

Applied Statistics with R

David Dalpiaz

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Chapter 1

Introduction

Welcome to Applied Statistics with R!

1.1 About This Book

This book was originally (and currently) designed for use with STAT 420, Methods of Applied Statistics, at the University of Illinois at Urbana-Champaign. It may certainly be used elsewhere, but any references to “this course” in this book specifically refer to STAT 420.

This book is under active development. When possible, it would be best to always access the text online to be sure you are using the most up-to-date version. Also, the html version provides additional features such as changing text size, font, and colors. If you are in need of a local copy, a **pdf version** is continuously maintained.

Since this book is under active development you may encounter errors ranging from typos, to broken code, to poorly explained topics. If you do, please let us know! Simply send an email and we will make the changes as soon as possible. (`dalpiaz2 AT illinois DOT edu`) Or, if you know RMarkdown and are familiar with GitHub, make a pull request and fix an issue yourself! This process is partially automated by the edit button in the top-left corner of the html version. If your suggestion or fix becomes part of the book, you will be added to the list at the end of this chapter. We’ll also link to your GitHub account, or personal website upon request.

This text uses MathJax to render mathematical notation for the web. Occasionally, but rarely, a JavaScript error will prevent MathJax from rendering correctly. In this case, you will see the “code” instead of the expected mathematical equations. From experience, this is almost always fixed by simply refreshing the page. You’ll also notice that if you right-click any equation you can obtain the MathML Code (for copying into Microsoft Word) or the TeX command used to generate the equation.

$$a^2 + b^2 = c^2$$

1.2 Conventions

R code will be typeset using a `monospace` font which is syntax highlighted.

```
a = 3
b = 4
sqrt(a ^ 2 + b ^ 2)
```

R output lines, which would appear in the console will begin with `##`. They will generally not be syntax highlighted.

```
## [1] 5
```

We use the quantity p to refer to the number of β parameters in a linear model, **not** the number of predictors.

1.3 Acknowledgements

Material in this book was heavily influenced by:

- Alex Stepanov
 - Longtime instructor of STAT 420 at the University of Illinois at Urbana-Champaign. The author of this book actually took Alex's STAT 420 class many years ago! Alex provided or inspired many of the examples in the text.
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- James Balamuta
 - Current graduate student at the University of Illinois at Urbana-Champaign. Provided the initial push to write this book by introducing the author to the `bookdown` package in R. Also a frequent contributor via GitHub.

Your name could be here! Suggest an edit! Correct a typo! If you submit a correction and would like to be listed below, please provide your name as you would like it to appear, as well as a link to a GitHub, LinkedIn, or personal website.

- Daniel McQuillan
- Mason Rubenstein
- Yuhang Wang
- Zhao Liu
- Jinfeng Xiao
- Somu Palaniappan
- Michael Hung-Yiu Chan
- Eloise Rosen

1.4 License



Figure 1.1: This work is licensed under a Creative Commons Attribution-NonCommercial-ShareAlike 4.0 International License.

Chapter 2

Introduction to R

2.1 Getting Started

R is both a programming language and software environment for statistical computing, which is *free* and *open-source*. To get started, you will need to install two pieces of software:

- R, the actual programming language.
 - Choose your operating system, and select the most recent version, 3.4.1.
- RStudio, an excellent IDE for working with R.
 - Note, you must have R installed to use RStudio. RStudio is simply an interface used to interact with R.

The popularity of R is on the rise, and everyday it becomes a better tool for statistical analysis. It even generated this book! (A skill you will learn in this course.) There are many good resources for learning R.

The following few chapters will serve as a whirlwind introduction to R. They are by no means meant to be a complete reference for the R language, but simply an introduction to the basics that we will need along the way. Several of the more important topics will be re-stressed as they are actually needed for analyses.

These introductory R chapters may feel like an overwhelming amount of information. You are not expected to pick up everything the first time through. You should try all of the code from these chapters, then return to them a number of times as you return to the concepts when performing analyses.

R is used both for software development and data analysis. We will operate in a grey area, somewhere between these two tasks. Our main goal will be to analyze data, but we will also perform programming exercises that help illustrate certain concepts.

RStudio has a large number of useful keyboard shortcuts. A list of these can be found using a keyboard shortcut – the keyboard shortcut to rule them all:

- On Windows: **Alt + Shift + K**
- On Mac: **Option + Shift + K**

The RStudio team has developed a number of “cheatsheets” for working with both R and RStudio. This particular cheatsheet for Base R will summarize many of the concepts in this document.

When programming, it is often a good practice to follow a style guide. (Where do spaces go? Tabs or spaces? Underscores or CamelCase when naming variables?) No style guide is “correct” but it helps to be aware of what others do. The more import thing is to be consistent within your own code.

- Hadley Wickham Style Guide from Advanced R
- Google Style Guide

For this course, our main deviation from these two guides is the use of `=` in place of `<-`. (More on that later.)

2.2 Basic Calculations

To get started, we'll use R like a simple calculator.

Addition, Subtraction, Multiplication and Division

Math	R	Result
$3 + 2$	<code>3 + 2</code>	5
$3 - 2$	<code>3 - 2</code>	1
$3 \cdot 2$	<code>3 * 2</code>	6
$3/2$	<code>3 / 2</code>	1.5

Exponents

Math	R	Result
3^2	<code>3 ^ 2</code>	9
$2^{(-3)}$	<code>2 ^ (-3)</code>	0.125
$100^{1/2}$	<code>100 ^ (1 / 2)</code>	10
$\sqrt{100}$	<code>sqrt(100)</code>	10

Mathematical Constants

Math	R	Result
π	<code>pi</code>	3.1415927
e	<code>exp(1)</code>	2.7182818

Logarithms

Note that we will use `ln` and `log` interchangeably to mean the natural logarithm. There is no `ln()` in R, instead it uses `log()` to mean the natural logarithm.

Math	R	Result
$\log(e)$	<code>log(exp(1))</code>	1
$\log_{10}(1000)$	<code>log10(1000)</code>	3
$\log_2(8)$	<code>log2(8)</code>	3
$\log_4(16)$	<code>log(16, base = 4)</code>	2

Trigonometry

Math	R	Result
$\sin(\pi/2)$	<code>sin(pi / 2)</code>	1
$\cos(0)$	<code>cos(0)</code>	1

2.3 Getting Help

In using R as a calculator, we have seen a number of functions: `sqrt()`, `exp()`, `log()` and `sin()`. To get documentation about a function in R, simply put a question mark in front of the function name and RStudio will display the documentation, for example:

```
?log
?sin
?paste
?lm
```

Frequently one of the most difficult things to do when learning R is asking for help. First, you need to decide to ask for help, then you need to know *how* to ask for help. Your very first line of defense should be to Google your error message or a short description of your issue. (The ability to solve problems using this method is quickly becoming an extremely valuable skill.) If that fails, and it eventually will, you should ask for help. There are a number of things you should include when emailing an instructor, or posting to a help website such as Stack Exchange.

- Describe what you expect the code to do.
- State the end goal you are trying to achieve. (Sometimes what you expect the code to do, is not what you want to actually do.)
- Provide the full text of any errors you have received.
- Provide enough code to recreate the error. Often for the purpose of this course, you could simply email your entire .R or .Rmd file.
- Sometimes it is also helpful to include a screenshot of your entire RStudio window when the error occurs.

If you follow these steps, you will get your issue resolved much quicker, and possibly learn more in the process. Do not be discouraged by running into errors and difficulties when learning R. (Or any technical skill.) It is simply part of the learning process.

2.4 Installing Packages

R comes with a number of built-in functions and datasets, but one of the main strengths of R as an open-source project is its package system. Packages add additional functions and data. Frequently if you want to do something in R, and it is not available by default, there is a good chance that there is a package that will fulfill your needs.

To install a package, use the `install.packages()` function. Think of this as buying a recipe book from the store, bringing it home, and putting it on your shelf.

```
install.packages("ggplot2")
```

Once a package is installed, it must be loaded into your current R session before being used. Think of this as taking the book off of the shelf and opening it up to read.

```
library(ggplot2)
```

Once you close R, all the packages are closed and put back on the imaginary shelf. The next time you open R, you do not have to install the package again, but you do have to load any packages you intend to use by invoking `library()`.

Chapter 3

Data and Programming

3.1 Data Types

R has a number of basic data *types*.

- Numeric
 - Also known as Double. The default type when dealing with numbers.
 - Examples: 1, 1.0, 42.5
- Integer
 - Examples: 1L, 2L, 42L
- Complex
 - Example: 4 + 2i
- Logical
 - Two possible values: TRUE and FALSE
 - You can also use T and F, but this is *not* recommended.
 - NA is also considered logical.
- Character
 - Examples: "a", "Statistics", "1 plus 2."

3.2 Data Structures

R also has a number of basic data *structures*. A data structure is either homogeneous (all elements are of the same data type) or heterogeneous (elements can be of more than one data type).

Dimension	Homogeneous	Heterogeneous
1	Vector	List
2	Matrix	Data Frame
3+	Array	

3.2.1 Vectors

Many operations in R make heavy use of **vectors**. Vectors in R are indexed starting at 1. That is what the [1] in the output is indicating, that the first element of the row being displayed is the first element of the vector. Larger vectors will start additional rows with [*] where * is the index of the first element of the row.

Possibly the most common way to create a vector in R is using the `c()` function, which is short for “combine.” As the name suggests, it combines a list of elements separated by commas.

```
c(1, 3, 5, 7, 8, 9)
```

```
## [1] 1 3 5 7 8 9
```

Here R simply outputs this vector. If we would like to store this vector in a **variable** we can do so with the **assignment** operator `=`. In this case the variable `x` now holds the vector we just created, and we can access the vector by typing `x`.

```
x = c(1, 3, 5, 7, 8, 9)
x
```

```
## [1] 1 3 5 7 8 9
```

As an aside, there is a long history of the assignment operator in R, partially due to the keys available on the keyboards of the creators of the S language. (Which preceded R.) For simplicity we will use `=`, but know that often you will see `<-` as the assignment operator.

The pros and cons of these two are well beyond the scope of this book, but know that for our purposes you will have no issue if you simply use `=`. If you are interested in the weird cases where the difference matters, check out The R Inferno.

If you wish to use `<-`, you will still need to use `=`, however only for argument passing. Some users like to keep assignment (`<-`) and argument passing (`=`) separate. No matter what you choose, the more important thing is that you **stay consistent**. Also, if working on a larger collaborative project, you should use whatever style is already in place.

Because vectors must contain elements that are all the same type, R will automatically coerce to a single type when attempting to create a vector that combines multiple types.

```
c(42, "Statistics", TRUE)
```

```
## [1] "42"           "Statistics"    "TRUE"
```

```
c(42, TRUE)
```

```
## [1] 42  1
```

Frequently you may wish to create a vector based on a sequence of numbers. The quickest and easiest way to do this is with the `:` operator, which creates a sequence of integers between two specified integers.

```
(y = 1:100)
```

```
## [1] 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18
## [19] 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36
## [37] 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54
## [55] 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72
## [73] 73 74 75 76 77 78 79 80 81 82 83 84 85 86 87 88 89 90
## [91] 91 92 93 94 95 96 97 98 99 100
```

Here we see R labeling the rows after the first since this is a large vector. Also, we see that by putting parentheses around the assignment, R both stores the vector in a variable called `y` and automatically outputs `y` to the console.

Note that scalars do not exists in R. They are simply vectors of length 1.

```
2
```

```
## [1] 2
```

If we want to create a sequence that isn't limited to integers and increasing by 1 at a time, we can use the `seq()` function.

```
seq(from = 1.5, to = 4.2, by = 0.1)
```

```
## [1] 1.5 1.6 1.7 1.8 1.9 2.0 2.1 2.2 2.3 2.4 2.5 2.6 2.7 2.8 2.9 3.0 3.1 3.2 3.3
## [20] 3.4 3.5 3.6 3.7 3.8 3.9 4.0 4.1 4.2
```

We will discuss functions in detail later, but note here that the input labels `from`, `to`, and `by` are optional.

```
seq(1.5, 4.2, 0.1)
```

```
## [1] 1.5 1.6 1.7 1.8 1.9 2.0 2.1 2.2 2.3 2.4 2.5 2.6 2.7 2.8 2.9 3.0 3.1 3.2 3.3
## [20] 3.4 3.5 3.6 3.7 3.8 3.9 4.0 4.1 4.2
```

Another common operation to create a vector is `rep()`, which can repeat a single value a number of times.

```
rep("A", times = 10)
```

```
## [1] "A" "A" "A" "A" "A" "A" "A" "A" "A" "A"
```

The `rep()` function can be used to repeat a vector some number of times.

```
rep(x, times = 3)
```

```
## [1] 1 3 5 7 8 9 1 3 5 7 8 9 1 3 5 7 8 9
```

We have now seen four different ways to create vectors:

- `c()`
- `:`
- `seq()`
- `rep()`

So far we have mostly used them in isolation, but they are often used together.

```
c(x, rep(seq(1, 9, 2), 3), c(1, 2, 3), 42, 2:4)

## [1] 1 3 5 7 8 9 1 3 5 7 9 1 3 5 7 9 1 3 5 7 9 1 2 3 42
## [26] 2 3 4
```

The length of a vector can be obtained with the `length()` function.

```
length(x)
```

```
## [1] 6
```

```
length(y)
```

```
## [1] 100
```

3.2.1.1 Subsetting

To subset a vector, we use square brackets, `[]`.

```
x
```

```
## [1] 1 3 5 7 8 9
```

```
x[1]
```

```
## [1] 1
```

```
x[3]
```

```
## [1] 5
```

We see that `x[1]` returns the first element, and `x[3]` returns the third element.

```
x[-2]
```

```
## [1] 1 5 7 8 9
```

We can also exclude certain indexes, in this case the second element.

```
x[1:3]
```

```
## [1] 1 3 5
```

```
x[c(1,3,4)]
```

```
## [1] 1 5 7
```

Lastly we see that we can subset based on a vector of indices.

All of the above are subsetting a vector using a vector of indexes. (Remember a single number is still a vector.) We could instead use a vector of logical values.

```
z = c(TRUE, TRUE, FALSE, TRUE, TRUE, FALSE)
z
```

```
## [1] TRUE TRUE FALSE TRUE TRUE FALSE
```

```
x[z]
```

```
## [1] 1 3 7 8
```

3.2.2 Vectorization

One of the biggest strengths of R is its use of vectorized operations. (Frequently the lack of understanding of this concept leads of a belief that R is *slow*. R is not the fastest language, but it has a reputation for being slower than it really is.)

```
x = 1:10
x + 1
```

```
## [1] 2 3 4 5 6 7 8 9 10 11
```

```
2 * x
```

```
## [1] 2 4 6 8 10 12 14 16 18 20
```

```
2 ^ x
```

```
## [1] 2 4 8 16 32 64 128 256 512 1024
```

```
sqrt(x)
```

```
## [1] 1.000000 1.414214 1.732051 2.000000 2.236068 2.449490 2.645751 2.828427
## [9] 3.000000 3.162278
```

```
log(x)
```

```
## [1] 0.0000000 0.6931472 1.0986123 1.3862944 1.6094379 1.7917595 1.9459101
## [8] 2.0794415 2.1972246 2.3025851
```

We see that when a function like `log()` is called on a vector `x`, a vector is returned which has applied the function to each element of the vector `x`.

Operator	Summary	Example	Result
----------	---------	---------	--------

3.2.3 Logical Operators

Operator	Summary	Example	Result
<code>x < y</code>	<code>x</code> less than <code>y</code>	<code>3 < 42</code>	TRUE
<code>x > y</code>	<code>x</code> greater than <code>y</code>	<code>3 > 42</code>	FALSE
<code>x <= y</code>	<code>x</code> less than or equal to <code>y</code>	<code>3 <= 42</code>	TRUE
<code>x >= y</code>	<code>x</code> greater than or equal to <code>y</code>	<code>3 >= 42</code>	FALSE
<code>x == y</code>	<code>x</code> equal to <code>y</code>	<code>3 == 42</code>	FALSE
<code>x != y</code>	<code>x</code> not equal to <code>y</code>	<code>3 != 42</code>	TRUE
<code>!x</code>	not <code>x</code>	<code>!(3 > 42)</code>	TRUE
<code>x y</code>	<code>x</code> or <code>y</code>	<code>(3 > 42) TRUE</code>	TRUE
<code>x & y</code>	<code>x</code> and <code>y</code>	<code>(3 < 4) & (42 > 13)</code>	TRUE

In R, logical operators are vectorized.

```
x = c(1, 3, 5, 7, 8, 9)

x > 3
## [1] FALSE FALSE  TRUE  TRUE  TRUE  TRUE

x < 3
## [1]  TRUE FALSE FALSE FALSE FALSE FALSE

x == 3
## [1] FALSE  TRUE FALSE FALSE FALSE FALSE

x != 3
## [1]  TRUE FALSE  TRUE  TRUE  TRUE  TRUE

x == 3 & x != 3
## [1] FALSE FALSE FALSE FALSE FALSE FALSE

x == 3 | x != 3
## [1]  TRUE  TRUE  TRUE  TRUE  TRUE  TRUE
```

This is extremely useful for subsetting.

```
x[x > 3]

## [1] 5 7 8 9
```

```
x[x != 3]

## [1] 1 5 7 8 9
```

- TODO: coercion

```
sum(x > 3)

## [1] 4

as.numeric(x > 3)

## [1] 0 0 1 1 1 1
```

Here we see that using the `sum()` function on a vector of logical TRUE and FALSE values that is the result of `x > 3` results in a numeric result. R is first automatically coercing the logical to numeric where TRUE is 1 and FALSE is 0. This coercion from logical to numeric happens for most mathematical operations.

```
which(x > 3)

## [1] 3 4 5 6

x[which(x > 3)]

## [1] 5 7 8 9

max(x)

## [1] 9

which(x == max(x))

## [1] 6

which.max(x)

## [1] 6
```

3.2.4 More Vectorization

```

x = c(1, 3, 5, 7, 8, 9)
y = 1:100

x + 2

## [1] 3 5 7 9 10 11

x + rep(2, 6)

## [1] 3 5 7 9 10 11

x > 3

## [1] FALSE FALSE TRUE TRUE TRUE TRUE

x > rep(3, 6)

## [1] FALSE FALSE TRUE TRUE TRUE TRUE

x + y

## Warning in x + y: longer object length is not a multiple of shorter object
## length

## [1] 2 5 8 11 13 15 8 11 14 17 19 21 14 17 20 23 25 27
## [19] 20 23 26 29 31 33 26 29 32 35 37 39 32 35 38 41 43 45
## [37] 38 41 44 47 49 51 44 47 50 53 55 57 50 53 56 59 61 63
## [55] 56 59 62 65 67 69 62 65 68 71 73 75 68 71 74 77 79 81
## [73] 74 77 80 83 85 87 80 83 86 89 91 93 86 89 92 95 97 99
## [91] 92 95 98 101 103 105 98 101 104 107

length(x)

## [1] 6

length(y)

## [1] 100

length(y) / length(x)

## [1] 16.66667

(x + y) - y

## Warning in x + y: longer object length is not a multiple of shorter object
## length

## [1] 1 3 5 7 8 9 1 3 5 7 8 9 1 3 5 7 8 9 1 3 5 7 8 9 1 3 5 7 8 9 1
## [38] 3 5 7 8 9 1 3 5 7 8 9 1 3 5 7 8 9 1 3 5 7 8 9 1 3 5 7 8 9 1 3 5 7 8 9 1 3
## [75] 5 7 8 9 1 3 5 7 8 9 1 3 5 7 8 9 1 3 5 7 8 9 1 3 5 7

```

```

y = 1:60
x + y

## [1]  2  5  8 11 13 15  8 11 14 17 19 21 14 17 20 23 25 27 20 23 26 29 31 33 26
## [26] 29 32 35 37 39 32 35 38 41 43 45 38 41 44 47 49 51 44 47 50 53 55 57 50 53
## [51] 56 59 61 63 56 59 62 65 67 69

length(y) / length(x)

## [1] 10

rep(x, 10) + y

## [1]  2  5  8 11 13 15  8 11 14 17 19 21 14 17 20 23 25 27 20 23 26 29 31 33 26
## [26] 29 32 35 37 39 32 35 38 41 43 45 38 41 44 47 49 51 44 47 50 53 55 57 50 53
## [51] 56 59 61 63 56 59 62 65 67 69

all(x + y == rep(x, 10) + y)

## [1] TRUE

identical(x + y, rep(x, 10) + y)

## [1] TRUE

# ?any
# ?all.equal

```

3.2.5 Matrices

R can also be used for **matrix** calculations. Matrices have rows and columns containing a single data type. In a matrix, the order of rows and columns is important. (This is not true of *data frames*, which we will see later.)

Matrices can be created using the **matrix** function.

```

x = 1:9
x

## [1] 1 2 3 4 5 6 7 8 9

X = matrix(x, nrow = 3, ncol = 3)
X

##      [,1] [,2] [,3]
## [1,]    1    4    7
## [2,]    2    5    8
## [3,]    3    6    9

```

Note here that we are using two different variables: lower case `x`, which stores a vector and capital `X`, which stores a matrix. (Following the usual mathematical convention.) We can do this because R is case sensitive.

By default the `matrix` function reorders a vector into columns, but we can also tell R to use rows instead.

```
Y = matrix(x, nrow = 3, ncol = 3, byrow = TRUE)
Y
```

```
##      [,1] [,2] [,3]
## [1,]    1    2    3
## [2,]    4    5    6
## [3,]    7    8    9
```

We can also create a matrix of a specified dimension where every element is the same, in this case 0.

```
Z = matrix(0, 2, 4)
Z
```

```
##      [,1] [,2] [,3] [,4]
## [1,]    0    0    0    0
## [2,]    0    0    0    0
```

Like vectors, matrices can be subsetted using square brackets, `[]`. However, since matrices are two-dimensional, we need to specify both a row and a column when subsetting.

```
X
```

```
##      [,1] [,2] [,3]
## [1,]    1    4    7
## [2,]    2    5    8
## [3,]    3    6    9
```

```
X[1, 2]
```

```
## [1] 4
```

Here we accessed the element in the first row and the second column. We could also subset an entire row or column.

```
X[1, ]
```

```
## [1] 1 4 7
```

```
X[, 2]
```

```
## [1] 4 5 6
```

We can also use vectors to subset more than one row or column at a time. Here we subset to the first and third column of the second row.

```
X[2, c(1, 3)]
```

```
## [1] 2 8
```

Matrices can also be created by combining vectors as columns, using `cbind`, or combining vectors as rows, using `rbind`.

```
x = 1:9
rev(x)
```

```
## [1] 9 8 7 6 5 4 3 2 1
```

```
rep(1, 9)
```

```
## [1] 1 1 1 1 1 1 1 1 1
```

```
rbind(x, rev(x), rep(1, 9))
```

```
## [,1] [,2] [,3] [,4] [,5] [,6] [,7] [,8] [,9]
## x     1     2     3     4     5     6     7     8     9
##      9     8     7     6     5     4     3     2     1
##      1     1     1     1     1     1     1     1     1
```

```
cbind(col_1 = x, col_2 = rev(x), col_3 = rep(1, 9))
```

```
##           col_1 col_2 col_3
## [1,]       1     9     1
## [2,]       2     8     1
## [3,]       3     7     1
## [4,]       4     6     1
## [5,]       5     5     1
## [6,]       6     4     1
## [7,]       7     3     1
## [8,]       8     2     1
## [9,]       9     1     1
```

When using `rbind` and `cbind` you can specify “argument” names that will be used as column names.

R can then be used to perform matrix calculations.

```
x = 1:9
y = 9:1
X = matrix(x, 3, 3)
Y = matrix(y, 3, 3)
X
```

```
##           [,1] [,2] [,3]
## [1,]       1     4     7
## [2,]       2     5     8
## [3,]       3     6     9
```

Y

```
##      [,1] [,2] [,3]
## [1,]    9    6    3
## [2,]    8    5    2
## [3,]    7    4    1
```

X + Y

```
##      [,1] [,2] [,3]
## [1,]   10   10   10
## [2,]   10   10   10
## [3,]   10   10   10
```

X - Y

```
##      [,1] [,2] [,3]
## [1,]   -8   -2    4
## [2,]   -6    0    6
## [3,]   -4    2    8
```

X * Y

```
##      [,1] [,2] [,3]
## [1,]    9   24   21
## [2,]   16   25   16
## [3,]   21   24    9
```

X / Y

```
##      [,1]      [,2]      [,3]
## [1,] 0.1111111 0.6666667 2.333333
## [2,] 0.2500000 1.0000000 4.000000
## [3,] 0.4285714 1.5000000 9.000000
```

Note that `X * Y` is not matrix multiplication. It is element by element multiplication. (Same for `X / Y`). Instead, matrix multiplication uses `%*%`. Other matrix functions include `t()` which gives the transpose of a matrix and `solve()` which returns the inverse of a square matrix if it is invertible.

X %*% Y

```
##      [,1] [,2] [,3]
## [1,]   90   54   18
## [2,]  114   69   24
## [3,]  138   84   30
```

`t(X)`

```
##      [,1] [,2] [,3]
## [1,]    1    2    3
## [2,]    4    5    6
## [3,]    7    8    9
```

```
Z = matrix(c(9, 2, -3, 2, 4, -2, -3, -2, 16), 3, byrow = TRUE)
Z
```

```
##      [,1] [,2] [,3]
## [1,]    9    2   -3
## [2,]    2    4   -2
## [3,]   -3   -2   16

solve(Z)

##           [,1]           [,2]           [,3]
## [1,]  0.12931034 -0.05603448  0.01724138
## [2,] -0.05603448  0.29094828  0.02586207
## [3,]  0.01724138  0.02586207  0.06896552
```

To verify that `solve(Z)` returns the inverse, we multiply it by `Z`. We would expect this to return the identity matrix, however we see that this is not the case due to some computational issues. However, R also has the `all.equal()` function which checks for equality, with some small tolerance which accounts for some computational issues. The `identical()` function is used to check for exact equality.

```
solve(Z) %*% Z
```

```
##           [,1]           [,2]           [,3]
## [1,] 1.000000e+00 -6.245005e-17  0.000000e+00
## [2,] 8.326673e-17  1.000000e+00  5.551115e-17
## [3,] 2.775558e-17  0.000000e+00  1.000000e+00
```

```
diag(3)
```

```
##      [,1] [,2] [,3]
## [1,]    1    0    0
## [2,]    0    1    0
## [3,]    0    0    1
```

```
all.equal(solve(Z) %*% Z, diag(3))
```

```
## [1] TRUE
```

R has a number of matrix specific functions for obtaining dimension and summary information.

```
X = matrix(1:6, 2, 3)
X
```

```
##      [,1] [,2] [,3]
## [1,]    1    3    5
## [2,]    2    4    6
```

```
dim(X)

## [1] 2 3

rowSums(X)

## [1] 9 12

colSums(X)

## [1] 3 7 11

rowMeans(X)

## [1] 3 4

colMeans(X)

## [1] 1.5 3.5 5.5
```

The `diag()` function can be used in a number of ways. We can extract the diagonal of a matrix.

```
diag(Z)

## [1] 9 4 16
```

Or create a matrix with specified elements on the diagonal. (And 0 on the off-diagonals.)

```
diag(1:5)

##      [,1] [,2] [,3] [,4] [,5]
## [1,]    1    0    0    0    0
## [2,]    0    2    0    0    0
## [3,]    0    0    3    0    0
## [4,]    0    0    0    4    0
## [5,]    0    0    0    0    5
```

Or, lastly, create a square matrix of a certain dimension with 1 for every element of the diagonal and 0 for the off-diagonals.

```
diag(5)

##      [,1] [,2] [,3] [,4] [,5]
## [1,]    1    0    0    0    0
## [2,]    0    1    0    0    0
## [3,]    0    0    1    0    0
## [4,]    0    0    0    1    0
## [5,]    0    0    0    0    1
```

Calculations with Vectors and Matrices

Certain operations in R, for example `%*%` have different behavior on vectors and matrices. To illustrate this, we will first create two vectors.

```
a_vec = c(1, 2, 3)
b_vec = c(2, 2, 2)
```

Note that these are indeed vectors. They are not matrices.

```
c(is.vector(a_vec), is.vector(b_vec))
```

```
## [1] TRUE TRUE
```

```
c(is.matrix(a_vec), is.matrix(b_vec))
```

```
## [1] FALSE FALSE
```

When this is the case, the `%*%` operator is used to calculate the **dot product**, also known as the **inner product** of the two vectors.

The dot product of vectors $\mathbf{a} = [a_1, a_2, \dots, a_n]$ and $\mathbf{b} = [b_1, b_2, \dots, b_n]$ is defined to be

$$\mathbf{a} \cdot \mathbf{b} = \sum_{i=1}^n a_i b_i = a_1 b_1 + a_2 b_2 + \dots + a_n b_n.$$

```
a_vec %*% b_vec # inner product
```

```
##      [,1]
## [1,]    12
```

```
a_vec %o% b_vec # outer product
```

```
##      [,1] [,2] [,3]
## [1,]    2    2    2
## [2,]    4    4    4
## [3,]    6    6    6
```

The `%o%` operator is used to calculate the **outer product** of the two vectors.

When vectors are coerced to become matrices, they are column vectors. So a vector of length n becomes an $n \times 1$ matrix after coercion.

```
as.matrix(a_vec)
```

```
##      [,1]
## [1,]    1
## [2,]    2
## [3,]    3
```

If we use the `%*%` operator on matrices, `%*%` again performs the expected matrix multiplication. So you might expect the following to produce an error, because the dimensions are incorrect.

```
as.matrix(a_vec) %*% b_vec
```

```
##      [,1] [,2] [,3]
## [1,]    2    2    2
## [2,]    4    4    4
## [3,]    6    6    6
```

At face value this is a 3×1 matrix, multiplied by a 3×1 matrix. However, when `b_vec` is automatically coerced to be a matrix, R decided to make it a “row vector”, a 1×3 matrix, so that the multiplication has conformable dimensions.

If we had coerced both, then R would produce an error.

```
as.matrix(a_vec) %*% as.matrix(b_vec)
```

Another way to calculate a *dot product* is with the `crossprod()` function. Given two vectors, the `crossprod()` function calculates their dot product. The function has a rather misleading name.

```
crossprod(a_vec, b_vec) # inner product
```

```
##      [,1]
## [1,]    12
```

```
tcrossprod(a_vec, b_vec) # outer product
```

```
##      [,1] [,2] [,3]
## [1,]    2    2    2
## [2,]    4    4    4
## [3,]    6    6    6
```

These functions could be very useful later. When used with matrices X and Y as arguments, it calculates

$$X^\top Y.$$

When dealing with linear models, the calculation

$$X^\top X$$

is used repeatedly.

```
C_mat = matrix(c(1, 2, 3, 4, 5, 6), 2, 3)
D_mat = matrix(c(2, 2, 2, 2, 2, 2), 2, 3)
```

This is useful both as a shortcut for a frequent calculation and as a more efficient implementation than using `t()` and `%*%`.

```
crossprod(C_mat, D_mat)
```

```
##      [,1] [,2] [,3]
## [1,]    6    6    6
## [2,]   14   14   14
## [3,]   22   22   22
```

```
t(C_mat) %*% D_mat

##      [,1] [,2] [,3]
## [1,]    6    6    6
## [2,]   14   14   14
## [3,]   22   22   22

all.equal(crossprod(C_mat, D_mat), t(C_mat) %*% D_mat)
```

```
## [1] TRUE
```

```
crossprod(C_mat, C_mat)
```

```
##      [,1] [,2] [,3]
## [1,]    5   11   17
## [2,]   11   25   39
## [3,]   17   39   61
```

```
t(C_mat) %*% C_mat
```

```
##      [,1] [,2] [,3]
## [1,]    5   11   17
## [2,]   11   25   39
## [3,]   17   39   61
```

```
all.equal(crossprod(C_mat, C_mat), t(C_mat) %*% C_mat)
```

```
## [1] TRUE
```

3.2.6 Lists

A list is a one-dimensional heterogeneous data structure. So it is indexed like a vector with a single integer value, but each element can contain an element of any type.

```
# creation
list(42, "Hello", TRUE)
```

```
## [[1]]
## [1] 42
##
## [[2]]
## [1] "Hello"
##
## [[3]]
## [1] TRUE
```

```
ex_list = list(
  a = c(1, 2, 3, 4),
  b = TRUE,
  c = "Hello!",
  d = function(arg = 42) {print("Hello World!")},
  e = diag(5)
)
```

Lists can be subset using two syntaxes, the `$` operator, and square brackets `[]`. The `$` operator returns a named **element** of a list. The `[]` syntax returns a **list**, while the `[[]]` returns an **element** of a list.

- `ex_list[1]` returns a list contain the first element.
- `ex_list[[1]]` returns the first element of the list, in this case, a vector.

```
# subsetting
ex_list$c
```

```
##      [,1] [,2] [,3] [,4] [,5]
## [1,]     1     0     0     0     0
## [2,]     0     1     0     0     0
## [3,]     0     0     1     0     0
## [4,]     0     0     0     1     0
## [5,]     0     0     0     0     1
```

```
ex_list[1:2]
```

```
## $a
## [1] 1 2 3 4
##
## $b
## [1] TRUE
```

```
ex_list[1]
```

```
## $a
## [1] 1 2 3 4
```

```
ex_list[[1]]
```

```
## [1] 1 2 3 4
```

```
ex_list[c("e", "a")]
```

```
## $e
##      [,1] [,2] [,3] [,4] [,5]
## [1,]     1     0     0     0     0
## [2,]     0     1     0     0     0
## [3,]     0     0     1     0     0
## [4,]     0     0     0     1     0
## [5,]     0     0     0     0     1
##
## $a
## [1] 1 2 3 4
```

```
ex_list["e"]
```

```
## $e
##      [,1] [,2] [,3] [,4] [,5]
## [1,]    1    0    0    0    0
## [2,]    0    1    0    0    0
## [3,]    0    0    1    0    0
## [4,]    0    0    0    1    0
## [5,]    0    0    0    0    1
```

```
ex_list[["e"]]
```

```
##      [,1] [,2] [,3] [,4] [,5]
## [1,]    1    0    0    0    0
## [2,]    0    1    0    0    0
## [3,]    0    0    1    0    0
## [4,]    0    0    0    1    0
## [5,]    0    0    0    0    1
```

```
ex_list$d
```

```
## function(arg = 42) {print("Hello World!")}
```

```
ex_list$d(arg = 1)
```

```
## [1] "Hello World!"
```

3.2.7 Data Frames

We have previously seen vectors and matrices for storing data as we introduced R. We will now introduce a **data frame** which will be the most common way that we store and interact with data in this course.

```
example_data = data.frame(x = c(1, 3, 5, 7, 9, 1, 3, 5, 7, 9),
                           y = c(rep("Hello", 9), "Goodbye"),
                           z = rep(c(TRUE, FALSE), 5))
```

Unlike a matrix, which can be thought of as a vector rearranged into rows and columns, a data frame is not required to have the same data type for each element. A data frame is a **list** of vectors. So, each vector must contain the same data type, but the different vectors can store different data types.

```
example_data
```

```
##   x     y     z
## 1 1 Hello TRUE
## 2 3 Hello FALSE
## 3 5 Hello TRUE
## 4 7 Hello FALSE
## 5 9 Hello TRUE
## 6 1 Hello FALSE
```

```
## 7 3 Hello TRUE
## 8 5 Hello FALSE
## 9 7 Hello TRUE
## 10 9 Goodbye FALSE
```

Unlike a list which has more flexibility, the elements of a data frame must all be vectors, and have the same length.

```
example_data$x

## [1] 1 3 5 7 9 1 3 5 7 9

all.equal(length(example_data$x),
          length(example_data$y),
          length(example_data$z))

## [1] TRUE

str(example_data)

## 'data.frame': 10 obs. of 3 variables:
## $ x: num 1 3 5 7 9 1 3 5 7 9
## $ y: Factor w/ 2 levels "Goodbye","Hello": 2 2 2 2 2 2 2 2 2 1
## $ z: logi TRUE FALSE TRUE FALSE TRUE FALSE ...

nrow(example_data)

## [1] 10

ncol(example_data)

## [1] 3

dim(example_data)

## [1] 10 3
```

The `data.frame()` function above is one way to create a data frame. We can also import data from various file types in into R, as well as use data stored in packages.

The example data above can also be found here as a .csv file. To read this data into R, we would use the `read_csv()` function from the `readr` package. Note that R has a built in function `read.csv()` that operates very similarly. The `readr` function `read_csv()` has a number of advantages. For example, it is much faster reading larger data. It also uses the `tibble` package to read the data as a tibble.

```
library(readr)
example_data_from_csv = read_csv("data/example-data.csv")
```

This particular line of code assumes that the file `example_data.csv` exists in a folder called `data` in your current working directory.

```
example_data_from_csv
```

```
## # A tibble: 10 x 3
##       x     y     z
##   <int> <chr> <lgl>
## 1     1 Hello  TRUE
## 2     3 Hello FALSE
## 3     5 Hello  TRUE
## 4     7 Hello FALSE
## 5     9 Hello  TRUE
## 6     1 Hello FALSE
## 7     3 Hello  TRUE
## 8     5 Hello FALSE
## 9     7 Hello  TRUE
## 10    9 Goodbye FALSE
```

A tibble is simply a data frame that prints with sanity. Notice in the output above that we are given additional information such as dimension and variable type.

The `as_tibble()` function can be used to coerce a regular data frame to a tibble.

```
library(tibble)
example_data = as_tibble(example_data)
example_data
```

```
## # A tibble: 10 x 3
##       x     y     z
##   <dbl> <fctr> <lgl>
## 1     1 Hello  TRUE
## 2     3 Hello FALSE
## 3     5 Hello  TRUE
## 4     7 Hello FALSE
## 5     9 Hello  TRUE
## 6     1 Hello FALSE
## 7     3 Hello  TRUE
## 8     5 Hello FALSE
## 9     7 Hello  TRUE
## 10    9 Goodbye FALSE
```

Alternatively, we could use the “Import Dataset” feature in RStudio which can be found in the environment window. (By default, the top-right pane of RStudio.) Once completed, this process will automatically generate the code to import a file. The resulting code will be shown in the console window. In recent versions of RStudio, `read_csv()` is used by default, thus reading in a tibble.

Earlier we looked at installing packages, in particular the `ggplot2` package. (A package for visualization. While not necessary for this course, it is quickly growing in popularity.)

```
library(ggplot2)
```

Inside the `ggplot2` package is a dataset called `mpg`. By loading the package using the `library()` function, we can now access `mpg`.

When using data from inside a package, there are three things we would generally like to do:

- Look at the raw data.
- Understand the data. (Where did it come from? What are the variables? Etc.)
- Visualize the data.

To look at the data, we have two useful commands: `head()` and `str()`.

```
head(mpg, n = 10)
```

```
## # A tibble: 10 x 11
##   manufacturer     model displ year cyl trans   drv   cty   hwy fl
##   <chr>       <chr> <dbl> <int> <int> <chr> <chr> <int> <int> <chr>
## 1 audi         a4      1.8  1999     4 auto(15) f    18    29 p
## 2 audi         a4      1.8  1999     4 manual(m5) f    21    29 p
## 3 audi         a4      2.0  2008     4 manual(m6) f    20    31 p
## 4 audi         a4      2.0  2008     4 auto(av)   f    21    30 p
## 5 audi         a4      2.8  1999     6 auto(15)  f    16    26 p
## 6 audi         a4      2.8  1999     6 manual(m5) f    18    26 p
## 7 audi         a4      3.1  2008     6 auto(av)   f    18    27 p
## 8 audi a4 quattro 1.8  1999     4 manual(m5) 4    18    26 p
## 9 audi a4 quattro 1.8  1999     4 auto(15)   4    16    25 p
## 10 audi a4 quattro 2.0  2008    4 manual(m6) 4    20    28 p
## # ... with 1 more variables: class <chr>
```

The function `head()` will display the first `n` observations of the data frame. The `head()` function was more useful before tibbles. Notice that `mpg` is a tibble already, so the output from `head()` indicates there are only 10 observations. Note that this applies to `head(mpg, n = 10)` and not `mpg` itself. Also note that tibbles print a limited number of rows and columns by default. The last line of the printed output indicates with rows and columns were omitted.

```
mpg
```

```
## # A tibble: 234 x 11
##   manufacturer     model displ year cyl trans   drv   cty   hwy fl
##   <chr>       <chr> <dbl> <int> <int> <chr> <chr> <int> <int> <chr>
## 1 audi         a4      1.8  1999     4 auto(15) f    18    29 p
## 2 audi         a4      1.8  1999     4 manual(m5) f    21    29 p
## 3 audi         a4      2.0  2008     4 manual(m6) f    20    31 p
## 4 audi         a4      2.0  2008     4 auto(av)   f    21    30 p
## 5 audi         a4      2.8  1999     6 auto(15)  f    16    26 p
## 6 audi         a4      2.8  1999     6 manual(m5) f    18    26 p
## 7 audi         a4      3.1  2008     6 auto(av)   f    18    27 p
## 8 audi a4 quattro 1.8  1999     4 manual(m5) 4    18    26 p
## 9 audi a4 quattro 1.8  1999     4 auto(15)   4    16    25 p
## 10 audi a4 quattro 2.0  2008    4 manual(m6) 4    20    28 p
## # ... with 224 more rows, and 1 more variables: class <chr>
```

The function `str()` will display the “structure” of the data frame. It will display the number of **observations** and **variables**, list the variables, give the type of each variable, and show some elements of each variable. This information can also be found in the “Environment” window in RStudio.

```
str(mpg)
```

```
## Classes 'tbl_df', 'tbl' and 'data.frame': 234 obs. of 11 variables:
## $ manufacturer: chr "audi" "audi" "audi" "audi" ...
## $ model      : chr "a4" "a4" "a4" "a4" ...
## $ displ       : num 1.8 1.8 2 2 2.8 2.8 3.1 1.8 1.8 2 ...
## $ year        : int 1999 1999 2008 2008 1999 1999 2008 1999 1999 2008 ...
## $ cyl         : int 4 4 4 4 6 6 6 4 4 4 ...
## $ trans       : chr "auto(l5)" "manual(m5)" "manual(m6)" "auto(av)" ...
## $ drv         : chr "f" "f" "f" "f" ...
## $ cty         : int 18 21 20 21 16 18 18 18 16 20 ...
## $ hwy         : int 29 29 31 30 26 26 27 26 25 28 ...
## $ fl          : chr "p" "p" "p" "p" ...
## $ class       : chr "compact" "compact" "compact" "compact" ...
```

It is important to note that while matrices have rows and columns, data frames (tibbles) instead have observations and variables. When displayed in the console or viewer, each row is an observation and each column is a variable. However generally speaking, their order does not matter, it is simply a side-effect of how the data was entered or stored.

In this dataset an observation is for a particular model-year of a car, and the variables describe attributes of the car, for example its highway fuel efficiency.

To understand more about the data set, we use the `?` operator to pull up the documentation for the data.

```
?mpg
```

R has a number of functions for quickly working with and extracting basic information from data frames. To quickly obtain a vector of the variable names, we use the `names()` function.

```
names(mpg)
```

```
## [1] "manufacturer" "model"           "displ"          "year"          "cyl"
## [6] "trans"         "drv"             "cty"            "hwy"           "fl"
## [11] "class"
```

To access one of the variables **as a vector**, we use the `$` operator.

```
mpg$year
```

```
## [1] 1999 1999 2008 2008 1999 1999 2008 1999 1999 2008 2008 1999 1999 2008 2008
## [16] 1999 2008 2008 2008 1999 2008 1999 1999 2008 2008 2008 2008 2008 2008 2008
## [31] 1999 1999 1999 2008 1999 2008 1999 1999 1999 1999 2008 2008 2008 2008 1999
## [46] 1999 2008 2008 2008 1999 1999 2008 2008 2008 1999 1999 1999 2008 2008 2008
## [61] 2008 1999 2008 1999 2008 2008 2008 2008 2008 1999 1999 1999 2008 1999 1999
## [76] 1999 2008 1999 1999 1999 2008 2008 1999 1999 1999 1999 1999 2008 1999 2008
## [91] 1999 1999 2008 2008 1999 1999 2008 2008 1999 1999 1999 1999 1999 1999 2008
## [106] 2008 2008 2008 1999 1999 2008 2008 1999 1999 2008 1999 1999 2008 2008 2008
## [121] 2008 2008 2008 2008 1999 1999 2008 2008 2008 1999 2008 2008 1999 1999 1999
## [136] 1999 2008 1999 2008 2008 1999 1999 1999 2008 2008 2008 2008 1999 1999 2008
## [151] 1999 1999 2008 2008 1999 1999 1999 2008 2008 1999 1999 2008 2008 2008 2008
## [166] 1999 1999 1999 1999 2008 2008 2008 1999 1999 1999 1999 2008 2008 1999
```

```
## [181] 1999 2008 2008 1999 1999 2008 1999 1999 2008 2008 1999 1999 2008 1999 1999
## [196] 1999 2008 2008 1999 2008 1999 1999 2008 1999 1999 2008 2008 1999 1999 2008
## [211] 2008 1999 1999 1999 2008 2008 2008 1999 1999 1999 1999 1999 1999 1999
## [226] 2008 2008 1999 1999 2008 2008 1999 1999 2008
```

```
mpg$hwy
```

```
## [1] 29 29 31 30 26 26 27 26 25 28 27 25 25 25 25 24 25 23 20 15 20 17 17 26 23
## [26] 26 25 24 19 14 15 17 27 30 26 29 26 24 24 22 22 24 24 17 22 21 23 23 19 18
## [51] 17 17 19 19 12 17 15 17 17 12 17 16 18 15 16 12 17 17 16 12 15 16 17 15 17
## [76] 17 18 17 19 17 19 19 17 17 17 16 16 17 15 17 26 25 26 24 21 22 23 22 20 33
## [101] 32 32 29 32 34 36 36 29 26 27 30 31 26 26 28 26 29 28 27 24 24 24 22 19 20
## [126] 17 12 19 18 14 15 18 18 15 17 16 18 17 19 19 17 29 27 31 32 27 26 26 25 25
## [151] 17 17 20 18 26 26 27 28 25 25 24 27 25 26 23 26 26 26 25 27 25 27 20 20
## [176] 19 17 20 17 29 27 31 31 26 26 28 27 29 31 31 26 26 27 30 33 35 37 35 15 18
## [201] 20 20 22 17 19 18 20 29 26 29 29 24 44 29 26 29 29 29 23 24 44 41 29 26
## [226] 28 29 29 29 28 29 26 26 26
```

We can use the `dim()`, `nrow()` and `ncol()` functions to obtain information about the dimension of the data frame.

```
dim(mpg)
```

```
## [1] 234 11
```

```
nrow(mpg)
```

```
## [1] 234
```

```
ncol(mpg)
```

```
## [1] 11
```

Here `nrow()` is also the number of observations, which in most cases is the *sample size*.

Subsetting data frames can work much like subsetting matrices using square brackets, `[,]`. Here, we find fuel efficient vehicles earning over 35 miles per gallon and only display `manufacturer`, `model` and `year`.

```
mpg[mpg$hwy > 35, c("manufacturer", "model", "year")]
```

```
## # A tibble: 6 x 3
##   manufacturer     model   year
##   <chr>       <chr> <int>
## 1 honda        civic  2008
## 2 honda        civic  2008
## 3 toyota       corolla 2008
## 4 volkswagen   jetta  1999
## 5 volkswagen   new beetle 1999
## 6 volkswagen   new beetle 1999
```

An alternative would be to use the `subset()` function, which has a much more readable syntax.

```
subset(mpg, subset = hwy > 35, select = c("manufacturer", "model", "year"))
```

Lastly, we could use the `filter` and `select` functions from the `dplyr` package which introduces the `%>%` operator from the `magrittr` package. This is not necessary for this course, however the `dplyr` package is something you should be aware of as it is becoming a popular tool in the R world.

```
library(dplyr)
mpg %>% filter(hwy > 35) %>% select(manufacturer, model, year)
```

All three approaches produce the same results. Which you use will be largely based on a given situation as well as user preference.

When subsetting a data frame, be aware of what is being returned, as sometimes it may be a vector instead of a data frame. Also note that there are differences between subsetting a data frame and a tibble. A data frame operates more like a matrix where it is possible to reduce the subset to a vector. A tibble operates more like a list where it always subsets to another tibble.

3.3 Programming Basics

3.3.1 Control Flow

In R, the if/else syntax is:

```
if (...) {
  some R code
} else {
  more R code
}
```

For example,

```
x = 1
y = 3
if (x > y) {
  z = x * y
  print("x is larger than y")
} else {
  z = x + 5 * y
  print("x is less than or equal to y")
}
```

```
## [1] "x is less than or equal to y"
```

```
z
```

```
## [1] 16
```

R also has a special function `ifelse()` which is very useful. It returns one of two specified values based on a conditional statement.

```
ifelse(4 > 3, 1, 0)
```

```
## [1] 1
```

The real power of `ifelse()` comes from its ability to be applied to vectors.

```
fib = c(1, 1, 2, 3, 5, 8, 13, 21)
ifelse(fib > 6, "Foo", "Bar")
```

```
## [1] "Bar" "Bar" "Bar" "Bar" "Bar" "Foo" "Foo" "Foo"
```

Now a `for` loop example,

```
x = 11:15
for (i in 1:5) {
  x[i] = x[i] * 2
}
x
```

```
## [1] 22 24 26 28 30
```

Note that this `for` loop is very normal in many programming languages, but not in R. In R we would not use a loop, instead we would simply use a vectorized operation.

```
x = 11:15
x = x * 2
x
```

```
## [1] 22 24 26 28 30
```

3.3.2 Functions

So far we have been using functions, but haven't actually discussed some of their details.

```
function_name(arg1 = 10, arg2 = 20)
```

To use a function, you simply type its name, followed by an open parenthesis, then specify values of its arguments, then finish with a closing parenthesis.

An **argument** is a variable which is used in the body of the function. Specifying the values of the arguments is essentially providing the inputs to the function.

We can also write our own functions in R. For example, we often like to “standardize” variables, that is, subtracting the sample mean, and dividing by the sample standard deviation.

$$\frac{x - \bar{x}}{s}$$

In R we would write a function to do this. When writing a function, there are three thing you must do.

- Give the function a name. Preferably something that is short, but descriptive.
- Specify the arguments using `function()`
- Write the body of the function within curly braces, `{}`.

```
standardize = function(x) {
  m = mean(x)
  std = sd(x)
  result = (x - m) / std
  result
}
```

Here the name of the function is `standardize`, and the function has a single argument `x` which is used in the body of function. Note that the output of the final line of the body is what is returned by the function. In this case the function returns the vector stored in the variable `results`.

To test our function, we will take a random sample of size `n = 10` from a normal distribution with a mean of 2 and a standard deviation of 5.

```
(test_sample = rnorm(n = 10, mean = 2, sd = 5))

## [1] 6.6069246 -0.6624968 -2.6341316 -1.1762580 5.2279147 3.2163787
## [7] 9.2205114 11.0871978 -2.8642329 -3.1835508

standardize(x = test_sample)

## [1] 0.7750857 -0.5914652 -0.9621054 -0.6880452 0.5158509 0.1377099
## [7] 1.2664040 1.6173153 -1.0053612 -1.0653886
```

This function could be written much more succinctly, simply performing all the operations on one line and immediately returning the result, without storing any of the intermediate results.

```
standardize = function(x) {
  (x - mean(x)) / sd(x)
}
```

When specifying arguments, you can provide default arguments.

```
power_of_num = function(num, power = 2) {
  num ^ power
}
```

Let's look at a number of ways that we could run this function to perform the operation 10^2 resulting in 100.

```
power_of_num(10)
```

```
## [1] 100
```

```
power_of_num(10, 2)
```

```
## [1] 100
```

```
power_of_num(num = 10, power = 2)
```

```
## [1] 100
```

```
power_of_num(power = 2, num = 10)
```

```
## [1] 100
```

Note that without using the argument names, the order matters. The following code will not evaluate to the same output as the previous example.

```
power_of_num(2, 10)
```

```
## [1] 1024
```

Also, the following line of code would produce an error since arguments without a default value must be specified.

```
power_of_num(power = 5)
```

To further illustrate a function with a default argument, we will write a function that calculates sample variance two ways.

By default, it will calculate the unbiased estimate of σ^2 , which we will call s^2 .

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (x - \bar{x})^2$$

It will also have the ability to return the biased estimate (based on maximum likelihood) which we will call $\hat{\sigma}^2$.

$$\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (x - \bar{x})^2$$

```
get_var = function(x, biased = FALSE) {
  n = length(x) - 1 * !biased
  (1 / n) * sum((x - mean(x)) ^ 2)
}
```

```
get_var(test_sample)
```

```
## [1] 28.2975
```

```
get_var(test_sample, biased = FALSE)
```

```
## [1] 28.2975
```

```
var(test_sample)
```

```
## [1] 28.2975
```

We see the function is working as expected, and when returning the unbiased estimate it matches R's built-in function `var()`. Finally, let's examine the biased estimate of σ^2 .

```
get_var(test_sample, biased = TRUE)
```

```
## [1] 25.46775
```


Chapter 4

Summarizing Data

4.1 Summary Statistics

R has built in functions for a large number of summary statistics. For numeric variables, we can summarize data with the center and spread.

Central Tendency

Measure	R	Result
Mean	<code>mean(mpg\$cty)</code>	16.8589744
Median	<code>median(mpg\$cty)</code>	17

Spread

Measure	R	Result
Variance	<code>var(mpg\$cty)</code>	18.1130736
Standard Deviation	<code>sd(mpg\$cty)</code>	4.2559457
IQR	<code>IQR(mpg\$cty)</code>	5
Minimum	<code>min(mpg\$cty)</code>	9
Maximum	<code>max(mpg\$cty)</code>	35
Range	<code>range(mpg\$cty)</code>	9, 35

Categorical

For categorical variables, counts and percentages can be used for summary.

```
table(mpg$drv)
```

```
##  
##   4   f   r  
## 103 106  25
```

```
table(mpg$drv) / nrow(mpg)

##          4           f           r
## 0.4401709 0.4529915 0.1068376
```

4.2 Plotting

Now that we have some data to work with, and we have learned about the data at the most basic level, our next task is to visualize the data. Often, a proper visualization can illuminate features of the data that can inform further analysis.

We will look at four methods of visualizing data that we will use throughout the course:

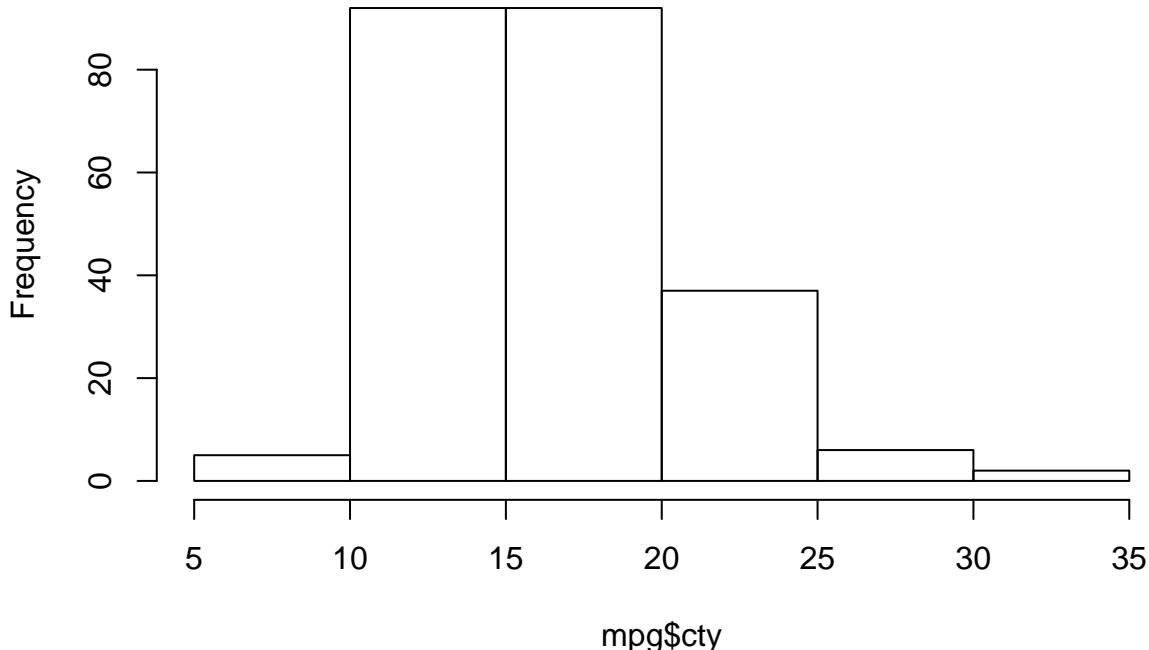
- Histograms
- Barplots
- Boxplots
- Scatterplots

4.2.1 Histograms

When visualizing a single numerical variable, a **histogram** will be our go-to tool, which can be created in R using the `hist()` function.

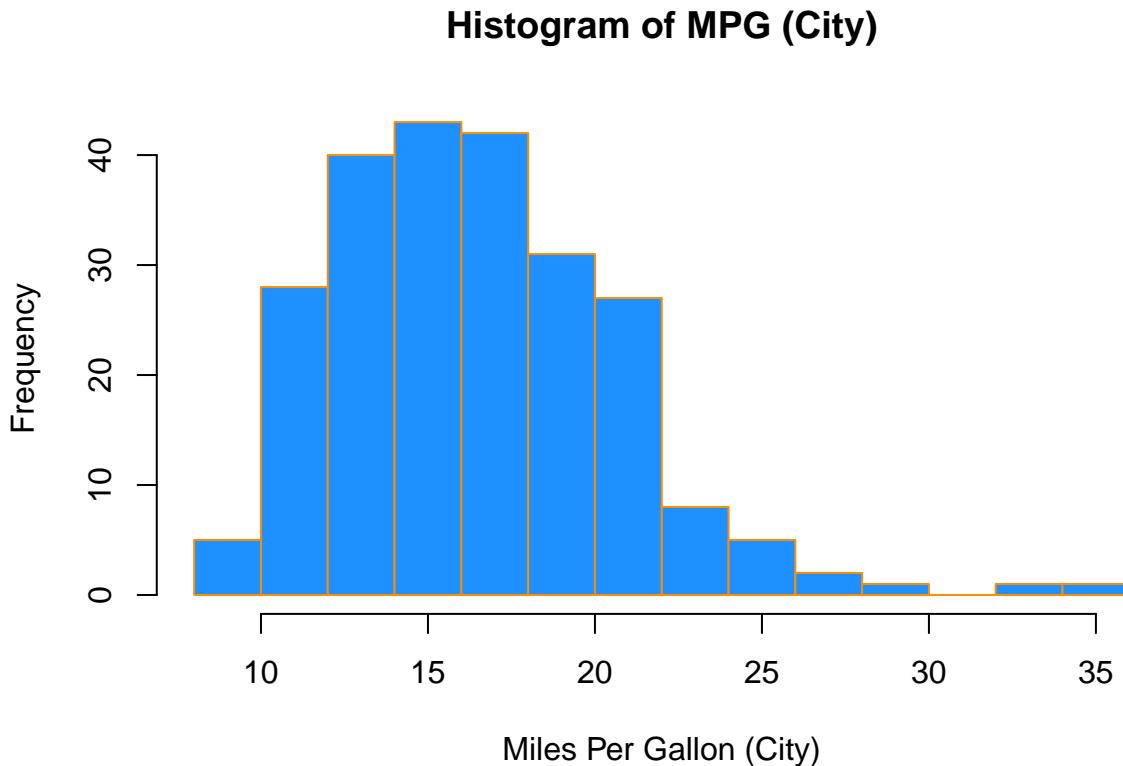
```
hist(mpg$cty)
```

Histogram of mpg\$cty



The histogram function has a number of parameters which can be changed to make our plot look much nicer. Use the `?` operator to read the documentation for the `hist()` to see a full list of these parameters.

```
hist(mpg$cty,
  xlab = "Miles Per Gallon (City)",
  main = "Histogram of MPG (City)",
  breaks = 12,
  col = "dodgerblue",
  border = "darkorange")
```

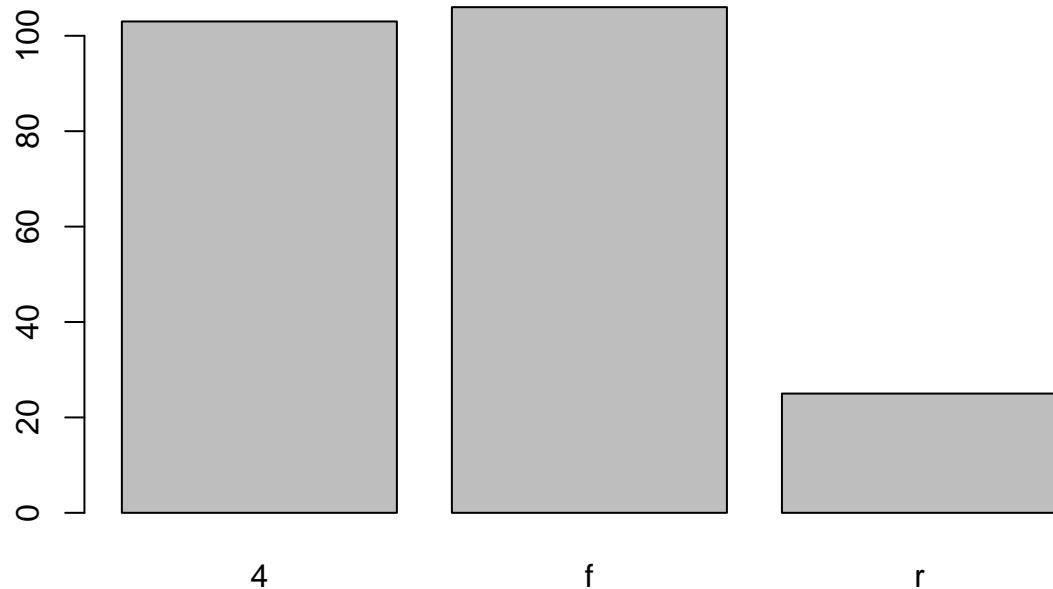


Importantly, you should always be sure to label your axes and give the plot a title. The argument `breaks` is specific to `hist()`. Entering an integer will give a suggestion to R for how many bars to use for the histogram. By default R will attempt to intelligently guess a good number of `breaks`, but as we can see here, it is sometimes useful to modify this yourself.

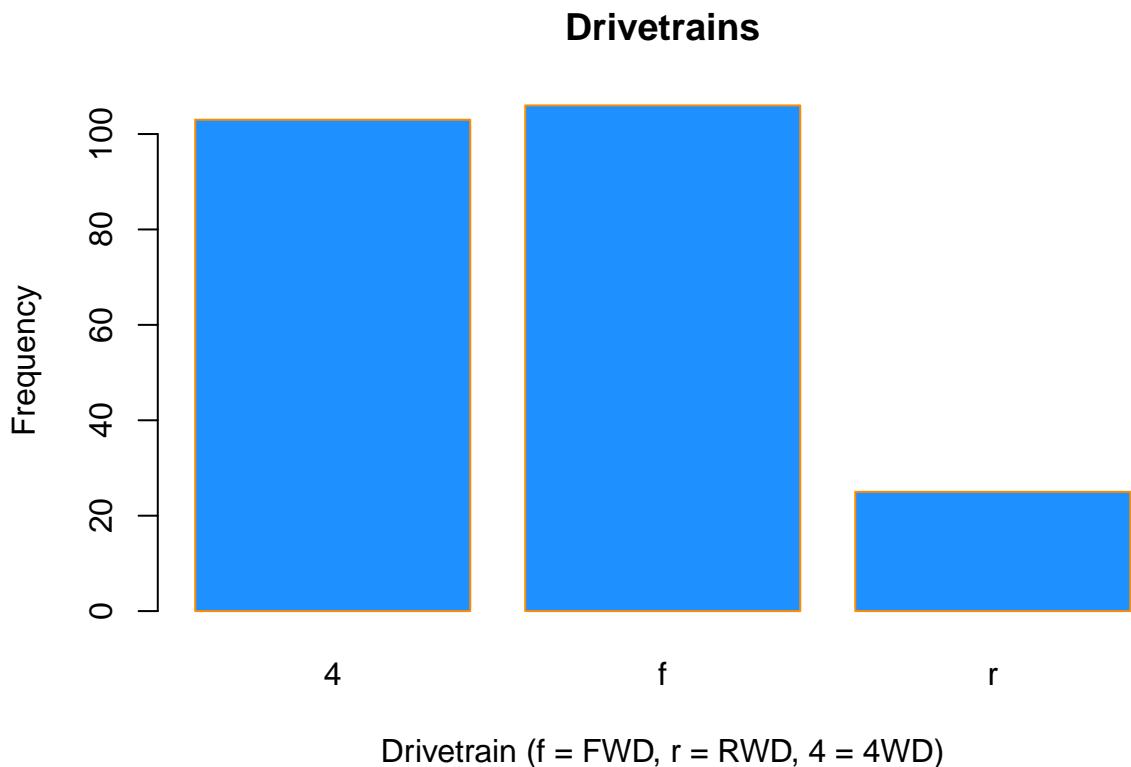
4.2.2 Barplots

Somewhat similar to a histogram, a barplot can provide a visual summary of a categorical variable, or a numeric variable with a finite number of values, like a ranking from 1 to 10.

```
barplot(table(mpg$drv))
```



```
barplot(table(mpg$drv),
       xlab = "Drivetrain (f = FWD, r = RWD, 4 = 4WD)",
       ylab = "Frequency",
       main = "Drivetrains",
       col = "dodgerblue",
       border = "darkorange")
```



4.2.3 Boxplots

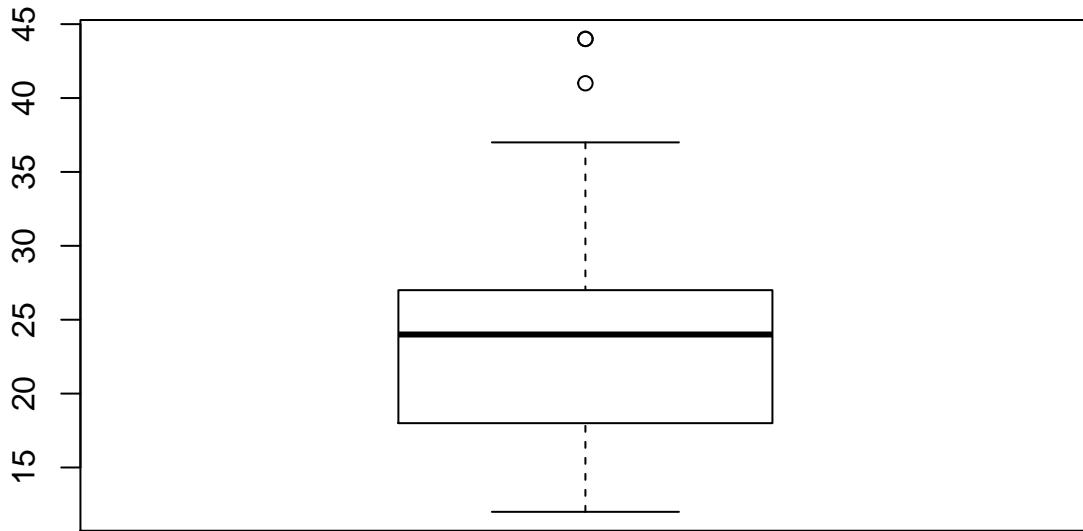
To visualize the relationship between a numerical and categorical variable, we will use a **boxplot**. In the `mpg` dataset, the `drv` variable takes a small, finite number of values. A car can only be front wheel drive, 4 wheel drive, or rear wheel drive.

```
unique(mpg$drv)
```

```
## [1] "f" "4" "r"
```

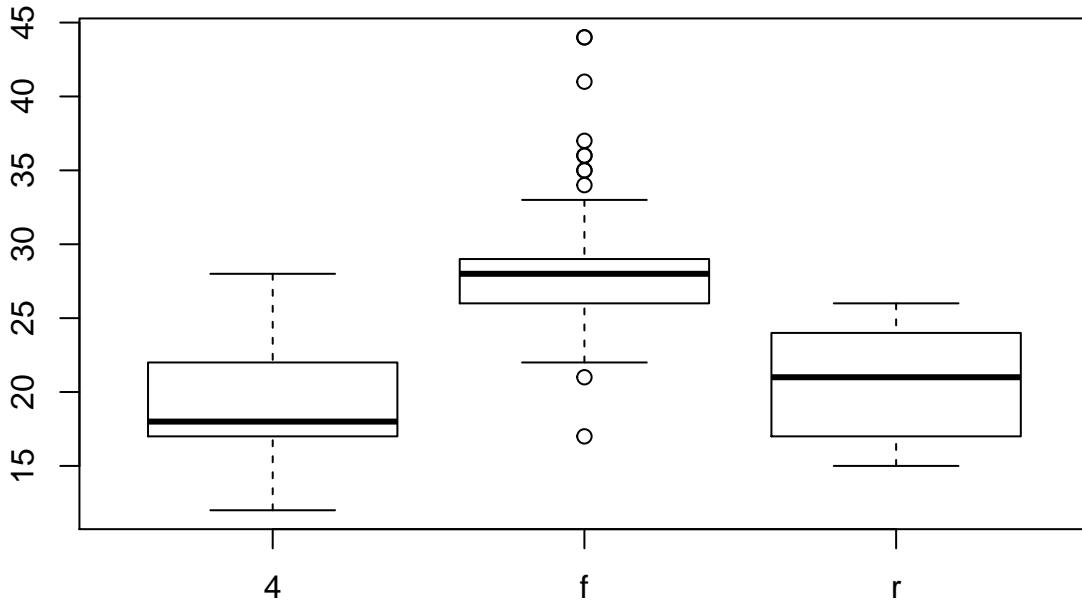
First note that we can use a single boxplot as an alternative to a histogram for visualizing a single numerical variable. To do so in R, we use the `boxplot()` function.

```
boxplot(mpg$hwy)
```



However, more often we will use boxplots to compare a numerical variable for different values of a categorical variable.

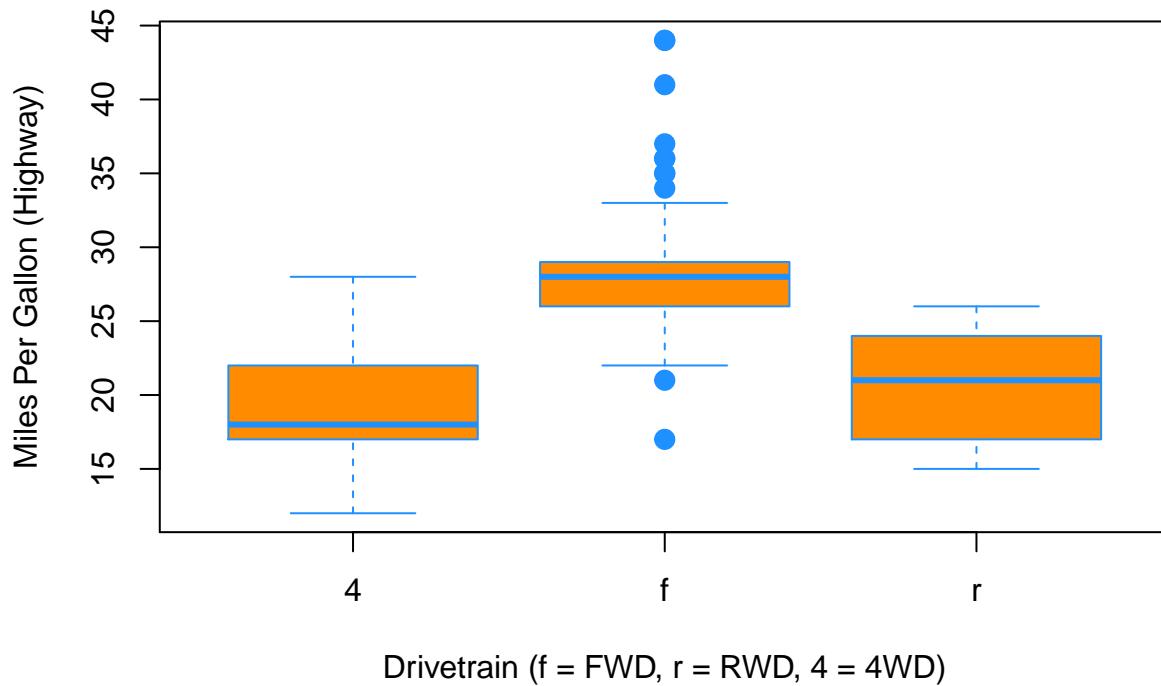
```
boxplot(hwy ~ drv, data = mpg)
```



Here used the `boxplot()` command to create side-by-side boxplots. However, since we are now dealing with two variables, the syntax has changed. The R syntax `hwy ~ drv`, `data = mpg` reads “Plot the `hwy` variable against the `drv` variable using the dataset `mpg`.” We see the use of a `~` (which specifies a formula) and also a `data =` argument. This will be a syntax that is common to many functions we will use in this course.

```
boxplot(hwy ~ drv, data = mpg,
        xlab = "Drivetrain (f = FWD, r = RWD, 4 = 4WD)",
        ylab = "Miles Per Gallon (Highway)",
        main = "MPG (Highway) vs Drivetrain",
        pch = 20,
        cex = 2,
        col = "darkorange",
        border = "dodgerblue")
```

MPG (Highway) vs Drivetrain

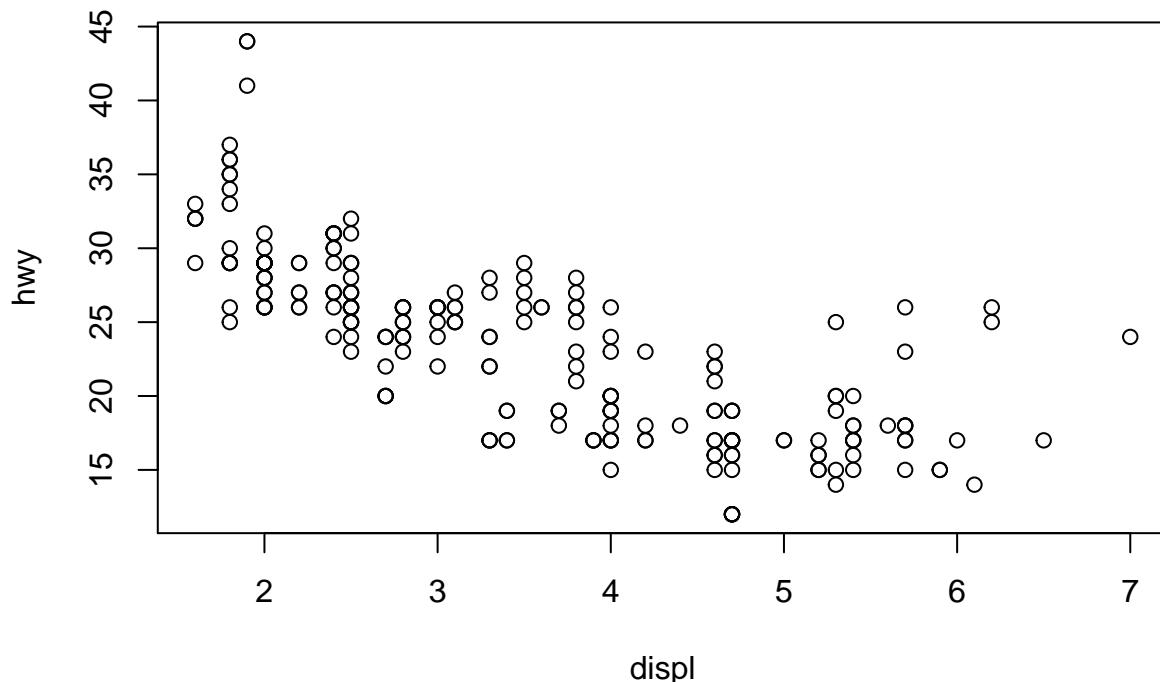


Again, `boxplot()` has a number of additional arguments which have the ability to make our plot more visually appealing.

4.2.4 Scatterplots

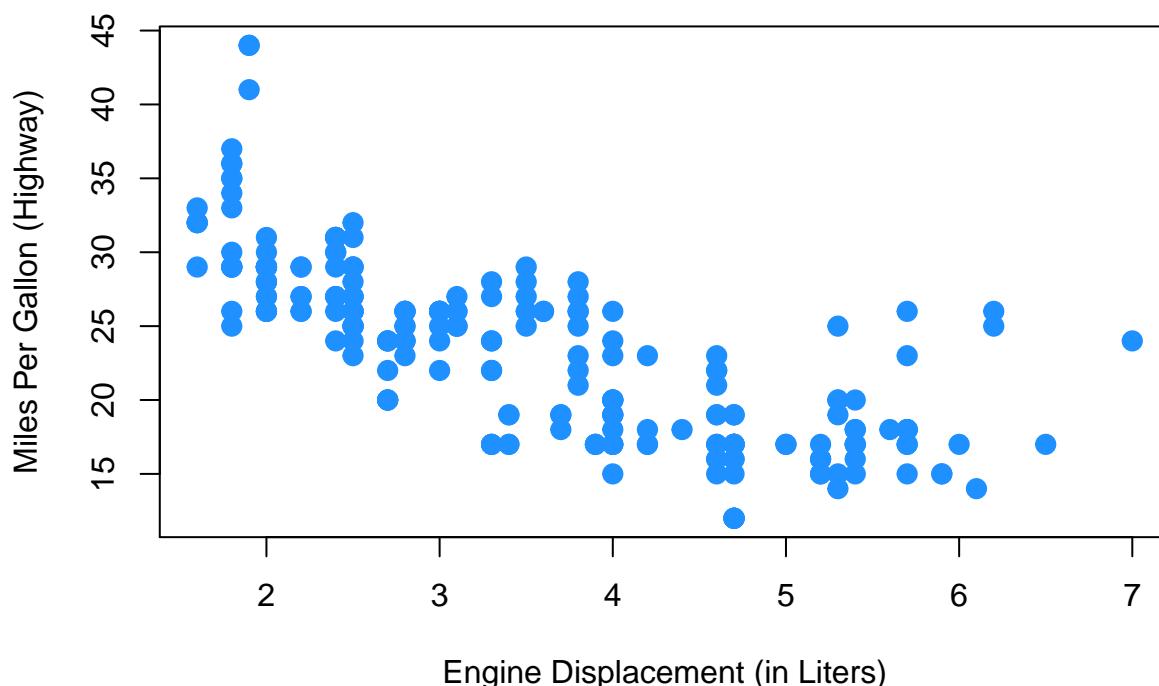
Lastly, to visualize the relationship between two numeric variables we will use a **scatterplot**. This can be done with the `plot()` function and the `~` syntax we just used with a boxplot. (The function `plot()` can also be used more generally; see the documentation for details.)

```
plot(hwy ~ displ, data = mpg)
```



```
plot(hwy ~ displ, data = mpg,
      xlab = "Engine Displacement (in Liters)",
      ylab = "Miles Per Gallon (Highway)",
      main = "MPG (Highway) vs Engine Displacement",
      pch = 20,
      cex = 2,
      col = "dodgerblue")
```

MPG (Highway) vs Engine Displacement



Chapter 5

Probability and Statistics in R

5.1 Probability in R

5.1.1 Distributions

When working with different statistical distributions, we often want to make probabilistic statements based on the distribution.

We typically want to know one of four things:

- The density (pdf) at a particular value.
- The distribution (cdf) at a particular value.
- The quantile value corresponding to a particular probability.
- A random draw of values from a particular distribution.

This used to be done with statistical tables printed in the back of textbooks. Now, R has functions for obtaining density, distribution, quantile and random values.

The general naming structure of the relevant R functions is:

- `dname` calculates density (pdf) at input `x`.
- `pname` calculates distribution (cdf) at input `x`.
- `qname` calculates the quantile at an input probability.
- `rname` generates a random draw from a particular distribution.

Note that `name` represents the name of the given distribution.

For example, consider a random variable X which is $N(\mu = 2, \sigma^2 = 25)$. (Note, we are parameterizing using the variance σ^2 . R however uses the standard deviation.)

To calculate the value of the pdf at $x = 3$, that is, the height of the curve at $x = 3$, use:

```
dnorm(x = 3, mean = 2, sd = 5)
```

```
## [1] 0.07820854
```

To calculate the value of the cdf at $x = 3$, that is, $P(X \leq 3)$, the probability that X is less than or equal to 3, use:

```
pnorm(q = 3, mean = 2, sd = 5)
```

```
## [1] 0.5792597
```

Or, to calculate the quantile for probability 0.975, use:

```
qnorm(p = 0.975, mean = 2, sd = 5)
```

```
## [1] 11.79982
```

Lastly, to generate a random sample of size $n = 10$, use:

```
rnorm(n = 10, mean = 2, sd = 5)
```

```
## [1] 2.6651816 5.7066984 3.5789494 2.0295151 0.3362493 -1.3312304
## [7] 6.5353069 4.9504921 4.8994457 4.9922787
```

These functions exist for many other distributions, including but not limited to:

Command	Distribution
*binom	Binomial
*t	t
*pois	Poisson
*f	F
*chisq	Chi-Squared

Where * can be d, p, q, and r. Each distribution will have its own set of parameters which need to be passed to the functions as arguments. For example, `dbinom()` would not have arguments for `mean` and `sd`, since those are not parameters of the distribution. Instead a binomial distribution is usually parameterized by n and p , however R chooses to call them something else. To find the names that R uses we would use `?dbinom` and see that R instead calls the arguments `size` and `prob`. For example:

```
dbinom(x = 6, size = 10, prob = 0.75)
```

```
## [1] 0.145998
```

Also note that, when using the dname functions with discrete distributions, they are the pmf of the distribution. For example, the above command is $P(Y = 6)$ if $Y \sim b(n = 10, p = 0.75)$. (The probability of flipping an unfair coin 10 times and seeing 6 heads, if the probability of heads is 0.75.)

5.2 Hypothesis Tests in R

A prerequisite for STAT 420 is an understanding of the basics of hypothesis testing. Recall the basic structure of hypothesis tests:

- An overall model and related assumptions are made. (The most common being observations following a normal distribution.)

- The **null** (H_0) and **alternative** (H_1 or H_A) hypothesis are specified. Usually the null specifies a particular value of a parameter.
- With given data, the **value** of the *test statistic* is calculated.
- Under the general assumptions, as well as assuming the null hypothesis is true, the **distribution** of the *test statistic* is known.
- Given the distribution and value of the test statistic, as well as the form of the alternative hypothesis, we can calculate a **p-value** of the test.
- Based on the **p-value** and pre-specified level of significance, we make a decision. One of:
 - Fail to reject the null hypothesis.
 - Reject the null hypothesis.

We'll do some quick review of two of the most common tests to show how they are performed using R.

5.2.1 One Sample t-Test: Review

Suppose $x_i \sim N(\mu, \sigma^2)$ and we want to test $H_0 : \mu = \mu_0$ versus $H_1 : \mu \neq \mu_0$.

Assuming σ is unknown, we use the one-sample Student's *t* test statistic:

$$t = \frac{\bar{x} - \mu_0}{s/\sqrt{n}} \sim t_{n-1},$$

where $\bar{x} = \frac{\sum_{i=1}^n x_i}{n}$ and $s = \sqrt{\frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2}$.

A $100(1 - \alpha)\%$ confidence interval for μ is given by,

$$\bar{x} \pm t_{n-1}(\alpha/2) \frac{s}{\sqrt{n}}$$

where $t_{n-1}(\alpha/2)$ is the critical value such that $P(t > t_{n-1}(\alpha/2)) = \alpha/2$ for $n - 1$ degrees of freedom.

5.2.2 One Sample t-Test: Example

Suppose a grocery store sells “16 ounce” boxes of *Captain Crisp* cereal. A random sample of 9 boxes was taken and weighed. The weight in ounces are stored in the data frame `capt_crisp`.

```
capt_crisp = data.frame(weight = c(15.5, 16.2, 16.1, 15.8, 15.6, 16.0, 15.8, 15.9, 16.2))
```

The company that makes *Captain Crisp* cereal claims that the average weight of a box is at least 16 ounces. We will assume the weight of cereal in a box is normally distributed and use a 0.05 level of significance to test the company's claim.

To test $H_0 : \mu \geq 16$ versus $H_1 : \mu < 16$, the test statistic is

$$t = \frac{\bar{x} - \mu_0}{s/\sqrt{n}}$$

The sample mean \bar{x} and the sample standard deviation s can be easily computed using R. We also create variables which store the hypothesized mean and the sample size.

```
x_bar = mean(capt_crisp$weight)
s      = sd(capt_crisp$weight)
mu_0   = 16
n      = 9
```

We can then easily compute the test statistic.

```
t = (x_bar - mu_0) / (s / sqrt(n))
t
```

```
## [1] -1.2
```

Under the null hypothesis, the test statistic has a t distribution with $n - 1$ degrees of freedom, in this case 8.

To complete the test, we need to obtain the p-value of the test. Since this is a one-sided test with a less-than alternative, we need to area to the left of -1.2 for a t distribution with 8 degrees of freedom. That is,

$$P(t_8 < -1.2)$$

```
pt(t, df = n - 1)
```

```
## [1] 0.1322336
```

We now have the p-value of our test, which is greater than our significance level (0.05), so we fail to reject the null hypothesis.

Alternatively, this entire process could have been completed using one line of R code.

```
t.test(x = capt_crisp$weight, mu = 16, alternative = c("less"), conf.level = 0.95)
```

```
##
##  One Sample t-test
##
## data:  capt_crisp$weight
## t = -1.2, df = 8, p-value = 0.1322
## alternative hypothesis: true mean is less than 16
## 95 percent confidence interval:
##       -Inf 16.05496
## sample estimates:
## mean of x
##          15.9
```

We supply R with the data, the hypothesized value of μ , the alternative, and the confidence level. R then returns a wealth of information including:

- The value of the test statistic.
- The degrees of freedom of the distribution under the null hypothesis.
- The p-value of the test.
- The confidence interval which corresponds to the test.
- An estimate of μ .

Since the test was one-sided, R returned a one-sided confidence interval. If instead we wanted a two-sided interval for the mean weight of boxes of *Captain Crisp* cereal we could modify our code.

```
capt_test_results = t.test(capt_crisp$weight, mu = 16,
                           alternative = c("two.sided"), conf.level = 0.95)
```

This time we have stored the results. By doing so, we can directly access portions of the output from `t.test()`. To see what information is available we use the `names()` function.

```
names(capt_test_results)
```

```
## [1] "statistic"    "parameter"    "p.value"      "conf.int"      "estimate"
## [6] "null.value"   "alternative"  "method"       "data.name"
```

We are interested in the confidence interval which is stored in `conf.int`.

```
capt_test_results$conf.int
```

```
## [1] 15.70783 16.09217
## attr(,"conf.level")
## [1] 0.95
```

Let's check this interval "by hand." The one piece of information we are missing is the critical value, $t_{n-1}(\alpha/2) = t_8(0.025)$, which can be calculated in R using the `qt()` function.

```
qt(0.975, df = 8)
```

```
## [1] 2.306004
```

So, the 95% CI for the mean weight of a cereal box is calculated by plugging into the formula,

$$\bar{x} \pm t_{n-1}(\alpha/2) \frac{s}{\sqrt{n}}$$

```
c(mean(capt_crisp$weight) - qt(0.975, df = 8) * sd(capt_crisp$weight) / sqrt(9),
  mean(capt_crisp$weight) + qt(0.975, df = 8) * sd(capt_crisp$weight) / sqrt(9))
```

```
## [1] 15.70783 16.09217
```

5.2.3 Two Sample t-Test: Review

Suppose $x_i \sim N(\mu_x, \sigma^2)$ and $y_i \sim N(\mu_y, \sigma^2)$.

Want to test $H_0 : \mu_x - \mu_y = \mu_0$ versus $H_1 : \mu_x - \mu_y \neq \mu_0$.

Assuming σ is unknown, use the two-sample Student's t test statistic:

$$t = \frac{(\bar{x} - \bar{y}) - \mu_0}{s_p \sqrt{\frac{1}{n} + \frac{1}{m}}} \sim t_{n+m-2},$$

where $\bar{x} = \frac{\sum_{i=1}^n x_i}{n}$, $\bar{y} = \frac{\sum_{i=1}^m y_i}{m}$, and $s_p^2 = \frac{(n-1)s_x^2 + (m-1)s_y^2}{n+m-2}$.

