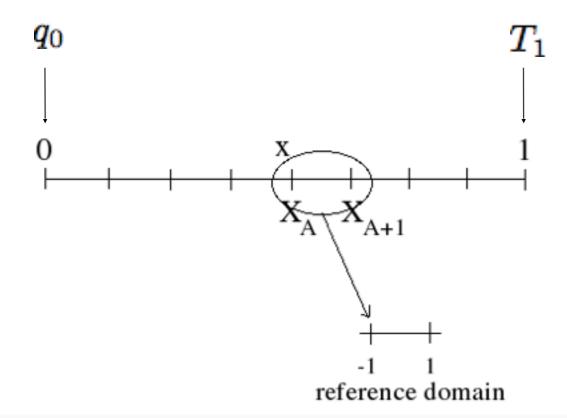
Finite-element methods

Strong form:

$$\partial_x^2 T + f = 0$$

Boundary conditions:
$$\begin{cases} T(1) &= T_1 \\ -\partial_x T(0) &= q_0 \end{cases}$$



Explore two sets of boundary conditions:

•
$$T_1 = 1$$
, $q_0 = 1$, and $f = 0$

•
$$T_1 = 1$$
, $q_0 = 1$, and $f = 1$

Weak form:
$$-\int_0^1 \partial_x w \partial_x T \mathrm{d}x + q_0 w(0) + \int_0^1 w f \mathrm{d}x = 0$$

Test function and temperature field expanded on some basis functions

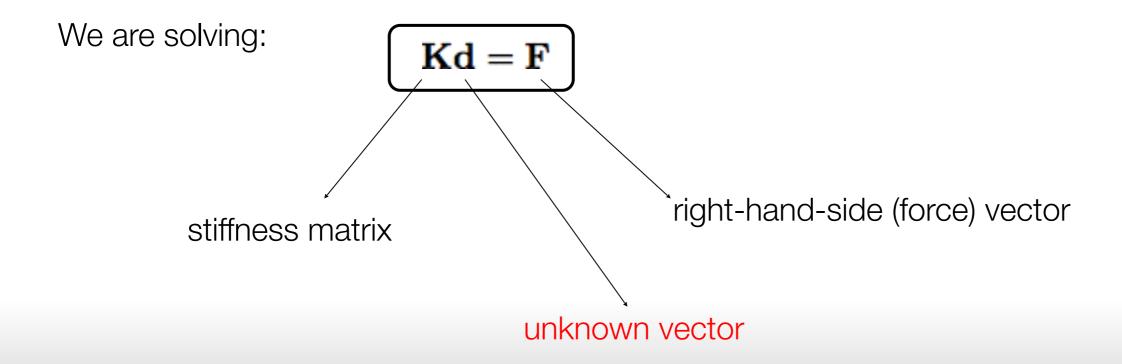
$$w(x) = \sum_{A=1}^{N} c_A N_A(x)$$

$$T(x) = \sum_{A=1}^{N_{el}} d_A N_A(x) + T_1 N_{n+1}(x)$$

$$-\sum_{B} \int_{0}^{1} \partial_{x} N_{A} d_{B} \partial_{x} N_{B} dx - \int_{0}^{1} \partial_{x} N_{A} q \partial_{x} N_{n+1} dx + \int_{0}^{1} N_{A} f dx + h N_{A}(0) = 0$$

$$-\sum_{B} \int_{0}^{1} \partial_{x} N_{A} d_{B} \partial_{x} N_{B} dx - \int_{0}^{1} \partial_{x} N_{A} q \partial_{x} N_{n+1} dx + \int_{0}^{1} N_{A} f dx + h N_{A}(0) = 0$$

$$\begin{cases} K_{AB} \equiv a(N_A, N_B) = \int_0^1 \partial_x N_A \partial_x N_B dx \\ F_A \equiv \int_0^1 N_A f dx + N_A(0)h - a(N_A, N_{n+1})q \end{cases}$$
$$a(w, u) \equiv \int_0^1 \partial_x w \partial_x u dx$$



Global level:

