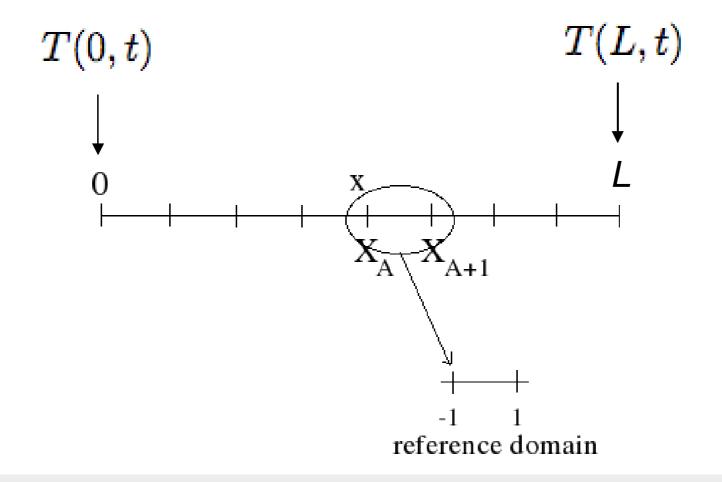
Spectral-element method

1D unsteady-state diffusion equation

Strong form: $\rho c_p \partial_t T - \partial_x (\kappa \partial_x T) = 0$

IC & BC:

$$\begin{cases}
T(x,0) = 0 \\
T(L,t) = 0 \\
T(0,t) = 10
\end{cases}$$



Weak form

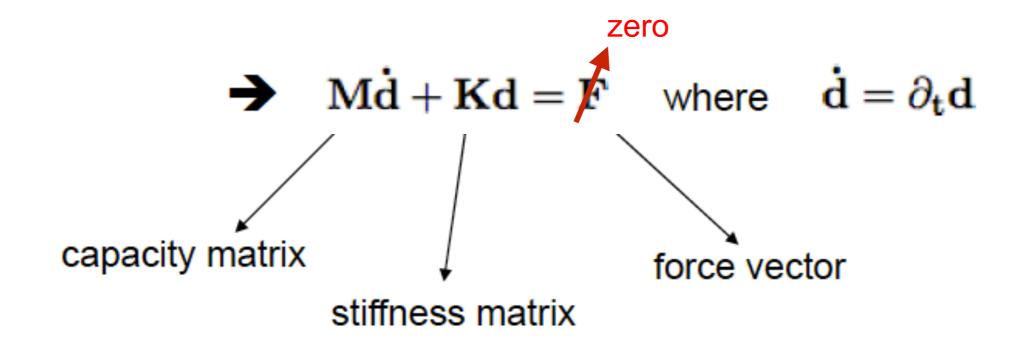
Weak form:
$$\int_0^L w \, \rho c_p \, \partial_t T \mathrm{d}x = - \int_0^L \kappa \, \partial_x w \, \partial_x T \mathrm{d}x + w \kappa \, \partial_x T \bigg|_0^L$$

Temperature field (and test function) expanded on basis functions:

$$T(x(\xi),t) = \sum_{lpha}^{N} T^{lpha}(t) l_{lpha}^{N}(\xi)$$
 unknowns

Weak form

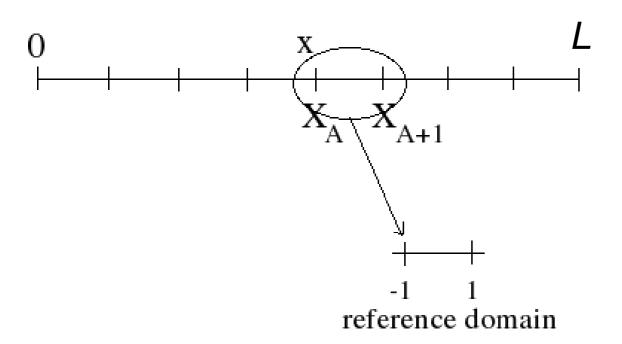
Weak form:
$$\int_0^L w \, \rho c_p \, \partial_t T \mathrm{d}x = - \int_0^L \kappa \, \partial_x w \, \partial_x T \mathrm{d}x + w \kappa \, \partial_x T \bigg|_0^L$$



Reference domain

Definition of the reference domain:

