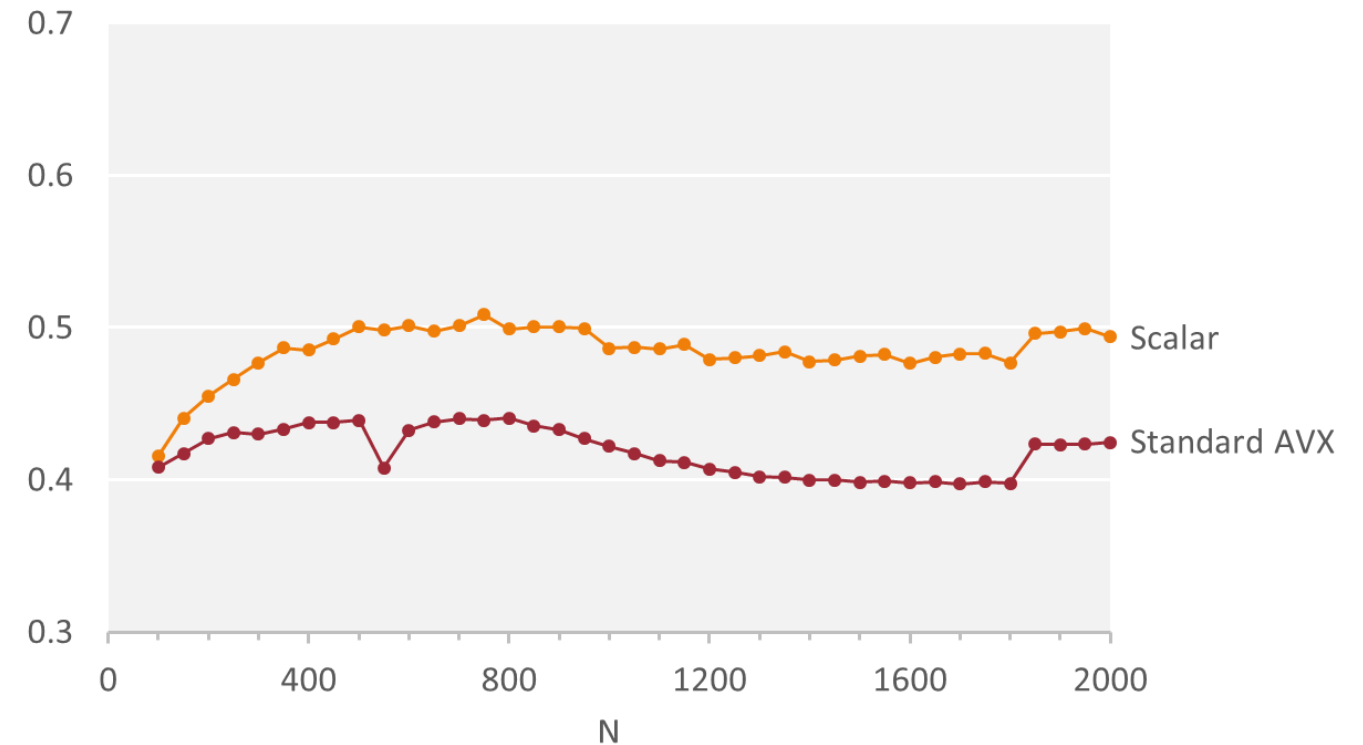
`f = add(c,d)`

`g = add(e,f)`

`store(g)`

## Scalar and AVX Performance

[flops/cycle]



# Vectorization Issues: Scheduling

## Standard

```
a = load()  
b = load()  
c = load()  
d = load()
```

```
e = add(a,b)  
f = add(c,d)  
g = add(e,f)
```

```
store(g)
```

