CS4223 Tutorial 5: Data Level Parallelism

1. Consider the following vector code

```
LV V1,Rx ;load vector X

MULVS V2,V1,F0 ;vector-scalar mult

LV V3,Ry ;load vector Y

ADDV.D V4,V2,V3 ;add

SV Ry,V4 ;store the result
```

Assume 4 cycle vector add latency, 6 cycle vector multiply latency, and 10 cycle vector load/store latency. Adder, multiplier, and load/store units are all pipelined. Also assume 8-lane vector processor, that is, the processor contains 8 units of pipelined adder, multiplier, and load/store unit. Further assume that there is no conflict among the memory bank accesses. How long will it take to execute this code if vector length = 32, VLRMAX = 32 and there is no chaining?

ANS: It will require $32/8 = \frac{4}{4}$ iterations per instructions because there are 8 lanes and vector length is 32.

So LV/SV will take 10+3 = 13 cycles; ADDV.D will take 4+3 = 7 cycles, and MULTVS will take 6+3 = 9 cycles.

In this case, MULV.S and LV can execute in parallel.

```
So total cycles = 13 \text{ (LV)} + 13 \text{ (MULVS, LV)} + 7 \text{ (ADDV)} + 13 \text{ (SV)} = 46 \text{ cycles}
```

Note that as the units are pipelined, the next 8 elements can be fed into the pipeline while the first 8 elements are being processed.

2. Consider the following code fragment that produces 128 results.

```
for (i=0; i<64; i++) {
    a[i] = u * b[i];
    c[i] = b[i] + v;
}
```

Assume a vector pipeline with the following pipeline latencies and one lane per operation. Also assume there are no bank conflicts in the accesses for the above loop.

Operation Start-up penalty

Vector load/store 12 cycles
Vector multiply 7 cycles
Vector add 6 cycles

(a) Write the vector version of this code in assembly language.

ANS:

LD ru, u

LD rv, v

LV Vb, rb

MULV Va, Vb, ru

ADDV Vc, Vb, rv

SV Va, ra

SV Vc, rc

(b) Assuming no chaining and single memory pipeline, how many clock cycles will be required to execute this code fragment including start-up overheads.

ANS:

We ignore the scalar loads (first two instructions). The rest can be put into 4 chains.

LV Vb, rb

MULV Va, Vb, ru ADDV Vc, Vb, rv

SV Va, ra SV Vc, rc

12 cycle for load + 63 cycles

7 cycle for the next chain startup + 63 cycles

12 cycle for store + 63 cycles

12 cycle for store + 63 cycles

(c) If the vector sequence is chained but still has single memory pipeline, how many clock cycles will be required to execute this code fragment including start-up overheads?

ANS: 3 chains

LV Vb, rb MULV Va, Vb, ru ADDV Vc, Vb, rv

SV Va, ra

SV Vc, rc

12 +7 cycle for first chain startup + 63 cycles

12 cycle for store + 63 cycles

12 cycle for store + 63 cycles

(d) Assuming three memory pipelines and chaining, how many clock cycles are required to execute this code fragment including start-up overheads?

```
ANS: 1 chain
12 +7 + 12 cycle for chain startup + 63 cycles
```

2. Consider the following code, which multiplies two vectors that contain single-precision complex values:

Assume that the processor runs at 700 MHz and has a maximum vector length of 64. The load/store unit has a startup overhead of 15 cycles; the multiply unit, 8 cycles; the add/subtract unit, 5 cycles.

- a) What is the arithmetic intensity (number of operations per byte transferred) of this kernel? This code reads four floats and writes two floats, i.e., 6x4 byte = 24 byte for every six FLOP, so arithmetic intensity = 6/24 = 0.25
- b) Convert this loop into VMIPS assembly code using strip mining.

This is the assembly code. For the C-code with strip mining, please see slide 37 of DLP lecture. The part in red is the vector code. The rest takes care of strip mining.