A $100(1-\alpha)\%$ CI for $\mu_x - \mu_y$ is given by

$$(\bar{x} - \bar{y}) \pm t_{n+m-2}(\alpha/2) \left(s_p \sqrt{\frac{1}{n} + \frac{1}{m}} \right),$$

where $t_{n+m-2}(\alpha/2)$ is the critical value such that $P(t > t_{n+m-2}(\alpha/2)) = \alpha/2$.

5.2.4 Two Sample t-Test: Example

Assume that the distributions of X and Y are $N(\mu_1, \sigma^2)$ and $N(\mu_2, \sigma^2)$, respectively. Given the $n = 6$ observations of X ,

```
x = c(70, 82, 78, 74, 94, 82)
n = length(x)
```

and the $m = 8$ observations of Y ,

```
y = c(64, 72, 60, 76, 72, 80, 84, 68)
m = length(y)
```

we will test $H_0 : \mu_1 = \mu_2$ versus $H_1 : \mu_1 > \mu_2$.

First, note that we can calculate the sample means and standard deviations.

```
x_bar = mean(x)
s_x    = sd(x)
y_bar = mean(y)
s_y    = sd(y)
```

We can then calculate the pooled standard deviation.

$$s_p = \sqrt{\frac{(n-1)s_x^2 + (m-1)s_y^2}{n+m-2}}$$

```
s_p = sqrt(((n - 1) * s_x ^ 2 + (m - 1) * s_y ^ 2) / (n + m - 2))
```

Thus, the relevant t test statistic is given by

$$t = \frac{(\bar{x} - \bar{y}) - \mu_0}{s_p \sqrt{\frac{1}{n} + \frac{1}{m}}}.$$

```
t = ((x_bar - y_bar) - 0) / (s_p * sqrt(1 / n + 1 / m))
t
```

```
## [1] 1.823369
```

Note that $t \sim t_{n+m-2} = t_{12}$, so we can calculate the p-value, which is

$$P(t_{12} > 1.8233692).$$

```
1 - pt(t, df = n + m - 2)
```

```
## [1] 0.04661961
```

But, then again, we could have simply performed this test in one line of R.

```
t.test(x, y, alternative = c("greater"), var.equal = TRUE)
```

```
##
##  Two Sample t-test
##
## data: x and y
## t = 1.8234, df = 12, p-value = 0.04662
## alternative hypothesis: true difference in means is greater than 0
## 95 percent confidence interval:
##  0.1802451      Inf
## sample estimates:
## mean of x mean of y
##        80         72
```

Recall that a two-sample t -test can be done with or without an equal variance assumption. Here `var.equal = TRUE` tells R we would like to perform the test under the equal variance assumption.

Above we carried out the analysis using two vectors `x` and `y`. In general, we will have a preference for using data frames.

```
t_test_data = data.frame(values = c(x, y),
                           group = c(rep("A", length(x)), rep("B", length(y))))
```

We now have the data stored in a single variables (`values`) and have created a second variable (`group`) which indicates which “sample” the value belongs to.

```
t_test_data
```

```
##   values group
## 1     70    A
## 2     82    A
## 3     78    A
## 4     74    A
## 5     94    A
## 6     82    A
## 7     64    B
## 8     72    B
## 9     60    B
## 10    76    B
## 11    72    B
## 12    80    B
## 13    84    B
## 14    68    B
```

Now to perform the test, we still use the `t.test()` function but with the `~` syntax and a `data` argument.

```
t.test(values ~ group, data = t_test_data,
       alternative = c("greater"), var.equal = TRUE)

##
##  Two Sample t-test
##
## data:  values by group
## t = 1.8234, df = 12, p-value = 0.04662
## alternative hypothesis: true difference in means is greater than 0
## 95 percent confidence interval:
##  0.1802451      Inf
## sample estimates:
## mean in group A mean in group B
##                 80                  72
```

5.3 Simulation

Simulation and model fitting are related but opposite processes.

- In **simulation**, the *data generating process* is known. We will know the form of the model as well as the value of each of the parameters. In particular, we will often control the distribution and parameters which define the randomness, or noise in the data.
- In **model fitting**, the *data* is known. We will then assume a certain form of model and find the best possible values of the parameters given the observed data. Essentially we are seeking to uncover the truth. Often we will attempt to fit many models, and we will learn metrics to assess which model fits best.

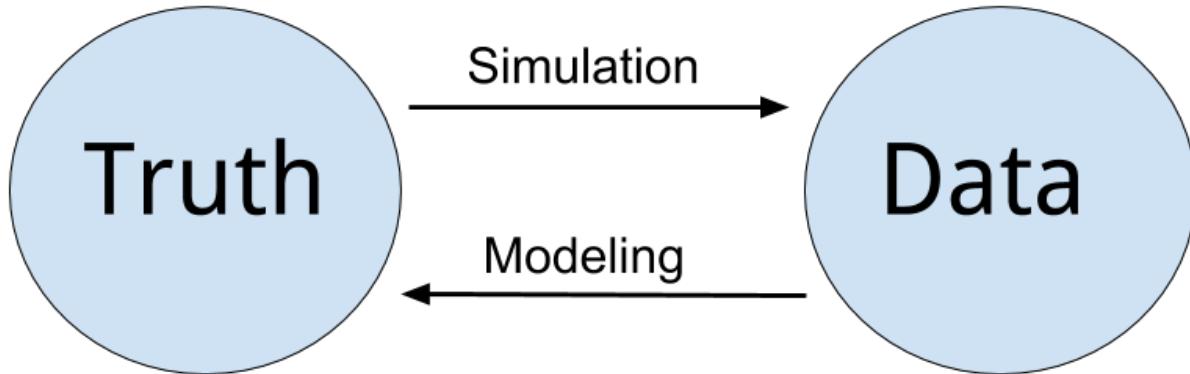


Figure 5.1: Simulation vs Modeling

Often we will simulate data according to a process we decide, then use a modeling method seen in class. We can then verify how well the method works, since we know the data generating process.

One of the biggest strengths of R is its ability to carry out simulations using built-in functions for generating random samples from certain distributions. We'll look at two very simple examples here, however simulation will be a topic we revisit several times throughout the course.

5.3.1 Paired Differences

Consider the model:

$$\begin{aligned} X_{11}, X_{12}, \dots, X_{1n} &\sim N(\mu_1, \sigma^2) \\ X_{21}, X_{22}, \dots, X_{2n} &\sim N(\mu_2, \sigma^2) \end{aligned}$$

Assume that $\mu_1 = 6$, $\mu_2 = 5$, $\sigma^2 = 4$ and $n = 25$.

Let

$$\begin{aligned} \bar{X}_1 &= \frac{1}{n} \sum_{i=1}^n X_{1i} \\ \bar{X}_2 &= \frac{1}{n} \sum_{i=1}^n X_{2i} \\ D &= \bar{X}_1 - \bar{X}_2. \end{aligned}$$

Suppose we would like to calculate $P(0 < D < 2)$. First we will need to obtain the distribution of D .

Recall,

$$\bar{X}_1 \sim N\left(\mu_1, \frac{\sigma^2}{n}\right)$$

and

$$\bar{X}_2 \sim N\left(\mu_2, \frac{\sigma^2}{n}\right).$$

Then,

$$D = \bar{X}_1 - \bar{X}_2 \sim N\left(\mu_1 - \mu_2, \frac{\sigma^2}{n} + \frac{\sigma^2}{n}\right) = N\left(6 - 5, \frac{4}{25} + \frac{4}{25}\right).$$

So,

$$D \sim N(\mu = 1, \sigma^2 = 0.32).$$

Thus,

$$P(0 < D < 2) = P(D < 2) - P(D < 0).$$

This can then be calculated using R without a need to first standardize, or use a table.

```
pnorm(2, mean = 1, sd = sqrt(0.32)) - pnorm(0, mean = 1, sd = sqrt(0.32))
```

```
## [1] 0.9229001
```

An alternative approach, would be to **simulate** a large number of observations of D then use the **empirical distribution** to calculate the probability.

Our strategy will be to repeatedly:

- Generate a sample of 25 random observations from $N(\mu_1 = 6, \sigma^2 = 4)$. Call the mean of this sample \bar{x}_{1s} .
- Generate a sample of 25 random observations from $N(\mu_1 = 5, \sigma^2 = 4)$. Call the mean of this sample \bar{x}_{2s} .
- Calculate the differences of the means, $d_s = \bar{x}_{1s} - \bar{x}_{2s}$.

We will repeat the process a large number of times. Then we will use the distribution of the simulated observations of d_s as an estimate for the true distribution of D .

```
set.seed(42)
num_samples = 10000
differences = rep(0, num_samples)
```

Before starting our **for** loop to perform the operation, we set a seed for reproducibility, create and set a variable **num_samples** which will define the number of repetitions, and lastly create a variables **differences** which will store the simulate values, d_s .

By using **set.seed()** we can reproduce the random results of **rnorm()** each time starting from that line.

```
for (s in 1:num_samples) {
  x1 = rnorm(n = 25, mean = 6, sd = 2)
  x2 = rnorm(n = 25, mean = 5, sd = 2)
  differences[s] = mean(x1) - mean(x2)
}
```

To estimate $P(0 < D < 2)$ we will find the proportion of values of d_s (among the 10000 values of d_s generated) that are between 0 and 2.

```
mean(0 < differences & differences < 2)
```

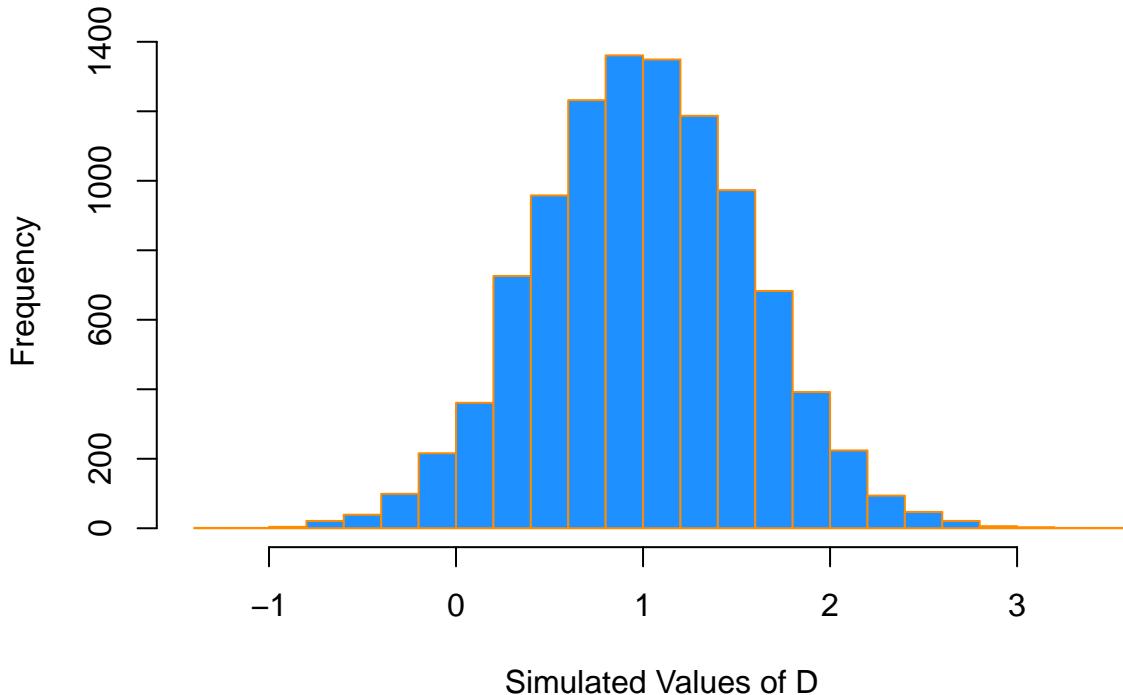
```
## [1] 0.9222
```

Recall that above we derived the distribution of D to be $N(\mu = 1, \sigma^2 = 0.32)$

If we look at a histogram of the differences, we find that it looks very much like a normal distribution.

```
hist(differences, breaks = 20,
     main = "Empirical Distribution of D",
     xlab = "Simulated Values of D",
     col = "dodgerblue",
     border = "darkorange")
```

Empirical Distribution of D



Also the sample mean and variance are very close to what we would expect.

```
mean(differences)
```

```
## [1] 1.001423
```

```
var(differences)
```

```
## [1] 0.3230183
```

We could have also accomplished this task with a single line of more “idiomatic” R.

```
set.seed(42)
diffs = replicate(10000, mean(rnorm(25, 6, 2)) - mean(rnorm(25, 5, 2)))
```

Use `?replicate` to take a look at the documentation for the `replicate` function and see if you can understand how this line performs the same operations that our `for` loop above executed.

```
mean(differences == diff)
```

```
## [1] 1
```

We see that by setting the same seed for the randomization, we actually obtain identical results!

5.3.2 Distribution of a Sample Mean

For another example of simulation, we will simulate observations from a Poisson distribution, and examine the empirical distribution of the sample mean of these observations.

Recall, if

$$X \sim \text{Pois}(\mu)$$

then

$$E[X] = \mu$$

and

$$\text{Var}[X] = \mu.$$

Also, recall that for a random variable X with finite mean μ and finite variance σ^2 , the central limit theorem tells us that the mean, \bar{X} of a random sample of size n is approximately normal for *large* values of n . Specifically, as $n \rightarrow \infty$,

$$\bar{X} \xrightarrow{d} N\left(\mu, \frac{\sigma^2}{n}\right).$$

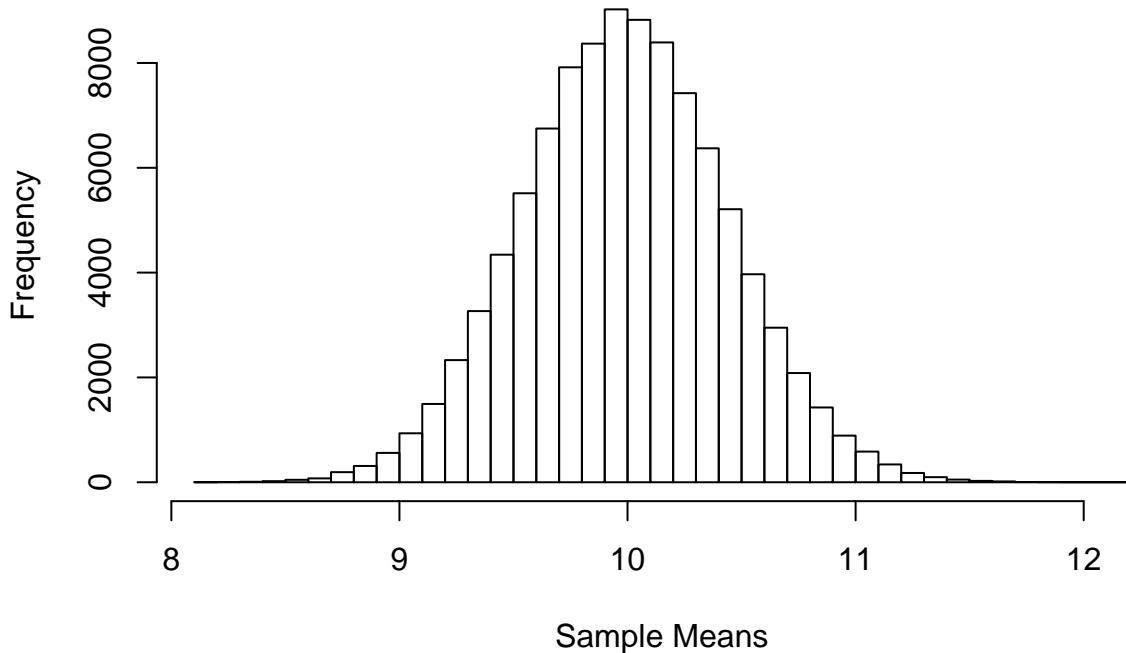
The following verifies this result for a Poisson distribution with $\mu = 10$ and a sample size of $n = 50$.

```
set.seed(1337)
mu      = 10
sample_size = 50
samples   = 100000
x_bars    = rep(0, samples)

for(i in 1:samples){
  x_bars[i] = mean(rpois(sample_size, lambda = mu))
}

x_bar_hist = hist(x_bars, breaks = 50,
                  main = "Histogram of Sample Means",
                  xlab = "Sample Means")
```

Histogram of Sample Means



Now we will compare sample statistics from the empirical distribution with their known values based on the parent distribution.

```
c(mean(x_bars), mu)

## [1] 10.00008 10.00000

c(var(x_bars), mu / sample_size)

## [1] 0.1989732 0.2000000

c(sd(x_bars), sqrt(mu) / sqrt(sample_size))

## [1] 0.4460641 0.4472136
```

And here, we will calculate the proportion of sample means that are within 2 standard deviations of the population mean.

```
mean(x_bars > mu - 2 * sqrt(mu) / sqrt(sample_size) &
      x_bars < mu + 2 * sqrt(mu) / sqrt(sample_size))

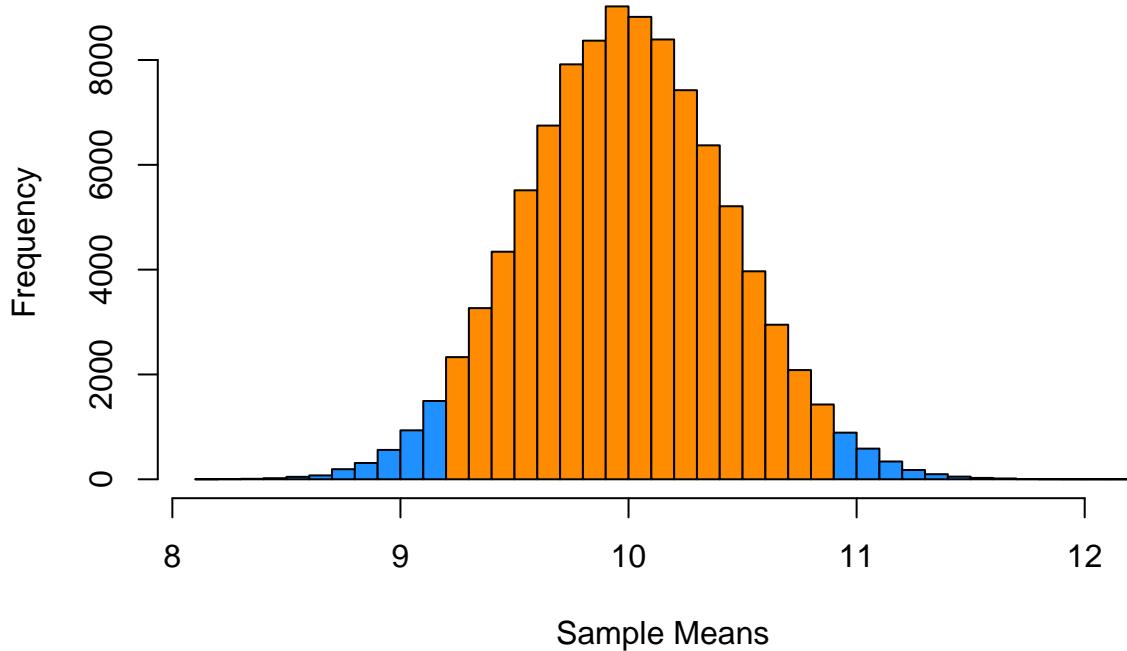
## [1] 0.95429
```

This last histogram uses a bit of a trick to approximately shade the bars that are within two standard deviations of the mean.)

```
shading = ifelse(x_bar_hist$breaks > mu - 2 * sqrt(mu) / sqrt(sample_size) &
                  x_bar_hist$breaks < mu + 2 * sqrt(mu) / sqrt(sample_size),
                  "darkorange", "dodgerblue")

x_bar_hist = hist(x_bars, breaks = 50, col = shading,
                   main = "Histogram of Sample Means, Two Standard Deviations",
                   xlab = "Sample Means")
```

Histogram of Sample Means, Two Standard Deviations



Chapter 6

R Resources

So far, we have seen a lot of R, and a lot of R quickly. Again, the preceding chapters were in no way meant to be a complete reference for the R language, but rather an introduction to many of the concepts we will need in this text. The following resources are not necessary for the remainder of this text, but you may find them useful if you would like a deeper understanding of R:

6.1 Beginner Tutorials and References

- Try R from Code School.
 - An interactive introduction to the basics of R. Useful for getting up to speed on R's syntax.
- Quick-R by Robert Kabacoff.
 - A good reference for R basics.
- R Tutorial by Chi Yau.
 - A combination reference and tutorial for R basics.
- R Programming for Data Science by Roger Peng
 - A great text for R programming beginners. Discusses R from the ground up, highlighting programming details we might not discuss.

6.2 Intermediate References

- R for Data Science by Hadley Wickham and Garrett Grolemund.
 - Similar to Advanced R, but focuses more on data analysis, while still introducing programming concepts. Especially useful for working in the tidyverse.
- The Art of R Programming by Norman Matloff.
 - Gentle introduction to the programming side of R. (Whereas we will focus more on the data analysis side.) A free electronic version is available through the Illinois library.

6.3 Advanced References

- Advanced R by Hadley Wickham.
 - From the author of several extremely popular R packages. Good follow-up to The Art of R Programming. (And more up-to-date material.)
- The R Inferno by Patrick Burns.
 - Likens learning the tricks of R to descending through the levels of hell. Very advanced material, but may be important if R becomes a part of your everyday toolkit.
- Efficient R Programming by Colin Gillespie and Robin Lovelace
 - Discusses both efficient R programs, as well as programming in R efficiently.

6.4 Quick Comparisons to Other Languages

Those who are familiar with other languages may find the following “cheatsheets” helpful for transitioning to R.

- MATLAB and Python
- Stata
- Julia

6.5 RStudio and RMarkdown

The following videos were made as an introduction to R, RStudio, and RMarkdown for STAT 420 at UIUC. If you are currently using this text for a Coursera course, you can find updated videos there.

- RStudio Basics
- RMarkdown Intro
- RMarkdown Basics
- RMarkdown Tips and Tricks

Note that RStudio and RMarkdown are constantly receiving excellent support and updates, so these videos already contain some outdated information. For example, as of recent RStudio versions, the “Import Dataset” functionality has been updated to utilize the `readr` and `tibble` packages. Additionally, working interactively with RMarkdown documents in RStudio has a long list of new functionality.

RStudio provides their own tutorial for RMarkdown. They also have an excellent RStudio “cheatsheets” which visually identifies many of the features available in the IDE.

6.6 RMarkdown Template

This .zip file contains the files necessary to produce this rendered document. This document is a more complete version of a template than what is seen in the above videos.

Chapter 7

Simple Linear Regression

“All models are wrong, but some are useful.”

— George E. P. Box

After reading this chapter you will be able to:

- Understand the concept of a model.
- Describe two ways in which regression coefficients are derived.
- Estimate and visualize a regression model using R.
- Interpret regression coefficients and statistics in the context of real-world problems.
- Use a regression model to make predictions.

7.1 Modeling

Let’s consider a simple example of how the speed of a car affects its stopping distance, that is, how far it travels before it comes to a stop. To examine this relationship, we will use the `cars` dataset which, is a default R dataset. Thus, we don’t need to load a package first; it is immediately available.

To get a first look at the data you can use the `View()` function inside RStudio.

```
View(cars)
```

We could also take a look at the variable names, the dimension of the data frame, and some sample observations with `str()`.

```
str(cars)
```

```
## 'data.frame':    50 obs. of  2 variables:  
##   $ speed: num  4 4 7 7 8 9 10 10 10 11 ...  
##   $ dist : num  2 10 4 22 16 10 18 26 34 17 ...
```

As we have seen before with data frames, there are a number of additional functions to access some of this information directly.

```
dim(cars)

## [1] 50  2

nrow(cars)

## [1] 50

ncol(cars)

## [1] 2
```

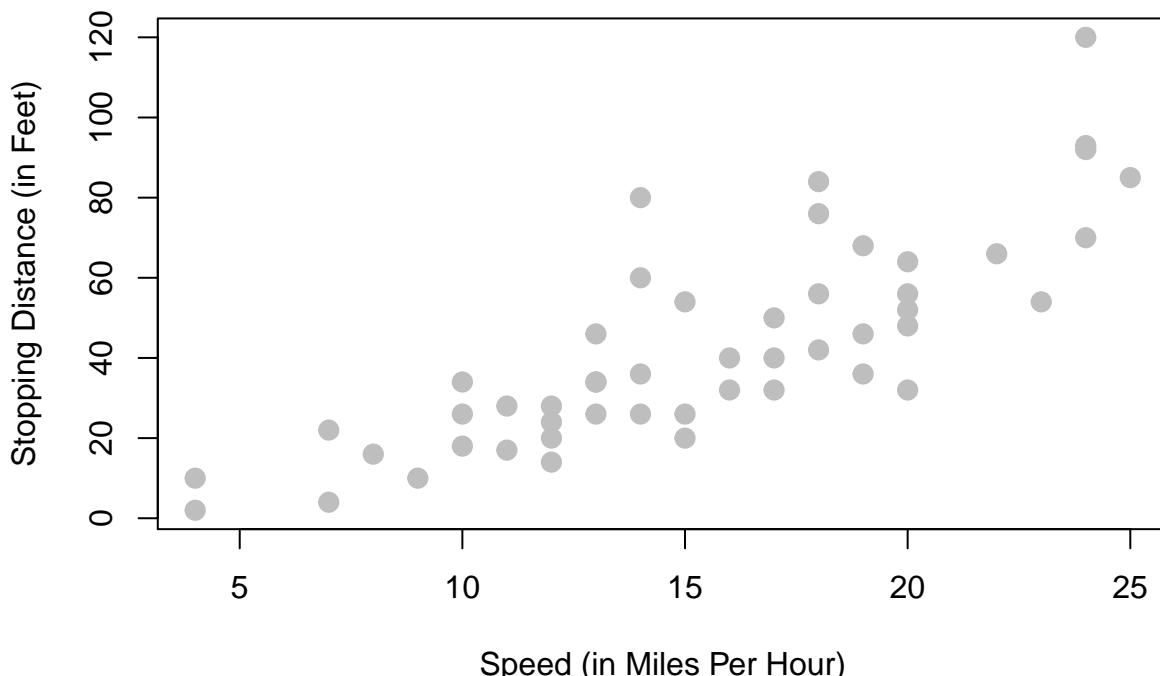
Other than the two variable names and the number of observations, this data is still just a bunch of numbers, so we should probably obtain some context.

```
?cars
```

Reading the documentation we learn that this is data gathered during the 1920s about the speed of cars and the resulting distance it takes for the car to come to a stop. The interesting task here is to determine how far a car travels before stopping, when traveling at a certain speed. So, we will first plot the stopping distance against the speed.

```
plot(dist ~ speed, data = cars,
     xlab = "Speed (in Miles Per Hour)",
     ylab = "Stopping Distance (in Feet)",
     main = "Stopping Distance vs Speed",
     pch = 20,
     cex = 2,
     col = "grey")
```

Stopping Distance vs Speed



Let's now define some terminology. We have pairs of data, (x_i, y_i) , for $i = 1, 2, \dots, n$, where n is the sample size of the dataset.

We use i as an index, simply for notation. We use x_i as the **predictor** (explanatory) variable. The predictor variable is used to help *predict* or explain the **response** (target, outcome) variable, y_i .

Other texts may use the term independent variable instead of predictor and dependent variable in place of response. However, those monikers imply mathematical characteristics that might not be true. While these other terms are not incorrect, independence is already a strictly defined concept in probability. For example, when trying to predict a person's weight given their height, would it be accurate to say that height is independent of weight? Certainly not, but that is an unintended implication of saying "independent variable." We prefer to stay away from this nomenclature.

In the **cars** example, we are interested in using the predictor variable **speed** to predict and explain the response variable **dist**.

Broadly speaking, we would like to model the relationship between X and Y using the form

$$Y = f(X) + \epsilon.$$

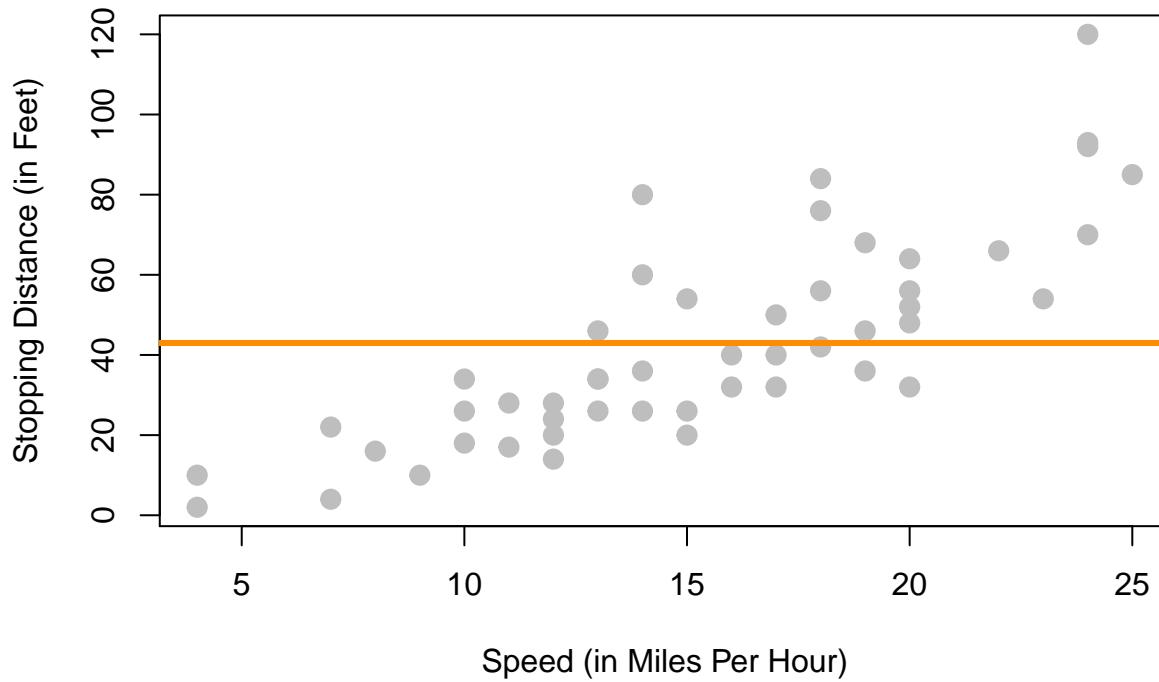
The function f describes the functional relationship between the two variables, and the ϵ term is used to account for error. This indicates that if we plug in a given value of X as input, our output is a value of Y , within a certain range of error. You could think of this a number of ways:

- Response = Prediction + Error
- Response = Signal + Noise
- Response = Model + Unexplained
- Response = Deterministic + Random
- Response = Explainable + Unexplainable

What sort of function should we use for $f(X)$ for the **cars** data?

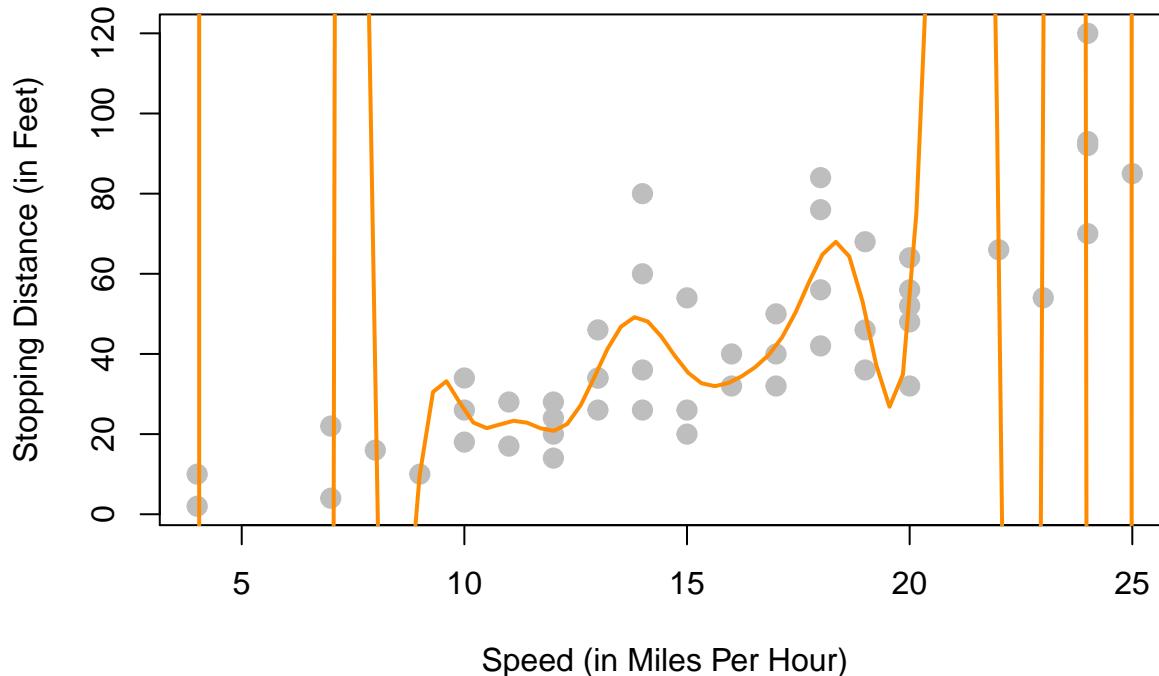
We could try to model the data with a horizontal line. That is, the model for y does not depend on the value of x . (Some function $f(X) = c$.) In the plot below, we see this doesn't seem to do a very good job. Many of the data points are very far from the orange line representing c . This is an example of **underfitting**. The obvious fix is to make the function $f(X)$ actually depend on x .

Stopping Distance vs Speed

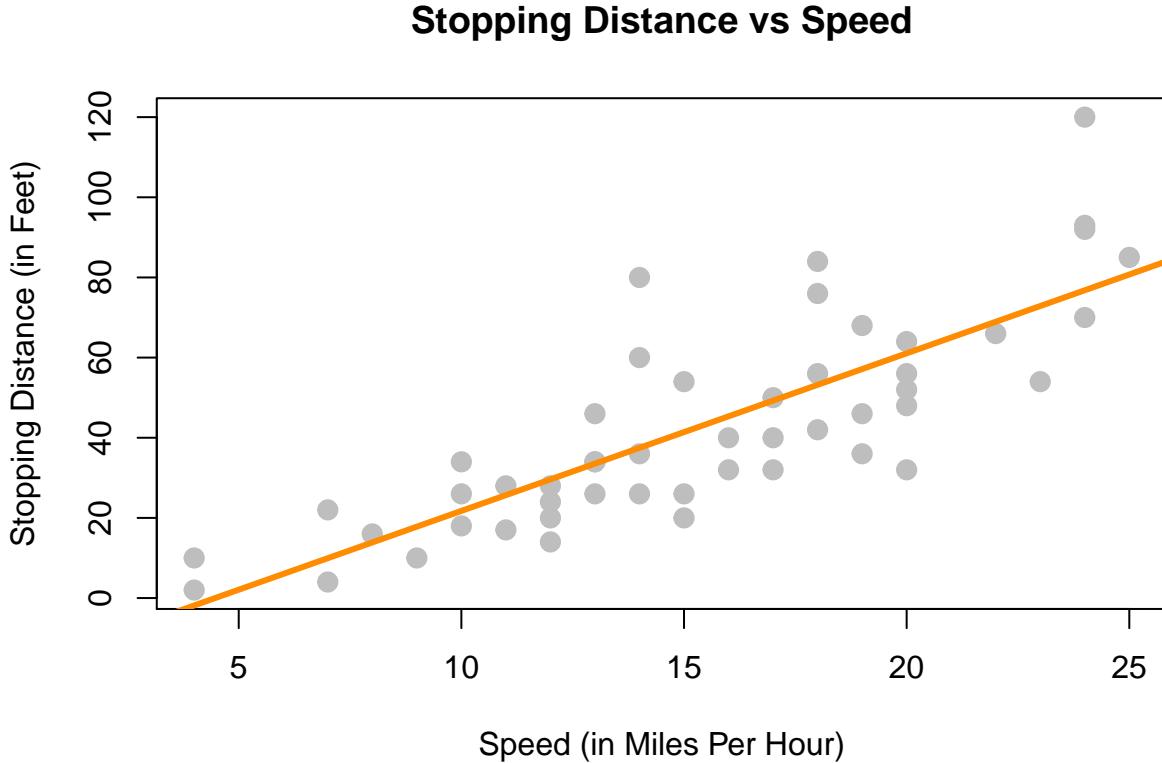


We could also try to model the data with a very “wiggly” function that tries to go through as many of the data points as possible. This also doesn’t seem to work very well. The stopping distance for a speed of 5 mph shouldn’t be off the chart! (Even in 1920.) This is an example of **overfitting**. (Note that in this example no function will go through every point, since there are some x values that have several possible y values in the data.)

Stopping Distance vs Speed



Lastly, we could try to model the data with a well chosen line rather than one of the two extremes previously attempted. The line on the plot below seems to summarize the relationship between stopping distance and speed quite well. As speed increases, the distance required to come to a stop increases. There is still some variation about this line, but it seems to capture the overall trend.



With this in mind, we would like to restrict our choice of $f(X)$ to *linear* functions of X . We will write our model using β_1 for the slope, and β_0 for the intercept,

$$Y = \beta_0 + \beta_1 X + \epsilon.$$

7.1.1 Simple Linear Regression Model

We now define what we will call the simple linear regression model,

$$Y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$

where

$$\epsilon_i \sim N(0, \sigma^2).$$

That is, the ϵ_i are *independent and identically distributed* (iid) normal random variables with mean 0 and variance σ^2 . This model has three parameters to be estimated: β_0 , β_1 , and σ^2 , which are fixed, but unknown constants.

We have slightly modified our notation here. We are now using Y_i and x_i , since we will be fitting this model to a set of n data points, for $i = 1, 2, \dots, n$.

Recall that we use capital Y to indicate a random variable, and lower case y to denote a potential value of the random variable. Since we will have n observations, we have n random variables Y_i and their possible values y_i .

In the simple linear regression model, the x_i are assumed to be fixed, known constants, and are thus notated with a lower case variable. The response Y_i remains a random variable because of the random behavior of the error variable, ϵ_i . That is, each response Y_i is tied to an observable x_i and a random, unobservable, ϵ_i .

Essentially, we could explicitly think of the Y_i as having a different distribution for each X_i . In other words, Y_i has a conditional distribution dependent on the value of X_i , written x_i . Doing so, we still make no distributional assumptions of the X_i , since we are only interested in the distribution of the Y_i for a particular value x_i .

$$Y_i | X_i \sim N(\beta_0 + \beta_1 x_i, \sigma^2)$$

The random Y_i are a function of x_i , thus we can write its mean as a function of x_i ,

$$\mathbb{E}[Y_i | X_i = x_i] = \beta_0 + \beta_1 x_i.$$

However, its variance remains constant for each x_i ,

$$\text{Var}[Y_i | X_i = x_i] = \sigma^2.$$

This is visually displayed in the image below. We see that for any value x , the expected value of Y is $\beta_0 + \beta_1 x$. At each value of x , Y has the same variance σ^2 .

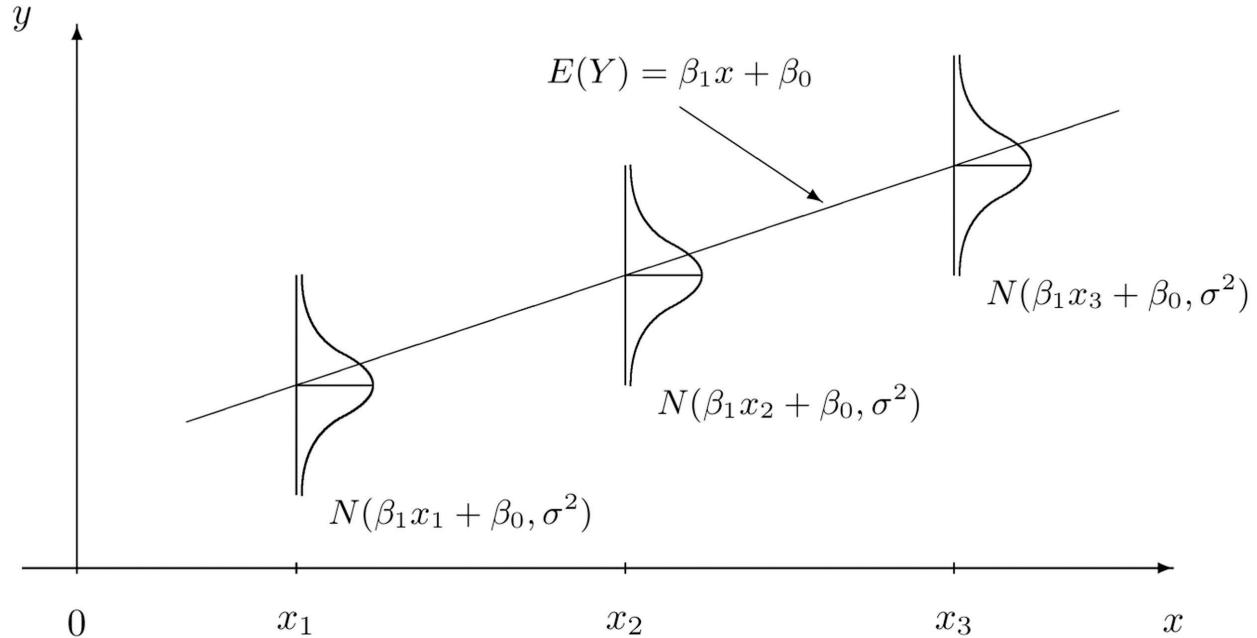


Figure 7.1: Simple Linear Regression Model Introductory Statistics (Shafer and Zhang), UC David Stat Wiki

Often, we directly talk about the assumptions that this model makes. They can be cleverly shortened to **LINE**.

- **Linear.** The relationship between Y and x is linear, of the form $\beta_0 + \beta_1 x$.

- **Indepedent.** The errors ϵ are independent.
- **Normal.** The errors, ϵ are normally distributed. That is the “error” around the line follows a normal distribution.
- **Equal Variance.** At each value of x , the variance of Y is the same, σ^2 .

We are also assuming that the values of x are fixed, that is, not random. We do not make a distributional assumption about the predictor variable.

As a side note, we will often refer to simple linear regression as **SLR**. Some explanation of the name SLR:

- **Simple** refers to the fact that we are using a single predictor variable. Later we will use multiple predictor variables.
- **Linear** tells us that our model for Y is a linear combination of the predictors X . (In this case just the one.) Right now, this always results in a model that is a line, but later we will see how this is not always the case.
- **Regression** simply means that we are attempting to measure the relationship between a response variable and (one or more) predictor variables. In the case of SLR, both the response and the predictor are *numeric* variables.

So SLR models Y as a linear function of X , but how do we actually define a good line? There are an infinite number of lines we could use, so we will attempt to find one with “small errors.” That is a line with as many points as close to it as possible. The questions now becomes, how do we find such a line? There are many approaches we could take.

We could find the line that has the smallest maximum distance from any of the points to the line. That is,

$$\operatorname{argmin}_{\beta_0, \beta_1} \max |y_i - (\beta_0 + \beta_1 x_i)|.$$

We could find the line that minimizes the sum of all the distances from the points to the line. That is,

$$\operatorname{argmin}_{\beta_0, \beta_1} \sum_{i=1}^n |y_i - (\beta_0 + \beta_1 x_i)|.$$

We could find the line that minimizes the sum of all the squared distances from the points to the line. That is,

$$\operatorname{argmin}_{\beta_0, \beta_1} \sum_{i=1}^n (y_i - (\beta_0 + \beta_1 x_i))^2.$$

This last option is called the method of **least squares**. It is essentially the de-facto method for fitting a line to data. (You may have even seen it before in a linear algebra course.) Its popularity is largely due to the fact that it is mathematically “easy.” (Which was important historically, as computers are a modern contraption.) It is also very popular because many relationships are well approximated by a linear function.

7.2 Least Squares Approach

Given observations (x_i, y_i) , for $i = 1, 2, \dots, n$, we want to find values of β_0 and β_1 which minimize

$$f(\beta_0, \beta_1) = \sum_{i=1}^n (y_i - (\beta_0 + \beta_1 x_i))^2 = \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i)^2.$$

We will call these values $\hat{\beta}_0$ and $\hat{\beta}_1$.

First, we take a partial derivative with respect to both β_0 and β_1 .

$$\begin{aligned}\frac{\partial f}{\partial \beta_0} &= -2 \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i) \\ \frac{\partial f}{\partial \beta_1} &= -2 \sum_{i=1}^n (x_i)(y_i - \beta_0 - \beta_1 x_i)\end{aligned}$$

We then set each of the partial derivatives equal to zero and solving the resulting system of equations.

$$\begin{aligned}\sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i) &= 0 \\ \sum_{i=1}^n (x_i)(y_i - \beta_0 - \beta_1 x_i) &= 0\end{aligned}$$

While solving the system of equations, one common algebraic rearrangement results in the **normal equations**.

$$\begin{aligned}n\beta_0 + \beta_1 \sum_{i=1}^n x_i &= \sum_{i=1}^n y_i \\ \beta_0 \sum_{i=1}^n x_i + \beta_1 \sum_{i=1}^n x_i^2 &= \sum_{i=1}^n x_i y_i\end{aligned}$$

Finally, we finish solving the system of equations.

$$\begin{aligned}\hat{\beta}_1 &= \frac{\sum_{i=1}^n x_i y_i - \frac{(\sum_{i=1}^n x_i)(\sum_{i=1}^n y_i)}{n}}{\sum_{i=1}^n x_i^2 - \frac{(\sum_{i=1}^n x_i)^2}{n}} = \frac{S_{xy}}{S_{xx}} \\ \hat{\beta}_0 &= \bar{y} - \hat{\beta}_1 \bar{x}\end{aligned}$$

Here, we have defined some notation for the expression we've obtained. Note that they have alternative forms which are much easier to work with. (We won't do it here, but you can try to prove the equalities below on your own, for "fun.") We use the capital letter S to denote "summation" which replaces the capital letter Σ when we calculate these values based on observed data, (x_i, y_i) . The subscripts such as xy denote over which variables the function $(z - \bar{z})$ is applied.

$$\begin{aligned}S_{xy} &= \sum_{i=1}^n x_i y_i - \frac{(\sum_{i=1}^n x_i)(\sum_{i=1}^n y_i)}{n} = \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y}) \\ S_{xx} &= \sum_{i=1}^n x_i^2 - \frac{(\sum_{i=1}^n x_i)^2}{n} = \sum_{i=1}^n (x_i - \bar{x})^2 \\ S_{yy} &= \sum_{i=1}^n y_i^2 - \frac{(\sum_{i=1}^n y_i)^2}{n} = \sum_{i=1}^n (y_i - \bar{y})^2\end{aligned}$$

Note that these summations S are not to be confused with sample standard deviation s .

By using the above alternative expressions for S_{xy} and S_{xx} , we arrive at a cleaner, more useful expression for $\hat{\beta}_1$.

$$\hat{\beta}_1 = \frac{S_{xy}}{S_{xx}} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2}$$

Traditionally we would now calculate $\hat{\beta}_0$ and $\hat{\beta}_1$ by hand for the `cars` dataset. However because we are living in the 21st century and are intelligent (or lazy or efficient, depending on your perspective), we will utilize R to do the number crunching for us.

To keep some notation consistent with above mathematics, we will store the response variable as `y` and the predictor variable as `x`.

```
x = cars$speed
y = cars$dist
```

We then calculate the three sums of squares defined above.

```
Sxy = sum((x - mean(x)) * (y - mean(y)))
Sxx = sum((x - mean(x))^ 2)
Syy = sum((y - mean(y))^ 2)
c(Sxy, Sxx, Syy)
```

```
## [1] 5387.40 1370.00 32538.98
```

Then finally calculate $\hat{\beta}_0$ and $\hat{\beta}_1$.

```
beta_1_hat = Sxy / Sxx
beta_0_hat = mean(y) - beta_1_hat * mean(x)
c(beta_0_hat, beta_1_hat)
```

```
## [1] -17.579095 3.932409
```

What do these values tell us about our dataset?

The slope *parameter* β_1 tells us that for an increase in speed of one mile per hour, the **mean** stopping distance increases by β_1 . It is important to specify that we are talking about the mean. Recall that $\beta_0 + \beta_1 x$ is the estimated mean of Y , in this case stopping distance, for a particular value of x . (In this case speed.) So β_1 tells us how the mean of Y is affected by a change in x .

Similarly, the *estimate* $\hat{\beta}_1 = 3.93$ tells us that for an increase in speed of one mile per hour, the **estimated mean** stopping distance increases by 3.93 feet. Here we should be sure to specify we are discussing an estimated quantity. Recall that \hat{y} is the estimated mean of Y , so $\hat{\beta}_1$ tells us how the estimated mean of Y is affected by changing x .

The intercept *parameter* β_0 tells us the **mean** stopping distance for a car traveling zero miles per hour. (Not moving.) The *estimate* $\hat{\beta}_0 = -17.58$ tells us that the **estimated** mean stopping distance for a car traveling zero miles per hour is -17.58 feet. So when you apply the brakes to a car that is not moving, it moves backwards? This doesn't seem right. (Extrapolation, which we will see later, is the issue here.)

7.2.1 Making Predictions

We can now write the **fitted** or estimated line,

$$\hat{y} = \hat{\beta}_0 + \hat{\beta}_1 x.$$

In this case,

$$\hat{y} = -17.58 + 3.93x.$$

We can now use this line to make predictions. First, let's see the possible x values in the `cars` dataset. Since some x values may appear more than once, we use the `unique()` to return each unique value only once.

```
unique(cars$speed)
```

```
## [1] 4 7 8 9 10 11 12 13 14 15 16 17 18 19 20 22 23 24 25
```

Let's make a prediction for the stopping distance of a car traveling at 8 miles per hour.

$$\hat{y} = -17.58 + 3.93 \times 8$$

```
beta_0_hat + beta_1_hat * 8
```

```
## [1] 13.88018
```

This tells us that the estimated mean stopping distance of a car traveling at 8 miles per hour is 13.88.

Now let's make a prediction for the stopping distance of a car traveling at 21 miles per hour. This is considered **interpolation** as 21 is not an observed value of x . (But is in the data range.) We can use the special `%in%` operator to quickly verify this in R.

```
8 %in% unique(cars$speed)
```

```
## [1] TRUE
```

```
21 %in% unique(cars$speed)
```

```
## [1] FALSE
```

```
min(cars$speed) < 21 & 21 < max(cars$speed)
```

```
## [1] TRUE
```

$$\hat{y} = -17.58 + 3.93 \times 21$$

```
beta_0_hat + beta_1_hat * 21
```

```
## [1] 65.00149
```

Lastly, we can make a prediction for the stopping distance of a car traveling at 50 miles per hour. This is considered **extrapolation** as 50 is not an observed value of x and is outside data range. We should be less confident in predictions of this type.

```
range(cars$speed)

## [1] 4 25

range(cars$speed)[1] < 50 & 50 < range(cars$speed)[2]

## [1] FALSE

 $\hat{y} = -17.58 + 3.93 \times 50$ 

beta_0_hat + beta_1_hat * 50

## [1] 179.0413
```

Cars travel 50 miles per hour rather easily today, but not in the 1920s!

This is also an issue we saw when interpreting $\hat{\beta}_0 = -17.58$, which is equivalent to making a prediction at $x = 0$. We should not be confident in the estimated linear relationship outside of the range of data we have observed.

7.2.2 Residuals

If we think of our model as “Response = Prediction + Error,” we can then write it as

$$y = \hat{y} + e.$$

We then define a **residual** to be the observed value minus the predicted value.

$$e_i = y_i - \hat{y}_i$$

Let’s calculate the residual for the prediction we made for a car traveling 8 miles per hour. First, we need to obtain the observed value of y for this x value.

```
which(cars$speed == 8)

## [1] 5

cars[5, ]

##   speed dist
## 5     8    16

cars[which(cars$speed == 8), ]

##   speed dist
## 5     8    16
```

We can then calculate the residual.

$$e = 16 - 13.88 = 2.12$$

```
16 - (beta_0_hat + beta_1_hat * 8)
```

```
## [1] 2.119825
```

The positive residual value indicates that the observed stopping distance is actually 2.12 feet more than what was predicted.

7.2.3 Variance Estimation

We'll now use the residuals for each of the points to create an estimate for the variance, σ^2 .

Recall that,

$$\mathbb{E}[Y_i | X_i = x_i] = \beta_0 + \beta_1 x_i.$$

So,

$$\hat{y}_i = \hat{\beta}_0 + \hat{\beta}_1 x_i$$

is a natural estimate for the mean of Y_i for a given value of x_i .

Also, recall that when we specified the model, we had three unknown parameters; β_0 , β_1 , and σ^2 . The method of least squares gave us estimates for β_0 and β_1 , however, we have yet to see an estimate for σ^2 . We will now define s_e^2 which will be an estimate for σ^2 .

$$\begin{aligned} s_e^2 &= \frac{1}{n-2} \sum_{i=1}^n (y_i - (\hat{\beta}_0 + \hat{\beta}_1 x_i))^2 \\ &= \frac{1}{n-2} \sum_{i=1}^n (y_i - \hat{y}_i)^2 \\ &= \frac{1}{n-2} \sum_{i=1}^n e_i^2 \end{aligned}$$

This probably seems like a natural estimate, aside from the use of $n - 2$, which we will put off explaining until the next chapter. It should actually look rather similar to something we have seen before.

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$$

Here, s^2 is the estimate of σ^2 when we have a single random variable X . In this case \bar{x} is an estimate of μ which is assumed to be the same for each x .

Now, in the regression case, with s_e^2 each y has a different mean because of the relationship with x . Thus, for each y_i , we use a different estimate of the mean, that is \hat{y}_i .

```
y_hat = beta_0_hat + beta_1_hat * x
e      = y - y_hat
n      = length(e)
s2_e   = sum(e^2) / (n - 2)
s2_e
```

```
## [1] 236.5317
```

Just as with the univariate measure of variance, this value of 236.53 doesn't have a practical interpretation in terms of stopping distance. Taking the square root, however, computes the standard deviation of the residuals, also known as *residual standard error*.

```
s_e = sqrt(s2_e)
s_e
```

```
## [1] 15.37959
```

This tells us that our estimates of mean stopping distance are “typically” off by 15.38 feet.

7.3 Decomposition of Variation

We can re-express $y_i - \bar{y}$, which measures the deviation of an observation from the sample mean, in the following way,

$$y_i - \bar{y} = (y_i - \hat{y}_i) + (\hat{y}_i - \bar{y}).$$

This is the common mathematical trick of “adding zero.” In this case we both added and subtracted \hat{y}_i .

Here, $y_i - \hat{y}_i$ measures the deviation of an observation from the fitted regression line and $\hat{y}_i - \bar{y}$ measures the deviation of the fitted regression line from the sample mean.

If we square then sum both sides of the equation above, we can obtain the following,

$$\sum_{i=1}^n (y_i - \bar{y})^2 = \sum_{i=1}^n (y_i - \hat{y}_i)^2 + \sum_{i=1}^n (\hat{y}_i - \bar{y})^2.$$

This should be somewhat alarming or amazing. How is this true? For now we will leave this questions unanswered. (Think about this, and maybe try to prove it.) We will now define three of the quantities seen in this equation.

Sum of Squares Total

$$\text{SST} = \sum_{i=1}^n (y_i - \bar{y})^2$$

The quantity “Sum of Squares Total,” or SST, represents the **total variation** of the observed y values. This should be a familiar looking expression. Note that,

$$s^2 = \frac{1}{n-1} \sum_{i=1}^n (y_i - \bar{y})^2 = \frac{1}{n-1} \text{SST}.$$

Sum of Squares Regression

$$\text{SSReg} = \sum_{i=1}^n (\hat{y}_i - \bar{y})^2$$

The quantity “Sum of Squares Regression,” SSReg, represents the **explained variation** of the observed y values.

Sum of Squares Error

$$\text{SSE} = \text{RSS} = \sum_{i=1}^n (y_i - \hat{y}_i)^2$$

The quantity “Sum of Squares Error,” SSE, represents the **unexplained variation** of the observed y values. You will often see SSE written as RSS, or “Residual Sum of Squares.”

```
SST   = sum((y - mean(y)) ^ 2)
SSReg = sum((y_hat - mean(y)) ^ 2)
SSE   = sum((y - y_hat) ^ 2)
c(SST = SST, SSReg = SSReg, SSE = SSE)
```

```
##      SST     SSReg      SSE
## 32538.98 21185.46 11353.52
```

Note that,

$$s_e^2 = \frac{\text{SSE}}{n - 2}.$$

```
SSE / (n - 2)
```

```
## [1] 236.5317
```

We can use R to verify that this matches our previous calculation of s_e^2 .

```
s2_e == SSE / (n - 2)
```

```
## [1] TRUE
```

These three measures also do not have an important practical interpretation individually. But together, they’re about to reveal a new statistic to help measure the strength of a SLR model.

7.3.1 Coefficient of Determination

The **coefficient of determination**, R^2 , is defined as

$$\begin{aligned} R^2 &= \frac{\text{SSReg}}{\text{SST}} = \frac{\sum_{i=1}^n (\hat{y}_i - \bar{y})^2}{\sum_{i=1}^n (y_i - \bar{y})^2} \\ &= \frac{\text{SST} - \text{SSE}}{\text{SST}} = 1 - \frac{\text{SSE}}{\text{SST}} \\ &= 1 - \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{\sum_{i=1}^n (y_i - \bar{y})^2} = 1 - \frac{\sum_{i=1}^n e_i^2}{\sum_{i=1}^n (y_i - \bar{y})^2} \end{aligned}$$

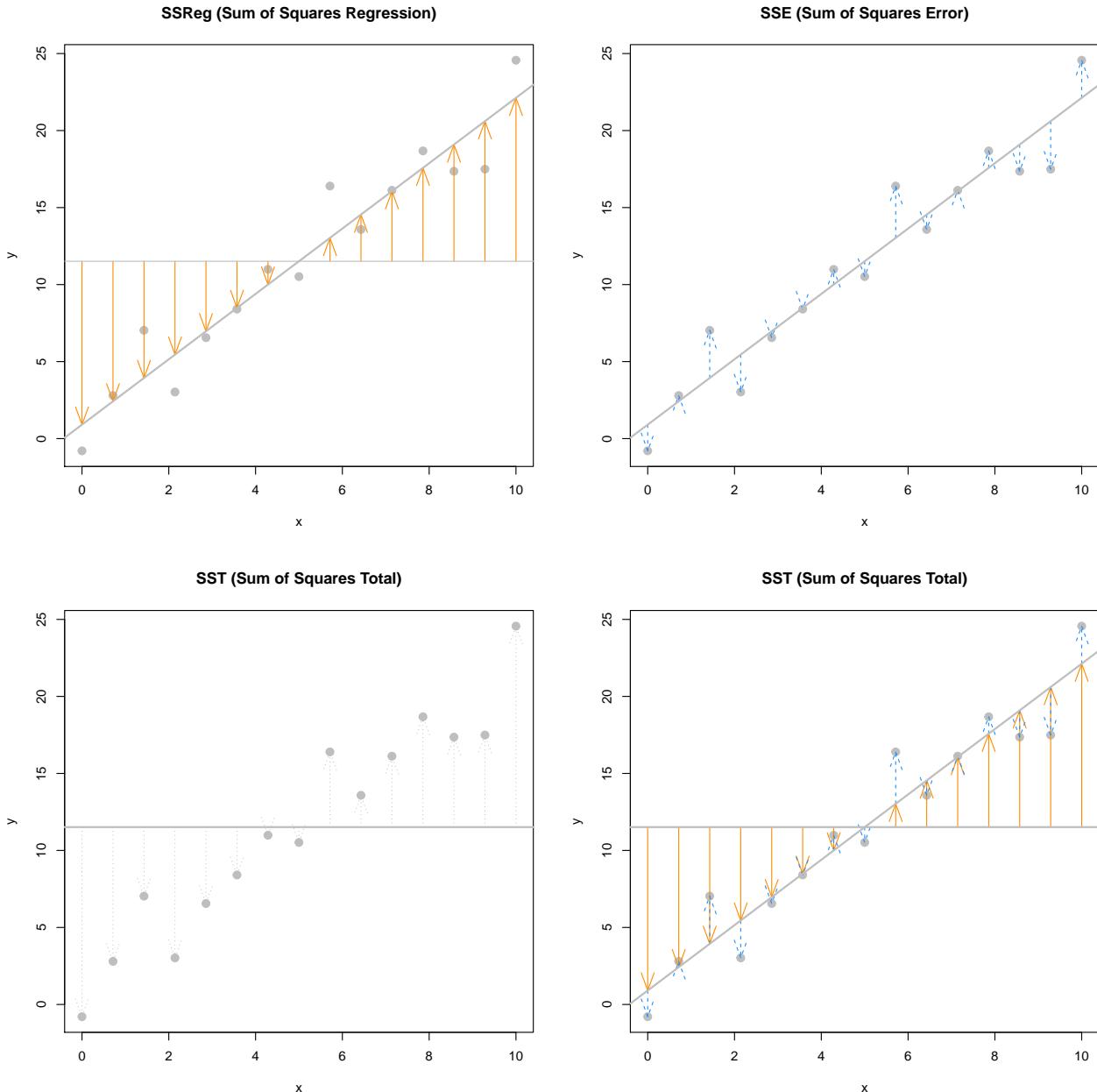
The coefficient of determination is interpreted as the proportion of observed variation in y that can be explained by the simple linear regression model.

```
R2 = SSReg / SST
R2
```

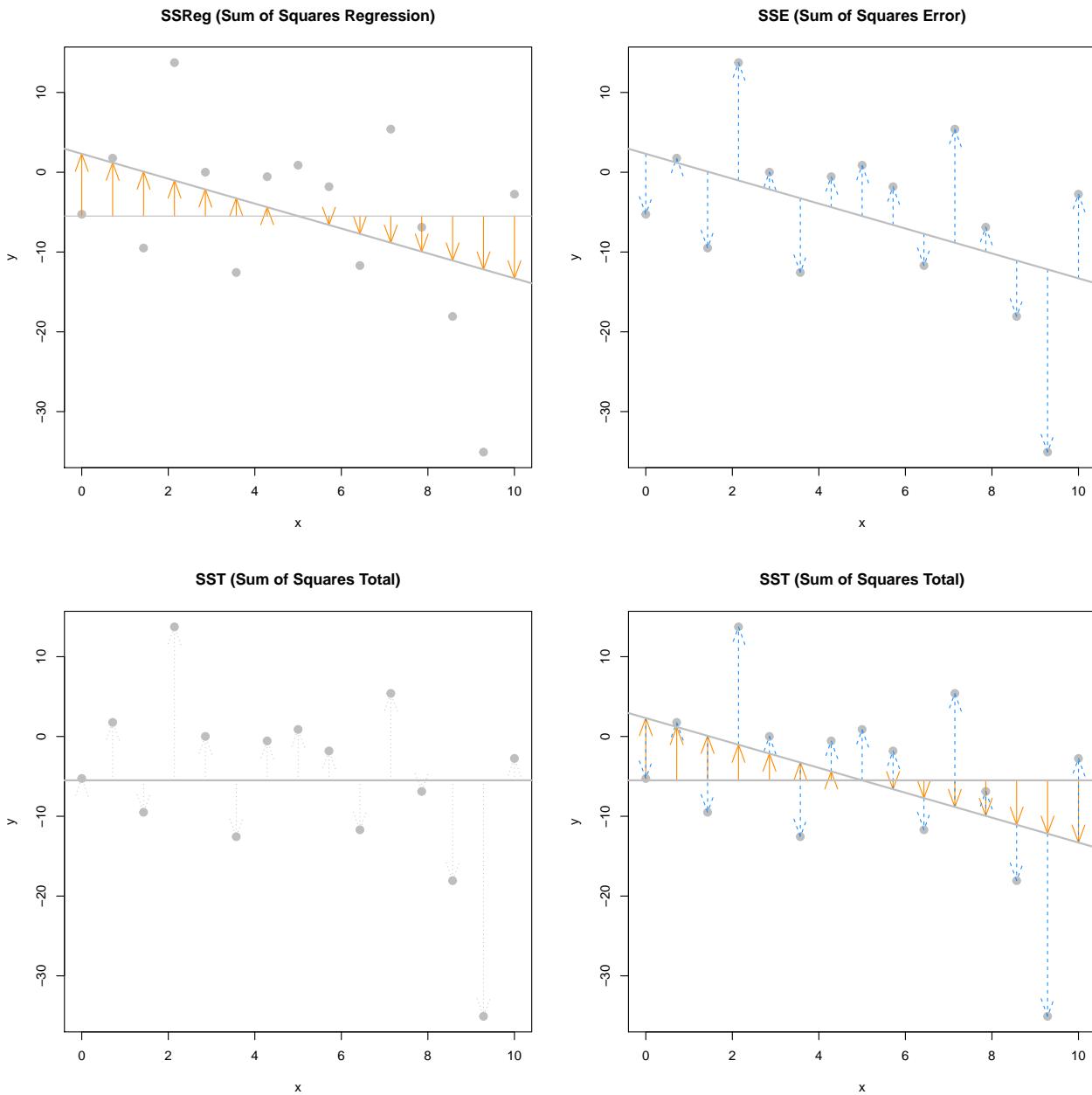
```
## [1] 0.6510794
```

For the `cars` example, we calculate $R^2 = 0.65$. We then say that 65% of the observed variability in stopping distance is explained by the linear relationship with speed.

The following plots visually demonstrate the three “sums of squares” for a simulated dataset which has $R^2 = 0.92$ which is a somewhat high value. Notice in the final plot, that the orange arrows account for a larger proportion of the total arrow.



The next plots again visually demonstrate the three “sums of squares,” this time for a simulated dataset which has $R^2 = 0.19$. Notice in the final plot, that now the blue arrows account for a larger proportion of the total arrow.



7.4 The `lm` Function

So far we have done regression by deriving the least squares estimates, then writing simple R commands to perform the necessary calculations. Since this is such a common task, this is functionality that is built directly into R via the `lm()` command.

The `lm()` command is used to fit **linear models** which actually account for a broader class of models than simple linear regression, but we will use SLR as our first demonstration of `lm()`. The `lm()` function will be one of our most commonly used tools, so you may want to take a look at the documentation by using `?lm`. You'll notice there is a lot of information there, but we will start with just the very basics. This is documentation you will want to return to often.

We'll continue using the `cars` data, and essentially use the `lm()` function to check the work we had previously done.

```
stop_dist_model = lm(dist ~ speed, data = cars)
```

This line of code fits our very first linear model. The syntax should look somewhat familiar. We use the `dist ~ speed` syntax to tell R we would like to model the response variable `dist` as a linear function of the predictor variable `speed`. In general, you should think of the syntax as `response ~ predictor`. The `data = cars` argument then tells R that that `dist` and `speed` variables are from the dataset `cars`. We then store this result in a variable `stop_dist_model`.

The variable `stop_dist_model` now contains a wealth of information, and we will now see how to extract and use that information. The first thing we will do is simply output whatever is stored immediately in the variable `stop_dist_model`.

```
stop_dist_model
```

```
##  
## Call:  
## lm(formula = dist ~ speed, data = cars)  
##  
## Coefficients:  
## (Intercept)      speed  
## -17.579        3.932
```

We see that it first tells us the formula we input into R, that is `lm(formula = dist ~ speed, data = cars)`. We also see the coefficients of the model. We can check that these are what we had calculated previously. (Minus some rounding that R is doing when displaying the results. They are stored with full precision.)

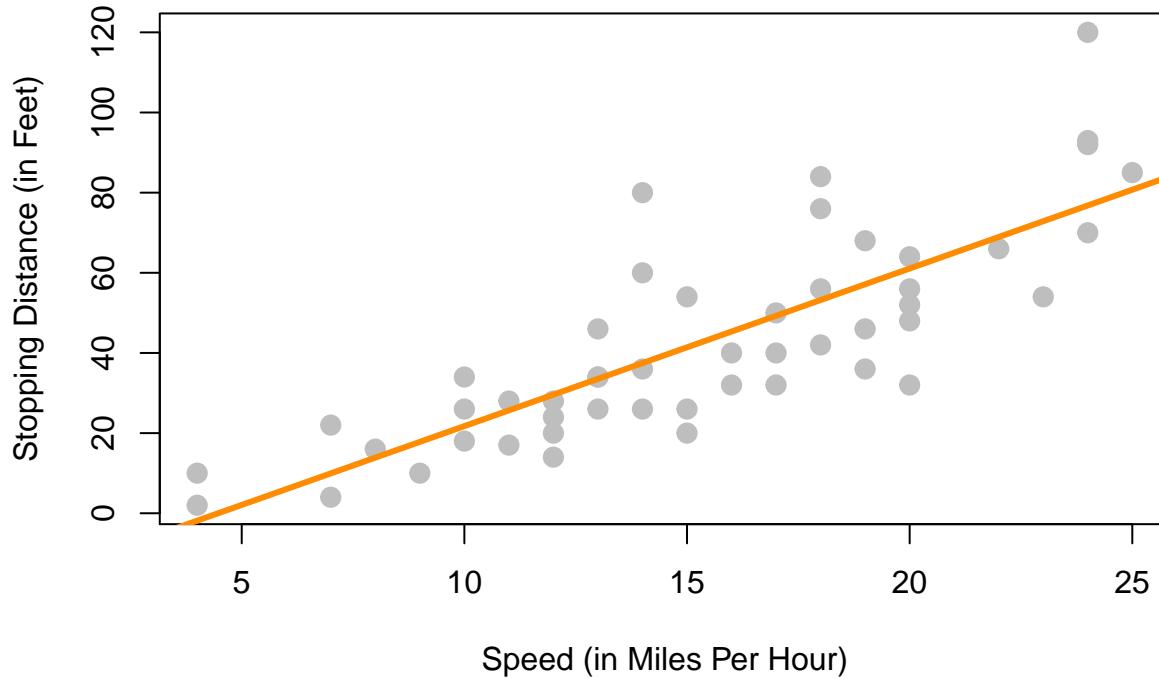
```
c(beta_0_hat, beta_1_hat)
```

```
## [1] -17.579095  3.932409
```

Next, it would be nice to add the fitted line to the scatterplot. To do so we will use the `abline()` function.

```
plot(dist ~ speed, data = cars,  
     xlab = "Speed (in Miles Per Hour)",  
     ylab = "Stopping Distance (in Feet)",  
     main = "Stopping Distance vs Speed",  
     pch = 20,  
     cex = 2,  
     col = "grey")  
abline(stop_dist_model, lwd = 3, col = "darkorange")
```

Stopping Distance vs Speed



The `abline()` function is used to add lines of the form $a + bx$ to a plot. (Hence `abline`.) When we give it `stop_dist_model` as an argument, it automatically extracts the regression coefficient estimates ($\hat{\beta}_0$ and $\hat{\beta}_1$) and uses them as the slope and intercept of the line. Here we also use `lwd` to modify the width of the line, as well as `col` to modify the color of the line.

The “thing” that is returned by the `lm()` function is actually an object of class `lm` which is a list. The exact details of this are unimportant unless you are seriously interested in the inner-workings of R, but know that we can determine the names of the elements of the list using the `names()` command.

```
names(stop_dist_model)
```

```
## [1] "coefficients"   "residuals"        "effects"          "rank"
## [5] "fitted.values"  "assign"           "qr"              "df.residual"
## [9] "xlevels"         "call"            "terms"           "model"
```

We can then use this information to, for example, access the residuals using the `$` operator.

```
stop_dist_model$residuals
```

```
##      1       2       3       4       5       6       7
## 3.849460 11.849460 -5.947766 12.052234 2.119825 -7.812584 -3.744993
##      8       9      10      11      12      13      14
## 4.255007 12.255007 -8.677401 2.322599 -15.609810 -9.609810 -5.609810
##     15      16      17      18      19      20      21
## -1.609810 -7.542219  0.457781  0.457781 12.457781 -11.474628 -1.474628
##     22      23      24      25      26      27      28
## 22.525372 42.525372 -21.407036 -15.407036 12.592964 -13.339445 -5.339445
##     29      30      31      32      33      34      35
```

```

## -17.271854 -9.271854  0.728146 -11.204263  2.795737 22.795737 30.795737
##      36       37       38       39       40       41       42
## -21.136672 -11.136672 10.863328 -29.069080 -13.069080 -9.069080 -5.069080
##      43       44       45       46       47       48       49
##    2.930920 -2.933898 -18.866307 -6.798715 15.201285 16.201285 43.201285
##      50
##    4.268876

```

Another way to access stored information in `stop_dist_model` are the `coef()`, `resid()`, and `fitted()` functions. These return the coefficients, residuals, and fitted values, respectively.

```
coef(stop_dist_model)
```

```

## (Intercept)      speed
## -17.579095   3.932409

```

```
resid(stop_dist_model)
```

```

##      1       2       3       4       5       6       7
##  3.849460 11.849460 -5.947766 12.052234  2.119825 -7.812584 -3.744993
##      8       9      10      11      12      13      14
##  4.255007 12.255007 -8.677401  2.322599 -15.609810 -9.609810 -5.609810
##     15      16      17      18      19      20      21
## -1.609810 -7.542219  0.457781  0.457781 12.457781 -11.474628 -1.474628
##     22      23      24      25      26      27      28
## 22.525372 42.525372 -21.407036 -15.407036 12.592964 -13.339445 -5.339445
##     29      30      31      32      33      34      35
## -17.271854 -9.271854  0.728146 -11.204263  2.795737 22.795737 30.795737
##     36      37      38      39      40      41      42
## -21.136672 -11.136672 10.863328 -29.069080 -13.069080 -9.069080 -5.069080
##     43      44      45      46      47      48      49
##    2.930920 -2.933898 -18.866307 -6.798715 15.201285 16.201285 43.201285
##      50
##    4.268876

```

```
fitted(stop_dist_model)
```

```

##      1       2       3       4       5       6       7       8
## -1.849460 -1.849460  9.947766  9.947766 13.880175 17.812584 21.744993 21.744993
##      9      10      11      12      13      14      15      16
## 21.744993 25.677401 25.677401 29.609810 29.609810 29.609810 29.609810 33.542219
##     17      18      19      20      21      22      23      24
## 33.542219 33.542219 33.542219 37.474628 37.474628 37.474628 37.474628 41.407036
##     25      26      27      28      29      30      31      32
## 41.407036 41.407036 45.339445 45.339445 49.271854 49.271854 49.271854 53.204263
##     33      34      35      36      37      38      39      40
## 53.204263 53.204263 53.204263 57.136672 57.136672 57.136672 61.069080 61.069080
##     41      42      43      44      45      46      47      48
## 61.069080 61.069080 61.069080 68.933898 72.866307 76.798715 76.798715 76.798715
##     49      50
## 76.798715 80.731124

```

An R function that is useful in many situations is `summary()`. We see that when it is called on our model, it returns a good deal of information. By the end of the course, you will know what every value here is used for. For now, you should immediately notice the coefficient estimates, and you may recognize the R^2 value we saw earlier.

```
summary(stop_dist_model)

##
## Call:
## lm(formula = dist ~ speed, data = cars)
##
## Residuals:
##    Min     1Q Median     3Q    Max
## -29.069 -9.525 -2.272  9.215 43.201
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) -17.5791   6.7584 -2.601  0.0123 *
## speed        3.9324   0.4155  9.464 1.49e-12 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 15.38 on 48 degrees of freedom
## Multiple R-squared:  0.6511, Adjusted R-squared:  0.6438
## F-statistic: 89.57 on 1 and 48 DF,  p-value: 1.49e-12
```

The `summary()` command also returns a list, and we can again use `names()` to learn what about the elements of this list.

```
names(summary(stop_dist_model))

## [1] "call"          "terms"         "residuals"      "coefficients"
## [5] "aliased"       "sigma"         "df"            "r.squared"
## [9] "adj.r.squared" "fstatistic"    "cov.unscaled"
```

So, for example, if we wanted to directly access the value of R^2 , instead of copy and pasting it out of the printed statement from `summary()`, we could do so.

```
summary(stop_dist_model)$r.squared

## [1] 0.6510794
```

Another value we may want to access is s_e , which R calls `sigma`.

```
summary(stop_dist_model)$sigma

## [1] 15.37959
```

Note that this is the same result seen earlier as `s_e`. You may also notice that this value was display above as a result of the `summary()` command, which R labeled the “Residual Standard Error.”

$$s_e = \text{RSE} = \sqrt{\frac{1}{n-2} \sum_{i=1}^n e_i^2}$$

Often it is useful to talk about s_e (or RSE) instead of s_e^2 because of their units. The units of s_e in the `cars` example is feet, while the units of s_e^2 is feet-squared.

Another useful function, which we will use almost as often as `lm()` is the `predict()` function.

```
predict(stop_dist_model, newdata = data.frame(speed = 8))
```

```
##      1
## 13.88018
```

The above code reads “predict the stopping distance of a car traveling 8 miles per hour using the `stop_dist_model`.” Importantly, the second argument to `predict()` is a data frame that we make in place. We do this so that we can specify that 8 is a value of `speed`, so that `predict` knows how to use it with the model stored in `stop_dist_model`. We see that this result is what we had calculated “by hand” previously.

We could also predict multiple values at once.

```
predict(stop_dist_model, newdata = data.frame(speed = c(8, 21, 50)))
```

```
##      1      2      3
## 13.88018 65.00149 179.04134
```

$$\begin{aligned}\hat{y} &= -17.58 + 3.93 \times 8 = 13.88 \\ \hat{y} &= -17.58 + 3.93 \times 21 = 65 \\ \hat{y} &= -17.58 + 3.93 \times 50 = 179.04\end{aligned}$$

Or we could calculate the fitted value for each of the original data points. We can simply supply the original data frame, `cars`, since it contains a variables called `speed` which has the values we would like to predict at.

```
predict(stop_dist_model, newdata = cars)
```

```
##      1      2      3      4      5      6      7      8
## -1.849460 -1.849460 9.947766 9.947766 13.880175 17.812584 21.744993 21.744993
##      9     10     11     12     13     14     15     16
## 21.744993 25.677401 25.677401 29.609810 29.609810 29.609810 29.609810 33.542219
##     17     18     19     20     21     22     23     24
## 33.542219 33.542219 33.542219 37.474628 37.474628 37.474628 37.474628 41.407036
##     25     26     27     28     29     30     31     32
## 41.407036 41.407036 45.339445 45.339445 49.271854 49.271854 49.271854 53.204263
##     33     34     35     36     37     38     39     40
## 53.204263 53.204263 53.204263 57.136672 57.136672 57.136672 61.069080 61.069080
##     41     42     43     44     45     46     47     48
## 61.069080 61.069080 61.069080 68.933898 72.866307 76.798715 76.798715 76.798715
##     49     50
## 76.798715 80.731124
```

```
# predict(stop_dist_model, newdata = data.frame(speed = cars$speed))
```

This is actually equivalent to simply calling `predict()` on `stop_dist_model` without a second argument.

```
predict(stop_dist_model)
```

```
##      1      2      3      4      5      6      7      8
## -1.849460 -1.849460 9.947766 9.947766 13.880175 17.812584 21.744993 21.744993
##      9     10     11     12     13     14     15     16
## 21.744993 25.677401 25.677401 29.609810 29.609810 29.609810 29.609810 33.542219
##     17     18     19     20     21     22     23     24
## 33.542219 33.542219 33.542219 37.474628 37.474628 37.474628 37.474628 41.407036
##     25     26     27     28     29     30     31     32
## 41.407036 41.407036 45.339445 45.339445 49.271854 49.271854 49.271854 53.204263
##     33     34     35     36     37     38     39     40
## 53.204263 53.204263 53.204263 57.136672 57.136672 57.136672 61.069080 61.069080
##     41     42     43     44     45     46     47     48
## 61.069080 61.069080 61.069080 68.933898 72.866307 76.798715 76.798715 76.798715
##     49     50
## 76.798715 80.731124
```

Note that then in this case, this is the same as using `fitted()`.

```
fitted(stop_dist_model)
```

```
##      1      2      3      4      5      6      7      8
## -1.849460 -1.849460 9.947766 9.947766 13.880175 17.812584 21.744993 21.744993
##      9     10     11     12     13     14     15     16
## 21.744993 25.677401 25.677401 29.609810 29.609810 29.609810 29.609810 33.542219
##     17     18     19     20     21     22     23     24
## 33.542219 33.542219 33.542219 37.474628 37.474628 37.474628 37.474628 41.407036
##     25     26     27     28     29     30     31     32
## 41.407036 41.407036 45.339445 45.339445 49.271854 49.271854 49.271854 53.204263
##     33     34     35     36     37     38     39     40
## 53.204263 53.204263 53.204263 57.136672 57.136672 57.136672 61.069080 61.069080
##     41     42     43     44     45     46     47     48
## 61.069080 61.069080 61.069080 68.933898 72.866307 76.798715 76.798715 76.798715
##     49     50
## 76.798715 80.731124
```

7.5 Maximum Likelihood Estimation (MLE) Approach

Recall the model,

$$Y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$

where $\epsilon_i \sim N(0, \sigma^2)$.

Then we can find the mean and variance of each Y_i .

$$\mathbb{E}[Y_i | X_i = x_i] = \beta_0 + \beta_1 x_i$$

and

$$\text{Var}[Y_i | X_i = x_i] = \sigma^2.$$

Additionally, the Y_i follow a normal distribution conditioned on the x_i .

$$Y_i | X_i \sim N(\beta_0 + \beta_1 x_i, \sigma^2)$$

Recall that the pdf of a random variable $X \sim N(\mu, \sigma^2)$ is given by

$$f_X(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2\right].$$

Then we can write the pdf of each of the Y_i as

$$f_{Y_i}(y_i; x_i, \beta_0, \beta_1, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{1}{2}\left(\frac{y_i - (\beta_0 + \beta_1 x_i)}{\sigma}\right)^2\right].$$

Given n data points (x_i, y_i) we can write the likelihood, which is a function of the three parameters β_0 , β_1 , and σ^2 . Since the data have been observed, we use lower case y_i to denote that these values are no longer random.

$$L(\beta_0, \beta_1, \sigma^2) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left[-\frac{1}{2}\left(\frac{y_i - \beta_0 - \beta_1 x_i}{\sigma}\right)^2\right]$$

Our goal is to find values of β_0 , β_1 , and σ^2 which maximize this function, which is a straightforward multivariate calculus problem.

We'll start by doing a bit of rearranging to make our task easier.

$$L(\beta_0, \beta_1, \sigma^2) = \left(\frac{1}{\sqrt{2\pi\sigma^2}}\right)^n \exp\left[-\frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i)^2\right]$$

Then, as is often the case when finding MLEs, for mathematical convenience we will take the natural logarithm of the likelihood function since log is a monotonically increasing function. Then we will proceed to maximize the log-likelihood, and the resulting estimates will be the same as if we had not taken the log.

$$\log L(\beta_0, \beta_1, \sigma^2) = -\frac{n}{2} \log(2\pi) - \frac{n}{2} \log(\sigma^2) - \frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i)^2$$

Note that we use log to mean the natural logarithm. We now take a partial derivative with respect to each of the parameters.

$$\begin{aligned}\frac{\partial \log L(\beta_0, \beta_1, \sigma^2)}{\partial \beta_0} &= \frac{1}{\sigma^2} \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i) \\ \frac{\partial \log L(\beta_0, \beta_1, \sigma^2)}{\partial \beta_1} &= \frac{1}{\sigma^2} \sum_{i=1}^n (x_i)(y_i - \beta_0 - \beta_1 x_i) \\ \frac{\partial \log L(\beta_0, \beta_1, \sigma^2)}{\partial \sigma^2} &= -\frac{n}{2\sigma^2} + \frac{1}{2(\sigma^2)^2} \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i)^2\end{aligned}$$

We then set each of the partial derivatives equal to zero and solve the resulting system of equations.

$$\begin{aligned}\sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i) &= 0 \\ \sum_{i=1}^n (x_i)(y_i - \beta_0 - \beta_1 x_i) &= 0 \\ -\frac{n}{2\sigma^2} + \frac{1}{2(\sigma^2)^2} \sum_{i=1}^n (y_i - \beta_0 - \beta_1 x_i)^2 &= 0\end{aligned}$$

You may notice that the first two equations also appear in the least squares approach. Then, skipping the issue of actually checking if we have found a maximum, we then arrive at our estimates. We call these estimates the maximum likelihood estimates.

$$\begin{aligned}\hat{\beta}_1 &= \frac{\sum_{i=1}^n x_i y_i - \frac{(\sum_{i=1}^n x_i)(\sum_{i=1}^n y_i)}{n}}{\sum_{i=1}^n x_i^2 - \frac{(\sum_{i=1}^n x_i)^2}{n}} = \frac{S_{xy}}{S_{xx}} \\ \hat{\beta}_0 &= \bar{y} - \hat{\beta}_1 \bar{x} \\ \hat{\sigma}^2 &= \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2\end{aligned}$$

Note that $\hat{\beta}_0$ and $\hat{\beta}_1$ are the same as the least squares estimates. However we now have a new estimate of σ^2 , that is $\hat{\sigma}^2$. So we now have two different estimates of σ^2 .

$$\begin{aligned}s_e^2 &= \frac{1}{n-2} \sum_{i=1}^n (y_i - \hat{y}_i)^2 = \frac{1}{n-2} \sum_{i=1}^n e_i^2 && \text{Least Squares} \\ \hat{\sigma}^2 &= \frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2 = \frac{1}{n} \sum_{i=1}^n e_i^2 && \text{MLE}\end{aligned}$$

In the next chapter, we will discuss in detail the difference between these two estimates, which involves biasedness.

7.6 Simulating SLR

We return again to more examples of simulation. This will be a common theme!

In practice you will almost never have a true model, and you will use data to attempt to recover information about the unknown true model. With simulation, we decide the true model and simulate data from it. Then

we apply a method to the data, in this case least squares. Now, since we know the true model, we can assess how well it did.

For this example, we will simulate $n = 21$ observations from the model

$$Y = 5 - 2x + \epsilon.$$

That is $\beta_0 = 5$, $\beta_1 = -2$, and let $\epsilon \sim N(\mu = 0, \sigma^2 = 9)$. Or, even more succinctly we could write

$$Y | X \sim N(\mu = 5 - 2x, \sigma^2 = 9).$$

We first set the true parameters of the model to be simulated.

```
num_obs = 21
beta_0  = 5
beta_1  = -2
sigma   = 3
```

Next, we obtain simulated values of ϵ_i after setting a seed for reproducibility.

```
set.seed(1)
epsilon = rnorm(n = num_obs, mean = 0, sd = sigma)
```

Now, since the x_i values in SLR are considered fixed and known, we simply specify 20 values. Another common practice is to generate them from a uniform distribution, and then use them for the remainder of the analysis.

```
x_vals = seq(from = 0, to = 10, length.out = num_obs)
# set.seed(1)
# x_vals = runif(num_obs, 0, 10)
```

We then generate the y values according the specified functional relationship.

```
y_vals = beta_0 + beta_1 * x_vals + epsilon
```

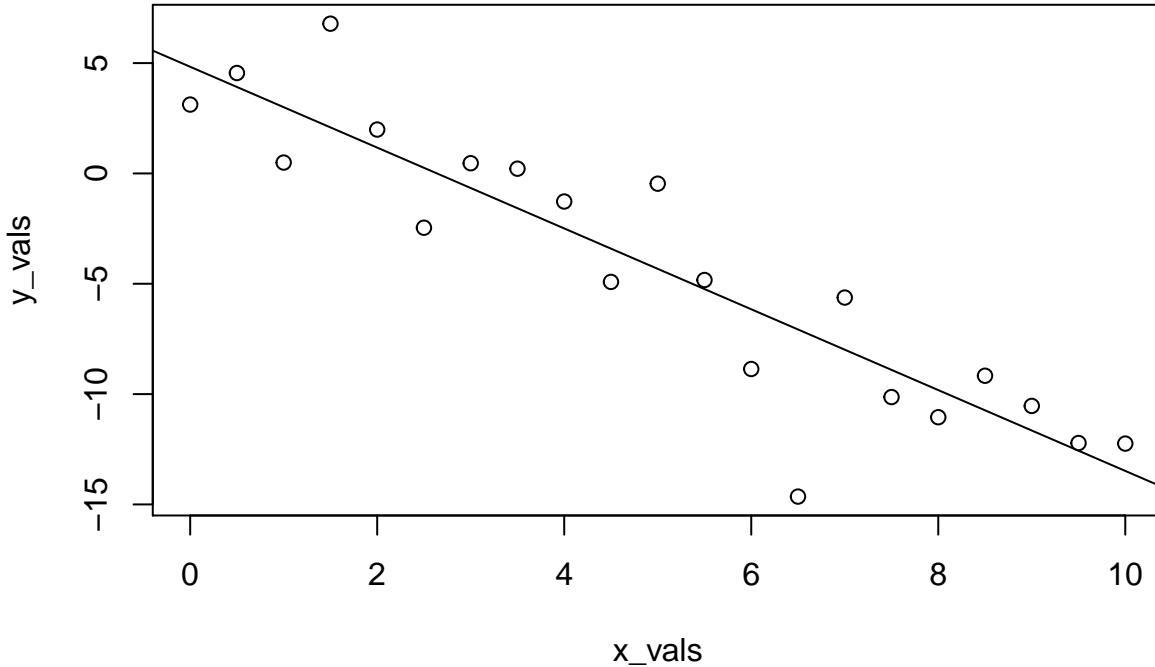
The data, (x_i, y_i) , represent a possible sample from the true distribution. Now to check how well the method of least squares works, we use `lm()` to fit the model to our simulated data, then take a look at the estimated coefficients.

```
sim_fit = lm(y_vals ~ x_vals)
coef(sim_fit)
```

```
## (Intercept)      x_vals
##     4.832639    -1.831401
```

And look at that, they aren't too far from the true parameters we specified!

```
plot(y_vals ~ x_vals)
abline(sim_fit)
```



We should say here, that we're being sort of lazy, and not the good kinda of lazy that could be considered efficient. Any time you simulate data, you should consider doing two things: writing a function, and storing the data in a data frame.