Consider the mapping $\xi: [X_A, X_{A+1}] \to [\xi_1, \xi_2]$, such that



$$\begin{cases} \xi(X_A) &= \xi_1 = -1 \\ \xi(X_{A+1}) &= \xi_2 = 1 \end{cases}$$

$$x(\xi) = \sum_{a=1}^{2} X_a N_a(\xi)$$

with shape functions being degree-1 Lagrange polynomials

$$N_a(\xi) = \frac{1}{2}(1 + \xi_a \xi)$$
 a=1,2

Jacobian:
$$J = \frac{\partial x}{\partial \xi}$$

Reference domain

Interpolation:

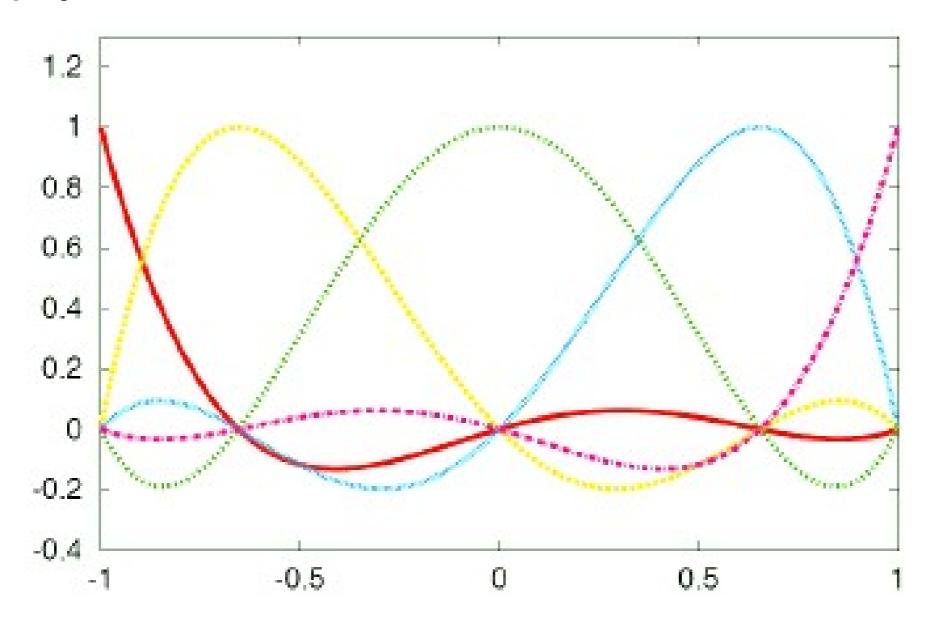
$$T(x(\xi),t) = \sum_{\alpha}^{N} T^{\alpha}(t) l_{\alpha}^{N}(\xi)$$

Gauss-Lobatto-Legendre quadrature integration rule:

$$\int_{\Omega_e} T(x,t) dx = \int_{-1}^{1} T(x(\xi),t) J(\xi) d\xi$$
$$\sim \sum_{\alpha=0}^{N} \hat{\omega}_{\alpha} T^{\alpha}(t) J^{\alpha}$$

Basis functions

Lagrange polynomials:



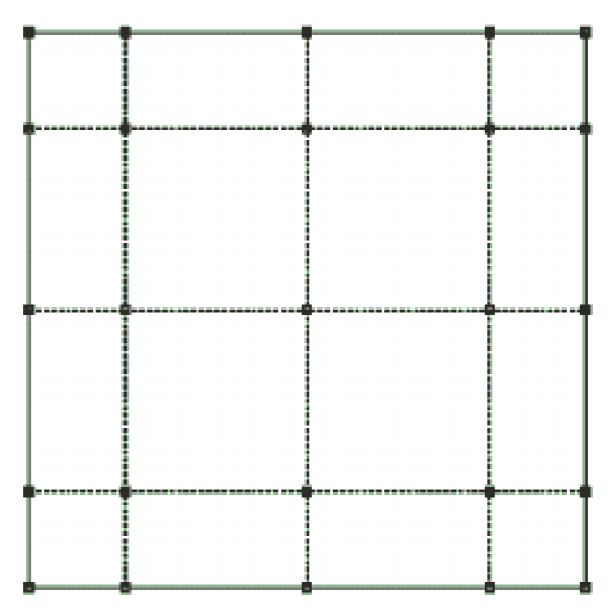
degree-4 polynomials

Lagrange polynomials property:

$$l_{\alpha}^{N}(\xi_{\beta}) = \delta_{\alpha\beta}$$

Basis functions

Gauss-Lobatto-Legendre points:



degree-4 GLL points (2D quad example)