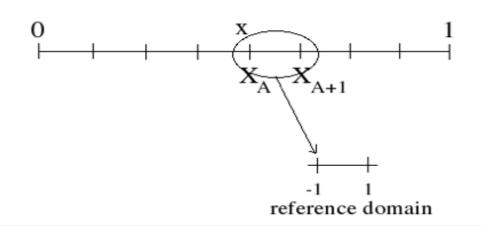
$$\begin{cases} K_{AB} \equiv a(N_A, N_B) = \int_0^1 \partial_x N_A \partial_x N_B dx \\ F_A \equiv \int_0^1 N_A f dx + N_A(0)h - a(N_A, N_{n+1})q \end{cases}$$

$$\rightarrow$$
 Kd = F

$$\int_0^1 g(x)dx = \sum_{\Omega_e} \int_{\Omega_e} g(x)dx = \sum_{\Omega_e} \int_{-1}^1 g(x(\xi))Jd\xi \qquad \qquad J = \frac{dx}{d\xi}$$

Local level:

Consider the mapping $\xi: [X_A, X_{A+1}] \to [\xi_1, \xi_2]$, such that



$$\begin{cases} \xi(X_A) &= \xi_1 = -1 \\ \xi(X_{A+1}) &= \xi_2 = 1 \end{cases}$$

Local (element) resolution:

$$N_a(\xi) = \frac{1}{2}(1 + \xi_a \xi)$$
 a=1,2

Stiffness matrix:

$$k_{ab}^e = a(N_a, N_b) = \int_{\Omega_e} \partial_x N_a \partial_x N_b \mathrm{d}x$$

Change of variables (reference domain)

$$k_{ab}^e = \frac{2}{h_e} \int_{-1}^1 \partial_{\xi} N_a \partial_{\xi} N_b \mathrm{d}\xi$$

Matrix form

$$k^e = rac{1}{h_e} \left(egin{array}{cc} 1 & -1 \ -1 & 1 \end{array}
ight)$$

Local (element) resolution:

$$N_a(\xi) = \frac{1}{2}(1 + \xi_a \xi)$$
 a=1,2

Force vector:

$$f_a^e = \int_{\Omega_e} N_A f \mathrm{d}x + \left\{ egin{array}{ll} \delta_{a1} q_0 & ext{for } e=1 \ -k_{a2}^e T_1 & ext{for } e=N_{el} \ 0 & ext{else} \end{array}
ight.$$

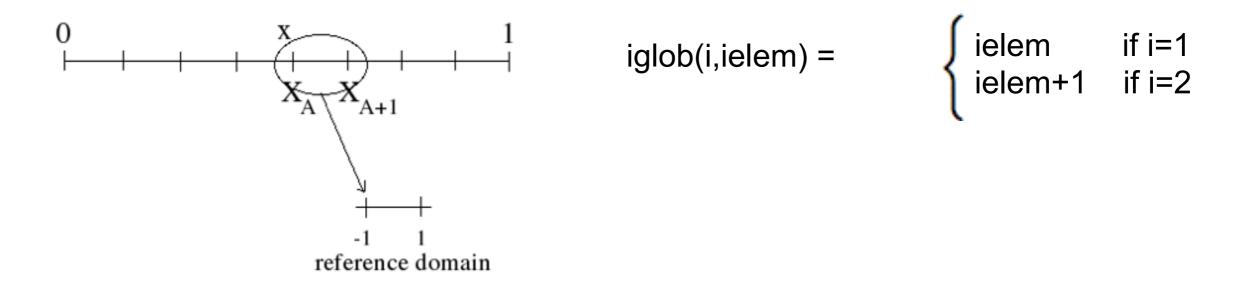
◆ Change of variables (reference domain)

$$f_a^e = \frac{h_e}{2} \int_{-1}^1 N_a f d\xi + \text{boundary terms}$$

Matrix form

$$f^e = rac{h_e}{6} \left(egin{array}{c} 2f_1 + f_2 \ f_1 + 2f_2 \end{array}
ight) + {
m boundary \ terms}$$

Assembling: back to global level



code example:

```
do ielem = 1, nelem
    do i = 1,2
        u(iglobe(i,ielem)) = u(iglobe(i,ielem)) + u_local(i,ielem)
    end
end
```



