

1 THINKING OUTSIDE THE BOX -
2 PREDICTING BIOTIC INTERACTIONS IN
3 DATA-POOR ENVIRONMENTS

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1 Abstract

Large networks of ecological interactions, such as food webs, are complex to characterize, be it empirically or theoretically. The former requires exhaustive observations, while the latter generally requires ample data to be validated. We therefore wondered whether readily available data, namely empirically described interactions in a variety of ecosystems, could be combined to predict species interactions in data deficient ecosystems. To test this, we built a biotic interactions catalogue from a collection of 94 empirical food webs, detailed predator-prey interaction databases and interactions from the Global Biotic Interactions (GloBI) database. We used an unsupervised machine learning method to predict interactions between any given set of taxa, given pairwise taxonomic proximity and known consumer and resource sets found in the interaction catalogue. Initial results suggest that pairwise interactions can be predicted with high accuracy. Although results are seemingly dependent on the comprehensiveness of the catalogue knowledge of taxonomy was found to complement well the catalogue and improve predictions, especially as empirical information available diminished. Given it's high accuracy, this methodology could democratize the use of food webs and network level descriptors in remote location where empirical data is hard to gather. Network characteristics could then be efficiently evaluated and correlated to levels of environmental stressors in order to improve vulnerability assessments of ecosystems to global changes, opening promising avenues for further research and for management initiatives.

Keywords: Interactions, machine learning, food webs, K-nearest neighbour, taxonomy, St. Lawrence

2 Introduction

Large networks of ecological interactions, such as food webs, are complex to characterize (Martinez, 1992; Pascual and Dunne, 2006). Empirical descriptions require exhaustive observations, while theoretical inference generally requires ample data to be validated. For this reason, studies focusing on communities of interacting species remain understudied, even though we acknowledge the importance of considering the reticulated nature of complex networks (Ings et al., 2009; Tylianakis et al., 2008). When time is of the essence, the long term studies required quickly become impractical and the use of network level approaches is relegated to the sideline.

Alternatively, a currently evolving approach is to predict interactions using proxies such as functional traits, phylogenies and spatial distributions (e.g. Gravel et al., 2013; Morales-Castilla et al., 2015; Bartomeus et al., 2016). For example, multiple traits can play a significant role in community dynamics and influence the presence and intensity of biotic interactions, like the influence of body size on predator-prey interactions, a literal take on *big fish eats small fish* (Cohen et al., 2003; Brose et al., 2006; Gravel et al., 2013). However, the time

53 required to gather the necessary data to apply those methods may still be re-
54 strictive, or the data be unavailable altogether, so much so that other methods
55 have been developed to fill the gaps in knowledge (e.g. Schrod et al., 2015).

56 We therefore wondered whether more readily available data could be used to
57 infer interactions in data deficient ecosystems. There is an increasing amount
58 of data describing worldwide species interactions, some freely available through
59 the Global Biotic Interactions (GloBI) database (Poelen et al., 2014). Another
60 readily available piece of information on species is their taxonomy, through
61 initiatives like the World Register of Marine Species (WoRMS; Bailly et al.,
62 2016). More than simple nomenclature, evolutionary processes are thought
63 to influence consumer-resource relationships (Mouquet et al., 2012; Rohr and
64 Bascompte, 2014) so that taxonomically related species would be more likely
65 to share similar types of both consumers and resources (Eklöf et al., 2012;
66 Morales-Castilla et al., 2015; Gray et al., 2015). Based on that assumption,
67 taxonomy might be useful in predicting interactions for species lacking detailed
68 information on their biology, but which have a taxonomically related species
69 for which such information is available. The objective of this work is thus to
70 combine empirical biotic interactions originating from a variety of ecosystems
71 with taxonomic relatedness to predict interactions in data deficient ecosystems.
72 As an example, we compare the observed interactions in the southern Gulf of
73 St. Lawrence (SGSL; Savenkoff et al., 2004) with predictions made using our
74 approach.

75 3 Methods

76 The objective of our methodology is to predict the interactions between all pairs
77 of taxa within an arbitrary set N_1 , using a set of taxa N_0 with empirically de-
78 scribed interactions from which we can extract pairs of consumers and resources
79 and their taxonomy. We couple the use of empirical data with an unsupervised
80 machine learning method to achieve this.

81 3.1 Biotic interaction catalogue

82 We built a biotic interaction catalogue to serve as a set of taxa N_0 for training
83 the algorithm with empirically described interactions. The empirical data used
84 to construct the interaction catalogue was gathered in two successive steps. The
85 first consisted of gathering data from a collection of 94 empirical food webs in
86 marine and coastal ecosystems from which we extracted pairwise taxa inter-
87 actions (see Brose et al., 2005; Kortsch et al., 2015; University of Canberra,
88 2016 for more information). We also used a detailed predator-prey interaction
89 database describing trophic relationships of 68 predators and their prey (Barnes
90 et al., 2008). From these datasets, only interactions between taxa at the taxo-
91 nomic scale of the family or higher were selected for inclusion in the catalogue.