GLL points are the n+1 roots of $\ (1-\xi^2)P_n'(\xi)=0$

 P_n : Legendre polynomial of degree n

Mass matrix

Local (element) resolution: Capacity/mass matrix

$$\int_{\Omega_{e}} w \, \rho c_{p} \, \partial_{t} T dx = \int_{-1}^{1} \rho(x(\xi)) c_{p}(x(\xi)) \, w(x(\xi)) \, \partial_{t} T(x(\xi), t) J(\xi) d\xi$$

$$\sim \sum_{\alpha=0}^{N} \hat{\omega}_{\alpha} \rho^{\alpha} c_{p}^{\alpha} J^{\alpha} \sum_{\beta}^{N} w^{\beta} l_{\beta}^{N}(\xi_{\alpha}) \sum_{\gamma}^{N} \partial_{t} T^{\gamma} l_{\gamma}^{N}(\xi_{\alpha})$$

$$= \sum_{\alpha=0}^{N} \hat{\omega}_{\alpha} \rho^{\alpha} c_{p}^{\alpha} J^{\alpha} w^{\alpha} \, \partial_{t} T^{\alpha}$$

diagonal matrix

Stiffness matrix

Local (element) resolution: Stiffness matrix

$$\int_{\Omega_{e}} \kappa \, \partial_{x} w \, \partial_{x} T dx = \int_{-1}^{1} \kappa(x(\xi)) \left[\partial_{x} w(x(\xi))\right] \left[\partial_{x} T(x(\xi), t)\right] J(\xi) d\xi$$

$$\sim \sum_{\alpha=0}^{N} \hat{\omega}_{\alpha} \kappa^{\alpha} \left[\sum_{\beta}^{N} w^{\beta} l_{\beta}^{\prime N}(\xi_{\alpha}) \partial_{x} \xi(\xi_{\alpha})\right] \left[\sum_{\gamma}^{N} T^{\gamma} l_{\gamma}^{\prime N}(\xi_{\alpha}) \partial_{x} \xi(\xi_{\alpha})\right] J^{\alpha}$$

$$=> M_{\alpha_1} \partial_t T^{\alpha_1}(t) = \sum_{\gamma=0}^N K_{\alpha_1 \gamma} T^{\gamma}(t)$$

Matricial form:

$$M\partial_t T = KT$$

Boundaries

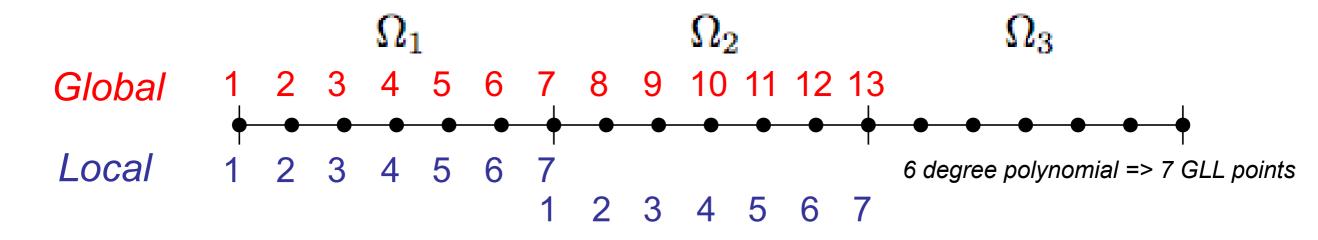
Boundary conditions:

$$w\kappa\partial_x T=w^N\kappa^N\sum_{lpha=0}^N T^lpha(t)l_lpha'^N(\xi_N)\partial_x\xi(\xi_N) \quad \text{at } x=L$$

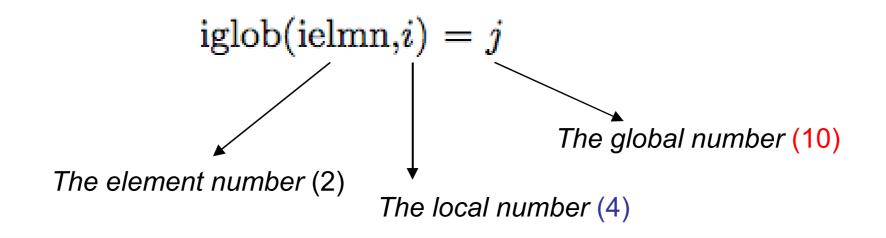
$$w\kappa\partial_x T=w^0\kappa^0\sum_{lpha=0}^N T^lpha(t)l_lpha'^N(\xi_0)\partial_x\xi(\xi_0) \quad \text{at } x=0$$