The function below, `sim_slr()`, can be used for the same task as above, but is much more flexible. Notice that we provide `x` to the function, instead of generating `x` inside the function. In the SLR model, the x_i are considered known values. That is, they are not random, so we do not assume a distribution for the x_i . Because of this, we will repeatedly use the same `x` values across all simulations.

```
sim_slr = function(x, beta_0 = 10, beta_1 = 5, sigma = 1) {
  n = length(x)
  epsilon = rnorm(n, mean = 0, sd = sigma)
  y = beta_0 + beta_1 * x + epsilon
  data.frame(predictor = x, response = y)
}
```

Here, we use the function to repeat the analysis above.

```
set.seed(1)
sim_data = sim_slr(x = x_vals, beta_0 = 5, beta_1 = -2, sigma = 3)
```

This time, the simulated observations are stored in a data frame.

```
head(sim_data)
```

	predictor	response
## 1	0.0	3.1206386
## 2	0.5	4.5509300
## 3	1.0	0.4931142
## 4	1.5	6.7858424
## 5	2.0	1.9885233
## 6	2.5	-2.4614052

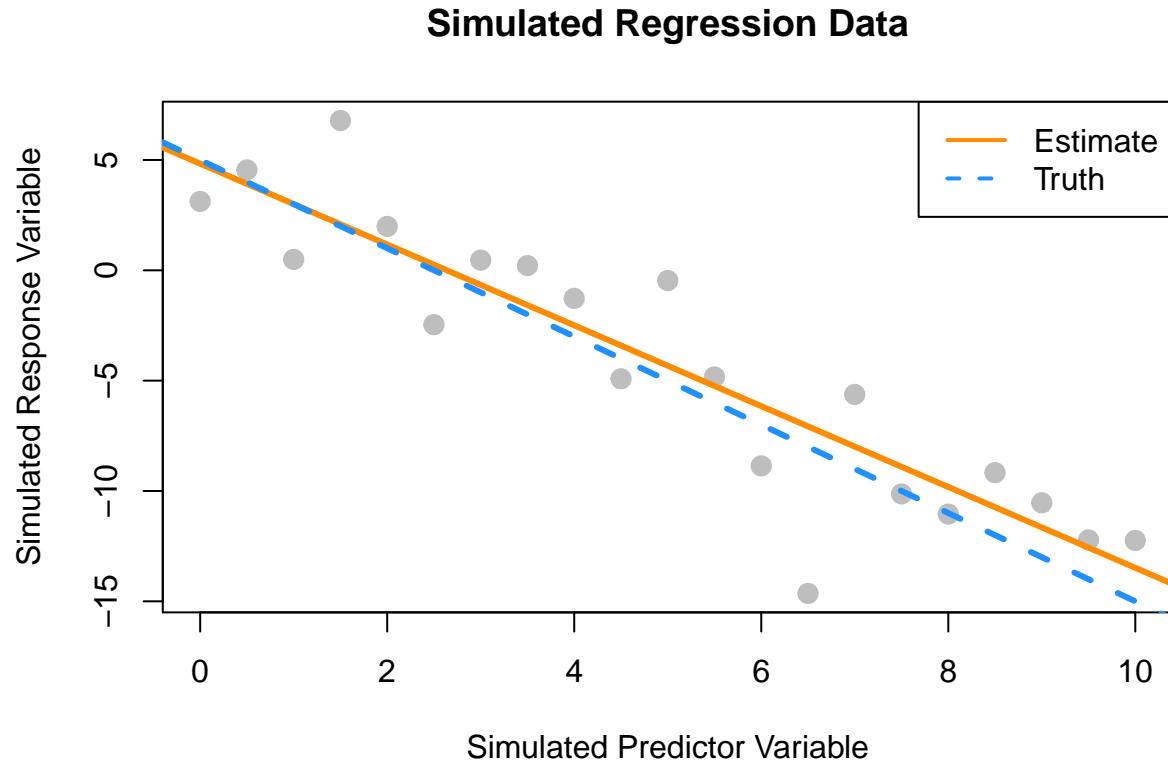
Now when we fit the model with `lm()` we can use a `data` argument, a very good practice.

```
sim_fit = lm(response ~ predictor, data = sim_data)
coef(sim_fit)
```

```
## (Intercept)  predictor
##     4.832639   -1.831401
```

And this time, we'll make the plot look a lot nicer.

```
plot(response ~ predictor, data = sim_data,
      xlab = "Simulated Predictor Variable",
      ylab = "Simulated Response Variable",
      main = "Simulated Regression Data",
      pch = 20,
      cex = 2,
      col = "grey")
abline(sim_fit, lwd = 3, lty = 1, col = "darkorange")
abline(beta_0, beta_1, lwd = 3, lty = 2, col = "dodgerblue")
legend("topright", c("Estimate", "Truth"), lty = c(1, 2), lwd = 2,
       col = c("darkorange", "dodgerblue"))
```



7.7 History

For some brief background on the history of linear regression, see “Galton, Pearson, and the Peas: A Brief History of Linear Regression for Statistics Instructors” from the Journal of Statistics Education as well as the Wikipedia page on the history of regression analysis and lastly the article for regression to the mean which details the origins of the term “regression.”

Chapter 8

Inference for Simple Linear Regression

“There are three types of lies: lies, damn lies, and statistics.”

— Benjamin Disraeli

After reading this chapter you will be able to:

- Understand the distributions of regression estimates.
- Create interval estimates for regression parameters, mean response, and predictions.
- Test for significance of regression.

Last chapter we defined the simple linear regression model,

$$Y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$

where $\epsilon_i \sim N(0, \sigma^2)$. We then used observations (x_i, y_i) , for $i = 1, 2, \dots, n$, to find values of β_0 and β_1 which minimized

$$f(\beta_0, \beta_1) = \sum_{i=1}^n (y_i - (\beta_0 + \beta_1 x_i))^2.$$

We called these values $\hat{\beta}_0$ and $\hat{\beta}_1$, which we found to be

$$\begin{aligned}\hat{\beta}_1 &= \frac{S_{xy}}{S_{xx}} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sum_{i=1}^n (x_i - \bar{x})^2} \\ \hat{\beta}_0 &= \bar{y} - \hat{\beta}_1 \bar{x}.\end{aligned}$$

We also estimated σ^2 using s_e^2 . In other words, we found that s_e is an estimate of σ , where;

$$s_e = \text{RSE} = \sqrt{\frac{1}{n-2} \sum_{i=1}^n e_i^2}$$

which we also called RSE, for “Residual Standard Error.”

When applied to the `cars` data, we obtained the following results:

```

stop_dist_model = lm(dist ~ speed, data = cars)
summary(stop_dist_model)

## 
## Call:
## lm(formula = dist ~ speed, data = cars)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -29.069  -9.525  -2.272   9.215  43.201
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) -17.5791    6.7584  -2.601  0.0123 *
## speed        3.9324    0.4155   9.464 1.49e-12 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 15.38 on 48 degrees of freedom
## Multiple R-squared:  0.6511, Adjusted R-squared:  0.6438
## F-statistic: 89.57 on 1 and 48 DF,  p-value: 1.49e-12

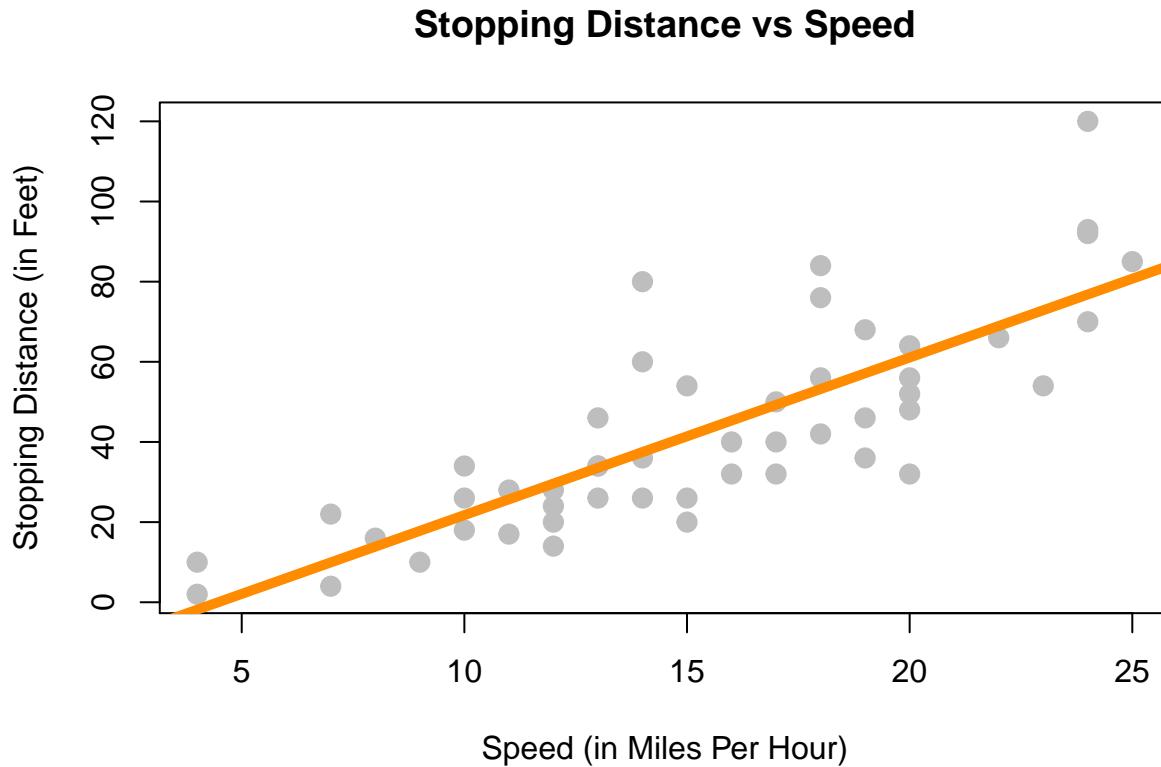
```

Last chapter, we only discussed the `Estimate`, `Residual standard error`, and `Multiple R-squared` values. In this chapter, we will discuss all of the information under `Coefficients` as well as `F-statistic`.

```

plot(dist ~ speed, data = cars,
      xlab = "Speed (in Miles Per Hour)",
      ylab = "Stopping Distance (in Feet)",
      main = "Stopping Distance vs Speed",
      pch = 20,
      cex = 2,
      col = "grey")
abline(stop_dist_model, lwd = 5, col = "darkorange")

```



To get started, we'll note that there is another equivalent expression for S_{xy} which we did not see last chapter,

$$S_{xy} = \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y}) = \sum_{i=1}^n (x_i - \bar{x})y_i.$$

This may be a surprising equivalence. (Maybe try to prove it.) However, it will be useful for illustrating concepts in this chapter.

Note that, $\hat{\beta}_1$ is a **sample statistic** when calculated with observed data as written above, as is $\hat{\beta}_0$.

However, in this chapter it will often be convenient to use both $\hat{\beta}_1$ and $\hat{\beta}_0$ as **random variables**, that is, we have not yet observed the values for each Y_i . When this is the case, we will use a slightly different notation, substituting in capital Y_i for lower case y_i .

$$\begin{aligned}\hat{\beta}_1 &= \frac{\sum_{i=1}^n (x_i - \bar{x})Y_i}{\sum_{i=1}^n (x_i - \bar{x})^2} \\ \hat{\beta}_0 &= \bar{Y} - \hat{\beta}_1 \bar{x}\end{aligned}$$

Last chapter we argued that these estimates of unknown model parameters β_0 and β_1 were good because we obtained them by minimizing errors. We will now discuss the Gauss–Markov theorem which takes this idea further, showing that these estimates are actually the “best” estimates, from a certain point of view.

8.1 Gauss–Markov Theorem

The **Gauss–Markov theorem** tells us that when estimating the parameters of the simple linear regression model β_0 and β_1 , the $\hat{\beta}_0$ and $\hat{\beta}_1$ which we derived are the **best linear unbiased estimates**, or *BLUE* for short. (The actual conditions for the Gauss–Markov theorem are more relaxed than the SLR model.)

We will now discuss *linear*, *unbiased*, and *best* as is relates to these estimates.

Linear

Recall, in the SLR setup that the x_i values are considered fixed and known quantities. Then a **linear** estimate is one which can be written as a linear combination of the Y_i . In the case of $\hat{\beta}_1$ we see

$$\hat{\beta}_1 = \frac{\sum_{i=1}^n (x_i - \bar{x}) Y_i}{\sum_{i=1}^n (x_i - \bar{x})^2} = \sum_{i=1}^n k_i Y_i = k_1 Y_1 + k_2 Y_2 + \cdots + k_n Y_n$$

$$\text{where } k_i = \frac{(x_i - \bar{x})}{\sum_{i=1}^n (x_i - \bar{x})^2}.$$

In a similar fashion, we could show that $\hat{\beta}_0$ can be written as a linear combination of the Y_i . Thus both $\hat{\beta}_0$ and $\hat{\beta}_1$ are linear estimators.

Unbiased

Now that we know our estimates are *linear*, how good are these estimates? One measure of the “goodness” of an estimate is its **bias**. Specifically, we prefer estimates that are **unbiased**, meaning their expected value is the parameter being estimated.

In the case of the regression estimates, we have,

$$\begin{aligned} E[\hat{\beta}_0] &= \beta_0 \\ E[\hat{\beta}_1] &= \beta_1. \end{aligned}$$

This tells us that, when the conditions of the SLR model are met, on average our estimates will be correct. However, as we saw last chapter when simulating from the SLR model, that does not mean that each individual estimate will be correct. Only that, if we repeated the process an infinite number of times, on average the estimate would be correct.

Best

Now, if we restrict ourselves to both *linear* and *unbiased* estimates, how do we define the *best* estimate? The estimate with the **minimum variance**.

First note that it is very easy to create an estimate for β_1 that has very low variance, but is not unbiased. For example, define:

$$\hat{\theta}_{BAD} = 5.$$

Then, since $\hat{\theta}_{BAD}$ is a constant value,

$$\text{Var}[\hat{\theta}_{BAD}] = 0.$$

However since,

$$E[\hat{\theta}_{BAD}] = 5$$

we say that $\hat{\theta}_{BAD}$ is a biased estimator unless $\beta_1 = 5$, which we would not know ahead of time. For this reason, it is a terrible estimate (unless by chance $\beta_1 = 5$) even though it has the smallest possible variance.

This is part of the reason we restrict ourselves to *unbiased* estimates. What good is an estimate, if it estimates the wrong quantity?

So now, the natural question is, what are the variances of $\hat{\beta}_0$ and $\hat{\beta}_1$? They are,

$$\begin{aligned}\text{Var}[\hat{\beta}_0] &= \sigma^2 \left(\frac{1}{n} + \frac{\bar{x}^2}{S_{xx}} \right) \\ \text{Var}[\hat{\beta}_1] &= \frac{\sigma^2}{S_{xx}}.\end{aligned}$$

These quantify the variability of the estimates due to random chance during sampling. Are these “the best”? Are these variances as small as we can possibly get? You’ll just have to take our word for it that they are because showing that this is true is beyond the scope of this course.

8.2 Sampling Distributions

Now that we have “redefined” the estimates for $\hat{\beta}_0$ and $\hat{\beta}_1$ as random variables, we can discuss their **sampling distribution**, which is the distribution when a statistic is considered a random variable.

Since both $\hat{\beta}_0$ and $\hat{\beta}_1$ are a linear combination of the Y_i and each Y_i is normally distributed, then both $\hat{\beta}_0$ and $\hat{\beta}_1$ also follow a normal distribution.

Then, putting all of the above together, we arrive at the distributions of $\hat{\beta}_0$ and $\hat{\beta}_1$.

For $\hat{\beta}_1$ we say,

$$\hat{\beta}_1 = \frac{S_{xy}}{S_{xx}} = \frac{\sum_{i=1}^n (x_i - \bar{x}) Y_i}{\sum_{i=1}^n (x_i - \bar{x})^2} \sim N \left(\beta_1, \frac{\sigma^2}{\sum_{i=1}^n (x_i - \bar{x})^2} \right).$$

Or more succinctly,

$$\hat{\beta}_1 \sim N \left(\beta_1, \frac{\sigma^2}{S_{xx}} \right).$$

And for $\hat{\beta}_0$,

$$\hat{\beta}_0 = \bar{Y} - \hat{\beta}_1 \bar{x} \sim N \left(\beta_0, \frac{\sigma^2 \sum_{i=1}^n x_i^2}{n \sum_{i=1}^n (x_i - \bar{x})^2} \right).$$

Or more succinctly,

$$\hat{\beta}_0 \sim N \left(\beta_0, \sigma^2 \left(\frac{1}{n} + \frac{\bar{x}^2}{S_{xx}} \right) \right)$$

At this point we have neglected to prove a number of these results. Instead of working through the tedious derivations of these sampling distributions, we will instead justify these results to ourselves using simulation.

A note to current readers: These derivations and proofs may be added to an appendix at a later time. You can also find these results in nearly any standard linear regression textbook. At UIUC, these results will likely be presented in both STAT 424 and STAT 425. However, since you will not be asked to perform derivations of this type in this course, they are for now omitted.

8.2.1 Simulating Sampling Distributions

To verify the above results, we will simulate samples of size $n = 100$ from the model

$$Y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$

where $\epsilon_i \sim N(0, \sigma^2)$. In this case, the parameters are known to be:

- $\beta_0 = 3$
- $\beta_1 = 6$
- $\sigma^2 = 4$

Then, based on the above, we should find that

$$\hat{\beta}_1 \sim N\left(\beta_1, \frac{\sigma^2}{S_{xx}}\right)$$

and

$$\hat{\beta}_0 \sim N\left(\beta_0, \sigma^2 \left(\frac{1}{n} + \frac{\bar{x}^2}{S_{xx}}\right)\right).$$

First we need to decide ahead of time what our x values will be for this simulation, since the x values in SLR are also considered known quantities. The choice of x values is arbitrary. Here we also set a seed for randomization, and calculate S_{xx} which we will need going forward.

```
set.seed(42)
sample_size = 100 # this is n
x = seq(-1, 1, length = sample_size)
Sxx = sum((x - mean(x)) ^ 2)
```

We also fix our parameter values.

```
beta_0 = 3
beta_1 = 6
sigma  = 2
```

With this information, we know the sampling distributions should be:

```
(var_beta_1_hat = sigma ^ 2 / Sxx)

## [1] 0.1176238

(var_beta_0_hat = sigma ^ 2 * (1 / sample_size + mean(x) ^ 2 / Sxx))

## [1] 0.04
```

$$\hat{\beta}_1 \sim N(6, 0.1176238)$$

and

$$\hat{\beta}_0 \sim N(3, 0.04).$$

That is,

$$\begin{aligned} E[\hat{\beta}_1] &= 6 \\ \text{Var}[\hat{\beta}_1] &= 0.1176238 \end{aligned}$$

and

$$\begin{aligned} E[\hat{\beta}_0] &= 3 \\ \text{Var}[\hat{\beta}_0] &= 0.04. \end{aligned}$$

We now simulate data from this model 10,000 times. Note this may not be the most R way of doing the simulation. We perform the simulation in this manner in an attempt at clarity. For example, we could have used the `sim_slr()` function from the previous chapter. We also simply store variables in the global environment instead of creating a data frame for each new simulated dataset.

```
num_samples = 10000
beta_0_hats = rep(0, num_samples)
beta_1_hats = rep(0, num_samples)

for(i in 1:num_samples) {
  eps = rnorm(sample_size, mean = 0, sd = sigma)
  y   = beta_0 + beta_1 * x + eps

  sim_model = lm(y ~ x)

  beta_0_hats[i] = coef(sim_model)[1]
  beta_1_hats[i] = coef(sim_model)[2]
}
```

Each time we simulated the data, we obtained values of the estimated coefficients. The variables `beta_0_hats` and `beta_1_hats` now store 10,000 simulated values of $\hat{\beta}_0$ and $\hat{\beta}_1$ respectively.

We first verify the distribution of $\hat{\beta}_1$.

```
mean(beta_1_hats) # empirical mean

## [1] 6.001998

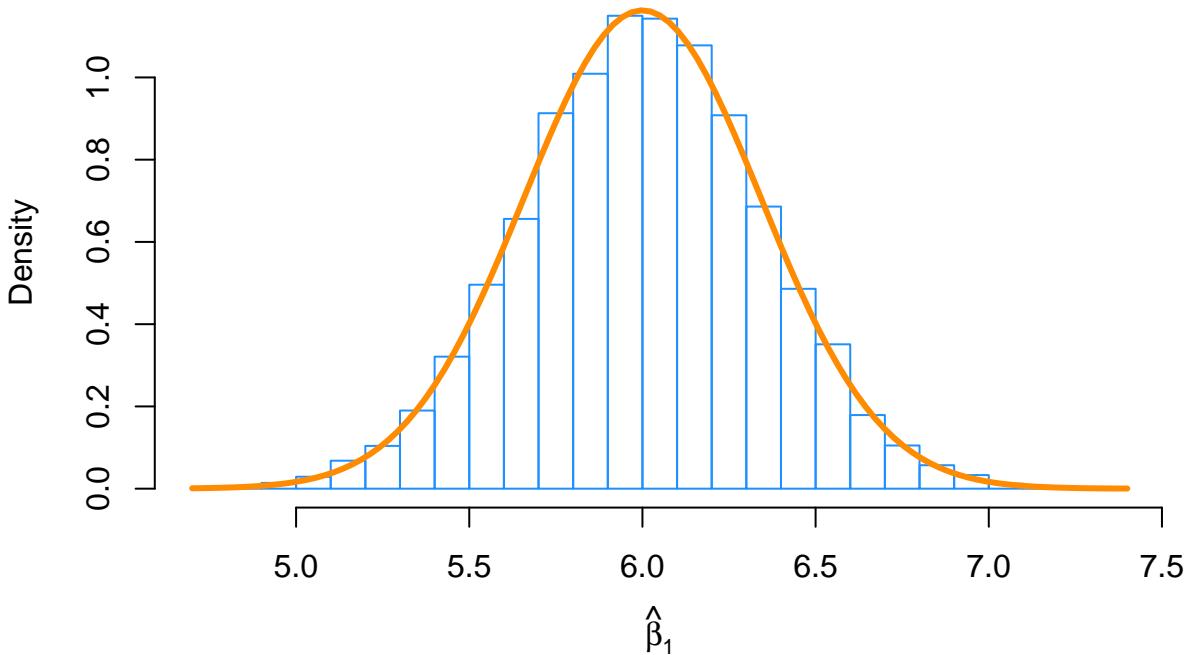
beta_1           # true mean

## [1] 6
```

```
var(beta_1_hats) # empirical variance
## [1] 0.11899
var_beta_1_hat # true variance
## [1] 0.1176238
```

We see that the empirical and true means and variances are *very* similar. We also verify that the empirical distribution is normal. To do so, we plot a histogram of the `beta_1_hats`, and add the curve for the true distribution of $\hat{\beta}_1$. We use `prob = TRUE` to put the histogram on the same scale as the normal curve.

```
# note need to use prob = TRUE
hist(beta_1_hats, prob = TRUE, breaks = 20,
      xlab = expression(hat(beta)[1]), main = "", border = "dodgerblue")
curve(dnorm(x, mean = beta_1, sd = sqrt(var_beta_1_hat)),
      col = "darkorange", add = TRUE, lwd = 3)
```



We then repeat the process for $\hat{\beta}_0$.

```
mean(beta_0_hats) # empirical mean
## [1] 3.001147
beta_0 # true mean
## [1] 3
```

```

var(beta_0_hats) # empirical variance

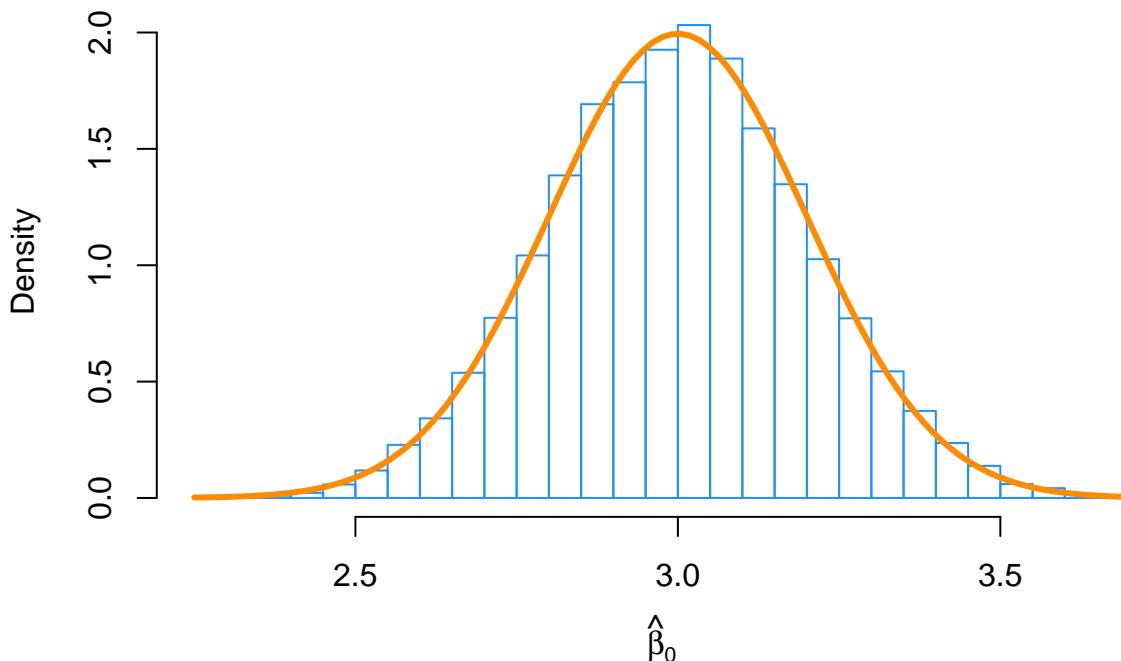
## [1] 0.04017924

var_beta_0_hat # true variance

## [1] 0.04

hist(beta_0_hats, prob = TRUE, breaks = 25,
      xlab = expression(hat(beta)[0]), main = "", border = "dodgerblue")
curve(dnorm(x, mean = beta_0, sd = sqrt(var_beta_0_hat)),
      col = "darkorange", add = TRUE, lwd = 3)

```

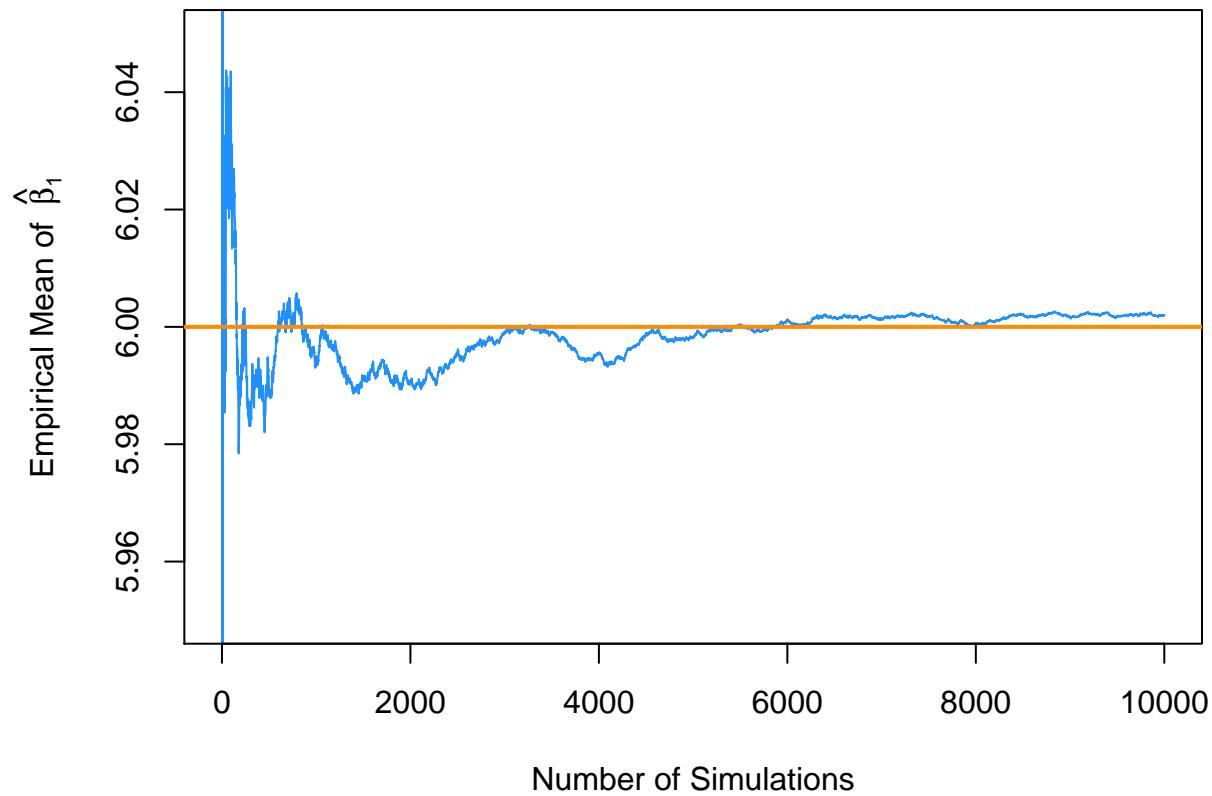


In this simulation study, we have only simulated a finite number of samples. To truly verify the distributional results, we would need to observe an infinite number of samples. However, the following plot should make it clear that if we continued simulating, the empirical results would get closer and closer to what we should expect.

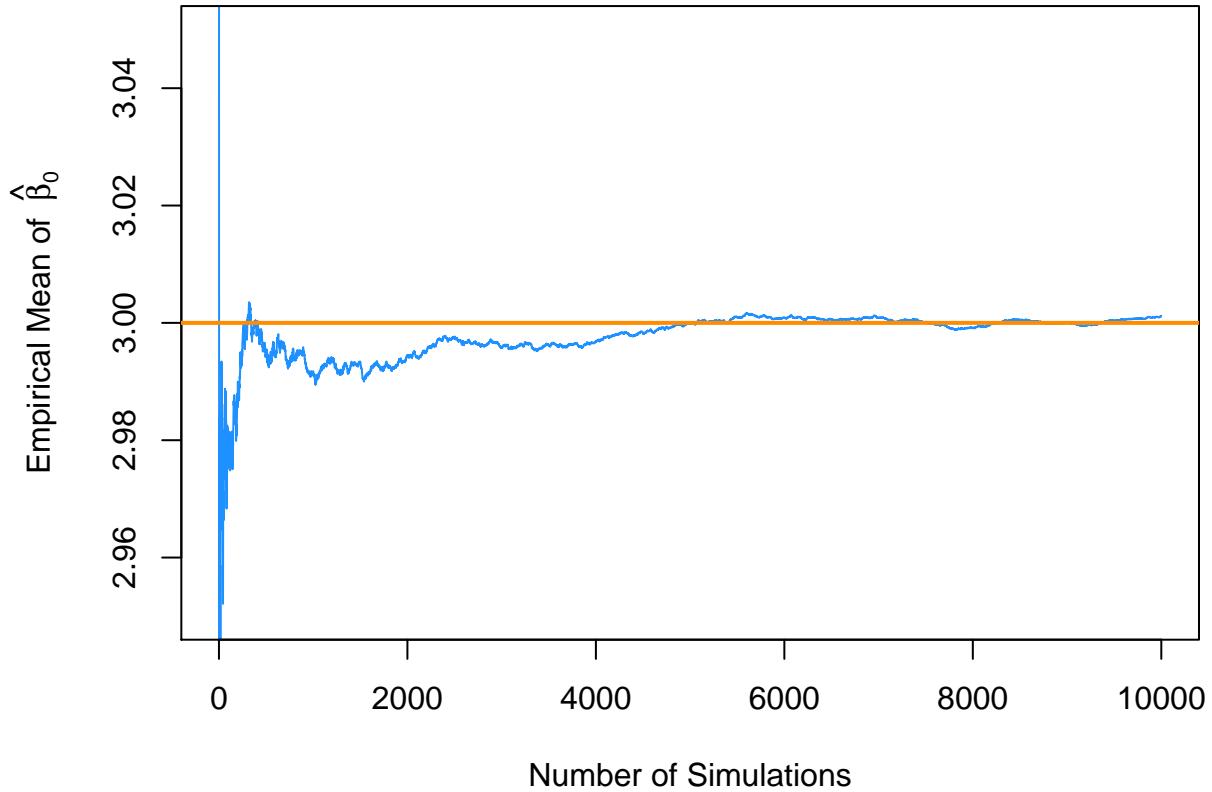
```

par(mar = c(5, 5, 1, 1)) # adjusted plot margins, otherwise the "hat" does not display
plot(cumsum(beta_1_hats) / (1:length(beta_1_hats)), type = "l", ylim = c(5.95, 6.05),
      xlab = "Number of Simulations",
      ylab = expression("Empirical Mean of " ~ hat(beta)[1]),
      col = "dodgerblue")
abline(h = 6, col = "darkorange", lwd = 2)

```



```
par(mar = c(5, 5, 1, 1)) # adjusted plot margins, otherwise the "hat" does not display
plot(cumsum(beta_0_hats) / (1:length(beta_0_hats)), type = "l", ylim = c(2.95, 3.05),
     xlab = "Number of Simulations",
     ylab = expression("Empirical Mean of " ~ hat(beta)[0]),
     col = "dodgerblue")
abline(h = 3, col = "darkorange", lwd = 2)
```



8.3 Standard Errors

So now we believe the two distributional results,

$$\begin{aligned}\hat{\beta}_0 &\sim N\left(\beta_0, \sigma^2 \left(\frac{1}{n} + \frac{\bar{x}^2}{S_{xx}}\right)\right) \\ \hat{\beta}_1 &\sim N\left(\beta_1, \frac{\sigma^2}{S_{xx}}\right).\end{aligned}$$

Then by standardizing these results we find that

$$\frac{\hat{\beta}_0 - \beta_0}{\text{SD}[\hat{\beta}_0]} \sim N(0, 1)$$

and

$$\frac{\hat{\beta}_1 - \beta_1}{\text{SD}[\hat{\beta}_1]} \sim N(0, 1)$$

where

$$\text{SD}[\hat{\beta}_0] = \sigma \sqrt{\frac{1}{n} + \frac{\bar{x}^2}{S_{xx}}}$$

and

$$\text{SD}[\hat{\beta}_1] = \frac{\sigma}{\sqrt{S_{xx}}}.$$

Since we don't know σ in practice, we will have to estimate it using s_e , which we plug into our existing expression for the standard deviations of our estimates.

These two new expressions are called **standard errors** which are the *estimated* standard deviations of the sampling distributions.

$$\text{SE}[\hat{\beta}_0] = s_e \sqrt{\frac{1}{n} + \frac{\bar{x}^2}{S_{xx}}}$$

$$\text{SE}[\hat{\beta}_1] = \frac{s_e}{\sqrt{S_{xx}}}$$

Now if we divide by the standard error, instead of the standard deviation, we obtain the following results which will allow us to make confidence intervals and perform hypothesis testing.

$$\frac{\hat{\beta}_0 - \beta_0}{\text{SE}[\hat{\beta}_0]} \sim t_{n-2}$$

$$\frac{\hat{\beta}_1 - \beta_1}{\text{SE}[\hat{\beta}_1]} \sim t_{n-2}$$

To see this, first note that,

$$\frac{\text{RSS}}{\sigma^2} = \frac{(n-2)s_e^2}{\sigma^2} \sim \chi_{n-2}^2.$$

Also recall that a random variable T defined as,

$$T = \frac{Z}{\sqrt{\frac{\chi_d^2}{d}}}$$

follows a t distribution with d degrees of freedom, where χ_d^2 is a χ^2 random variable with d degrees of freedom.

We write,

$$T \sim t_d$$

to say that the random variable T follows a t distribution with d degrees of freedom.

Then we use the classic trick of “multiply by 1” and some rearranging to arrive at

$$\begin{aligned}
\frac{\hat{\beta}_1 - \beta_1}{\text{SE}[\hat{\beta}_1]} &= \frac{\hat{\beta}_1 - \beta_1}{s_e / \sqrt{S_{xx}}} \\
&= \frac{\hat{\beta}_1 - \beta_1}{s_e / \sqrt{S_{xx}}} \cdot \frac{\sigma / \sqrt{S_{xx}}}{\sigma / \sqrt{S_{xx}}} \\
&= \frac{\hat{\beta}_1 - \beta_1}{\sigma / \sqrt{S_{xx}}} \cdot \frac{\sigma / \sqrt{S_{xx}}}{s_e / \sqrt{S_{xx}}} \\
&= \frac{\hat{\beta}_1 - \beta_1}{\sigma / \sqrt{S_{xx}}} \Big/ \sqrt{\frac{s_e^2}{\sigma^2}} \\
&= \frac{\hat{\beta}_1 - \beta_1}{\text{SD}[\hat{\beta}_1]} \Big/ \sqrt{\frac{\frac{(n-2)s_e^2}{\sigma^2}}{n-2}} \sim \frac{Z}{\sqrt{\frac{\chi_{n-2}^2}{n-2}}} \sim t_{n-2}
\end{aligned}$$

where $Z \sim N(0, 1)$.

Recall that a t distribution is similar to a standard normal, but with heavier tails. As the degrees of freedom increases, the t distribution becomes more and more like a standard normal. Below we plot a standard normal distribution as well as two examples of a t distribution with different degrees of freedom. Notice how the t distribution with the larger degrees of freedom is more similar to the standard normal curve.

```

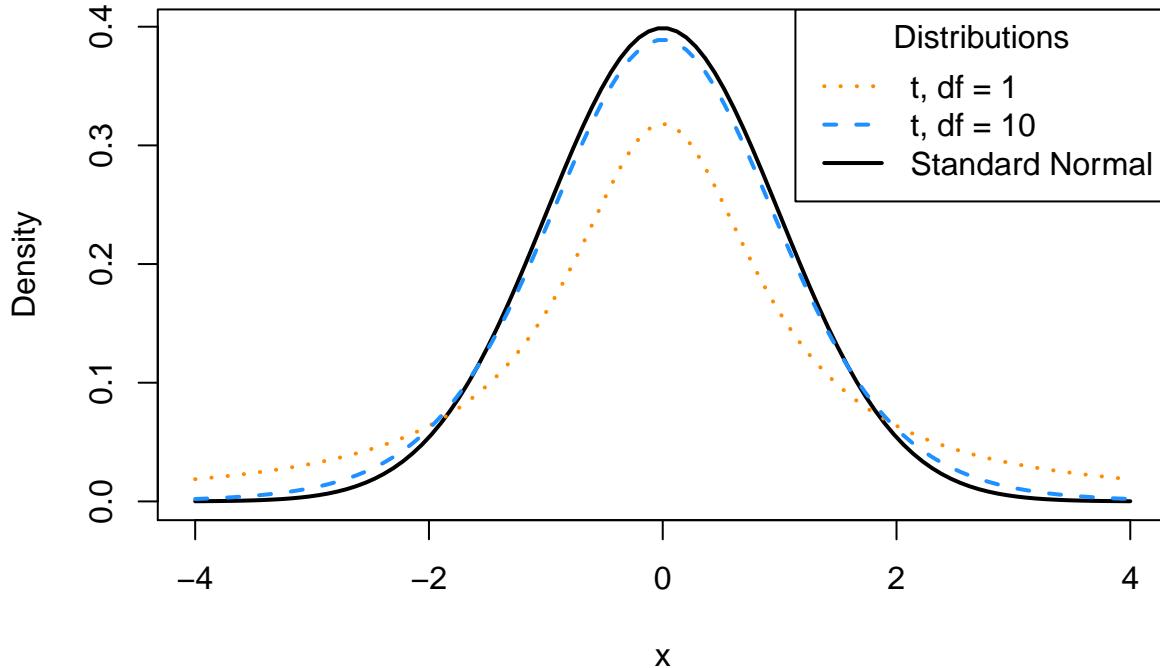
# define grid of x values
x = seq(-4, 4, length = 100)

# plot curve for standard normal
plot(x, dnorm(x), type = "l", lty = 1, lwd = 2,
      xlab = "x", ylab = "Density", main = "Normal vs t Distributions")
# add curves for t distributions
lines(x, dt(x, df = 1), lty = 3, lwd = 2, col = "darkorange")
lines(x, dt(x, df = 10), lty = 2, lwd = 2, col = "dodgerblue")

# add legend
legend("topright", title = "Distributions",
       legend = c("t, df = 1", "t, df = 10", "Standard Normal"),
       lwd = 2, lty=c(3, 2, 1), col = c("darkorange", "dodgerblue", "black"))

```

Normal vs t Distributions



8.4 Confidence Intervals for Slope and Intercept

Recall that confidence intervals for means often take the form:

$$\text{EST} \pm \text{CRIT} \cdot \text{SE}$$

or

$$\text{EST} \pm \text{MARGIN}$$

where EST is an estimate for the parameter of interest, SE is the standard error of the estimate, and MARGIN = CRIT · SE.

Then, for β_0 and β_1 we can create confidence intervals using

$$\hat{\beta}_0 \pm t_{\alpha/2, n-2} \cdot \text{SE}[\hat{\beta}_0] \quad \hat{\beta}_0 \pm t_{\alpha/2, n-2} \cdot s_e \sqrt{\frac{1}{n} + \frac{\bar{x}^2}{S_{xx}}}$$

and

$$\hat{\beta}_1 \pm t_{\alpha/2, n-2} \cdot \text{SE}[\hat{\beta}_1] \quad \hat{\beta}_1 \pm t_{\alpha/2, n-2} \cdot \frac{s_e}{\sqrt{S_{xx}}}$$

where $t_{\alpha/2, n-2}$ is the critical value such that $P(t_{n-2} > t_{\alpha/2, n-2}) = \alpha/2$.

8.5 Hypothesis Tests

“We may speak of this hypothesis as the ‘null hypothesis’, and it should be noted that the null hypothesis is never proved or established, but is possibly disproved, in the course of experimentation.”

— Ronald Aylmer Fisher

Recall that a test statistic (TS) for testing means often take the form:

$$\text{TS} = \frac{\text{EST} - \text{HYP}}{\text{SE}}$$

where EST is an estimate for the parameter of interest, HYP is a hypothesized value of the parameter, and SE is the standard error of the estimate.

So, to test

$$H_0 : \beta_0 = \beta_{00} \quad \text{vs} \quad H_1 : \beta_0 \neq \beta_{00}$$

we use the test statistic

$$t = \frac{\hat{\beta}_0 - \beta_{00}}{\text{SE}[\hat{\beta}_0]} = \frac{\hat{\beta}_0 - \beta_{00}}{s_e \sqrt{\frac{1}{n} + \frac{\bar{x}^2}{S_{xx}}}}$$

which, under the null hypothesis, follows a t distribution with $n - 2$ degrees of freedom. We use β_{00} to denote the hypothesized value of β_0 .

Similarly, to test

$$H_0 : \beta_1 = \beta_{10} \quad \text{vs} \quad H_1 : \beta_1 \neq \beta_{10}$$

we use the test statistic

$$t = \frac{\hat{\beta}_1 - \beta_{10}}{\text{SE}[\hat{\beta}_1]} = \frac{\hat{\beta}_1 - \beta_{10}}{s_e / \sqrt{S_{xx}}}$$

which again, under the null hypothesis, follows a t distribution with $n - 2$ degrees of freedom. We now use β_{10} to denote the hypothesized value of β_1 .

8.6 cars Example

We now return to the `cars` example from last chapter to illustrate these concepts. We first fit the model using `lm()` then use `summary()` to view the results in greater detail.

```
stop_dist_model = lm(dist ~ speed, data = cars)
summary(stop_dist_model)
```

```

## 
## Call:
## lm(formula = dist ~ speed, data = cars)
## 
## Residuals:
##      Min       1Q   Median       3Q      Max 
## -29.069  -9.525  -2.272   9.215  43.201 
## 
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)    
## (Intercept) -17.5791    6.7584  -2.601   0.0123 *  
## speed        3.9324    0.4155   9.464 1.49e-12 *** 
## --- 
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1 
## 
## Residual standard error: 15.38 on 48 degrees of freedom 
## Multiple R-squared:  0.6511, Adjusted R-squared:  0.6438 
## F-statistic: 89.57 on 1 and 48 DF,  p-value: 1.49e-12

```

8.6.1 Tests in R

We will now discuss the results displayed called **Coefficients**. First recall that we can extract this information directly.

```
names(summary(stop_dist_model))
```

```

## [1] "call"          "terms"         "residuals"      "coefficients" 
## [5] "aliased"       "sigma"         "df"            "r.squared"    
## [9] "adj.r.squared" "fstatistic"    "cov.unscaled"

```

```
summary(stop_dist_model)$coefficients
```

```

##             Estimate Std. Error   t value   Pr(>|t|)    
## (Intercept) -17.579095  6.7584402 -2.601058 1.231882e-02
## speed        3.932409   0.4155128  9.463990 1.489836e-12

```

The `names()` function tells us what information is available, and then we use the `$` operator and `coefficients` to extract the information we are interested in. Two values here should be immediately familiar.

$$\hat{\beta}_0 = -17.5790949$$

and

$$\hat{\beta}_1 = 3.9324088$$

which are our estimates for the model parameters β_0 and β_1 .

Let's now focus on the second row of output, which is relevant to β_1 .

```
summary(stop_dist_model)$coefficients[2,]

##      Estimate Std. Error     t value   Pr(>|t|)
## 3.932409e+00 4.155128e-01 9.463990e+00 1.489836e-12
```

Again, the first value, `Estimate` is

$$\hat{\beta}_1 = 3.9324088.$$

The second value, `Std. Error`, is the standard error of $\hat{\beta}_1$,

$$\text{SE}[\hat{\beta}_1] = \frac{s_e}{\sqrt{S_{xx}}} = 0.4155128.$$

The third value, `t value`, is the value of the test statistic for testing $H_0 : \beta_1 = 0$ vs $H_1 : \beta_1 \neq 0$,

$$t = \frac{\hat{\beta}_1 - 0}{\text{SE}[\hat{\beta}_1]} = \frac{\hat{\beta}_1 - 0}{s_e / \sqrt{S_{xx}}} = 9.46399.$$

Lastly, `Pr(>|t|)`, gives us the p-value of that test.

$$\text{p-value} = 1.4898365 \times 10^{-12}$$

Note here, we are specifically testing whether or not $\beta_1 = 0$.

The first row of output reports the same values, but for β_0 .

```
summary(stop_dist_model)$coefficients[1,]

##      Estimate Std. Error     t value   Pr(>|t|)
## -17.57909489  6.75844017 -2.60105800  0.01231882
```

In summary, the following code stores the information of `summary(stop_dist_model)$coefficients` in a new variable `stop_dist_model_test_info`, then extracts each element into a new variable which describes the information it contains.

```
stop_dist_model_test_info = summary(stop_dist_model)$coefficients

beta_0_hat      = stop_dist_model_test_info[1, 1] # Estimate
beta_0_hat_se   = stop_dist_model_test_info[1, 2] # Std. Error
beta_0_hat_t    = stop_dist_model_test_info[1, 3] # t value
beta_0_hat_pval = stop_dist_model_test_info[1, 4] # Pr(>/t/)

beta_1_hat      = stop_dist_model_test_info[2, 1] # Estimate
beta_1_hat_se   = stop_dist_model_test_info[2, 2] # Std. Error
beta_1_hat_t    = stop_dist_model_test_info[2, 3] # t value
beta_1_hat_pval = stop_dist_model_test_info[2, 4] # Pr(>/t/)
```

We can then verify some equivalent expressions: the t test statistic for $\hat{\beta}_1$ and the two-sided p-value associated with that test statistic.

```
(beta_1_hat - 0) / beta_1_hat_se

## [1] 9.46399

beta_1_hat_t

## [1] 9.46399

2 * pt(abs(beta_1_hat_t), df = length(resid(stop_dist_model)) - 2, lower.tail = FALSE)

## [1] 1.489836e-12

beta_1_hat_pval

## [1] 1.489836e-12
```

8.6.2 Significance of Regression, t-Test

We pause to discuss the **significance of regression** test. First, note that based on the above distributional results, we could test β_0 and β_1 against any particular value, and perform both one and two-sided tests.

However, one very specific test,

$$H_0 : \beta_1 = 0 \quad \text{vs} \quad H_1 : \beta_1 \neq 0$$

is used most often. Let's think about this test in terms of the simple linear regression model,

$$Y_i = \beta_0 + \beta_1 x_i + \epsilon_i.$$

If we assume the null hypothesis is true, then $\beta_1 = 0$ and we have the model,

$$Y_i = \beta_0 + \epsilon_i.$$

In this model, the response does **not** depend on the predictor. So then we could think of this test in the following way,

- Under H_0 there is not a significant linear relationship between x and y .
- Under H_1 there is a significant **linear** relationship between x and y .

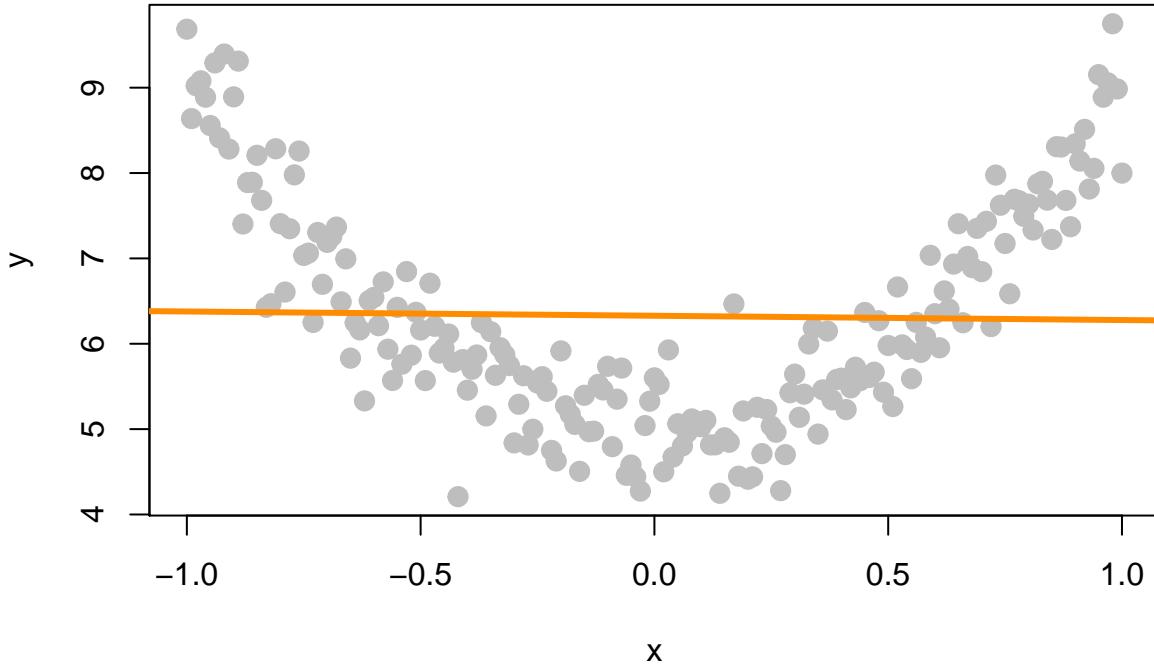
For the `cars` example,

- Under H_0 there is not a significant linear relationship between speed and stopping distance.
- Under H_1 there is a significant **linear** relationship between speed and stopping distance.

Again, that test is seen in the output from `summary()`,

$$\text{p-value} = 1.4898365 \times 10^{-12}.$$

With this extremely low p-value, we would reject the null hypothesis at any reasonable α level, say for example $\alpha = 0.01$. So we say there is a significant **linear** relationship between speed and stopping distance. Notice that we emphasize **linear**.



In this plot of simulated data, we see a clear relationship between x and y , however it is not a linear relationship. If we fit a line to this data, it is very flat. The resulting test for $H_0 : \beta_1 = 0$ vs $H_1 : \beta_1 \neq 0$ gives a large p-value, in this case 0.7564548, so we would fail to reject and say that there is no significant linear relationship between x and y . We will see later how to fit a curve to this data using a “linear” model, but for now, realize that testing $H_0 : \beta_1 = 0$ vs $H_1 : \beta_1 \neq 0$ can only detect straight line relationships.

8.6.3 Confidence Intervals in R

Using R we can very easily obtain the confidence intervals for β_0 and β_1 .

```
confint(stop_dist_model, level = 0.99)
```

```
##              0.5 %    99.5 %
## (Intercept) -35.706610  0.5484205
## speed        2.817919  5.0468988
```

This automatically calculates 99% confidence intervals for both β_0 and β_1 , the first row for β_0 , the second row for β_1 .

For the `cars` example when interpreting these intervals, we say, we are 99% confident that for an increase in speed of 1 mile per hour, the average increase in stopping distance is between 2.8179187 and 5.0468988 feet, which is the interval for β_1 .

Note that this 99% confidence interval does **not** contain the hypothesized value of 0. Since it does not contain 0, it is equivalent to rejecting the test of $H_0 : \beta_1 = 0$ vs $H_1 : \beta_1 \neq 0$ at $\alpha = 0.01$, which we had seen previously.

You should be somewhat suspicious of the confidence interval for β_0 , as it covers negative values, which correspond to negative stopping distances. Technically the interpretation would be that we are 99% confident that the average stopping distance of a car traveling 0 miles per hour is between -35.7066103 and 0.5484205 feet, but we don't really believe that, since we are actually certain that it would be non-negative.

Note, we can extract specific values from this output a number of ways. This code is not run, and instead, you should check how it relates to the output of the code above.

```
confint(stop_dist_model, level = 0.99)[1,]
confint(stop_dist_model, level = 0.99)[1, 1]
confint(stop_dist_model, level = 0.99)[1, 2]
confint(stop_dist_model, parm = "(Intercept)", level = 0.99)
confint(stop_dist_model, level = 0.99)[2,]
confint(stop_dist_model, level = 0.99)[2, 1]
confint(stop_dist_model, level = 0.99)[2, 2]
confint(stop_dist_model, parm = "speed", level = 0.99)
```

We can also verify that calculations that R is performing for the β_1 interval.

```
# store estimate
beta_1_hat = coef(stop_dist_model)[2]

# store standard error
beta_1_hat_se = summary(stop_dist_model)$coefficients[2, 2]

# calculate critical value for two-sided 99% CI
crit = qt(0.995, df = length(resid(stop_dist_model)) - 2)

# est - margin, est + margin
c(beta_1_hat - crit * beta_1_hat_se, beta_1_hat + crit * beta_1_hat_se)

##      speed      speed
## 2.817919 5.046899
```

8.7 Confidence Interval for Mean Response

In addition to confidence intervals for β_0 and β_1 , there are two other common interval estimates used with regression. The first is called a **confidence interval for the mean response**. Often, we would like an interval estimate for the mean, $E[Y | X = x]$ for a particular value of x .

In this situation we use $\hat{y}(x)$ as our estimate of $E[Y | X = x]$. We modify our notation slightly to make it clear that the predicted value is a function of the x value.

$$\hat{y}(x) = \hat{\beta}_0 + \hat{\beta}_1 x$$

Recall that,

$$E[Y | X = x] = \beta_0 + \beta_1 x.$$

Thus, $\hat{y}(x)$ is a good estimate since it is unbiased:

$$\mathbb{E}[\hat{y}(x)] = \beta_0 + \beta_1 x.$$

We could then derive,

$$\text{Var}[\hat{y}(x)] = \sigma^2 \left(\frac{1}{n} + \frac{(x - \bar{x})^2}{S_{xx}} \right).$$

Like the other estimates we have seen, $\hat{y}(x)$ also follows a normal distribution. Since $\hat{\beta}_0$ and $\hat{\beta}_1$ are linear combinations of normal random variables, $\hat{y}(x)$ is as well.

$$\hat{y}(x) \sim N \left(\beta_0 + \beta_1 x, \sigma^2 \left(\frac{1}{n} + \frac{(x - \bar{x})^2}{S_{xx}} \right) \right)$$

And lastly, since we need to estimate this variance, we arrive at the standard error of our estimate,

$$\text{SE}[\hat{y}(x)] = s_e \sqrt{\frac{1}{n} + \frac{(x - \bar{x})^2}{S_{xx}}}.$$

We can then use this to find the confidence interval for the mean response,

$$\hat{y}(x) \pm t_{\alpha/2, n-2} \cdot s_e \sqrt{\frac{1}{n} + \frac{(x - \bar{x})^2}{S_{xx}}}$$

To find confidence intervals for the mean response using R, we use the `predict()` function. We give the function our fitted model as well as new data, stored as a data frame. (This is important, so that R knows the name of the predictor variable.) Here, we are finding the confidence interval for the mean stopping distance when a car is travelling 5 miles per hour and when a car is travelling 21 miles per hour.

```
new_speeds = data.frame(speed = c(5, 21))
predict(stop_dist_model, newdata = new_speeds,
        interval = c("confidence"), level = 0.99)

##           fit      lwr      upr
## 1  2.082949 -10.89309 15.05898
## 2 65.001489  56.45836 73.54462
```

8.8 Prediction Interval for New Observations

Sometimes we would like an interval estimate for a new observation, Y , for a particular value of x . This is very similar to an interval for the mean response, $\mathbb{E}[Y | X = x]$, but different in one very important way.

Our best guess for a new observation is still $\hat{y}(x)$. The estimated mean is still the best prediction we can make. The difference is in the amount of variability. We know that observations will vary about the true regression line according to a $N(0, \sigma^2)$ distribution. Because of this we add an extra factor of σ^2 to our estimate's variability in order to account for the variability of observations about the regression line.

$$\begin{aligned}
 \text{Var}[\hat{y}(x) + \epsilon] &= \text{Var}[\hat{y}(x)] + \text{Var}[\epsilon] \\
 &= \sigma^2 \left(\frac{1}{n} + \frac{(x - \bar{x})^2}{S_{xx}} \right) + \sigma^2 \\
 &= \sigma^2 \left(1 + \frac{1}{n} + \frac{(x - \bar{x})^2}{S_{xx}} \right) \\
 \hat{y}(x) + \epsilon &\sim N \left(\beta_0 + \beta_1 x, \sigma^2 \left(1 + \frac{1}{n} + \frac{(x - \bar{x})^2}{S_{xx}} \right) \right) \\
 \text{SE}[\hat{y}(x) + \epsilon] &= s_e \sqrt{1 + \frac{1}{n} + \frac{(x - \bar{x})^2}{S_{xx}}}
 \end{aligned}$$

We can then find a **prediction interval** using,

$$\hat{y}(x) \pm t_{\alpha/2, n-2} \cdot s_e \sqrt{1 + \frac{1}{n} + \frac{(x - \bar{x})^2}{S_{xx}}}.$$

To calculate this for a set of points in R notice there is only a minor change in syntax from finding a confidence interval for the mean response.

```

predict(stop_dist_model, newdata = new_speeds,
        interval = c("prediction"), level = 0.99)

##          fit      lwr      upr
## 1  2.082949 -41.16099 45.32689
## 2 65.001489  22.87494 107.12803

```

Also notice that these two intervals are wider than the corresponding confidence intervals for the mean response.

8.9 Confidence and Prediction Bands

Often we will like to plot both confidence intervals for the mean response and prediction intervals for all possible values of x . We calls these confidence and prediction bands.

```

speed_grid = seq(min(cars$speed), max(cars$speed), by = 0.01)
dist_ci_band = predict(stop_dist_model,
                      newdata = data.frame(speed = speed_grid),
                      interval = "confidence", level = 0.99)
dist_pi_band = predict(stop_dist_model,
                      newdata = data.frame(speed = speed_grid),
                      interval = "prediction", level = 0.99)

plot(dist ~ speed, data = cars,
     xlab = "Speed (in Miles Per Hour)",
     ylab = "Stopping Distance (in Feet)",
     main = "Stopping Distance vs Speed",

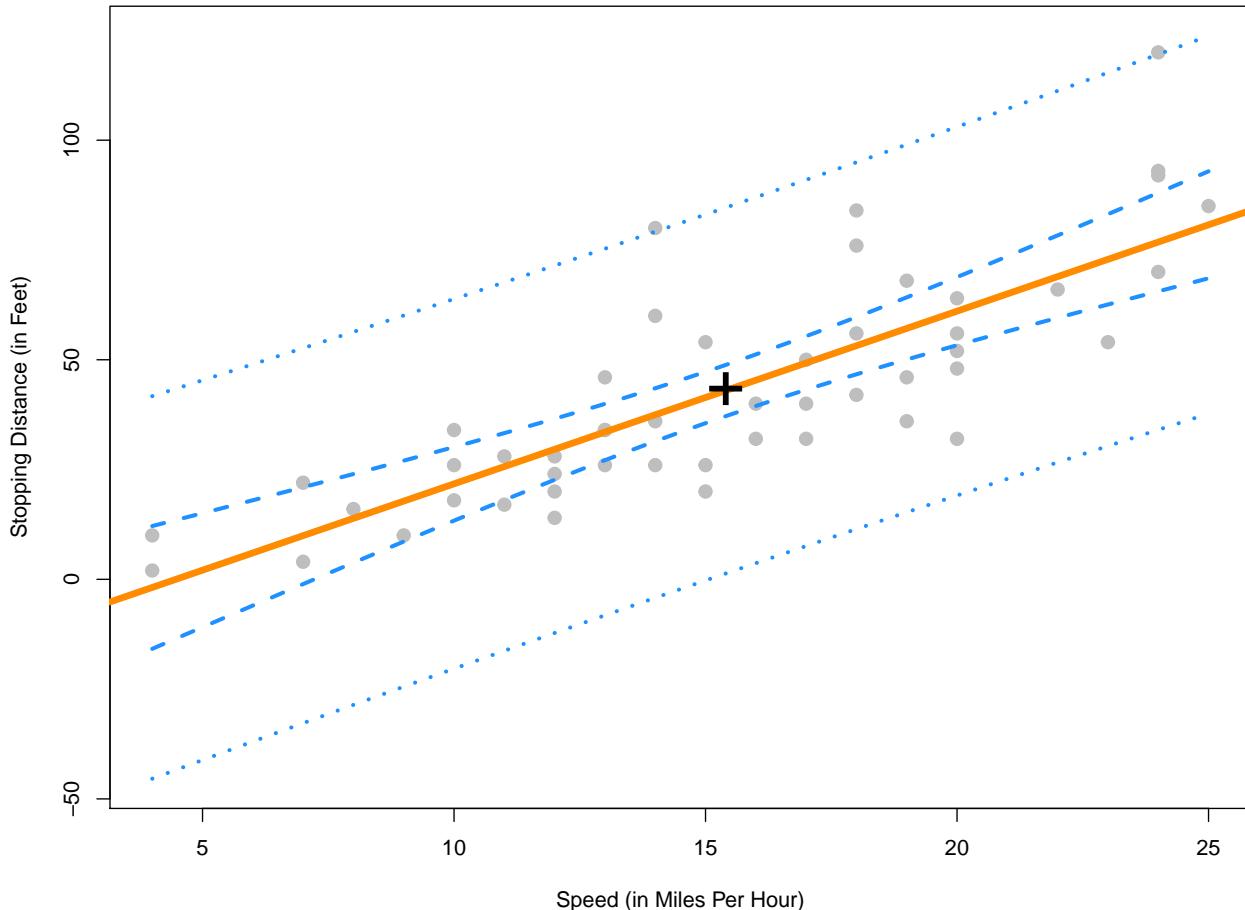
```

```

pch  = 20,
cex  = 2,
col  = "grey",
ylim = c(min(dist_pi_band), max(dist_pi_band)))
abline(stop_dist_model, lwd = 5, col = "darkorange")

lines(speed_grid, dist_ci_band[,"lwr"], col = "dodgerblue", lwd = 3, lty = 2)
lines(speed_grid, dist_ci_band[,"upr"], col = "dodgerblue", lwd = 3, lty = 2)
lines(speed_grid, dist_pi_band[,"lwr"], col = "dodgerblue", lwd = 3, lty = 3)
lines(speed_grid, dist_pi_band[,"upr"], col = "dodgerblue", lwd = 3, lty = 3)
points(mean(cars$speed), mean(cars$dist), pch = "+", cex = 3)

```

Stopping Distance vs Speed

Some things to notice:

- We use the `ylim` argument to stretch the y -axis of the plot, since the bands extend further than the points.
- We add a point at the point (\bar{x}, \bar{y}) .
 - This is a point that the regression line will **always** pass through. (Think about why.)
 - This is the point where both the confidence and prediction bands are the narrowest. Look at the standard errors of both to understand why.
- The prediction bands (dotted blue) are less curved than the confidence bands (dashed blue). This is a result of the extra factor of σ^2 added to the variance at any value of x .

8.10 Significance of Regression, F-Test

In the case of simple linear regression, the t test for the significance of the regression is equivalent to another test, the F test for the significance of the regression. This equivalence will only be true for simple linear regression, and in the next chapter we will only use the F test for the significance of the regression.

Recall from last chapter the decomposition of variance we saw before calculating R^2 ,

$$\sum_{i=1}^n (y_i - \bar{y})^2 = \sum_{i=1}^n (y_i - \hat{y}_i)^2 + \sum_{i=1}^n (\hat{y}_i - \bar{y})^2,$$

or, in short,

$$\text{SST} = \text{SSReg} + \text{SSE}.$$

To develop the F test, we will arrange this information in an **ANOVA** table,

Source	Sum of Squares	Degrees of Freedom	Mean Square	F
Regression	$\sum_{i=1}^n (\hat{y}_i - \bar{y})^2$	1	$\text{SSReg}/1$	MSReg/MSE
Error	$\sum_{i=1}^n (y_i - \hat{y}_i)^2$	$n - 2$	$\text{SSE}/(n - 2)$	
Total	$\sum_{i=1}^n (y_i - \bar{y})^2$	$n - 1$		

ANOVA, or Analysis of Variance will be a concept we return to often in this course. For now, we will focus on the results of the table, which is the F statistic,

$$F = \frac{\sum_{i=1}^n (\hat{y}_i - \bar{y})^2 / 1}{\sum_{i=1}^n (y_i - \hat{y}_i)^2 / (n - 2)} \sim F_{1, n-2}$$

which follows an F distribution with degrees of freedom 1 and $n - 2$ under the null hypothesis. An F distribution is a continuous distribution which takes only positive values and has two parameters, which are the two degrees of freedom.

Recall, in the significance of the regression test, Y does **not** depend on x in the null hypothesis.

$$H_0 : \beta_1 = 0 \quad Y_i = \beta_0 + \epsilon_i$$

While in the alternative hypothesis Y may depend on x .

$$H_1 : \beta_1 \neq 0 \quad Y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$

We can use the F statistic to perform this test.

$$F = \frac{\sum_{i=1}^n (\hat{y}_i - \bar{y})^2 / 1}{\sum_{i=1}^n (y_i - \hat{y}_i)^2 / (n - 2)}$$

In particular, we will reject the null when the F statistic is large, that is, when there is a low probability that the observations could have come from the null model by chance. We will let R calculate the p-value for us.

To perform the F test in R you can look at the last row of the output from `summary()` called **F-statistic** which gives the value of the test statistic, the relevant degrees of freedom, as well as the p-value of the test.

```
summary(stop_dist_model)

##
## Call:
## lm(formula = dist ~ speed, data = cars)
##
## Residuals:
##    Min      1Q  Median      3Q     Max 
## -29.069 -9.525 -2.272  9.215 43.201 
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)    
## (Intercept) -17.5791   6.7584  -2.601  0.0123 *  
## speed        3.9324   0.4155   9.464 1.49e-12 *** 
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1 
##
## Residual standard error: 15.38 on 48 degrees of freedom
## Multiple R-squared:  0.6511, Adjusted R-squared:  0.6438 
## F-statistic: 89.57 on 1 and 48 DF,  p-value: 1.49e-12
```

Additionally, you can use the `anova()` function to display the information in an ANOVA table.

```
anova(stop_dist_model)

## Analysis of Variance Table
##
## Response: dist
##           Df Sum Sq Mean Sq F value    Pr(>F)    
## speed       1  21186 21185.5 89.567 1.49e-12 ***
## Residuals  48  11354   236.5
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

This also gives a p-value for the test. You should notice that the p-value from the t test was the same. You might also notice that the value of the test statistic for the t test, 9.46399, can be squared to obtain the value of the F statistic, 89.5671065.

Note that there is another equivalent way to do this in R, which we will return to often to compare two models.

```
anova(lm(dist ~ 1, data = cars), lm(dist ~ speed, data = cars))
```

```
## Analysis of Variance Table
##
## Model 1: dist ~ 1
## Model 2: dist ~ speed
##   Res.Df   RSS Df Sum of Sq    F    Pr(>F)    
## 1     49 32539
## 2     48 11354  1      21186 89.567 1.49e-12 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

The model statement `lm(dist ~ 1, data = cars)` applies the model $Y_i = \beta_0 + \epsilon_i$ to the cars data. Note that $\hat{y} = \bar{y}$ when $Y_i = \beta_0 + \epsilon_i$.

The model statement `lm(dist ~ speed, data = cars)` applies the model $Y_i = \beta_0 + \beta_1 x_i + \epsilon_i$.

We can then think of this usage of `anova()` as directly comparing the two models. (Notice we get the same p-value again.)

Chapter 9

Multiple Linear Regression

“Life is really simple, but we insist on making it complicated.”

— Confucius

After reading this chapter you will be able to:

- Construct and interpret linear regression models with more than one predictor.
- Understand how regression models are derived using matrices.
- Create interval estimates and perform hypothesis tests for multiple regression parameters.
- Formulate and interpret interval estimates for the mean response under various conditions.
- Compare nested models using an ANOVA F-Test.

The last two chapters we saw how to fit a model that assumed a linear relationship between a response variable and a single predictor variable. Specifically, we defined the simple linear regression model,

$$Y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$

where $\epsilon_i \sim N(0, \sigma^2)$.

However, it is rarely the case that a dataset will have a single predictor variable. It is also rarely the case that a response variable will only depend on a single variable. So in this chapter, we will extend our current linear model to allow a response to depend on *multiple* predictors.

```
# read the data from the web
autompq = read.table(
  "http://archive.ics.uci.edu/ml/machine-learning-databases/auto-mpg/auto-mpg.data",
  quote = "\",
  comment.char = """",
  stringsAsFactors = FALSE)
# give the dataframe headers
colnames(autompq) = c("mpg", "cyl", "disp", "hp", "wt", "acc", "year", "origin", "name")
# remove missing data, which is stored as "?"
autompq = subset(autompq, autompq$hp != "?")
# remove the plymouth reliant, as it causes some issues
autompq = subset(autompq, autompq$name != "plymouth reliant")
# give the dataset row names, based on the engine, year and name
rownames(autompq) = paste(autompq$cyl, "cylinder", autompq$year, autompq$name)
```

```
# remove the variable for name, as well as origin
autompg = subset(autompg, select = c("mpg", "cyl", "disp", "hp", "wt", "acc", "year"))
# change horsepower from character to numeric
autompg$hp = as.numeric(autompg$hp)
# check final structure of data
str(autompg)
```

```
## 'data.frame': 390 obs. of 7 variables:
## $ mpg : num 18 15 18 16 17 15 14 14 14 15 ...
## $ cyl : int 8 8 8 8 8 8 8 8 ...
## $ disp: num 307 350 318 304 302 429 454 440 455 390 ...
## $ hp : num 130 165 150 150 140 198 220 215 225 190 ...
## $ wt : num 3504 3693 3436 3433 3449 ...
## $ acc : num 12 11.5 11 12 10.5 10 9 8.5 10 8.5 ...
## $ year: int 70 70 70 70 70 70 70 70 70 70 ...
```

We will once again discuss a dataset with information about cars. This dataset, which can be found at the UCI Machine Learning Repository contains a response variable `mpg` which stores the city fuel efficiency of cars, as well as several predictor variables for the attributes of the vehicles. We load the data, and perform some basic tidying before moving on to analysis.

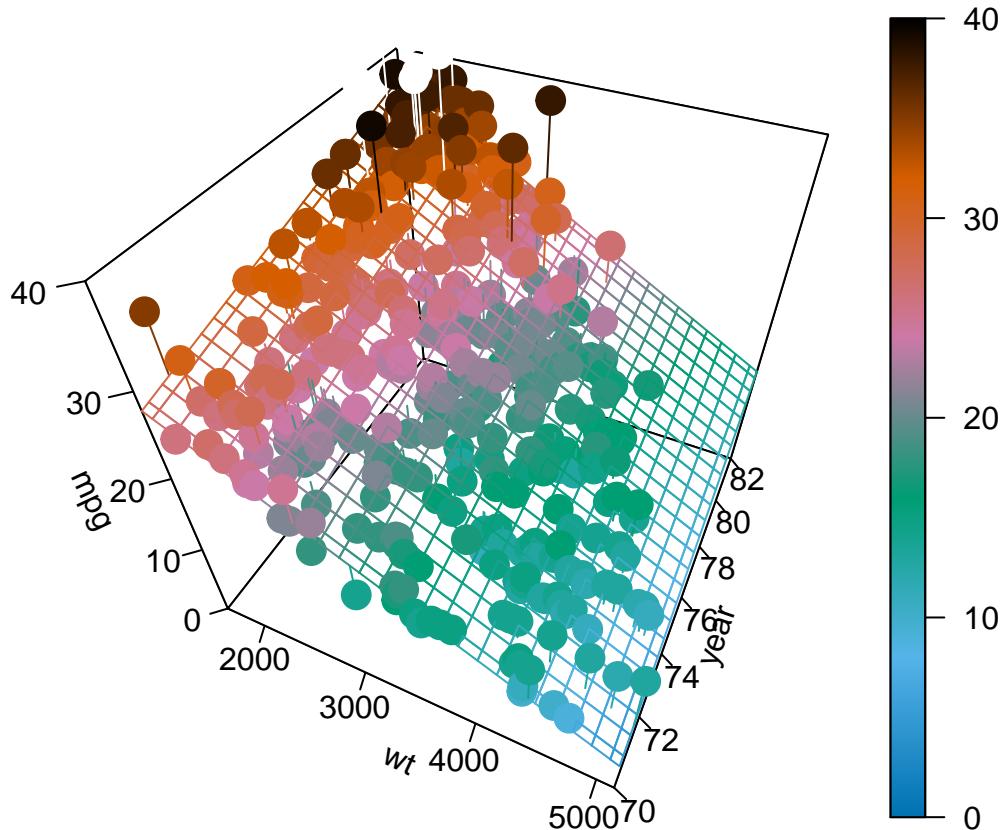
For now we will focus on using two variables, `wt` and `year`, as predictor variables. That is, we would like to model the fuel efficiency (`mpg`) of a car as a function of its weight (`wt`) and model year (`year`). To do so, we will define the following linear model,

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \epsilon_i, \quad i = 1, 2, \dots, n$$

where $\epsilon_i \sim N(0, \sigma^2)$. In this notation we will define:

- x_{i1} as the weight (`wt`) of the i th car.
- x_{i2} as the model year (`year`) of the i th car.

The picture below will visualize what we would like to accomplish. The data points (x_{i1}, x_{i2}, y_i) now exist in 3-dimensional space, so instead of fitting a line to the data, we will fit a plane. (We'll soon move to higher dimensions, so this will be the last example that is easy to visualize and think about this way.)



How do we find such a plane? Well, we would like a plane that is as close as possible to the data points. That is, we would like it to minimize the errors it is making. How will we define these errors? Squared distance of course! So, we would like to minimize

$$f(\beta_0, \beta_1, \beta_2) = \sum_{i=1}^n (y_i - (\beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2}))^2$$

with respect to β_0 , β_1 , and β_2 . How do we do so? It is another straightforward multivariate calculus problem. All we have done is add an extra variable since we did this last time. So again, we take a derivative with respect to each of β_0 , β_1 , and β_2 and set them equal to zero, then solve the resulting system of equations. That is,

$$\begin{aligned}\frac{\partial f}{\partial \beta_0} &= 0 \\ \frac{\partial f}{\partial \beta_1} &= 0 \\ \frac{\partial f}{\partial \beta_2} &= 0\end{aligned}$$

After doing so, we will once again obtain the **normal equations**.

$$\begin{aligned} n\beta_0 + \beta_1 \sum_{i=1}^n x_{i1} + \beta_2 \sum_{i=1}^n x_{i2} &= \sum_{i=1}^n y_i \\ \beta_0 \sum_{i=1}^n x_{i1} + \beta_1 \sum_{i=1}^n x_{i1}^2 + \beta_2 \sum_{i=1}^n x_{i1}x_{i2} &= \sum_{i=1}^n x_{i1}y_i \\ \beta_0 \sum_{i=1}^n x_{i2} + \beta_1 \sum_{i=1}^n x_{i1}x_{i2} + \beta_2 \sum_{i=1}^n x_{i2}^2 &= \sum_{i=1}^n x_{i2}y_i \end{aligned}$$

We now have three equations and three variables, which we could solve, or we could simply let R solve for us.

```
mpg_model = lm(mpg ~ wt + year, data = autompg)
coef(mpg_model)
```

```
##   (Intercept)          wt          year
## -14.637641945 -0.006634876  0.761401955
```

$$\hat{y} = -14.6376419 + -0.0066349x_1 + 0.761402x_2$$

Here we have once again fit our model using `lm()`, however we have introduced a new syntactical element. The formula `mpg ~ wt + year` now reads: “model the response variable `mpg` as a linear function of `wt` and `year`”. That is, it will estimate an intercept, as well as slope coefficients for `wt` and `year`. We then extract these as we have done before using `coef()`.

In the multiple linear regression setting, some of the interpretations of the coefficients change slightly.

Here, $\hat{\beta}_0 = -14.6376419$ is our estimate for β_0 , the mean miles per gallon for a car that weighs 0 pounds and was built in 1900. We see our estimate here is negative, which is a physical impossibility. However, this isn’t unexpected, as we shouldn’t expect our model to be accurate for cars from 1900 which weigh 0 pounds. (Because they never existed!) This isn’t much of a change from SLR. That is, β_0 is still simply the mean when all of the predictors are 0.

The interpretation of the coefficients in front of our predictors are slightly different than before. For example $\hat{\beta}_1 = -0.0066349$ is our estimate for β_1 , the average change in miles per gallon for an increase in weight (x_1) of one-pound **for a car of a certain model year**, that is, for a fixed value of x_2 . Note that this coefficient is actually the same for any given value of x_2 . Later, we will look at models that allow for a different change in mean response for different values of x_2 . Also note that this estimate is negative, which we would expect since, in general, fuel efficiency decreases for larger vehicles. Recall that in the multiple linear regression setting, this interpretation is dependent on a fixed value for x_2 , that is, “for a car of a certain model year.” It is possible that the indirect relationship between fuel efficiency and weight does not hold when an additional factor, say `year`, is included, and thus we could have the sign of our coefficient flipped.

Lastly, $\hat{\beta}_2 = 0.761402$ is our estimate for β_2 , the average change in miles per gallon for a one-year increase in model year (x_2) for a car of a certain weight, that is, for a fixed value of x_1 . It is not surprising that the estimate is positive. We expect that as time passes and the years march on, technology would improve so that a car of a specific weight would get better mileage now as compared to their predecessors. And yet, the coefficient could have been negative because we are also including weight as variable, and not strictly as a fixed value.

9.1 Matrix Approach to Regression

In our above example we used two predictor variables, but it will only take a little more work to allow for an arbitrary number of predictor variables and derive their coefficient estimates. We can consider the model,

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \cdots + \beta_{p-1} x_{i(p-1)} + \epsilon_i, \quad i = 1, 2, \dots, n$$

where $\epsilon_i \sim N(0, \sigma^2)$. In this model, there are $p - 1$ predictor variables, x_1, x_2, \dots, x_{p-1} . There are a total of p β -parameters and a single parameter σ^2 for the variance of the errors. (It should be noted that almost as often, authors will use p as the number of predictors, making the total number of β parameters $p + 1$. This is always something you should be aware of when reading about multiple regression. There is not a standard that is used most often.)

If we were to stack together the n linear equations that represent each Y_i into a column vector, we get the following.

$$\begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{11} & x_{12} & \cdots & x_{1(p-1)} \\ 1 & x_{21} & x_{22} & \cdots & x_{2(p-1)} \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & x_{n1} & x_{n2} & \cdots & x_{n(p-1)} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_{p-1} \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$Y = X\beta + \epsilon$$

$$Y = \begin{bmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{bmatrix}, \quad X = \begin{bmatrix} 1 & x_{11} & x_{12} & \cdots & x_{1(p-1)} \\ 1 & x_{21} & x_{22} & \cdots & x_{2(p-1)} \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & x_{n1} & x_{n2} & \cdots & x_{n(p-1)} \end{bmatrix}, \quad \beta = \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_{p-1} \end{bmatrix}, \quad \epsilon = \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

So now with data,

$$y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$$

Just as before, we can estimate β by minimizing,

$$f(\beta_0, \beta_1, \beta_2, \dots, \beta_{p-1}) = \sum_{i=1}^n (y_i - (\beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \cdots + \beta_{p-1} x_{i(p-1)}))^2,$$

which would require taking p derivatives, which result in following **normal equations**.

$$\begin{bmatrix} n & \sum_{i=1}^n x_{i1} & \sum_{i=1}^n x_{i2} & \cdots & \sum_{i=1}^n x_{i(p-1)} \\ \sum_{i=1}^n x_{i1} & \sum_{i=1}^n x_{i1}^2 & \sum_{i=1}^n x_{i1}x_{i2} & \cdots & \sum_{i=1}^n x_{i1}x_{i(p-1)} \\ \vdots & \vdots & \vdots & & \vdots \\ \sum_{i=1}^n x_{i(p-1)} & \sum_{i=1}^n x_{i(p-1)}x_{i1} & \sum_{i=1}^n x_{i(p-1)}x_{i2} & \cdots & \sum_{i=1}^n x_{i(p-1)}^2 \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_{p-1} \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^n y_i \\ \sum_{i=1}^n x_{i1}y_i \\ \vdots \\ \sum_{i=1}^n x_{i(p-1)}y_i \end{bmatrix}$$

The normal equations can be written much more succinctly in matrix notation,

$$X^\top X \beta = X^\top y.$$

We can then solve this expression by multiplying both sides by the inverse of $X^\top X$, which exists, provided the columns of X are linearly independent. Then as always, we denote our solution with a hat.

$$\hat{\beta} = (X^\top X)^{-1} X^\top y$$

To verify that this is what R has done for us in the case of two predictors, we create an X matrix. Note that the first column is all 1s, and the remaining columns contain the data.

```
n = nrow(autompg)
p = length(coef(mpg_model))
X = cbind(rep(1, n), autompg$wt, autompg$year)
y = autompg$mpg

(beta_hat = solve(t(X) %*% X) %*% t(X) %*% y)

##           [,1]
## [1,] -14.637641945
## [2,] -0.006634876
## [3,]  0.761401955

coef(mpg_model)

##   (Intercept)          wt          year
## -14.637641945 -0.006634876  0.761401955
```

$$\hat{\beta} = \begin{bmatrix} -14.6376419 \\ -0.0066349 \\ 0.761402 \end{bmatrix}$$

In our new notation, the fitted values can be written

$$\hat{y} = X \hat{\beta}.$$

$$\hat{y} = \begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \\ \vdots \\ \hat{y}_n \end{bmatrix}$$

Then, we can create a vector for the residual values,

$$e = \begin{bmatrix} e_1 \\ e_2 \\ \vdots \\ e_n \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix} - \begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \\ \vdots \\ \hat{y}_n \end{bmatrix}.$$

And lastly, we can update our estimate for σ^2 .

$$s_e^2 = \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{n - p} = \frac{e^\top e}{n - p}$$

Recall, we like this estimate because it is unbiased, that is,

$$\mathbb{E}[s_e^2] = \sigma^2$$

Note that the change from the SLR estimate to now is in the denominator. Specifically we now divide by $n - p$ instead of $n - 2$. Or actually, we should note that in the case of SLR, there are two β parameters and thus $p = 2$.

Also note that if we fit the model $Y_i = \beta + \epsilon_i$ that $\hat{y} = \bar{y}$ and $p = 1$ and s_e^2 would become

$$s_e^2 = \frac{\sum_{i=1}^n (y_i - \bar{y})^2}{n - 1}$$

which is likely the very first sample standard deviation you saw in a mathematical statistics class. The same reason for $n - 1$ in this case, that we estimated one parameter, so we lose one degree of freedom. Now, in general, we are estimating p parameters, the β parameters, so we lose p degrees of freedom.

Also, recall that most often we will be interested in s_e , the residual standard error as R calls it,

$$s_e = \sqrt{\frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{n - p}}.$$

In R, we could directly access s_e for a fitted model, as we have seen before.

```
summary(mpg_model)$sigma
```

```
## [1] 3.431367
```

And we can now verify that our math above is indeed calculating the same quantities.

```
y_hat = X %*% solve(t(X) %*% X) %*% t(X) %*% y
e      = y - y_hat
sqrt(e %*% e / (n - p))
```

```
## [,1]
## [1,] 3.431367
```

```
sqrt(sum((y - y_hat) ^ 2) / (n - p))
```

```
## [1] 3.431367
```

9.2 Sampling Distribution

As we can see in the output below, the results of calling `summary()` are similar to SLR, but there are some differences, most obviously a new row for the added predictor variable.

```
summary(mpg_model)

##
## Call:
## lm(formula = mpg ~ wt + year, data = autompg)
##
## Residuals:
##    Min     1Q Median     3Q    Max
## -8.852 -2.292 -0.100  2.039 14.325
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) -14.6376419  4.0233914 -3.638 0.000312 ***
## wt          -0.0066349  0.0002149 -30.881 < 2e-16 ***
## year         0.7614020  0.0497266  15.312 < 2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 3.431 on 387 degrees of freedom
## Multiple R-squared:  0.8082, Adjusted R-squared:  0.8072
## F-statistic: 815.6 on 2 and 387 DF, p-value: < 2.2e-16
```

To understand these differences in detail, we will need to first obtain the sampling distribution of $\hat{\beta}$.

The derivation of the sampling distribution of $\hat{\beta}$ involves the multivariate normal distribution. These brief notes from semesters past give a basic overview. These are simply for your information, as we will not present the derivation in full here.