## Rescheduled

```
a = load()  
b = load()  
e = add(a,b)  
  
c = load()  
d = load()
```

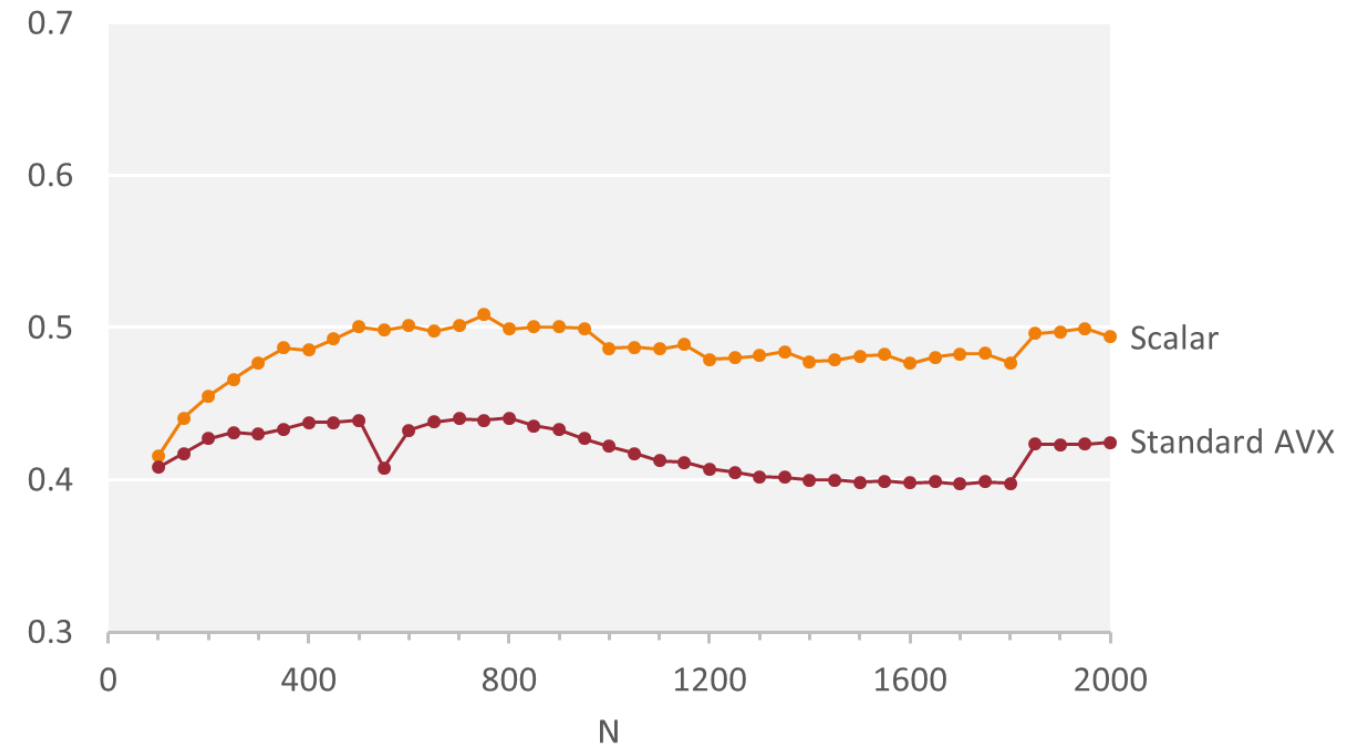
```
f = add(c,d)
```

```
g = add(e,f)
```

```
store(g)
```

## Scalar and AVX Performance

[flops/cycle]