92 As empirical food webs are vastly dominated by non-interactions, these
93 datasets yielded a highly skewed distribution of interactions vs non-interactions.

94 To counterbalance this, the second step of data compilation consisted of extract-
 95 ing observed interactions from the Global Biotic Interaction (GloBI) database
 96 (Poelen et al., 2014), which describes binary interactions for a wide range of
 97 taxa worldwide. We extracted all interactions available on GloBI for species
 98 belonging to the families of taxa identified through step 1. Interactions were
 99 extracted using the rGloBI package in R (Poelen et al., 2015). As per step 1,
 100 only interactions between taxa at the taxonomic scale of the family or higher
 101 were retained

102 The nomenclature used between datasets and food webs varied substantially.
 103 Taxa names thus had to be verified, modified according to the scientific nomen-
 104 clature and validated. This process was performed using the Taxize package in
 105 R (Chamberlain and Szöcs, 2013; Chamberlain et al., 2014) and manually veri-
 106 fied for errors. The same package was used to extract the taxonomy of all taxa
 107 for which interactions were obtained in previous steps. The complete R code
 108 and data used to build the catalogue is available at https://github.com/david-beauchesne/Interaction_catalog.
 109

110 3.2 Unsupervised machine learning

111 We use the K -nearest neighbor (KNN) algorithm (Murphy, 2012) to predict
 112 pairwise interactions for a set of taxa S . The KNN algorithm predicts missing
 113 entries or proposes additional entries by a majority vote based on the K nearest
 114 (i.e. most similar) entries (see Box 1 for an example). In this case, taxa are
 115 described by a set of resources when considered as a consumer, a set of consumers
 116 when considered as a resource and their taxonomy (i.e. kingdom, phylum, class,
 117 order, family, genus, species). Similarity between taxa was evaluated using the
 118 Tanimoto similarity measure, which compares two vectors with i elements based
 119 on the number of elements they share and contain:

$$\text{tanimoto}(\mathbf{x}, \mathbf{y}) = \frac{\sum_i x_i \wedge y_i}{\sum_i x_i \vee y_i}, \quad (1)$$

120 where \wedge is bitwise *and*, while \vee is the bitwise *or* operators. Adding a weight-
 121 ing scheme, we can measure the similarity using two different sets of vectors with
 122 i and j elements, respectively.

$$\text{tanimoto}_t(\mathbf{x}, \mathbf{y}, w_t) = w_t \text{tanimoto}(\mathbf{x}_i, \mathbf{y}_i) + (1 - w_t) \text{tanimoto}(\mathbf{x}_j, \mathbf{y}_j), \quad (2)$$

123 where w_t is the weight given to vector i , \mathbf{x}_i , \mathbf{y}_i are the resource or consumer
 124 sets of the two taxa and \mathbf{x}_j and \mathbf{y}_j are the vectors for the taxonomy of two taxa.
 125 When $w_t = 0$ only resource or consumer sets are used to compute similarity,
 126 while $w_t = 1$ solely uses taxonomy.

3.3 Predicting interactions, Biotic predictor algorithm, Two-way Tanimoto algorithm, Feng shui name algorithm, Find a name for the algorithm

The XXX algorithm is built on a series of logical steps that ultimately predicts a candidate resources list C_R for each taxon in N_1 (Figure 1). For all consumer taxa T_C in N_1 , the algorithm first verifies whether it has empirical resources T_R listed in the catalogue (Step S1, Figure 1). When it does, if T_R are also in N_1 , they are added as predicted resources for T_C (S2, S3). This corresponds to what we refer to as the catalogue contribution to resource predictions. Two taxa in N_1 that are known to interact through the catalogue are automatically assumed to interact in N_1 .

Otherwise, the algorithm passes to what we refer to as the predictive contribution to resource predictions (S4 to S16), with candidate resources for T_C identified with the KNN algorithm. If T_R are absent from N_1 , K most similar resources $T_{R'}$ are identified in N_1 to add to C_R (S4 to S7). Then for all T_C in N_1 , the algorithm identifies K most similar consumers $T_{C'}$ in N_0 and extracts their resource sets (S8). As before, if those resources are found in N_1 (S9) they are added to C_R (S10 to S12), otherwise K most similar resources $T_{R'}$ are identified in N_1 (S13) to add to C_R (S14 to S16). A simple working example is presented at Box 1. Note that other parameters are used in the algorithm, but not presented here for the sake of message clarity. A more comprehensive mathematical description of the algorithm and the parameters used is however available through Figure 1 and the complete R code and data used for the algorithm is available at https://github.com/david-beauchesne/Predict_interactions.