Our goal now is to obtain the distribution of the $\hat{\beta}$ vector,

$$\hat{\beta} = \begin{bmatrix} \hat{\beta}_0 \\ \hat{\beta}_1 \\ \hat{\beta}_2 \\ \vdots \\ \hat{\beta}_{p-1} \end{bmatrix}$$

Recall from last time that when discussing sampling distributions, we now consider $\hat{\beta}$ to be a random vector, thus we use Y instead of the data vector y .

$$\hat{\beta} = (X^\top X)^{-1} X^\top Y$$

Then it is a consequence of the multivariate normal distribution that,

$$\hat{\beta} \sim N\left(\beta, \sigma^2 (X^\top X)^{-1}\right).$$

We then have

$$E[\hat{\beta}] = \beta$$

and for any $\hat{\beta}_j$ we have

$$\mathbb{E}[\hat{\beta}_j] = \beta_j.$$

We also have

$$\text{Var}[\hat{\beta}] = \sigma^2 (X^\top X)^{-1}$$

and for any $\hat{\beta}_j$ we have

$$\text{Var}[\hat{\beta}_j] = \sigma^2 C_{jj}$$

where

$$C = (X^\top X)^{-1}$$

and the elements of C are denoted

$$C = \begin{bmatrix} C_{00} & C_{01} & C_{02} & \cdots & C_{0(p-1)} \\ C_{10} & C_{11} & C_{12} & \cdots & C_{1(p-1)} \\ C_{20} & C_{21} & C_{22} & \cdots & C_{2(p-1)} \\ \vdots & \vdots & \vdots & & \vdots \\ C_{(p-1)0} & C_{(p-1)1} & C_{(p-1)2} & \cdots & C_{(p-1)(p-1)} \end{bmatrix}.$$

Essentially, the diagonal elements correspond to the β vector.

Then the standard error for the $\hat{\beta}$ vector is given by

$$\text{SE}[\hat{\beta}] = s_e \sqrt{(X^\top X)^{-1}}$$

and for a particular $\hat{\beta}_j$

$$\text{SE}[\hat{\beta}_j] = s_e \sqrt{C_{jj}}.$$

Lastly, each of the $\hat{\beta}_j$ follows a normal distribution,

$$\hat{\beta}_j \sim N(\beta_j, \sigma^2 C_{jj}).$$

thus

$$\frac{\hat{\beta}_j - \beta_j}{s_e \sqrt{C_{jj}}} \sim t_{n-p}.$$

Now that we have the necessary distributional results, we can move on to perform tests and make interval estimates.

9.2.1 Single Parameter Tests

The first test we will see is a test for a single β_j .

$$H_0 : \beta_j = 0 \quad \text{vs} \quad H_1 : \beta_j \neq 0$$

Again, the test statistic takes the form

$$\text{TS} = \frac{\text{EST} - \text{HYP}}{\text{SE}}.$$

In particular,

$$t = \frac{\hat{\beta}_j - \beta_j}{\text{SE}[\hat{\beta}_j]} = \frac{\hat{\beta}_j - 0}{s_e \sqrt{C_{jj}}},$$

which, under the null hypothesis, follows a t distribution with $n - p$ degrees of freedom.

Recall our model for mpg,

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \epsilon_i, \quad i = 1, 2, \dots, n$$

where $\epsilon_i \sim N(0, \sigma^2)$.

- x_{i1} as the weight (`wt`) of the i th car.
- x_{i2} as the model year (`year`) of the i th car.

Then the test

$$H_0 : \beta_1 = 0 \quad \text{vs} \quad H_1 : \beta_1 \neq 0$$

can be found in the `summary()` output, in particular:

```
summary(mpg_model)$coef
```

	Estimate	Std. Error	t value	Pr(> t)
## (Intercept)	-14.637641945	4.0233913563	-3.638135	3.118311e-04
## wt	-0.006634876	0.0002148504	-30.881372	1.850466e-106
## year	0.761401955	0.0497265950	15.311765	1.036597e-41

The estimate (`Estimate`), standard error (`Std. Error`), test statistic (`t value`), and p-value (`Pr(>|t|)`) for this test are displayed in the second row, labeled `wt`. Remember that the p-value given here is specifically for a two-sided test, where the hypothesized value is 0.

Also note in this case, by hypothesizing that $\beta_1 = 0$ the null and alternative essentially specify two different models:

- $H_0: Y = \beta_0 + \beta_2 x_2 + \epsilon$
- $H_1: Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \epsilon$

This is important. We are not simply testing whether or not there is a relationship between weight and fuel efficiency. We are testing if there is a relationship between weight and fuel efficiency, given that a term for year is in the model. (Note, we dropped some indexing here, for readability.)

9.2.2 Confidence Intervals

Since $\hat{\beta}_j$ is our estimate for β_j and we have

$$\mathbb{E}[\hat{\beta}_j] = \beta_j$$

as well as the standard error,

$$\text{SE}[\hat{\beta}_j] = s_e \sqrt{C_{jj}}$$

and the sampling distribution of $\hat{\beta}_j$ is Normal, then we can easily construct confidence intervals for each of the $\hat{\beta}_j$.

$$\hat{\beta}_j \pm t_{\alpha/2, n-p} \cdot s_e \sqrt{C_{jj}}$$

We can find these in R using the same method as before. Now there will simply be additional rows for the additional β .

```
confint(mpg_model, level = 0.99)
```

```
##           0.5 %      99.5 %
## (Intercept) -25.052563681 -4.222720208
## wt          -0.007191036 -0.006078716
## year         0.632680051  0.890123859
```

9.2.3 Confidence Intervals for Mean Response

As we saw in SLR, we can create confidence intervals for the mean response, that is, an interval estimate for $E[Y | X = x]$. In SLR, the mean of Y was only dependent on a single value x . Now, in multiple regression, $E[Y | X = x]$ is dependent on the value of each of the predictors, so we define the vector x_0 to be,

$$x_0 = \begin{bmatrix} 1 \\ x_{01} \\ x_{02} \\ \vdots \\ x_{0(p-1)} \end{bmatrix}.$$

Then our estimate of $E[Y | X = x_0]$ for a set of values x_0 is given by

$$\begin{aligned} \hat{y}(x_0) &= x_0^\top \hat{\beta} \\ &= \hat{\beta}_0 + \hat{\beta}_1 x_{01} + \hat{\beta}_2 x_{02} + \cdots + \hat{\beta}_{p-1} x_{0(p-1)}. \end{aligned}$$

As with SLR, this is an unbiased estimate.

$$\begin{aligned} \mathbb{E}[\hat{y}(x_0)] &= x_0^\top \beta \\ &= \beta_0 + \beta_1 x_{01} + \beta_2 x_{02} + \cdots + \beta_{p-1} x_{0(p-1)} \end{aligned}$$

To make an interval estimate, we will also need its standard error.

$$\text{SE}[\hat{y}(x_0)] = s_e \sqrt{x_0^\top (X^\top X)^{-1} x_0}$$

Putting it all together, we obtain a confidence interval for the mean response.

$$\hat{y}(x_0) \pm t_{\alpha/2, n-p} \cdot s_e \sqrt{x_0^\top (X^\top X)^{-1} x_0}$$

The math has changed a bit, but the process in R remains almost identical. Here, we create a data frame for two additional cars. One car that weighs 3500 pounds produced in 1976, as well as a second car that weighs 5000 pounds which was produced in 1981.

```
new_cars = data.frame(wt = c(3500, 5000), year = c(76, 81))
new_cars
```

```
##      wt year
## 1 3500   76
## 2 5000   81
```

We can then use the `predict()` function with `interval = "confidence"` to obtain intervals for the mean fuel efficiency for both new cars. Again, it is important to make the data passed to `newdata` a data frame, so that R knows which values are for which variables.

```
predict(mpg_model, newdata = new_cars, interval = "confidence", level = 0.99)
```

```
##       fit     lwr      upr
## 1 20.00684 19.4712 20.54248
## 2 13.86154 12.3341 15.38898
```

R then reports the estimate $\hat{y}(x_0)$ (`fit`) for each, as well as the lower (`lwr`) and upper (`upr`) bounds for the interval at a desired level (99%).

A word of caution here: one of these estimates is good while one is suspect.

```
new_cars$wt

## [1] 3500 5000

range(autompg$wt)

## [1] 1613 5140
```

Note that both of the weights of the new cars are within the range of observed values.

```
new_cars$year

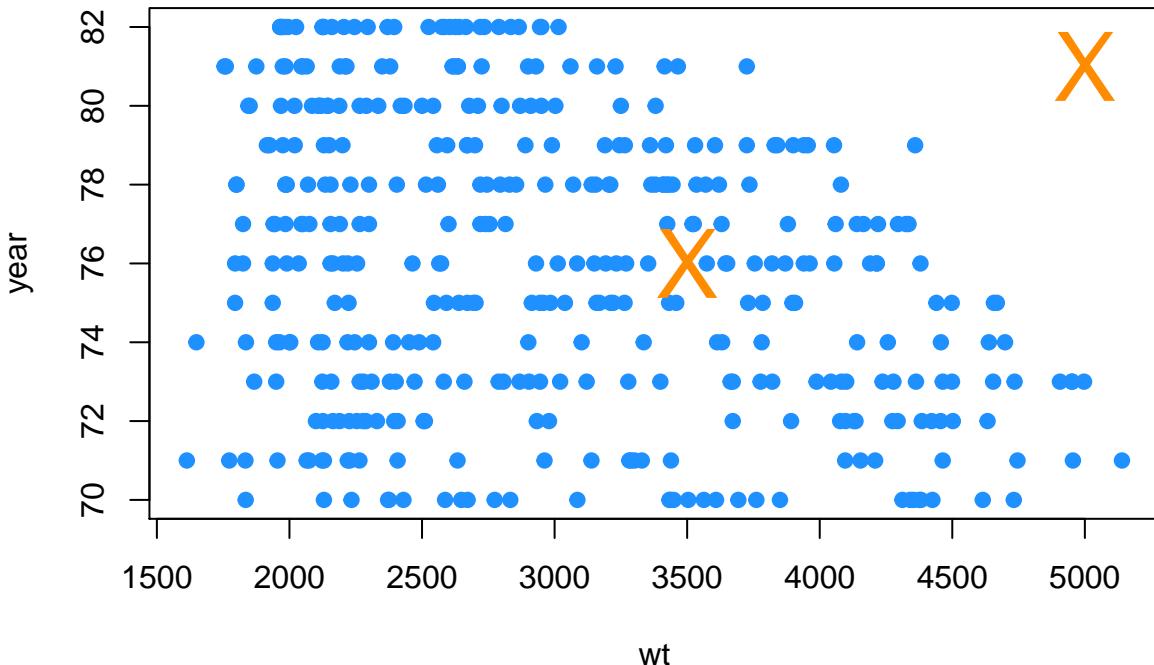
## [1] 76 81
```

```
range(autompg$year)
```

```
## [1] 70 82
```

As are the years of each of the new cars.

```
plot(year ~ wt, data = autompg, pch = 20, col = "dodgerblue", cex = 1.5)
points(new_cars, col = "darkorange", cex = 3, pch = "X")
```



However, we have to consider weight and year together now. And based on the above plot, one of the new cars is within the “blob” of observed values, while the other, the car from 1981 weighing 5000 pounds, is noticeably outside of the observed values. This is a hidden extrapolation which you should be aware of when using multiple regression.

Shifting gears back to the new data pair that can be reasonably estimated, we do a quick verification of some of the mathematics in R.

```
x0 = c(1, 3500, 76)
x0 %*% beta_hat
```

```
## [,1]
## [1,] 20.00684
```

$$x_0 = \begin{bmatrix} 1 \\ 3500 \\ 76 \end{bmatrix}$$

$$\hat{\beta} = \begin{bmatrix} -14.6376419 \\ -0.0066349 \\ 0.761402 \end{bmatrix}$$

$$\hat{y}(x_0) = x_0^\top \hat{\beta} = [1 \ 3500 \ 76] \begin{bmatrix} -14.6376419 \\ -0.0066349 \\ 0.761402 \end{bmatrix} = 20.0068411$$

Also note that, using a particular value for x_0 , we can essentially extract certain $\hat{\beta}_j$ values.

```
beta_hat
```

```
##           [,1]
## [1,] -14.637641945
## [2,] -0.006634876
## [3,]  0.761401955
```

```
x0 = c(0, 0, 1)
x0 %*% beta_hat
```

```
##           [,1]
## [1,]  0.761402
```

With this in mind, confidence intervals for the individual $\hat{\beta}_j$ are actually a special case of a confidence interval for mean response.

9.2.4 Prediction Intervals

As with SLR, creating prediction intervals involves one slight change to the standard error to account for the fact that we are now considering an observation, instead of a mean.

Here we use $\hat{y}(x_0)$ to estimate Y_0 , a new observation of Y at the predictor vector x_0 .

$$\begin{aligned}\hat{y}(x_0) &= x_0^\top \hat{\beta} \\ &= \hat{\beta}_0 + \hat{\beta}_1 x_{01} + \hat{\beta}_2 x_{02} + \cdots + \hat{\beta}_{p-1} x_{0(p-1)}\end{aligned}$$

$$\begin{aligned}\text{E}[\hat{y}(x_0)] &= x_0^\top \beta \\ &= \beta_0 + \beta_1 x_{01} + \beta_2 x_{02} + \cdots + \beta_{p-1} x_{0(p-1)}\end{aligned}$$

As we did with SLR, we need to account for the additional variability of an observation about its mean.

$$\text{SE}[\hat{y}(x_0) + \epsilon] = s_e \sqrt{1 + x_0^\top (X^\top X)^{-1} x_0}$$

Then we arrive at our updated prediction interval for MLR.

$$\hat{y}(x_0) \pm t_{\alpha/2, n-p} \cdot s_e \sqrt{1 + x_0^\top (X^\top X)^{-1} x_0}$$

```
new_cars
```

```
##      wt year
## 1 3500   76
## 2 5000   81
```

```
predict(mpg_model, newdata = new_cars, interval = "prediction", level = 0.99)
```

```
##          fit      lwr      upr
## 1 20.00684 11.108294 28.90539
## 2 13.86154  4.848751 22.87432
```

9.3 Significance of Regression

The decomposition of variation that we had seen in SLR still holds for MLR.

$$\sum_{i=1}^n (y_i - \bar{y})^2 = \sum_{i=1}^n (y_i - \hat{y}_i)^2 + \sum_{i=1}^n (\hat{y}_i - \bar{y})^2$$

That is,

$$\text{SST} = \text{SSReg} + \text{SSE}.$$

This means that, we can still calculate R^2 in the same manner as before, which R continues to do automatically.

```
summary(mpg_model)$r.squared
```

```
## [1] 0.8082355
```

The interpretation changes slightly as compared to SLR. In this MLR case, we say that 80.82% for the observed variation in miles per gallon is explained by the linear relationship with the two predictor variables, weight and year.

In multiple regression, the significance of regression test is

$$H_0 : \beta_1 = \beta_2 = \cdots = \beta_{p-1} = 0.$$

Here, we see that the null hypothesis sets all of the β_j equal to 0, *except* the intercept, β_0 . We could then say that the null model, or “model under the null hypothesis” is

$$Y_i = \beta_0 + \epsilon_i.$$

This is a model where the *regression* is insignificant. **None** of the predictors have a significant linear relationship with the response. Notationally, we will denote the fitted values of this model as \hat{y}_{0i} , which in this case happens to be:

$$\hat{y}_{0i} = \bar{y}.$$

The alternative hypothesis here is that at least one of the β_j from the null hypothesis is not 0.

$$H_1 : \text{At least one of } \beta_j \neq 0, j = 1, 2, \dots, (p-1)$$

We could then say that the full model, or “model under the alternative hypothesis” is

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \cdots + \beta_{(p-1)} x_{i(p-1)} + \epsilon_i$$

This is a model where the regression is significant. **At least one** of the predictors has a significant linear relationship with the response. There is some linear relationship between y and the predictors, x_1, x_2, \dots, x_{p-1} .

We will denote the fitted values of this model as \hat{y}_{1i} .

To develop the F test for the significance of the regression, we will arrange the variance decomposition into an ANOVA table.

Source	Sum of Squares	Degrees of Freedom	Mean Square	F
Regression	$\sum_{i=1}^n (\hat{y}_{1i} - \bar{y})^2$	$p - 1$	$SS_{\text{Reg}}/(p - 1)$	MS_{Reg}/MSE
Error	$\sum_{i=1}^n (y_i - \hat{y}_{1i})^2$	$n - p$	$SSE/(n - p)$	
Total	$\sum_{i=1}^n (y_i - \bar{y})^2$	$n - 1$		

In summary, the F statistic is

$$F = \frac{\sum_{i=1}^n (\hat{y}_{1i} - \bar{y})^2 / (p - 1)}{\sum_{i=1}^n (y_i - \hat{y}_{1i})^2 / (n - p)},$$

and the p-value is calculated as

$$P(F_{p-1, n-p} > F)$$

since we reject for large values of F . A large value of the statistic corresponds to a large portion of the variance being explained by the regression. Here $F_{p-1, n-p}$ represents a random variable which follows an F distribution with $p - 1$ and $n - p$ degrees of freedom.

To perform this test in R, we first explicitly specify the two models in R and save the results in different variables. We then use `anova()` to compare the two models, giving `anova()` the null model first and the alternative (full) model second. (Specifying the full model first will result in the same p-value, but some nonsensical intermediate values.)

In this case,

- $H_0: Y_i = \beta_0 + \epsilon_i$
- $H_1: Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \epsilon_i$

That is, in the null model, we use neither of the predictors, whereas in the full (alternative) model, at least one of the predictors is useful.

```
null_mpg_model = lm(mpg ~ 1, data = autompg)
full_mpg_model = lm(mpg ~ wt + year, data = autompg)
anova(null_mpg_model, full_mpg_model)
```

```
## Analysis of Variance Table
##
## Model 1: mpg ~ 1
## Model 2: mpg ~ wt + year
##   Res.Df   RSS Df Sum of Sq    F    Pr(>F)
## 1     389 23761.7
```

```
## 2      387 4556.6 2      19205 815.55 < 2.2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

First, notice that R does not display the results in the same manner as the table above. More important than the layout of the table are its contents. We see that the value of the F statistic is 815.55, and the p-value is extremely low, so we reject the null hypothesis at any reasonable α and say that the regression is significant. At least one of `wt` or `year` has a useful linear relationship with `mpg`.

```
summary(mpg_model)
```

```
##
## Call:
## lm(formula = mpg ~ wt + year, data = autompg)
##
## Residuals:
##     Min      1Q Median      3Q     Max
## -8.852 -2.292 -0.100  2.039 14.325
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) -14.6376419  4.0233914 -3.638 0.000312 ***
## wt          -0.0066349  0.0002149 -30.881 < 2e-16 ***
## year         0.7614020  0.0497266  15.312 < 2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 3.431 on 387 degrees of freedom
## Multiple R-squared:  0.8082, Adjusted R-squared:  0.8072
## F-statistic: 815.6 on 2 and 387 DF,  p-value: < 2.2e-16
```

Notice that the value reported in the row for `F-statistic` is indeed the F test statistic for the significance of the regression test, and additionally it reports the two relevant degrees of freedom.

Also, note that none of the individual t -tests are equivalent to the F -test as they were in SLR. This equivalence only holds for SLR because the individual test for β_1 is the same as testing for all non-intercept parameters, since there is only one.

We can also verify the sums of squares and degrees of freedom directly in R. You should match these to the table from R and use this to match R's output to the written table above.

```
# SSReg
sum((fitted(full_mpg_model) - fitted(null_mpg_model)) ^ 2)
```

```
## [1] 19205.03
```

```
# SSE
sum(resid(full_mpg_model) ^ 2)
```

```
## [1] 4556.646
```

```
# SST
sum(resid(null_mpg_model) ^ 2)

## [1] 23761.67

# Degrees of Freedom: Regression
length(coef(full_mpg_model)) - length(coef(null_mpg_model))

## [1] 2

# Degrees of Freedom: Error
length(resid(full_mpg_model)) - length(coef(full_mpg_model))

## [1] 387

# Degrees of Freedom: Total
length(resid(null_mpg_model)) - length(coef(null_mpg_model))

## [1] 389
```

9.4 Nested Models

The significance of the regression test is actually a special case of testing what we will call **nested models**. More generally we can compare two models, where one model is “nested” inside the other, meaning one model contains a subset of the predictors from only the larger model.

Consider the following full model,

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \cdots + \beta_{(p-1)} x_{i(p-1)} + \epsilon_i$$

This model has $p - 1$ predictors, for a total of p β -parameters. We will denote the fitted values of this model as \hat{y}_{1i} .

Let the null model be

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \cdots + \beta_{(q-1)} x_{i(q-1)} + \epsilon_i$$

where $q < p$. This model has $q - 1$ predictors, for a total of q β -parameters. We will denote the fitted values of this model as \hat{y}_{0i} .

The difference between these two models can be codified by the null hypothesis of a test.

$$H_0 : \beta_q = \beta_{q+1} = \cdots = \beta_{p-1} = 0.$$

Specifically, the β -parameters from the full model that are not in the null model are zero. The resulting model, which is nested, is the null model.

We can then perform this test using an F -test, which is the result of the following ANOVA table.

Source	Sum of Squares	Degrees of Freedom	Mean Square	F
Diff	$\sum_{i=1}^n (\hat{y}_{1i} - \hat{y}_{0i})^2$	$p - q$	$SSD/(p - q)$	MSD/MSE
Full	$\sum_{i=1}^n (y_i - \hat{y}_{1i})^2$	$n - p$	$SSE/(n - p)$	
Null	$\sum_{i=1}^n (y_i - \hat{y}_{0i})^2$	$n - q$		

$$F = \frac{\sum_{i=1}^n (\hat{y}_{1i} - \hat{y}_{0i})^2 / (p - q)}{\sum_{i=1}^n (y_i - \hat{y}_{1i})^2 / (n - p)}.$$

Notice that the row for “Diff” compares the sum of the squared differences of the fitted values. The degrees of freedom is then the difference of the number of β -parameters estimated between the two models.

For example, the `autompg` dataset has a number of additional variables that we have yet to use.

```
names(autompg)

## [1] "mpg"   "cyl"   "disp"  "hp"    "wt"    "acc"   "year"
```

We'll continue to use `mpg` as the response, but now we will consider two different models.

- Full: `mpg ~ wt + year + cyl + disp + hp + acc`
- Null: `mpg ~ wt + year`

Note that these are nested models, as the null model contains a subset of the predictors from the full model, and no additional predictors. Both models have an intercept β_0 as well as a coefficient in front of each of the predictors. We could then write the null hypothesis for comparing these two models as,

$$H_0 : \beta_{\text{cyl}} = \beta_{\text{disp}} = \beta_{\text{hp}} = \beta_{\text{acc}} = 0$$

The alternative is simply that at least one of the β_j from the null is not 0.

To perform this test in R we first define both models, then give them to the `anova()` command.

```
null_mpg_model = lm(mpg ~ wt + year, data = autompg)
#full_mpg_model = lm(mpg ~ wt + year + cyl + disp + hp + acc, data = autompg)
full_mpg_model = lm(mpg ~ ., data = autompg)
anova(null_mpg_model, full_mpg_model)
```

```
## Analysis of Variance Table
##
## Model 1: mpg ~ wt + year
## Model 2: mpg ~ cyl + disp + hp + wt + acc + year
##   Res.Df   RSS Df Sum of Sq    F Pr(>F)
## 1     387 4556.6
## 2     383 4530.5  4      26.18 0.5533 0.6967
```

Here we have used the formula `mpg ~ .` to define to full model. This is the same as the commented out line. Specifically, this a common shortcut in R which reads, “model `mpg` as the response with each of the remaining variables in the data frame as predictors.”

Here we see that the value of the F statistic is 0.553, and the p-value is very large, so we fail to reject the null hypothesis at any reasonable α and say that none of `cyl`, `disp`, `hp`, and `acc` are significant with `wt` and `year` already in the model.

Again, we verify the sums of squares and degrees of freedom directly in R. You should match these to the table from R, and use this to match R's output to the written table above.

```
# SSDiff
sum((fitted(full_mpg_model) - fitted(null_mpg_model)) ^ 2)

## [1] 26.17981

# SSE (For Full)
sum(resid(full_mpg_model) ^ 2)

## [1] 4530.466

# SST (For Null)
sum(resid(null_mpg_model) ^ 2)

## [1] 4556.646

# Degrees of Freedom: Diff
length(coef(full_mpg_model)) - length(coef(null_mpg_model))

## [1] 4

# Degrees of Freedom: Full
length(resid(full_mpg_model)) - length(coef(full_mpg_model))

## [1] 383

# Degrees of Freedom: Null
length(resid(null_mpg_model)) - length(coef(null_mpg_model))

## [1] 387
```

9.5 Simulation

Since we ignored the derivation of certain results, we will again use simulation to convince ourselves of some of the above results. In particular, we will simulate samples of size $n = 100$ from the model

$$Y_i = 5 + -2x_{i1} + 6x_{i2} + \epsilon_i, \quad i = 1, 2, \dots, n$$

where $\epsilon_i \sim N(0, \sigma^2 = 16)$. Here we have two predictors, so $p = 3$.

```
set.seed(1337)
n = 100 # sample size
p = 3

beta_0 = 5
beta_1 = -2
beta_2 = 6
sigma = 4
```

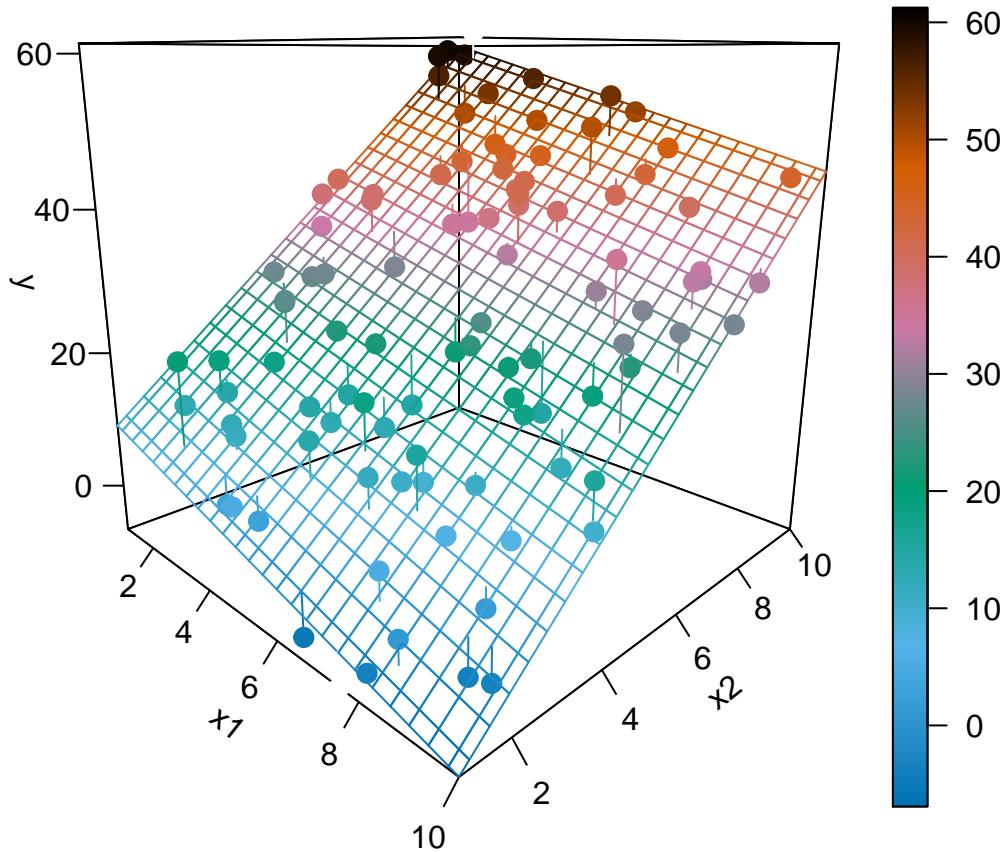
As is the norm with regression, the x values are considered fixed and known quantities, so we will simulate those first, and they remain the same for the rest of the simulation study. Also note we create an x_0 which is all 1, which we need to create our X matrix. If you look at the matrix formulation of regression, this unit vector of all 1s is a “predictor” that puts the intercept into the model. We also calculate the C matrix for later use.

```
x0 = rep(1, n)
x1 = sample(seq(1, 10, length = n))
x2 = sample(seq(1, 10, length = n))
X = cbind(x0, x1, x2)
C = solve(t(X) %*% X)
```

We then simulate the response according the model above. Lastly, we place the two predictors and response into a data frame. Note that we do **not** place x_0 in the data frame. This is a result of R adding an intercept by default.

```
eps      = rnorm(n, mean = 0, sd = sigma)
y       = beta_0 + beta_1 * x1 + beta_2 * x2 + eps
sim_data = data.frame(x1, x2, y)
```

Plotting this data and fitting the regression produces the following plot.



We then calculate

$$\hat{\beta} = (X^\top X)^{-1} X^\top y.$$

```
(beta_hat = C %*% t(X) %*% y)
```

```
##          [,1]
## x0   5.293609
## x1  -1.798593
## x2   5.775081
```

Notice that these values are the same as the coefficients found using `lm()` in R.

```
coef(lm(y ~ x1 + x2, data = sim_data))
```

```
## (Intercept)           x1           x2
## 5.293609    -1.798593     5.775081
```

Also, these values are close to what we would expect.

```
c(beta_0, beta_1, beta_2)
```

```
## [1] 5 -2 6
```

We then calculated the fitted values in order to calculate s_e , which we see is the same as the `sigma` which is returned by `summary()`.

```
y_hat = X %*% beta_hat
(s_e = sqrt(sum((y - y_hat) ^ 2) / (n - p)))

## [1] 3.976044

summary(lm(y ~ x1 + x2, data = sim_data))$sigma

## [1] 3.976044
```

So far so good. Everything checks out. Now we will finally simulate from this model repeatedly in order to obtain an empirical distribution of $\hat{\beta}_2$.

We expect $\hat{\beta}_2$ to follow a normal distribution,

$$\hat{\beta}_2 \sim N(\beta_2, \sigma^2 C_{22}).$$

In this case,

$$\hat{\beta}_2 \sim N(\mu = 6, \sigma^2 = 16 \times 0.0014777 = 0.0236438).$$

$$\hat{\beta}_2 \sim N(\mu = 6, \sigma^2 = 0.0236438).$$

Note that C_{22} corresponds to the element in the **third** row and **third** column since β_2 is the **third** parameter in the model and because R is indexed starting at 1. However, we index the C matrix starting at 0 to match the diagonal elements to the corresponding β_j .

```
c[3, 3]

## [1] 0.00147774

c[2 + 1, 2 + 1]

## [1] 0.00147774

sigma ^ 2 * c[2 + 1, 2 + 1]

## [1] 0.02364383
```

We now perform the simulation a large number of times. Each time, we update the `y` variable in the data frame, leaving the `x` variables the same. We then fit a model, and store $\hat{\beta}_2$.

```
num_sims = 10000
beta_hat_2 = rep(0, num_sims)
for(i in 1:num_sims) {
  eps = rnorm(n, mean = 0, sd = sigma)
  sim_data$y = beta_0 * x0 + beta_1 * x1 + beta_2 * x2 + eps
  fit = lm(y ~ x1 + x2, data = sim_data)
  beta_hat_2[i] = coef(fit)[3]
}
```

We then see that the mean of the simulated values is close to the true value of β_2 .

```
mean(beta_hat_2)
```

```
## [1] 5.99871
```

```
beta_2
```

```
## [1] 6
```

We also see that the variance of the simulated values is close to the true variance of $\hat{\beta}_2$.

$$\text{Var}[\hat{\beta}_2] = \sigma^2 \cdot C_{22} = 16 \times 0.0014777 = 0.0236438$$

```
var(beta_hat_2)
```

```
## [1] 0.02360853
```

```
sigma ^ 2 * C[2 + 1, 2 + 1]
```

```
## [1] 0.02364383
```

The standard deviations found from the simulated data and the parent population are also very close.

```
sd(beta_hat_2)
```

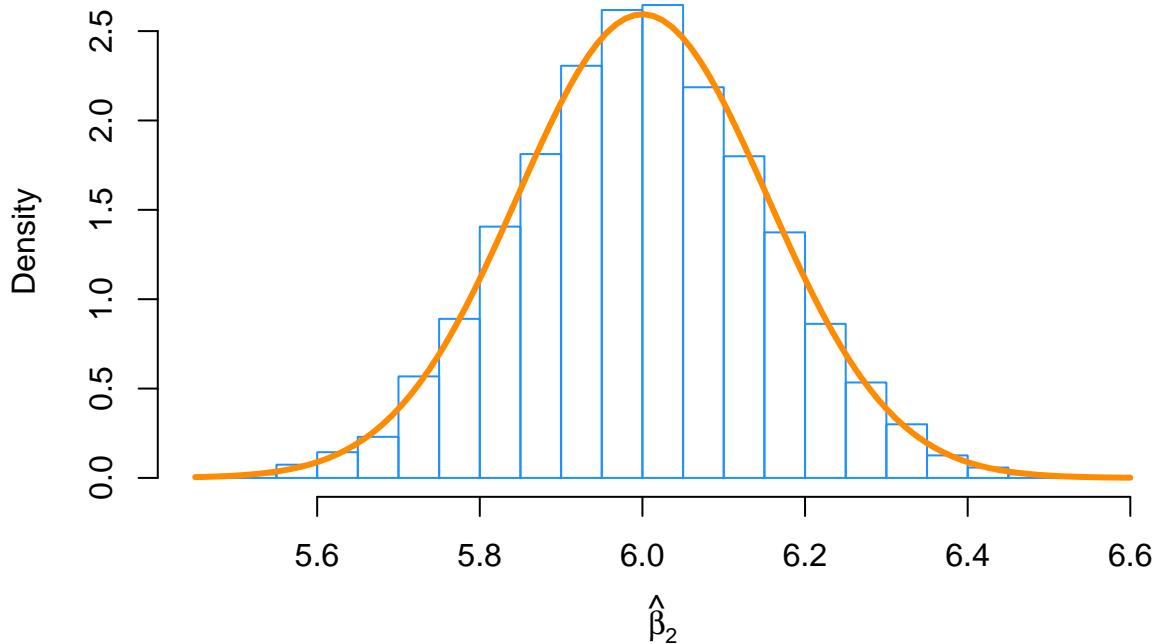
```
## [1] 0.1536507
```

```
sqrt(sigma ^ 2 * C[2 + 1, 2 + 1])
```

```
## [1] 0.1537655
```

Lastly, we plot a histogram of the *simulated values*, and overlay the *true distribution*.

```
hist(beta_hat_2, prob = TRUE, breaks = 20,
      xlab = expression(hat(beta)[2]), main = "", border = "dodgerblue")
curve(dnorm(x, mean = beta_2, sd = sqrt(sigma ^ 2 * C[2 + 1, 2 + 1])),
      col = "darkorange", add = TRUE, lwd = 3)
```



This looks good! The simulation-based histogram appears to be Normal with mean 6 and spread of about 0.15 as you measure from center to inflection point. That matches really well with the sampling distribution of $\hat{\beta}_2 \sim N(\mu = 6, \sigma^2 = 0.0236438)$.

One last check, we verify the 68 – 95 – 99.7 rule.

```
sd_bh2 = sqrt(sigma ^ 2 * C[2 + 1, 2 + 1])
# We expect these to be: 0.68, 0.95, 0.997
mean(beta_2 - 1 * sd_bh2 < beta_hat_2 & beta_hat_2 < beta_2 + 1 * sd_bh2)
```

```
## [1] 0.6811
```

```
mean(beta_2 - 2 * sd_bh2 < beta_hat_2 & beta_hat_2 < beta_2 + 2 * sd_bh2)
```

```
## [1] 0.955
```

```
mean(beta_2 - 3 * sd_bh2 < beta_hat_2 & beta_hat_2 < beta_2 + 3 * sd_bh2)
```

```
## [1] 0.9972
```


Chapter 10

Model Building

“Statisticians, like artists, have the bad habit of falling in love with their models.”

— George Box

Let’s take a step back and consider the process of finding a model for data at a higher level. We are attempting to find a model for a response variable y based on a number of predictors $x_1, x_2, x_3, \dots, x_{p-1}$.

Essentially, we are trying to discover the functional relationship between y and the predictors. In the previous chapter we were fitting models for a car’s fuel efficiency (`mpg`) as a function of its attributes (`wt`, `year`, `cyl`, `disp`, `hp`, `acc`). We also consider y to be a function of some noise. Rarely if ever do we expect there to be an *exact* functional relationship between the predictors and the response.

$$y = f(x_1, x_2, x_3, \dots, x_{p-1}) + \epsilon$$

We can think of this as

$$\text{response} = \text{signal} + \text{noise}.$$

We *could* consider all sorts of complicated functions for f . You will likely encounter several ways of doing this in future machine learning courses. So far in this course we have focused on (multiple) linear regression. That is

$$\begin{aligned} y &= f(x_1, x_2, x_3, \dots, x_{p-1}) + \epsilon \\ &= \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_{p-1} x_{p-1} + \epsilon \end{aligned}$$

In the big picture of possible models that we could fit to this data, this is a rather restrictive model. What do we mean by a restrictive model?

10.1 Family, Form, and Fit

When modeling data, there are a number of choices that need to be made.

- What **family** of models will be considered?
- What **form** of the model will be used?
- How will the model be **fit**?

Let’s work backwards and discuss each of these.

10.1.1 Fit

Consider one of the simplest models we could fit to data, simple linear regression.

$$y = f(x_1, x_2, x_3, \dots, x_{p-1}) + \epsilon = \beta_0 + \beta_1 x_1 + \epsilon$$

So here, despite having multiple predictors, we chose to use only one. How is this model **fit**? We will almost exclusively use the method of least squares, but recall, we had seen alternative methods of fitting this model.

$$\underset{\beta_0, \beta_1}{\operatorname{argmin}} \max |y_i - (\beta_0 + \beta_1 x_i)|$$

$$\underset{\beta_0, \beta_1}{\operatorname{argmin}} \sum_{i=1}^n |y_i - (\beta_0 + \beta_1 x_i)|$$

$$\underset{\beta_0, \beta_1}{\operatorname{argmin}} \sum_{i=1}^n (y_i - (\beta_0 + \beta_1 x_i))^2$$

Any of these methods (we will always use the last, least squares) will obtain estimates of the unknown parameters β_0 and β_1 . Since those are the only unknowns of the specified model, we have then *fit* the model. The fitted model is then

$$\hat{y} = \hat{f}(x_1, x_2, x_3, \dots, x_{p-1}) = \hat{\beta}_0 + \hat{\beta}_1 x_1$$

Note that, now we have dropped the term for the noise. We don't make any effort to model the noise, only the signal.

10.1.2 Form

What are the different **forms** a model could take? Currently, for the linear models we have considered, the only method for altering the form of the model is to control the predictors used. For example, one form of the multiple linear regression model is simple linear regression.

$$y = f(x_1, x_2, x_3, \dots, x_{p-1}) + \epsilon = \beta_0 + \beta_1 x_1 + \epsilon$$

We could also consider a SLR model with a different predictor, thus altering the form of the model.

$$y = f(x_1, x_2, x_3, \dots, x_{p-1}) + \epsilon = \beta_0 + \beta_2 x_2 + \epsilon$$

Often, we'll use multiple predictors in our model. Very often, we will at least try a model with all possible predictors.

$$\begin{aligned} y &= f(x_1, x_2, x_3, \dots, x_{p-1}) + \epsilon \\ &= \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_{p-1} x_{p-1} + \epsilon \end{aligned}$$

We could also use some, but not all of the predictors.

$$\begin{aligned} y &= f(x_1, x_2, x_3, \dots, x_{p-1}) + \epsilon \\ &= \beta_0 + \beta_1 x_1 + \beta_3 x_3 + \beta_5 x_5 + \epsilon \end{aligned}$$

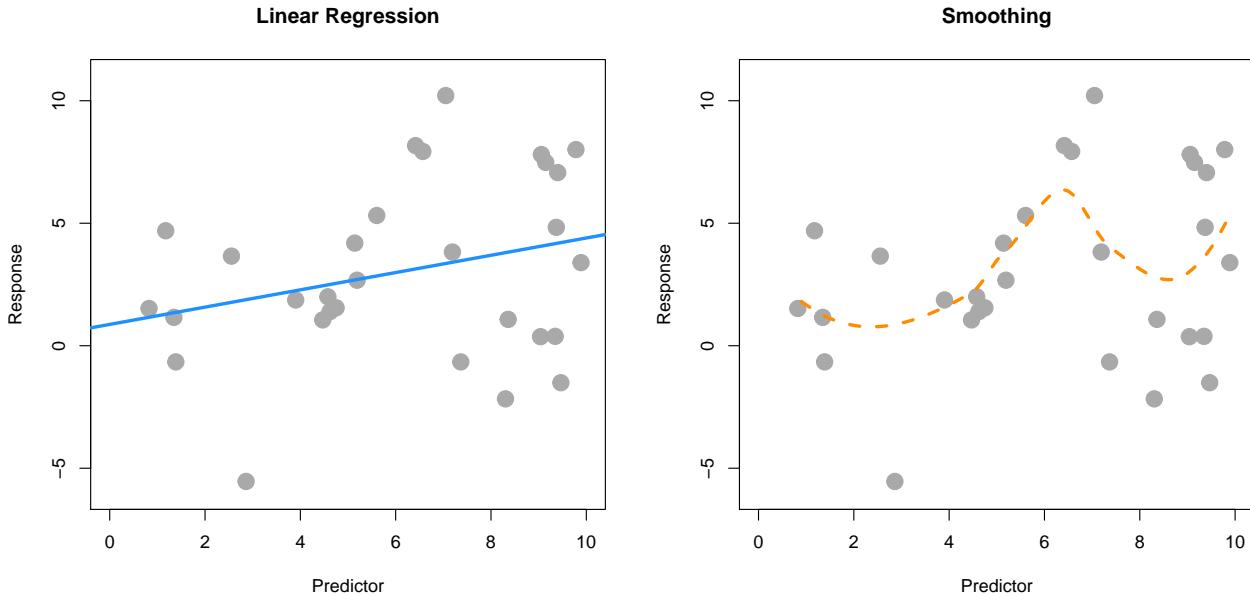
These forms are **restrictive** in two senses. First, they only allow for linear relationships between the response and the predictors. This seems like an obvious restriction of linear models, but in fact, we will soon see how to use linear models for *non-linear* relationships. (It will involve transforming variables.) Second, how one variable affects the response is the same for **any** values of the other predictors. Soon we will see how to create models where the effect of x_1 can be different for different values of x_2 . We will discuss the concept of *interaction*.

10.1.3 Family

A **family** of models is a broader grouping of many possible *forms* of a model. For example, above we saw several forms of models from the family of linear models. We will only ever concern ourselves with linear models, which model a response as a linear combination of predictors. There are certainly other families of models.

For example, there are several families of *non-parametric* regression. Smoothing is a broad family of models. As are regression trees.

In linear regression, we specified models with parameters, β_j and fit the model by finding the best values of these parameters. This is a *parametric* approach. A non-parametric approach skips the step of specifying a model with parameters, and are often described as more of an algorithm. Non-parametric models are often used in machine learning.



Here, SLR (parametric) is used on the left, while smoothing (non-parametric) is used on the right. SLR finds the best slope and intercept. Smoothing produces the fitted y value at a particular x value by considering the y values of the data in a neighborhood of the x value considered. (Local smoothing.)

Why the focus on **linear models**? Two big reasons:

- Linear models are **the** go-to model. Linear models have been around for a long time, and are computationally easy. A linear model may not be the final model you use, but often, it should be the first model you try.
- The ideas behind linear models can be easily transferred to other modeling techniques.

10.1.4 Assumed Model, Fitted Model

When searching for a model, we often need to make assumptions. These assumptions are codified in the **family** and **form** of the model. For example

$$y = \beta_0 + \beta_1 x_1 + \beta_3 x_3 + \beta_5 x_5 + \epsilon$$

assumes that y is a linear combination of x_1 , x_3 , and x_5 as well as some noise. This assumes that the effect of x_1 on y is β_1 , which is the same for all values of x_3 and x_5 . That is, we are using the *family* of linear models with a particular *form*.

Suppose we then *fit* this model to some data and obtain the **fitted model**. For example, in R we would use

```
fit = lm(y ~ x1 + x3 + x5, data = some_data)
```

This is R's way of saying the *family* is *linear* and specifying the *form* from above. An additive model with the specified predictors as well as an intercept. We then obtain

$$\hat{y} = 1.5 + 0.9x_1 + 1.1x_3 + 2.3x_5.$$

This is our best guess for the function f in

$$y = f(x_1, x_2, x_3, \dots, x_{p-1}) + \epsilon$$

for the assumed **family** and **form**. Fitting a model only gives us the best fit for the family and form that we specify. So the natural question is; how do we choose the correct family and form? We'll focus on *form* since we are focusing on the *family* of linear models.

10.2 Explanation versus Prediction

What is the purpose of fitting a model to data? Usually it is to accomplish one of two goals. We can use a model to **explain** the relationship between the response and the predictors. Models can also be used to **predict** the response based on the predictors. Often, a good model will do both, but we'll discuss both goals separately since the process of finding models for explaining and predicting have some differences.

For our purposes, since we are only considering linear models, searching for a good model is essentially searching for a good **form** of a model.

10.2.1 Explanation

If the goal of a model is to explain the relationship between the response and the predictors, we are looking for a model that is **small** and **interpretable**, but still fits the data well. When discussing linear models, the **size** of a model is essentially the number of β parameters used.

Suppose we would like to find a model that explains fuel efficiency (`mpg`) based on a car's attributes (`wt`, `year`, `cyl`, `disp`, `hp`, `acc`). Perhaps we are a car manufacturer trying to engineer a fuel efficient vehicle. If this is the case, we are interested in both which predictor variables are useful for explaining the car's fuel efficiency, as well as how those variables effect fuel efficiency. By understanding this relationship, we can use this knowledge to our advantage when designing a car.

To explain a relationship, we are interested in keeping models as small as possible, since smaller models are easy to interpret. The fewer predictors the less considerations we need to make in our design process.

Note that *linear* models of any size are rather interpretable to begin with. Later in your data analysis careers, you will see more complicated models that may fit data better, but are much harder, if not impossible to interpret. These models aren't nearly as useful for explaining a relationship. This is another reason to always attempt a linear model. If it fits as well as more complicated methods, it will be the easiest to understand.

To find small and interpretable models, we will eventually use selection procedures, which search among many possible forms of a model. For now we will do this in a more ad-hoc manner using **inference** techniques we have already encountered. To use inference as we have seen it, we need an additional assumption in addition to the family and form of the model.

$$y = \beta_0 + \beta_1 x_1 + \beta_3 x_3 + \beta_5 x_5 + \epsilon$$

Our additional assumption is about the error term.

$$\epsilon \sim N(0, \sigma^2)$$

This assumption, that the errors are normally distributed with some common variance is the key to all of the inference we have done so far. We will discuss this in great detail later.

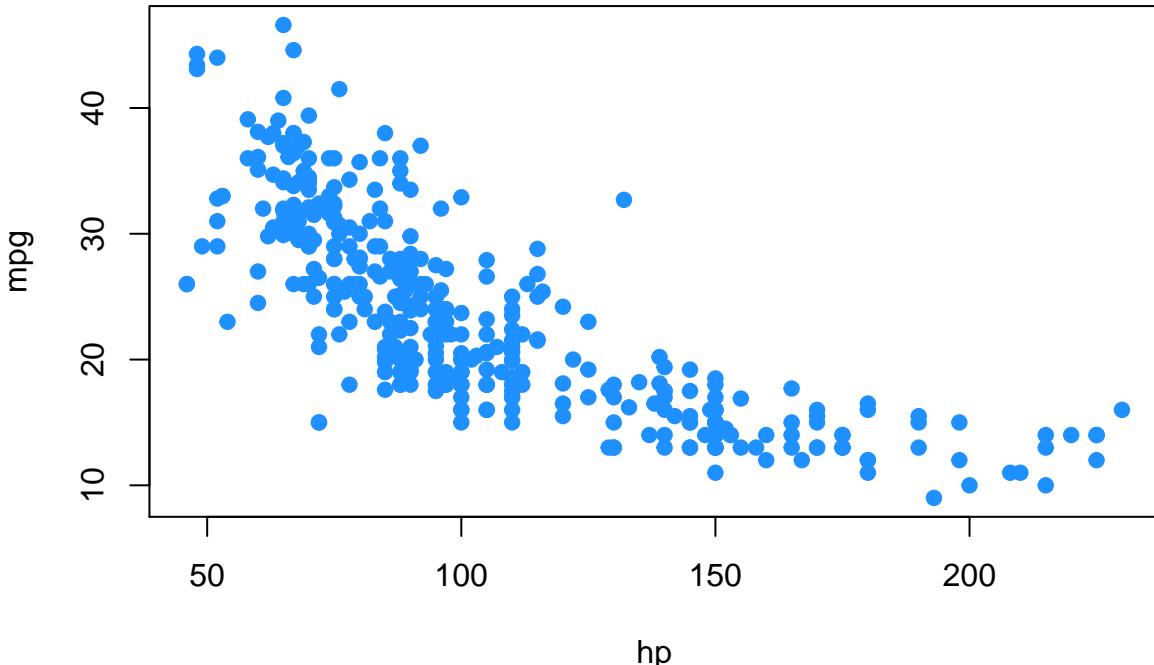
So with our inference tools (ANOVA and *t*-test) we have two potential strategies. Start with a very small model (no predictors) and attempt to add predictors. Or, start with a big model (all predictors) and attempt to remove predictors.

10.2.1.1 Correlation and Causation

A word of caution when using a model to *explain* a relationship. There are two terms often used to describe a relationship between two variables: *causation* and *correlation*. Correlation is often also referred to as association.

Just because two variables are correlated does not necessarily mean that one causes the other. For example, consider modeling `mpg` as only a function of `hp`.

```
plot(mpg ~ hp, data = autompg, col = "dodgerblue", pch = 20, cex = 1.5)
```



Does an increase in horsepower cause a drop in fuel efficiency? Or, perhaps the causality is reversed and an increase in fuel efficiency cause a decrease in horsepower. Or, perhaps there is a third variable that explains both!

The issue here is that we have **observational** data. With observational data, we can only detect *associations*. To speak with confidence about *causality*, we would need to run **experiments**. Often, this decision is made for us, before we ever see data, so we can only modify our interpretation.

This is a concept that you should encounter often in your statistics education. For some further reading, and some related fallacies, see: Wikipedia: Correlation does not imply causation.

We'll discuss this further when we discuss experimental design and traditional ANOVA techniques. (All of which has recently been re-branded as A/B testing.)

10.2.2 Prediction

If the goal of a model is to predict the response, then the **only** consideration is how well the model fits the data. For this, we will need a metric. In regression problems, this is most often RMSE.

$$\text{RMSE}(\text{model, data}) = \sqrt{\frac{1}{n} \sum_{i=1}^n (y_i - \hat{y}_i)^2}$$

where

- y_i are the actual values of the response for the given data
- \hat{y}_i are the predicted values using the fitted model and the predictors from the data

Correlation and causation are *not* an issue here. If a predictor is correlated with the response, it is useful for prediction. For example, in elementary school aged children their shoe size certainly doesn't *cause* them to read at a higher level, however we could very easily use shoe size to make a prediction about a child's reading ability. The larger their shoe size, the better they read. There's a lurking variable here though, their age! (Don't send your kids to school with size 14 shoes, it won't make them read better!)

Also, since we are not performing inference, the extra assumption about the errors is not needed. The only thing we care about is how close the fitted model is to the data. Least squares is least squares. For a specified model, it will find the values of the parameters which will minimize the squared error loss. Your results might be largely uninterpretable and useless for inference, but for prediction none of that matters.

Suppose instead of the manufacturer who would like to build a car, we are a consumer who wishes to purchase a new car. However this particular car is so new, it has not been rigorously tested, so we are unsure of what fuel efficiency to expect. (And, as skeptics, we don't trust what the manufacturer is telling us.) In this case, we would like to use the model to help *predict* the fuel efficiency of this car based on its attributes, which are the predictors of the model. The smaller the errors the model makes, the more confident we are in its prediction.

10.2.2.1 Test-Train Split

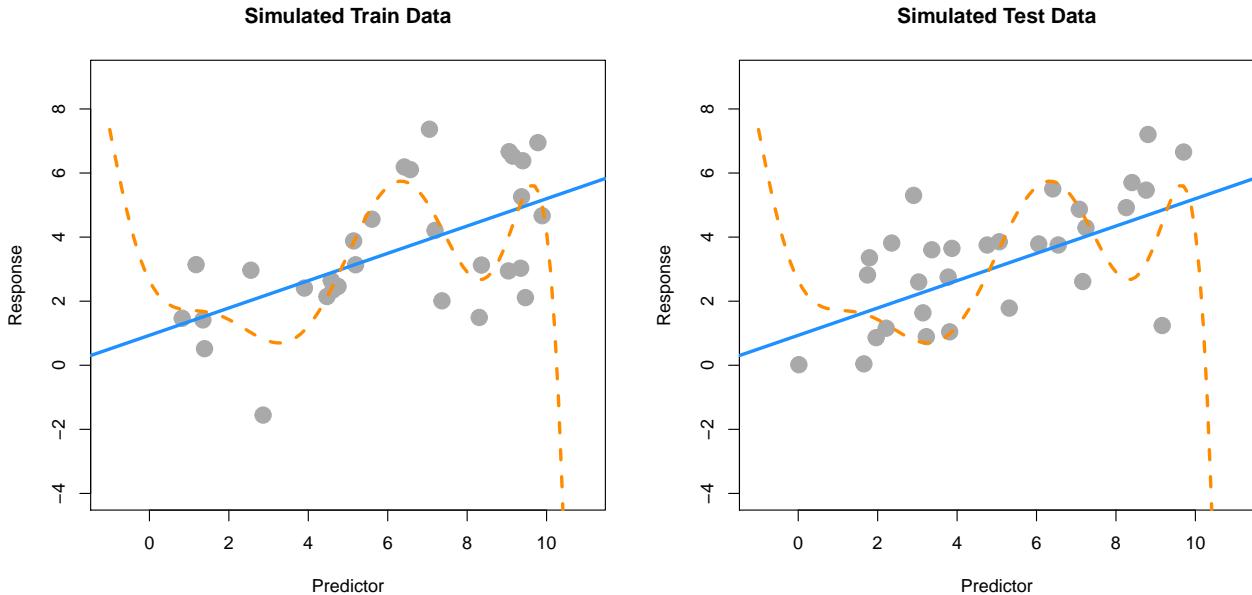
The trouble with using RMSE to identify how well a model fits data, is that RMSE is **always** (equal or) lower for a larger model. This would suggest that we should always use the largest model possible when looking for a model that predicts well. The problem with this is the potential to **overfit** to the data. So, we want a model that fits well, but does not overfit. To understand overfitting, we need to think about applying a model to seen and unseen data.

Suppose we fit a model using all data available and we evaluate RMSE on this fitted model and all of the seen data. We will call this data the **training** data, and this RMSE the **train RMSE**.

Now, suppose we magically encounter some additional additional data. To truly asses how well the model predicts, we should evaluate how well our models predicts the response of this data. We will call this data the **test** data and this RMSE the **test RMSE**.

- Train RMSE: model fit on seen data, evaluated on seen data
- Test RMSE: model fit on seen data, evaluated on **unseen** data

Below, we simulate some data and fit two models. We will call the solid blue line the “simple” model. The dashed orange line will be called the “complex” model, which was fit with methods we do not yet know.



The left panel shows the data that was used to fit the two models. Clearly the “complex” model fits the data much better. The right panel shows additional data that was simulated in the same manner as the original data. Here we see that the “simple” model fits much better. The dashed orange line almost seems random.

Model	Train RMSE	Test RMSE
Simple	1.71	1.45
Complex	1.41	2.07

The more “complex”, wiggly, model fits the training data much better as it has a much lower train RMSE. However, we see that the “simple” model fits the test data much better, with a much lower test RMSE. This means that the complex model has *overfit* the data, and we prefer the simple model. When choosing a model for prediction, we prefer a model that predicts unseen data.

In practice, you can't simply generate more data to evaluate your models. Instead we split existing data into data used to fit the model (train) and data used to evaluate the model (test). Never fit a model with test data.

10.3 Summary

Models can be used to **explain** relationships and **predict** observations.

When using model to,

- **explain**; we prefer *small* and *interpretable* models.
- **predict**; we prefer models that make the smallest errors possible, without *overfitting*.

Linear models can accomplish both these goals. Later, we will see that often a linear model that accomplishes one of these goals, usually accomplishes the other.

Chapter 11

Categorical Predictors and Interactions

“The greatest value of a picture is when it forces us to notice what we never expected to see.”

— John Tukey

After reading this chapter you will be able to:

- Include and interpret categorical variables in a linear regression model by way of dummy variables.
- Understand the implications of using a model with a categorical variable in two ways: levels serving as unique predictors versus levels serving as a comparison to a baseline.
- Construct and interpret linear regression models with interaction terms.
- Identify categorical variables in a data set and convert them into factor variables, if necessary, using R.

So far in each of our analyses, we have only used numeric variables as predictors. We have also only used *additive models*, meaning the effect any predictor had on the response was not dependent on the other predictors. In this chapter, we will remove both of these restrictions. We will fit models with categorical predictors, and use models that allow predictors to *interact*. The mathematics of multiple regression will remain largely unchanging, however, we will pay close attention to interpretation, as well as some difference in R usage.

11.1 Dummy Variables

For this chapter, we will briefly use the built in dataset `mtcars` before returning to our `autompg` dataset that we created in the last chapter. The `mtcars` dataset is somewhat smaller, so we'll quickly take a look at the entire dataset.

```
mtcars
```

```
##          mpg cyl  disp  hp drat    wt  qsec vs am gear carb
## Mazda RX4     21.0   6 160.0 110 3.90 2.620 16.46  0  1    4    4
## Mazda RX4 Wag 21.0   6 160.0 110 3.90 2.875 17.02  0  1    4    4
## Datsun 710    22.8   4 108.0  93 3.85 2.320 18.61  1  1    4    1
## Hornet 4 Drive 21.4   6 258.0 110 3.08 3.215 19.44  1  0    3    1
```

```

## Hornet Sportabout 18.7   8 360.0 175 3.15 3.440 17.02 0 0 3 2
## Valiant          18.1   6 225.0 105 2.76 3.460 20.22 1 0 3 1
## Duster 360       14.3   8 360.0 245 3.21 3.570 15.84 0 0 3 4
## Merc 240D        24.4   4 146.7  62 3.69 3.190 20.00 1 0 4 2
## Merc 230          22.8   4 140.8  95 3.92 3.150 22.90 1 0 4 2
## Merc 280          19.2   6 167.6 123 3.92 3.440 18.30 1 0 4 4
## Merc 280C         17.8   6 167.6 123 3.92 3.440 18.90 1 0 4 4
## Merc 450SE        16.4   8 275.8 180 3.07 4.070 17.40 0 0 3 3
## Merc 450SL        17.3   8 275.8 180 3.07 3.730 17.60 0 0 3 3
## Merc 450SLC       15.2   8 275.8 180 3.07 3.780 18.00 0 0 3 3
## Cadillac Fleetwood 10.4   8 472.0 205 2.93 5.250 17.98 0 0 3 4
## Lincoln Continental 10.4   8 460.0 215 3.00 5.424 17.82 0 0 3 4
## Chrysler Imperial  14.7   8 440.0 230 3.23 5.345 17.42 0 0 3 4
## Fiat 128           32.4   4  78.7  66 4.08 2.200 19.47 1 1 4 1
## Honda Civic         30.4   4  75.7  52 4.93 1.615 18.52 1 1 4 2
## Toyota Corolla     33.9   4  71.1  65 4.22 1.835 19.90 1 1 4 1
## Toyota Corona      21.5   4 120.1  97 3.70 2.465 20.01 1 0 3 1
## Dodge Challenger    15.5   8 318.0 150 2.76 3.520 16.87 0 0 3 2
## AMC Javelin         15.2   8 304.0 150 3.15 3.435 17.30 0 0 3 2
## Camaro Z28          13.3   8 350.0 245 3.73 3.840 15.41 0 0 3 4
## Pontiac Firebird    19.2   8 400.0 175 3.08 3.845 17.05 0 0 3 2
## Fiat X1-9            27.3   4  79.0  66 4.08 1.935 18.90 1 1 4 1
## Porsche 914-2        26.0   4 120.3  91 4.43 2.140 16.70 0 1 5 2
## Lotus Europa          30.4   4  95.1 113 3.77 1.513 16.90 1 1 5 2
## Ford Pantera L       15.8   8 351.0 264 4.22 3.170 14.50 0 1 5 4
## Ferrari Dino          19.7   6 145.0 175 3.62 2.770 15.50 0 1 5 6
## Maserati Bora         15.0   8 301.0 335 3.54 3.570 14.60 0 1 5 8
## Volvo 142E            21.4   4 121.0 109 4.11 2.780 18.60 1 1 4 2

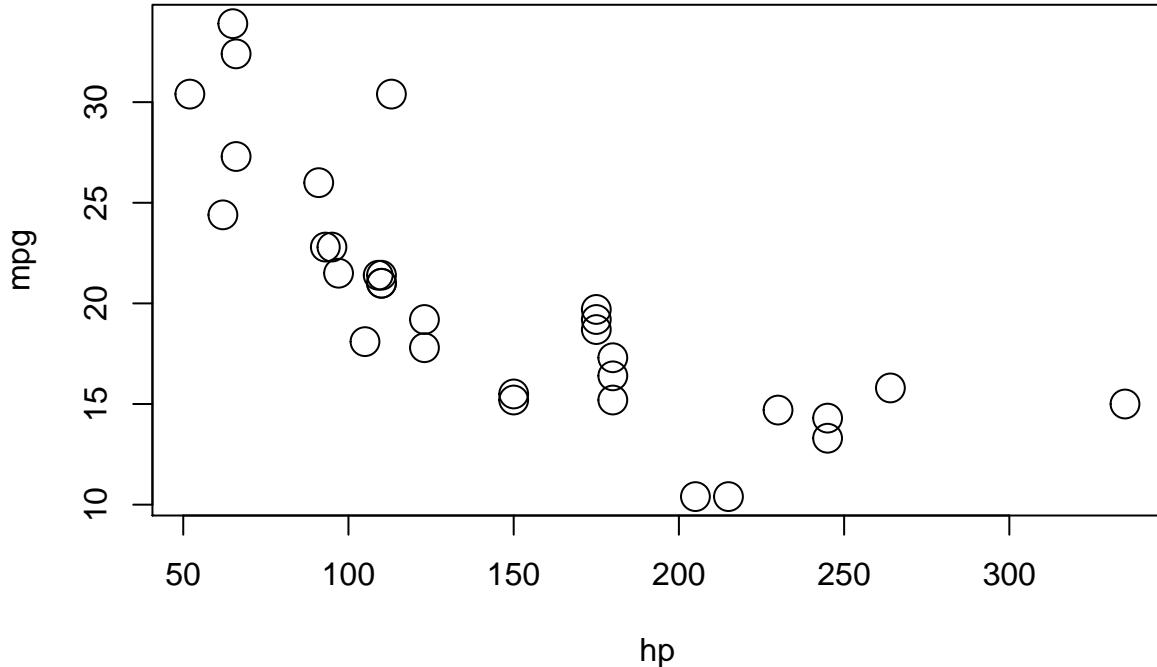
```

We will be interested in three of the variables: `mpg`, `hp`, and `am`.

- `mpg`: fuel efficiency, in miles per gallon.
- `hp`: horsepower, in foot-pounds per second.
- `am`: transmission. Automatic or manual.

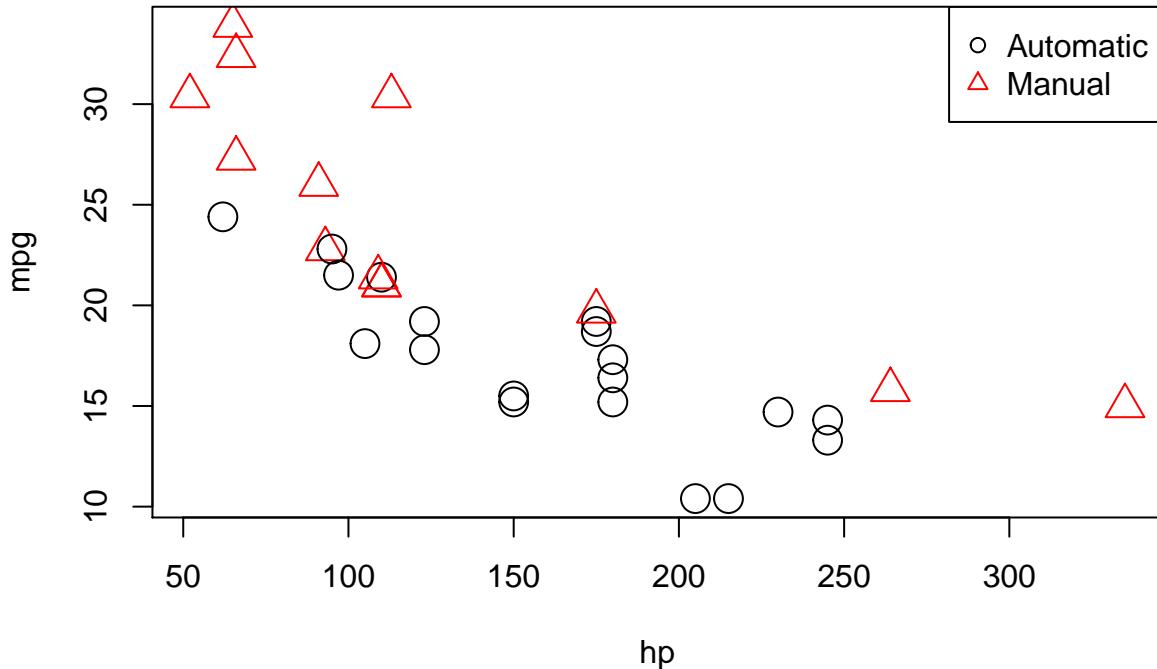
As we often do, we will start by plotting the data. We are interested in `mpg` as the response variable, and `hp` as a predictor.

```
plot(mpg ~ hp, data = mtcars, cex = 2)
```



Since we are also interested in the transmission type, we could also label the points accordingly.

```
plot(mpg ~ hp, data = mtcars, col = am + 1, pch = am + 1, cex = 2)
legend("topright", c("Automatic", "Manual"), col = c(1, 2), pch = c(1, 2))
```



We used a common R “trick” when plotting this data. The `am` variable takes two possible values; 0 for automatic transmission, and 1 for manual transmissions. R can use numbers to represent colors, however the color for 0 is white. So we take the `am` vector and add 1 to it. Then observations with automatic transmissions are now represented by 1, which is black in R, and manual transmission are represented by 2, which is red in R. (Note, we are only adding 1 inside the call to `plot()`, we are not actually modifying the values stored in `am`.)

We now fit the SLR model

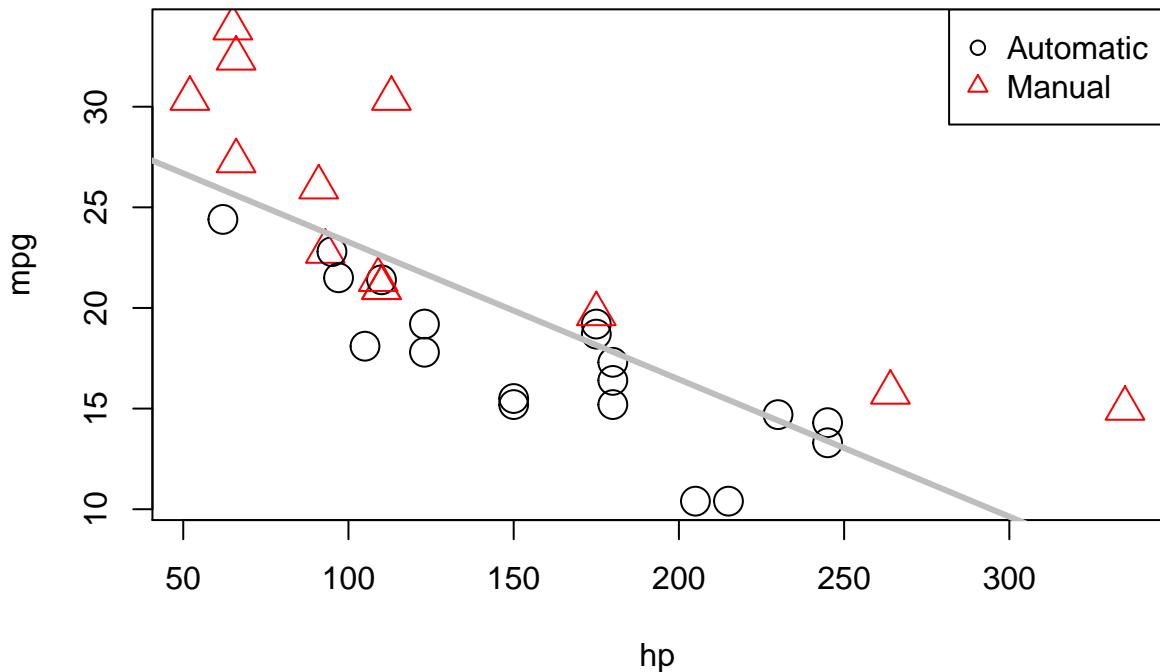
$$Y = \beta_0 + \beta_1 x_1 + \epsilon,$$

where Y is `mpg` and x_1 is `hp`. For notational brevity, we drop the index i for observations.

```
mpg_hp_slr = lm(mpg ~ hp, data = mtcars)
```

We then re-plot the data and add the fitted line to the plot.

```
plot(mpg ~ hp, data = mtcars, col = am + 1, pch = am + 1, cex = 2)
abline(mpg_hp_slr, lwd = 3, col = "grey")
legend("topright", c("Automatic", "Manual"), col = c(1, 2), pch = c(1, 2))
```



We should notice a pattern here. The red, manual observations largely fall above the line, while the black, automatic observations are mostly below the line. This means our model underestimates the fuel efficiency of manual transmissions, and overestimates the fuel efficiency of automatic transmissions. To correct for this, we will add a predictor to our model, namely, `am` as x_2 .

Our new model is

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \epsilon,$$

where x_1 and Y remain the same, but now

$$x_2 = \begin{cases} 1 & \text{manual transmission} \\ 0 & \text{automatic transmission} \end{cases}.$$

In this case, we call x_2 a **dummy variable**. A dummy variable is somewhat unfortunately named, as it is in no way “dumb”. In fact, it is actually somewhat clever. A dummy variable is a numerical variable that is used in a regression analysis to “code” for a binary categorical variable. Let’s see how this works.

First, note that `am` is already a dummy variable, since it uses the values 0 and 1 to represent automatic and manual transmissions. Often, a variable like `am` would store the character values `auto` and `man` and we would either have to convert these to 0 and 1, or, as we will see later, R will take care of creating dummy variables for us.

So, to fit the above model, we do so like any other multiple regression model we have seen before.

```
mpg_hp_add = lm(mpg ~ hp + am, data = mtcars)
```

Briefly checking the output, we see that R has estimated the three β parameters.

```
mpg_hp_add
```

```
##  
## Call:  
## lm(formula = mpg ~ hp + am, data = mtcars)  
##  
## Coefficients:  
## (Intercept)          hp          am  
##     26.58491     -0.05889      5.27709
```

Since x_2 can only take values 0 and 1, we can effectively write two different models, one for manual and one for automatic transmissions.

For automatic transmissions, that is $x_2 = 0$, we have,

$$Y = \beta_0 + \beta_1 x_1 + \epsilon.$$

Then for manual transmissions, that is $x_2 = 1$, we have,

$$Y = (\beta_0 + \beta_2) + \beta_1 x_1 + \epsilon.$$

Notice that these models share the same slope, β_1 , but have different intercepts, differing by β_2 . So the change in `mpg` is the same for both models, but on average `mpg` differs by β_2 between the two transmission types.

We'll now calculate the estimated slope and intercept of these two models so that we can add them to a plot. Note that:

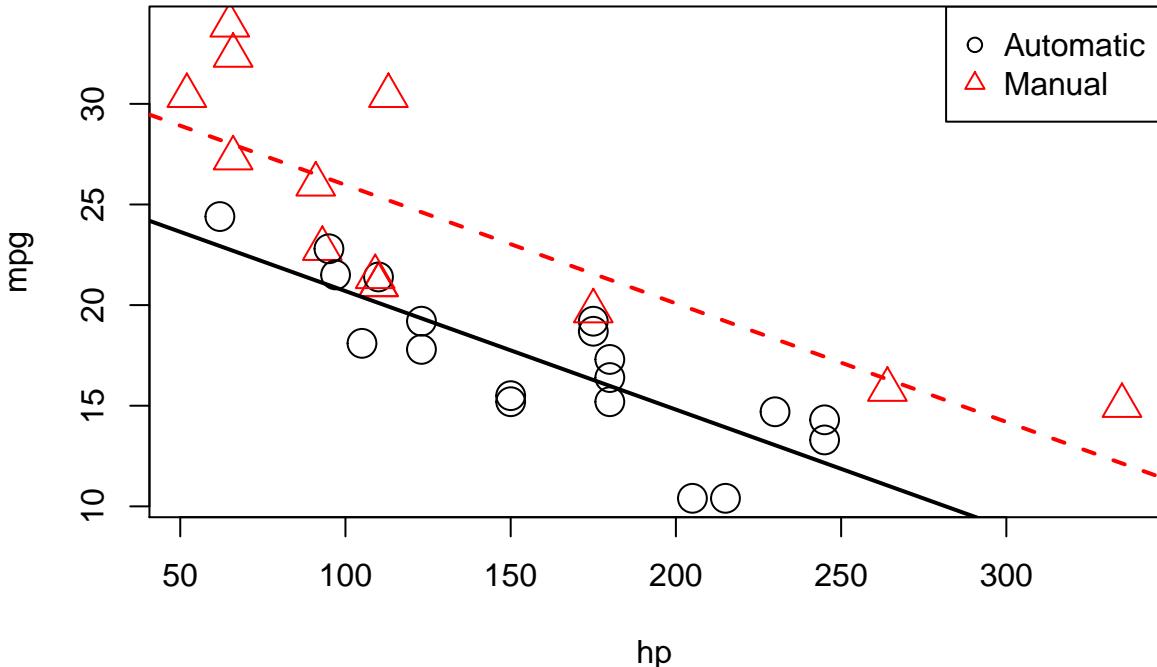
- $\hat{\beta}_0 = \text{coef}(\text{mpg_hp_add})[1] = 26.5849137$
- $\hat{\beta}_1 = \text{coef}(\text{mpg_hp_add})[2] = -0.0588878$
- $\hat{\beta}_2 = \text{coef}(\text{mpg_hp_add})[3] = 5.2770853$

We can then combine these to calculate the estimated slope and intercepts.

```
int_auto = coef(mpg_hp_add)[1]  
int_manu = coef(mpg_hp_add)[1] + coef(mpg_hp_add)[3]  
  
slope_auto = coef(mpg_hp_add)[2]  
slope_manu = coef(mpg_hp_add)[2]
```

Re-plotting the data, we use these slopes and intercepts to add the “two” fitted models to the plot.

```
plot(mpg ~ hp, data = mtcars, col = am + 1, pch = am + 1, cex = 2)
abline(int_auto, slope_auto, col = 1, lty = 1, lwd = 2) # add line for auto
abline(int_manu, slope_manu, col = 2, lty = 2, lwd = 2) # add line for manual
legend("topright", c("Automatic", "Manual"), col = c(1, 2), pch = c(1, 2))
```



We notice right away that the points are no longer systematically incorrect. The red, manual observations vary about the red line in no particular pattern without underestimating the observations as before. The black, automatic points vary about the black line, also without an obvious pattern.

They say a picture is worth a thousand words, but as a statistician, sometimes a picture is worth an entire analysis. The above picture makes it plainly obvious that β_2 is significant, but let's verify mathematically. Essentially we would like to test:

$$H_0 : \beta_2 = 0 \quad \text{vs} \quad H_1 : \beta_2 \neq 0.$$

This is nothing new. Again, the math is the same as the multiple regression analyses we have seen before. We could perform either a t or F test here. The only difference is a slight change in interpretation. We could think of this as testing a model with a single line (H_0) against a model that allows two lines (H_1).

To obtain the test statistic and p-value for the t -test, we would use

```
summary(mpg_hp_add)$coefficients["am",]
```

```
##      Estimate    Std. Error     t value   Pr(>|t|) 
## 5.27708530818 1.07954057578 4.88826953480 0.00003460318
```

To do the same for the F test, we would use

```
anova(mpg_hp_slr, mpg_hp_add)
```

```

## Analysis of Variance Table
##
## Model 1: mpg ~ hp
## Model 2: mpg ~ hp + am
##   Res.Df   RSS Df Sum of Sq    F    Pr(>F)
## 1     30 447.67
## 2     29 245.44  1    202.24 23.895 0.0000346 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

```

Notice that these are indeed testing the same thing, as the p-values are exactly equal. (And the F test statistic is the t test statistic squared.)

Recapping some interpretations:

- $\hat{\beta}_0 = 26.5849137$ is the estimated average `mpg` for a car with an automatic transmission and **0 hp**.
- $\hat{\beta}_0 + \hat{\beta}_2 = 31.8619991$ is the estimated average `mpg` for a car with a manual transmission and **0 hp**.
- $\hat{\beta}_2 = 5.2770853$ is the estimated **difference** in average `mpg` for cars with manual transmissions as compared to those with automatic transmission, for **any hp**.
- $\hat{\beta}_1 = -0.0588878$ is the estimated change in average `mpg` for an increase in one `hp`, for **either** transmission types.

We should take special notice of those last two. In the model,

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \epsilon,$$

we see β_1 is the average change in Y for an increase in x_1 , *no matter* the value of x_2 . Also, β_2 is always the difference in the average of Y for *any* value of x_1 . These are two restrictions we won't always want, so we need a way to specify a more flexible model.

Here we restricted ourselves to a single numerical predictor x_1 and one dummy variable x_2 . However, the concept of a dummy variable can be used with larger multiple regression models. We only use a single numerical predictor here for ease of visualization since we can think of the “two lines” interpretation. But in general, we can think of a dummy variable as creating “two models,” one for each category of a binary categorical variable.

11.2 Interactions

To remove the “same slope” restriction, we will now discuss **interaction**. To illustrate this concept, we will return to the `autompq` dataset we created in the last chapter, with a few more modifications.

```

# read data frame from the web
autompq = read.table(
  "http://archive.ics.uci.edu/ml/machine-learning-databases/auto-mpg/auto-mpg.data",
  quote = "\"",
  comment.char = "",
  stringsAsFactors = FALSE)
# give the dataframe headers
colnames(autompq) = c("mpg", "cyl", "disp", "hp", "wt", "acc", "year", "origin", "name")
# remove missing data, which is stored as "?"

```

```

autompq = subset(autompq, autompq$hp != "?")
# remove the plymouth reliant, as it causes some issues
autompq = subset(autompq, autompq$name != "plymouth reliant")
# give the dataset row names, based on the engine, year and name
rownames(autompq) = paste(autompq$cyl, "cylinder", autompq$year, autompq$name)
# remove the variable for name
autompq = subset(autompq, select = c("mpg", "cyl", "disp", "hp", "wt", "acc", "year", "origin"))
# change horsepower from character to numeric
autompq$hp = as.numeric(autompq$hp)
# create a summary variable for foreign vs domestic cars. domestic = 1.
autompq$domestic = as.numeric(autompq$origin == 1)
# remove 3 and 5 cylinder cars (which are very rare.)
autompq = autompq[autompq$cyl != 5,]
autompq = autompq[autompq$cyl != 3,]
# the following line would verify the remaining cylinder possibilities are 4, 6, 8
#unique(autompq$cyl)
# change cyl to a factor variable
autompq$cyl = as.factor(autompq$cyl)

```

```
str(autompq)
```

```

## 'data.frame':   383 obs. of  9 variables:
## $ mpg      : num  18 15 18 16 17 15 14 14 14 15 ...
## $ cyl      : Factor w/ 3 levels "4","6","8": 3 3 3 3 3 3 3 3 3 3 ...
## $ disp     : num  307 350 318 304 302 429 454 440 455 390 ...
## $ hp       : num  130 165 150 150 140 198 220 215 225 190 ...
## $ wt       : num  3504 3693 3436 3433 3449 ...
## $ acc      : num  12 11.5 11 12 10.5 10 9 8.5 10 8.5 ...
## $ year     : int  70 70 70 70 70 70 70 70 70 70 ...
## $ origin   : int  1 1 1 1 1 1 1 1 1 1 ...
## $ domestic: num  1 1 1 1 1 1 1 1 1 1 ...

```

We've removed cars with 3 and 5 cylinders , as well as created a new variable `domestic` which indicates whether or not a car was built in the United States. Removing the 3 and 5 cylinders is simply for ease of demonstration later in the chapter and would not be done in practice. The new variable `domestic` takes the value 1 if the car was built in the United States, and 0 otherwise, which we will refer to as "foreign." (We are arbitrarily using the United States as the reference point here.) We have also made `cyl` and `origin` into factor variables, which we will discuss later.

We'll now be concerned with three variables: `mpg`, `disp`, and `domestic`. We will use `mpg` as the response. We can fit a model,

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \epsilon,$$

where

- Y is `mpg`, the fuel efficiency in miles per gallon,
- x_1 is `disp`, the displacement in cubic inches,
- x_2 is `domestic` as described above, which is a dummy variable.

$$x_2 = \begin{cases} 1 & \text{Domestic} \\ 0 & \text{Foreign} \end{cases}$$

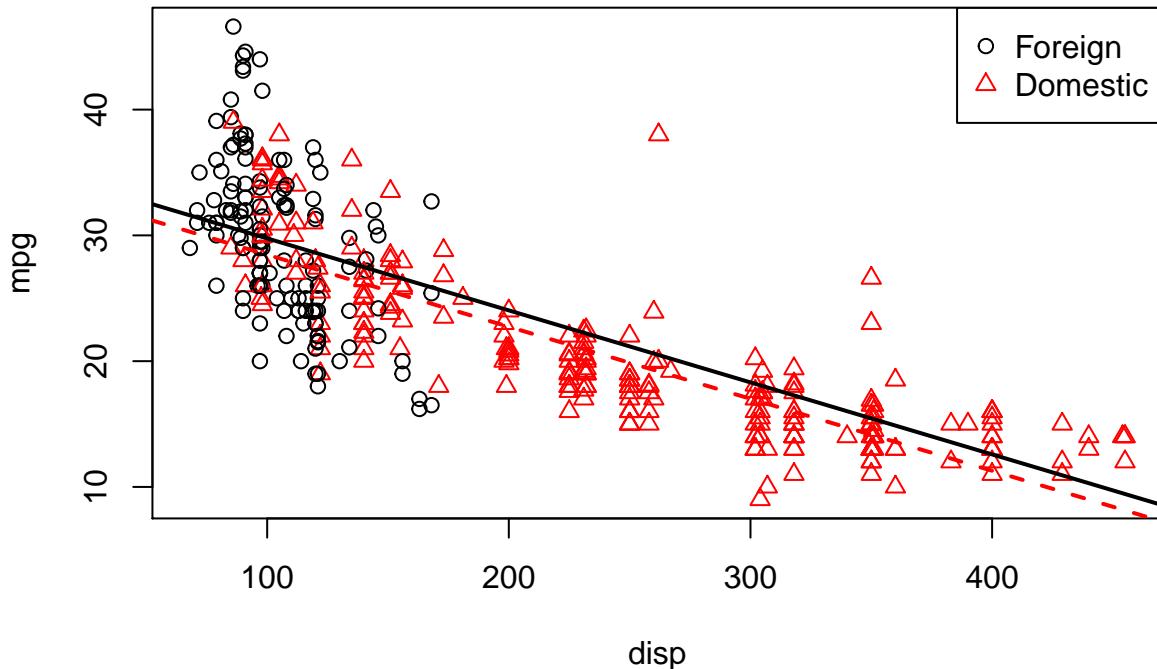
We will fit this model, extract the slope and intercept for the “two lines,” plot the data and add the lines.

```
mpg_disp_add = lm(mpg ~ disp + domestic, data = autompg)

int_for = coef(mpg_disp_add)[1]
int_dom = coef(mpg_disp_add)[1] + coef(mpg_disp_add)[3]

slope_for = coef(mpg_disp_add)[2]
slope_dom = coef(mpg_disp_add)[2]

plot(mpg ~ disp, data = autompg, col = domestic + 1, pch = domestic + 1)
abline(int_for, slope_for, col = 1, lty = 1, lwd = 2) # add line for foreign cars
abline(int_dom, slope_dom, col = 2, lty = 2, lwd = 2) # add line for domestic cars
legend("topright", c("Foreign", "Domestic"), pch = c(1, 2), col = c(1, 2))
```



This is a model that allows for two *parallel* lines, meaning the `mpg` can be different on average between foreign and domestic cars of the same engine displacement, but the change in average `mpg` for an increase in displacement is the same for both. We can see this model isn't doing very well here. The red line fits the red points fairly well, but the black line isn't doing very well for the black points, it should clearly have a more negative slope. Essentially, we would like a model that allows for two different slopes.

Consider the following model,

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_1 x_2 + \epsilon,$$

where x_1 , x_2 , and Y are the same as before, but we have added a new **interaction** term $x_1 x_2$ which multiplies x_1 and x_2 , so we also have an additional β parameter β_3 .

This model essentially creates two slopes and two intercepts, β_2 being the difference in intercepts and β_3 being the difference in slopes. To see this, we will break down the model into the two “sub-models” for foreign and domestic cars.

For foreign cars, that is $x_2 = 0$, we have

$$Y = \beta_0 + \beta_1 x_1 + \epsilon.$$

For domestic cars, that is $x_2 = 1$, we have

$$Y = (\beta_0 + \beta_2) + (\beta_1 + \beta_3)x_1 + \epsilon.$$

These two models have both different slopes and intercepts.

- β_0 is the average mpg for a foreign car with **0** disp.
- β_1 is the change in average mpg for an increase of one disp, for **foreign** cars.
- $\beta_0 + \beta_2$ is the average mpg for a domestic car with **0** disp.
- $\beta_1 + \beta_3$ is the change in average mpg for an increase of one disp, for **domestic** cars.

How do we fit this model in R? There are a number of ways.

One method would be to simply create a new variable, then fit a model like any other.

```
autompq$x3 = autompq$disp * autompq$domestic # THIS CODE NOT RUN!
do_not_do_this = lm(mpg ~ disp + domestic + x3, data = autompq) # THIS CODE NOT RUN!
```

You should only do this as a last resort. We greatly prefer not to have to modify our data simply to fit a model. Instead, we can tell R we would like to use the existing data with an interaction term, which it will create automatically when we use the : operator.

```
mpg_disp_int = lm(mpg ~ disp + domestic + disp:domestic, data = autompq)
```

An alternative method, which will fit the exact same model as above would be to use the * operator. This method automatically creates the interaction term, as well as any “lower order terms,” which in this case are the first order terms for disp and domestic

```
mpg_disp_int2 = lm(mpg ~ disp * domestic, data = autompq)
```

We can quickly verify that these are doing the same thing.

```
coef(mpg_disp_int)
```

```
## (Intercept)      disp      domestic disp:domestic
## 46.0548423 -0.1569239 -12.5754714   0.1025184
```

```
coef(mpg_disp_int2)
```

```
## (Intercept)      disp      domestic disp:domestic
## 46.0548423 -0.1569239 -12.5754714   0.1025184
```

We see that both the variables, and their coefficient estimates are indeed the same for both models.

```
summary(mpg_disp_int)
```

```

## 
## Call:
## lm(formula = mpg ~ disp + domestic + disp:domestic, data = autompg)
## 
## Residuals:
##       Min     1Q   Median     3Q    Max 
## -10.8332 -2.8956 -0.8332  2.2828 18.7749 
## 
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)    
## (Intercept) 46.05484   1.80582  25.504 < 2e-16 ***
## disp        -0.15692   0.01668  -9.407 < 2e-16 *** 
## domestic     -12.57547  1.95644  -6.428 3.90e-10 *** 
## disp:domestic  0.10252   0.01692   6.060 3.29e-09 *** 
## --- 
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1 
## 
## Residual standard error: 4.308 on 379 degrees of freedom 
## Multiple R-squared:  0.7011, Adjusted R-squared:  0.6987 
## F-statistic: 296.3 on 3 and 379 DF,  p-value: < 2.2e-16

```

We see that using `summary()` gives the usual output for a multiple regression model. We pay close attention to the row for `disp:domestic` which tests,

$$H_0 : \beta_3 = 0.$$

In this case, testing for $\beta_3 = 0$ is testing for two lines with parallel slopes versus two lines with possibly different slopes. The `disp:domestic` line in the `summary()` output uses a *t*-test to perform the test.

We could also use an ANOVA *F*-test. The additive model, without interaction is our null model, and the interaction model is the alternative.