# Vectorization Issues: Scheduling

## Standard

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a = load()  
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e = add(a,b)  
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```
store(g)
```

## Rescheduled

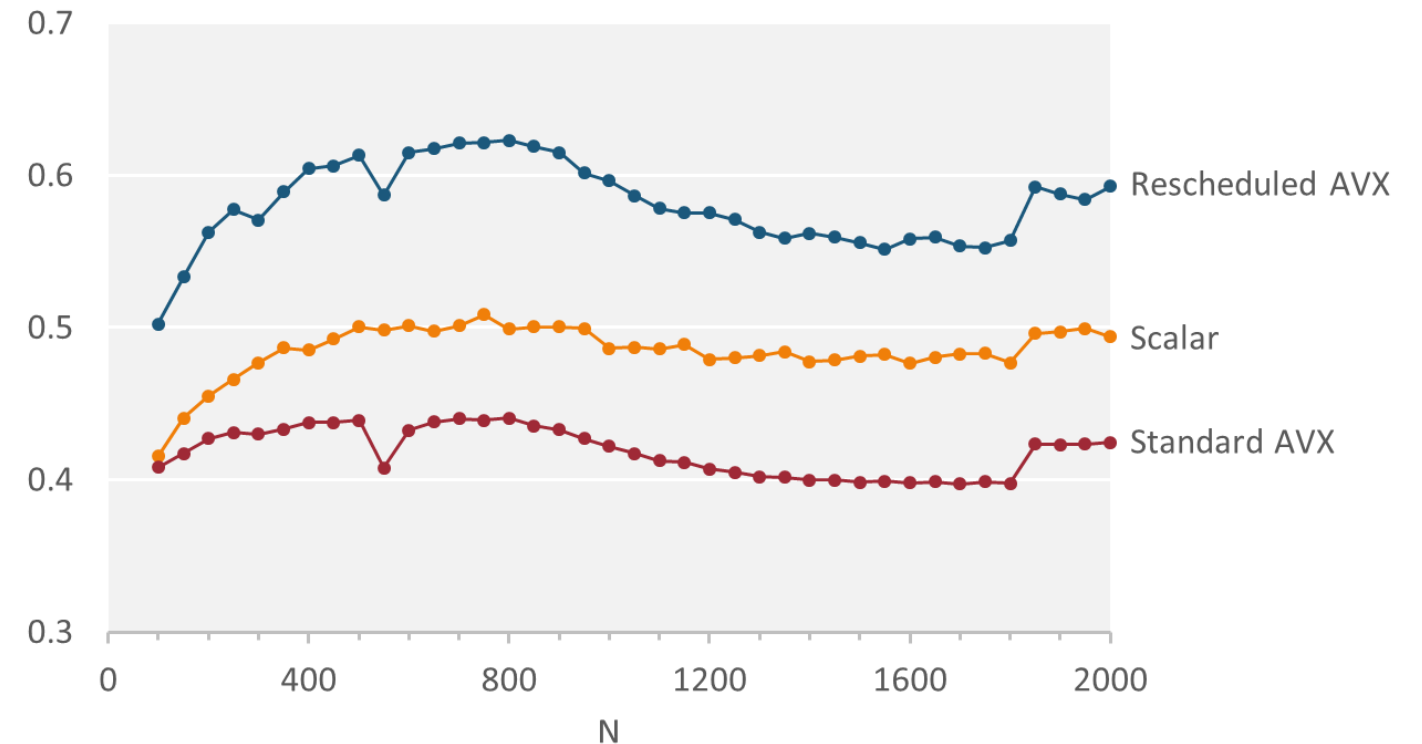
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d = load()  
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