3.4 Algorithm prediction accuracy

We used datasets including more than 50 taxa (Christian and Luczkovich, 1999; Link, 2002; Thompson et al., 2004; Brose et al., 2005; Barnes et al., 2008; Kortsch et al., 2015) to assess the prediction accuracy of the algorithm. Testing accuracy of a particular dataset was done by first removing from the catalogue all pairwise interacting taxa originating from that dataset. Accuracy was evaluated using three different statistics:

1. $Score_y$ is the fraction of interactions correctly predicted:

$$Score_y = \frac{a}{a + c} \quad (3)$$

2. $Score_{\neg y}$ is the fraction of non-interactions correctly predicted:

$$Score_{\neg y} = \frac{d}{b + d} \quad (4)$$

3. TSS, The True Skilled Statistics (TSS) evaluated prediction success by considering both true and false predictions, returning a value ranging from

162 1 (prefect predictions) to -1 (inverted predictions; Allouche et al., 2006):

$$TSS = \frac{(ad - bc)}{(a + c)(b + d)} \quad (5)$$

163 where a is the number of links predicted and observed, b is the number
 164 predicted but not observed, c is the number of non-interaction predicted but
 165 interactions observed and d is the number of non-interaction predicted absent
 166 and observed. These three statistics give a different perspective on prediction
 167 accuracy, focusing in turn on true interactions and non-interactions, and on
 168 both true and false predictions.

169 We evaluated the three statistics for the complete algorithm and for the cat-
 170 alogue and the predictions individually to evaluate their respective contribution
 171 to the algorithm predictive accuracy. Multiple w_t values were also tested to
 172 evaluate whether taxa similarity measured as a function of resource/consumer
 173 sets or taxonomy contributed more significantly towards increased predictive
 174 accuracy. The same was done with multiple K values.

175 Finally, we evaluated the influence of the comprehensiveness of the cata-
 176 logue on prediction accuracy. We selected the arctic food web from Kortsch
 177 et al. (2015) as a test. This food web was selected as it is highly detailed tax-
 178 onomically. Furthermore, once removed from the catalogue, almost 100% of its
 179 taxa still had information available on sets of consumers and resources, which
 180 necessary for testing the impact of catalogue comprehensiveness on prediction
 181 accuracy. We iteratively and randomly ($n = 50$ randomizations) removed a
 182 percentage of empirical data describing the food web taxa from the catalogue
 183 before generating new predictions with the algorithm. We also tested w_t values
 184 of 0.5 and 1 to evaluate whether taxonomic similarity could support predic-
 185 tive accuracy in cases when empirical data for species in N_1 in the catalogue is
 186 unavailable.

187 4 Results

188 4.1 Biotic interaction catalogue

189 The data compilation process allowed us to build an interaction catalogue com-
 190 posed of 276708 pairwise interactions (interactions = 72110; non-interactions =
 191 204598). A total of 9712 taxa (Superfamily = 15; Family = 591; Subfamily =
 192 29; Tribe = 8; Genus = 1972; Species = 7097) are included in the catalogue,
 193 4159 of which have data as consumers and 4375 as resources.

194 4.2 Algorithm predictive accuracy

195 The overall predictive accuracy of the algorithm ranges between 80% to al-
 196 most 100% in certain cases (Figure 2). Both interactions and non-interactions
 197 are well predicted by the algorithm. TSS scores are lower than $Score_y$ and
 198 $Score_{-y}$ due to misclassified interactions and non-interactions. This can also

be observed through the effect of varying K values, which increases the number of potential candidate resources for each taxa in the predictive portion of the algorithm. Prediction accuracy increases for interactions, while it decreases for non-interactions, as K values increase.

Similarity being predominantly measured with resource/consumer sets (w_t closer to 0) yielded better predictions than when measured with taxonomy (w_t closer to 1; Figure 2). Resource/consumer sets therefore appears to serve as a better predictor of similarity between taxa for interactions predictions. It is nonetheless interesting to note that although the predictive contribution of the algorithm decreases as w_t increases, an increased mean and decreased variability values for the TSS and $Score_y$ statistics is also observed (Figure 2). This suggests that while using taxonomy for similarity measurements yields lower predictive accuracy, it may also complement the catalogue contribution by predicting interactions not captured through empirical data, effectively increasing the predictive accuracy of the complete algorithm.

The partitioning of the catalogue and predictive portions of the algorithm shows that it is dependent on the comprehensiveness of the catalogue for high prediction accuracy (Figures 2, 3). As the amount of empirical data available in the catalogue decreases so does the overall accuracy of the algorithm (Figures 3). The predictive contribution of the algorithm however slows down the decrease in the prediction efficiency of the algorithm. Prediction accuracy still remains around 75% with only 40% of N_1 taxa found in the catalogue (Figures 3). Furthermore, the use of taxonomy for similarity measurements is more efficient as empirical data becomes scarcer and no different than resource/consumer sets for the complete algorithm when ample data is available (Figures 3).