```
anova(mpg_disp_add, mpg_disp_int)
```

```

## Analysis of Variance Table
## 
## Model 1: mpg ~ disp + domestic
## Model 2: mpg ~ disp + domestic + disp:domestic
##   Res.Df   RSS Df Sum of Sq    F    Pr(>F)    
## 1     380 7714.0
## 2     379 7032.6  1   681.36 36.719 3.294e-09 ***
## --- 
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

```

Again we see this test has the same p-value as the *t*-test. Also the p-value is extremely low, so between the two, we choose the interaction model.

```

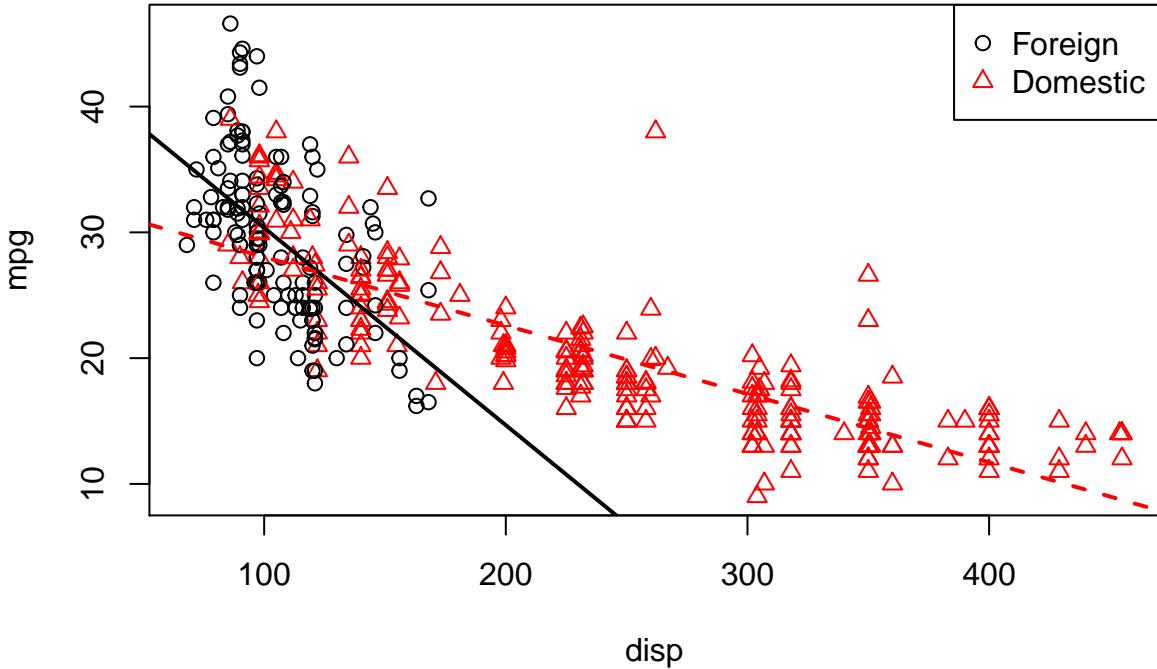
int_for = coef(mpg_disp_int)[1]
int_dom = coef(mpg_disp_int)[1] + coef(mpg_disp_int)[3]

slope_for = coef(mpg_disp_int)[2]
slope_dom = coef(mpg_disp_int)[2] + coef(mpg_disp_int)[4]

```

Here we again calculate the slope and intercepts for the two lines for use in plotting.

```
plot(mpg ~ disp, data = autompg, col = domestic + 1, pch = domestic + 1)
abline(int_for, slope_for, col = 1, lty = 1, lwd = 2) # line for foreign cars
abline(int_dom, slope_dom, col = 2, lty = 2, lwd = 2) # line for domestic cars
legend("topright", c("Foreign", "Domestic"), pch = c(1, 2), col = c(1, 2))
```



We see that these lines fit the data much better, which matches the result of our tests.

So far we have only seen interaction between a categorical variable (`domestic`) and a numerical variable (`disp`). While this is easy to visualize, since it allows for different slopes for two lines, it is not the only type of interaction we can use in a model. We can also consider interactions between two numerical variables.

Consider the model,

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_1 x_2 + \epsilon,$$

where

- Y is `mpg`, the fuel efficiency in miles per gallon,
- x_1 is `disp`, the displacement in cubic inches,
- x_2 is `hp`, the horsepower, in foot-pounds per second.

How does `mpg` change based on `disp` in this model? We can rearrange some terms to see how.

$$Y = \beta_0 + (\beta_1 + \beta_3 x_2)x_1 + \beta_2 x_2 + \epsilon$$

So, for a one unit increase in x_1 (`disp`), the mean of Y (`mpg`) increases $\beta_1 + \beta_3 x_2$, which is a different value depending on the value of x_2 (`hp`)!

Since we're now working in three dimensions, this model can't be easily justified via visualizations like the previous example. Instead, we will have to rely on a test.

```

mpg_disp_add_hp = lm(mpg ~ disp + hp, data = autompg)
mpg_disp_int_hp = lm(mpg ~ disp * hp, data = autompg)
summary(mpg_disp_int_hp)

##
## Call:
## lm(formula = mpg ~ disp * hp, data = autompg)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -10.7849  -2.3104  -0.5699   2.1453  17.9211
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) 52.40819978  1.52272673  34.42 <2e-16 ***
## disp        -0.10017377  0.00663825 -15.09 <2e-16 ***
## hp          -0.21981997  0.01986944 -11.06 <2e-16 ***
## disp:hp      0.00056583  0.00005165   10.96 <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 3.896 on 379 degrees of freedom
## Multiple R-squared:  0.7554, Adjusted R-squared:  0.7535
## F-statistic: 390.2 on 3 and 379 DF,  p-value: < 2.2e-16

```

Using `summary()` we focus on the row for `disp:hp` which tests,

$$H_0 : \beta_3 = 0.$$

Again, we see a very low p-value so we reject the null (additive model) in favor of the interaction model. Again, there is an equivalent *F*-test.

```

anova(mpg_disp_add_hp, mpg_disp_int_hp)

##
## Analysis of Variance Table
##
## Model 1: mpg ~ disp + hp
## Model 2: mpg ~ disp * hp
##   Res.Df   RSS Df Sum of Sq    F    Pr(>F)
## 1     380 7576.6
## 2     379 5754.2  1    1822.3 120.03 < 2.2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

```

We can take a closer look at the coefficients of our fitted interaction model.

```

coef(mpg_disp_int_hp)

## (Intercept)          disp           hp         disp:hp
## 52.4081997848 -0.1001737655 -0.2198199720  0.0005658269

```

- $\hat{\beta}_0 = 52.4081998$ is the estimated average `mpg` for a car with 0 `disp` and 0 `hp`.
- $\hat{\beta}_1 = -0.1001738$ is the estimated change in average `mpg` for an increase in 1 `disp`, **for a car with 0 hp**.
- $\hat{\beta}_2 = -0.21982$ is the estimated change in average `mpg` for an increase in 1 `hp`, **for a car with 0 disp**.
- $\hat{\beta}_3 = 0.0005658$ is an estimate of the modification to the change in average `mpg` for an increase in `disp`, for a car of a certain `hp` (or vice versa).

That last coefficient needs further explanation. Recall the rearrangement we made earlier

$$Y = \beta_0 + (\beta_1 + \beta_3 x_2)x_1 + \beta_2 x_2 + \epsilon.$$

So, our estimate for $\beta_1 + \beta_3 x_2$, is $\hat{\beta}_1 + \hat{\beta}_3 x_2$, which in this case is

$$-0.1001738 + 0.0005658x_2.$$

This says that, for an increase of one `disp` we see an estimated change in average `mpg` of $-0.1001738 + 0.0005658x_2$. So how `disp` and `mpg` are related, depends on the `hp` of the car.

So for a car with 50 `hp`, the estimated change in average `mpg` for an increase of one `disp` is

$$-0.1001738 + 0.0005658 \cdot 50 = -0.0718824$$

And for a car with 350 `hp`, the estimated change in average `mpg` for an increase of one `disp` is

$$-0.1001738 + 0.0005658 \cdot 350 = 0.0978657$$

Notice the sign changed!

11.3 Factor Variables

So far in this chapter, we have limited our use of categorical variables to binary categorical variables. Specifically, we have limited ourselves to dummy variables which take a value of 0 or 1 and represent a categorical variable numerically.

We will now discuss **factor** variables, which is a special way that R deals with categorical variables. With factor variables, a human user can simply think about the categories of a variable, and R will take care of the necessary dummy variables without any 0/1 assignment being done by the user.

```
is.factor(autompq$domestic)
```

```
## [1] FALSE
```

Earlier when we used the `domestic` variable, it was **not** a factor variable. It was simply a numerical variable that only took two possible values, 1 for domestic, and 0 for foreign. Let's create a new variable `origin` that stores the same information, but in a different way.

```
autompq$origin[autompq$domestic == 1] = "domestic"
autompq$origin[autompq$domestic == 0] = "foreign"
head(autompq$origin)
```

```
## [1] "domestic" "domestic" "domestic" "domestic" "domestic" "domestic"
```

Now the `origin` variable stores "domestic" for domestic cars and "foreign" for foreign cars.

```
is.factor(autompq$origin)
```

```
## [1] FALSE
```

However, this is simply a vector of character values. A vector of car models is a character variable in R. A vector of Vehicle Identification Numbers (VINs) is a character variable as well. But those don't represent a short list of levels that might influence a response variable. We will want to **coerce** this origin variable to be something more: a factor variable.

```
autompq$origin = as.factor(autompq$origin)
```

Now when we check the structure of the `autompq` dataset, we see that `origin` is a factor variable.

```
str(autompq)
```

```
## 'data.frame':    383 obs. of  9 variables:
## $ mpg      : num  18 15 18 16 17 15 14 14 14 15 ...
## $ cyl      : Factor w/ 3 levels "4","6","8": 3 3 3 3 3 3 3 3 3 3 ...
## $ disp     : num  307 350 318 304 302 429 454 440 455 390 ...
## $ hp       : num  130 165 150 150 140 198 220 215 225 190 ...
## $ wt       : num  3504 3693 3436 3433 3449 ...
## $ acc      : num  12 11.5 11 12 10.5 10 9 8.5 10 8.5 ...
## $ year     : int  70 70 70 70 70 70 70 70 70 ...
## $ origin   : Factor w/ 2 levels "domestic","foreign": 1 1 1 1 1 1 1 1 1 ...
## $ domestic: num  1 1 1 1 1 1 1 1 1 1 ...
```

Factor variables have **levels** which are the possible values (categories) that the variable may take, in this case foreign or domestic.

```
levels(autompq$origin)
```

```
## [1] "domestic" "foreign"
```

Recall that previously we have fit the model

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_1 x_2 + \epsilon,$$

where

- Y is `mpg`, the fuel efficiency in miles per gallon,
- x_1 is `disp`, the displacement in cubic inches,
- x_2 is `domestic` a dummy variable where 1 indicates a domestic car.

```
(mod_dummy = lm(mpg ~ disp * domestic, data = autompg))
```

```
##  
## Call:  
## lm(formula = mpg ~ disp * domestic, data = autompg)  
##  
## Coefficients:  
## (Intercept) disp domestic disp:domestic  
## 46.0548  -0.1569  -12.5755   0.1025
```

So here we see that

$$\hat{\beta}_0 + \hat{\beta}_2 = 46.0548423 + -12.5754714 = 33.4793709$$

is the estimated average mpg for a **domestic** car with 0 disp.

Now let's try to do the same, but using our new factor variable.

```
(mod_factor = lm(mpg ~ disp * origin, data = autompg))
```

```
##  
## Call:  
## lm(formula = mpg ~ disp * origin, data = autompg)  
##  
## Coefficients:  
## (Intercept) disp originforeign disp:originforeign  
## 33.47937  -0.05441  12.57547   -0.10252
```

It seems that it doesn't produce the same results. Right away we notice that the intercept is different, as is the coefficient in front of disp. We also notice that the remaining two coefficients are of the same magnitude as their respective counterparts using the domestic variable, but with a different sign. Why is this happening?

It turns out, that by using a factor variable, R is automatically creating a dummy variable for us. However, it is not the dummy variable that we had originally used ourselves.

R is fitting the model

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_1 x_2 + \epsilon,$$

where

- Y is mpg, the fuel efficiency in miles per gallon,
- x_1 is disp, the displacement in cubic inches,
- x_2 is a **dummy variable created by R**. It uses 1 to represent a **foreign car**.

So now,

$$\hat{\beta}_0 = 33.4793709$$

is the estimated average mpg for a **domestic** car with 0 disp, which is indeed the same as before.

When R created x_2 , the dummy variable, it used domestic cars as the **reference** level, that is the default value of the factor variable. So when the dummy variable is 0, the model represents this reference level, which is domestic. (R makes this choice because domestic comes before foreign alphabetically.)

So the two models have different estimated coefficients, but due to the different model representations, they are actually the same model.

11.3.1 Factors with More Than Two Levels

Let's now consider a factor variable with more than two levels. In this dataset, cyl is an example.

```
is.factor(autompg$cyl)

## [1] TRUE

levels(autompg$cyl)

## [1] "4" "6" "8"
```

Here the cyl variable has three possible levels: 4, 6, and 8. You may wonder, why not simply use cyl as a numerical variable? You certainly could.

However, that would force the difference in average mpg between 4 and 6 cylinders to be the same as the difference in average mpg between 6 and 8 cylinders. That usually make sense for a continuous variable, but not for a discrete variable with so few possible values. In the case of this variable, there is no such thing as a 7-cylinder engine or a 6.23-cylinder engine in personal vehicles. For these reasons, we will simply consider cyl to be categorical. This is a decision that will commonly need to be made with ordinal variables. Often, with a large number of categories, the decision to treat them as numerical variables is appropriate because a large number of dummy variables are then needed to represent these variables.

Let's define three dummy variables related to the cyl factor variable.

$$v_1 = \begin{cases} 1 & 4 \text{ cylinder} \\ 0 & \text{not 4 cylinder} \end{cases}$$

$$v_2 = \begin{cases} 1 & 6 \text{ cylinder} \\ 0 & \text{not 6 cylinder} \end{cases}$$

$$v_3 = \begin{cases} 1 & 8 \text{ cylinder} \\ 0 & \text{not 8 cylinder} \end{cases}$$

Now, let's fit an additive model in R, using mpg as the response, and disp and cyl as predictors. This should be a model that uses “three regression lines” to model mpg, one for each of the possible cyl levels. They will all have the same slope (since it is an additive model), but each will have its own intercept.

```
(mpg_disp_add_cyl = lm(mpg ~ disp + cyl, data = autompg))
```

```
##
## Call:
## lm(formula = mpg ~ disp + cyl, data = autompg)
```

```
##
## Coefficients:
## (Intercept)      disp      cyl6      cyl8
## 34.99929     -0.05217    -3.63325    -2.03603
```

The question is, what is the model that R has fit here? It has chosen to use the model

$$Y = \beta_0 + \beta_1 x + \beta_2 v_2 + \beta_3 v_3 + \epsilon,$$

where

- Y is `mpg`, the fuel efficiency in miles per gallon,
- x is `disp`, the displacement in cubic inches,
- v_2 and v_3 are the dummy variables define above.

Why doesn't R use v_1 ? Essentially because it doesn't need to. To create three lines, it only needs two dummy variables since it is using a reference level, which in this case is a 4 cylinder car. The three "sub models" are then:

- 4 Cylinder: $Y = \beta_0 + \beta_1 x + \epsilon$
- 6 Cylinder: $Y = (\beta_0 + \beta_2) + \beta_1 x + \epsilon$
- 8 Cylinder: $Y = (\beta_0 + \beta_3) + \beta_1 x + \epsilon$

Notice that they all have the same slope. However, using the two dummy variables, we achieve the three intercepts.

- β_0 is the average `mpg` for a 4 cylinder car with 0 `disp`.
- $\beta_0 + \beta_2$ is the average `mpg` for a 6 cylinder car with 0 `disp`.
- $\beta_0 + \beta_3$ is the average `mpg` for a 8 cylinder car with 0 `disp`.

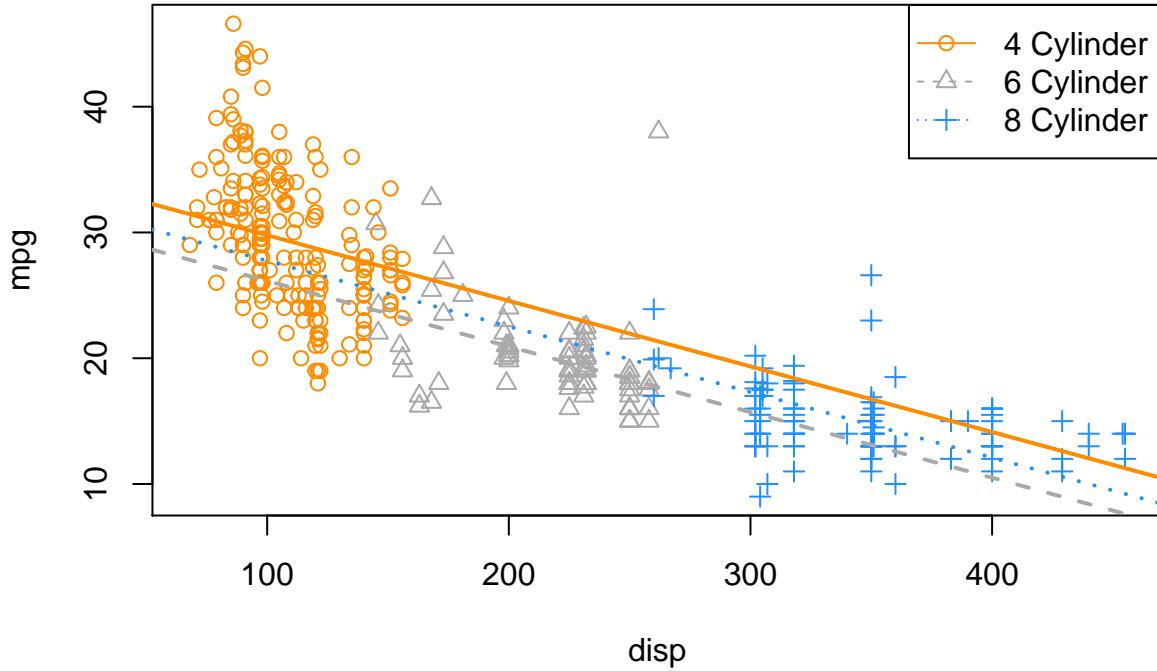
So because 4 cylinder is the reference level, β_0 is specific to 4 cylinders, but β_2 and β_3 are used to represent quantities relative to 4 cylinders.

As we have done before, we can extract these intercepts and slopes for the three lines, and plot them accordingly.

```
int_4cyl = coef(mpg_disp_add_cyl)[1]
int_6cyl = coef(mpg_disp_add_cyl)[1] + coef(mpg_disp_add_cyl)[3]
int_8cyl = coef(mpg_disp_add_cyl)[1] + coef(mpg_disp_add_cyl)[4]

slope_all_cyl = coef(mpg_disp_add_cyl)[2]

plot_colors = c("Darkorange", "Darkgrey", "Dodgerblue")
plot(mpg ~ disp, data = autompg, col = plot_colors[cyl], pch = as.numeric(cyl))
abline(int_4cyl, slope_all_cyl, col = plot_colors[1], lty = 1, lwd = 2)
abline(int_6cyl, slope_all_cyl, col = plot_colors[2], lty = 2, lwd = 2)
abline(int_8cyl, slope_all_cyl, col = plot_colors[3], lty = 3, lwd = 2)
legend("topright", c("4 Cylinder", "6 Cylinder", "8 Cylinder"),
       col = plot_colors, lty = c(1, 2, 3), pch = c(1, 2, 3))
```



On this plot, we have

- 4 Cylinder: orange dots, solid orange line.
- 6 Cylinder: grey dots, dashed grey line.
- 8 Cylinder: blue dots, dotted blue line.

The odd result here is that we're estimating that 8 cylinder cars have better fuel efficiency than 6 cylinder cars at **any** displacement! The dotted blue line is always above the dashed grey line. That doesn't seem right. Maybe for very large displacement engines that could be true, but that seems wrong for medium to low displacement.

To attempt to fix this, we will try using an interaction model, that is, instead of simply three intercepts and one slope, we will allow for three slopes. Again, we'll let R take the wheel, (no pun intended) then figure out what model it has applied.

```
(mpg_disp_int_cyl = lm(mpg ~ disp * cyl, data = autompg))
```

```
##  
## Call:  
## lm(formula = mpg ~ disp * cyl, data = autompg)  
##  
## Coefficients:  
## (Intercept)      disp      cyl6      cyl8    disp:cyl6    disp:cyl8  
##     43.59052    -0.13069   -13.20026   -20.85706     0.08299     0.10817  
  
# could also use mpg ~ disp + cyl + disp:cyl
```

R has again chosen to use 4 cylinder cars as the reference level, but this also now has an effect on the interaction terms. R has fit the model.

$$Y = \beta_0 + \beta_1 x + \beta_2 v_2 + \beta_3 v_3 + \gamma_2 x v_2 + \gamma_3 x v_3 + \epsilon$$

We're using γ like a β parameter for simplicity, so that, for example β_2 and γ_2 are both associated with v_2 .

Now, the three “sub models” are:

- 4 Cylinder: $Y = \beta_0 + \beta_1 x + \epsilon$.
- 6 Cylinder: $Y = (\beta_0 + \beta_2) + (\beta_1 + \gamma_2)x + \epsilon$.
- 8 Cylinder: $Y = (\beta_0 + \beta_3) + (\beta_1 + \gamma_3)x + \epsilon$.

Interpreting some parameters and coefficients then:

- $(\beta_0 + \beta_2)$ is the average `mpg` of a 6 cylinder car with 0 `disp`
- $(\hat{\beta}_1 + \hat{\gamma}_3) = -0.1306935 + 0.1081714 = -0.0225221$ is the estimated change in average `mpg` for an increase of one `disp`, for an 8 cylinder car.

So, as we have seen before β_2 and β_3 change the intercepts for 6 and 8 cylinder cars relative to the reference level of β_0 for 4 cylinder cars.

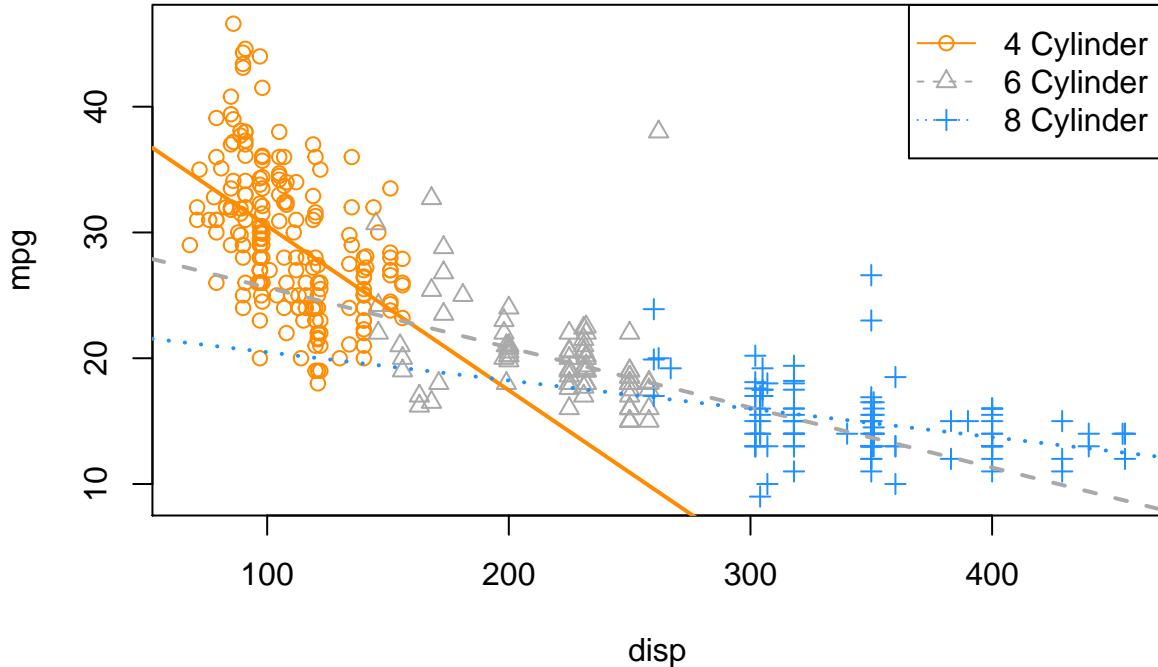
Now, similarly γ_2 and γ_3 change the slopes for 6 and 8 cylinder cars relative to the reference level of β_1 for 4 cylinder cars.

Once again, we extract the coefficients and plot the results.

```
int_4cyl = coef(mpg_disp_int_cyl)[1]
int_6cyl = coef(mpg_disp_int_cyl)[1] + coef(mpg_disp_int_cyl)[3]
int_8cyl = coef(mpg_disp_int_cyl)[1] + coef(mpg_disp_int_cyl)[4]

slope_4cyl = coef(mpg_disp_int_cyl)[2]
slope_6cyl = coef(mpg_disp_int_cyl)[2] + coef(mpg_disp_int_cyl)[5]
slope_8cyl = coef(mpg_disp_int_cyl)[2] + coef(mpg_disp_int_cyl)[6]

plot_colors = c("Darkorange", "Darkgrey", "Dodgerblue")
plot(mpg ~ disp, data = autompg, col = plot_colors[cyl], pch = as.numeric(cyl))
abline(int_4cyl, slope_4cyl, col = plot_colors[1], lty = 1, lwd = 2)
abline(int_6cyl, slope_6cyl, col = plot_colors[2], lty = 2, lwd = 2)
abline(int_8cyl, slope_8cyl, col = plot_colors[3], lty = 3, lwd = 2)
legend("topright", c("4 Cylinder", "6 Cylinder", "8 Cylinder"),
      col = plot_colors, lty = c(1, 2, 3), pch = c(1, 2, 3))
```



This looks much better! We can see that for medium displacement cars, 6 cylinder cars now perform better than 8 cylinder cars, which seems much more reasonable than before.

To completely justify the interaction model (i.e., a unique slope for each `cyl` level) compared to the additive model (single slope), we can perform an F -test. Notice first, that there is no t -test that will be able to do this since the difference between the two models is not a single parameter.

We will test,

$$H_0 : \gamma_2 = \gamma_3 = 0$$

which represents the parallel regression lines we saw before,

$$Y = \beta_0 + \beta_1 x + \beta_2 v_2 + \beta_3 v_3 + \epsilon.$$

Again, this is a difference of two parameters, thus no t -test will be useful.

```
anova(mpg_disp_add_cyl, mpg_disp_int_cyl)
```

```
## Analysis of Variance Table
##
## Model 1: mpg ~ disp + cyl
## Model 2: mpg ~ disp * cyl
##   Res.Df   RSS Df Sum of Sq    F    Pr(>F)
## 1     379 7299.5
## 2     377 6551.7  2     747.79 21.515 1.419e-09 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

As expected, we see a very low p-value, and thus reject the null. We prefer the interaction model over the additive model.

Recapping a bit:

- Null Model: $Y = \beta_0 + \beta_1 x + \beta_2 v_2 + \beta_3 v_3 + \epsilon$
 - Number of parameters: $q = 4$
- Full Model: $Y = \beta_0 + \beta_1 x + \beta_2 v_2 + \beta_3 v_3 + \gamma_2 xv_2 + \gamma_3 xv_3 + \epsilon$
 - Number of parameters: $p = 6$

```
length(coef(mpg_disp_int_cyl)) - length(coef(mpg_disp_add_cyl))
```

```
## [1] 2
```

We see there is a difference of two parameters, which is also displayed in the resulting ANOVA table from R. Notice that the following two values also appear on the ANOVA table.

```
nrow(automp) - length(coef(mpg_disp_int_cyl))
```

```
## [1] 377
```

```
nrow(automp) - length(coef(mpg_disp_add_cyl))
```

```
## [1] 379
```

11.4 Parameterization

So far we have been simply letting R decide how to create the dummy variables, and thus R has been deciding the parameterization of the models. To illustrate the ability to use alternative parameterizations, we will recreate the data, but directly creating the dummy variables ourselves.

```
new_param_data = data.frame(
  y = automp$mpg,
  x = automp$disp,
  v1 = 1 * as.numeric(automp$cyl == 4),
  v2 = 1 * as.numeric(automp$cyl == 6),
  v3 = 1 * as.numeric(automp$cyl == 8))

head(new_param_data, 20)
```

	y	x	v1	v2	v3
## 1	18	307	0	0	1
## 2	15	350	0	0	1
## 3	18	318	0	0	1
## 4	16	304	0	0	1
## 5	17	302	0	0	1
## 6	15	429	0	0	1
## 7	14	454	0	0	1
## 8	14	440	0	0	1
## 9	14	455	0	0	1
## 10	15	390	0	0	1
## 11	15	383	0	0	1
## 12	14	340	0	0	1

```
## 13 15 400 0 0 1
## 14 14 455 0 0 1
## 15 24 113 1 0 0
## 16 22 198 0 1 0
## 17 18 199 0 1 0
## 18 21 200 0 1 0
## 19 27 97 1 0 0
## 20 26 97 1 0 0
```

Now,

- y is `mpg`
- x is `disp`, the displacement in cubic inches,
- $v1$, $v2$, and $v3$ are dummy variables as defined above.

First let's try to fit an additive model using x as well as the three dummy variables.

```
lm(y ~ x + v1 + v2 + v3, data = new_param_data)
```

```
##
## Call:
## lm(formula = y ~ x + v1 + v2 + v3, data = new_param_data)
##
## Coefficients:
## (Intercept)           x           v1           v2           v3
## 32.96326     -0.05217     2.03603    -1.59722       NA
```

What is happening here? Notice that R is essentially ignoring $v3$, but why? Well, because R uses an intercept, it cannot also use $v3$. This is because

$$\mathbf{1} = v_1 + v_2 + v_3$$

which means that $\mathbf{1}$, v_1 , v_2 , and v_3 are linearly dependent. This would make the $X^\top X$ matrix singular, but we need to be able to invert it to solve the normal equations and obtain $\hat{\beta}$. With the intercept, $v1$, and $v2$, R can make the necessary “three intercepts”. So, in this case $v3$ is the reference level.

If we remove the intercept, then we can directly obtain all “three intercepts” without a reference level.

```
lm(y ~ 0 + x + v1 + v2 + v3, data = new_param_data)
```

```
##
## Call:
## lm(formula = y ~ 0 + x + v1 + v2 + v3, data = new_param_data)
##
## Coefficients:
##           x           v1           v2           v3
## -0.05217  34.99929  31.36604  32.96326
```

Here, we are fitting the model

$$Y = \mu_1 v_1 + \mu_2 v_2 + \mu_3 v_3 + \beta x + \epsilon.$$

Thus we have:

- 4 Cylinder: $Y = \mu_1 + \beta x + \epsilon$
- 6 Cylinder: $Y = \mu_2 + \beta x + \epsilon$
- 8 Cylinder: $Y = \mu_3 + \beta x + \epsilon$

We could also do something similar with the interaction model, and give each line an intercept and slope, without the need for a reference level.

```
lm(y ~ 0 + v1 + v2 + v3 + x:v1 + x:v2 + x:v3, data = new_param_data)
```

```
##
## Call:
## lm(formula = y ~ 0 + v1 + v2 + v3 + x:v1 + x:v2 + x:v3, data = new_param_data)
##
## Coefficients:
##           v1          v2          v3          v1:x         v2:x         v3:x
## 43.59052  30.39026  22.73346 -0.13069 -0.04770 -0.02252
```

$$Y = \mu_1 v_1 + \mu_2 v_2 + \mu_3 v_3 + \beta_1 x v_1 + \beta_2 x v_2 + \beta_3 x v_3 + \epsilon$$

- 4 Cylinder: $Y = \mu_1 + \beta_1 x + \epsilon$
- 6 Cylinder: $Y = \mu_2 + \beta_2 x + \epsilon$
- 8 Cylinder: $Y = \mu_3 + \beta_3 x + \epsilon$

Using the original data, we have (at least) three equivalent ways to specify the interaction model with R.

```
lm(mpg ~ disp * cyl, data = autompg)
```

```
##
## Call:
## lm(formula = mpg ~ disp * cyl, data = autompg)
##
## Coefficients:
## (Intercept)      disp      cyl6      cyl8   disp:cyl6   disp:cyl8
##     43.59052    -0.13069   -13.20026   -20.85706     0.08299     0.10817
```

```
lm(mpg ~ 0 + cyl + disp : cyl, data = autompg)
```

```
##
## Call:
## lm(formula = mpg ~ 0 + cyl + disp:cyl, data = autompg)
##
## Coefficients:
##      cyl4      cyl6      cyl8 cyl4:disp cyl6:disp cyl8:disp
## 43.59052  30.39026  22.73346 -0.13069 -0.04770 -0.02252
```

```
lm(mpg ~ 0 + disp + cyl + disp : cyl, data = autompg)
```

```
##
## Call:
## lm(formula = mpg ~ 0 + disp + cyl + disp:cyl, data = autompg)
##
## Coefficients:
##      disp      cyl4      cyl6      cyl8  disp:cyl6  disp:cyl8
## -0.13069   43.59052   30.39026   22.73346    0.08299    0.10817
```

They all fit the same model, importantly each using six parameters, but the coefficients mean slightly different things in each. However, once they are interpreted as slopes and intercepts for the “three lines” they will have the same result.

Use `?all.equal` to learn about the `all.equal()` function, and think about how the following code verifies that the residuals of the two models are the same.

```
all.equal(fitted(lm(mpg ~ disp * cyl, data = autompg)),
          fitted(lm(mpg ~ 0 + cyl + disp : cyl, data = autompg)))
```

```
## [1] TRUE
```

11.5 Building Larger Models

Now that we have seen how to incorporate categorical predictors as well as interaction terms, we can start to build much larger, much more flexible models which can potentially fit data better.

Let’s define a “big” model,

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \beta_4 x_1 x_2 + \beta_5 x_1 x_3 + \beta_6 x_2 x_3 + \beta_7 x_1 x_2 x_3 + \epsilon.$$

Here,

- Y is `mpg`.
- x_1 is `disp`.
- x_2 is `hp`.
- x_3 is `domestic`, which is a dummy variable we defined, where `1` is a domestic vehicle.

First thing to note here, we have included a new term $x_1 x_2 x_3$ which is a three-way interaction. Interaction terms can be larger and larger, up to the number of predictors in the model.

Since we are using the three-way interaction term, we also use all possible two-way interactions, as well as each of the first order (**main effect**) terms. This is the concept of a **hierarchy**. Any time a “higher-order” term is in a model, the related “lower-order” terms should also be included. Mathematically their inclusion or exclusion is sometimes irrelevant, but from an interpretation standpoint, it is best to follow the hierarchy rules.

Let’s do some rearrangement to obtain a “coefficient” in front of x_1 .

$$Y = \beta_0 + \beta_2 x_2 + \beta_3 x_3 + \beta_6 x_2 x_3 + (\beta_1 + \beta_4 x_2 + \beta_5 x_3 + \beta_7 x_2 x_3) x_1 + \epsilon.$$

Specifically, the “coefficient” in front of x_1 is

$$(\beta_1 + \beta_4 x_2 + \beta_5 x_3 + \beta_7 x_2 x_3).$$

Let’s discuss this “coefficient” to help us understand the idea of the *flexibility* of a model. Recall that,

- β_1 is the coefficient for a first order term,
- β_4 and β_5 are coefficients for two-way interactions,
- β_7 is the coefficient for the three-way interaction.

If the two and three way interactions were not in the model, the whole “coefficient” would simply be

$$\beta_1.$$

Thus, no matter the values of x_2 and x_3 , β_1 would determine the relationship between x_1 (`disp`) and Y (`mpg`).

With the addition of the two-way interactions, now the “coefficient” would be

$$(\beta_1 + \beta_4 x_2 + \beta_5 x_3).$$

Now, changing x_1 (`disp`) has a different effect on Y (`mpg`), depending on the values of x_2 and x_3 .

Lastly, adding the three-way interaction gives the whole “coefficient”

$$(\beta_1 + \beta_4 x_2 + \beta_5 x_3 + \beta_7 x_2 x_3)$$

which is even more flexible. Now changing x_1 (`disp`) has a different effect on Y (`mpg`), depending on the values of x_2 and x_3 , but in a more flexible way which we can see with some more rearrangement. Now the “coefficient” in front of x_3 in this “coefficient” is dependent on x_2 .

$$(\beta_1 + \beta_4 x_2 + (\beta_5 + \beta_7 x_2) x_3)$$

It is so flexible, it is becoming hard to interpret!

Let's fit this three-way interaction model in R.

```
big_model = lm(mpg ~ disp * hp * domestic, data = autompg)
summary(big_model)
```

```
##
## Call:
## lm(formula = mpg ~ disp * hp * domestic, data = autompg)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -11.9410  -2.2147  -0.4008   1.9430  18.4094
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept) 60.6457838  6.6000851  9.189 < 2e-16 ***
## disp        -0.1415870  0.0634395 -2.232  0.0262 *
## hp          -0.3544717  0.0812261 -4.364 0.0000165 ***
## domestic    -12.5718884  7.0643505 -1.780  0.0759 .
## disp:hp      0.0013690  0.0006727  2.035  0.0426 *
## disp:domestic 0.0493298  0.0640046  0.771  0.4414
## hp:domestic  0.1851530  0.0870881  2.126  0.0342 *
## disp:hp:domestic -0.0009163  0.0006768 -1.354  0.1766
## ---
```

```
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 3.88 on 375 degrees of freedom
## Multiple R-squared:  0.76, Adjusted R-squared:  0.7556
## F-statistic: 169.7 on 7 and 375 DF,  p-value: < 2.2e-16
```

Do we actually need this large of a model? Let's first test for the necessity of the three-way interaction term. That is,

$$H_0 : \beta_7 = 0.$$

So,

- Full Model: $Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \beta_4 x_1 x_2 + \beta_5 x_1 x_3 + \beta_6 x_2 x_3 + \beta_7 x_1 x_2 x_3 + \epsilon$
- Null Model: $Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \beta_4 x_1 x_2 + \beta_5 x_1 x_3 + \beta_6 x_2 x_3 + \epsilon$

We fit the null model in R as `two_way_int_mod`, then use `anova()` to perform an F -test as usual.

```
two_way_int_mod = lm(mpg ~ disp * hp + disp * domestic + hp * domestic, data = autompg)
#two_way_int_mod = lm(mpg ~ (disp + hp + domestic) ^ 2, data = autompg)
anova(two_way_int_mod, big_model)
```

```
## Analysis of Variance Table
##
## Model 1: mpg ~ disp * hp + disp * domestic + hp * domestic
## Model 2: mpg ~ disp * hp * domestic
##   Res.Df   RSS Df Sum of Sq    F Pr(>F)
## 1     376 5673.2
## 2     375 5645.6  1    27.599 1.8332 0.1766
```

We see the p-value is somewhat large, so we would fail to reject. We prefer the smaller, less flexible, null model, without the three-way interaction.

A quick note here: the full model does still “fit better.” Notice that it has a smaller RMSE than the null model, which means the full model makes smaller (squared) errors on average.

```
mean(resid(big_model) ^ 2)

## [1] 14.74053

mean(resid(two_way_int_mod) ^ 2)

## [1] 14.81259
```

However, it is not much smaller. We could even say that, the difference is insignificant. This is an idea we will return to later in greater detail.

Now that we have chosen the model without the three-way interaction, can we go further? Do we need the two-way interactions? Let's test

$$H_0 : \beta_4 = \beta_5 = \beta_6 = 0.$$

Remember we already chose $\beta_7 = 0$, so,

- Full Model: $Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \beta_4 x_1 x_2 + \beta_5 x_1 x_3 + \beta_6 x_2 x_3 + \epsilon$
- Null Model: $Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \epsilon$

We fit the null model in R as `additive_mod`, then use `anova()` to perform an F -test as usual.

```
additive_mod = lm(mpg ~ disp + hp + domestic, data = autompg)
anova(additive_mod, two_way_int_mod)
```

```
## Analysis of Variance Table
##
## Model 1: mpg ~ disp + hp + domestic
## Model 2: mpg ~ disp * hp + disp * domestic + hp * domestic
##   Res.Df   RSS Df Sum of Sq    F    Pr(>F)
## 1     379 7369.7
## 2     376 5673.2  3    1696.5 37.478 < 2.2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

Here the p-value is small, so we reject the null, and we prefer the full (alternative) model. Of the models we have considered, our final preference is for

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \beta_4 x_1 x_2 + \beta_5 x_1 x_3 + \beta_6 x_2 x_3 + \epsilon.$$

Chapter 12

Model Diagnostics

“Your assumptions are your windows on the world. Scrub them off every once in a while, or the light won’t come in.”

— Isaac Asimov

After reading this chapter you will be able to:

- Understand the assumptions of a regression model.
- Assess regression model assumptions using visualizations and tests.
- Understand leverage, outliers, and influential points.
- Be able to identify unusual observations in regression models.

12.1 Model Assumptions

Recall the multiple linear regression model that we have defined.

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \cdots + \beta_{p-1} x_{i(p-1)} + \epsilon_i, \quad i = 1, 2, \dots, n.$$

Using matrix notation, this model can be written much more succinctly as

$$Y = X\beta + \epsilon.$$

Given data, we found the estimates for the β parameters using

$$\hat{\beta} = (X^\top X)^{-1} X^\top y.$$

We than noted that these estimates had mean

$$E[\hat{\beta}] = \beta,$$

and variance

$$\text{Var}[\hat{\beta}] = \sigma^2 (X^\top X)^{-1}.$$

In particular, an individual parameter, say $\hat{\beta}_j$ had a normal distribution

$$\hat{\beta}_j \sim N(\beta_j, \sigma^2 C_{jj})$$

where C was the matrix defined as

$$C = (X^\top X)^{-1}.$$

We then used this fact to define

$$\frac{\hat{\beta}_j - \beta_j}{s_e \sqrt{C_{jj}}} \sim t_{n-p},$$

which we used to perform hypothesis testing.

So far we have looked at various metrics such as RMSE, RSE and R^2 to determine how well our model fit our data. Each of these in some way considers the expression

$$\sum_{i=1}^n (y_i - \hat{y}_i)^2.$$

So, essentially each of these looks at how close the data points are to the model. However is that all we care about?

- It could be that the errors are made in a systematic way, which means that our model is misspecified. We may need additional interaction terms, or polynomial terms which we will see later.
- It is also possible that at a particular set of predictor values, the errors are very small, but at a different set of predictor values, the errors are large.
- Perhaps most of the errors are very small, but some are very large. This would suggest that the errors do not follow a normal distribution.

Are these issues that we care about? If all we would like to do is predict, possibly not, since we would only care about the size of our errors. However, if we would like to perform inference, for example to determine if a particular predictor is important, we care a great deal. All of the distributional results, such as a t -test for a single predictor, are derived under the assumptions of our model.

Technically, the assumptions of the model are encoded directly in a model statement such as,

$$Y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \cdots + \beta_{p-1} x_{i(p-1)} + \epsilon_i$$

where $\epsilon_i \sim N(0, \sigma^2)$.

Often, the **assumptions of linear regression**, are stated as,

- Linearity: the response can be written as a linear combination of the predictors. (With noise about this true linear relationship.)
- Independence: the errors are independent.
- Normality: the distribution of the errors should follow a normal distribution.
- Equal Variance: the error variance is the same at any set of predictor values.

The linearity assumption is encoded as

$$\beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \cdots + \beta_{p-1} x_{i(p-1)},$$

while the remaining three, are all encoded in

$$\epsilon_i \sim N(0, \sigma^2),$$

since the ϵ_i are *iid* normal random variables with constant variance.

If these assumptions are met, great! We can perform inference, **and it is valid**. If these assumptions are *not* met, we can still “perform” a *t*-test using R, but the results are **not valid**. The distributions of the parameter estimates will not be what we expect. Hypothesis tests will then accept or reject incorrectly. Essentially, **garbage in, garbage out**.

12.2 Checking Assumptions

We’ll now look at a number of tools for checking the assumptions of a linear model. To test these tools, we’ll use data simulated from three models:

$$\text{Model 1: } Y = 3 + 5x + \epsilon, \quad \epsilon \sim N(0, 1)$$

$$\text{Model 2: } Y = 3 + 5x + \epsilon, \quad \epsilon \sim N(0, x^2)$$

$$\text{Model 3: } Y = 3 + 5x^2 + \epsilon, \quad \epsilon \sim N(0, 25)$$

```
sim_1 = function(sample_size = 500) {
  x = runif(n = sample_size) * 5
  y = 3 + 5 * x + rnorm(n = sample_size, mean = 0, sd = 1)
  data.frame(x, y)
}

sim_2 = function(sample_size = 500) {
  x = runif(n = sample_size) * 5
  y = 3 + 5 * x + rnorm(n = sample_size, mean = 0, sd = x)
  data.frame(x, y)
}

sim_3 = function(sample_size = 500) {
  x = runif(n = sample_size) * 5
  y = 3 + 5 * x ^ 2 + rnorm(n = sample_size, mean = 0, sd = 5)
  data.frame(x, y)
}
```

12.2.1 Fitted versus Residuals Plot

Probably our most useful tool will be a **Fitted versus Residuals Plot**. It will be useful for checking both the **linearity** and **constant variance** assumptions.

Data generated from Model 1 above should not show any signs of violating assumptions, so we'll use this to see what a good fitted versus residuals plot should look like. First, we'll simulate observations from this model.

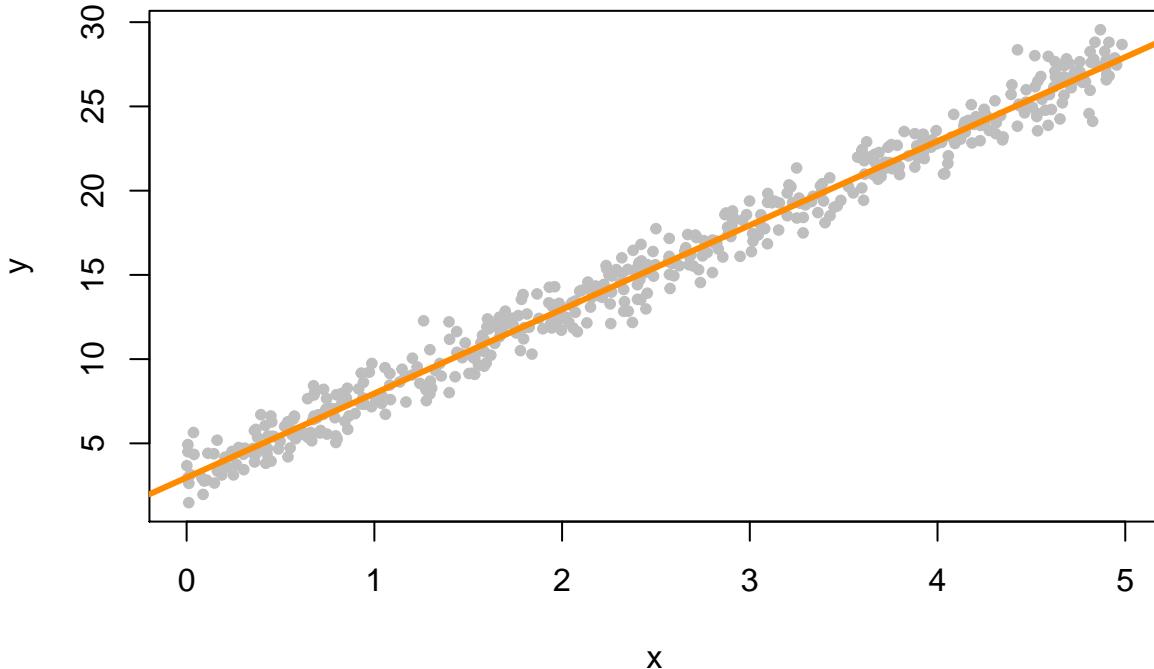
```
set.seed(42)
sim_data_1 = sim_1()
head(sim_data_1)
```

```
##          x          y
## 1 4.574030 24.773995
## 2 4.685377 26.475936
## 3 1.430698  8.954993
## 4 4.152238 23.951210
## 5 3.208728 20.341344
## 6 2.595480 14.943525
```

We then fit the model and add the fitted line to a scatterplot.

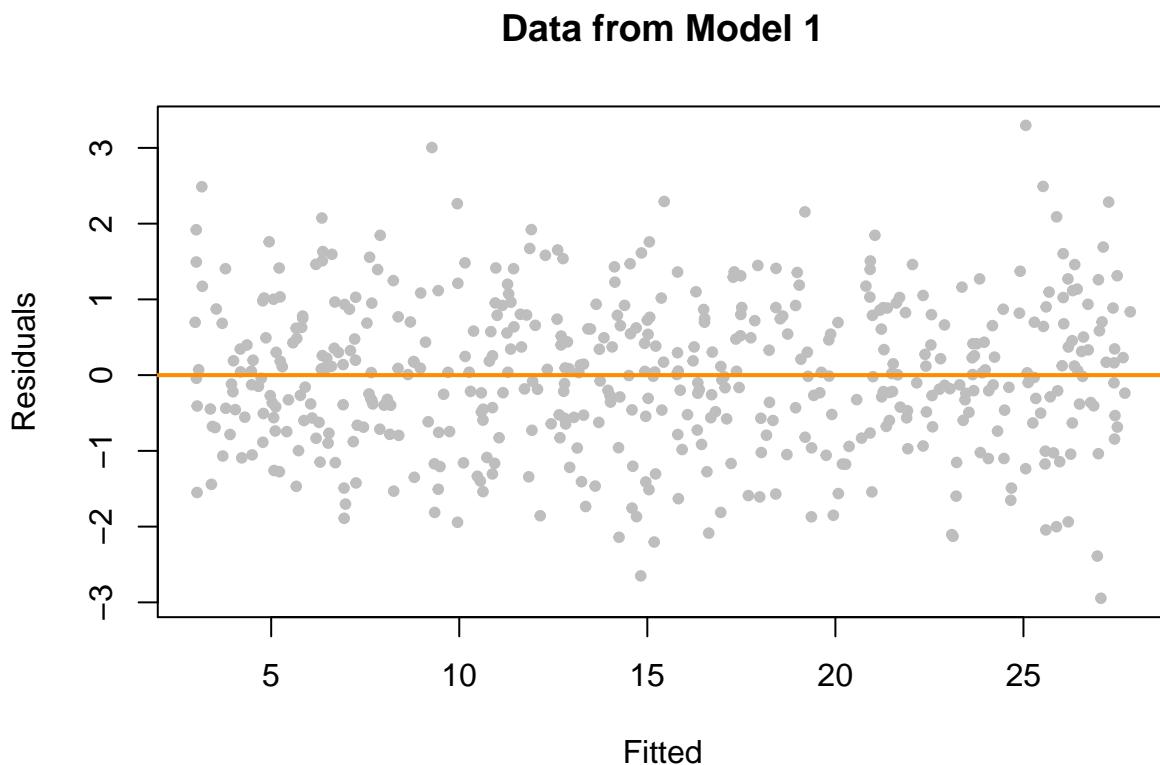
```
plot(y ~ x, data = sim_data_1, col = "grey", pch = 20,
     main = "Data from Model 1")
fit_1 = lm(y ~ x, data = sim_data_1)
abline(fit_1, col = "darkorange", lwd = 3)
```

Data from Model 1



We now plot a fitted versus residuals plot. Note, this is residuals on the y -axis despite the ordering in the name. Sometimes you will see this called a residuals versus fitted, or residuals versus predicted plot.

```
plot(fitted(fit_1), resid(fit_1), col = "grey", pch = 20,
      xlab = "Fitted", ylab = "Residuals", main = "Data from Model 1")
abline(h = 0, col = "darkorange", lwd = 2)
```



We should look for two things in this plot.

- At any fitted value, the mean of the residuals should be roughly 0. If this is the case, the *linearity* assumption is valid. For this reason, we generally add a horizontal line at $y = 0$ to emphasize this point.
- At every fitted value, the spread of the residuals should be roughly the same. If this is the case, the *constant variance* assumption is valid.

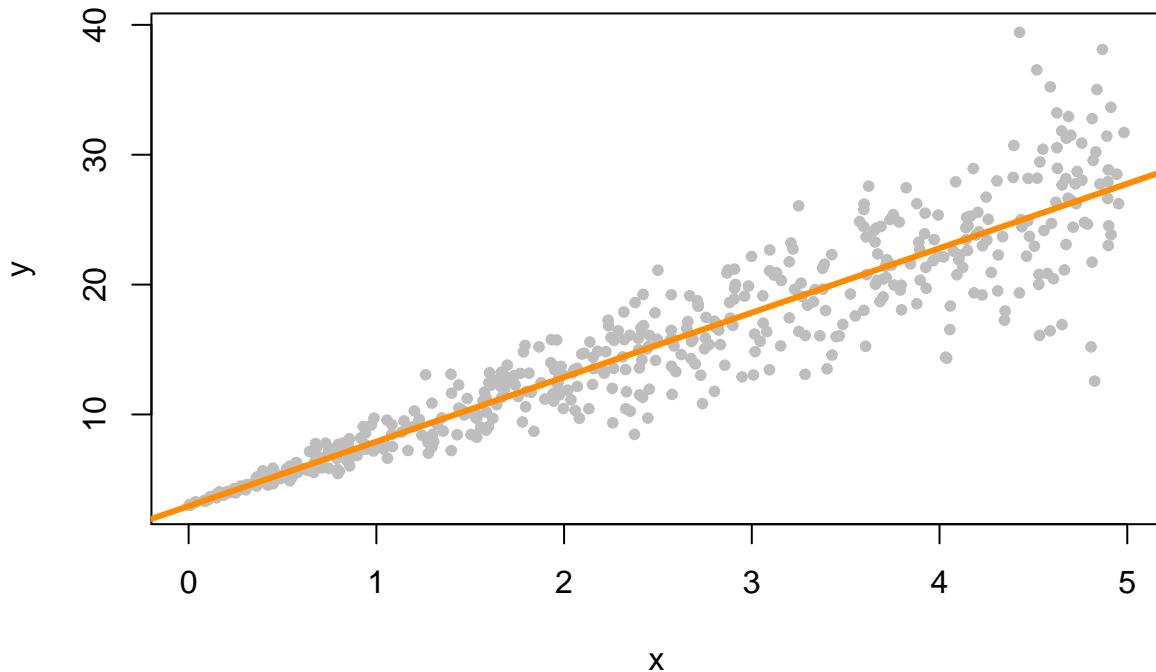
Here we see this is the case for both.

To get a better idea of how a fitted versus residuals plot can be useful, we will simulate from models with violated assumptions.

Model 2 is an example of non-constant variance. In this case, the variance is larger for larger values of the predictor variable x .

```
set.seed(42)
sim_data_2 = sim_2()
fit_2 = lm(y ~ x, data = sim_data_2)
plot(y ~ x, data = sim_data_2, col = "grey", pch = 20,
      main = "Data from Model 2")
abline(fit_2, col = "darkorange", lwd = 3)
```

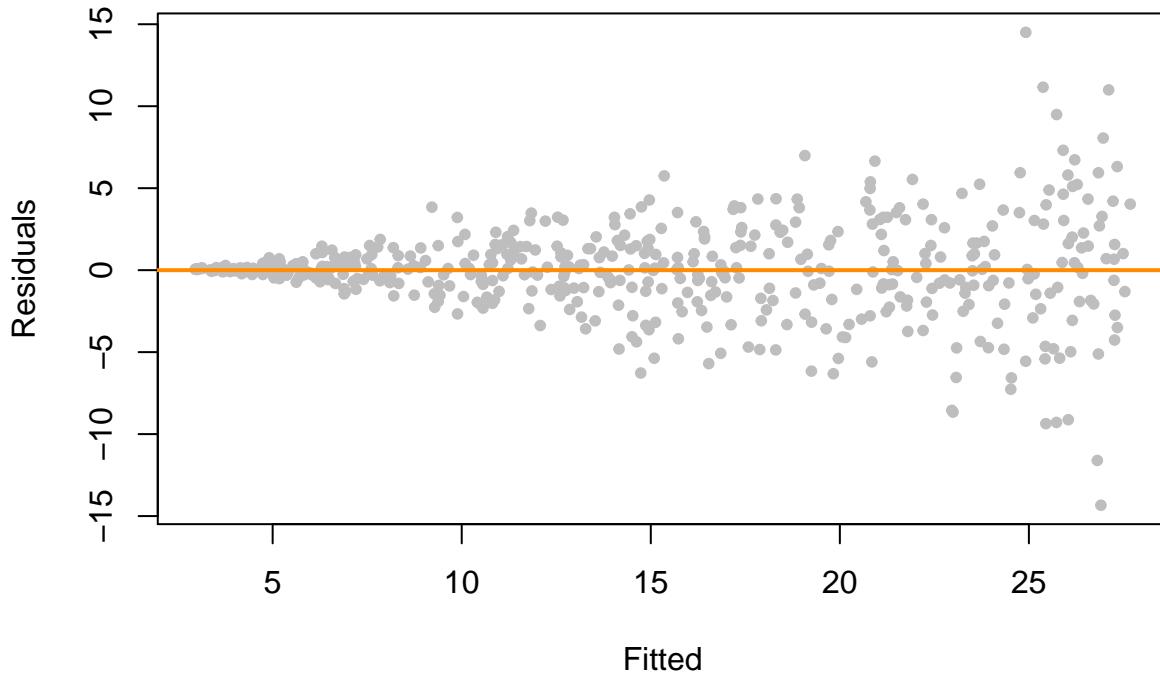
Data from Model 2



This actually is rather easy to see here by adding the fitted line to a scatterplot. This is because we are only performing simple linear regression. With multiple regression, a fitted versus residuals plot is a necessity, since adding a fitted regression to a scatterplot isn't exactly possible.

```
plot(fitted(fit_2), resid(fit_2), col = "grey", pch = 20,
      xlab = "Fitted", ylab = "Residuals", main = "Data from Model 2")
abline(h = 0, col = "darkorange", lwd = 2)
```

Data from Model 2

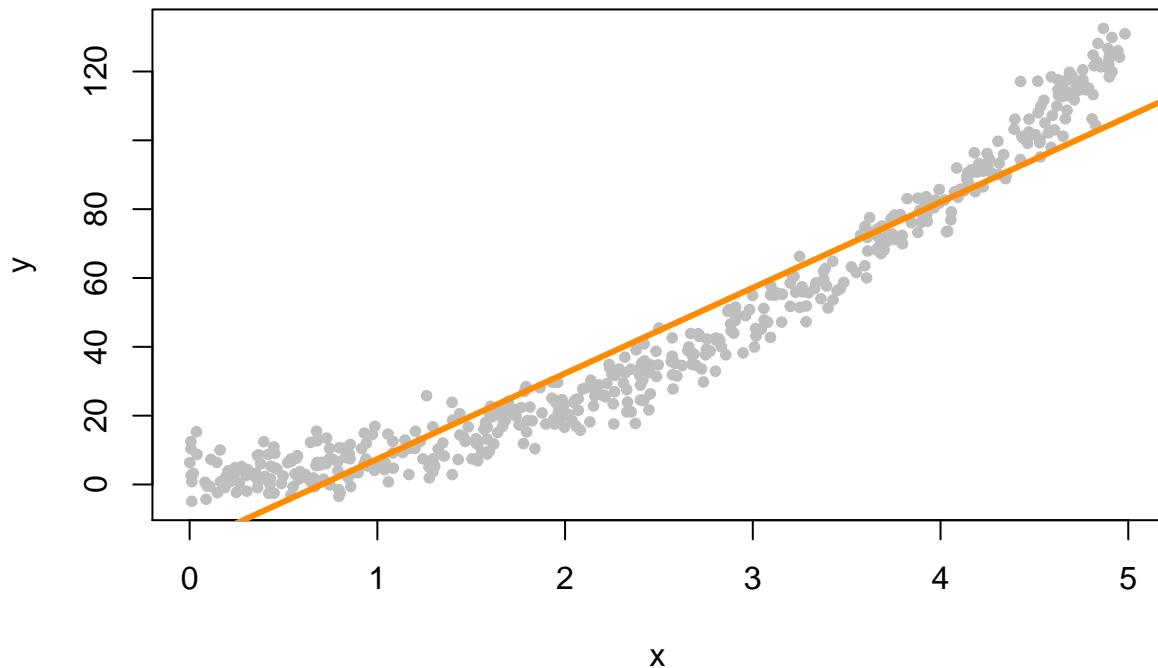


On the fitted versus residuals plot, we see two things very clearly. For any fitted value, the residuals seem roughly centered at 0. This is good! The linearity assumption is not violated. However, we also see very clearly, that for larger fitted values, the spread of the residuals is larger. This is bad! The constant variance assumption is violated here.

Now we will demonstrate a model which does not meet the linearity assumption. Model 3 is an example of a model where Y is not a linear combination of the predictors. In this case the predictor is x , but the model uses x^2 . (We'll see later that this is something that a "linear" model can deal with. The fix is simple, just make x^2 a predictor!)

```
set.seed(42)
sim_data_3 = sim_3()
fit_3 = lm(y ~ x, data = sim_data_3)
plot(y ~ x, data = sim_data_3, col = "grey", pch = 20,
     main = "Data from Model 3")
abline(fit_3, col = "darkorange", lwd = 3)
```

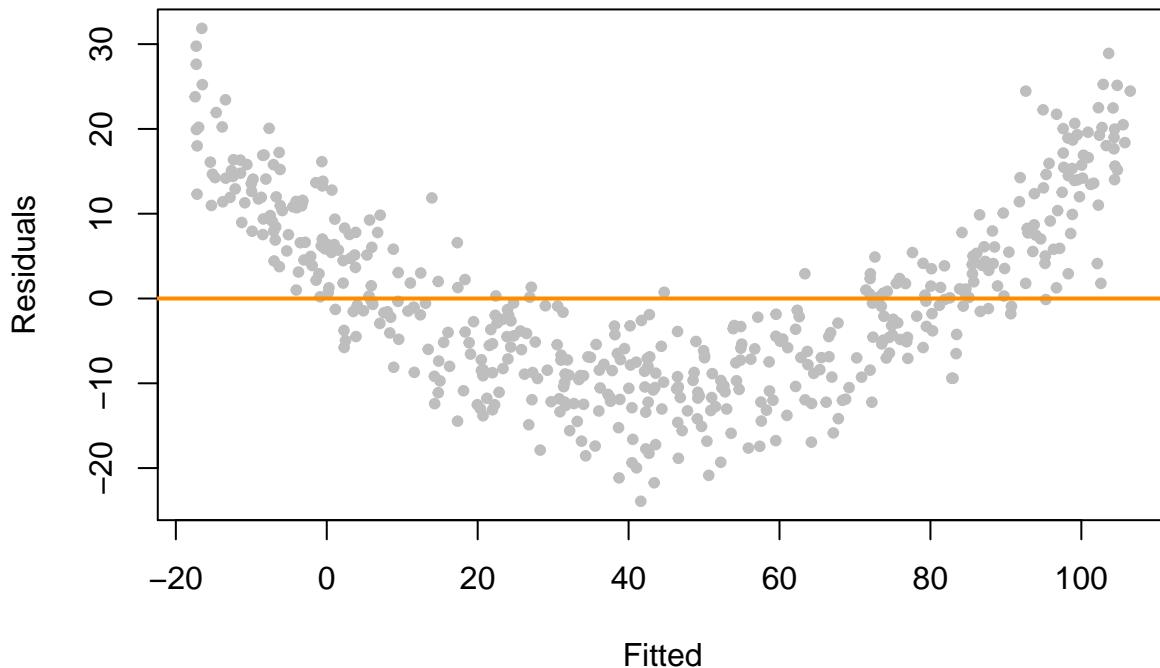
Data from Model 3



Again, this is rather clear on the scatterplot, but again, we wouldn't be able to check this plot for multiple regression.

```
plot(fitted(fit_3), resid(fit_3), col = "grey", pch = 20,
      xlab = "Fitted", ylab = "Residuals", main = "Data from Model 3")
abline(h = 0, col = "darkorange", lwd = 2)
```

Data from Model 3



This time on the fitted versus residuals plot, for any fitted value, the spread of the residuals is about the same. However, they are not even close to centered at zero! At small and large fitted values the model is underestimating, while at medium fitted values, the model is overestimating. These are systematic errors, not random noise. So the constant variance assumption is met, but the linearity assumption is violated. The form of our model is simply wrong. We're trying to fit a line to a curve!

12.2.2 Breusch-Pagan Test

Constant variance is often called **homoscedasticity**. Conversely, non-constant variance is called **heteroscedasticity**. We've seen how we can use a fitted versus residuals plot to look for these attributes.

While a fitted versus residuals plot can give us an idea about homoscedasticity, sometimes we would prefer a more formal test. There are many tests for constant variance, but here we will present one, the **Breusch-Pagan Test**. The exact details of the test will be omitted here, but importantly the null and alternative can be considered to be,

- H_0 : Homoscedasticity. The errors have constant variance about the true model.
- H_1 : Heteroscedasticity. The errors have non-constant variance about the true model.

Isn't that convenient? A test that will specifically test the **constant variance** assumption.

The Breusch-Pagan Test can not be performed by default in R, however the function `bptest` in the `lmtest` package implements the test.

```
#install.packages("lmtest")
library(lmtest)
```

Let's try it on the three models we fit above. Recall,

- `fit_1` had no violation of assumptions,
- `fit_2` violated the constant variance assumption, but not linearity,
- `fit_3` violated linearity, but not constant variance.

```
bptest(fit_1)
```

```
##  
## studentized Breusch-Pagan test  
##  
## data: fit_1  
## BP = 1.0234, df = 1, p-value = 0.3117
```

For `fit_1` we see a large p-value, so we do not reject the null of homoscedasticity, which is what we would expect.

```
bptest(fit_2)
```

```
##  
## studentized Breusch-Pagan test  
##  
## data: fit_2  
## BP = 76.693, df = 1, p-value < 2.2e-16
```

For `fit_2` we see a small p-value, so we reject the null of homoscedasticity. The constant variance assumption is violated. This matches our findings with a fitted versus residuals plot.

```
bptest(fit_3)
```

```
##  
## studentized Breusch-Pagan test  
##  
## data: fit_3  
## BP = 0.33466, df = 1, p-value = 0.5629
```

Lastly, for `fit_3` we again see a large p-value, so we do not reject the null of homoscedasticity, which matches our findings with a fitted versus residuals plot.

12.2.3 Histograms

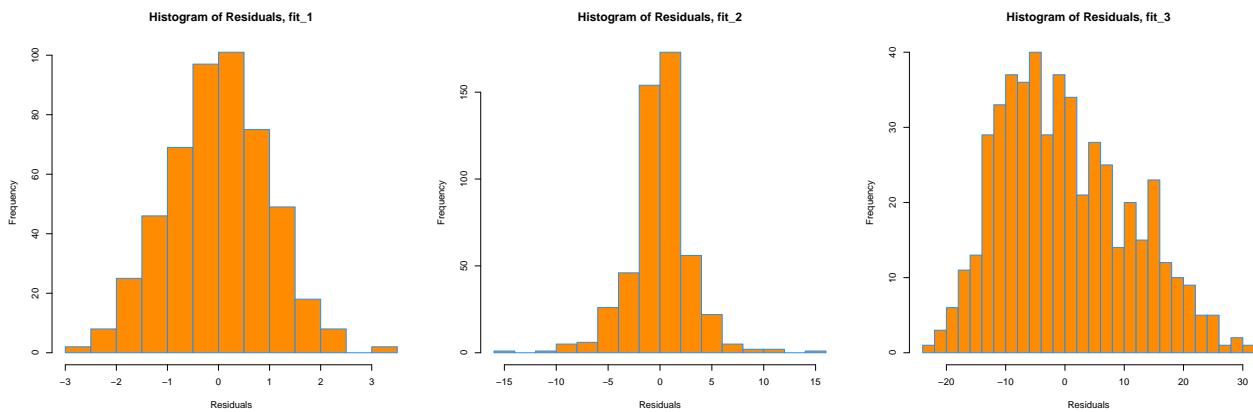
We have a number of tools for assessing the normality assumption. The most obvious would be to make a histogram of the residuals. If it appears roughly normal, then we'll believe the errors could truly be normal.

```
par(mfrow = c(1, 3))  
hist(resid(fit_1),  
     xlab = "Residuals",  
     main = "Histogram of Residuals, fit_1",  
     col = "darkorange",  
     border = "dodgerblue",  
     breaks = 20)  
hist(resid(fit_2),
```

```

xlab  = "Residuals",
main  = "Histogram of Residuals, fit_2",
col   = "darkorange",
border = "dodgerblue",
breaks = 20)
hist(resid(fit_3),
xlab  = "Residuals",
main  = "Histogram of Residuals, fit_3",
col   = "darkorange",
border = "dodgerblue",
breaks = 20)

```



Above are histograms for each of the three regression we have been considering. Notice that the first, for **fit_1** appears very normal. The third, for **fit_3**, appears to be very non-normal. However **fit_2** is not as clear. It does have a rough bell shape, however, it also has a very sharp peak. For this reason we will usually use more powerful tools such as **Q-Q plots** and the **Shapiro-Wilk test** for assessing the normality of errors.

12.2.4 Q-Q Plots

Another visual method for assessing the normality of errors, which is more powerful than a histogram, is a normal quantile-quantile plot, or **Q-Q plot** for short.

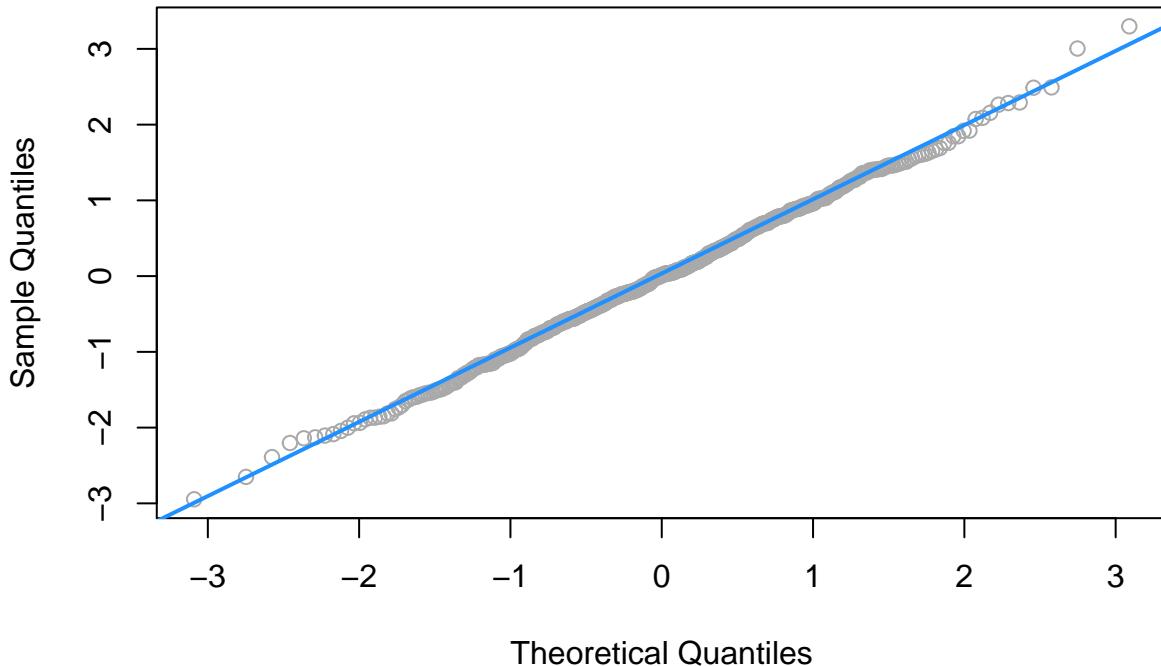
In R these are very easy to make. The `qqnorm()` function plots the points, and the `qqline()` function adds the necessary line. We create a Q-Q plot for the residuals of **fit_1** to check if the errors could truly be normally distributed.

```

qqnorm(resid(fit_1), main = "Normal Q-Q Plot, fit_1", col = "darkgrey")
qqline(resid(fit_1), col = "dodgerblue", lwd = 2)

```

Normal Q-Q Plot, fit_1



In short, if the points of the plot do not closely follow a straight line, this would suggest that the data do not come from a normal distribution.

The calculations required to create the plot vary depending on the implementation, but essentially the y -axis is the sorted data (observed, or sample quantiles), and the x -axis is the values we would expect if the data did come from a normal distribution (theoretical quantiles).

The Wikipedia page for Normal probability plots gives details on how this is implemented in R if you are interested.

Also, to get a better idea of how Q-Q plots work, here is a quick function which creates a Q-Q plot:

```
qq_plot = function(e) {

  n = length(e)
  normal_quantiles = qnorm(((1:n - 0.5) / n))
  # normal_quantiles = qnorm((1:n) / (n + 1))

  # plot theoretical versus observed quantiles
  plot(normal_quantiles, sort(e),
    xlab = c("Theoretical Quantiles"),
    ylab = c("Sample Quantiles"),
    col = "darkgrey")
  title("Normal Q-Q Plot")

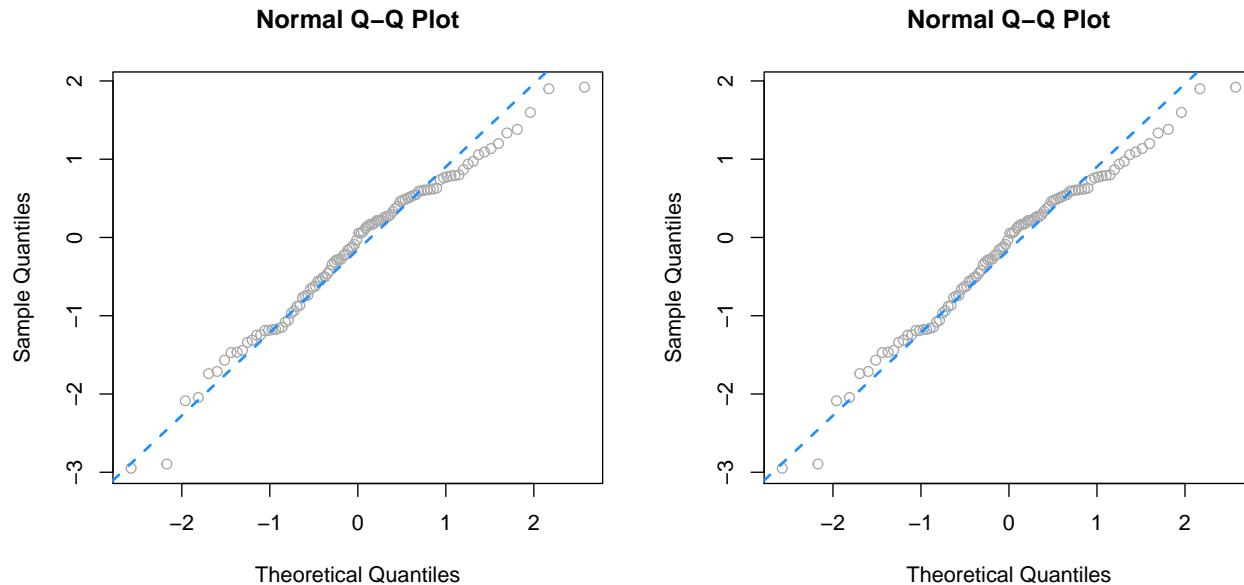
  # calculate line through the first and third quartiles
  slope    = (quantile(e, 0.75) - quantile(e, 0.25)) / (qnorm(0.75) - qnorm(0.25))
  intercept = quantile(e, 0.25) - slope * qnorm(0.25)

  # add to existing plot
  abline(intercept, slope, lty = 2, lwd = 2, col = "dodgerblue")
}
```

```
}
```

We can then verify that it is essentially equivalent to using `qqnorm()` and `qqline()` in R.

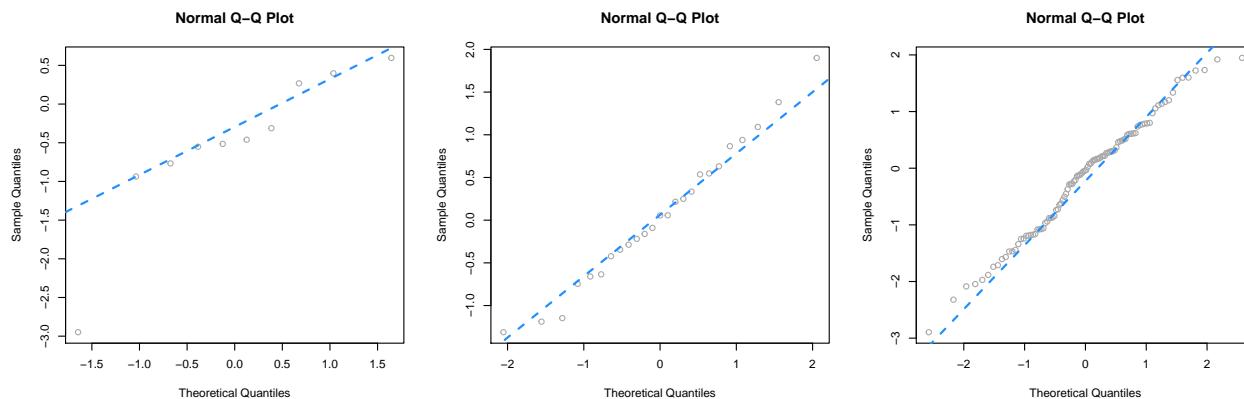
```
set.seed(420)
x = rnorm(100, mean = 0 , sd = 1)
par(mfrow = c(1, 2))
qqnorm(x, col = "darkgrey")
qqline(x, lty = 2, lwd = 2, col = "dodgerblue")
qq_plot(x)
```



To get a better idea of what “close to the line” means, we perform a number of simulations, and create Q-Q plots.

First we simulate data from a normal distribution with different sample sizes, and each time create a Q-Q plot.

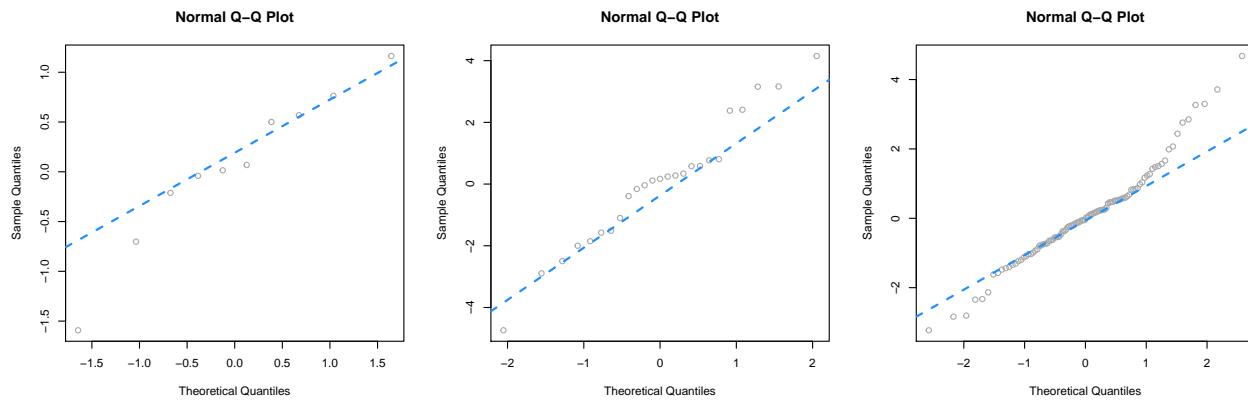
```
par(mfrow = c(1, 3))
set.seed(420)
qq_plot(rnorm(10))
qq_plot(rnorm(25))
qq_plot(rnorm(100))
```



Since this data is sampled from a normal distribution, these are all, by definition, good Q-Q plots. The points are “close to the line” and we would conclude that this data could have been sampled from a normal distribution. Notice in the first plot, one point is *somewhat* far from the line, but just one point, in combination with the small sample size, is not enough to make us worried. We see with the large sample size, all of the points are rather close to the line.

Next, we simulate data from a t distribution with a small degrees of freedom, for different sample sizes.

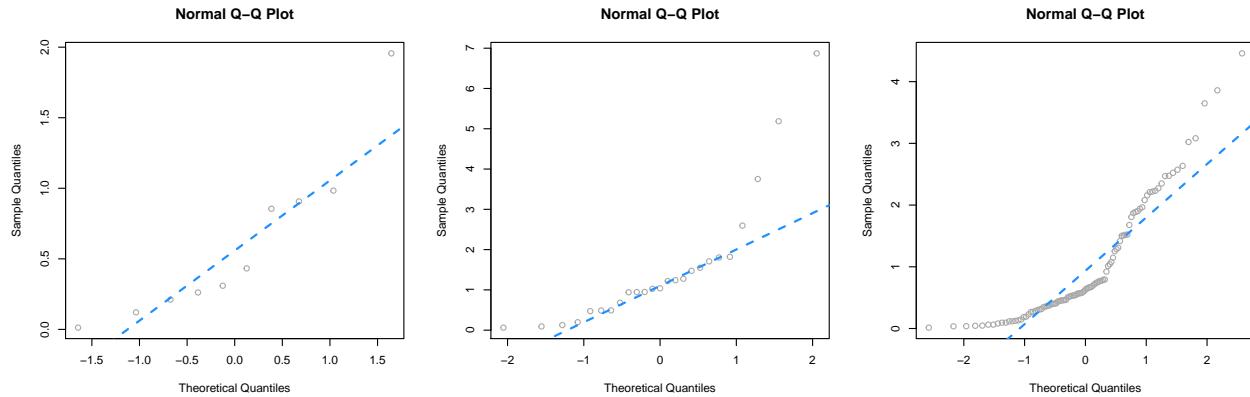
```
par(mfrow = c(1, 3))
set.seed(420)
qq_plot(rt(10, df = 4))
qq_plot(rt(25, df = 4))
qq_plot(rt(100, df = 4))
```



Recall, that as the degrees of freedom for a t distribution become larger, the distribution becomes more and more similar to a normal. Here, using 4 degrees of freedom, we have a distribution that is somewhat normal, it is symmetrical and roughly bell-shaped, however it has “fat tails.” This presents itself clearly in the third panel. While many of the points are close to the line, at the edges, there are large discrepancies. This indicates that the values are too small (negative) or too large (positive) compared to what we would expect for a normal distribution. So for the sample size of 100, we would conclude that that normality assumption is violated. (If these were residuals of a model.) For sample sizes of 10 and 25 we may be suspicious, but not entirely confident. Reading Q-Q plots, is a bit of an art, not completely a science.

Next, we simulate data from an exponential distribution.

```
par(mfrow = c(1, 3))
set.seed(420)
qq_plot(rexp(10))
qq_plot(rexp(25))
qq_plot(rexp(100))
```



This is a distribution that is not very similar to a normal, so in all three cases, we see points that are far from the lines, so we would think that the normality assumption is violated.

For a better understanding of which Q-Q plots are “good,” repeat the simulations above a number of times (without setting the seed) and pay attention to the differences between those that are simulated from normal, and those that are not. Also consider different samples sizes and distribution parameters.

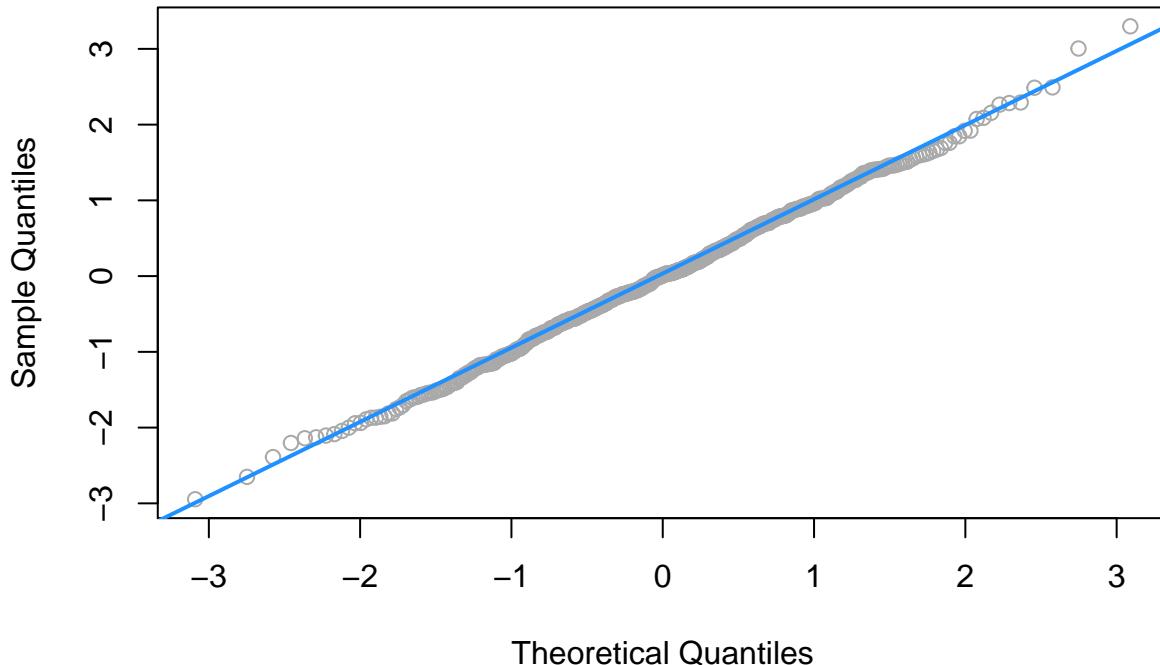
Returning to our three regressions, recall,

- `fit_1` had no violation of assumptions,
- `fit_2` violated the constant variance assumption, but not linearity,
- `fit_3` violated linearity, but not constant variance.

We'll now create a Q-Q plot for each to asses normality of errors.

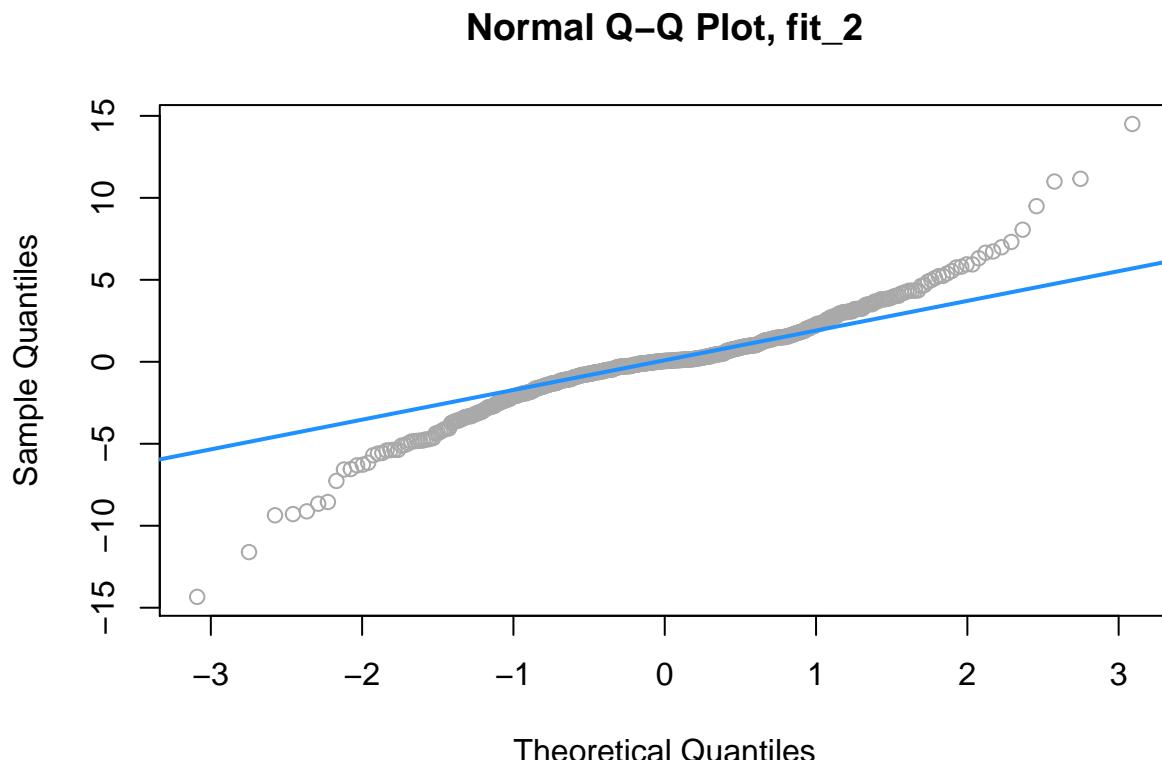
```
qqnorm(resid(fit_1), main = "Normal Q-Q Plot, fit_1", col = "darkgrey")
qqline(resid(fit_1), col = "dodgerblue", lwd = 2)
```

Normal Q–Q Plot, fit_1



For `fit_1`, we have a near perfect Q-Q plot. We would believe the errors follow a normal distribution.

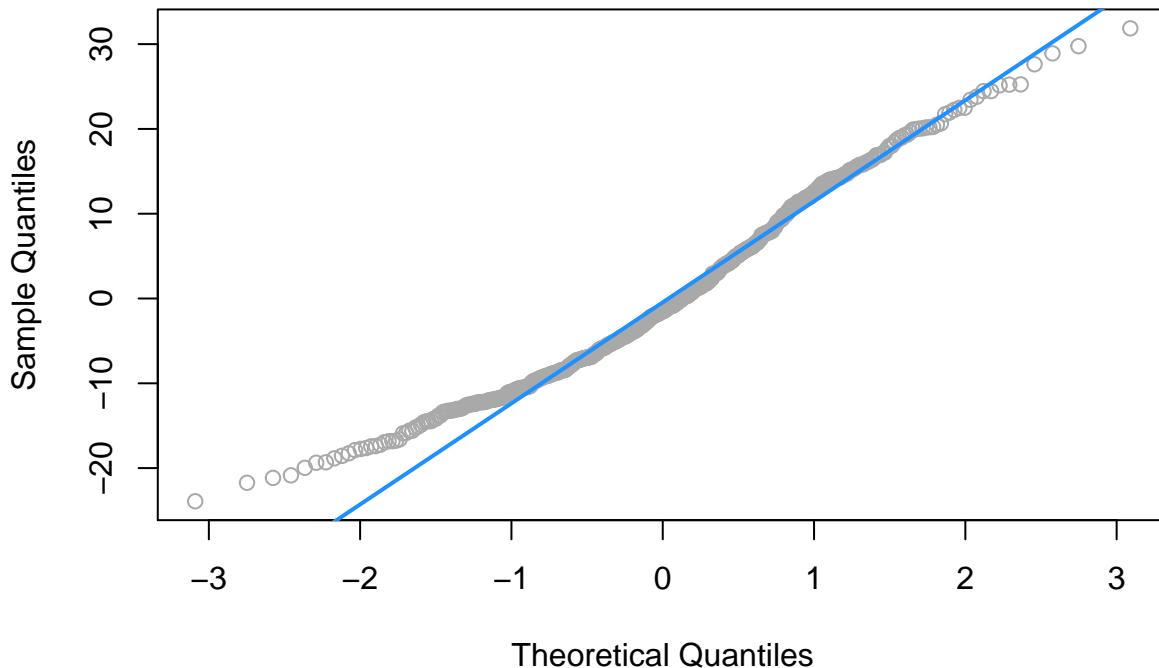
```
qqnorm(resid(fit_2), main = "Normal Q-Q Plot, fit_2", col = "darkgrey")
qqline(resid(fit_2), col = "dodgerblue", lwd = 2)
```



For `fit_2`, we have a suspect Q-Q plot. We would probably **not** believe the errors follow a normal distribution.

