

MAPPING GAUSSIAN PROCESS PRIORS TO BAYESIAN NEURAL NETWORKS

Daniel Flam-Shepherd, James Requeima and David Duvenaud

NIPS WORKSHOP ON BAYESIAN DEEP LEARNING

The main objective

Minimize the KL divergence of prior $p_{\text{GP}}(\mathbf{f}) \equiv \mathcal{GP}(\mathbf{f}|\mathbf{0}, \mathbf{K})$ to prior $p_{\text{BNN}}(\mathbf{f}|\phi)$ in function space! Note ϕ are variational parameters of $q(\mathbf{w}|\phi)$

$$\mathcal{K}(\phi) = \mathbb{KL}[p_{\text{BNN}}(\mathbf{f}|\phi) \mid p_{\text{GP}}(\mathbf{f})] \quad (1)$$

$$= -\mathbb{H}[p_{\text{BNN}}(\mathbf{f}|\phi)] - \mathbb{E}_{p_{\text{BNN}}(\mathbf{f}|\phi)}[\log p_{\text{GP}}(\mathbf{f})] \quad (2)$$

But this is infinite! Approximate it by taking expectations over $p(\mathbf{X})$:

$$\mathcal{L}_{\mathbf{X}}(\phi) \equiv \mathbb{E}_{\mathbf{X} \sim p(\mathbf{X})}[\mathcal{K}(\phi)]$$

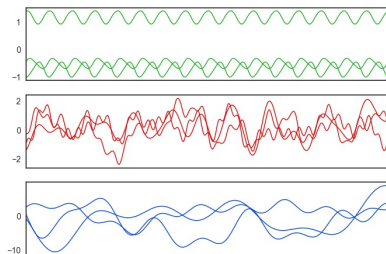
Assume normality of $p_{\text{BNN}}(\mathbf{f}|\phi)$ and use MC estimation:

$$\mathcal{L}_{\mathbf{X}}(\phi) \approx -\frac{1}{2} \log |\Sigma_{\mathbf{f}}| - \frac{1}{S} \sum_{s=1}^S \mathbb{E}_{\mathbf{X} \sim p(\mathbf{X})}[\log p_{\text{GP}}(\mathbf{f}^{(s)}(\mathbf{X}))] \quad (3)$$

Now find $\phi^* = \underset{\phi}{\operatorname{argmin}} \mathcal{L}_{\mathbf{X}}(\phi)$

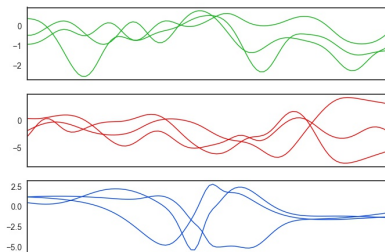
Two Experiments with different kernels

Red are samples of $p_{\text{BNN}}(\mathbf{f}(\mathbf{X})|\phi^*)$ (optimized ones)! Green are samples from the GP prior and Blue are non-optimized samples of $p_{\text{BNN}}(\mathbf{f}(\mathbf{X}))$.



$$k(x, x') = e^{-2 \sin^2(\pi|x-x'|)/25}$$

(a)



$$k(x, x') = e^{-(x-x')^2/2}$$

(b)

Check out our poster!!