4.3 Southern Gulf of St. Lawrence

As an example, we used the XXX algorithm to predict interactions in the southern Gulf of St. Lawrence (SGSL) in eastern Canada. The empirical data and taxa list come from Savenkoff et al. (2004). They present a list of 29 functional groups for a total of 80 taxa presented at least at taxonomical scale of the family. Other coarser taxa families were not used for this example (see Table S1 in Supplementary information (SI) and Savenkoff et al. (2004) for a complete description of functional groups). As their analysis was performed on the functional groups rather than the taxa themselves, we used the algorithm to predict interactions between all 80 taxa selected. We then aggregated them back to their original functional groups to compare with interactions presented in Savenkoff et al. (2004). In total, there were empirical data available in the catalogue for 78% of SGSL taxa (62/80). The algorithm correctly predicted close to 80% of interactions ($a = 135/170$) and non-interactions ($d = 354/455$) extracted from Savenkoff et al. (2004). It also predicted an additional 101 interactions (c) that were not noted in Savenkoff et al. (2004) and failed to predict 36 observed interactions that were (c), resulting in a TSS score of 0.57. A visual comparison of results obtained from the algorithm with interactions noted in Savenkoff et al. (2004) is available at Figure 4. The network presented is

centered on the observed and predicted interactions of the capelin (*Mallotus villosus*) and piscivorous small pelagic feeders (e.g. *Scomber scombrus* and *Illex illecebrosus*).

5 Discussion

5.1 Algorithm accuracy

We show that out of the box interaction inference for a set of taxa with incomplete or unavailable preexisting information can be achieved with high accuracy using a combination of empirical data describing biotic interactions and taxonomic relatedness. Although the efficiency of the algorithm is dependent on the comprehensiveness of the interactions catalogue, taxonomic proximity acts as a complement to increase the number of observed interactions correctly predicted. Taxonomic proximity also supports the efficiency of the algorithm when catalogue comprehensiveness decreases.

5.2 Usefulness of taxonomic relatedness

While we found that taxonomy could be useful as a complement to predictions made using empirical data, the accuracy of predictions made using the KNN algorithm could be improved. While evolutionary history plays a significant role in influencing consumer-resource trait matching and food web structure (Mouquet et al., 2012; Rohr and Bascompte, 2014), phylogenetic constraints do not account efficiently for certain traits such as body size (Eklöf and Stouffer, 2016). Including traits like body size and metabolism as an additional component of this algorithm could thus help increasing overall prediction accuracy, especially in cases where the catalogue lacks data on taxa for which interactions have to be predicted. Although promising, such an approach would undermine the premise under which this method was built and which constitutes its main strength, *i.e.* predicting interactions in data deficient environments using readily available data.

5.3 Interactions classification

That $Score_y$ and $Score_{-y}$ are inversely proportional means that non-interactions are misclassified as interactions in the process of increasing $Score_y$, consequently decreasing $Score_{-y}$. This could either stem from the algorithm poorly predicting non-interactions or from the empirical data itself. Accuracy evaluation assumes that non-interactions from empirical food web are observed data, yet it is usually not the case. Most empirical webs have a strong focus attributed to higher order consumer species and often uneven effort made to thoroughly detail species interactions (Dunne2006). Furthermore, the methodologies used to obtain consumer-resource data, often relying on gut content analyses, which is efficient at observing interactions, may be inefficient to detect absence of interactions in natural systems (Dunne2006). This is especially true with our methodology,

where we predict interactions between species whose co-occurrence may have been observed in the other ecosystems we are using to predict interactions. Misclassified interactions could thus be real, albeit unobserved through empirical data available.

5.4 Southern Gulf of St. Lawrence

The St Lawrence example (Figure 4 and SI) provides great material to discuss predictions in greater detail. The algorithm fails to predict 20% of interactions presented in Savenkoff et al. (2004). Interactions that failed to be predicted were mainly centered on invertebrate species (e.g. polychaetes and mollusks) and large functional groups described by coarse taxonomic categories (e.g. diatoms) alongside few species in Savenkoff et al. (2004) (e.g. piscivorous small pelagic feeders; Table S3). As we focused on the taxa at least at the scale of family, it is likely that their functional groups had a broader range of possible interactions included than what the algorithm could predict using only a few taxa. Furthermore, the efficiency of the algorithm greatly depends on the underlying empirical data that defines the catalogue. If the empirical data used to build the catalogue focuses on higher order consumers, it should come as no surprise that the algorithm would be afflicted by the same limitations.