```
qqnorm(resid(fit_3), main = "Normal Q-Q Plot, fit_3", col = "darkgrey")
qqline(resid(fit_3), col = "dodgerblue", lwd = 2)
```

Normal Q–Q Plot, fit_3



Lastly, for `fit_3`, we again have a suspect Q–Q plot. We would probably **not** believe the errors follow a normal distribution.

12.2.5 Shapiro-Wilk Test

Histograms and Q–Q Plots give a nice visual representation of the residuals distribution, however if we are interested in formal testing, there are a number of options available. A commonly used test is the **Shapiro–Wilk test**, which is implemented in R.

```
set.seed(42)
shapiro.test(rnorm(25))

##
##  Shapiro-Wilk normality test
##
## data: rnorm(25)
## W = 0.9499, p-value = 0.2495

shapiro.test(rexp(25))

##
##  Shapiro-Wilk normality test
##
## data: rexp(25)
## W = 0.71164, p-value = 0.0000105
```

This gives us the value of the test statistic and its p-value. The null hypothesis assumes the data were sampled from a normal distribution, thus a small p-value indicates we believe there is only a small probability the data could have been sampled from a normal distribution.

For details, see: Wikipedia: Shapiro–Wilk test.

In the above examples, we see we fail to reject for the data sampled from normal, and reject on the non-normal data, for any reasonable α .

Returning again to `fit_1`, `fit_2` and `fit_3`, we see the result of running `shapiro.test()` on the residuals of each, returns a result for each that matches for decisions based on the Q-Q plots.

```
shapiro.test(resid(fit_1))

##
##  Shapiro-Wilk normality test
##
## data:  resid(fit_1)
## W = 0.99858, p-value = 0.9622

shapiro.test(resid(fit_2))

##
##  Shapiro-Wilk normality test
##
## data:  resid(fit_2)
## W = 0.93697, p-value = 1.056e-13

shapiro.test(resid(fit_3))

##
##  Shapiro-Wilk normality test
##
## data:  resid(fit_3)
## W = 0.97643, p-value = 0.0000003231
```

12.3 Unusual Observations

In addition to checking the assumptions of regression, we also look for any “unusual observations” in the data. Often a small number of data points can have an extremely large influence on a regression, sometimes so much so that the regression assumptions are violated as a result of these points.

The following three plots are inspired by an example from Linear Models with R.

```
par(mfrow = c(1, 3))
set.seed(42)
ex_data  = data.frame(x = 1:10,
                      y = 10:1 + rnorm(n = 10))
ex_model = lm(y ~ x, data = ex_data)

# low leverage, large residual, small influence
point_1 = c(5.4, 11)
ex_data_1 = rbind(ex_data, point_1)
model_1 = lm(y ~ x, data = ex_data_1)
plot(y ~ x, data = ex_data_1, cex = 2, pch = 20, col = "grey",
```

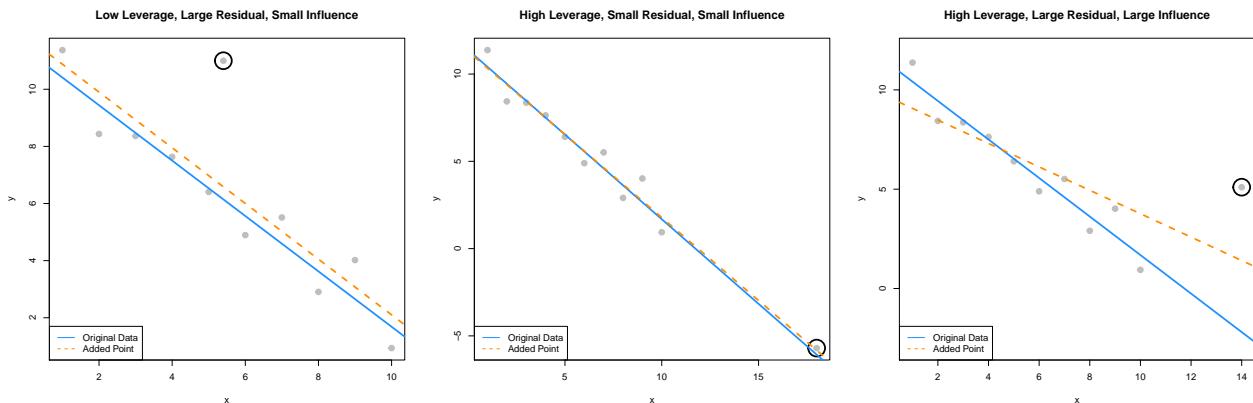
```

main = "Low Leverage, Large Residual, Small Influence")
points(x = point_1[1], y = point_1[2], pch = 1, cex = 4, col = "black", lwd = 2)
abline(ex_model, col = "dodgerblue", lwd = 2)
abline(model_1, lty = 2, col = "darkorange", lwd = 2)
legend("bottomleft", c("Original Data", "Added Point"),
       lty = c(1, 2), col = c("dodgerblue", "darkorange"))

# high leverage, small residual, small influence
point_2 = c(18, -5.7)
ex_data_2 = rbind(ex_data, point_2)
model_2 = lm(y ~ x, data = ex_data_2)
plot(y ~ x, data = ex_data_2, cex = 2, pch = 20, col = "grey",
     main = "High Leverage, Small Residual, Small Influence")
points(x = point_2[1], y = point_2[2], pch = 1, cex = 4, col = "black", lwd = 2)
abline(ex_model, col = "dodgerblue", lwd = 2)
abline(model_2, lty = 2, col = "darkorange", lwd = 2)
legend("bottomleft", c("Original Data", "Added Point"),
       lty = c(1, 2), col = c("dodgerblue", "darkorange"))

# high leverage, large residual, large influence
point_3 = c(14, 5.1)
ex_data_3 = rbind(ex_data, point_3)
model_3 = lm(y ~ x, data = ex_data_3)
plot(y ~ x, data = ex_data_3, cex = 2, pch = 20, col = "grey", ylim = c(-3, 12),
     main = "High Leverage, Large Residual, Large Influence")
points(x = point_3[1], y = point_3[2], pch = 1, cex = 4, col = "black", lwd = 2)
abline(ex_model, col = "dodgerblue", lwd = 2)
abline(model_3, lty = 2, col = "darkorange", lwd = 2)
legend("bottomleft", c("Original Data", "Added Point"),
       lty = c(1, 2), col = c("dodgerblue", "darkorange"))

```



The blue solid line in each plot is a regression fit to the 10 original data points stored in `ex_data`. The dashed orange line in each plot is the result of adding a single point to the original data in `ex_data`. This additional point is indicated by the circled point.

The slope of the regression for the original ten points, the solid blue line, is given by:

```
coef(ex_model)[2]
```

```
##          x
## -0.9696033
```

The added point in the first plot has a *small* effect on the slope, which becomes:

```
coef(model_1) [2]
```

```
##           x
## -0.9749534
```

We will say that this point has low leverage, is an outlier due to its large residual, but has small influence.

The added point in the second plot also has a *small* effect on the slope, which is:

```
coef(model_2) [2]
```

```
##           x
## -0.9507397
```

We will say that this point has high leverage, is not an outlier due to its small residual, and has a very small influence.

Lastly, the added point in the third plot has a *large* effect on the slope, which is now:

```
coef(model_3) [2]
```

```
##           x
## -0.5892241
```

This added point is influential. It both has high leverage, and is an outlier due to its large residual.

We've now mentioned three new concepts: leverage, outliers, and influential points, each of which we will discuss in detail.

12.3.1 Leverage

A data point with high **leverage**, is a data point that *could* have a large influence when fitting the model.

Recall that,

$$\hat{\beta} = (X^\top X)^{-1} X^\top y.$$

Thus,

$$\hat{y} = X \hat{\beta} = X (X^\top X)^{-1} X^\top y$$

Now we define,

$$H = X (X^\top X)^{-1} X^\top$$

which we will refer to as the *hat matrix*. The hat matrix is used to project onto the subspace spanned by the columns of X . It is also simply known as a projection matrix.

The hat matrix, is a matrix that takes the original y values, and adds a hat!

$$\hat{y} = Hy$$

The diagonal elements of this matrix are called the **leverages**

$$H_{ii} = h_i,$$

where h_i is the leverage for the i th observation.

Large values of h_i indicate extreme values in X , which may influence regression. Note that leverages only depend on X .

Here, p the number of β s is also the trace (and rank) of the hat matrix.

$$\sum_{i=1}^n h_i = p$$

What is a value of h_i that would be considered large? There is no exact answer to this question. A common heuristic would be to compare each leverage to two times the average leverage. A leverage larger than this is considered an observation to be aware of. That is, if

$$h_i > 2\bar{h}$$

we say that observation i has large leverage. Here,

$$\bar{h} = \frac{\sum_{i=1}^n h_i}{n} = \frac{p}{n}.$$

For simple linear regression, the leverage for each point is given by

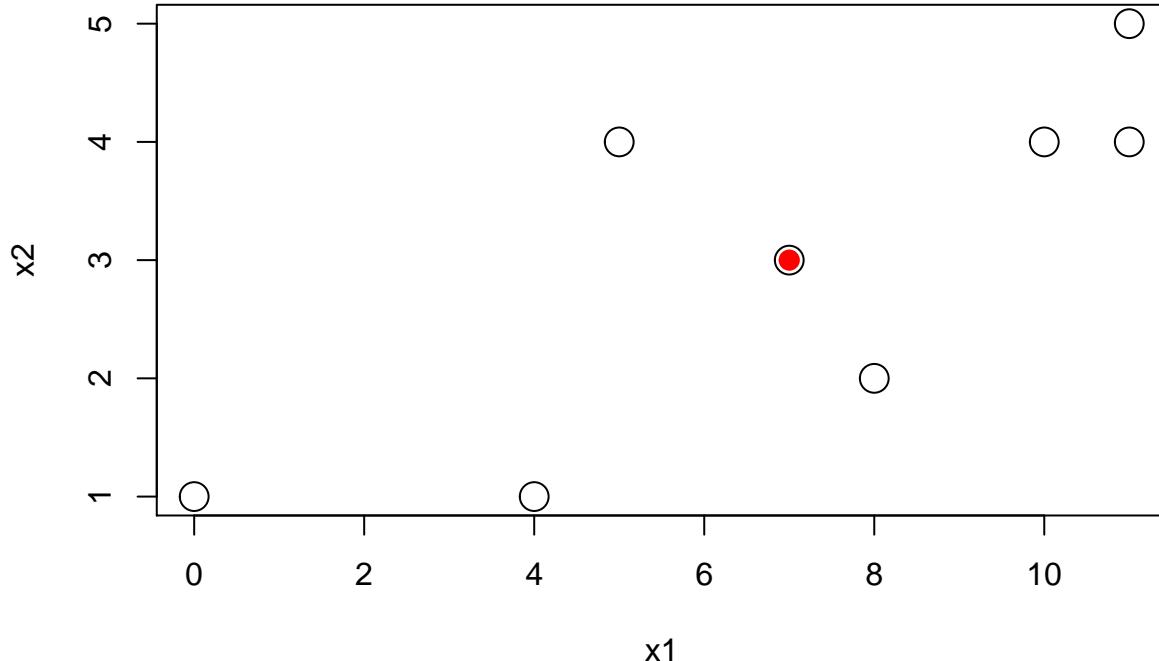
$$h_i = \frac{1}{n} + \frac{(x_i - \bar{x})^2}{S_{xx}}.$$

This expression should be familiar. (Think back to inference for SLR.) It suggests that the large leverages occur when x values are far from their mean. Recall that the regression goes through the point (\bar{x}, \bar{y}) .

There are multiple ways to find leverages in R.

```
lev_ex = data.frame(
  x1 = c(0, 11, 11, 7, 4, 10, 5, 8),
  x2 = c(1, 5, 4, 3, 1, 4, 4, 2),
  y  = c(11, 15, 13, 14, 0, 19, 16, 8))

plot(x2 ~ x1, data = lev_ex, cex = 2)
points(7, 3, pch = 20, col = "red", cex = 2)
```



Here we've created some multivariate data. Notice that we have plotted the x values, not the y values. The red point is $(7, 3)$ which is the mean of \mathbf{x}_1 and the mean of \mathbf{x}_2 respectively.

We could calculate the leverages using the expressions defined above. We first create the X matrix, then calculate H as defined, and extract the diagonal elements.

```
X = cbind(rep(1, 8), lev_ex$x1, lev_ex$x2)
H = X %*% solve(t(X) %*% X) %*% t(X)
diag(H)
```

```
## [1] 0.6000 0.3750 0.2875 0.1250 0.4000 0.2125 0.5875 0.4125
```

Notice here, we have two predictors, so the regression would have 3β parameters, so the sum of the diagonal elements is 3.

```
sum(diag(H))
```

```
## [1] 3
```

Alternatively, the method we will use more often, is to simply fit a regression, then use the `hatvalues()` function, which returns the leverages.

```
lev_fit = lm(y ~ ., data = lev_ex)
hatvalues(lev_fit)
```

```
##      1      2      3      4      5      6      7      8
## 0.6000 0.3750 0.2875 0.1250 0.4000 0.2125 0.5875 0.4125
```

Again, note that here we have “used” the y values to fit the regression, but R still ignores them when calculating the leverages, as leverages only depend on the x values.

```
coef(lev_fit)

## (Intercept)      x1      x2
##           3.7     -0.7      4.4
```

Let's see what happens to these coefficients when we modify the y value of the point with the highest leverage.

```
which.max(hatvalues(lev_fit))

## 1
## 1

lev_ex[which.max(hatvalues(lev_fit)),]

##   x1 x2  y
## 1  0  1 11
```

We see that the original y value is 11. We'll create a copy of the data, and modify this point to have a y value of 20.

```
lev_ex_1 = lev_ex
lev_ex_1$y[1] = 20
lm(y ~ ., data = lev_ex_1)

##
## Call:
## lm(formula = y ~ ., data = lev_ex_1)
##
## Coefficients:
## (Intercept)      x1      x2
##           8.875     -1.375      4.625
```

Notice the **large** changes in the coefficients. Also notice that each of the coefficients has changed in some way. Note that the leverages of the points would not have changed, as we have not modified any of the x values.

Now let's see what happens to these coefficients when we modify the y value of the point with the lowest leverage.

```
which.min(hatvalues(lev_fit))

## 4
## 4

lev_ex[which.min(hatvalues(lev_fit)),]

##   x1 x2  y
## 4  7  3 14
```

We see that the original y value is 14. We'll again create a copy of the data, and modify this point to have a y value of 30.

```
lev_ex_2 = lev_ex
lev_ex_2$y[4] = 30
lm(y ~ ., data = lev_ex_2)
```

```
##
## Call:
## lm(formula = y ~ ., data = lev_ex_2)
##
## Coefficients:
## (Intercept)          x1          x2
##           5.7         -0.7          4.4
```

This time despite a large change in the y value, there is only small change in the coefficients. Also, only the intercept has changed!

```
mean(lev_ex$x1)
```

```
## [1] 7
```

```
mean(lev_ex$x2)
```

```
## [1] 3
```

```
lev_ex[4,]
```

```
##   x1 x2  y
## 4  7  3 14
```

Notice that this point was the mean of both of the predictors.

Returning to our three plots, each with an added point, we can calculate the leverages for each. Note that the 11th data point each time is the added data point.

```
hatvalues(model_1)
```

```
##           1           2           3           4           5           6           7
## 0.33534597 0.23860732 0.16610842 0.11784927 0.09382988 0.09405024 0.11851036
##           8           9          10          11
## 0.16721022 0.24014985 0.33732922 0.09100926
```

```
hatvalues(model_2)
```

```
##           1           2           3           4           5           6           7
## 0.23238866 0.18663968 0.14979757 0.12186235 0.10283401 0.09271255 0.09149798
##           8           9          10          11
## 0.09919028 0.11578947 0.14129555 0.66599190
```

```
hatvalues(model_3)
```

```
##          1          2          3          4          5          6          7
## 0.27852761 0.21411043 0.16319018 0.12576687 0.10184049 0.09141104 0.09447853
##          8          9         10         11
## 0.11104294 0.14110429 0.18466258 0.49386503
```

Are any of these large?

```
hatvalues(model_1) > 2 * mean(hatvalues(model_1))
```

```
##      1      2      3      4      5      6      7      8      9      10     11
## FALSE FALSE
```

```
hatvalues(model_2) > 2 * mean(hatvalues(model_2))
```

```
##      1      2      3      4      5      6      7      8      9      10     11
## FALSE TRUE
```

```
hatvalues(model_3) > 2 * mean(hatvalues(model_3))
```

```
##      1      2      3      4      5      6      7      8      9      10     11
## FALSE TRUE
```

We see that in the second and third plots, the added point is a point of high leverage. Recall that only in the third plot did that have an influence on the regression. To understand why, we'll need to discuss outliers.

12.3.2 Outliers

Outliers are points which do not fit the model well. They may or may not have a large affect on the model. To identify outliers, we will look for observations with large residuals.

Note,

$$e = y - \hat{y} = Iy - Hy = (I - H)y$$

Then, under the assumptions of linear regression,

$$\text{Var}(e_i) = (1 - h_i)\sigma^2$$

and thus estimating σ^2 with s_e^2 gives

$$\text{SE}[e_i] = s_e \sqrt{(1 - h_i)}.$$

We can then look at the **standardized residual** for each observation, $i = 1, 2, \dots, n$,

$$r_i = \frac{e_i}{s_e \sqrt{1 - h_i}} \stackrel{\text{approx}}{\sim} N(\mu = 0, \sigma^2 = 1)$$

when n is large.

We can use this fact to identify “large” residuals. For example, standardized residuals greater than 2 in magnitude should only happen approximately 5 percent of the time.

Returning again to our three plots, each with an added point, we can calculate the residuals and standardized residuals for each. Standardized residuals can be obtained in R by using `rstandard()` where we would normally use `resid()`.

```
resid(model_1)
```

```
##      1      2      3      4      5      6      7
##  0.4949887 -1.4657145 -0.5629345 -0.3182468 -0.5718877 -1.1073271  0.4852728
##      8      9     10     11
## -1.1459548  0.9420814 -1.1641029  4.4138254
```

```
rstandard(model_1)
```

```
##      1      2      3      4      5      6      7
##  0.3464701 -0.9585470 -0.3517802 -0.1933575 -0.3428264 -0.6638841  0.2949482
##      8      9     10     11
## -0.7165857  0.6167268 -0.8160389  2.6418234
```

```
rstandard(model_1)[abs(rstandard(model_1)) > 2]
```

```
##      11
## 2.641823
```

In the first plot, we see that the 11th point, the added point, is a large standardized residual.

```
resid(model_2)
```

```
##      1      2      3      4      5      6
##  1.03288292 -0.95203397 -0.07346766  0.14700626 -0.13084829 -0.69050140
##      7      8      9     10     11
##  0.87788484 -0.77755647  1.28626601 -0.84413207  0.12449986
```

```
rstandard(model_2)
```

```
##      1      2      3      4      5      6
##  1.41447023 -1.26655590 -0.09559792  0.18822094 -0.16574677 -0.86977220
##      7      8      9     10     11
##  1.10506546 -0.98294409  1.64121833 -1.09295417  0.25846620
```

```
rstandard(model_2)[abs(rstandard(model_2)) > 2]
```

```
## named numeric(0)
```

In the second plot, we see that there are no points with large standardized residuals.

```
resid(model_3)
```

```
##          1          2          3          4          5          6
##  2.30296166 -0.04347087  0.47357980  0.33253808 -0.30683212 -1.22800087
##          7          8          9         10         11
## -0.02113027 -2.03808722 -0.33578039 -2.82769411  3.69191633
```

```
rstandard(model_3)
```

```
##          1          2          3          4          5          6
##  1.41302755 -0.02555591  0.26980722  0.18535382 -0.16873216 -0.67141143
##          7          8          9         10         11
## -0.01157256 -1.12656475 -0.18882474 -1.63206526  2.70453408
```

```
rstandard(model_3)[abs(rstandard(model_3)) > 2]
```

```
##          11
## 2.704534
```

In the last plot, we see that the 11th point, the added point, is a large standardized residual.

Recall that the added point in plots two and three were both high leverage, but now only the point in plot three has a large residual. We will now combine this information and discuss influence.

12.3.3 Influence

As we have now seen in the three plots, some outliers only change the regression a small amount (plot one) and some outliers have a large effect on the regression (plot three). Observations that fall into the later category, points with (some combination of) *high leverage and large residual*, we will call **influential**.

A common measure of influence is **Cook's Distance**, which is defined as

$$D_i = \frac{1}{p} r_i^2 \frac{h_i}{1 - h_i}.$$

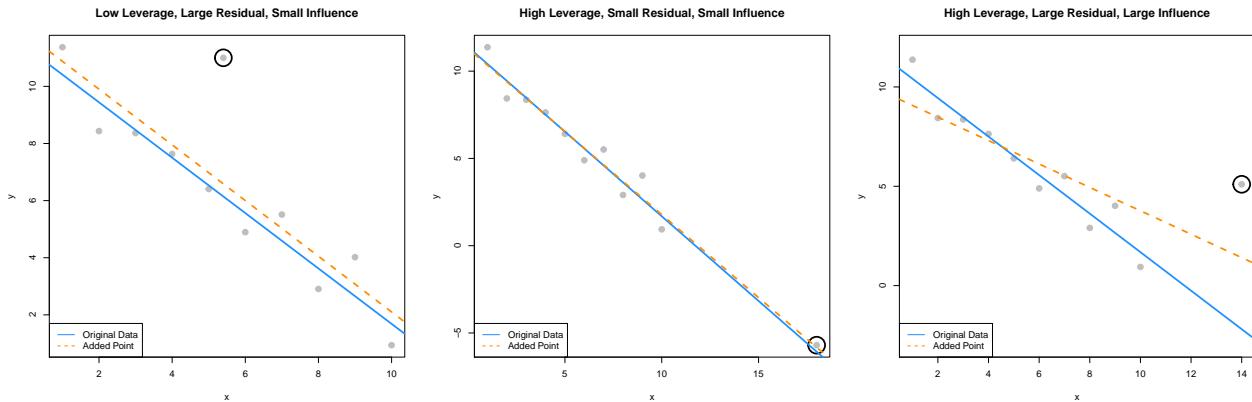
Notice that this is a function of both *leverage* and *standardized residuals*.

A Cook's Distance is often considered large if

$$D_i > \frac{4}{n}$$

and an observation with a large Cook's Distance is called influential. This is again simply a heuristic, and not an exact rule.

The Cook's distance for each point of a regression can be calculated using `cooks.distance()` which is a default function in R. Let's look for influential points in the three plots we had been considering.



Recall that the circled points in each plot have different characteristics:

- Plot One: low leverage, large residual.
- Plot Two: high leverage, small residual.
- Plot Three: high leverage, large residual.

We'll now directly check if each of these is influential.

```
cooks.distance(model_1)[11] > 4 / length(cooks.distance(model_1))
```

```
##      11
## FALSE
```

```
cooks.distance(model_2)[11] > 4 / length(cooks.distance(model_2))
```

```
##      11
## FALSE
```

```
cooks.distance(model_3)[11] > 4 / length(cooks.distance(model_3))
```

```
##      11
## TRUE
```

And, as expected, the added point in the third plot, with high leverage and a large residual is considered influential!

12.4 Data Analysis Examples

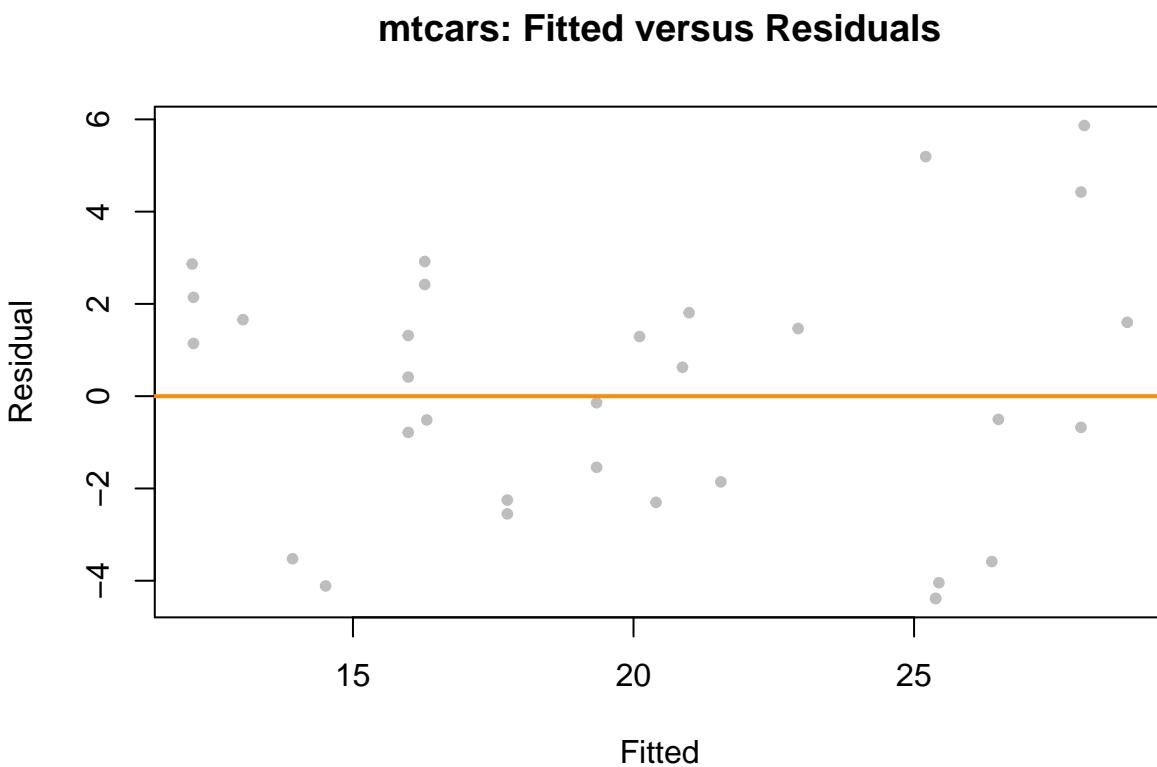
12.4.1 Good Diagnostics

Last chapter we fit an additive regression to the `mtcars` data with `mpg` as the response and `hp` and `am` as predictors. Let's perform some diagnostics on this model.

First, fit the model as we did last chapter.

```
mpg_hp_add = lm(mpg ~ hp + am, data = mtcars)

plot(fitted(mpg_hp_add), resid(mpg_hp_add), col = "grey", pch = 20,
      xlab = "Fitted", ylab = "Residual",
      main = "mtcars: Fitted versus Residuals")
abline(h = 0, col = "darkorange", lwd = 2)
```



The fitted versus residuals plot looks good. We don't see any obvious pattern, and the variance looks roughly constant. (Maybe a little larger for large fitted values, but not enough to worry about.)

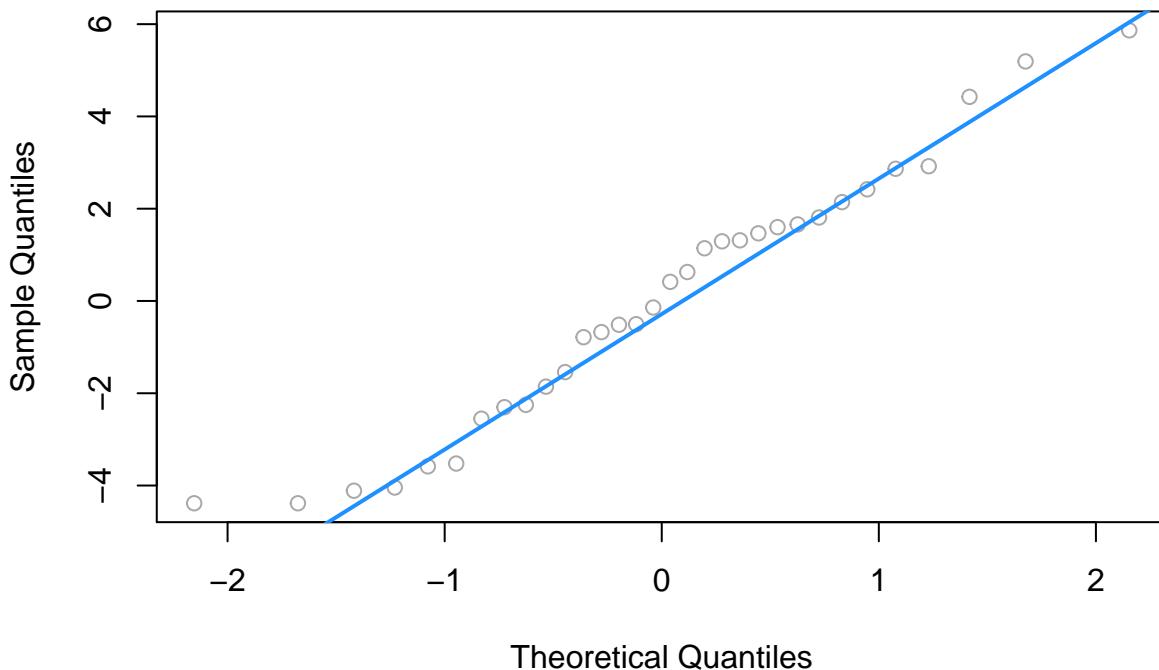
```
bptest(mpg_hp_add)
```

```
##  
## studentized Breusch-Pagan test  
##  
## data: mpg_hp_add  
## BP = 7.5858, df = 2, p-value = 0.02253
```

The Breusch-Pagan test verifies this, at least for a small α value.

```
qqnorm(resid(mpg_hp_add), col = "darkgrey")  
qqline(resid(mpg_hp_add), col = "dodgerblue", lwd = 2)
```

Normal Q–Q Plot



The Q–Q plot looks extremely good and the Shapiro-Wilk test agrees.

```
shapiro.test(resid(mpg_hp_add))

##
##  Shapiro-Wilk normality test
##
## data: resid(mpg_hp_add)
## W = 0.96485, p-value = 0.3706

sum(hatvalues(mpg_hp_add) > 2 * mean(hatvalues(mpg_hp_add)))
```

[1] 2

We see that there are two points of large leverage.

```
sum(abs(rstandard(mpg_hp_add)) > 2)

## [1] 1
```

There is also one point with a large residual. Do these result in any points that are considered influential?

```
cd_mpg_hp_add = cooks.distance(mpg_hp_add)
sum(cd_mpg_hp_add > 4 / length(cd_mpg_hp_add))
```

```
## [1] 2
```

```
large_cd_mpg = cd_mpg_hp_add > 4 / length(cd_mpg_hp_add)
cd_mpg_hp_add[large_cd_mpg]
```

```
## Toyota Corolla Maserati Bora
##      0.1772555      0.3447994
```

We find two influential points. Interestingly, they are **very** different cars.

```
coef(mpg_hp_add)
```

```
## (Intercept)          hp          am
## 26.5849137 -0.0588878 5.2770853
```

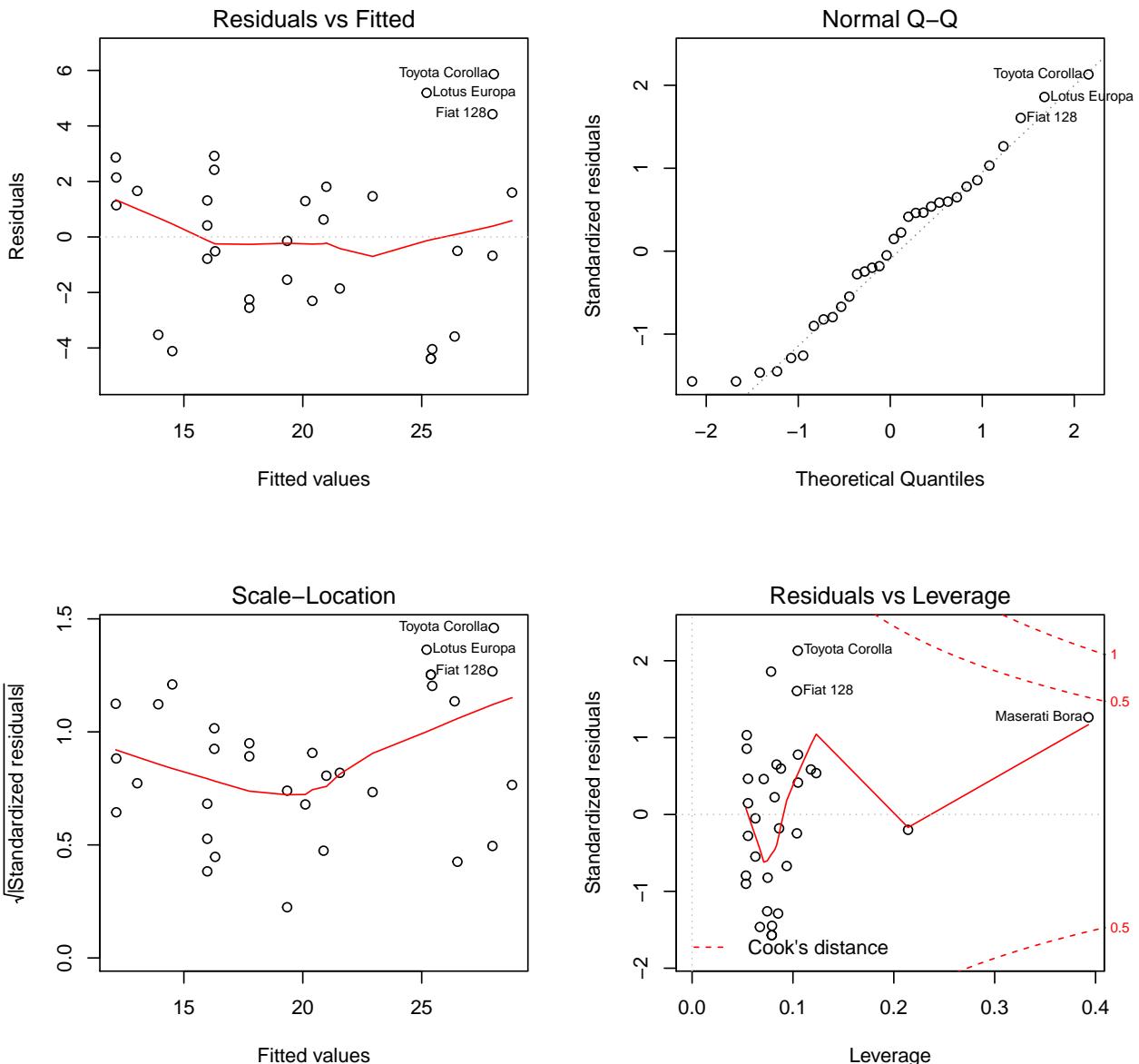
Since the diagnostics looked good, there isn't much need to worry about these two points, but let's see how much the coefficients change if we remove them.

```
mpg_hp_add_fix = lm(mpg ~ hp + am,
                     data = mtcars,
                     subset = cd_mpg_hp_add <= 4 / length(cd_mpg_hp_add))
coef(mpg_hp_add_fix)
```

```
## (Intercept)          hp          am
## 27.22190933 -0.06286249 4.29765867
```

It seems there isn't much of a change in the coefficients as a results of removing the supposed influential points. Notice we did not create a new dataset to accomplish this. We instead used the `subset` argument to `lm()`. Think about what the code `cd_mpg_hp_add <= 4 / length(cd_mpg_hp_add)` does here.

```
par(mfrow = c(2, 2))
plot(mpg_hp_add)
```



Notice that, calling `plot()` on a variable which stores an object created by `lm()` outputs four diagnostic plots by default. Use `?plot.lm` to learn more. The first two should already be familiar.

12.4.2 Suspect Diagnostics

Let's consider the model `big_model` from last chapter which was fit to the `autompq` dataset. It used `mpg` as the response, and considered many interaction terms between the predictors `disp`, `hp`, and `domestic`.

```
str(autompq)
```

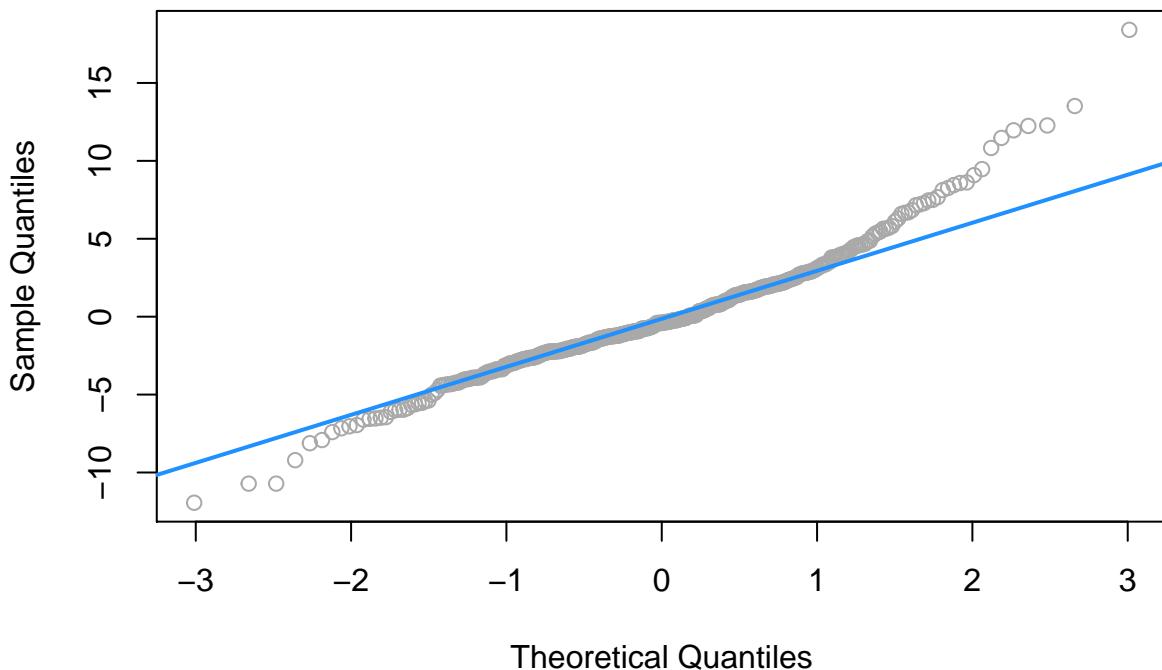
```
## 'data.frame':    383 obs. of  9 variables:
## $ mpg      : num  18 15 18 16 17 15 14 14 14 15 ...
## $ cyl      : Factor w/ 3 levels "4","6","8": 3 3 3 3 3 3 3 3 3 3 ...
## $ disp     : num  307 350 318 304 302 429 454 440 455 390 ...
## $ hp       : num  130 165 150 150 140 198 220 215 225 190 ...
```

```
## $ wt      : num  3504 3693 3436 3433 3449 ...
## $ acc     : num  12 11.5 11 12 10.5 10 9 8.5 10 8.5 ...
## $ year    : int  70 70 70 70 70 70 70 70 70 70 ...
## $ origin  : int  1 1 1 1 1 1 1 1 1 1 ...
## $ domestic: num  1 1 1 1 1 1 1 1 1 1 ...
```

```
big_model = lm(mpg ~ disp * hp * domestic, data = autompg)
```

```
qqnorm(resid(big_model), col = "darkgrey")
qqline(resid(big_model), col = "dodgerblue", lwd = 2)
```

Normal Q–Q Plot



```
shapiro.test(resid(big_model))
```

```
##
## Shapiro-Wilk normality test
##
## data: resid(big_model)
## W = 0.96161, p-value = 0.00000001824
```

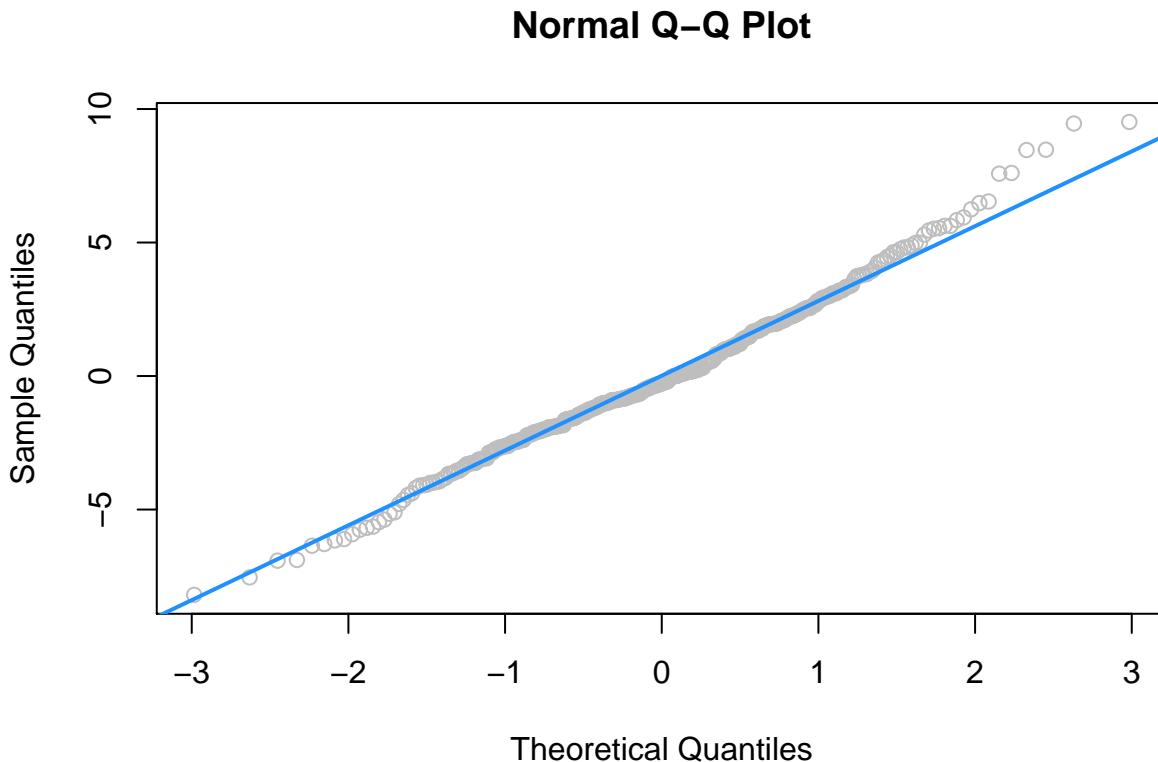
Here both the Q–Q plot, and the Shapiro-Wilk test suggest that the normality assumption is violated.

```
big_mod_cd = cooks.distance(big_model)
sum(big_mod_cd > 4 / length(big_mod_cd))
```

```
## [1] 31
```

Here, we find 31, so perhaps removing them will help!

```
big_model_fix = lm(mpg ~ disp * hp * domestic,
                    data = autompg,
                    subset = big_mod_cd < 4 / length(big_mod_cd))
qqnorm(resid(big_model_fix), col = "grey")
qqline(resid(big_model_fix), col = "dodgerblue", lwd = 2)
```



```
shapiro.test(resid(big_model_fix))

##
##  Shapiro-Wilk normality test
##
## data: resid(big_model_fix)
## W = 0.99035, p-value = 0.02068
```

Removing these points results in a much better Q-Q plot, and now Shapiro-Wilk fails to reject for a low α . We've now seen that sometimes modifying the data can fix issues with regression. However, next chapter, instead of modifying the data, we will modify the model via *transformations*.

Chapter 13

Transformations

“Give me a lever long enough and a fulcrum on which to place it, and I shall move the world.”

— Archimedes

After reading this chapter you will be able to:

- Understand the concept of a variance stabilizing transformation.
- Use transformations of the response to improve regression models.
- Use polynomial terms as predictors to fit more flexible regression models.

Last chapter we checked the assumptions of regression models and looked at ways to diagnose possible issues. This chapter we will use transformations of both response and predictor variables in order to correct issues with model diagnostics, and to also potentially simply make a model fit data better.

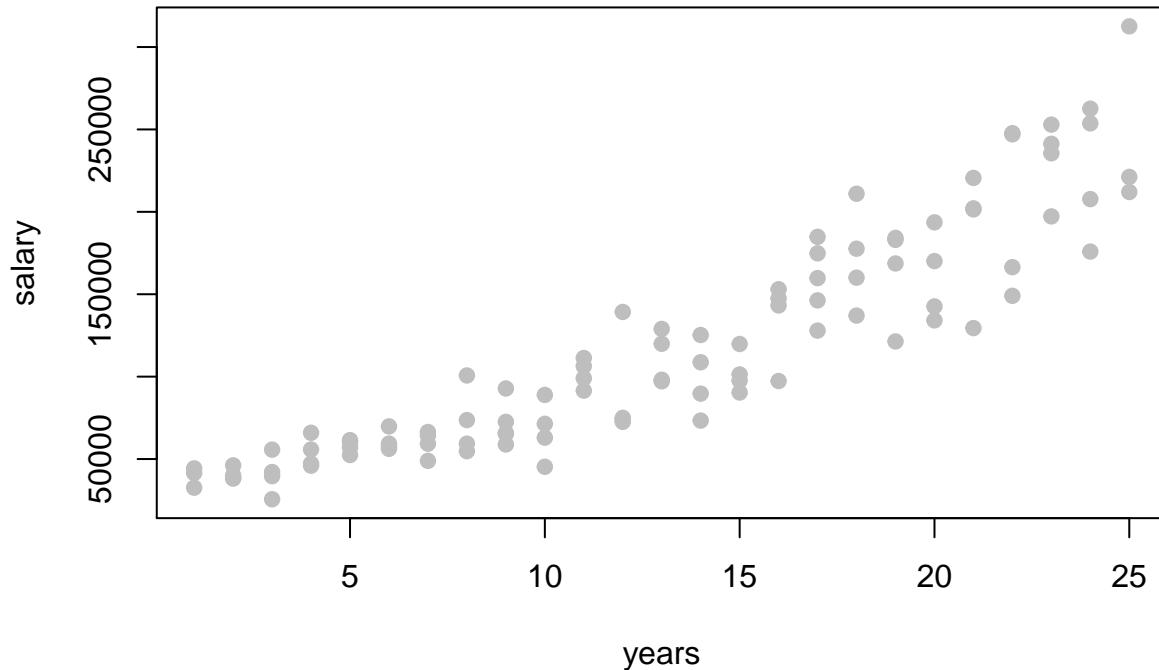
Note to current students: Please see the note at the end of this chapter. Also be aware that the code seen in the videos can be found in the a temporary chapter here.

13.1 Response Transformation

Let’s look at some (*fictional*) salary data from the (*fictional*) company *Initech*. We will try to model `salary` as a function of `years` of experience. The data can be found in `initech.csv`.

```
initech = read.csv("data/initech.csv")  
  
plot(salary ~ years, data = initech, col = "grey", pch = 20, cex = 1.5,  
      main = "Salaries at Initech, By Seniority")
```

Salaries at Initech, By Seniority



We first fit a simple linear model.

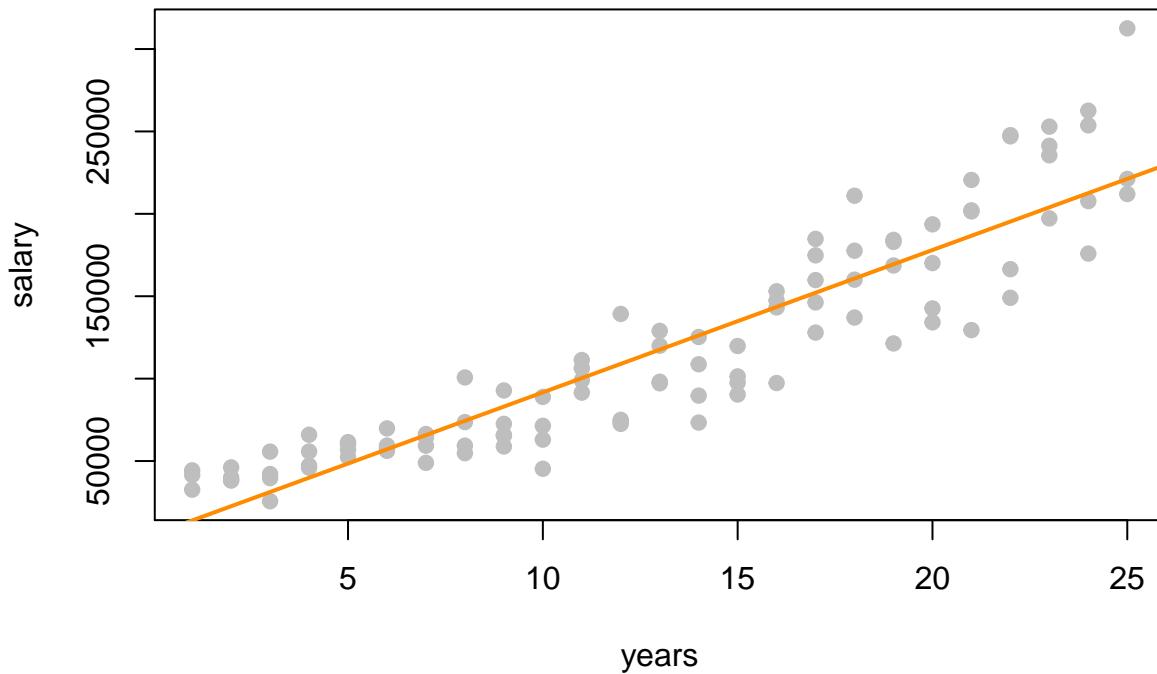
```
initech_fit = lm(salary ~ years, data = initech)
summary(initech_fit)

##
## Call:
## lm(formula = salary ~ years, data = initech)
##
## Residuals:
##    Min     1Q Median     3Q    Max 
## -57225 -18104    241  15589  91332 
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)    
## (Intercept)  5302       5750   0.922   0.359    
## years        8637       389   22.200  <2e-16 *** 
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 27360 on 98 degrees of freedom
## Multiple R-squared:  0.8341, Adjusted R-squared:  0.8324 
## F-statistic: 492.8 on 1 and 98 DF,  p-value: < 2.2e-16
```

This model appears significant, but does it meet the model assumptions?

```
plot(salary ~ years, data = initech, col = "grey", pch = 20, cex = 1.5,
      main = "Salaries at Initech, By Seniority")
abline(initech_fit, col = "darkorange", lwd = 2)
```

Salaries at Initech, By Seniority

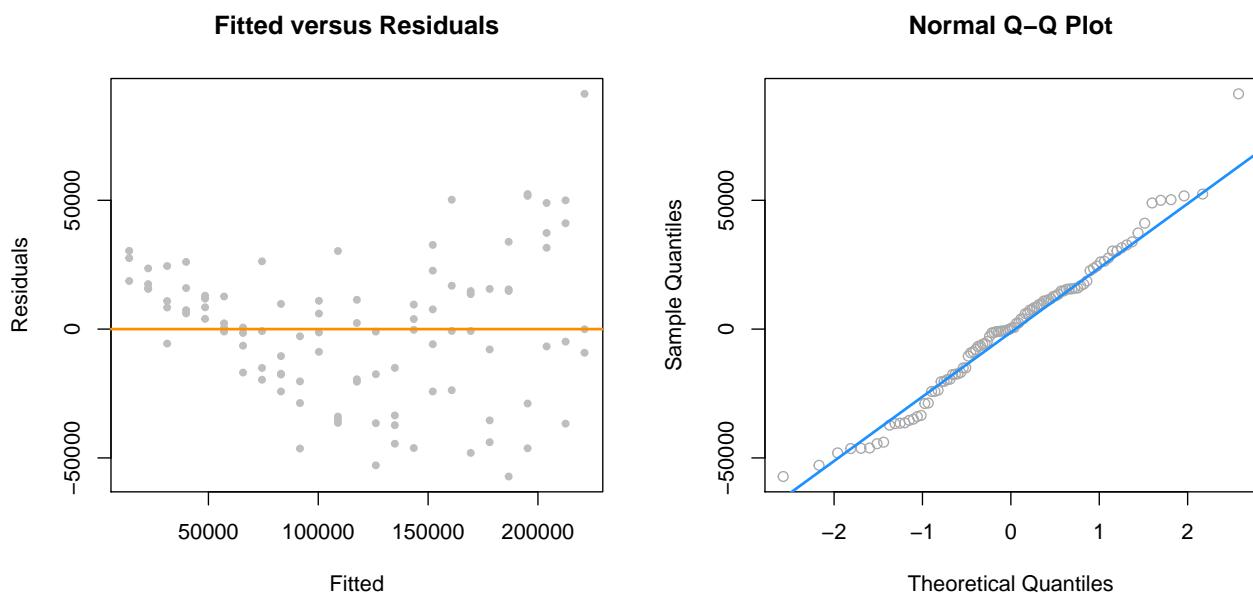


Adding the fitted line to the plot, we see that the linear relationship appears correct.

```
par(mfrow = c(1, 2))

plot(fitted(initech_fit), resid(initech_fit), col = "grey", pch = 20,
      xlab = "Fitted", ylab = "Residuals", main = "Fitted versus Residuals")
abline(h = 0, col = "darkorange", lwd = 2)

qqnorm(resid(initech_fit), main = "Normal Q-Q Plot", col = "darkgrey")
qqline(resid(initech_fit), col = "dodgerblue", lwd = 2)
```



However, from the fitted versus residuals plot it appears there is non-constant variance. Specifically, the variance increases as the fitted value increases.

13.1.1 Variance Stabilizing Transformations

Recall the fitted value is our estimate of the mean at a particular value of x . Under our usual assumptions,

$$\epsilon \sim N(0, \sigma^2)$$

and thus

$$\text{Var}[Y|X = x] = \sigma^2$$

which is a constant value for any value of x .

However, here we see that the variance is a function of the mean,

$$\text{Var}[Y | X = x] = h(\text{E}[Y | X = x]).$$

In this case, h is some increasing function.

In order to correct for this, we would like to find some function of Y , $g(Y)$ such that,

$$\text{Var}[g(Y) | X = x] = c$$

where c is a constant that does not depend on the mean, $\text{E}[Y | X = x]$. A transformation that accomplishes this is called a **variance stabilizing transformation**.

A common variance stabilizing transformation (VST) when we see increasing variance in a fitted versus residuals plot is $\log(Y)$. Also, if the values of a variable range over more than one order of magnitude and the variable is *strictly positive*, then replacing the variable by its logarithm is likely to be helpful.

A reminder, that for our purposes, \log and \ln are both the natural log. R uses \log to mean the natural log, unless a different base is specified.

We will now use a model with a log transformed response for the *Initech* data,

$$\log(Y_i) = \beta_0 + \beta_1 x_i + \epsilon_i.$$

Note, if we re-scale the model from a log scale back to the original scale of the data, we now have

$$Y_i = \exp(\beta_0 + \beta_1 x_i) \cdot \exp(\epsilon_i)$$

which has the errors entering the model in a multiplicative fashion.

Fitting this model in R requires only a minor modification to our formula specification.

```
initech_fit_log = lm(log(salary) ~ years, data = initech)
```

Note that while $\log(y)$ is considered the new response variable, we do not actually create a new variable in R, but simply transform the variable inside the model formula.

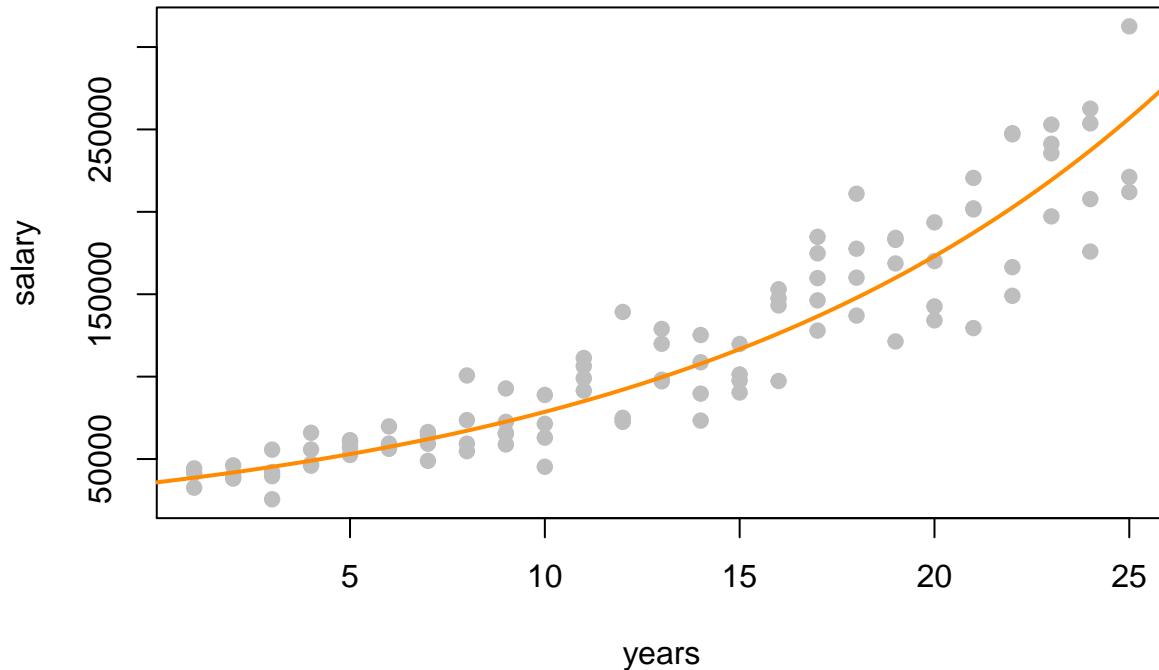
```
plot(log(salary) ~ years, data = initech, col = "grey", pch = 20, cex = 1.5,
     main = "Salaries at Initech, By Seniority")
abline(initech_fit_log, col = "darkorange", lwd = 2)
```



Plotting the data on the transformed log scale and adding the fitted line, the relationship again appears linear, and we can already see that the variation about the fitted line looks constant.

```
plot(salary ~ years, data = initech, col = "grey", pch = 20, cex = 1.5,
     main = "Salaries at Initech, By Seniority")
curve(exp(initech_fit_log$coef[1] + initech_fit_log$coef[2] * x),
      from = 0, to = 30, add = TRUE, col = "darkorange", lwd = 2)
```

Salaries at Initech, By Seniority

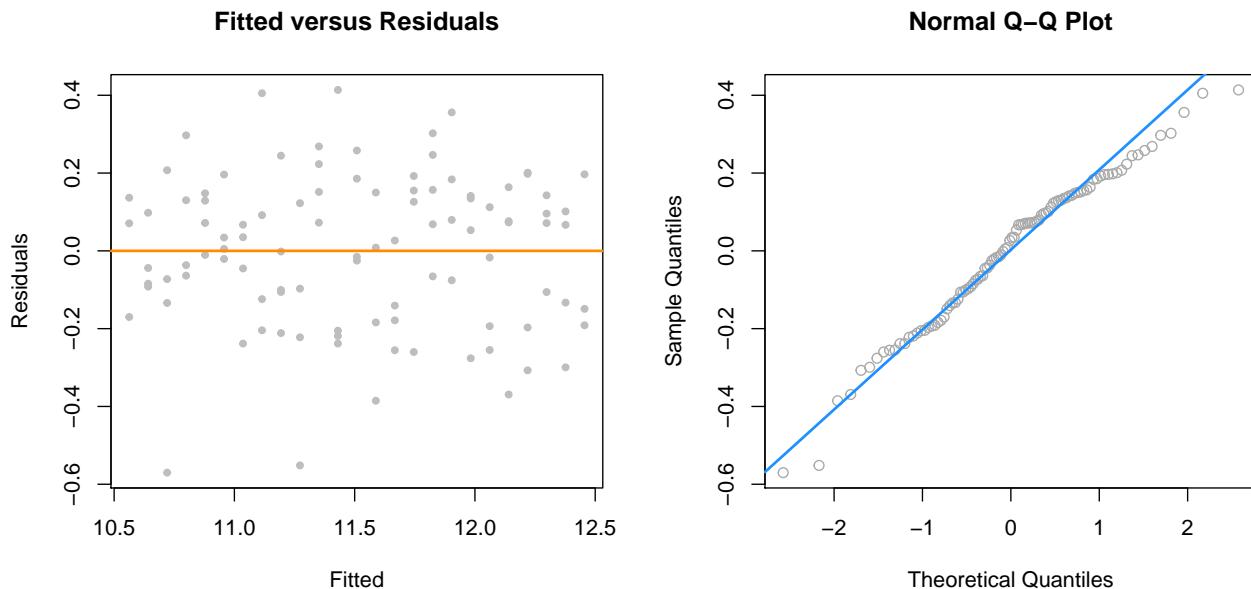


By plotting the data on the original scale, and adding the fitted regression, we see an exponential relationship. However, this is still a *linear* model, since the new transformed response, $\log(y)$, is still a *linear* combination of the predictors.

```
par(mfrow = c(1, 2))

plot(fitted(initech_fit_log), resid(initech_fit_log), col = "grey", pch = 20,
      xlab = "Fitted", ylab = "Residuals", main = "Fitted versus Residuals")
abline(h = 0, col = "darkorange", lwd = 2)

qqnorm(resid(initech_fit_log), main = "Normal Q-Q Plot", col = "darkgrey")
qqline(resid(initech_fit_log), col = "dodgerblue", lwd = 2)
```



The fitted versus residuals plot looks much better. It appears the constant variance assumption is no longer violated.

Comparing the RMSE using the original and transformed response, we also see that the log transformed model simply fits better, with a smaller average squared error.

```
sqrt(mean(resid(initech_fit) ^ 2))
```

```
## [1] 27080.16
```

```
sqrt(mean(resid(initech_fit_log) ^ 2))
```

```
## [1] 0.1934907
```

But wait, that isn't fair, this difference is simply due to the different scales being used.

```
sqrt(mean((itech$salary - fitted(initech_fit)) ^ 2))
```

```
## [1] 27080.16
```

```
sqrt(mean((itech$salary - exp(fitted(initech_fit_log))) ^ 2))
```

```
## [1] 24280.36
```

Transforming the fitted values of the log model back to the data scale, we do indeed see that it fits better!

```
summary(initech_fit_log)
```

```
##
## Call:
## lm(formula = log(salary) ~ years, data = initech)
##
```

```

## Residuals:
##      Min     1Q   Median     3Q    Max
## -0.57022 -0.13560  0.03048  0.14157  0.41366
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) 10.48381   0.04108 255.18 <2e-16 ***
## years       0.07888   0.00278  28.38 <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.1955 on 98 degrees of freedom
## Multiple R-squared:  0.8915, Adjusted R-squared:  0.8904
## F-statistic: 805.2 on 1 and 98 DF,  p-value: < 2.2e-16

```

Again, the transformed response is a *linear* combination of the predictors,

$$\log(\hat{y}(x)) = \hat{\beta}_0 + \hat{\beta}_1 x = 10.484 + 0.079x.$$

But now, if we re-scale the data from a log scale back to the original scale of the data, we now have

$$\hat{y}(x) = \exp(\hat{\beta}_0) \exp(\hat{\beta}_1 x) = \exp(10.484) \exp(0.079x).$$

We see that for every one additional year of experience, average salary increases $\exp(0.079) = 1.0822$ times. We are now multiplying, not adding.

While using a log transform is possibly the most common response variable transformation, many others exist. We will now consider a family of transformations and choose the best from among them, which includes the log transform.

13.1.2 Box-Cox Transformations

The Box-Cox method considers a family of transformations on strictly positive response variables,

$$g_\lambda(y) = \begin{cases} \frac{y^\lambda - 1}{\lambda} & \lambda \neq 0 \\ \log(y) & \lambda = 0 \end{cases}$$

The λ parameter is chosen by numerically maximizing the log-likelihood,

$$L(\lambda) = -\frac{n}{2} \log(RSS_\lambda/n) + (\lambda - 1) \sum \log(y_i).$$

A $100(1 - \alpha)\%$ confidence interval for λ is,

$$\left\{ \lambda : L(\lambda) > L(\hat{\lambda}) - \frac{1}{2} \chi^2_{1,\alpha} \right\}$$

which R will plot for us to help quickly select an appropriate λ value. We often choose a “nice” value from within the confidence interval, instead of the value of λ that truly maximizes the likelihood.

```
library(MASS)
library(faraway)
```

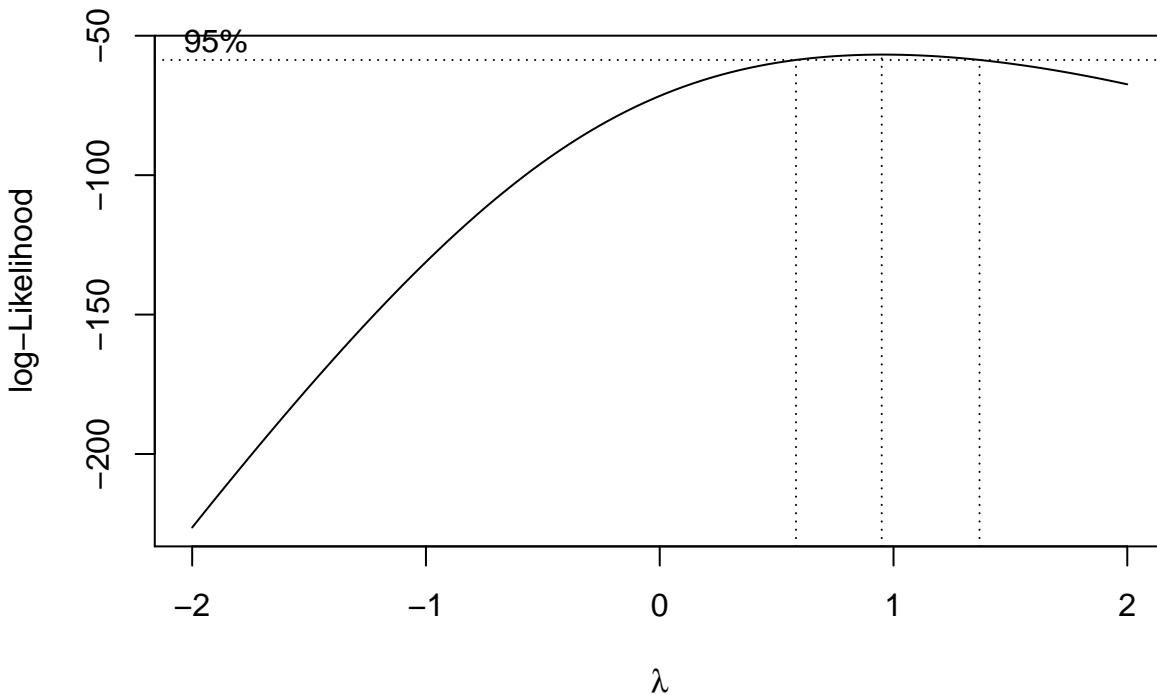
Here we need the `MASS` package for the `boxcox()` function, and we will consider a couple of datasets from the `faraway` package.

First we will use the `savings` dataset as an example of using the Box-Cox method to justify the use of no transformation. We fit an additive multiple regression model with `sr` as the response and each of the other variables as predictors.

```
savings_model = lm(sr ~ ., data = savings)
```

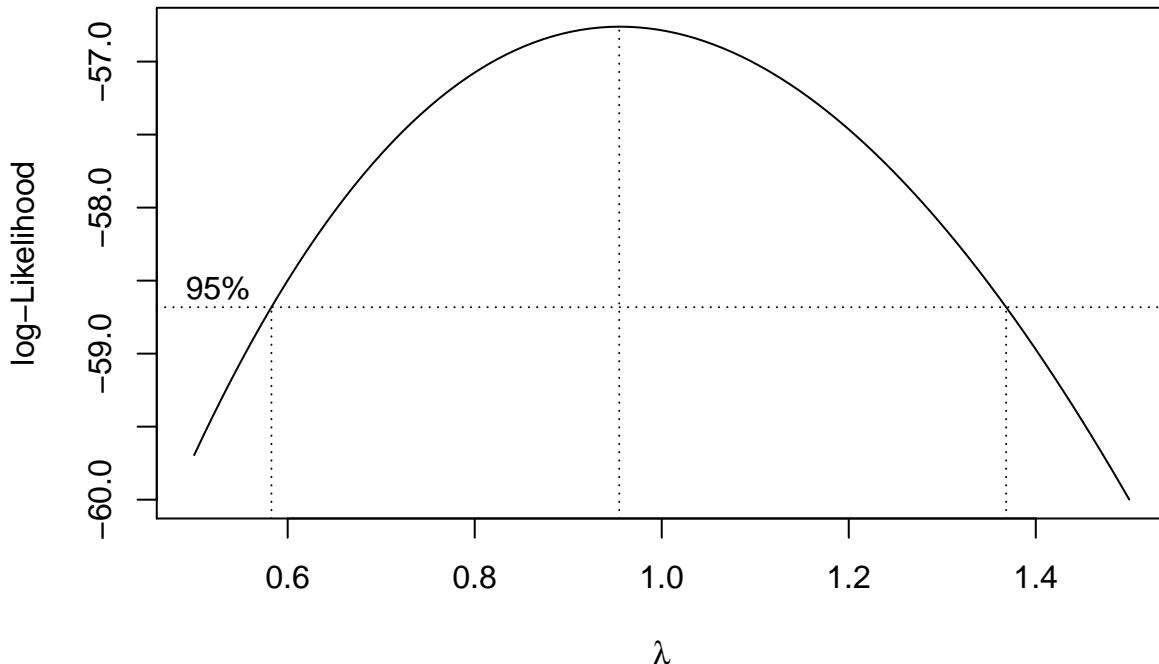
We then use the `boxcox()` function to find the best transformation of the form considered by the Box-Cox method.

```
boxcox(savings_model, plotit = TRUE)
```



R automatically plots the log-Likelihood as a function of possible λ values. It indicates both the value that maximizes the log-likelihood, as well as a confidence interval for the λ value that maximizes the log-likelihood.

```
boxcox(savings_model, plotit = TRUE, lambda = seq(0.5, 1.5, by = 0.1))
```

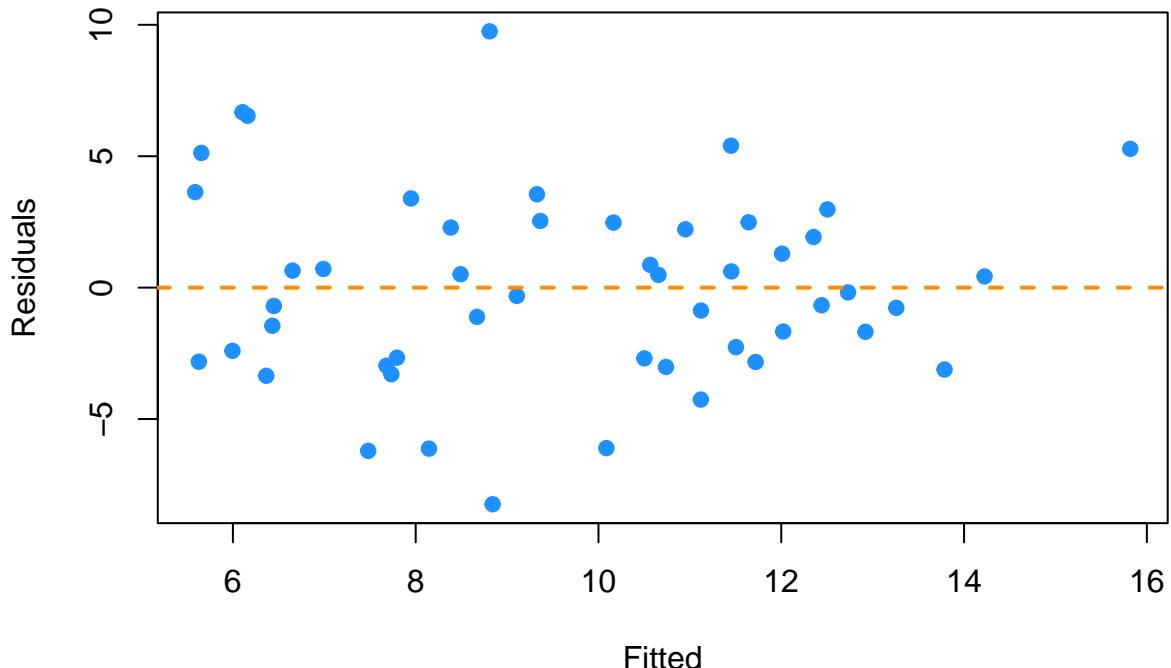


Note that we can specify a range of λ values to consider and thus be plotted. We often specify a range that is more visually interesting. Here we see that $\lambda = 1$ is both in the confidence interval, and is extremely close to the maximum. This suggests a transformation of the form

$$\frac{y^\lambda - 1}{\lambda} = \frac{y^1 - 1}{1} = y - 1.$$

This is essentially not a transformation. It would not change the variance or make the model fit better. By subtracting 1 from every value, we would only change the intercept of the model, and the resulting errors would be the same.

```
plot(fitted(savings_model), resid(savings_model), col = "dodgerblue",
      pch = 20, cex = 1.5, xlab = "Fitted", ylab = "Residuals")
abline(h = 0, lty = 2, col = "darkorange", lwd = 2)
```



Looking at a fitted versus residuals plot verifies that there likely are not any issue with the assumptions of this model, which Breusch-Pagan and Shapiro-Wilk tests verify.

```
library(lmtest)
btptest(savings_model)

##
## studentized Breusch-Pagan test
##
## data: savings_model
## BP = 4.9852, df = 4, p-value = 0.2888

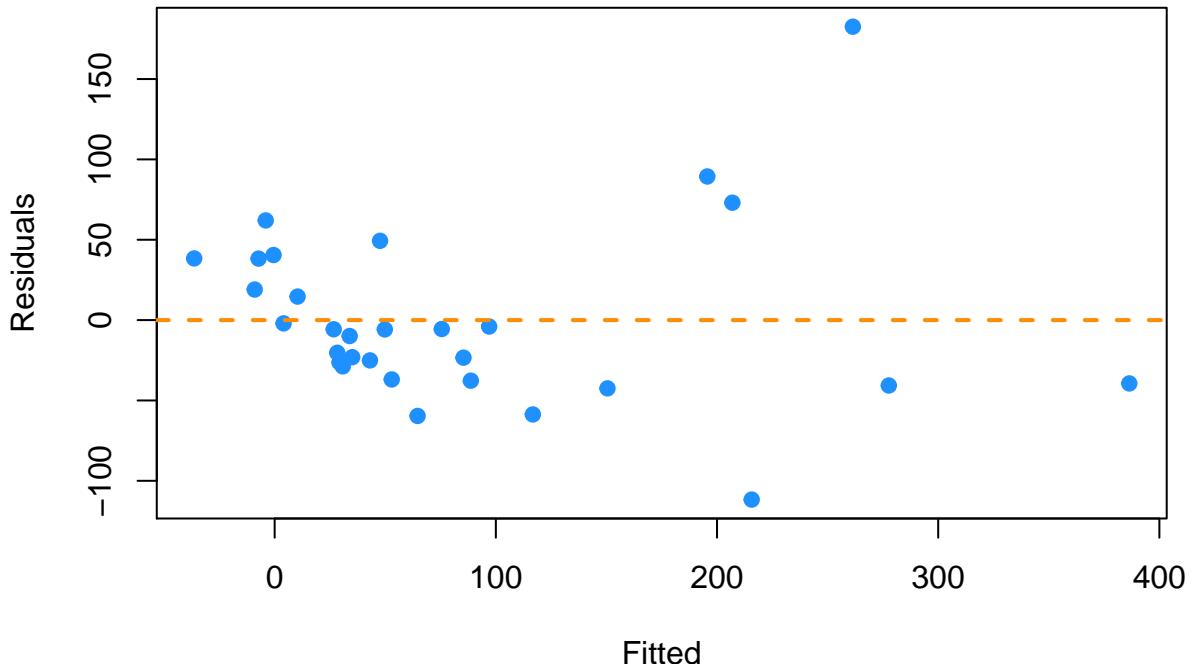
shapiro.test(resid(savings_model))

##
## Shapiro-Wilk normality test
##
## data: resid(savings_model)
## W = 0.98698, p-value = 0.8524
```

Now we will use the `gala` dataset as an example of using the Box-Cox method to justify a transformation other than log. We fit an additive multiple regression model with `Species` as the response and most of the other variables as predictors.

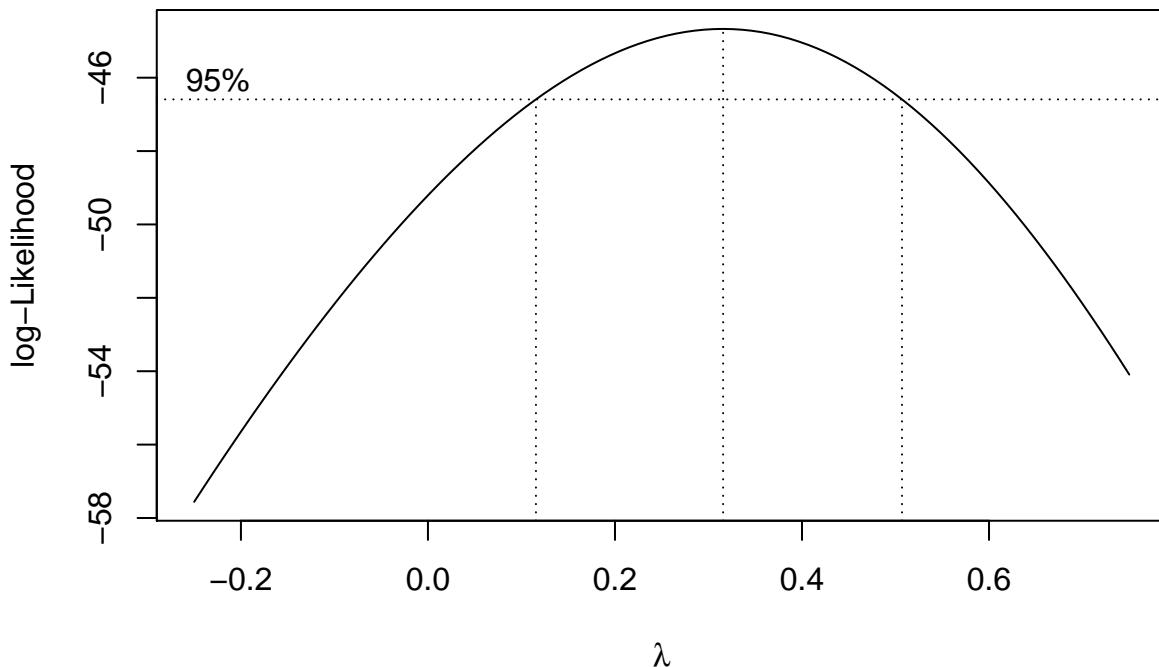
```
gala_model = lm(Species ~ Area + Elevation + Nearest + Scruz + Adjacent, data = gala)

plot(fitted(gala_model), resid(gala_model), col = "dodgerblue",
      pch = 20, cex = 1.5, xlab = "Fitted", ylab = "Residuals")
abline(h = 0, lty = 2, col = "darkorange", lwd = 2)
```



Even though there is not a lot of data for large fitted values, it still seems very clear that the constant variance assumption is violated.

```
boxcox(gala_model, lambda = seq(-0.25, 0.75, by = 0.05), plotit = TRUE)
```



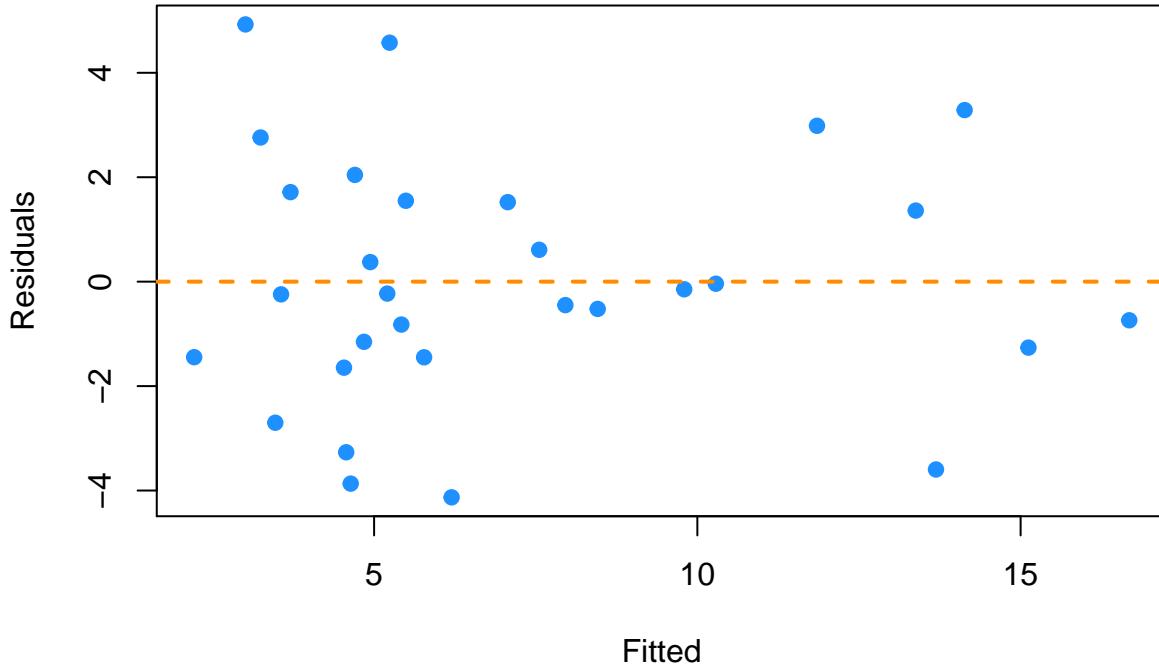
Using the Box-Cox method, we see that $\lambda = 0.3$ is both in the confidence interval, and is extremely close to the maximum, which suggests a transformation of the form

$$\frac{y^\lambda - 1}{\lambda} = \frac{y^{0.3} - 1}{0.3}.$$

We then fit a model with this transformation applied to the response.

```
gala_model_cox = lm(((Species ^ 0.3) - 1) / 0.3) ~ Area + Elevation + Nearest + Scruz + Adjacent, data = gala)
```

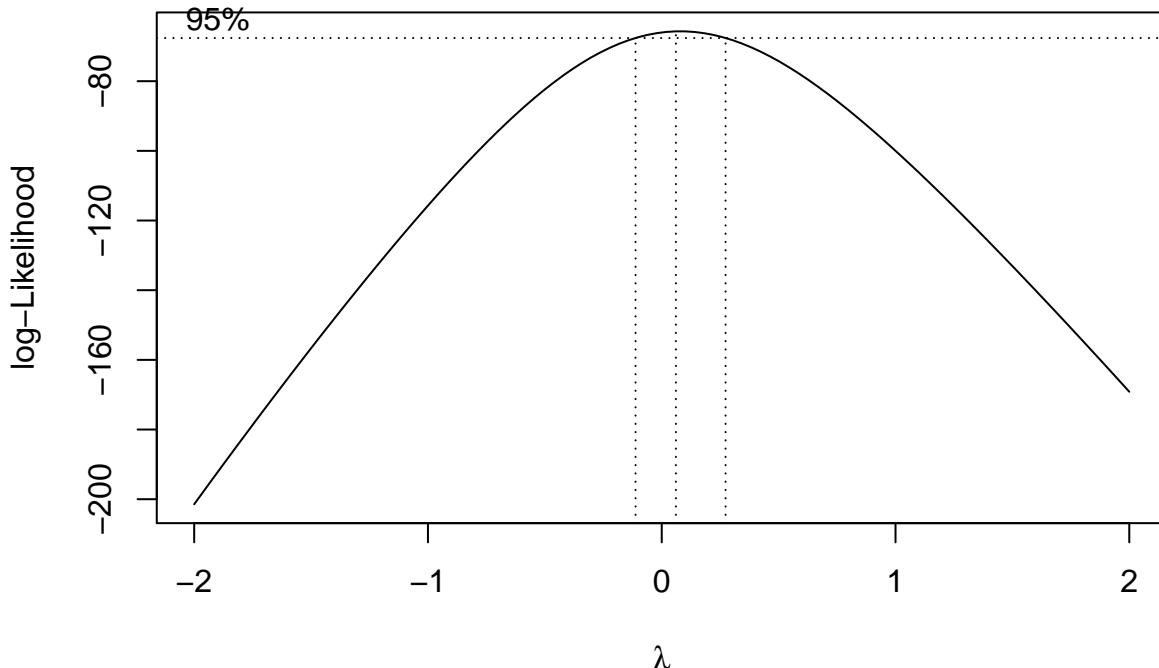
```
plot(fitted(gala_model_cox), resid(gala_model_cox), col = "dodgerblue",
      pch = 20, cex = 1.5, xlab = "Fitted", ylab = "Residuals")
abline(h = 0, lty = 2, col = "darkorange", lwd = 2)
```



The resulting fitted versus residuals plot looks much better!

Lastly, we return to the `initech` data, and the `initech_fit` model we had used earlier. Recall, that this was the untransformed model, that we used a log transform to fix.