Assume MVL = 64:

```
li $VL,44
                             # perform the first 44 ops
       li $r1,0
                             # initialize index
loop: lv $v1,a_re+$r1
                             # load a_re
       lv $v3,b re+$r1
                             # load b re
       mulvv.s $v5,$v1,$v3
                             #a+re*b re
       lv $v2,a_im+$r1
                             # load a_im
       lv $v4,b im+$r1
                             # load b im
       mulvv.s $v6,$v2,$v4
                             # a+im*b_im
       subvv.s $v5,$v5,$v6
                             # a+re*b_re - a+im*b_im
       sv $v5,c re+$r1
                             # store c re
       mulvv.s $v5,$v1,$v4
                             # a+re*b_im
       mulvv.s $v6,$v2,$v3
                             #a+im*b re
       addvv.s $v5,$v5,$v6
                             # a+re*b_im + a+im*b_re
       sv $v5,c im+$r1
                             # store c im
```

bne \$r1,0,else # check if first iteration

addi \$r1,\$r1,#176 # first iteration, increment by 44x4

li \$VL, 64 # reset VL to 64

j loop # guaranteed next iteration

else: addi \$r1,\$r1,#256 # not first iteration, increment by 64x4

skip: blt \$r1,1200,loop # next iteration?

- c) Assuming chaining and a single memory pipeline, how many clock cycles are required per complex result value, including start-up overhead?
 - 1. load a re
 - load b_re → a_re * b_re (chaining)
 - 3. load a_im
 - 4. load b_im → a_im*b_im → sub (chaining)
 - 5. a_re*b_im, store c_re
 - 6. a im*b re \rightarrow add \rightarrow store c im (chaining)

If you want accurate results, you should consider that the first outer loop processes only 44 vector elements. But for simplicity I will assume 64 vector elements.

- 1. Load 15 cycles + 63 cycles
- 2. Load 15 cycles + mult 8 cycles + 63 cycles
- 3. Load 15 cycles + 63 cycles
- 4. Load 15 cycles + mult 8 cycles + sub 5 cycles + 63 cycles
- 5. Store 15 cycles (worst path between mult and store) + 63 cycles
- 6. mult 8 cycles + add 5 cycles + store 15 cycles + 63 cycles

Calculate the total cycles = 502 cycles for 64 vector elements So 502/64 = 7.84 cycles per complex result

- d) Now assume that the processor has three memory pipelines and chaining. If there are no bank conflicts in the loop's accesses, how many clock cycles are required per result?
 - 1. load a_re, load b_re → a_re * b_re
 - 2. load a_im, load b_im \rightarrow a_im*b_im \rightarrow sub
 - 3. store c re, a re*b im
 - 4. $a_{im}*b_{re} \rightarrow add \rightarrow store c_{im}$
 - 1. Load 15 cycles + mult 8 cycles + 63 cycles (loads in parallel)
 - 2. Load 15 cycles + mult 8 cycles + sub 5 cycles + 63 cycles (loads in parallel)
 - 3. Store 15 cycles (worst path between store and mult) + 63 cycles
 - 4. mult 8 cycles + add 5 cycles + store 15 cycles + 63 cycles

3. The following kernel performs a portion of the finite-difference time-domain (FDTD) method for computing Maxwell's equations in a three-dimensional space, part of the SPEC06fp benchmarks:

Assume that dH1, dH2, Hy, Hz, dy, dz, Ca, Cb, Ex are all single-precision floating-point arrays. Assume IDx is an array of unsigned int.

a) What is the arithmetic intensity of this kernel?

Reads 40 bytes and writes 4 bytes for every 8 FLOPs, thus 8/44 FLOPs/byte = 0.18 FLOPs/byte

- b) Assume this kernel is to be executed on a processor that has 30 GB/sec of memory bandwidth. Will this kernel be memory bound or compute bound?
 - Having an arithmetic intensity of 0.18, if the processor has a peak floating-point throughout > (30 GB/s) \times (0.18 FLOPs/byte) = 5.4 GFLOPs/s, then this code is likely to be memory-bound, unless the working set fits well within the processor's cache.
- c) Develop a roofline model for this processor, assuming it has a peak computational throughput of 85 GFLOP/sec. [We will discussion roofline model in class]

The single precision arithmetic intensity corresponding to the edge of the roof is 85/30 = 2.83 FLOPs/byte.

At 1/8 arithmetic intensity, the performance will be 30*1/8 = 3.75 GFLOP