The algorithm also predicts substantially more interactions than those presented in Savenkoff et al. (2004) (Figure 4; Table S2). The catalogue is not currently built to take into account life stages of species. Considering life stages and the fact that they are not explicitly considered in the catalogue could explain additional interactions that seem suspicious at first, like the surprise amount of additional interactions predicted for small piscivorous pelagic feeders as consumers (Figure 4). Due to the aggregated nature of the SGSL web, we believe the TSS score to be an underestimate of the efficiency of the algorithm.

5.5 Perspectives

Overall, we believe our method performs well and offers promising avenues for further applied research and management initiatives. Interaction strength and species co-occurrence are major attributes affecting the probability of observing interactions. Interaction strength is instrumental to understanding community dynamics, stability and robustness (Laska and Wootton, 1998; Morales-Castilla et al., 2015), while the co-occurrence of species encloses valuable information on interactions and is a pre-requisite for them to exist (Cazelles et al., 2016). Considering them in our methodology would be highly valuable to correctly assess interactions in a given ecosystem and predict the spatial distribution of interaction networks.

Given its high efficiency and simplicity, our methodology could broaden the use and the accessibility of food webs and network level descriptors for integrative management initiatives such as cumulative impacts assessments and systematic planning (Giakoumi et al., 2015; Beauchesne et al., 2016), especially for remote locations where empirical data is hard to gather. Network characteristics

could be efficiently evaluated and correlated to levels of multiple environmental stressors to assess the vulnerability of ecosystems to global changes. We believe that the development of such predictive approaches could represent the first much needed steps towards the use of ecological networks in systematic impacts assessments.

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DRAFT

510 6.1 Box 1

511 The XXX algorithm follows a series of logical steps to predict resources for all
 512 taxa in an arbitrary set of taxa N_1 using a set of taxa N_0 with empirically
 513 described interactions from which we can extract sets of consumers and re-
 514 sources and their taxonomy. In this example, we are predicting interactions for
 515 a fictitious $N_1 = \{T_1, T_9, T_{10}, T_{11}, T_{12}\}$ using N_0 with information on 12 taxa.
 516 This catalogue holds information on consumer or resource for 10 taxa and the
 517 taxonomy for all 12 taxa in the list.

N_0 taxa ID	taxonomy	resource	consumer
T_1	$\{a, b, c\}$	$\{T_2, T_3, T_{12}\}$	$\{T_4\}$
T_2	$\{e, f, g\}$		$\{T_1, T_5\}$
T_3	$\{i, j, k\}$		$\{T_5\}$
T_4	$\{m, n, o\}$	$\{T_1, T_5\}$	
T_5	$\{a, b, d\}$	$\{T_8, T_9\}$	$\{T_4\}$
T_6	$\{i, q, r\}$	$\{T_2, T_8\}$	$\{T_4\}$
T_7	$\{e, f, h\}$		$\{T_1, T_6\}$
T_8	$\{s, t, u\}$		$\{T_5, T_6\}$
T_9	$\{s, t, v\}$		$\{T_5\}$
T_{10}	$\{i, j, l\}$		
T_{11}	$\{m, n, p\}$		
T_{12}	$\{q, r, s\}$		$\{T_1\}$

518 Similarity between all pairs of taxa in N_0 is measured for consumer, resource
 519 and taxonomic proximity using equation 1. The upper triangular matrix repre-
 520 sents similarity measured with taxa sets of resources/consumers, while the lower
 521 triangular represents taxonomic similarities. For consumer/resource set similar-
 522 ities, values of 0 mean that similarity equals 0 for both similarity measurements.
 523

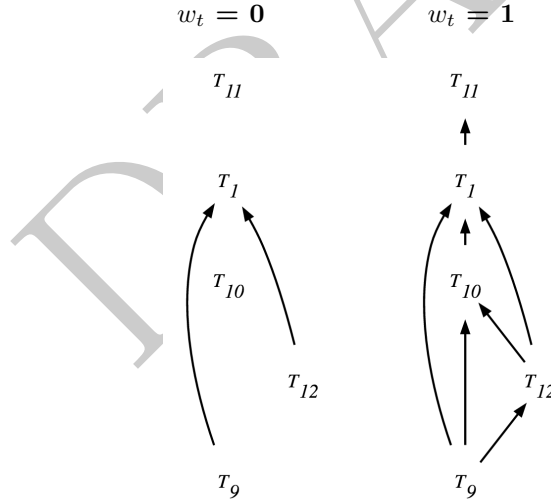
tanimoto(T_Cx, T_Cy) / tanimoto(T_Rx, T_Ry)												
	T_1	T_2	T_3	T_4	T_5	T_6	T_7	T_8	T_9	T_{10}	T_{11}	T_{12}
T_1	-	0	0	0	0/1	0.3/1	0	0	0	0	0	0
T_2	0	-	0/0.5	0	0	0	0/0.3	0/0.3	0/0.5	0	0	0/0.5
T_3	0	0	-	0	0	0	0	0/0.5	0/1	0	0	0
T_4	0	0	0	-	0	0	0	0	0	0	0	0
T_5	0.5	0	0	0	-	0.3/1	0	0	0	0	0	0
T_6	0	0	0.2	0	0	-	0	0	0	0	0	0
T_7	0	0.5	0	0	0	0	-	0/0.3	0	0	0	0/0.5
T_8	0	0	0	0	0	0	0	-	0	0	0	0
T_9	0	0	0	0	0	0	0	0.5	-	0	0	0
T_{10}	0	0	0.5	0	0	0.2	0	0	0	-	0	0
T_{11}	0	0	0	0.5	0	0	0	0	0	0	-	0
T_{12}	0	0	0	0	0	0.5	0	0.2	0.2	0	0	-

