01_serialEcho.cpp 2019-04-08 오후 11:43

```
// for incoming serial data
   int ib = 0;
   // piezo buzzer를 9번핀에 연결합니다.
5
   int buzzer = 9;
6
7
   void setup() {
8
     Serial.begin(9600);
                             // opens serial port, sets data rate to 9600 bps
     pinMode(buzzer,OUTPUT);
9
10
     pinMode(LED_BUILTIN, OUTPUT);
11
12
13
   void loop() {
     // send data only when you receive data:
14
     if (Serial.available() > 0) {
15
16
17
       // read the incoming byte:
       ib = Serial.read();
18
19
        //incomingByte = incomingByte+1;
20
       if(ib == '1')
21
       {
22
         tone(buzzer, 261, 1000);
23
         digitalWrite(LED_BUILTIN, HIGH); // turn the LED on (HIGH is the voltage level)
24
         Serial.print("Do");
25
26
       else if(ib == '2')
27
28
         tone(buzzer, 293, 1000);
29
        else if(ib == '3')
30
31
32
         tone(buzzer, 329, 1000);
33
        else if(ib == '4')
34
35
36
         tone(buzzer, 349, 1000);
37
38
        else if(ib == '5')
39
40
         tone(buzzer, 391, 1000);
41
42
       else if(ib == '6')
43
44
45
         tone(buzzer, 440, 1000);
46
47
48
       else if(ib == '7')
49
50
          tone(buzzer, 494, 1000);
51
52
53
54
        else if(ib == '0')
55
56
         digitalWrite(LED_BUILTIN, LOW);
                                             // turn the LED off by making the voltage LOW
57
         Serial.print("Off");
58
59
         noTone(buzzer);
60
61
        // say what you got:
62
        //Serial.print((char)incomingByte);
63
64
65
   }
```