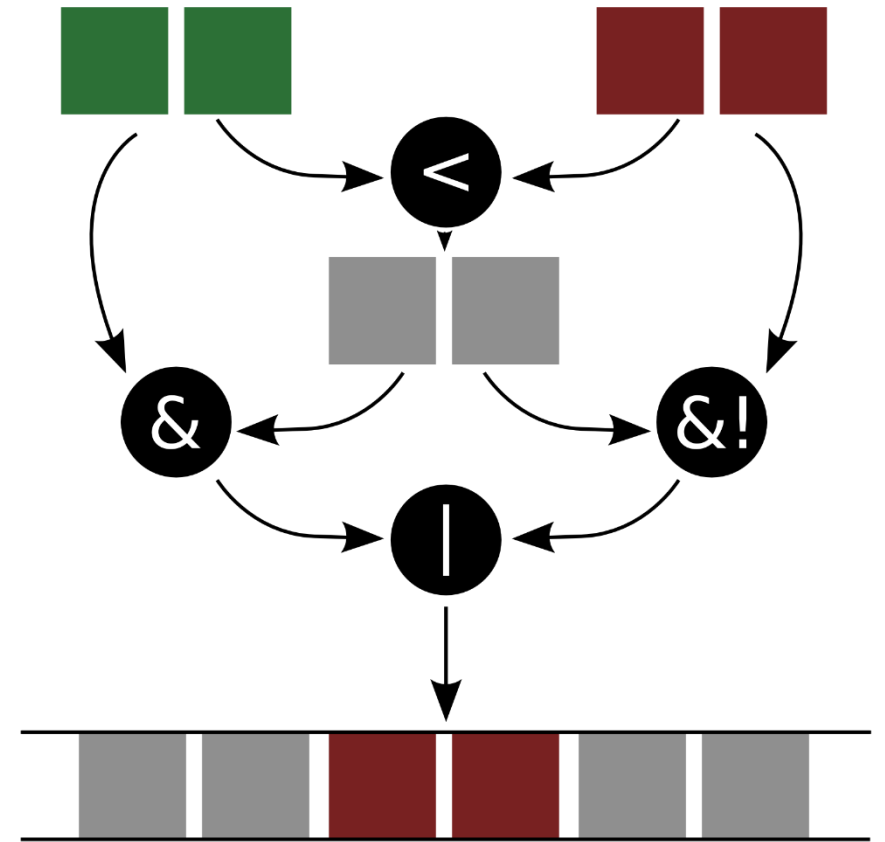
## Scalar and AVX Performance

[flops/cycle]

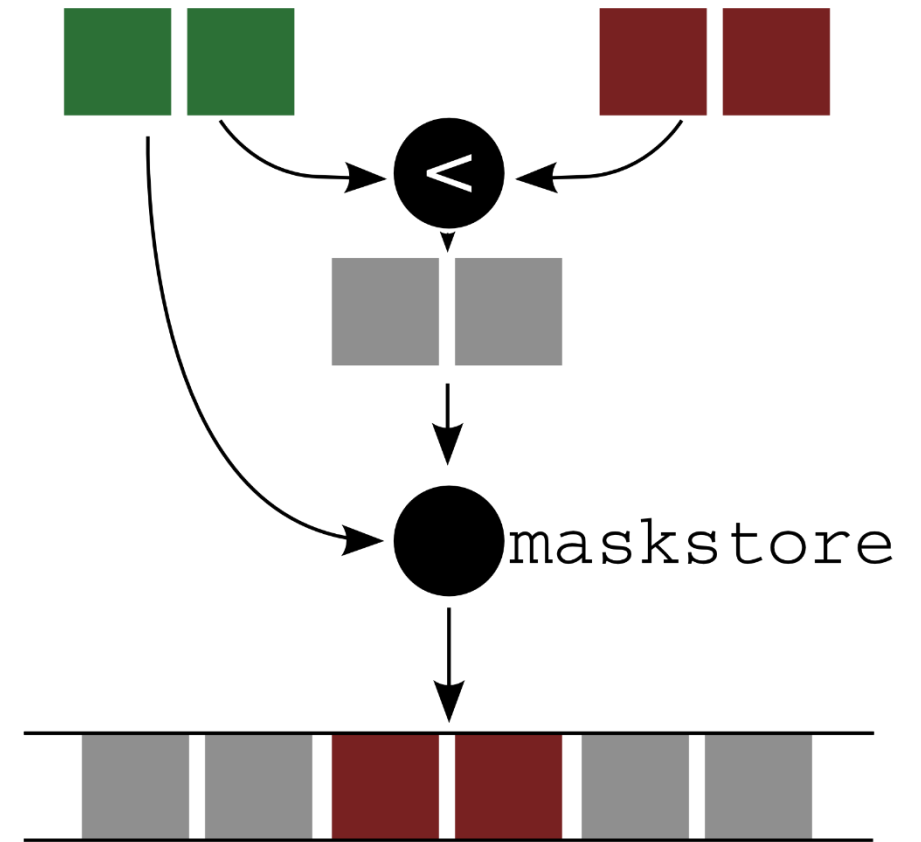




# Vectorization Issues: Maskstore



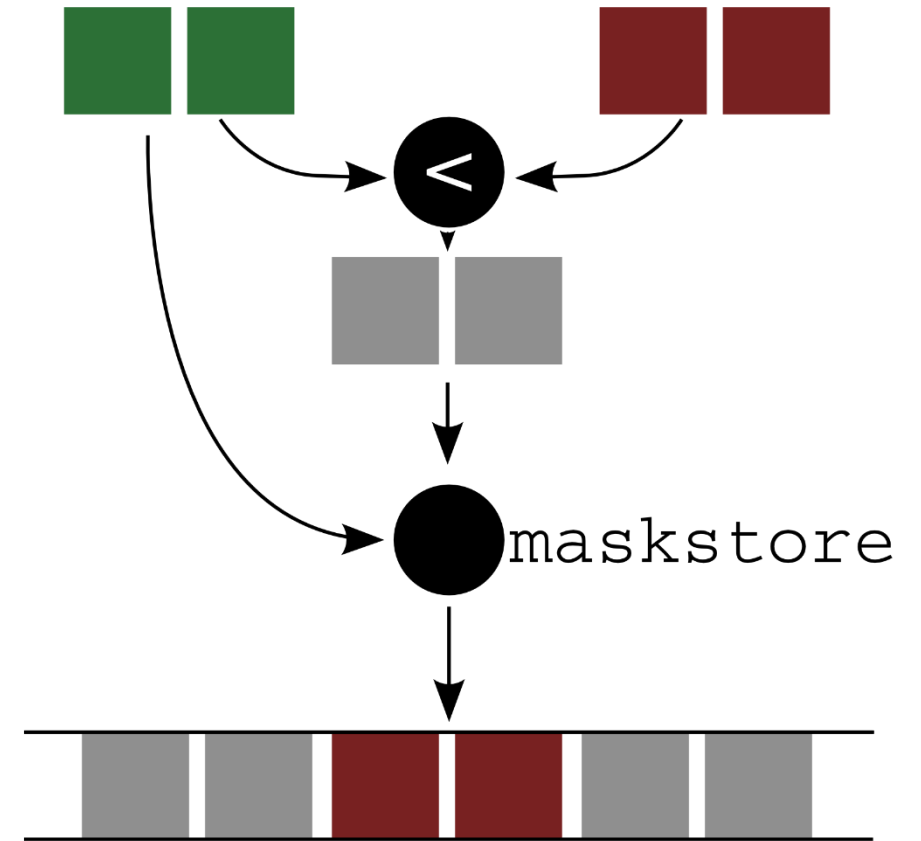