tanimoto(T_Tx, T_Ty)

524 From these, the algorithm goes through logical steps (Figure 1) to identify
525 a candidate resource list C_R for each taxon in N_1 using either empirical data
526 directly or K most similar taxa with equation 2. Going through the process for
527 T_1 , using $K = 1$ and $w_t = 1$:

Steps		Catalogue	Prediction
1	$I(T_1, T_R)$ in N_0 ?		
2	T_R in N_1 ?		
4-7	$T_2 = \text{no} \rightarrow t(T_2, T_{R'}, w_t) = \text{NA}$	$\{\}$	$\{\}$
4-7	$T_3 = \text{no} \rightarrow t(T_2, T_{R'}, w_t) = T_{10} = 0.5$	$\{\}$	$\{T_{10}\}$
3	$T_{12} = \text{yes}$	$\{T_{12}\}$	$\{T_{10}\}$
8	$t(T_1, T_{C'}, w_t) = T_5 = 0.5$		
9	$I(T_5, T_R)$ in N_1 ?		
13-16	$T_8 = \text{no} \rightarrow t(T_8, T_{R'}, w_t) = T_9 = 0.5$	$\{T_{12}\}$	$\{T_9, T_{10}\}$
10-12	$T_9 = \text{yes}$	$\{T_9, T_{12}\}$	$\{T_9, T_{10}\}$

528 The logical steps allow us to predict a set of resources for $T_1 = \{T_9, T_{10},$
529 $T_{12}\}$. Doing it for all taxa in N_1 with $w_t = 0$ and 1 predicts the following
530 networks:



6.2 Figures

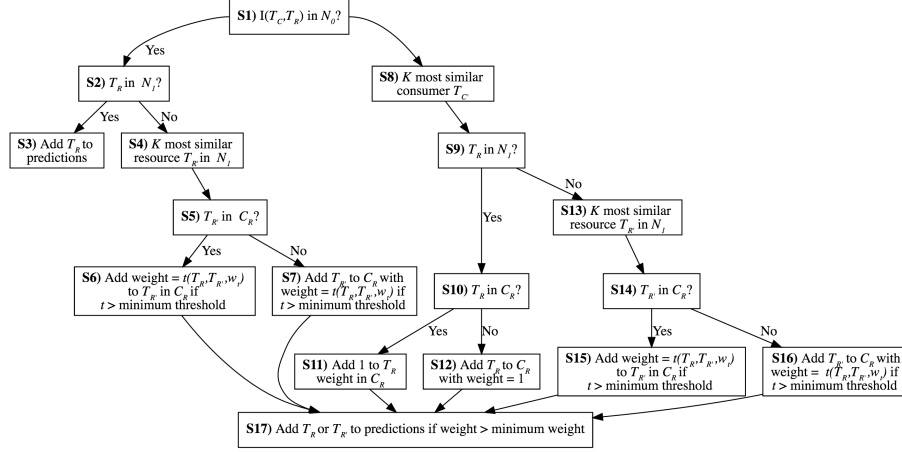


Figure 1: Description of logical steps used by the algorithm to suggest a list of candidate resources (C_R) for each consumer taxa (T_C) in an arbitrary set of N_1 for which interactions are predicted, using a set of taxa N_0 with empirically described interactions. Interactions between consumer and resource taxa are denoted as $I(T_C, T_R)$. K is the number of most similar neighbours selected for the KNN algorithm, t stands for tanimoto in equation 1, w_t is the weight given to sets of resources and consumers in equation 2, the minimum threshold is an arbitrary value setting the minimal similarity value accepted for taxa to be considered as close neighbours in the KNN algorithm, the weight is the value added to a candidate resource each time it is added to C_R and the minimum weight is the minimal weight value accepted for candidate resources to be selected as predicted sources in the algorithm.