```
boxcox(initech_fit)
```



Using the Box-Cox method, we see that $\lambda = 0$ is both in the interval, and extremely close to the maximum, which suggests a transformation of the form

$$\log(y).$$

So the Box-Cox method justifies our previous choice of a log transform!

13.2 Predictor Transformation

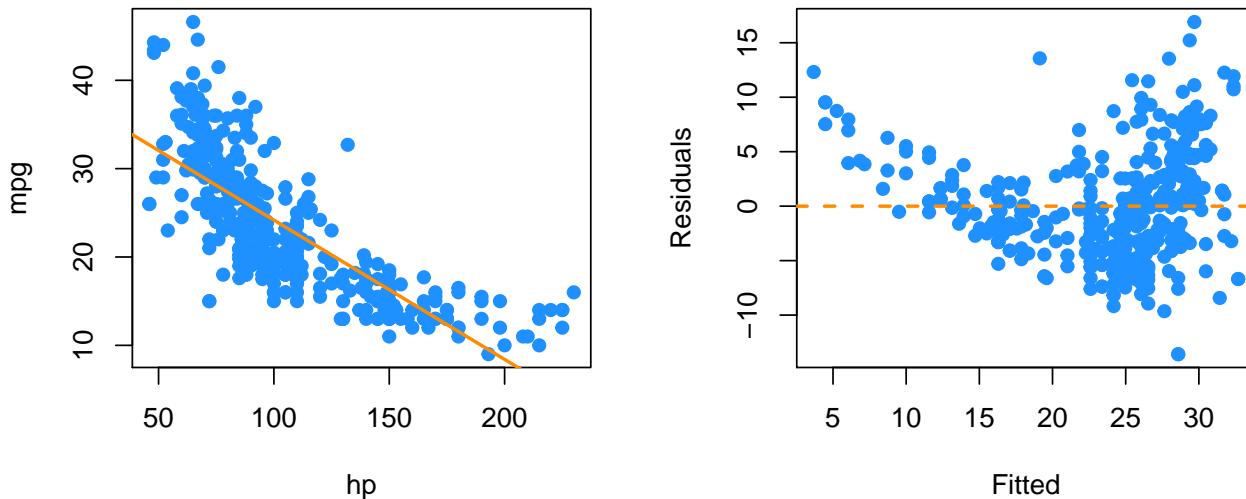
In addition to transformation of the response variable, we can also consider transformations of predictor variables. Sometimes these transformations can help with violation of model assumptions, and other times they can be used to simply fit a more flexible model.

```
str(autompg)
```

```
## 'data.frame':    383 obs. of  9 variables:
## $ mpg      : num  18 15 18 16 17 15 14 14 14 15 ...
## $ cyl      : Factor w/ 3 levels "4","6","8": 3 3 3 3 3 3 3 3 3 3 ...
## $ disp     : num  307 350 318 304 302 429 454 440 455 390 ...
## $ hp       : num  130 165 150 150 140 198 220 215 225 190 ...
## $ wt       : num  3504 3693 3436 3433 3449 ...
## $ acc      : num  12 11.5 11 12 10.5 10 9 8.5 10 8.5 ...
## $ year     : int  70 70 70 70 70 70 70 70 70 70 ...
## $ origin   : int  1 1 1 1 1 1 1 1 1 1 ...
## $ domestic: num  1 1 1 1 1 1 1 1 1 1 ...
```

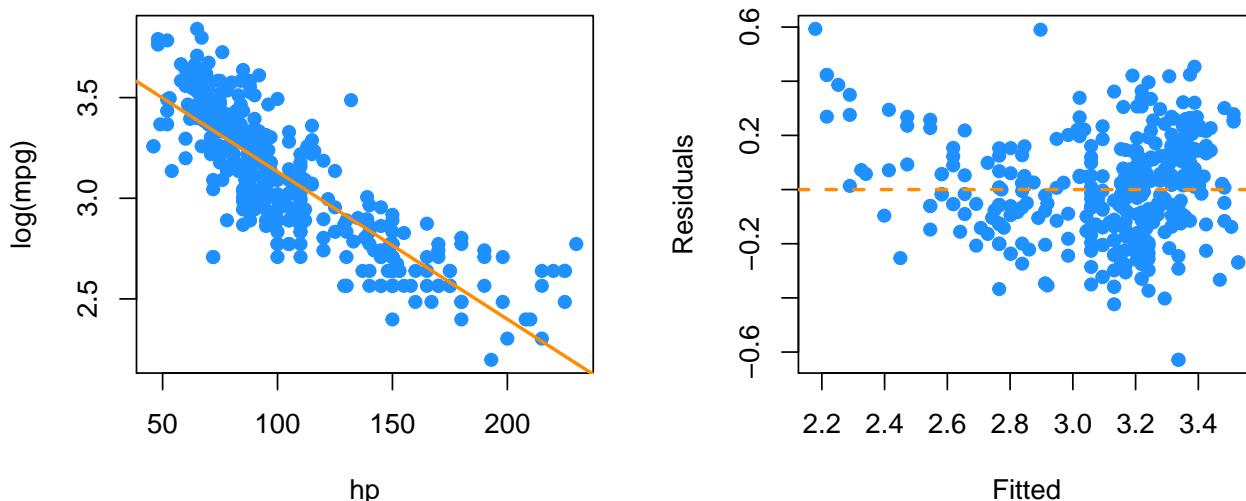
Recall the `autompg` dataset from the previous chapter. Here we will attempt to model `mpg` as a function of `hp`.

```
par(mfrow = c(1, 2))
plot(mpg ~ hp, data = autompg, col = "dodgerblue", pch = 20, cex = 1.5)
mpg_hp = lm(mpg ~ hp, data = autompg)
abline(mpg_hp, col = "darkorange", lwd = 2)
plot(fitted(mpg_hp), resid(mpg_hp), col = "dodgerblue",
      pch = 20, cex = 1.5, xlab = "Fitted", ylab = "Residuals")
abline(h = 0, lty = 2, col = "darkorange", lwd = 2)
```



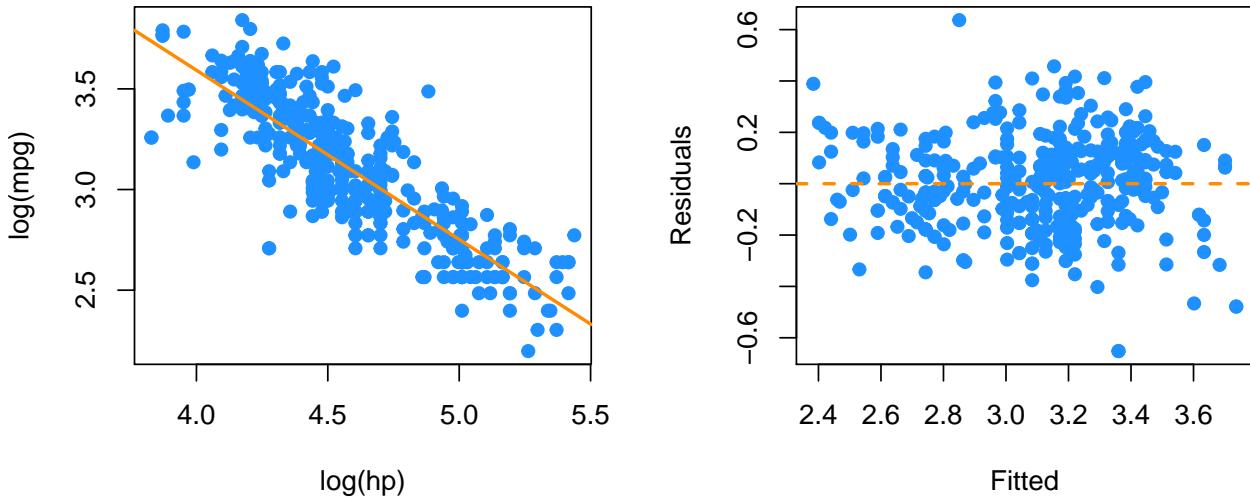
We first attempt SLR, but we see a rather obvious pattern in the fitted versus residuals plot, which includes increasing variance, so we attempt a log transform of the response.

```
par(mfrow = c(1, 2))
plot(log(mpg) ~ hp, data = autompg, col = "dodgerblue", pch = 20, cex = 1.5)
mpg_hp_log = lm(log(mpg) ~ hp, data = autompg)
abline(mpg_hp_log, col = "darkorange", lwd = 2)
plot(fitted(mpg_hp_log), resid(mpg_hp_log), col = "dodgerblue",
      pch = 20, cex = 1.5, xlab = "Fitted", ylab = "Residuals")
abline(h = 0, lty = 2, col = "darkorange", lwd = 2)
```



After performing the log transform of the response, we still have some of the same issues with the fitted versus response. Now, we will try also log transforming the **predictor**.

```
par(mfrow = c(1, 2))
plot(log(mpg) ~ log(hp), data = autompg, col = "dodgerblue", pch = 20, cex = 1.5)
mpg_hp_loglog = lm(log(mpg) ~ log(hp), data = autompg)
abline(mpg_hp_loglog, col = "darkorange", lwd = 2)
plot(fitted(mpg_hp_loglog), resid(mpg_hp_loglog), col = "dodgerblue",
      pch = 20, cex = 1.5, xlab = "Fitted", ylab = "Residuals")
abline(h = 0, lty = 2, col = "darkorange", lwd = 2)
```



Here, our fitted versus residuals plot looks good.

13.2.1 Polynomials

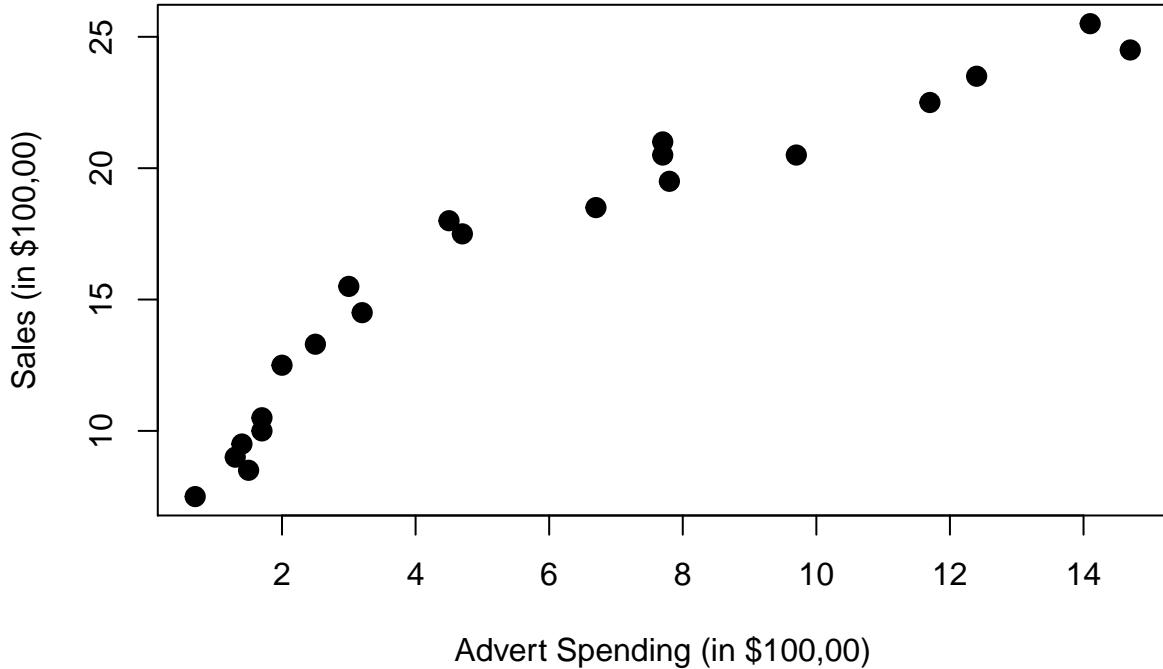
Another very common “transformation” of a predictor variable is the use of polynomial transformations. They are extremely useful as they allow for more flexible models, but do not change the units of the variables.

It should come as no surprise that sales of a product are related to the advertising budget for the product, but there are diminishing returns. A company cannot always expect linear returns based on an increased advertising budget.

Consider monthly data for the sales of *Initech* widgets, y , as a function of *Initech*'s advertising expenditure for said widget, x , both in ten thousand dollars. The data can be found in `marketing.csv`.

```
marketing = read.csv("data/marketing.csv")
```

```
plot(sales ~ advert, data = marketing,
      xlab = "Advert Spending (in $100,00)", ylab = "Sales (in $100,00)",
      pch = 20, cex = 2)
```



We would like to fit the model,

$$Y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \epsilon_i$$

where $\epsilon_i \sim N(0, \sigma^2)$ for $i = 1, 2, \dots, 21$.

The response y is now a **linear** function of “two” variables which now allows y to be a non-linear function of the original single predictor x . We consider this a transformation, although we have actually in some sense added another predictor.

Thus, our X matrix is,

$$\begin{bmatrix} 1 & x_1 & x_1^2 \\ 1 & x_2 & x_2^2 \\ 1 & x_3 & x_3^2 \\ \vdots & \vdots & \vdots \\ 1 & x_n & x_n^2 \end{bmatrix}$$

We can then proceed to fit the model as we have in the past for multiple linear regression.

$$\hat{\beta} = (X^\top X)^{-1} X^\top y.$$

Our estimates will have the usual properties. The mean is still

$$E[\hat{\beta}] = \beta,$$

and variance

$$\text{Var}[\hat{\beta}] = \sigma^2 (X^\top X)^{-1}.$$

We also maintain the same distributional results

$$\hat{\beta}_j \sim N(\beta_j, \sigma^2 C_{jj}).$$

```
mark_mod = lm(sales ~ advert, data = marketing)
summary(mark_mod)
```

```
##
## Call:
## lm(formula = sales ~ advert, data = marketing)
##
## Residuals:
##     Min      1Q  Median      3Q     Max 
## -2.7845 -1.4762 -0.5103  1.2361  3.1869 
## 
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)    
## (Intercept)  9.4502    0.6806   13.88 2.13e-11 ***
## advert       1.1918    0.0937   12.72 9.65e-11 ***  
## ---        
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
## 
## Residual standard error: 1.907 on 19 degrees of freedom
## Multiple R-squared:  0.8949, Adjusted R-squared:  0.8894 
## F-statistic: 161.8 on 1 and 19 DF,  p-value: 9.646e-11
```

While the SLR model is significant, the fitted versus residuals plot would have a very clear pattern.

```
mark_mod_poly2 = lm(sales ~ advert + I(advert ^ 2), data = marketing)
summary(mark_mod_poly2)
```

```
##
## Call:
## lm(formula = sales ~ advert + I(advert^2), data = marketing)
##
## Residuals:
##     Min      1Q  Median      3Q     Max 
## -1.9175 -0.8333 -0.1948  0.9292  2.1385 
## 
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)    
## (Intercept)  6.76161   0.67219  10.059 8.16e-09 ***
## advert       2.46231   0.24830   9.917 1.02e-08 ***  
## I(advert^2) -0.08745   0.01658  -5.275 5.14e-05 ***  
## ---        
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
## 
## Residual standard error: 1.228 on 18 degrees of freedom
## Multiple R-squared:  0.9587, Adjusted R-squared:  0.9541 
## F-statistic: 209 on 2 and 18 DF,  p-value: 3.486e-13
```

To add the second order term we need to use the `I()` function in the model specification around our newly created predictor. We see that with the first order term in the model, the quadratic term is also significant.

```

n = length(marketing$advert)
X = cbind(rep(1, n), marketing$advert, marketing$advert ^ 2)
t(X) %*% X

##          [,1]      [,2]      [,3]
## [1,]    21.00   120.70  1107.95
## [2,]   120.70  1107.95 12385.86
## [3,]  1107.95 12385.86 151369.12

solve(t(X) %*% X) %*% t(X) %*% marketing$sales

##          [,1]
## [1,]  6.76161045
## [2,]  2.46230964
## [3,] -0.08745394

```

Here we verify the parameter estimates were found as we would expect.

We could also add higher order terms, such as a third degree predictor. This is easy to do. Our X matrix simply becomes larger again.

$$Y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \beta_3 x_i^3 + \epsilon_i$$

$$\begin{bmatrix} 1 & x_1 & x_1^2 & x_1^3 \\ 1 & x_2 & x_2^2 & x_2^3 \\ 1 & x_3 & x_3^2 & x_3^3 \\ \vdots & \vdots & \vdots & \vdots \\ 1 & x_n & x_n^2 & x_n^3 \end{bmatrix}$$

```

mark_mod_poly3 = lm(sales ~ advert + I(advert ^ 2) + I(advert ^ 3), data = marketing)
summary(mark_mod_poly3)

```

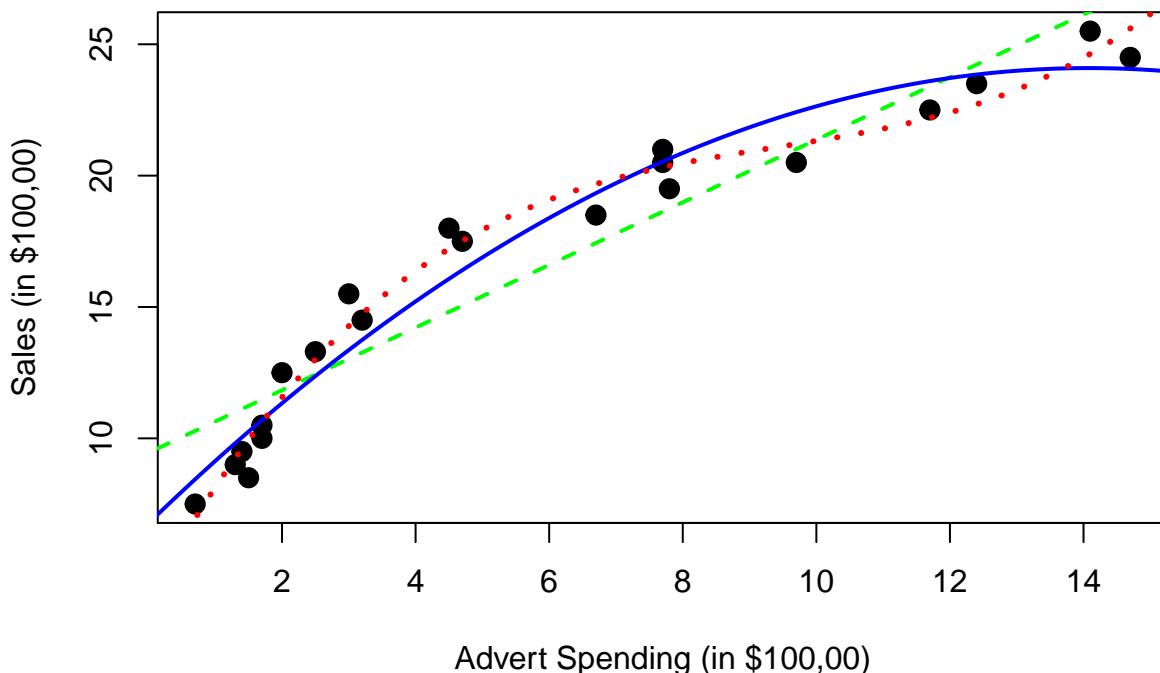
```

##
## Call:
## lm(formula = sales ~ advert + I(advert^2) + I(advert^3), data = marketing)
##
## Residuals:
##       Min     1Q   Median     3Q    Max 
## -1.44322 -0.61310 -0.01527  0.68131  1.22517 
##
## Coefficients:
##             Estimate Std. Error t value    Pr(>|t|)    
## (Intercept) 3.890070  0.761956   5.105 0.0000879488 ***
## advert      4.681864  0.501032   9.344 0.0000000414 ***
## I(advert^2) -0.455152  0.078977  -5.763 0.0000229561 ***
## I(advert^3)  0.016131  0.003429   4.704    0.000205 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
```

```
## Residual standard error: 0.8329 on 17 degrees of freedom
## Multiple R-squared:  0.9821, Adjusted R-squared:  0.9789
## F-statistic: 310.2 on 3 and 17 DF,  p-value: 4.892e-15
```

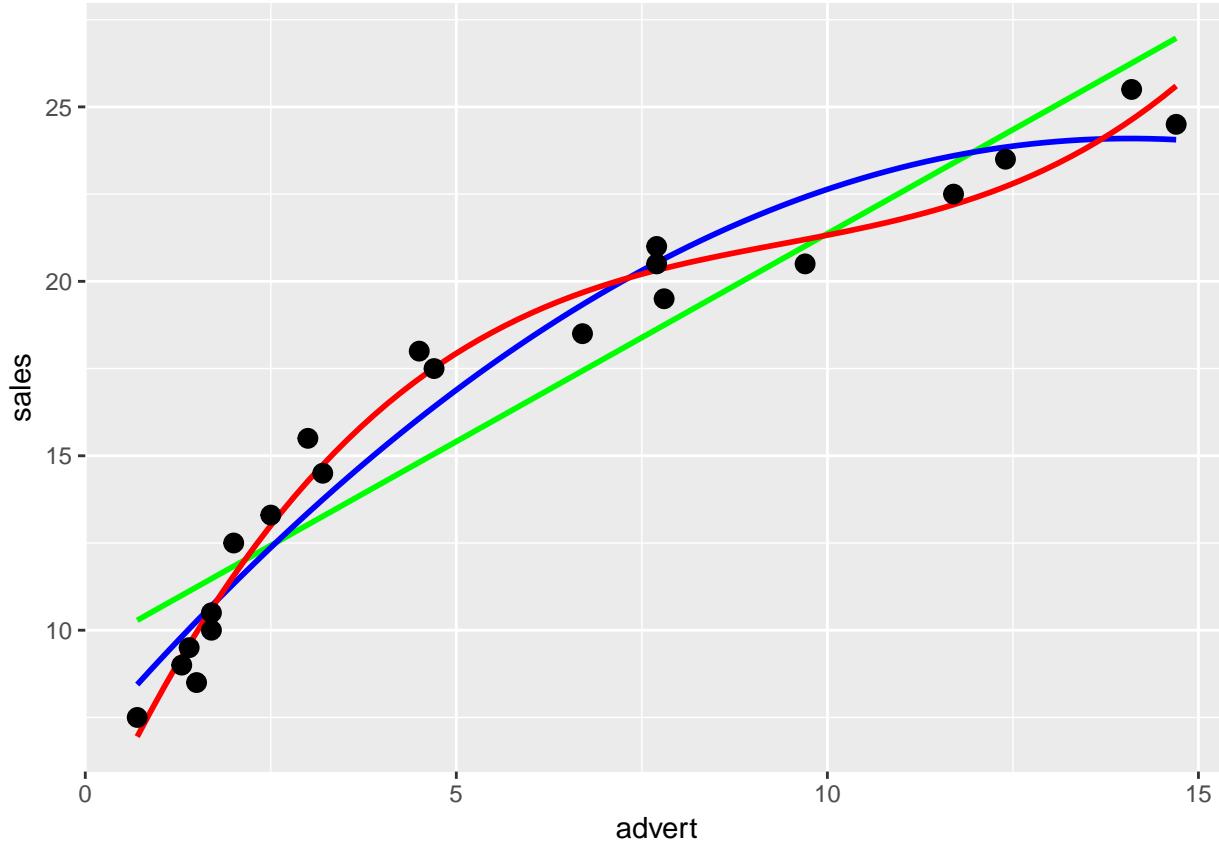
Now we see that with the first and second order terms in the model, the third order term is also significant. But does this make sense practically? The following plot should give hints as to why it doesn't. (The model with the third order term doesn't have diminishing returns!)

```
plot(sales ~ advert, data = marketing,
      xlab = "Advert Spending (in $100,00)", ylab = "Sales (in $100,00)",
      pch = 20, cex = 2)
abline(mark_mod, lty = 2, col = "green", lwd = 2)
xplot = seq(0, 16, by = 0.01)
lines(xplot, predict(mark_mod_poly2, newdata = data.frame(advert = xplot)),
      col = "blue", lwd = 2)
lines(xplot, predict(mark_mod_poly3, newdata = data.frame(advert = xplot)),
      col = "red", lty = 3, lwd = 3)
```



The previous plot was made using base graphics in R. The next plot was made using the package `ggplot2`, an increasingly popular plotting method in R.

```
library(ggplot2)
ggplot(data = marketing, aes(x = advert, y = sales)) +
  stat_smooth(method = "lm", se = FALSE, color = "green", formula = y ~ x) +
  stat_smooth(method = "lm", se = FALSE, color = "blue", formula = y ~ x + I(x ^ 2)) +
  stat_smooth(method = "lm", se = FALSE, color = "red", formula = y ~ x + I(x ^ 2) + I(x ^ 3)) +
  geom_point(colour = "black", size = 3)
```



Note we could fit a polynomial of an arbitrary order,

$$Y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \cdots + \beta_{p-1} x_i^{p-1} + \epsilon_i$$

However, we should be careful about over-fitting, since with a polynomial of degree one less than the number of observations, it is sometimes possible to fit a model perfectly.

```
set.seed(1234)
x = seq(0, 10)
y = 3 + x + 4 * x ^ 2 + rnorm(11, 0, 20)
plot(x, y, ylim = c(-300, 400), cex = 2, pch = 20)
fit = lm(y ~ x + I(x ^ 2))
#summary(fit)
fit_perf = lm(y ~ x + I(x ^ 2) + I(x ^ 3) + I(x ^ 4) + I(x ^ 5) + I(x ^ 6) +
+ I(x ^ 7) + I(x ^ 8) + I(x ^ 9) + I(x ^ 10))
summary(fit_perf)
```

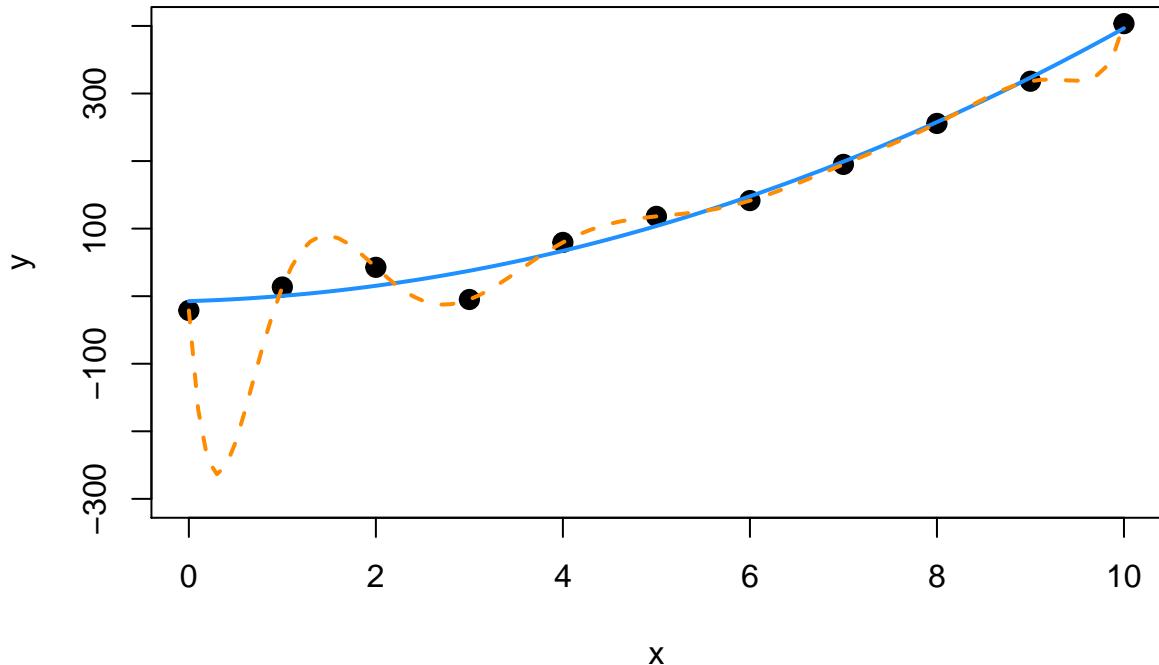
```
##
## Call:
## lm(formula = y ~ x + I(x^2) + I(x^3) + I(x^4) + I(x^5) + I(x^6) +
##     I(x^7) + I(x^8) + I(x^9) + I(x^10))
##
## Residuals:
## ALL 11 residuals are 0: no residual degrees of freedom!
##
## Coefficients:
```

```

##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) -21.141315     NA     NA     NA
## x          -1918.260330     NA     NA     NA
## I(x^2)      4969.169159     NA     NA     NA
## I(x^3)      -4932.231427     NA     NA     NA
## I(x^4)       2580.602473     NA     NA     NA
## I(x^5)      -803.533255     NA     NA     NA
## I(x^6)       156.982335     NA     NA     NA
## I(x^7)      -19.465675     NA     NA     NA
## I(x^8)        1.489665     NA     NA     NA
## I(x^9)      -0.064240     NA     NA     NA
## I(x^10)      0.001195     NA     NA     NA
##
## Residual standard error: NaN on 0 degrees of freedom
## Multiple R-squared:      1, Adjusted R-squared:      NaN
## F-statistic:   NaN on 10 and 0 DF,  p-value: NA

xplot = seq(0, 10, by = 0.1)
lines(xplot, predict(fit, newdata = data.frame(x = xplot)),
      col = "dodgerblue", lwd = 2, lty = 1)
lines(xplot, predict(fit_perf, newdata = data.frame(x = xplot)),
      col = "darkorange", lwd = 2, lty = 2)

```



Notice in the summary, R could not calculate standard errors. This is a result of being “out” of degrees of freedom. With 11 β parameters and 11 data points, we use up all the degrees of freedom before we can estimate σ .

In this example, the true relationship is quadratic, but the order 10 polynomial’s fit is “perfect”. Next chapter we will focus on the trade-off between goodness of fit (minimizing errors) and complexity of model.

Suppose you work for an automobile manufacturer which makes a large luxury sedan. You would like to know how the car performs from a fuel efficiency standpoint when it is driven at various speeds. Instead of testing the car at every conceivable speed (which would be impossible) you create an experiment where the car is driven at speeds of interest in increments of 5 miles per hour.

Our goal then, is to fit a model to this data in order to be able to predict fuel efficiency when driving at certain speeds. The data from this example can be found in `fuel_econ.csv`.

```
econ = read.csv("data/fuel_econ.csv")
```

In this example, we will be frequently looking at the fitted versus residuals plot, so we *should* write a function to make our life easier, but this is left as an exercise for homework.

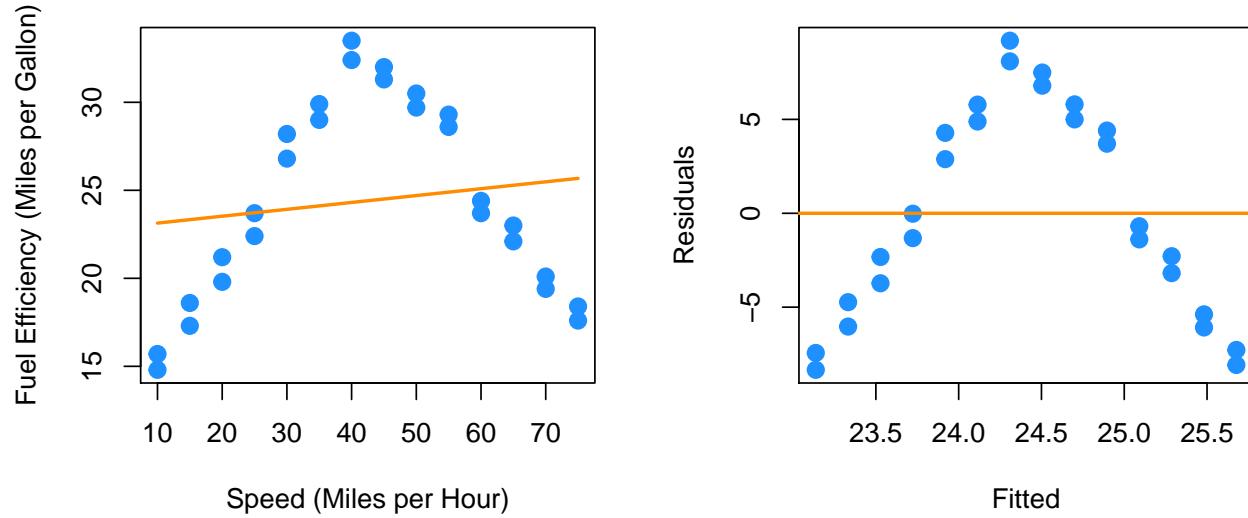
We will also be adding fitted curves to scatterplots repeatedly, so smartly we will write a function to do so.

```
plot_econ_curve = function(model){
  plot(mpg ~ mph, data = econ, xlab = "Speed (Miles per Hour)",
    ylab = "Fuel Efficiency (Miles per Gallon)", col = "dodgerblue",
    pch = 20, cex = 2)
  xplot = seq(10, 75, by = 0.1)
  lines(xplot, predict(model, newdata = data.frame(mph = xplot)),
    col = "darkorange", lwd = 2, lty = 1)
}
```

So now we first fit a simple linear regression to this data.

```
fit1 = lm(mpg ~ mph, data = econ)
```

```
par(mfrow = c(1, 2))
plot_econ_curve(fit1)
plot(fitted(fit1), resid(fit1), xlab = "Fitted", ylab = "Residuals",
  col = "dodgerblue", pch = 20, cex = 2)
abline(h = 0, col = "darkorange", lwd = 2)
```



Pretty clearly we can do better. Yes fuel efficiency does increase as speed increases, but only up to a certain point.

We will now add polynomial terms until we fit a suitable fit.

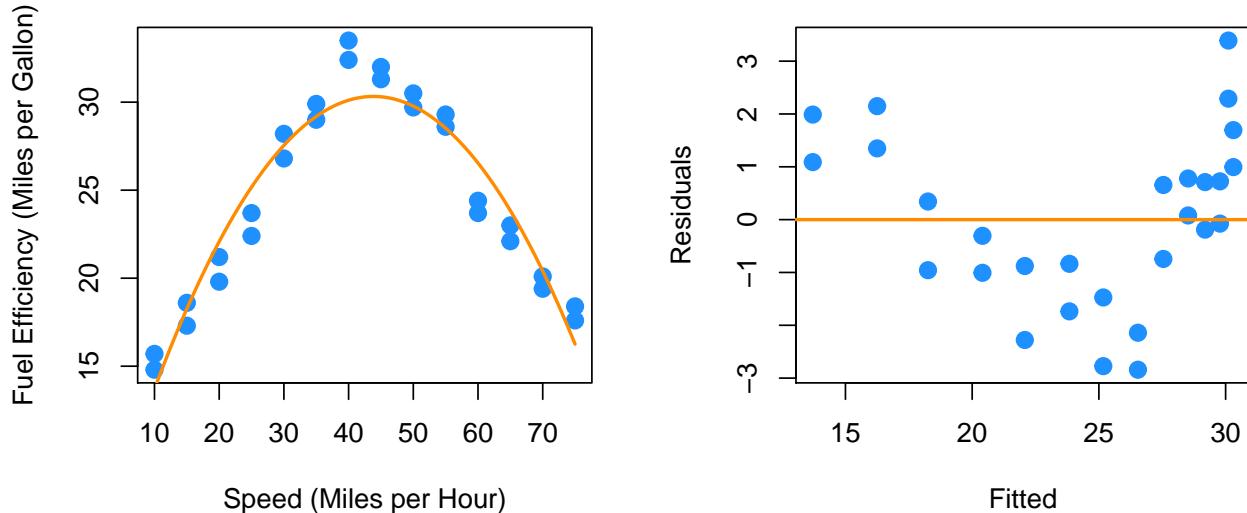
```
fit2 = lm(mpg ~ mph + I(mph ^ 2), data = econ)
summary(fit2)
```

```

## 
## Call:
## lm(formula = mpg ~ mph + I(mph^2), data = econ)
## 
## Residuals:
##      Min      1Q  Median      3Q     Max 
## -2.8411 -0.9694  0.0017  1.0181  3.3900 
## 
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)    
## (Intercept) 2.4444505  1.4241091   1.716   0.0984 .  
## mph         1.2716937  0.0757321  16.792 3.99e-15 *** 
## I(mph^2)    -0.0145014  0.0008719 -16.633 4.97e-15 *** 
## --- 
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1 
## 
## Residual standard error: 1.663 on 25 degrees of freedom 
## Multiple R-squared:  0.9188, Adjusted R-squared:  0.9123 
## F-statistic: 141.5 on 2 and 25 DF,  p-value: 2.338e-14 

par(mfrow = c(1, 2))
plot_econ_curve(fit2)
plot(fitted(fit2), resid(fit2), xlab = "Fitted", ylab = "Residuals",
      col = "dodgerblue", pch = 20, cex = 2)
abline(h = 0, col = "darkorange", lwd = 2)

```



While this model clearly fits much better, and the second order term is significant, we still see a pattern in the fitted versus residuals plot which suggests higher order terms will help. Also, we would expect the curve to flatten as speed increases or decreases, not go sharply downward as we see here.

```

fit3 = lm(mpg ~ mph + I(mph ^ 2) + I(mph ^ 3), data = econ)
summary(fit3)

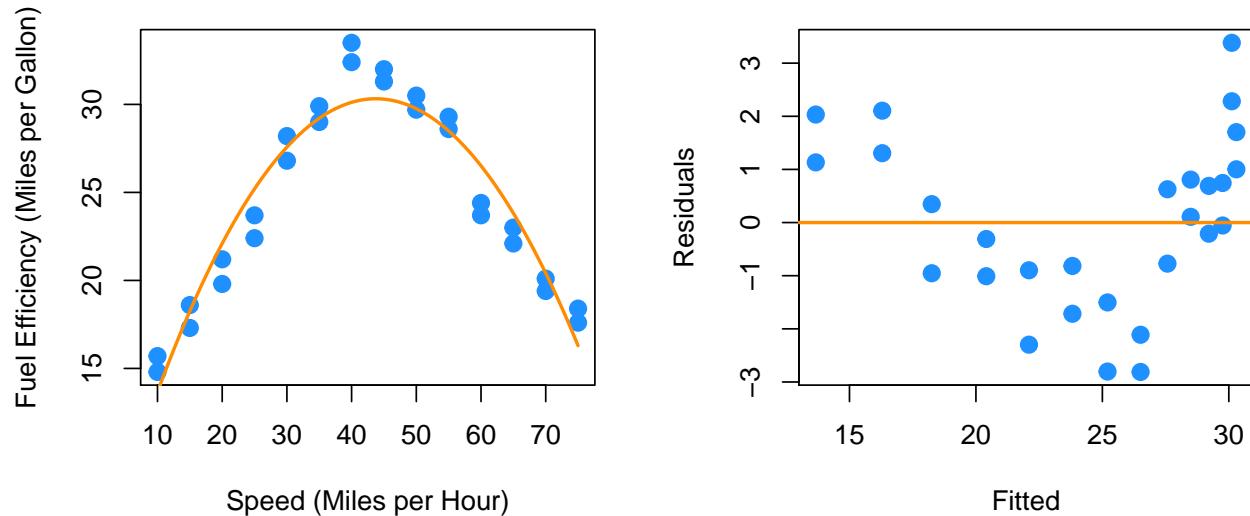
```

```

## 
## Call:
## lm(formula = mpg ~ mph + I(mph^2) + I(mph^3), data = econ)
## 
```

```
##
## Residuals:
##   Min     1Q Median     3Q    Max
## -2.8112 -0.9677  0.0264  1.0345  3.3827
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) 2.257842158 2.767928398  0.816  0.4227
## mph         1.290771239 0.252928479  5.103 0.000032 ***
## I(mph^2)    -0.015019730 0.006603861 -2.274  0.0322 *
## I(mph^3)    0.000004066 0.000051323  0.079  0.9375
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 1.697 on 24 degrees of freedom
## Multiple R-squared:  0.9188, Adjusted R-squared:  0.9087
## F-statistic: 90.56 on 3 and 24 DF,  p-value: 3.17e-13
```

```
par(mfrow = c(1, 2))
plot_econ_curve(fit3)
plot(fitted(fit3), resid(fit3), xlab = "Fitted", ylab = "Residuals",
      col = "dodgerblue", pch = 20, cex = 2)
abline(h = 0, col = "darkorange", lwd = 2)
```



Adding the third order term doesn't seem to help at all. The fitted curve hardly changes. This makes sense, since what we would like is for the curve to flatten at the extremes. For this we will need an even degree polynomial term.

```
fit4 = lm(mpg ~ mph + I(mph ^ 2) + I(mph ^ 3) + I(mph ^ 4), data = econ)
summary(fit4)
```

```
##
## Call:
## lm(formula = mpg ~ mph + I(mph^2) + I(mph^3) + I(mph^4), data = econ)
##
## Residuals:
```

```

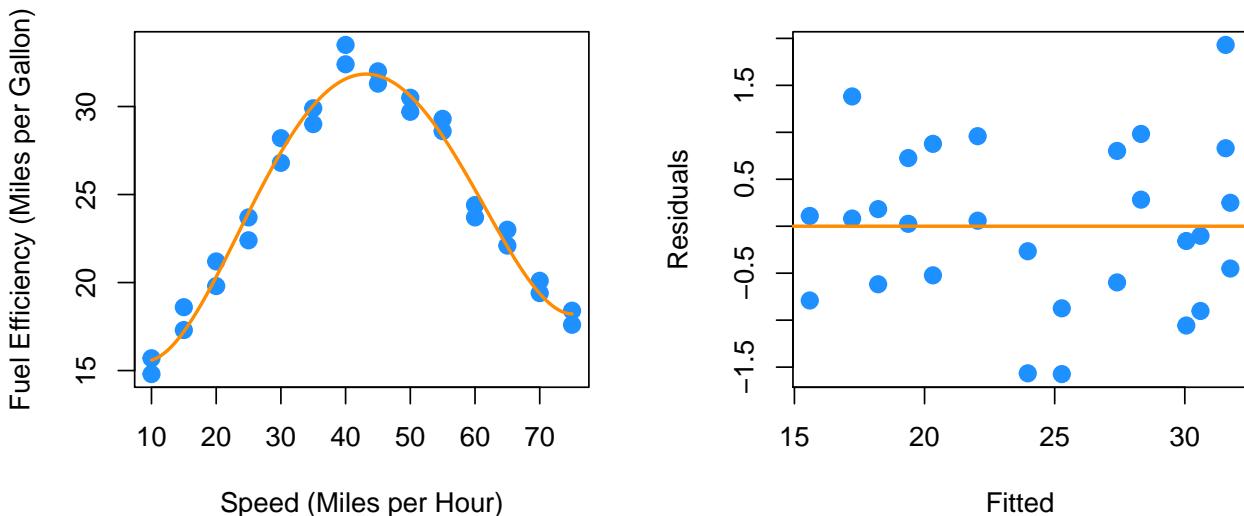
##      Min      1Q   Median      3Q      Max
## -1.57410 -0.60308  0.04236  0.74481  1.93038
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) 21.460464535 2.964796563 7.238 0.000000228 ***
## mph        -1.467700706 0.391271891 -3.751 0.00104 **
## I(mph^2)     0.108111931 0.016728286 6.463 0.000001354 ***
## I(mph^3)    -0.002129559 0.000284392 -7.488 0.000000131 ***
## I(mph^4)     0.000012551 0.000001665 7.539 0.000000117 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.9307 on 23 degrees of freedom
## Multiple R-squared:  0.9766, Adjusted R-squared:  0.9726
## F-statistic: 240.2 on 4 and 23 DF,  p-value: < 2.2e-16

```

```

par(mfrow = c(1, 2))
plot_econ_curve(fit4)
plot(fitted(fit4), resid(fit4), xlab = "Fitted",
      ylab = "Residuals",
      col = "dodgerblue", pch = 20, cex = 2)
abline(h = 0, col = "darkorange", lwd = 2)

```



Now we are making progress. The fourth order term is significant with the other terms in the model. Also we are starting to see what we expected for low and high speed. However, there still seems to be a bit of a pattern in the residuals, so we will again try more higher order terms. We will add the fifth and sixth together, since adding the fifth will be similar to adding the third.

```

fit6 = lm(mpg ~ mph + I(mph ^ 2) + I(mph ^ 3) + I(mph ^ 4) + I(mph ^ 5) + I(mph^6), data = econ)
summary(fit6)

```

```

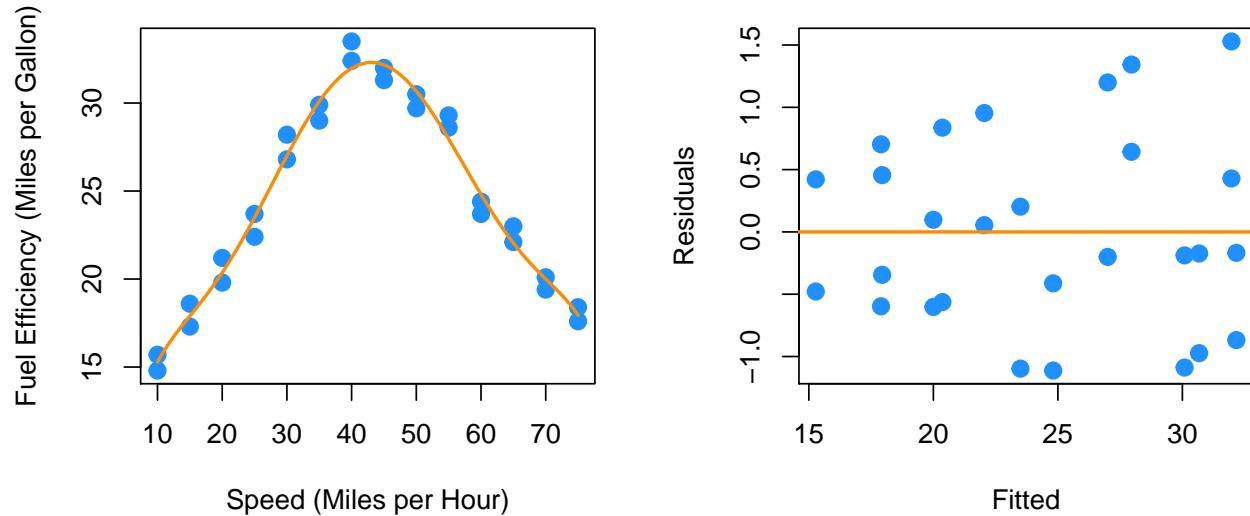
##
## Call:
## lm(formula = mpg ~ mph + I(mph^2) + I(mph^3) + I(mph^4) + I(mph^5) +
##     I(mph^6), data = econ)
## 
```

```

## Residuals:
##      Min      1Q   Median      3Q     Max
## -1.1129 -0.5717 -0.1707  0.5026  1.5288
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) -4.206e+00  1.204e+01 -0.349  0.7304
## mph         4.203e+00  2.553e+00  1.646  0.1146
## I(mph^2)    -3.521e-01  2.012e-01 -1.750  0.0947 .
## I(mph^3)    1.579e-02  7.691e-03  2.053  0.0527 .
## I(mph^4)   -3.473e-04  1.529e-04 -2.271  0.0338 *
## I(mph^5)    3.585e-06  1.518e-06  2.362  0.0279 *
## I(mph^6)   -1.402e-08  5.941e-09 -2.360  0.0280 *
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.8657 on 21 degrees of freedom
## Multiple R-squared:  0.9815, Adjusted R-squared:  0.9762
## F-statistic:  186 on 6 and 21 DF,  p-value: < 2.2e-16

par(mfrow = c(1, 2))
plot_econ_curve(fit6)
plot(fitted(fit6), resid(fit6), xlab = "Fitted", ylab = "Residuals",
      col = "dodgerblue", pch = 20, cex = 2)
abline(h = 0, col = "darkorange", lwd = 2)

```



Again the sixth order term is significant with the other terms in the model and here we see less pattern in the residuals plot. Let's now test for which of the previous two models we prefer. We will test

$$H_0 : \beta_5 = \beta_6 = 0.$$

```
anova(fit4, fit6)
```

```

## Analysis of Variance Table
##
## Model 1: mpg ~ mph + I(mph^2) + I(mph^3) + I(mph^4)

```

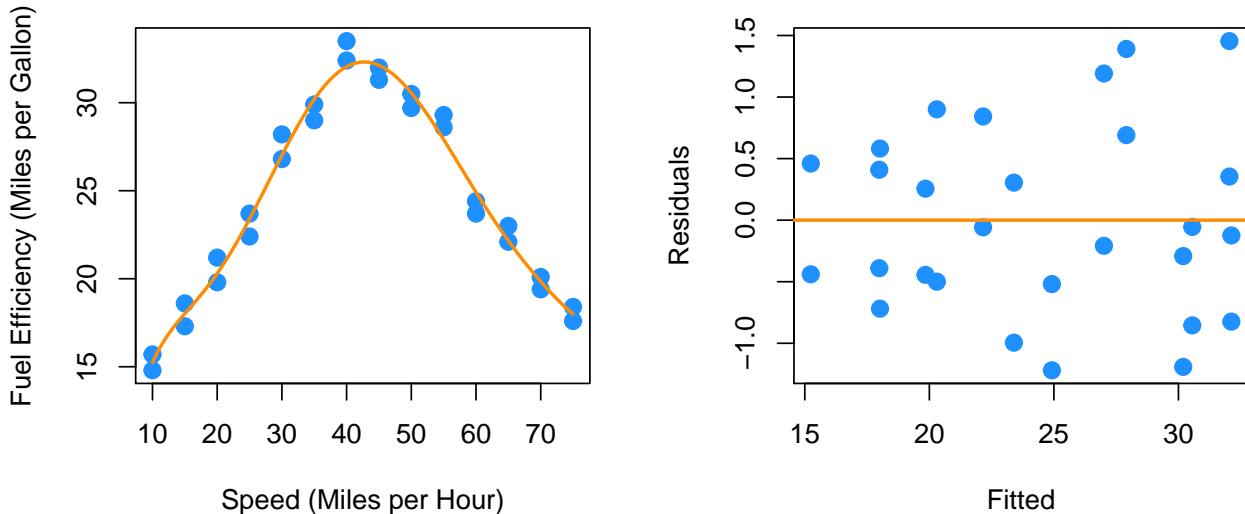
```
## Model 2: mpg ~ mph + I(mph^2) + I(mph^3) + I(mph^4) + I(mph^5) + I(mph^6)
##   Res.Df   RSS Df Sum of Sq    F Pr(>F)
## 1      23 19.922
## 2      21 15.739  2     4.1828 2.7905 0.0842 .
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
```

So, this test does not reject the null hypothesis at a level of significance of $\alpha = 0.05$, however the p-value is still rather small, and the fitted versus residuals plot is much better for the model with the sixth order term. This makes the sixth order model a good choice. We could repeat this process one more time.

```
fit8 = lm(mpg ~ mph + I(mph ^ 2) + I(mph ^ 3) + I(mph ^ 4) + I(mph ^ 5) +
          + I(mph ^ 6) + I(mph ^ 7) + I(mph ^ 8), data = econ)
summary(fit8)
```

```
##
## Call:
## lm(formula = mpg ~ mph + I(mph^2) + I(mph^3) + I(mph^4) + I(mph^5) +
##     I(mph^6) + I(mph^7) + I(mph^8), data = econ)
##
## Residuals:
##       Min     1Q Median     3Q    Max
## -1.21938 -0.50464 -0.09105  0.49029  1.45440
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) -1.202e+01  7.045e+01 -0.171   0.866
## mph         6.021e+00  2.014e+01   0.299   0.768
## I(mph^2)    -5.037e-01  2.313e+00 -0.218   0.830
## I(mph^3)    2.121e-02  1.408e-01   0.151   0.882
## I(mph^4)   -4.008e-04  5.017e-03 -0.080   0.937
## I(mph^5)    1.789e-06  1.080e-04   0.017   0.987
## I(mph^6)    4.486e-08  1.381e-06   0.032   0.974
## I(mph^7)   -6.456e-10  9.649e-09 -0.067   0.947
## I(mph^8)   2.530e-12  2.835e-11   0.089   0.930
##
## Residual standard error: 0.9034 on 19 degrees of freedom
## Multiple R-squared:  0.9818, Adjusted R-squared:  0.9741
## F-statistic: 128.1 on 8 and 19 DF,  p-value: 7.074e-15
```

```
par(mfrow = c(1, 2))
plot_econ_curve(fit8)
plot(fitted(fit8), resid(fit8), xlab = "Fitted", ylab = "Residuals",
      col = "dodgerblue", pch = 20, cex = 2)
abline(h = 0, col = "darkorange", lwd = 2)
```



```
summary(fit8)
```

```
##
## Call:
## lm(formula = mpg ~ mph + I(mph^2) + I(mph^3) + I(mph^4) + I(mph^5) +
##     I(mph^6) + I(mph^7) + I(mph^8), data = econ)
##
## Residuals:
##      Min        1Q    Median        3Q       Max
## -1.21938 -0.50464 -0.09105  0.49029  1.45440
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) -1.202e+01  7.045e+01 -0.171   0.866
## mph         6.021e+00  2.014e+01   0.299   0.768
## I(mph^2)    -5.037e-01  2.313e+00 -0.218   0.830
## I(mph^3)    2.121e-02  1.408e-01   0.151   0.882
## I(mph^4)   -4.008e-04  5.017e-03 -0.080   0.937
## I(mph^5)   1.789e-06  1.080e-04   0.017   0.987
## I(mph^6)   4.486e-08  1.381e-06   0.032   0.974
## I(mph^7)  -6.456e-10  9.649e-09 -0.067   0.947
## I(mph^8)  2.530e-12  2.835e-11   0.089   0.930
##
## Residual standard error: 0.9034 on 19 degrees of freedom
## Multiple R-squared:  0.9818, Adjusted R-squared:  0.9741
## F-statistic: 128.1 on 8 and 19 DF,  p-value: 7.074e-15
```

```
anova(fit6, fit8)
```

```
## Analysis of Variance Table
##
## Model 1: mpg ~ mph + I(mph^2) + I(mph^3) + I(mph^4) + I(mph^5) + I(mph^6)
## Model 2: mpg ~ mph + I(mph^2) + I(mph^3) + I(mph^4) + I(mph^5) + I(mph^6) +
##     I(mph^7) + I(mph^8)
##   Res.Df   RSS Df Sum of Sq    F Pr(>F)
## 1      21 15.739
```

```
## 2      19 15.506 2     0.2324 0.1424 0.8682
```

Here we would clearly stick with `fit6`. The eighth order term is not significant with the other terms in the model and the F-test does not reject.

As an aside, be aware that there is a quicker way to specify a model with many higher order terms.

```
fit6_alt = lm(mpg ~ poly(mph, 6), data = econ)
all.equal(fitted(fit6), fitted(fit6_alt))
```

```
## [1] TRUE
```

We first verify that this method produces the same fitted values. However, the estimated coefficients are different.

```
coef(fit6)
```

```
## (Intercept)          mph          I(mph^2)          I(mph^3)
## -4.20622377616269  4.20338221905924 -0.35214523989512  0.01579340288449
##           I(mph^4)          I(mph^5)          I(mph^6)
## -0.00034726647879  0.00000358520124 -0.00000001401995
```

```
coef(fit6_alt)
```

```
## (Intercept) poly(mph, 6)1 poly(mph, 6)2 poly(mph, 6)3 poly(mph, 6)4
## 24.40714286   4.16769628  -27.66685755   0.13446747   7.01671480
## poly(mph, 6)5 poly(mph, 6)6
## 0.09288754   -2.04307796
```

This is because `poly()` uses *orthogonal polynomials*, which solves an issue we will discuss in the next chapter.

```
summary(fit6)
```

```
##
## Call:
## lm(formula = mpg ~ mph + I(mph^2) + I(mph^3) + I(mph^4) + I(mph^5) +
##     I(mph^6), data = econ)
##
## Residuals:
##    Min      1Q  Median      3Q      Max
## -1.1129 -0.5717 -0.1707  0.5026  1.5288
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) -4.206e+00  1.204e+01 -0.349   0.7304
## mph         4.203e+00  2.553e+00  1.646   0.1146
## I(mph^2)    -3.521e-01  2.012e-01 -1.750   0.0947 .
## I(mph^3)    1.579e-02  7.691e-03  2.053   0.0527 .
## I(mph^4)   -3.473e-04  1.529e-04 -2.271   0.0338 *
## I(mph^5)    3.585e-06  1.518e-06  2.362   0.0279 *
## I(mph^6)   -1.402e-08  5.941e-09 -2.360   0.0280 *
```

```

## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.8657 on 21 degrees of freedom
## Multiple R-squared:  0.9815, Adjusted R-squared:  0.9762
## F-statistic:   186 on 6 and 21 DF,  p-value: < 2.2e-16

summary(fit6_alt)

```

```

##
## Call:
## lm(formula = mpg ~ poly(mph, 6), data = econ)
##
## Residuals:
##      Min     1Q Median     3Q    Max 
## -1.1129 -0.5717 -0.1707  0.5026  1.5288 
##
## Coefficients:
##             Estimate Std. Error t value    Pr(>|t|)    
## (Intercept) 24.40714   0.16360 149.184 < 2e-16 ***
## poly(mph, 6)1  4.16770   0.86571   4.814 0.0000930613 ***
## poly(mph, 6)2 -27.66686   0.86571  -31.958 < 2e-16 ***
## poly(mph, 6)3   0.13447   0.86571   0.155     0.878    
## poly(mph, 6)4   7.01671   0.86571   8.105 0.0000000668 ***
## poly(mph, 6)5   0.09289   0.86571   0.107     0.916    
## poly(mph, 6)6  -2.04308   0.86571  -2.360     0.028 *  
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.8657 on 21 degrees of freedom
## Multiple R-squared:  0.9815, Adjusted R-squared:  0.9762
## F-statistic:   186 on 6 and 21 DF,  p-value: < 2.2e-16

```

Notice though that the p-value for testing the degree 6 term is the same. Because of this, for the most part we can use these interchangeably.

To use `poly()` to obtain the same results as using `I()` repeatedly, we would need to set `raw = TRUE`.

```

fit6_alt2 = lm(mpg ~ poly(mph, 6, raw = TRUE), data = econ)
coef(fit6_alt2)

```

```

##             (Intercept) poly(mph, 6, raw = TRUE)1 poly(mph, 6, raw = TRUE)2
##              -4.20622377616269          4.20338221905924         -0.35214523989512
## poly(mph, 6, raw = TRUE)3 poly(mph, 6, raw = TRUE)4 poly(mph, 6, raw = TRUE)5
##              0.01579340288449        -0.00034726647879         0.00000358520124
## poly(mph, 6, raw = TRUE)6
##              -0.00000001401995

```

We've now seen how to transform predictor and response variables. In this chapter we have mostly focused on using this in the context of fixing SLR models. However, these concepts can easily be used together with categorical variables and interactions to build larger, more flexible models. In the next chapter, we will discuss how to choose a good model from a collection of possible models.

Please note: some data currently used in this chapter was used, changed, and passed around over the years in STAT 420 at UIUC. Its original sources, if they exist, are at this time unknown to the author. As a result, they should only be considered for use with STAT 420. Going forward they will likely be replaced with alternative sourceable data that illustrates the same concepts. That material is currently here.

Chapter 14

Collinearity

“If I look confused it is because I am thinking.”

— Samuel Goldwyn

After reading this chapter you will be able to:

- Identify collinearity in regression.
- Understand the effect of collinearity on regression models.

14.1 Exact Collinearity

Let's create a dataset where one of the predictors, x_3 , is a linear combination of the other predictors.

```
gen_exact_collin_data = function(num_samples = 100) {  
  x1 = rnorm(n = num_samples, mean = 80, sd = 10)  
  x2 = rnorm(n = num_samples, mean = 70, sd = 5)  
  x3 = 2 * x1 + 4 * x2 + 3  
  y = 3 + x1 + x2 + rnorm(n = num_samples, mean = 0, sd = 1)  
  data.frame(y, x1, x2, x3)  
}
```

Notice that the way we are generating this data, the response y only really depends on x_1 and x_2 .

```
set.seed(42)  
exact_collin_data = gen_exact_collin_data()  
head(exact_collin_data)
```

```
##          y      x1      x2      x3  
## 1 170.7135 93.70958 76.00483 494.4385  
## 2 152.9106 74.35302 75.22376 452.6011  
## 3 152.7866 83.63128 64.98396 430.1984  
## 4 170.6306 86.32863 79.24241 492.6269  
## 5 152.3320 84.04268 66.66613 437.7499  
## 6 151.3155 78.93875 70.52757 442.9878
```

What happens when we attempt to fit a regression model in R using all of the predictors?

```
exact_collin_fit = lm(y ~ x1 + x2 + x3, data = exact_collin_data)
summary(exact_collin_fit)
```

```
##
## Call:
## lm(formula = y ~ x1 + x2 + x3, data = exact_collin_data)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -2.57662 -0.66188 -0.08253  0.63706  2.52057
##
## Coefficients: (1 not defined because of singularities)
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) 2.957336  1.735165  1.704  0.0915 .
## x1          0.985629  0.009788 100.702 <2e-16 ***
## x2          1.017059  0.022545  45.112 <2e-16 ***
## x3            NA        NA        NA        NA
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 1.014 on 97 degrees of freedom
## Multiple R-squared:  0.9923, Adjusted R-squared:  0.9921
## F-statistic:  6236 on 2 and 97 DF,  p-value: < 2.2e-16
```

We see that R simply decides to exclude a variable. Why is this happening?

```
X = cbind(1, as.matrix(exact_collin_data[,-1]))
solve(t(X) %*% X)
```

If we attempt to find $\hat{\beta}$ using $(\mathbf{X}^T \mathbf{X})^{-1}$, we see that this is not possible, due to the fact that the columns of \mathbf{X} are linearly dependent. The previous lines of code were not run, because they produce an error!

When this happens, we say there is **exact collinearity** in the dataset.

As a result of this issue, R essentially chose to fit the model $y \sim x_1 + x_2$. However notice that two other models would accomplish exactly the same fit.

```
fit1 = lm(y ~ x1 + x2, data = exact_collin_data)
fit2 = lm(y ~ x1 + x3, data = exact_collin_data)
fit3 = lm(y ~ x2 + x3, data = exact_collin_data)
```

We see that the fitted values for each of the three models are exactly the same. This is a result of x_3 containing all of the information from x_1 and x_2 . As long as one of x_1 or x_2 are included in the model, x_3 can be used to recover the information from the variable not included.

```
all.equal(fitted(fit1), fitted(fit2))
```

```
## [1] TRUE
```

```
all.equal(fitted(fit2), fitted(fit3))
```

```
## [1] TRUE
```

While their fitted values are all the same, their estimated coefficients are wildly different. The sign of x_2 is switched in two of the models! So only `fit1` properly *explains* the relationship between the variables, `fit2` and `fit3` still *predict* as well as `fit1`, despite the coefficients having little to no meaning, a concept we will return to later.

```
coef(fit1)
```

```
## (Intercept)          x1          x2
## 2.9573357   0.9856291  1.0170586
```

```
coef(fit2)
```

```
## (Intercept)          x1          x3
## 2.1945418   0.4770998  0.2542647
```

```
coef(fit3)
```

```
## (Intercept)          x2          x3
## 1.4788921 -0.9541995  0.4928145
```

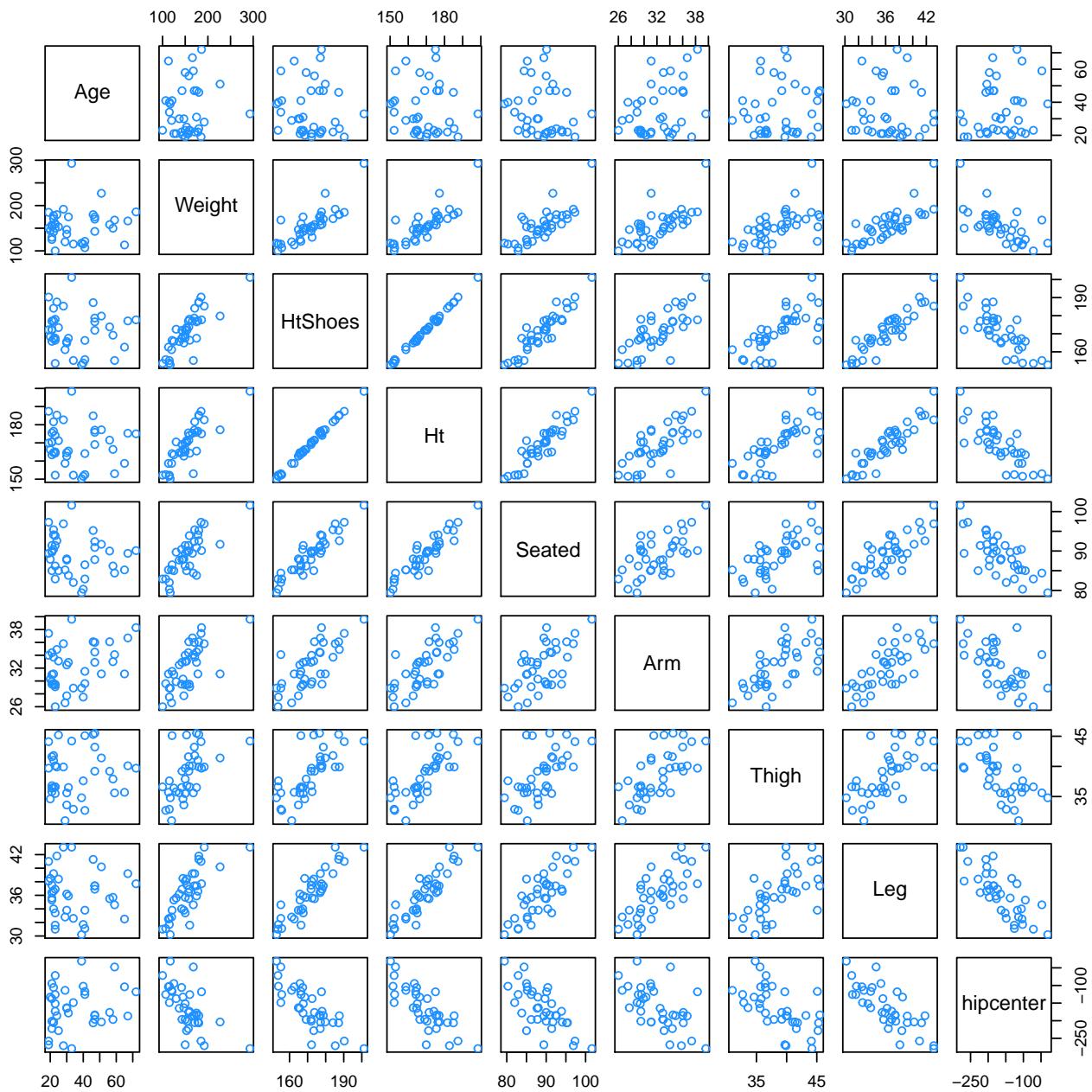
14.2 Collinearity

Exact collinearity is an extreme example of **collinearity**, which occurs in multiple regression when predictor variables are highly correlated. Collinearity is often called *multicollinearity*, since it is a phenomenon that really only occurs during multiple regression.

Looking at the `seatpos` dataset from the `faraway` package, we will see an example of this concept. The predictors in this dataset are various attributes of car drivers, such as their height, weight and age. The response variable `hipcenter` measures the “horizontal distance of the midpoint of the hips from a fixed location in the car in mm.” Essentially, it measures the position of the seat for a given driver. This is potentially useful information for car manufacturers considering comfort and safety when designing vehicles.

We will attempt to fit a model that predicts `hipcenter`. Two predictor variables are immediately interesting to us: `HtShoes` and `Ht`. We certainly expect a person’s height to be highly correlated to their height when wearing shoes. We’ll pay special attention to these two variables when fitting models.

```
library(faraway)
pairs(seatpos, col = "dodgerblue")
```



```
round(cor(seatpos), 2)
```

	Age	Weight	HtShoes	Ht	Seated	Arm	Thigh	Leg	hipcenter
##	1.00	0.08	-0.08	-0.09	-0.17	0.36	0.09	-0.04	0.21
## Age	1.00	0.08	-0.08	-0.09	-0.17	0.36	0.09	-0.04	0.21
## Weight	0.08	1.00	0.83	0.83	0.78	0.70	0.57	0.78	-0.64
## HtShoes	-0.08	0.83	1.00	1.00	0.93	0.75	0.72	0.91	-0.80
## Ht	-0.09	0.83	1.00	1.00	0.93	0.75	0.73	0.91	-0.80
## Seated	-0.17	0.78	0.93	0.93	1.00	0.63	0.61	0.81	-0.73
## Arm	0.36	0.70	0.75	0.75	0.63	1.00	0.67	0.75	-0.59
## Thigh	0.09	0.57	0.72	0.73	0.61	0.67	1.00	0.65	-0.59
## Leg	-0.04	0.78	0.91	0.91	0.81	0.75	0.65	1.00	-0.79
## hipcenter	0.21	-0.64	-0.80	-0.80	-0.73	-0.59	-0.59	-0.79	1.00

After loading the `faraway` package, we do some quick checks of correlation between the predictors. Visually,

we can do this with the `pairs()` function, which plots all possible scatterplots between pairs of variables in the dataset.

We can also do this numerically with the `cor()` function, which when applied to a dataset, returns all pairwise correlations. Notice this is a symmetric matrix. Recall that correlation measures strength and direction of the linear relationship between two variables. The correlation between `Ht` and `HtShoes` is extremely high. So high, that rounded to two decimal places, it appears to be 1!

Unlike exact collinearity, here we can still fit a model with all of the predictors, but what effect does this have?

```
hip_model = lm(hipcenter ~ ., data = seatpos)
summary(hip_model)

##
## Call:
## lm(formula = hipcenter ~ ., data = seatpos)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -73.827 -22.833 - 3.678  25.017  62.337
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) 436.43213 166.57162  2.620  0.0138 *
## Age          0.77572  0.57033  1.360  0.1843
## Weight        0.02631  0.33097  0.080  0.9372
## HtShoes     -2.69241  9.75304 -0.276  0.7845
## Ht           0.60134 10.12987  0.059  0.9531
## Seated        0.53375  3.76189  0.142  0.8882
## Arm          -1.32807  3.90020 -0.341  0.7359
## Thigh         -1.14312  2.66002 -0.430  0.6706
## Leg           -6.43905  4.71386 -1.366  0.1824
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 37.72 on 29 degrees of freedom
## Multiple R-squared:  0.6866, Adjusted R-squared:  0.6001
## F-statistic:  7.94 on 8 and 29 DF,  p-value: 0.00001306
```

One of the first things we should notice is that the F -test for the regression tells us that the regression is significant, however each individual predictor is not. Another interesting result is the opposite signs of the coefficients for `Ht` and `HtShoes`. This should seem rather counter-intuitive. Increasing `Ht` increases `hipcenter`, but increasing `HtShoes` decreases `hipcenter`?

This happens as a result of the predictors being highly correlated. For example, the `HtShoe` variable explains a large amount of the variation in `Ht`. When they are both in the model, their effects on the response are lessened individually, but together they still explain a large portion of the variation of `hipcenter`.

We define R_j^2 to be the proportion of observed variation in the j -th predictor explained by the other predictors. In other words R_j^2 is the multiple R-Squared for the regression of x_j on each of the other predictors.

```
ht_shoes_model = lm(HtShoes ~ . - hipcenter, data = seatpos)
summary(ht_shoes_model)$r.squared
```

```
## [1] 0.9967472
```

Here we see that the other predictors explain 99.67% of the variation in `HtShoe`. When fitting this model, we removed `hipcenter` since it is not a predictor.

14.2.1 Variance Inflation Factor.

Now note that the variance of $\hat{\beta}_j$ can be written as

$$\text{Var}(\hat{\beta}_j) = \sigma^2 C_{jj} = \sigma^2 \left(\frac{1}{1 - R_j^2} \right) \frac{1}{S_{x_j x_j}}$$

where

$$S_{x_j x_j} = \sum (x_{ij} - \bar{x}_j)^2.$$

This gives us a way to understand how collinearity affects our regression estimates.

We will call,

$$\frac{1}{1 - R_j^2}$$

the **variance inflation factor**. The variance inflation factor quantifies the effect of collinearity on the variance of our regression estimates. When R_j^2 is large, that is close to 1, x_j is well explained by the other predictors. With a large R_j^2 the variance inflation factor becomes large. This tells us that when x_j is highly correlated with other predictors, our estimate of β_j is highly variable.

The `vif` function from the `faraway` package calculates the VIFs for each of the predictors of a model.

```
vif(hip_model)
```

	Age	Weight	HtShoes	Ht	Seated	Arm	Thigh
##	1.997931	3.647030	307.429378	333.137832	8.951054	4.496368	2.762886
##		Leg					
##		6.694291					

In practice it is common to say that any VIF greater than 5 is cause for concern. So in this example we see there is a huge multicollinearity issue as many of the predictors have a VIF greater than 5.

Let's further investigate how the presence of collinearity actually effects a model. If we add a moderate amount of noise to the data, we see that the estimates of the coefficients change drastically. This is a rather undesirable effect. Adding random noise should not effect the coefficients of a model.

```
set.seed(1337)
noise = rnorm(n = nrow(seatpos), mean = 0, sd = 5)
hip_model_noise = lm(hipcenter + noise ~ ., data = seatpos)
```

Adding the noise had such a large effect, the sign of the coefficient for `Ht` has changed.

```
coef(hip_model)
```

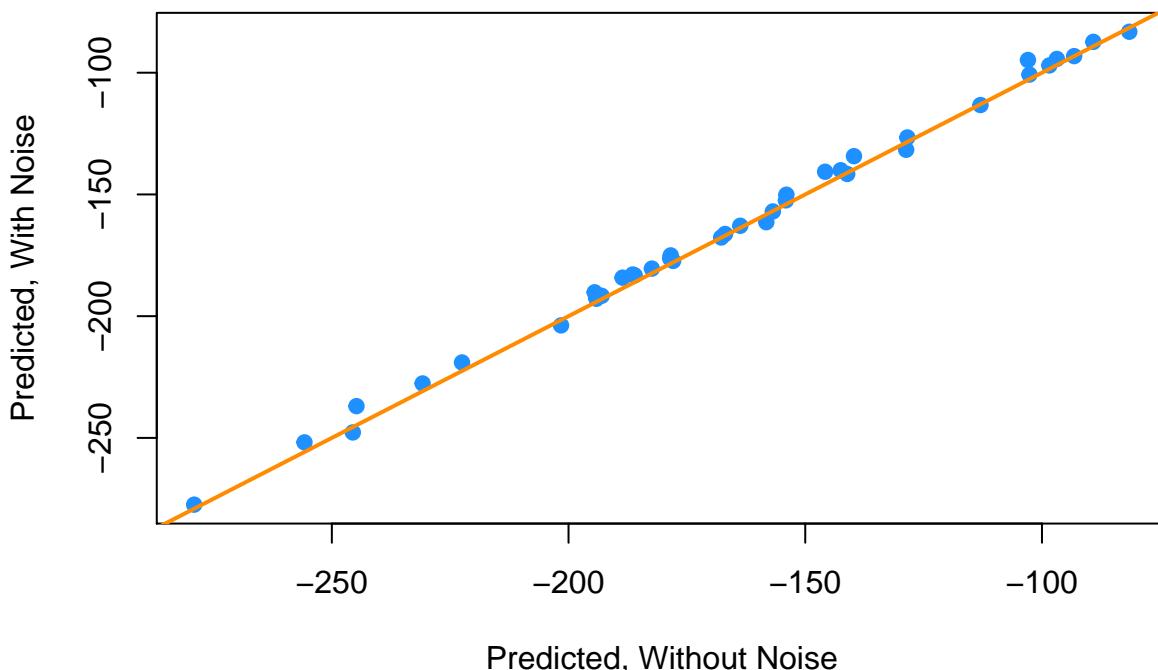
```
## (Intercept)          Age        Weight      HtShoes         Ht       Seated
## 436.43212823  0.77571620  0.02631308 -2.69240774  0.60134458  0.53375170
##      Arm        Thigh        Leg
## -1.32806864 -1.14311888 -6.43904627
```

```
coef(hip_model_noise)
```

```
## (Intercept)          Age        Weight      HtShoes         Ht       Seated
## 415.32909380  0.76578240  0.01910958 -2.90377584 -0.12068122  2.03241638
##      Arm        Thigh        Leg
## -1.02127944 -0.89034509 -5.61777220
```

This tells us that a model with collinearity is bad at explaining the relationship between the response and the predictors. We cannot even be confident in the direction of the relationship. However, does collinearity effect prediction?

```
plot(fitted(hip_model), fitted(hip_model_noise), col = "dodgerblue", pch = 20,
      xlab = "Predicted, Without Noise", ylab = "Predicted, With Noise", cex = 1.5)
abline(a = 0, b = 1, col = "darkorange", lwd = 2)
```



We see that by plotting the predicted values using both models against each other, they are actually rather similar.

Let's now look at a smaller model,

```
hip_model_small = lm(hipcenter ~ Age + Arm + Ht, data = seatpos)
summary(hip_model_small)
```

```

## 
## Call:
## lm(formula = hipcenter ~ Age + Arm + Ht, data = seatpos)
## 
## Residuals:
##      Min       1Q   Median       3Q      Max 
## -82.347 -24.745 -0.094  23.555  58.314 
## 
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)    
## (Intercept) 493.2491   101.0724   4.880 0.0000246 ***
## Age          0.7988     0.5111   1.563  0.12735    
## Arm         -2.9385    3.5210  -0.835  0.40979    
## Ht          -3.4991    0.9954  -3.515  0.00127 **  
## --- 
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1 
## 
## Residual standard error: 36.12 on 34 degrees of freedom
## Multiple R-squared:  0.6631, Adjusted R-squared:  0.6333 
## F-statistic:  22.3 on 3 and 34 DF,  p-value: 0.00000003649

vif(hip_model_small)

```

```

##      Age      Arm      Ht 
## 1.749943 3.996766 3.508693

```

Immediately we see that multicollinearity isn't an issue here.

```
anova(hip_model_small, hip_model)
```

```

## Analysis of Variance Table
## 
## Model 1: hipcenter ~ Age + Arm + Ht
## Model 2: hipcenter ~ Age + Weight + HtShoes + Ht + Seated + Arm + Thigh +
##           Leg
## Res.Df   RSS Df Sum of Sq    F Pr(>F)    
## 1     34 44354                                 
## 2     29 41262  5   3091.9 0.4346 0.8207

```

Also notice that using an F -test to compare the two models, we would prefer the smaller model.

We now investigate the effect of adding another variable to this smaller model. Specifically we want to look at adding the variable `HtShoes`. So now our possible predictors are `HtShoes`, `Age`, `Arm`, and `Ht`. Our response is still `hipcenter`.

To quantify this effect we will look at a **variable added plot** and a **partial correlation coefficient**. For both of these, we will look at the residuals of two models:

- Regressing the response (`hipcenter`) against all of the predictors except the predictor of interest (`HtShoes`).
- Regressing the predictor of interest (`HtShoes`) against the other predictors (`Age`, `Arm`, and `Ht`).

```
ht_shoes_model_small = lm(HtShoes ~ Age + Arm + Ht, data = seatpos)
```

So now, the residuals of `hip_model_small` give us the variation of `hipcenter` that is *unexplained* by `Age`, `Arm`, and `Ht`. Similarly, the residuals of `ht_shoes_model_small` give us the variation of `HtShoes` unexplained by `Age`, `Arm`, and `Ht`.

The correlation of these two residuals gives us the **partial correlation coefficient** of `HtShoes` and `hipcenter` with the effects of `Age`, `Arm`, and `Ht` removed.

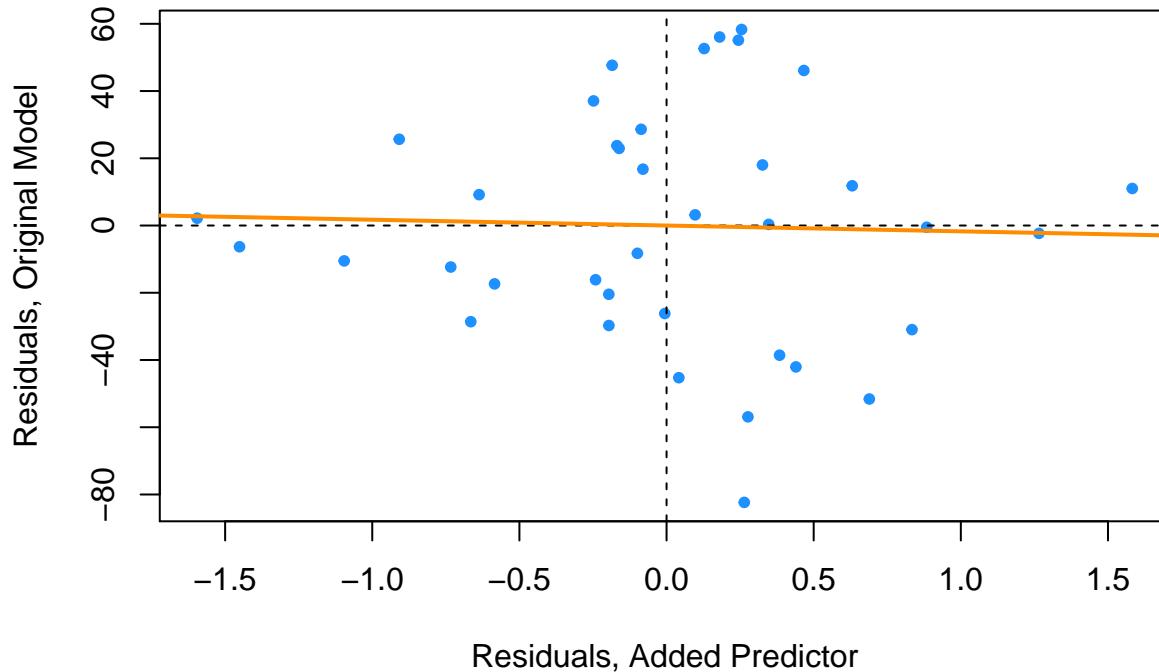
```
cor(resid(ht_shoes_model_small), resid(hip_model_small))
```

```
## [1] -0.03311061
```

Since this value is small, close to zero, it means that the variation of `hipcenter` that is unexplained by `Age`, `Arm`, and `Ht` shows very little correlation with the variation of `HtShoes` that is not explained by `Age`, `Arm`, and `Ht`. Thus adding `HtShoes` to the model would likely be of little benefit.

Similarly a **variable added plot** visualizes these residuals against each other. It is also helpful to regress the residuals of the response against the residuals of the predictor and add the regression line to the plot.

```
plot(resid(hip_model_small) ~ resid(ht_shoes_model_small),
      col = "dodgerblue", pch = 20,
      xlab = "Residuals, Added Predictor",
      ylab = "Residuals, Original Model")
abline(h = 0, lty = 2)
abline(v = 0, lty = 2)
abline(lm(resid(hip_model_small) ~ resid(ht_shoes_model_small)),
      col = "darkorange", lwd = 2)
```



Here the variable added plot shows almost no linear relationship. This tells us that adding `HtShoes` to the model would probably not be worthwhile. Since its variation is largely explained by the other predictors,

adding it to the model will not do much to improve the model. However it will increase the variation of the estimates and make the model much harder to interpret.

Had there been a strong linear relationship here, thus a large partial correlation coefficient, it would likely have been useful to add the additional predictor to the model.

This trade off is mostly true in general. As a model gets more predictors, errors will get smaller and its *prediction* will be better, but it will be harder to interpret. This is why, if we are interested in *explaining* the relationship between the predictors and the response, we often want a model that fits well, but with a small number of predictors with little correlation.

Next chapter we will learn about methods to find models that both fit well, but also have a small number of predictors. We will also discuss *overfitting*. Although, adding additional predictors will always make errors smaller, sometimes we will be “fitting the noise” and such a model will not generalize to additional observations well.

14.3 Simulation

Here we simulate example data with and without collinearity. We will note the difference in the distribution of the estimates of the β parameters, in particular their variance. However, we will also notice the similarity in their *MSE*.

We will use the model,

$$Y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \epsilon$$

where $\epsilon \sim N(\mu = 0, \sigma^2 = 25)$ and the β coefficients defined below.

```
set.seed(42)
beta_0 = 7
beta_1 = 3
beta_2 = 4
sigma = 5
```

We will use a sample size of 10, and 2500 simulations for both situations.

```
sample_size = 10
num_sim     = 2500
```

We'll first consider the situation with a collinearity issue, so we manually create the two predictor variables.

```
x1 = c(1, 2, 3, 4, 5, 6, 7, 8, 9, 10)
x2 = c(1, 2, 3, 4, 5, 7, 6, 10, 9, 8)
```

```
c(sd(x1), sd(x2))
```

```
## [1] 3.02765 3.02765
```

```
cor(x1, x2)
```

```
## [1] 0.9393939
```

Notice that they have extremely high correlation.

```
true_line_bad = beta_0 + beta_1 * x1 + beta_2 * x2
beta_hat_bad = matrix(0, num_sim, 2)
mse_bad       = rep(0, num_sim)
```

We perform the simulation 2500 times, each time fitting a regression model, and storing the estimated coefficients and the MSE.

```
for (s in 1:num_sim) {
  y = true_line_bad + rnorm(n = sample_size, mean = 0, sd = sigma)
  reg_out = lm(y ~ x1 + x2)
  beta_hat_bad[s, ] = coef(reg_out)[-1]
  mse_bad[s] = mean(resid(reg_out)^ 2)
}
```

Now we move to the situation without a collinearity issue, so we again manually create the two predictor variables.

```
z1 = c(1, 2, 3, 4, 5, 6, 7, 8, 9, 10)
z2 = c(9, 2, 7, 4, 5, 6, 3, 8, 1, 10)
```

Notice that the standard deviations of each are the same as before, however, now the correlation is extremely close to 0.

```
c(sd(z1), sd(z2))
```

```
## [1] 3.02765 3.02765
```

```
cor(z1, z2)
```

```
## [1] 0.03030303
```

```
true_line_good = beta_0 + beta_1 * z1 + beta_2 * z2
beta_hat_good = matrix(0, num_sim, 2)
mse_good       = rep(0, num_sim)
```

We then perform simulations and store the same results.

```
for (s in 1:num_sim) {
  y = true_line_good + rnorm(n = sample_size, mean = 0, sd = sigma)
  reg_out = lm(y ~ z1 + z2)
  beta_hat_good[s, ] = coef(reg_out)[-1]
  mse_good[s] = mean(resid(reg_out)^ 2)
}
```

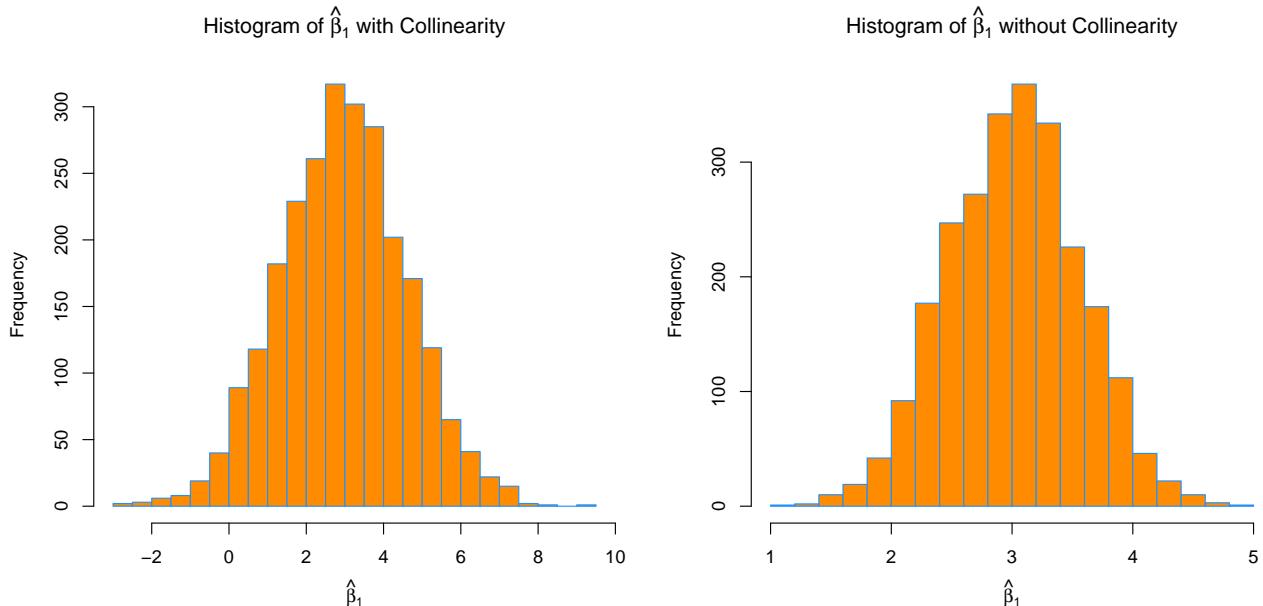
We'll now investigate the differences.

```
par(mfrow = c(1, 2))
hist(beta_hat_bad[, 1],
      col = "darkorange",
      border = "dodgerblue",
```

```

main = expression("Histogram of " *hat(beta)[1]* " with Collinearity"),
xlab = expression(hat(beta)[1]),
breaks = 20)
hist(beta_hat_good[, 1],
col = "darkorange",
border = "dodgerblue",
main = expression("Histogram of " *hat(beta)[1]* " without Collinearity"),
xlab = expression(hat(beta)[1]),
breaks = 20)

```



First, for β_1 , which has a true value of 3, we see that both with and without collinearity, the simulated values are centered near 3.