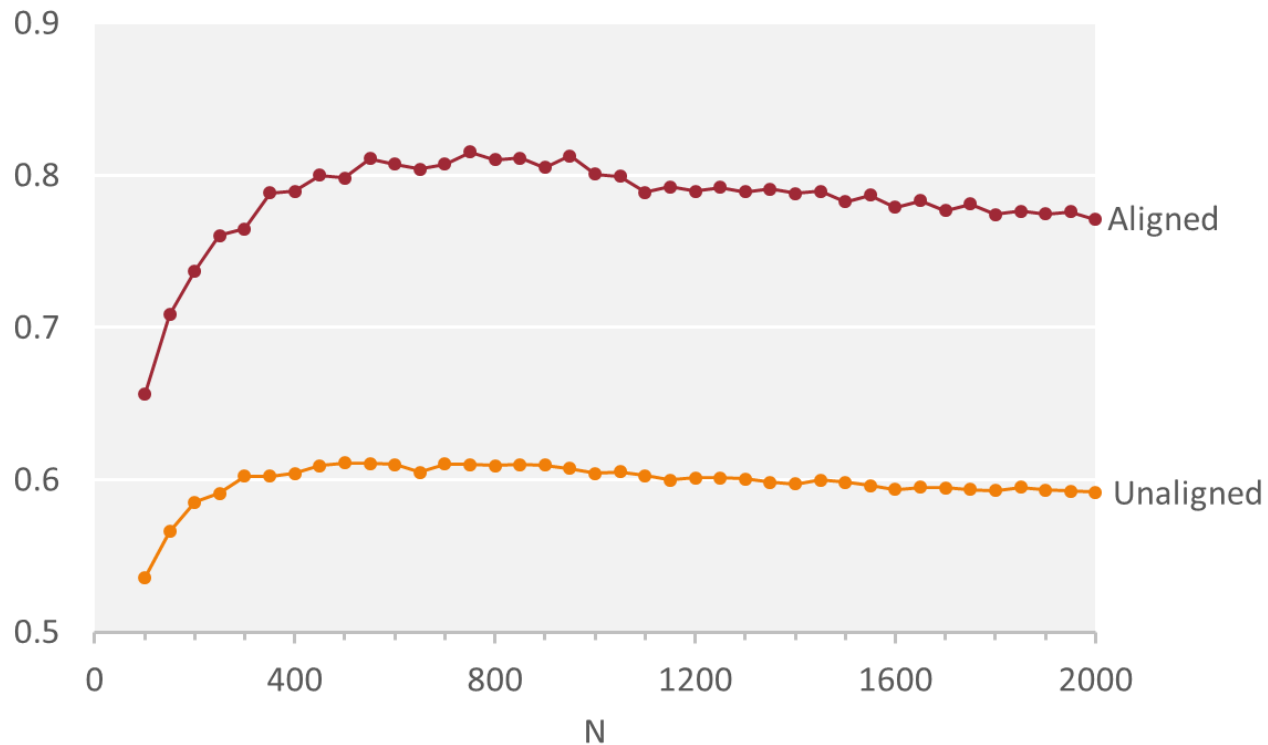
# Vectorization Issues: Maskstore



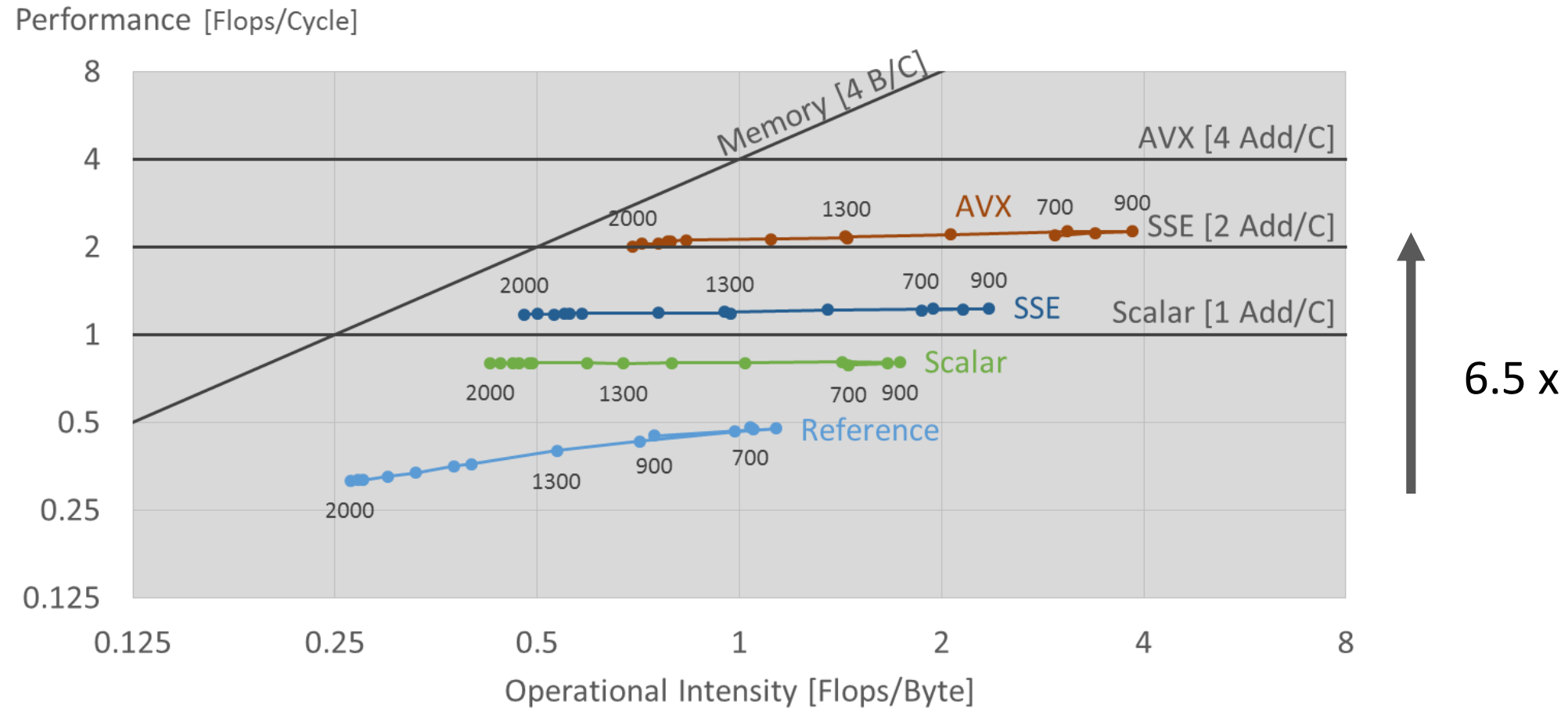
# Vectorization Issues: Maskstore

## Maskstore Performance

[flops/cycle]



# Roofline Plot





# Questions...?