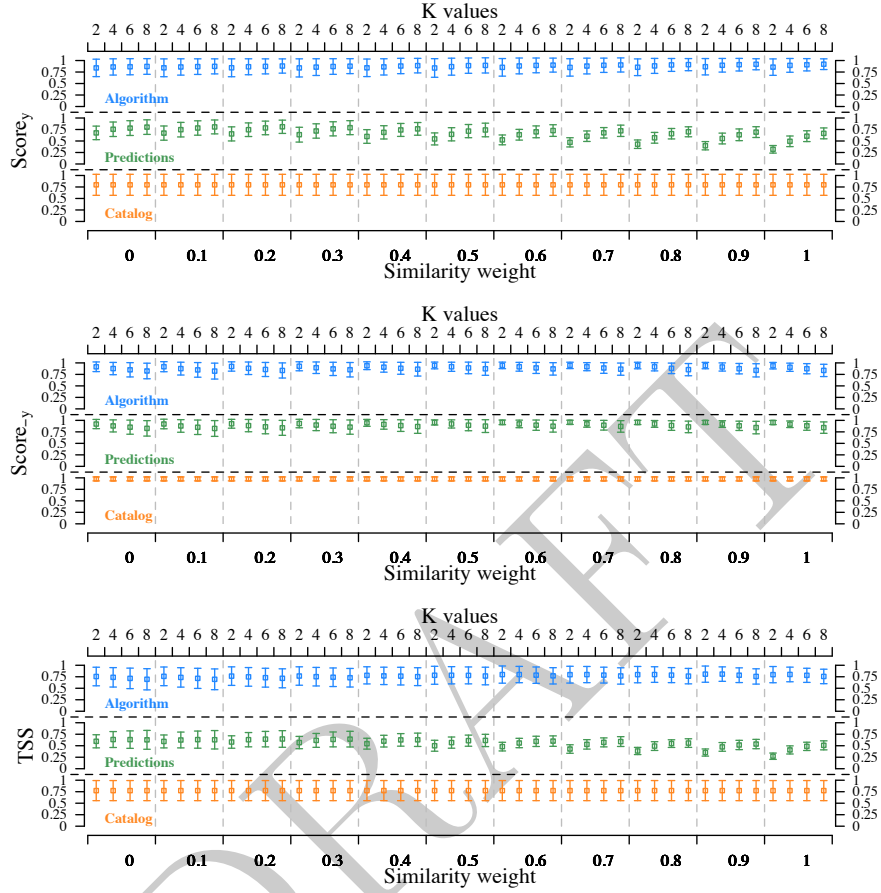


Figure 2: The graph presents the three statistics (*i.e.* $Score_y$, $Score_{-y}$ and TSS) used to evaluate the accuracy of the algorithm as a function of as a function of K values tested (*i.e.* 2, 4, 6 and 8 most similar seighbours, top x -axis) and trait weight (bottom x -axis), which varies between 0 and 1, and . A weight of 0 means that similarity is measured only using set of resources/consumers for each taxa, while a weight of 1 means that similarity is based solely on taxonomy. For each statistics, the topmost graph presents prediction accuracy for the complete algorithm, the middle graph corresponds to predictions made through the predictive portion of the algorithm (Steps S4-S16; Figure 1) and the bottom graph presents the catalogue contribution for the algorithm (Steps S1-S3; Figure 1). Note that the sum of the predictive and catalogue contributions can be over 100% as there is overlap between predictions made through both. The 7 datasets used for this analysis contained over 50 taxa (Christian and Luczkovich, 1999; Link, 2002; Thompson et al., 2004; Brose et al., 2005; Barnes et al., 2008; Kortsch et al., 2015)