Assembly

Local to Global:



You need an array which links Local (where the calculation is done) to Global (where you want to know the results which are marched in time):



Assembly

Assembling: back to global level

```
M_{local}(ielmn, i) = \omega_{\alpha} \rho^{\alpha} c_{p}^{\alpha} J^{\alpha}
M_{alobal}(:) = 0
!loop over the elements
                                                                  reference domain
do ielmn=1,Nel
!loop over the GLL points
    do i=1,NGLL
get the global index
    j=iglob(ielmn,i) M_{global}(j) = M_{global}(j) + M_{local}(ielmn,i)
    enddo
enddo
```

Time stepping

Time scheme: Predictor-Corrector algorithm

• Predictor:

$$T_{n+1} = T_n + \frac{1}{2}\Delta t \dot{T}_n$$

 $\dot{T}_{n+1} = 0$ (initialization at the beginning of each time step)

Solve:

$$rhs = -KT_{n+1}$$

 $\delta \dot{T}_{n+1} = M^{-1}rhs$

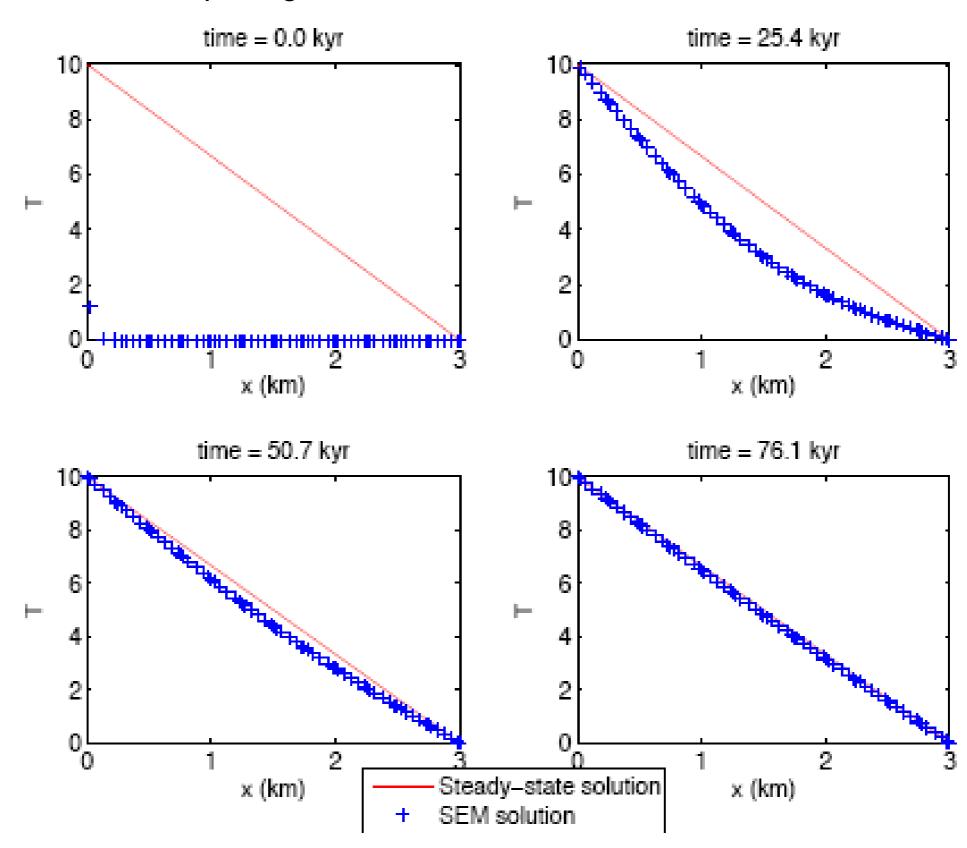
Corrector:

$$T_{n+1} = T_{n+1} + \frac{1}{2} \Delta t \delta \dot{T}_{n+1}$$

 $\dot{T}_{n+1} = \dot{T}_{n+1} + \delta \dot{T}_{n+1}$

SEM - 1D unsteady-state diffusion equation

Results: even element spacing



SEM - 1D unsteady-state diffusion equation

Results: variable conductivity