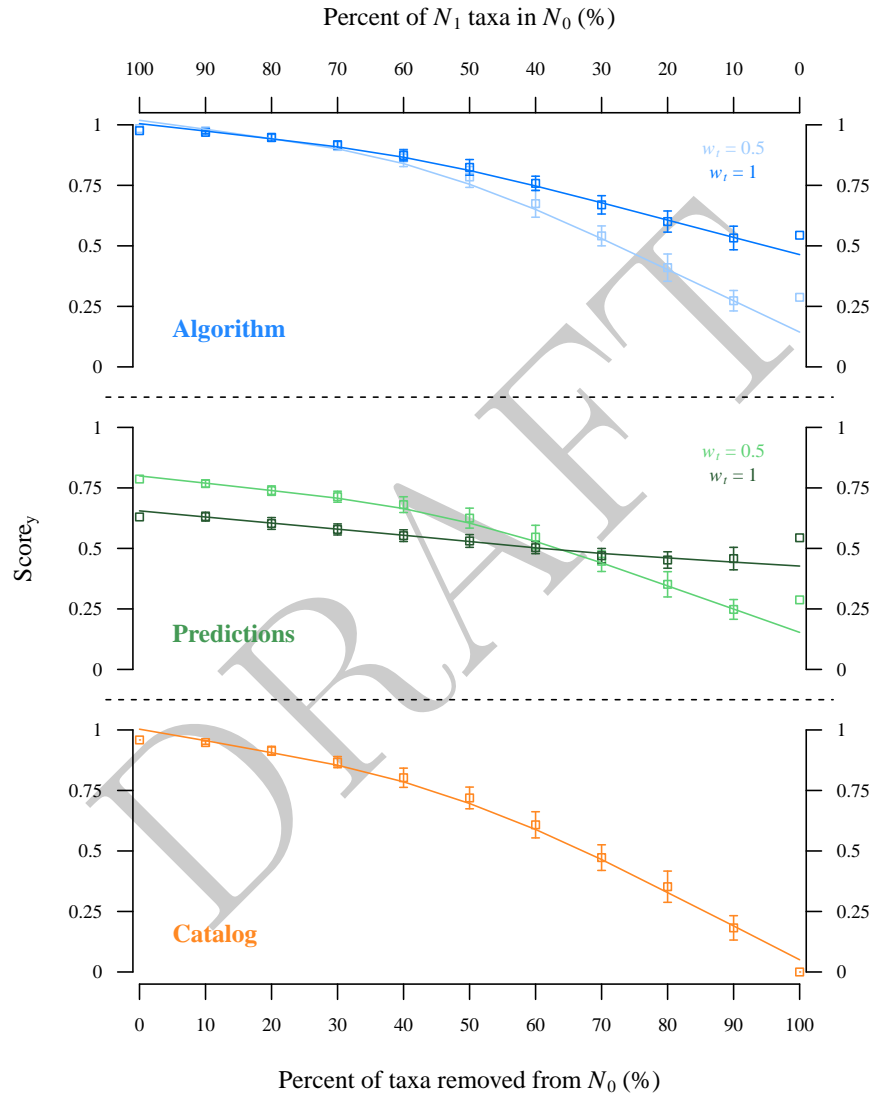


Figure 3: Caption on next page.

Figure 3: Graph presenting $Score_y$ as a function of catalogue comprehensiveness, *i.e.* the amount of information on sets of consumer and resources available in the catalogue. We tested this on the arctic food web from Kortsch et al. (2015). This food web was highly detailed taxonomically. Once removed from the catalogue, almost 100% of its taxa still had information available on sets of consumers and resources, which necessary for testing the impact of catalogue comprehensiveness on prediction accuracy. A random percentage of data available in the catalogue for taxa in the food web (*i.e.* 0 to 100%) was iteratively removed ($n = 50$ randomizations) before generating new predictions with the algorithm. w_t values of 0.5 and 1 were evaluated to verify the usefulness of taxonomy in supporting predictive accuracy. The topmost graph presents prediction accuracy for the complete algorithm, the middle graph corresponds to predictions made through the predictive portion of the algorithm (Steps S4-S16; Figure 1) and the bottom graph presents the catalogue contribution for the algorithm (Steps S1-S3; Figure 1). Note that the sum of the predictive and catalogue contributions can be over 100% as there is overlap between predictions made through both.

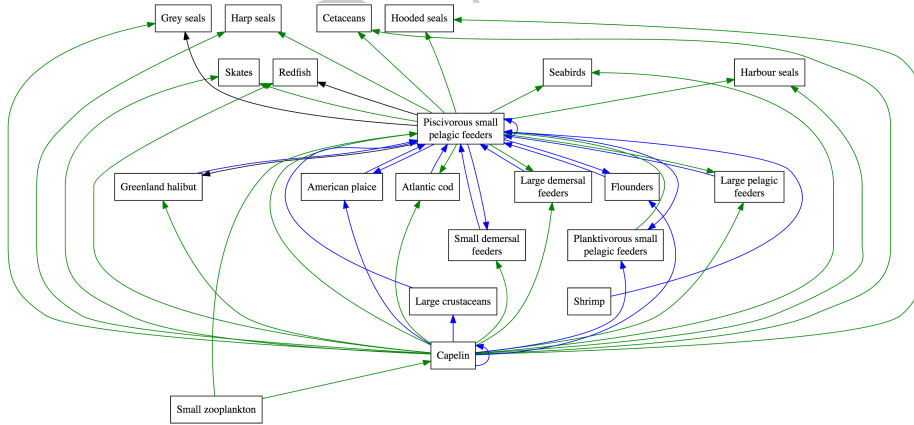


Figure 4: Example of results from the algorithm with the Network of the southern Gulf of St. Lawrence (Savenkoff et al., 2004) centered on interactions of the capelin (*Mallotus villosus*) and piscivorous small pelagic feeders (*e.g.* *Scomber scombrus* and *Illex illecebrosus*). Edge with colors green were both predicted and observed (26), black were observed only (3) and blue were predicted only (19). Arrows are pointed towards consumers.