```
mean(beta_hat_bad[, 1])
```

```
## [1] 2.963325
```

```
mean(beta_hat_good[, 1])
```

```
## [1] 3.013414
```

The way the predictors were created, the $S_{x_j x_j}$ portion of the variance is the same for the predictors in both cases, but the variance is still much larger in the simulations performed with collinearity. The variance is so large in the collinear case, that sometimes the estimated coefficient for β_1 is negative!

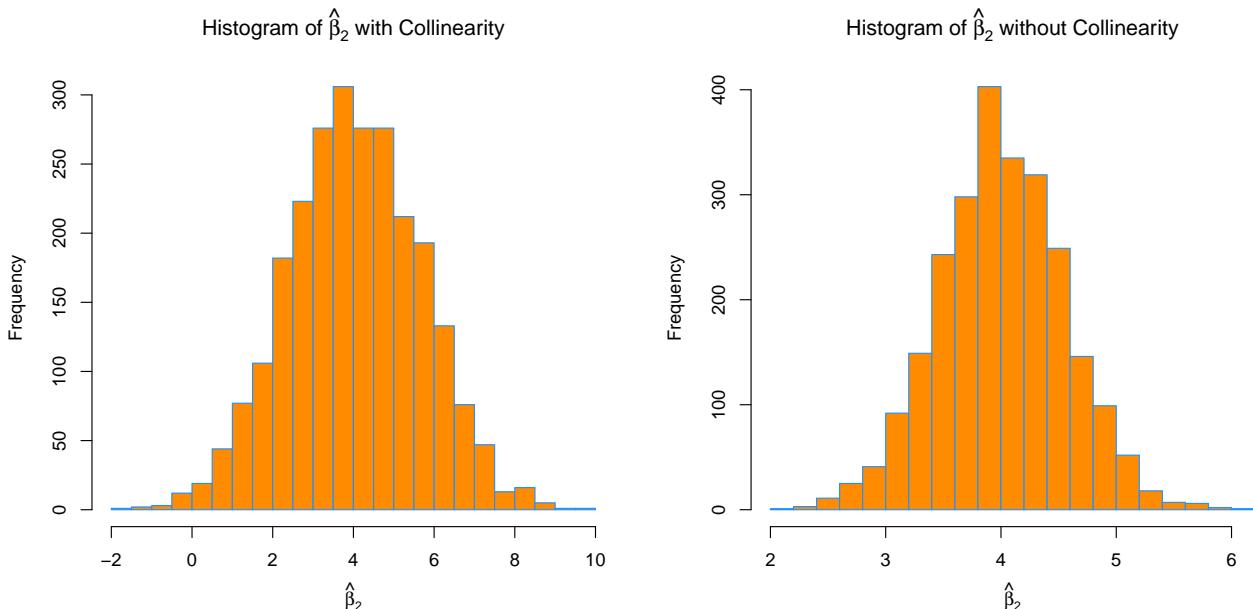
```
sd(beta_hat_bad[, 1])
```

```
## [1] 1.633294
```

```
sd(beta_hat_good[, 1])
```

```
## [1] 0.5484684
```

```
par(mfrow = c(1, 2))
hist(beta_hat_bad[, 2],
      col = "darkorange",
      border = "dodgerblue",
      main = expression("Histogram of " *hat(beta)[2]* " with Collinearity"),
      xlab = expression(hat(beta)[2]),
      breaks = 20)
hist(beta_hat_good[, 2],
      col = "darkorange",
      border = "dodgerblue",
      main = expression("Histogram of " *hat(beta)[2]* " without Collinearity"),
      xlab = expression(hat(beta)[2]),
      breaks = 20)
```



We see the same issues with β_2 . On average the estimates are correct, but the variance is again much larger with collinearity.

```
mean(beta_hat_bad[, 2])
```

```
## [1] 4.025059
```

```
mean(beta_hat_good[, 2])
```

```
## [1] 4.004913
```

```
sd(beta_hat_bad[, 2])
```

```
## [1] 1.642592
```

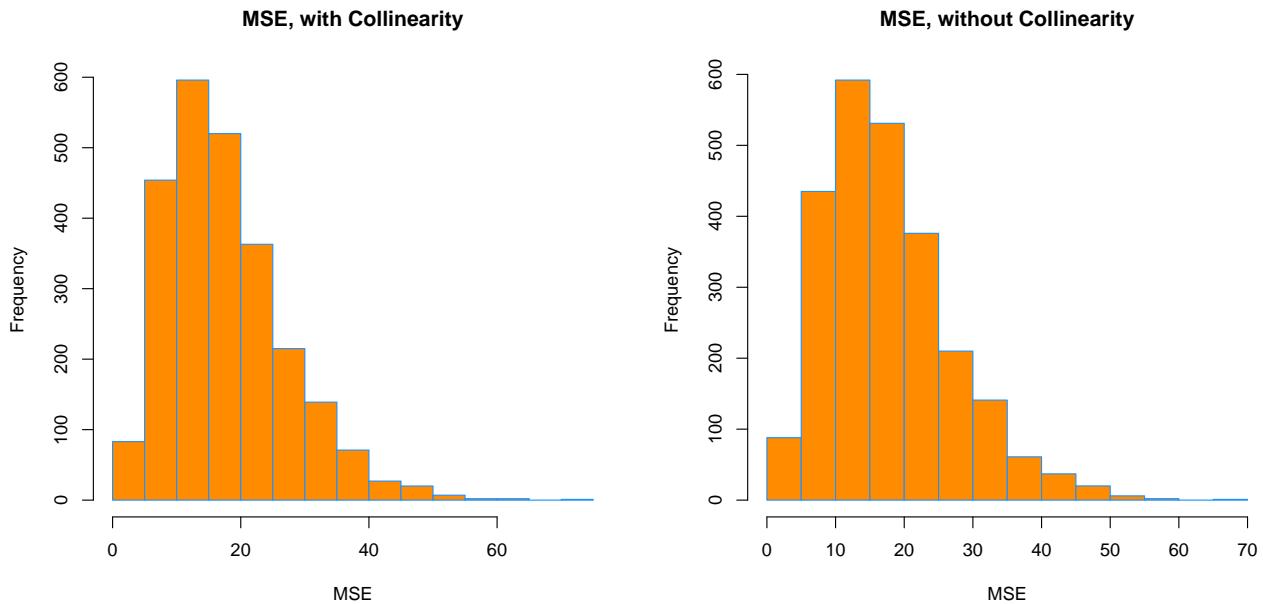
```

sd(beta_hat_good[, 2])

## [1] 0.5470381

par(mfrow = c(1, 2))
hist(mse_bad,
  col = "darkorange",
  border = "dodgerblue",
  main = "MSE, with Collinearity",
  xlab = "MSE")
hist(mse_good,
  col = "darkorange",
  border = "dodgerblue",
  main = "MSE, without Collinearity",
  xlab = "MSE")

```



Interestingly, in both cases, the MSE is roughly the same on average. Again, this is because collinearity effects a model's ability to *explain*, but not predict.

```

mean(mse_bad)

## [1] 17.7186

mean(mse_good)

## [1] 17.70513

```

Chapter 15

Variable Selection and Model Building

“Choose well. Your choice is brief, and yet endless.”

— Johann Wolfgang von Goethe

After reading this chapter you will be able to:

- Understand the trade-off between goodness-of-fit and model complexity.
- Use variable selection procedures to find a good model from a set of possible models.
- Understand the two uses of models: explanation and prediction.

Last chapter we saw how correlation between predictor variables can have undesirable effects on models. We used variance inflation factors to assess the severity of the collinearity issues caused by these correlations. We also saw how fitting a smaller model, leaving out some of the correlated predictors, results in a model which no longer suffers from collinearity issues. But how should we chose this smaller model?

This chapter, we will discuss several *criteria* and *procedures* for choosing a “good” model from among a choice of many.

15.1 Quality Criterion

So far, we have seen criteria such as R^2 and RMSE for assessing quality of fit. However, both of these have a fatal flaw. By increasing the size of a model, that is adding predictors, that can at worst not improve. It is impossible to add a predictor to a model and make R^2 or RMSE worse. That means, if we were to use either of these to chose between models, we would *always* simply choose the larger model. Eventually we would simply be fitting to noise.

This suggests that we need a quality criteria that takes into account the size of the model, since our preference is for small models that still fit well. We are willing to sacrifice a small amount of goodness-of-fit for obtaining a smaller model. We will look at three criteria that do this explicitly: AIC, BIC, and Adjusted R^2 . We will also look at one, Cross-Validated RMSE, which implicitly considers the size of the model.

15.1.1 Akaike Information Criterion

The first criteria we will discuss is the Akaike Information Criterion, or AIC for short. (Note that, when *Akaike* first introduced this metric, it was simply called *An* Information Criterion. The *A* has changed meaning over the years.)

Recall, the maximized log-likelihood of a regression model can be written as

$$\log L(\hat{\beta}, \hat{\sigma}^2) = -\frac{n}{2} \log(2\pi) - \frac{n}{2} \log\left(\frac{\text{RSS}}{n}\right) - \frac{n}{2},$$

where $\text{RSS} = \sum_{i=1}^n (y_i - \hat{y}_i)^2$ and $\hat{\beta}$ and $\hat{\sigma}^2$ were chosen to maximize the likelihood.

Then we can define AIC as

$$\text{AIC} = -2 \log L(\hat{\beta}, \hat{\sigma}^2) + 2p = n + n \log(2\pi) + n \log\left(\frac{\text{RSS}}{n}\right) + 2p,$$

which is a measure of quality of the model. The smaller the AIC, the better. To see why, let's talk about the two main components of AIC, the **likelihood** (which measures goodness-of-fit) and the **penalty** (which is a function of the size of the model).

The likelihood portion of AIC is given by

$$-2 \log L(\hat{\beta}, \hat{\sigma}^2) = n + n \log(2\pi) + n \log\left(\frac{\text{RSS}}{n}\right).$$

For the sake of comparing models, the only term here that will change is $n \log\left(\frac{\text{RSS}}{n}\right)$, which is function of RSS. The

$$n + n \log(2\pi)$$

terms will be constant across all models applied to the same data. So, when a model fits well, that is, has a low RSS, then this likelihood component will be small.

Similarly, we can discuss the penalty component of AIC which is,

$$2p,$$

where p is the number of β parameters in the model. We call this a penalty, because it is large when p is large, but we are seeking to find a small AIC

Thus, a good model, that is one with a small AIC, will have a good balance between fitting well, and using a small number of parameters. For comparing models

$$\text{AIC} = n \log\left(\frac{\text{RSS}}{n}\right) + 2p$$

is a sufficient expression, as $n + n \log(2\pi)$ is the same across all models for any particular dataset.

15.1.2 Bayesian Information Criterion

The Bayesian Information Criterion, or BIC, is similar to AIC, but has a larger penalty. BIC also quantifies the trade-off between a model which fits well and the number of model parameters, however for a reasonable sample size, generally picks a smaller model than AIC. Again, for model selection use the model with the smallest BIC.

$$\text{BIC} = -2 \log L(\hat{\beta}, \hat{\sigma}^2) + \log(n)p = n + n \log(2\pi) + n \log\left(\frac{\text{RSS}}{n}\right) + \log(n)p.$$

Notice that the AIC penalty was

$$2p,$$

whereas for BIC, the penalty is

$$\log(n)p.$$

So, for any dataset where $\log(n) > 2$ the BIC penalty will be larger than the AIC penalty, thus BIC will likely prefer a smaller model.

Note that, sometimes the penalty is considered a general expression of the form

$$k \cdot p.$$

Then, for AIC $k = 2$, and for BIC $k = \log(n)$.

For comparing models

$$\text{BIC} = n \log\left(\frac{\text{RSS}}{n}\right) + \log(n)p$$

is again a sufficient expression, as $n + n \log(2\pi)$ is the same across all models for any particular dataset.

15.1.3 Adjusted R-Squared

Recall,

$$R^2 = 1 - \frac{\text{SSE}}{\text{SST}} = 1 - \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{\sum_{i=1}^n (y_i - \bar{y})^2}.$$

We now define

$$R_a^2 = 1 - \frac{\text{SSE}/(n-p)}{\text{SST}/(n-1)} = 1 - \left(\frac{n-1}{n-p}\right)(1-R^2)$$

which we call the Adjusted R^2 .

Unlike R^2 which can never become smaller with added predictors, Adjusted R^2 effectively penalizes for additional predictors, and can decrease with added predictors. Like R^2 , larger is still better.

15.1.4 Cross-Validated RMSE

Each of the previous three metrics explicitly used p , the number of parameters, in their calculations. Thus, they all explicitly limit the size of models chosen when used to compare models.

We'll now briefly introduce **overfitting** and **cross-validation**.

```
make_poly_data = function(sample_size = 11) {
  x = seq(0, 10)
  y = 3 + x + 4 * x ^ 2 + rnorm(n = sample_size, mean = 0, sd = 20)
  data.frame(x, y)
}

set.seed(1234)
poly_data = make_poly_data()
```

Here we have generated data where the mean of Y is a quadratic function of a single predictor x , specifically,

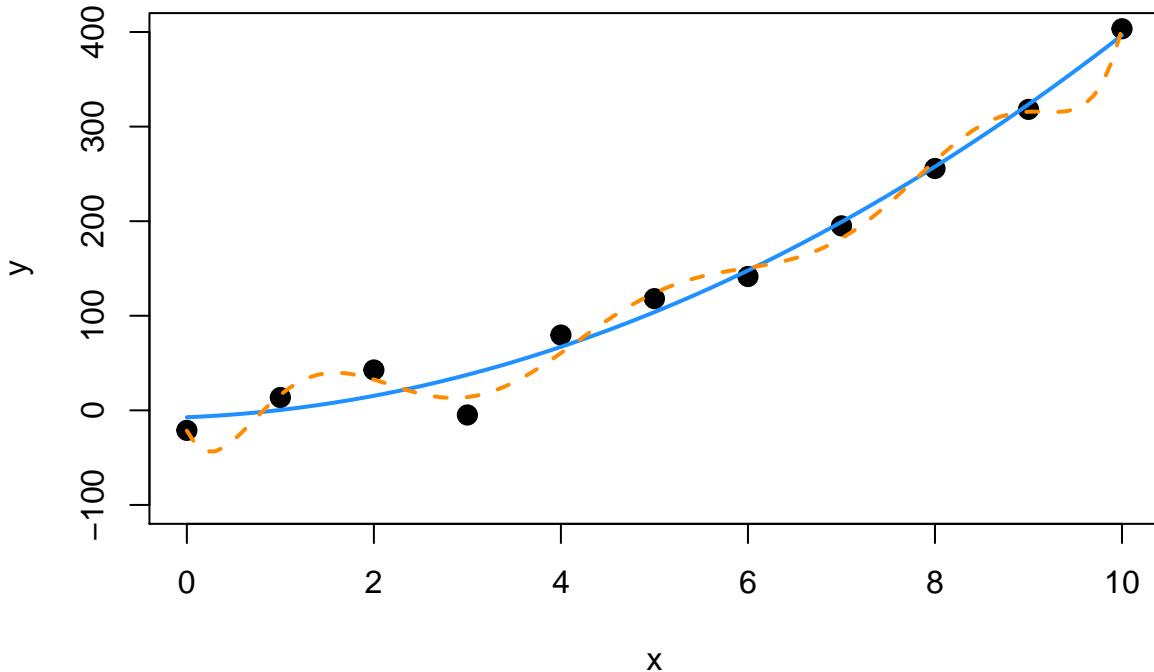
$$Y = 3 + x + 4x^2 + \epsilon.$$

We'll now fit two models to this data, one which has the correct form, quadratic, and one that is large, which includes terms up to and including an eighth degree.

```
fit_quad = lm(y ~ poly(x, degree = 2), data = poly_data)
fit_big = lm(y ~ poly(x, degree = 8), data = poly_data)
```

We then plot the data and the results of the two models.

```
plot(y ~ x, data = poly_data, ylim = c(-100, 400), cex = 2, pch = 20)
xplot = seq(0, 10, by = 0.1)
lines(xplot, predict(fit_quad, newdata = data.frame(x = xplot)),
      col = "dodgerblue", lwd = 2, lty = 1)
lines(xplot, predict(fit_big, newdata = data.frame(x = xplot)),
      col = "darkorange", lwd = 2, lty = 2)
```



We can see that the solid blue curve models this data rather nicely. The dashed orange curve fits the points better, making smaller errors, however it is unlikely that it is correctly modeling the true relationship between x and y . It is fitting the random noise. This is an example of **overfitting**.

We see that the larger model indeed has a lower RMSE.

```
sqrt(mean(resid(fit_quad) ^ 2))
```

```
## [1] 17.61812
```

```
sqrt(mean(resid(fit_big) ^ 2))
```

```
## [1] 10.4197
```

To correct for this, we will introduce cross-validation. We define the leave-one-out cross-validated RMSE to be

$$\text{RMSE}_{\text{LOOCV}} = \sqrt{\frac{1}{n} \sum_{i=1}^n e_{[i]}^2}.$$

The $e_{[i]}$ are the residual for the i th observation, when that observation is **not** used to fit the model.

$$e_{[i]} = y_i - \hat{y}_{[i]}$$

That is, the fitted value is calculated as

$$\hat{y}_{[i]} = \mathbf{x}_i^\top \hat{\beta}_{[i]}$$

where $\hat{\beta}_{[i]}$ are the estimated coefficients when the i th observation is removed from the dataset.

In general, to perform this calculation, we would be required to fit the model n times, once with each possible observation removed. However, for leave-one-out cross-validation and linear models, the equation can be rewritten as

$$\text{RMSE}_{\text{LOOCV}} = \sqrt{\frac{1}{n} \sum_{i=1}^n \left(\frac{e_i}{1 - h_i} \right)^2},$$

where h_i are the leverages and e_i are the usual residuals. This is great, because now we can obtain the LOOCV RMSE by fitting only one model! In practice 5 or 10 fold cross-validation are much more popular. For example, in 5-fold cross-validation, the model is fit 5 times, each time leaving out a fifth of the data, then predicting on those values. We'll leave in-depth examination of cross-validation to a machine learning course, and simply use LOOCV here.

Let's calculate LOOCV RMSE for both models, then discuss *why* we want to do so. We first write a function which calculates the LOOCV RMSE as defined using the shortcut formula for linear models.

```
calc_loocv_rmse = function(model) {
  sqrt(mean((resid(model) / (1 - hatvalues(model))) ^ 2))
}
```

Then calculate the metric for both models.

```
calc_loocv_rmse(fit_quad)
```

```
## [1] 23.57189
```

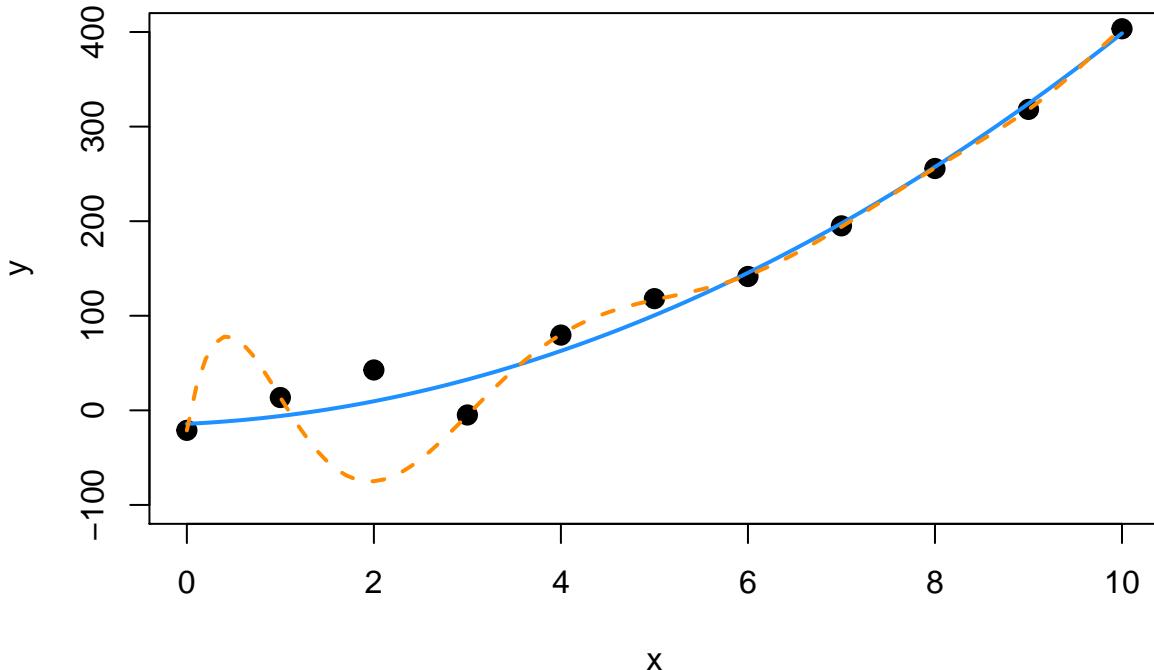
```
calc_loocv_rmse(fit_big)
```

```
## [1] 1334.357
```

Now we see that the quadratic model has a much smaller LOOCV RMSE, so we would prefer this quadratic model. This is because the large model has *severely* over-fit the data. By leaving a single data point out and fitting the large model, the resulting fit is much different than the fit using all of the data. For example, let's leave out the third data point and fit both models, then plot the result.

```
fit_quad_removed = lm(y ~ poly(x, degree = 2), data = poly_data[-3, ])
fit_big_removed = lm(y ~ poly(x, degree = 8), data = poly_data[-3, ])

plot(y ~ x, data = poly_data, ylim = c(-100, 400), cex = 2, pch = 20)
xplot = seq(0, 10, by = 0.1)
lines(xplot, predict(fit_quad_removed, newdata = data.frame(x = xplot)),
      col = "dodgerblue", lwd = 2, lty = 1)
lines(xplot, predict(fit_big_removed, newdata = data.frame(x = xplot)),
      col = "darkorange", lwd = 2, lty = 2)
```



We see that on average, the solid blue line for the quadratic model has similar errors as before. It has changed very slightly. However, the dashed orange line for the large model, has a huge error at the point that was removed and is much different than the previous fit.

This is the purpose of cross-validation. By assessing how the model fits points that were not used to perform the regression, we get an idea of how well the model will work for future observations. It assesses how well the model works in general, not simply on the observed data.

15.2 Selection Procedures

We've now seen a number of model quality criteria, but now we need to address which models to consider. Model selection involves both a quality criterion, plus a search procedure.

```
library(faraway)
hipcenter_mod = lm(hipcenter ~ ., data = seatpos)
coef(hipcenter_mod)
```

```
## (Intercept)          Age        Weight       HtShoes         Ht      Seated
## 436.43212823  0.77571620  0.02631308 -2.69240774  0.60134458  0.53375170
##      Arm          Thigh        Leg
## -1.32806864 -1.14311888 -6.43904627
```

Let's return to the `seatpos` data from the `faraway` package. Now, let's consider only models with first order terms, thus no interactions and no polynomials. There are *eight* predictors in this model. So if we consider all possible models, ranging from using 0 predictors, to all eight predictors, there are

$$\sum_{k=0}^{p-1} \binom{p-1}{k} = 2^{p-1} = 2^8 = 256$$

possible models.

If we had 10 or more predictors, we would already be considering over 1000 models! For this reason, we often search through possible models in an intelligent way, bypassing some models that are unlikely to be considered good. We will consider three search procedures: backwards, forwards, and stepwise.

15.2.1 Backward Search

Backward selection procedures start with all possible predictors in the model, then considers how deleting a single predictor will effect a chosen metric. Let's try this on the `seatpos` data. We will use the `step()` function in R which by default uses AIC as its metric of choice.

```
hipcenter_mod_back_aic = step(hipcenter_mod, direction = "backward")
```

```
## Start:  AIC=283.62
## hipcenter ~ Age + Weight + HtShoes + Ht + Seated + Arm + Thigh +
##           Leg
##
##              Df Sum of Sq   RSS   AIC
## - Ht         1     5.01 41267 281.63
## - Weight    1     8.99 41271 281.63
## - Seated    1    28.64 41290 281.65
## - HtShoes   1   108.43 41370 281.72
## - Arm       1   164.97 41427 281.78
## - Thigh     1   262.76 41525 281.87
## <none>          41262 283.62
## - Age       1   2632.12 43894 283.97
## - Leg       1   2654.85 43917 283.99
##
## Step:  AIC=281.63
## hipcenter ~ Age + Weight + HtShoes + Seated + Arm + Thigh + Leg
##
##              Df Sum of Sq   RSS   AIC
## - Weight    1    11.10 41278 279.64
## - Seated    1    30.52 41297 279.66
## - Arm       1   160.50 41427 279.78
## - Thigh     1   269.08 41536 279.88
## - HtShoes   1   971.84 42239 280.51
## <none>          41267 281.63
## - Leg       1   2664.65 43931 282.01
## - Age       1   2808.52 44075 282.13
##
## Step:  AIC=279.64
## hipcenter ~ Age + HtShoes + Seated + Arm + Thigh + Leg
##
##              Df Sum of Sq   RSS   AIC
## - Seated    1    35.10 41313 277.67
## - Arm       1   156.47 41434 277.78
## - Thigh     1   285.16 41563 277.90
## - HtShoes   1   975.48 42253 278.53
## <none>          41278 279.64
## - Leg       1   2661.39 43939 280.01
## - Age       1   3011.86 44290 280.31
##
## Step:  AIC=277.67
```

```

## hipcenter ~ Age + HtShoes + Arm + Thigh + Leg
##
##          Df Sum of Sq   RSS   AIC
## - Arm      1   172.02 41485 275.83
## - Thigh     1   344.61 41658 275.99
## - HtShoes   1  1853.43 43166 277.34
## <none>           41313 277.67
## - Leg       1  2871.07 44184 278.22
## - Age       1  2976.77 44290 278.31
##
## Step:  AIC=275.83
## hipcenter ~ Age + HtShoes + Thigh + Leg
##
##          Df Sum of Sq   RSS   AIC
## - Thigh     1    472.8 41958 274.26
## <none>           41485 275.83
## - HtShoes   1   2340.7 43826 275.92
## - Age       1   3501.0 44986 276.91
## - Leg       1   3591.7 45077 276.98
##
## Step:  AIC=274.26
## hipcenter ~ Age + HtShoes + Leg
##
##          Df Sum of Sq   RSS   AIC
## <none>           41958 274.26
## - Age       1   3108.8 45067 274.98
## - Leg       1   3476.3 45434 275.28
## - HtShoes   1   4218.6 46176 275.90

```

We start with the model `hipcenter ~ ..`, which is otherwise known as `hipcenter ~ Age + Weight + HtShoes + Ht + Seated + Arm + Thigh + Leg`. R will then repeatedly attempt to delete a predictor until it stops, or reaches the model `hipcenter ~ 1`, which contains no predictors.

At each “step”, R reports the current model, its AIC, and the possible steps with their RSS and more importantly AIC.

In this example, at the first step, the current model is `hipcenter ~ Age + Weight + HtShoes + Ht + Seated + Arm + Thigh + Leg` which has an AIC of 283.62. Note that when R is calculating this value, it is using `extractAIC()`, which uses the expression

$$AIC = n \log \left(\frac{RSS}{n} \right) + 2p,$$

which we quickly verify.

```
extractAIC(hipcenter_mod) # returns both p and AIC
```

```
## [1] 9.000 283.624
```

```
n = length(resid(hipcenter_mod))
(p = length(coef(hipcenter_mod)))
```

```
## [1] 9
```

```
n * log(mean(resid(hipcenter_mod) ^ 2)) + 2 * p
```

```
## [1] 283.624
```

Returning to the first step, R then gives us a row which shows the effect of deleting each of the current predictors. The - signs at the beginning of each row indicates we are considering removing a predictor. There is also a row with <none> which is a row for keeping the current model. Notice that this row has the smallest RSS, as it is the largest model.

We see that every row above <none> has a smaller AIC than the row for <none> with the one at the top, Ht, giving the lowest AIC. Thus we remove Ht from the model, and continue the process.

Notice, in the second step, we start with the model `hipcenter ~ Age + Weight + HtShoes + Seated + Arm + Thigh + Leg` and the variable Ht is no longer considered.

We continue the process until we reach the model `hipcenter ~ Age + HtShoes + Leg`. At this step, the row for <none> tops the list, as removing any additional variable will not improve the AIC. This is the model which is stored in `hipcenter_mod_back_aic`.

```
coef(hipcenter_mod_back_aic)
```

```
## (Intercept)      Age     HtShoes      Leg
## 456.2136538   0.5998327  -2.3022555  -6.8297461
```

We could also search through the possible models in a backwards fashion using BIC. To do so, we again use the `step()` function, but now specify `k = log(n)`, where `n` stores the number of observations in the data.

```
n = length(resid(hipcenter_mod))
hipcenter_mod_back_bic = step(hipcenter_mod, direction = "backward", k = log(n))
```

```
## Start:  AIC=298.36
## hipcenter ~ Age + Weight + HtShoes + Ht + Seated + Arm + Thigh +
##           Leg
##
##              Df Sum of Sq   RSS   AIC
## - Ht      1     5.01 41267 294.73
## - Weight  1     8.99 41271 294.73
## - Seated  1    28.64 41290 294.75
## - HtShoes 1   108.43 41370 294.82
## - Arm     1   164.97 41427 294.88
## - Thigh   1   262.76 41525 294.97
## - Age     1   2632.12 43894 297.07
## - Leg     1   2654.85 43917 297.09
## <none>            41262 298.36
##
## Step:  AIC=294.73
## hipcenter ~ Age + Weight + HtShoes + Seated + Arm + Thigh + Leg
##
##              Df Sum of Sq   RSS   AIC
## - Weight  1    11.10 41278 291.10
## - Seated  1    30.52 41297 291.12
## - Arm    1   160.50 41427 291.24
## - Thigh  1   269.08 41536 291.34
```

```

## - HtShoes 1 971.84 42239 291.98
## - Leg      1 2664.65 43931 293.47
## - Age      1 2808.52 44075 293.59
## <none>          41267 294.73
##
## Step: AIC=291.1
## hipcenter ~ Age + HtShoes + Seated + Arm + Thigh + Leg
##
##             Df Sum of Sq   RSS   AIC
## - Seated    1   35.10 41313 287.50
## - Arm       1   156.47 41434 287.61
## - Thigh     1   285.16 41563 287.73
## - HtShoes   1   975.48 42253 288.35
## - Leg       1   2661.39 43939 289.84
## - Age       1   3011.86 44290 290.14
## <none>          41278 291.10
##
## Step: AIC=287.5
## hipcenter ~ Age + HtShoes + Arm + Thigh + Leg
##
##             Df Sum of Sq   RSS   AIC
## - Arm       1   172.02 41485 284.02
## - Thigh     1   344.61 41658 284.18
## - HtShoes   1   1853.43 43166 285.53
## - Leg       1   2871.07 44184 286.41
## - Age       1   2976.77 44290 286.50
## <none>          41313 287.50
##
## Step: AIC=284.02
## hipcenter ~ Age + HtShoes + Thigh + Leg
##
##             Df Sum of Sq   RSS   AIC
## - Thigh     1   472.8 41958 280.81
## - HtShoes   1   2340.7 43826 282.46
## - Age       1   3501.0 44986 283.46
## - Leg       1   3591.7 45077 283.54
## <none>          41485 284.02
##
## Step: AIC=280.81
## hipcenter ~ Age + HtShoes + Leg
##
##             Df Sum of Sq   RSS   AIC
## - Age       1   3108.8 45067 279.89
## - Leg       1   3476.3 45434 280.20
## <none>          41958 280.81
## - HtShoes   1   4218.6 46176 280.81
##
## Step: AIC=279.89
## hipcenter ~ HtShoes + Leg
##
##             Df Sum of Sq   RSS   AIC
## - Leg       1   3038.8 48105 278.73
## <none>          45067 279.89
## - HtShoes   1   5004.4 50071 280.25

```

```
##
## Step: AIC=278.73
## hipcenter ~ HtShoes
##
##          Df Sum of Sq    RSS    AIC
## <none>            48105 278.73
## - HtShoes  1     83534 131639 313.35
```

The procedure is exactly the same, except at each step we look to improve the BIC, which R still labels AIC in the output.

The variable `hipcenter_mod_back_bic` stores the model chosen by this procedure.

```
coef(hipcenter_mod_back_bic)
```

```
## (Intercept)      HtShoes
## 565.592659   -4.262091
```

We note that this model is *smaller*, has fewer predictors, than the model chosen by AIC, which is what we would expect. Also note that while both models are different, neither uses both `Ht` and `HtShoes` which are extremely correlated.

We can use information from the `summary()` function to compare their Adjusted R^2 values. Note that either selected model performs better than the original full model.

```
summary(hipcenter_mod)$adj.r.squared
```

```
## [1] 0.6000855
```

```
summary(hipcenter_mod_back_aic)$adj.r.squared
```

```
## [1] 0.6531427
```

```
summary(hipcenter_mod_back_bic)$adj.r.squared
```

```
## [1] 0.6244149
```

We can also calculate the LOOCV RMSE for both selected models, as well as the full model.

```
calc_loocv_rmse(hipcenter_mod)
```

```
## [1] 44.44564
```

```
calc_loocv_rmse(hipcenter_mod_back_aic)
```

```
## [1] 37.58473
```

```
calc_loocv_rmse(hipcenter_mod_back_bic)
```

```
## [1] 37.40564
```

We see that we would prefer the model chosen via BIC if using LOOCV RMSE as our metric.

15.2.2 Forward Search

Forward selection is the exact opposite of backwards selection. Here we tell R to start with a model using no predictors, that is `hipcenter ~ 1`, then at each step R will attempt to add a predictor until it finds a good model or reaches `hipcenter ~ Age + Weight + HtShoes + Ht + Seated + Arm + Thigh + Leg`.

```
hipcenter_mod_start = lm(hipcenter ~ 1, data = seatpos)
hipcenter_mod_forw_aic = step(
  hipcenter_mod_start,
  scope = hipcenter ~ Age + Weight + HtShoes + Ht + Seated + Arm + Thigh + Leg,
  direction = "forward")
```

```
## Start: AIC=311.71
## hipcenter ~ 1
##
##          Df Sum of Sq   RSS   AIC
## + Ht      1     84023  47616 275.07
## + HtShoes 1     83534  48105 275.45
## + Leg     1     81568  50071 276.98
## + Seated   1     70392  61247 284.63
## + Weight   1     53975  77664 293.66
## + Thigh    1     46010  85629 297.37
## + Arm     1     45065  86574 297.78
## <none>           131639 311.71
## + Age     1     5541  126098 312.07
##
## Step: AIC=275.07
## hipcenter ~ Ht
##
##          Df Sum of Sq   RSS   AIC
## + Leg     1    2781.10 44835 274.78
## <none>           47616 275.07
## + Age     1    2353.51 45262 275.14
## + Weight   1    195.86 47420 276.91
## + Seated   1    101.56 47514 276.99
## + Arm     1     75.78 47540 277.01
## + HtShoes 1     25.76 47590 277.05
## + Thigh    1      4.63 47611 277.06
##
## Step: AIC=274.78
## hipcenter ~ Ht + Leg
##
##          Df Sum of Sq   RSS   AIC
## + Age     1    2896.60 41938 274.24
## <none>           44835 274.78
```

```

## + Arm      1   522.72 44312 276.33
## + Weight   1   445.10 44390 276.40
## + HtShoes  1    34.11 44801 276.75
## + Thigh    1    32.96 44802 276.75
## + Seated   1     1.12 44834 276.78
##
## Step: AIC=274.24
## hipcenter ~ Ht + Leg + Age
##
##          Df Sum of Sq   RSS   AIC
## <none>            41938 274.24
## + Thigh   1    372.71 41565 275.90
## + Arm     1    257.09 41681 276.01
## + Seated  1    121.26 41817 276.13
## + Weight  1     46.83 41891 276.20
## + HtShoes 1     13.38 41925 276.23

```

Again, by default R uses AIC as its quality metric when using the `step()` function. Also note that now the rows begin with a `+` which indicates addition of predictors to the current model from any step.

```

hipcenter_mod_forw_bic = step(
  hipcenter_mod_start,
  scope = hipcenter ~ Age + Weight + HtShoes + Ht + Seated + Arm + Thigh + Leg,
  direction = "forward", k = log(n))

```

```

## Start: AIC=313.35
## hipcenter ~ 1
##
##          Df Sum of Sq   RSS   AIC
## + Ht      1    84023  47616 278.34
## + HtShoes 1    83534  48105 278.73
## + Leg     1    81568  50071 280.25
## + Seated  1    70392  61247 287.91
## + Weight  1    53975  77664 296.93
## + Thigh   1    46010  85629 300.64
## + Arm     1    45065  86574 301.06
## <none>            131639 313.35
## + Age     1    5541   126098 315.35
##
## Step: AIC=278.34
## hipcenter ~ Ht
##
##          Df Sum of Sq   RSS   AIC
## <none>            47616 278.34
## + Leg     1   2781.10 44835 279.69
## + Age     1   2353.51 45262 280.05
## + Weight  1   195.86 47420 281.82
## + Seated  1   101.56 47514 281.90
## + Arm     1    75.78 47540 281.92
## + HtShoes 1    25.76 47590 281.96
## + Thigh   1     4.63 47611 281.98

```

We can make the same modification as last time to instead use BIC with forward selection.

```

summary(hipcenter_mod)$adj.r.squared

## [1] 0.6000855

summary(hipcenter_mod_forw_aic)$adj.r.squared

## [1] 0.6533055

summary(hipcenter_mod_forw_bic)$adj.r.squared

## [1] 0.6282374

```

We can compare the two selected models' Adjusted R^2 as well as their LOOCV RMSE. The results are very similar to those using backwards selection, although the models are not exactly the same.

```

calc_loocv_rmse(hipcenter_mod)

## [1] 44.44564

calc_loocv_rmse(hipcenter_mod_forw_aic)

## [1] 37.62516

calc_loocv_rmse(hipcenter_mod_forw_bic)

## [1] 37.2511

```

15.2.3 Stepwise Search

Stepwise search checks going both backwards and forwards at every step. It considers the addition of any variable not currently in the model, as well as the removal of any variable currently in the model.

Here we perform stepwise search using AIC as our metric. We start with the model `hipcenter ~ 1` and search up to `hipcenter ~ Age + Weight + HtShoes + Ht + Seated + Arm + Thigh + Leg`. Notice that at many of the steps, some rows begin with `-`, while others begin with `+`.

```

hipcenter_mod_both_aic = step(
  hipcenter_mod_start,
  scope = hipcenter ~ Age + Weight + HtShoes + Ht + Seated + Arm + Thigh + Leg,
  direction = "both")

## Start: AIC=311.71
## hipcenter ~ 1
##
##          Df Sum of Sq    RSS    AIC
## + Ht      1     84023  47616 275.07
## + HtShoes 1     83534  48105 275.45
## + Leg     1     81568  50071 276.98

```

```

## + Seated  1    70392 61247 284.63
## + Weight 1    53975 77664 293.66
## + Thigh   1    46010 85629 297.37
## + Arm    1    45065 86574 297.78
## <none>          131639 311.71
## + Age     1    5541 126098 312.07
##
## Step: AIC=275.07
## hipcenter ~ Ht
##
##           Df Sum of Sq   RSS   AIC
## + Leg      1    2781 44835 274.78
## <none>          47616 275.07
## + Age     1    2354 45262 275.14
## + Weight  1    196  47420 276.91
## + Seated  1    102  47514 276.99
## + Arm    1     76  47540 277.01
## + HtShoes 1     26  47590 277.05
## + Thigh   1      5  47611 277.06
## - Ht     1    84023 131639 311.71
##
## Step: AIC=274.78
## hipcenter ~ Ht + Leg
##
##           Df Sum of Sq   RSS   AIC
## + Age     1   2896.6 41938 274.24
## <none>          44835 274.78
## - Leg    1   2781.1 47616 275.07
## + Arm    1   522.7 44312 276.33
## + Weight 1   445.1 44390 276.40
## + HtShoes 1    34.1 44801 276.75
## + Thigh   1    33.0 44802 276.75
## + Seated  1     1.1 44834 276.78
## - Ht     1   5236.3 50071 276.98
##
## Step: AIC=274.24
## hipcenter ~ Ht + Leg + Age
##
##           Df Sum of Sq   RSS   AIC
## <none>          41938 274.24
## - Age     1   2896.6 44835 274.78
## - Leg    1   3324.2 45262 275.14
## - Ht     1   4238.3 46176 275.90
## + Thigh   1   372.7 41565 275.90
## + Arm    1   257.1 41681 276.01
## + Seated  1   121.3 41817 276.13
## + Weight  1    46.8 41891 276.20
## + HtShoes 1    13.4 41925 276.23

```

We could again instead use BIC as our metric.

```

hipcenter_mod_both_bic = step(
  hipcenter_mod_start,
  scope = hipcenter ~ Age + Weight + HtShoes + Ht + Seated + Arm + Thigh + Leg,

```

```

direction = "both", k = log(n))

## Start: AIC=313.35
## hipcenter ~ 1
##
##          Df Sum of Sq    RSS    AIC
## + Ht      1   84023  47616 278.34
## + HtShoes 1   83534  48105 278.73
## + Leg     1   81568  50071 280.25
## + Seated   1   70392  61247 287.91
## + Weight   1   53975  77664 296.93
## + Thigh    1   46010  85629 300.64
## + Arm     1   45065  86574 301.06
## <none>            131639 313.35
## + Age     1   5541  126098 315.35
##
## Step: AIC=278.34
## hipcenter ~ Ht
##
##          Df Sum of Sq    RSS    AIC
## <none>            47616 278.34
## + Leg     1   2781  44835 279.69
## + Age     1   2354  45262 280.05
## + Weight   1   196  47420 281.82
## + Seated   1   102  47514 281.90
## + Arm     1    76  47540 281.92
## + HtShoes  1    26  47590 281.96
## + Thigh    1     5  47611 281.98
## - Ht      1   84023 131639 313.35

```

Adjusted R^2 and LOOCV RMSE comparisons are similar to backwards and forwards, which is not at all surprising, as some of the models selected are the same as before.

```

summary(hipcenter_mod)$adj.r.squared

## [1] 0.6000855

summary(hipcenter_mod_both_aic)$adj.r.squared

## [1] 0.6533055

summary(hipcenter_mod_both_bic)$adj.r.squared

## [1] 0.6282374

calc_loocv_rmse(hipcenter_mod)

## [1] 44.44564

```

```
calc_loocv_rmse(hipcenter_mod_both_aic)
```

```
## [1] 37.62516
```

```
calc_loocv_rmse(hipcenter_mod_both_bic)
```

```
## [1] 37.2511
```

15.2.4 Exhaustive Search

Backward, forward, and stepwise search are all useful, but do have an obvious issue. By not checking every possible model, sometimes they will miss the best possible model. With an extremely large number of predictors, sometimes this is necessary since checking every possible model would be rather time consuming, even with current computers.

However, with a reasonably sized dataset, it isn't too difficult to check all possible models. To do so, we will use the `regsubsets()` function in the R package `leaps`.

```
library(leaps)
all_hipcenter_mod = summary(regsubsets(hipcenter ~ ., data = seatpos))
```

A few points about this line of code. First, note that we immediately use `summary()` and store those results. That is simply the intended use of `regsubsets()`. Second, inside of `regsubsets()` we specify the model `hipcenter ~ ..`. This will be the largest model considered, that is the model using all first-order predictors, and R will check all possible subsets.

We'll now look at the information stored in `all_hipcenter_mod`.

```
all_hipcenter_mod$which
```

```
##   (Intercept)    Age Weight HtShoes     Ht Seated    Arm Thigh    Leg
## 1      TRUE FALSE  FALSE  FALSE  TRUE  FALSE FALSE FALSE FALSE FALSE
## 2      TRUE FALSE  FALSE  FALSE  TRUE  FALSE FALSE FALSE FALSE  TRUE
## 3      TRUE  TRUE  FALSE  FALSE  TRUE  FALSE FALSE FALSE FALSE  TRUE
## 4      TRUE  TRUE  FALSE  TRUE FALSE FALSE FALSE  TRUE  TRUE  TRUE
## 5      TRUE  TRUE  FALSE  TRUE FALSE  TRUE  TRUE  TRUE  TRUE  TRUE
## 6      TRUE  TRUE  FALSE  TRUE FALSE  TRUE  TRUE  TRUE  TRUE  TRUE
## 7      TRUE  TRUE   TRUE  TRUE FALSE  TRUE  TRUE  TRUE  TRUE  TRUE
## 8      TRUE  TRUE   TRUE  TRUE  TRUE  TRUE  TRUE  TRUE  TRUE  TRUE
```

Using `$which` gives us the best model, according to RSS, for a model of each possible size, in this case ranging from one to eight predictors. For example the best model with four predictors ($p = 5$) would use Age, HtShoes, Thigh, and Leg.

```
all_hipcenter_mod$rss
```

```
## [1] 47615.79 44834.69 41938.09 41485.01 41313.00 41277.90 41266.80 41261.78
```

We can obtain the RSS for each of these models using `$rss`. Notice that these are decreasing since the models range from small to large.

Now that we have the RSS for each of these models, it is rather easy to obtain AIC, BIC, and Adjusted R^2 since they are all a function of RSS. Also, since we have the models with the best RSS for each size, they will result in the models with the best AIC, BIC, and Adjusted R^2 for each size. Then by picking from those, we can find the overall best AIC, BIC, and Adjusted R^2 .

Conveniently, Adjusted R^2 is automatically calculated.

```
all_hipcenter_mod$adjr2
```

```
## [1] 0.6282374 0.6399496 0.6533055 0.6466586 0.6371276 0.6257403 0.6133690
## [8] 0.6000855
```

To find which model has the highest Adjusted R^2 we can use the `which.max()` function.

```
(best_r2_ind = which.max(all_hipcenter_mod$adjr2))
```

```
## [1] 3
```

We can then extract the predictors of that model.

```
all_hipcenter_mod$which[best_r2_ind, ]
```

```
## (Intercept)      Age    Weight   HtShoes      Ht Seated
##     TRUE        TRUE    FALSE    FALSE      TRUE FALSE
##     Arm         Thigh     Leg
##     FALSE       FALSE    TRUE
```

We'll now calculate AIC and BIC for the each of the models with the best RSS. To do so, we will need both n and the p for the largest possible model.

```
p = length(coef(hipcenter_mod))
n = length(resid(hipcenter_mod))
```

We'll use the form of AIC which leaves out the constant term that is equal across all models.

$$\text{AIC} = n \log \left(\frac{\text{RSS}}{n} \right) + 2p.$$

Since we have the RSS of each model stored, this is easy to calculate.

```
hipcenter_mod_aic = n * log(all_hipcenter_mod$rss / n) + 2 * (2:p)
```

We can then extract the predictors of the model with the best AIC.

```
best_aic_ind = which.min(hipcenter_mod_aic)
all_hipcenter_mod$which[best_aic_ind, ]
```

```
## (Intercept)      Age     Weight    HtShoes      Ht     Seated
##   TRUE        TRUE    FALSE    FALSE    TRUE    FALSE
##   Arm        Thigh      Leg
##   FALSE       FALSE     TRUE
```

Let's fit this model so we can compare to our previously chosen models using AIC and search procedures.

```
hipcenter_mod_best_aic = lm(hipcenter ~ Age + Ht + Leg, data = seatpos)
```

The `extractAIC()` function will calculate the AIC defined above for a fitted model.

```
extractAIC(hipcenter_mod_best_aic)
```

```
## [1] 4.0000 274.2418
```

```
extractAIC(hipcenter_mod_back_aic)
```

```
## [1] 4.0000 274.2597
```

```
extractAIC(hipcenter_mod_forw_aic)
```

```
## [1] 4.0000 274.2418
```

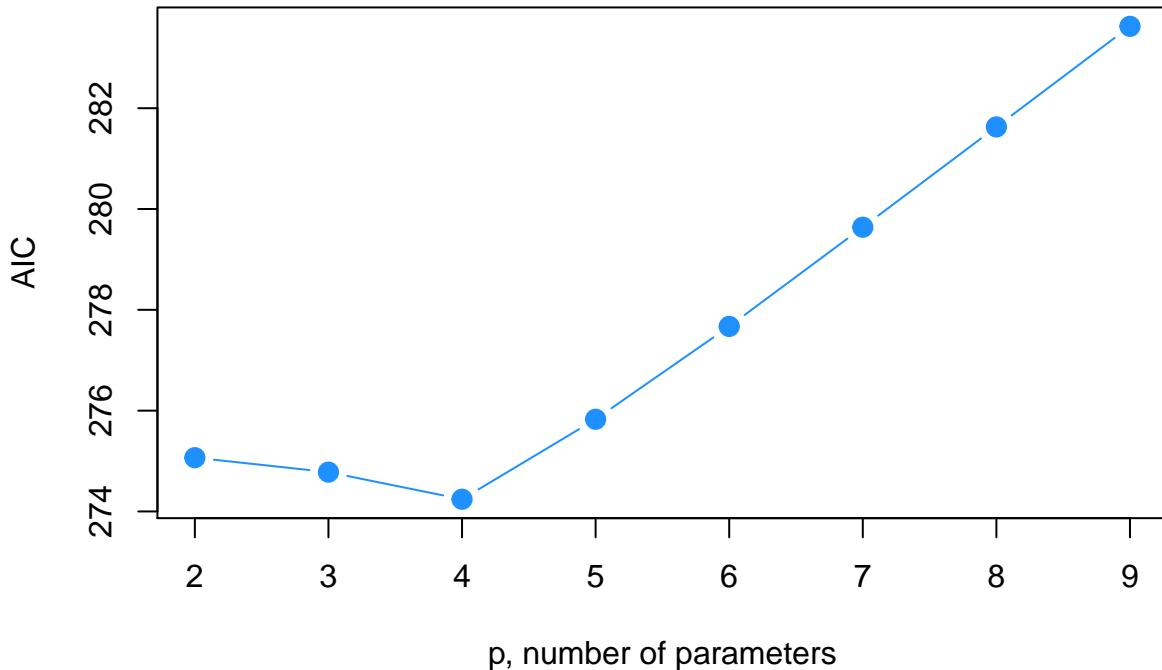
```
extractAIC(hipcenter_mod_both_aic)
```

```
## [1] 4.0000 274.2418
```

We see that two of the models chosen by search procedures have the best possible AIC, as they are the same model. This is however never guaranteed. We see that the model chosen using backwards selection does not achieve the smallest possible AIC.

```
plot(hipcenter_mod_aic ~ I(2:p), ylab = "AIC", xlab = "p, number of parameters",
      pch = 20, col = "dodgerblue", type = "b", cex = 2,
      main = "AIC vs Model Complexity")
```

AIC vs Model Complexity



We could easily repeat this process for BIC.

$$\text{BIC} = n \log \left(\frac{\text{RSS}}{n} \right) + \log(n)p.$$

```
hipcenter_mod_bic = n * log(all_hipcenter_mod$rss / n) + log(n) * (2:p)
```

```
which.min(hipcenter_mod_bic)
```

```
## [1] 1
```

```
all_hipcenter_mod$which[1,]
```

```
## (Intercept)      Age     Weight    HtShoes      Ht     Seated
##      TRUE    FALSE    FALSE    FALSE    TRUE    FALSE
##      Arm     Thigh      Leg
##      FALSE   FALSE    FALSE
```

```
hipcenter_mod_best_bic = lm(hipcenter ~ Ht, data = seatpos)
```

```
extractAIC(hipcenter_mod_best_bic, k = log(n))
```

```
## [1] 2.0000 278.3418
```

```
extractAIC(hipcenter_mod_back_bic, k = log(n))
```

```
## [1] 2.0000 278.7306
```

```
extractAIC(hipcenter_mod_forw_bic, k = log(n))
```

```
## [1] 2.0000 278.3418
```

```
extractAIC(hipcenter_mod_both_bic, k = log(n))
```

```
## [1] 2.0000 278.3418
```

15.3 Higher Order Terms

So far we have only allowed first-order terms in our models. Let's return to the `autompg` dataset to explore higher-order terms.

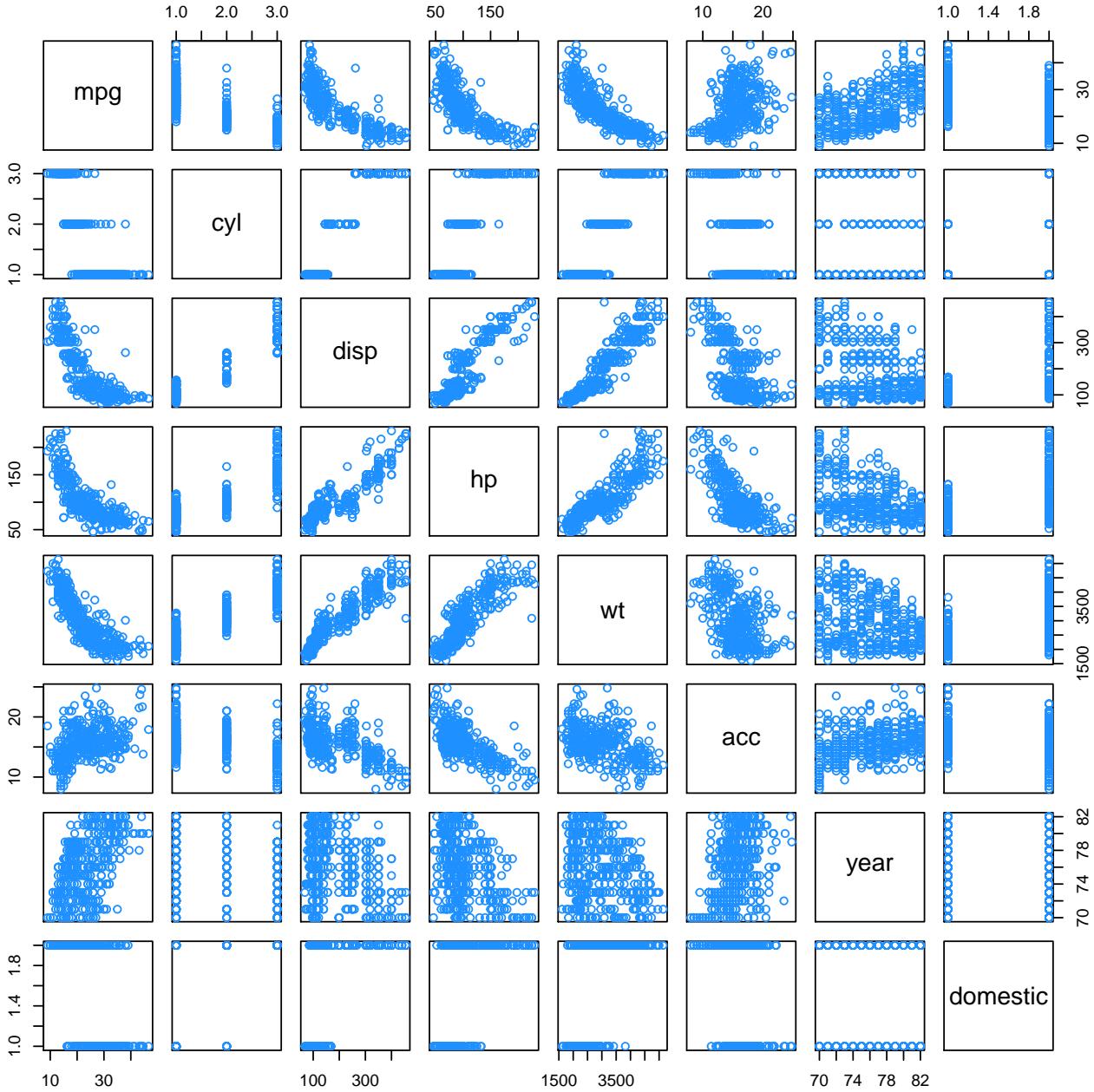
```
autompg = read.table(
  "http://archive.ics.uci.edu/ml/machine-learning-databases/auto-mpg/auto-mpg.data",
  quote = "\"",
  comment.char = "",
  stringsAsFactors = FALSE)
colnames(autompg) = c("mpg", "cyl", "disp", "hp", "wt", "acc",
                      "year", "origin", "name")
autompg = subset(autompg, autompg$hp != "?")
autompg = subset(autompg, autompg$name != "plymouth reliant")
rownames(autompg) = paste(autompg$cyl, "cylinder", autompg$year, autompg$name)
autompg$hp = as.numeric(autompg$hp)
autompg$domestic = as.numeric(autompg$origin == 1)
autompg = autompg[autompg$cyl != 5,]
autompg = autompg[autompg$cyl != 3,]
autompg$cyl = as.factor(autompg$cyl)
autompg$domestic = as.factor(autompg$domestic)
autompg = subset(autompg, select = c("mpg", "cyl", "disp", "hp",
                                     "wt", "acc", "year", "domestic"))
```

```
str(autompg)
```

```
## 'data.frame': 383 obs. of 8 variables:
## $ mpg      : num 18 15 18 16 17 15 14 14 14 15 ...
## $ cyl      : Factor w/ 3 levels "4","6","8": 3 3 3 3 3 3 3 3 3 3 ...
## $ disp     : num 307 350 318 304 302 429 454 440 455 390 ...
## $ hp       : num 130 165 150 150 140 198 220 215 225 190 ...
## $ wt       : num 3504 3693 3436 3433 3449 ...
## $ acc      : num 12 11.5 11 12 10.5 10 9 8.5 10 8.5 ...
## $ year     : int 70 70 70 70 70 70 70 70 70 70 ...
## $ domestic: Factor w/ 2 levels "0","1": 2 2 2 2 2 2 2 2 2 2 ...
```

Recall that we have two factor variables, `cyl` and `domestic`. The `cyl` variable has three levels, while the `domestic` variable has only two. Thus the `cyl` variable will be coded using two dummy variables, while the `domestic` variable will only need one. We will pay attention to this later.

```
pairs(automp, col = "dodgerblue")
```



We'll use the `pairs()` plot to determine which variables may benefit from a quadratic relationship with the response. We'll also consider all possible two-way interactions. We won't consider any three-order or higher. For example, we won't consider the interaction between first-order terms and the added quadratic terms.

So now, we'll fit this rather large model. We'll use a log-transformed response. Notice that `log(mpg) ~ . ^ 2` will automatically consider all first-order terms, as well as all two-way interactions. We use `I(var_name) ^ 2` to add quadratic terms for some variables. This generally works better than using `poly()` when performing variable selection.

```
autompq_big_mod = lm(
  log(mpg) ~ . ^ 2 + I(disp ^ 2) + I(hp ^ 2) + I(wt ^ 2) + I(acc ^ 2),
  data = autompq)
```

We think it is rather unlikely that we truly need all of these terms. There are quite a few!

```
length(coef(autompq_big_mod))

## [1] 40
```

We'll try backwards search with both AIC and BIC to attempt to find a smaller, more reasonable model.

```
autompq_mod_back_aic = step(autompq_big_mod, direction = "backward", trace = 0)
```

Notice that we used `trace = 0` in the function call. This suppresses the output for each step, and simply stores the chosen model. This is useful, as this code would otherwise create a large amount of output. If we had viewed the output, which you can try on your own by removing `trace = 0`, we would see that R only considers the `cyl` variable as a single variable, despite the fact that it is coded using two dummy variables. So removing `cyl` would actually remove two parameters from the resulting model.

You should also notice that R respects hierarchy when attempting to remove variables. That is, for example, R will not consider removing `hp` if `hp:disp` or `I(hp ^ 2)` are currently in the model.

We also use BIC.

```
n = length(resid(autompq_big_mod))
autompq_mod_back_bic = step(autompq_big_mod, direction = "backward",
                            k = log(n), trace = 0)
```

Looking at the coefficients of the two chosen models, we see they are still rather large.

```
coef(autompq_mod_back_aic)

##      (Intercept)          cyl6          cyl8          disp
## 3.6718839511472 -0.1602563336333 -0.8581644338393 -0.0093719707873
##           hp           wt           acc           year
## 0.0229353409493 -0.0003064496949 -0.1393888479750 -0.0019663606344
##   domestic1       I(hp^2)      cyl6:acc      cyl8:acc
## 0.9369323953411 -0.0000149766900  0.0072202979695  0.0504191492217
##    disp:wt        disp:year        hp:acc        hp:year
## 0.0000005797816  0.0000949376953 -0.0005062294609 -0.0001838985017
##    acc:year      acc:domestic1  year:domestic1
## 0.0023456252781 -0.0237246840975 -0.0073327246317
```

```
coef(autompq_mod_back_bic)

##      (Intercept)          cyl6          cyl8          disp
## 4.6578470390516 -0.1086165018406 -0.7611630775038 -0.0016093164199
##           hp           wt           acc           year
## 0.0026212660296 -0.0002635971659 -0.1670601021732 -0.0104564626969
##   domestic1       cyl6:acc      cyl8:acc        disp:wt
## 0.3341578960873  0.0043154925327  0.0461009496981  0.0000004102804
##    hp:acc        acc:year      acc:domestic1
## -0.0003386261424  0.0025001372156 -0.0219329407492
```

However, they are much smaller than the original full model. Also notice that the resulting models respect hierarchy.

```
length(coef(autompq_big_mod))

## [1] 40

length(coef(autompq_mod_back_aic))

## [1] 19

length(coef(autompq_mod_back_bic))

## [1] 15
```

Calculating the LOOCV RMSE for each, we see that the model chosen using BIC performs the best. That means that it is both the best model for prediction, since it achieves the best LOOCV RMSE, but also the best model for explanation, as it is also the smallest.

```
calc_loocv_rmse(autompq_big_mod)

## [1] 0.1112024

calc_loocv_rmse(autompq_mod_back_aic)

## [1] 0.1032888

calc_loocv_rmse(autompq_mod_back_bic)

## [1] 0.103134
```

15.4 Explanation versus Prediction

Throughout this chapter, we have attempted to find reasonably “small” models, which are good at **explaining** the relationship between the response and the predictors, that also have small errors which are thus good for making **predictions**.

We’ll further discuss the model `autompq_mod_back_bic` to better explain the difference between using models for *explaining* and *predicting*. This is the model fit to the `autompq` data that was chosen using Backwards Search and BIC, which obtained the lowest LOOCV RMSE of the models we considered.

```
autompq_mod_back_bic

## 
## Call:
## lm(formula = log(mpg) ~ cyl + disp + hp + wt + acc + year + domestic +
##     cyl:acc + disp:wt + hp:acc + acc:year + acc:domestic, data = autompq)
## 
```

```

## Coefficients:
## (Intercept) cyl6 cyl8 disp hp
## 4.6578470391 -0.1086165018 -0.7611630775 -0.0016093164 0.0026212660
## wt acc year domestic1 cyl6:acc
## -0.0002635972 -0.1670601022 -0.0104564627 0.3341578961 0.0043154925
## cyl8:acc disp:wt hp:acc acc:year acc:domestic1
## 0.0461009497 0.0000004103 -0.0003386261 0.0025001372 -0.0219329407

```

Notice this is a somewhat “large” model, which uses 15 parameters, including several interaction terms. Do we care that this is a “large” model? The answer is, **it depends**.

15.4.1 Explanation

Suppose we would like to use this model for explanation. Perhaps we are a car manufacturer trying to engineer a fuel efficient vehicle. If this is the case, we are interested in both what predictor variables are useful for explaining the car’s fuel efficiency, as well as how those variables effect fuel efficiency. By understanding this relationship, we can use this knowledge to our advantage when designing a car.

To explain a relationship, we are interested in keeping models as small as possible, since smaller models are easy to interpret. The fewer predictors the less considerations we need to make in our design process. Also the fewer interactions and polynomial terms, the easier it is to interpret any one parameter, since the parameter interpretations are conditional on which parameters are in the model.

Note that *linear* models are rather interpretable to begin with. Later in your data analysis careers, you will see more complicated models that may fit data better, but are much harder, if not impossible to interpret. These models aren’t very useful for explaining a relationship.

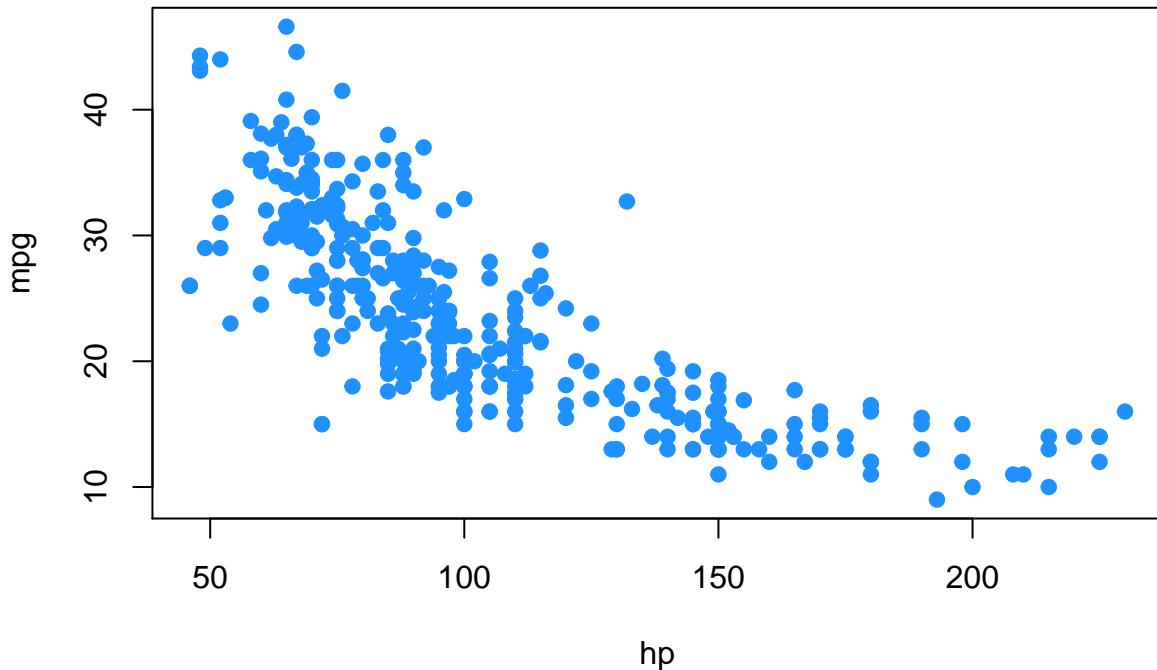
To find small and interpretable models, we would use selection criterion that *explicitly* penalize larger models, such as AIC and BIC. In this case we still obtained a somewhat large model, but much smaller than the model we used to start the selection process.

15.4.1.1 Correlation and Causation

A word of caution when using a model to *explain* a relationship. There are two terms often used to describe a relationship between two variables: *causation* and *correlation*. Correlation is often also referred to as association.

Just because two variable are correlated does not necessarily mean that one causes the other. For example, considering modeling mpg as only a function of hp.

```
plot(mpg ~ hp, data = autompg, col = "dodgerblue", pch = 20, cex = 1.5)
```



Does an increase in horsepower cause a drop in fuel efficiency? Or, perhaps the causality is reversed and an increase in fuel efficiency cause a decrease in horsepower. Or, perhaps there is a third variable that explains both!

The issue here is that we have **observational** data. With observational data, we can only detect associations. To speak with confidence about causality, we would need to run **experiments**.

This is a concept that you should encounter often in your statistics education. For some further reading, and some related fallacies, see: Wikipedia: Correlation does not imply causation.

15.4.2 Prediction

Suppose now instead of the manufacturer who would like to build a car, we are a consumer who wishes to purchase a new car. However this particular car is so new, it has not been rigorously tested, so we are unsure of what fuel efficiency to expect. (And, as skeptics, we don't trust what the manufacturer is telling us.)

In this case, we would like to use the model to help *predict* the fuel efficiency of this car based on its attributes, which are the predictors of the model. The smaller the errors the model makes, the more confident we are in its prediction. Thus, to find models for prediction, we would use selection criterion that *implicitly* penalize larger models, such as LOOCV RMSE. So long as the model does not over-fit, we do not actually care how large the model becomes. Explaining the relationship between the variables is not our goal here, we simply want to know what kind of fuel efficiency we should expect!

If we **only** care about prediction, we don't need to worry about correlation vs causation, and we don't need to worry about model assumptions.

If a variable is correlated with the response, it doesn't actually matter if it causes an effect on the response, it can still be useful for prediction. For example, in elementary school aged children their shoe size certainly doesn't *cause* them to read at a higher level, however we could very easily use shoe size to make a prediction about a child's reading ability. The larger their shoe size, the better they read. There's a lurking variable here though, their age! (Don't send your kids to school with size 14 shoes, it won't make them read better!)

We also don't care about model assumptions. Least squares is least squares. For a specified model, it will find the values of the parameters which will minimize the squared error loss. Your results might be largely uninterpretable and useless for inference, but for prediction none of that matters.

Chapter 16

Beyond

“End? No, the journey doesn’t end here.”

— J.R.R. Tolkien

After reading this chapter you will be able to:

- Understand the roadmap to continued education about models and the R programming language.

16.1 What’s Next

So you’ve completed STAT 420, where do you go from here? Now that you understand the basics of linear modeling, there is a wide world of applied statistics waiting to be explored. We’ll briefly detail some resources and discuss how they relate to what you have learned in STAT 420.

16.2 RStudio

RStudio has recently released version 1.0! This is exciting for a number of reasons, especially the release of R Notebooks. R Notebooks combine the RMarkdown you have already learned with the ability to work interactively.

16.3 Tidy Data

In this textbook, much of the data we have seen has been nice and tidy. It was rectangular where each row is an observation and each column is a variable. This is not always the case! Many packages have been developed to deal with data, and force it into a nice format, which is called tidy data, that we can then use for modeling. Often during analysis, this is where a large portion of your time will be spent.

The R community has started to call this collection of packages the Tidyverse. It was once called the Hadleyverse, as Hadley Wickham has authored so many of the packages. Hadley is writing a book called R for Data Science which describes the use of many of these packages. (And also how to use some to make the modeling process better!) This book is a great starting point for diving deeper into the R community. The two main packages are `dplyr` and `tidyverse` both of which are used internally in RStudio.

16.4 Visualization

In this course, we have mostly used the base plotting methods in R. When working with tidy data, many users prefer to use the `ggplot2` package, also developed by Hadley Wickham. RStudio provides a rather detailed “cheat sheet” for working with `ggplot2`. The community maintains a graph gallery of examples.

Use of the `manipulate` package with RStudio gives the ability to quickly change a static graphic to become interactive.

16.5 Web Applications

RStudio has made it incredible easy to create data products through the use of Shiny, which allows for the creation of web applications with R. RStudio maintains an ever-growing tutorial and gallery of examples.

16.6 Experimental Design

In the ANOVA chapter, we briefly discussed experimental design. This topic could easily be its own class, and is currently an area of revitalized interest with the rise of A/B testing. Two more classic statistical references include *Statistics for Experimenters* by Box, Hunter, and Hunter as well as *Design and Analysis of Experiments* by Douglas Montgomery. There are several R packages for design of experiments, list in the CRAN Task View.

16.7 Machine Learning

Using models for prediction is the key focus of machine learning. There are many methods, each with its own package, however R has a wonderful package called `caret`, *Classification And REgression Training*, which provides a unified interface to training these models. It also contains various utilities for data processing and visualization that are useful for predictive modeling.

Applied Predictive Modeling by Max Kuhn, the author of the `caret` package is a good general resource for predictive modeling, which obviously utilizes R. *An Introduction to Statistical Learning* by James, Witten, Hastie, and Tibshirani is a gentle introduction to machine learning from a statistical perspective which uses R and picks up right where this courses stops. This is based on the often referenced *The Elements of Statistical Learning* by Hastie, Tibshirani, and Friedman. Both are freely available online.

16.7.1 Deep Learning

While, it probably isn’t the best tool for the job, R now has the ability to train deep neural networks via TensorFlow.

16.8 Time Series

In this class we have only considered independent data. What if data is dependent? Time Series is the area of statistics which deals with this issue, and could easily span multiple courses.

Two books that are used in STAT 429 at the University of Illinois, both free:

- *Time Series Analysis and Its Applications: With R Examples* by Shumway and Stoffer

- A Tour of Time Series Analysis with R by Balamuta, Guerrier, Molinari, and Xu. This book is currently under development at UIUC.

Some tutorials:

- Little Book of R for Time Series
- Quick R: Time Series and Forecasting
- TSA: Start to Finish Examples

When performing time series analysis in R you should be aware of the many packages that are useful for analysis. It should be hard to avoid the `forecast` and `zoo` packages. Often the most difficult part will be dealing with time and date data. Make sure you are utilizing one of the many packages that help with this.

16.9 Bayesianism

In this class, we have worked within the frequentist view of statistics. There is an entire alternative universe of Bayesian statistics.

Doing Bayesian Data Analysis: A Tutorial with R, JAGS, and Stan by John Kruschke is a great introduction to the topic. It introduces the world of probabilistic programming, in particular Stan, which can be used in both R and Python.

16.10 High Performance Computing

Often R will be called a “slow” language, for two reasons. One, because many do not understand R. Two, because sometimes it really is. Luckily, it is easy to extend R via the `Rcpp` package to allow for faster code. Many modern R packages utilize `Rcpp` to achieve better performance.

16.11 Further R Resources

Also, don’t forget that previously in this book we have outlined a large number of R resources. Now that you’ve gotten started with R many of these will be much more useful.

If any of these topics interest you, and you would like more information, please don’t hesitate to start a discussion on the forums!

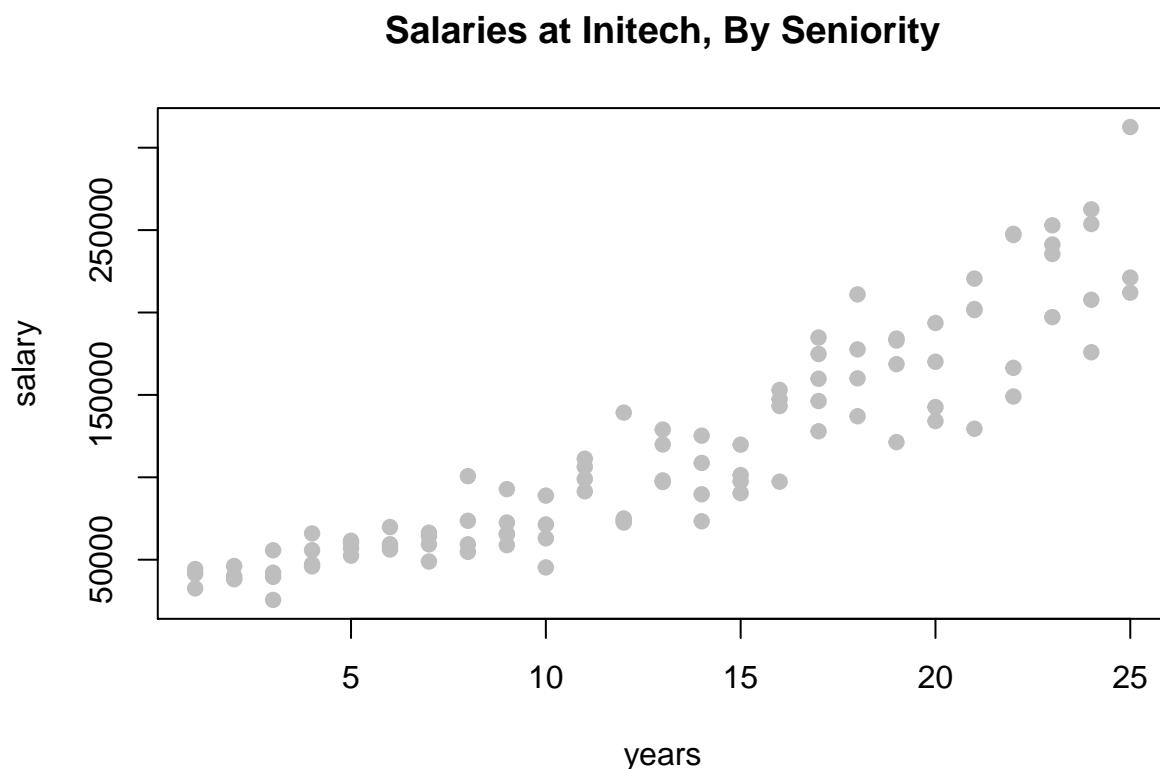
Chapter 17

Transformations Video

The following is code seen in videos for Week 8 for STAT 420 in the MCS-DS program. It will eventually be merged into the Transformations chapter of this book.

17.1 Response Transformations

```
initech = read.csv("data/initech.csv")  
  
plot(salary ~ years, data = initech, col = "grey", pch = 20, cex = 1.5,  
     main = "Salaries at Initech, By Seniority")
```

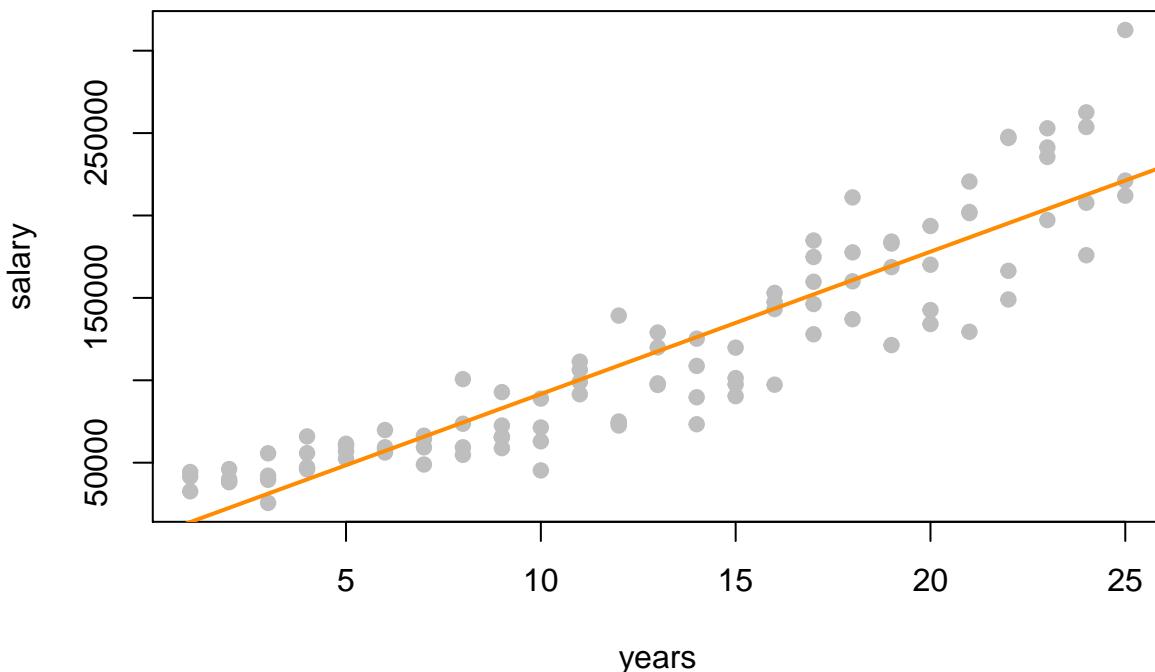


```
initech_fit = lm(salary ~ years, data = initech)
summary(initech_fit)
```

```
##
## Call:
## lm(formula = salary ~ years, data = initech)
##
## Residuals:
##    Min     1Q Median     3Q    Max
## -57225 -18104    241   15589  91332
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept)  5302       5750    0.922   0.359
## years        8637       389   22.200  <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 27360 on 98 degrees of freedom
## Multiple R-squared:  0.8341, Adjusted R-squared:  0.8324
## F-statistic: 492.8 on 1 and 98 DF,  p-value: < 2.2e-16
```

```
plot(salary ~ years, data = initech, col = "grey", pch = 20, cex = 1.5,
     main = "Salaries at Initech, By Seniority")
abline(initech_fit, col = "darkorange", lwd = 2)
```

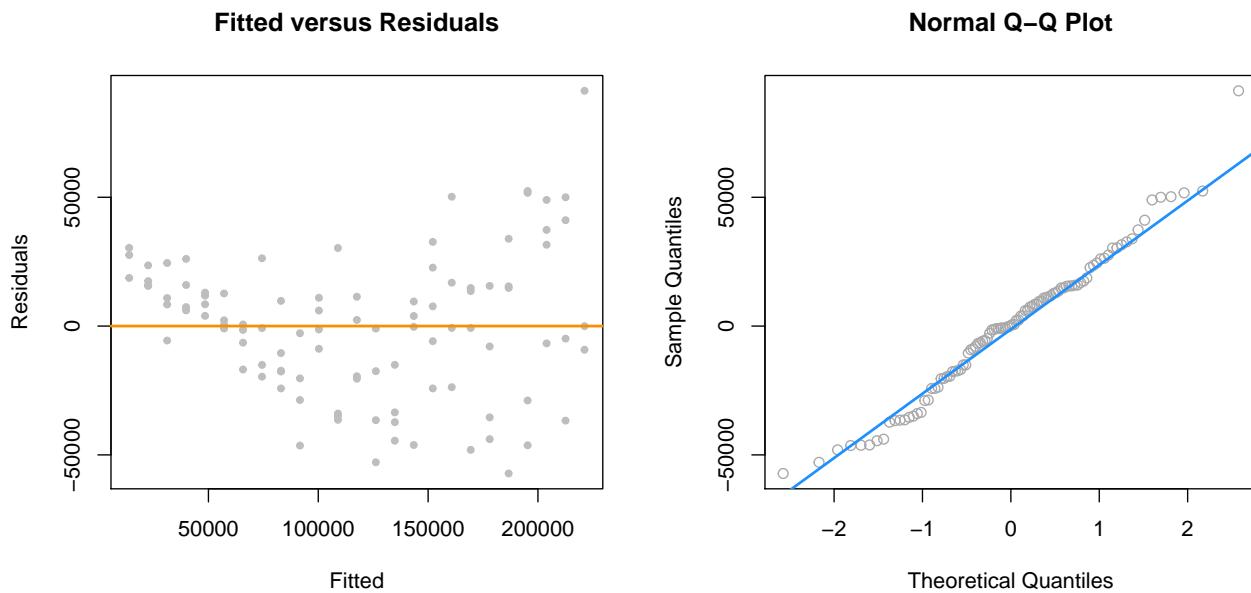
Salaries at Initech, By Seniority



```
par(mfrow = c(1, 2))

plot(fitted(initech_fit), resid(initech_fit), col = "grey", pch = 20,
      xlab = "Fitted", ylab = "Residuals", main = "Fitted versus Residuals")
abline(h = 0, col = "darkorange", lwd = 2)

qqnorm(resid(initech_fit), main = "Normal Q-Q Plot", col = "darkgrey")
qqline(resid(initech_fit), col = "dodgerblue", lwd = 2)
```

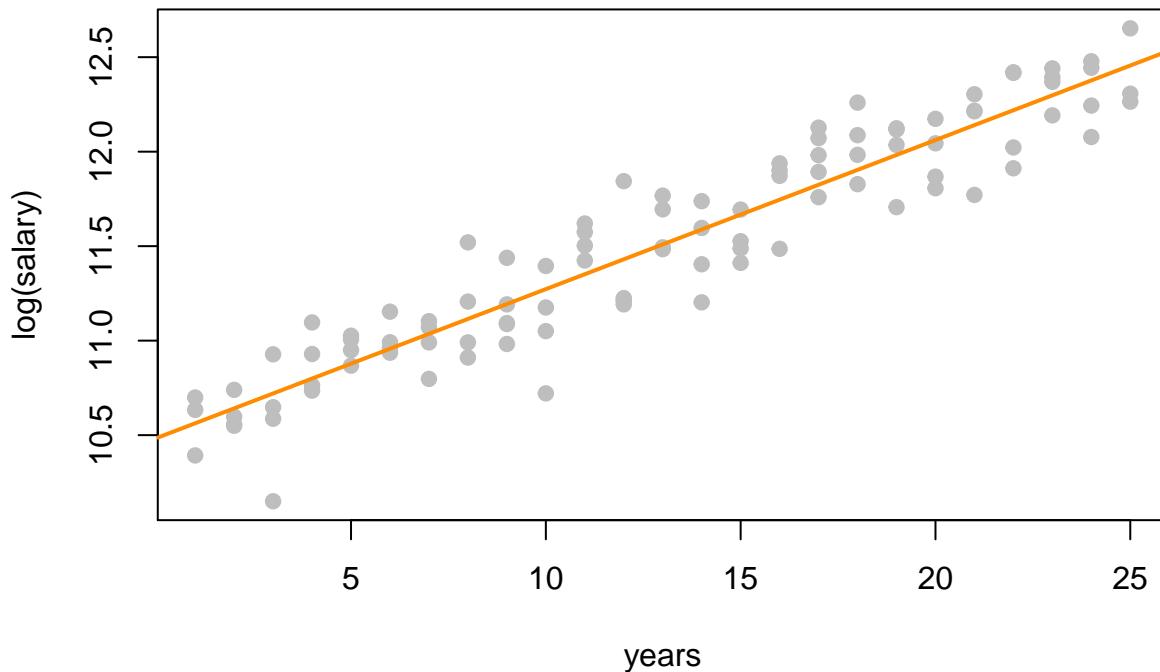


```
initech_fit_log = lm(log(salary) ~ years, data = initech)
```

$$\log(Y_i) = \beta_0 + \beta_1 x_i + \epsilon_i$$

```
plot(log(salary) ~ years, data = initech, col = "grey", pch = 20, cex = 1.5,
      main = "Salaries at Initech, By Seniority")
abline(initech_fit_log, col = "darkorange", lwd = 2)
```

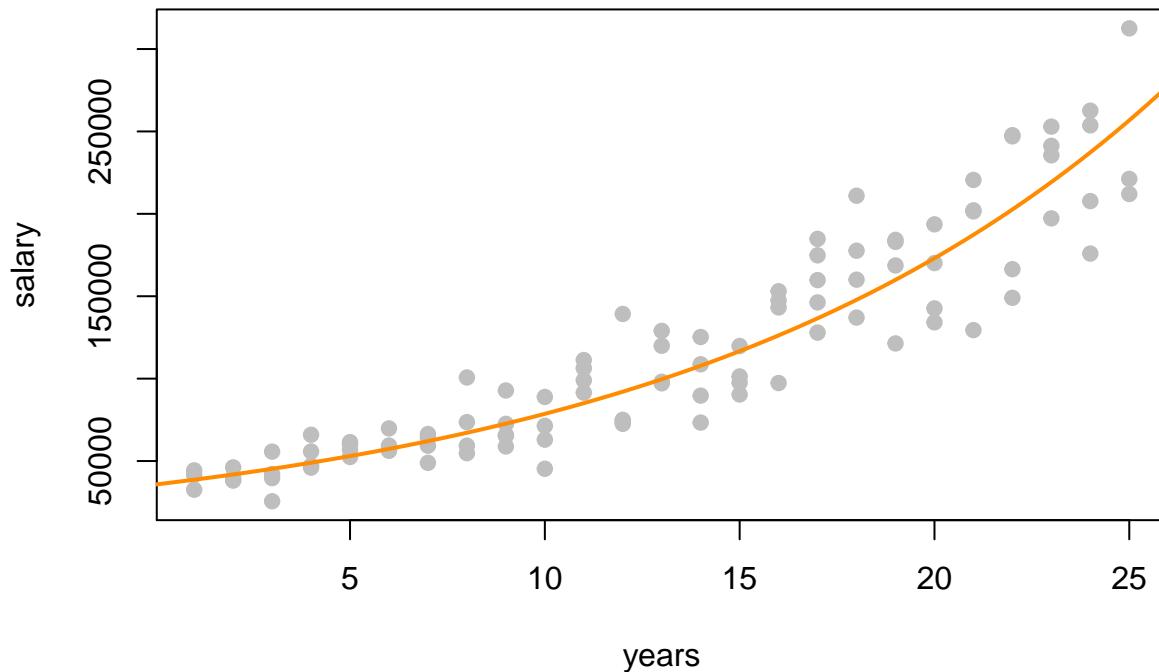
Salaries at Initech, By Seniority



$$Y_i = \exp(\beta_0 + \beta_1 x_i) \cdot \exp(\epsilon_i)$$

```
plot(salary ~ years, data = initech, col = "grey", pch = 20, cex = 1.5,
     main = "Salaries at Initech, By Seniority")
curve(exp(initech_fit_log$coef[1] + initech_fit_log$coef[2] * x),
      from = 0, to = 30, add = TRUE, col = "darkorange", lwd = 2)
```

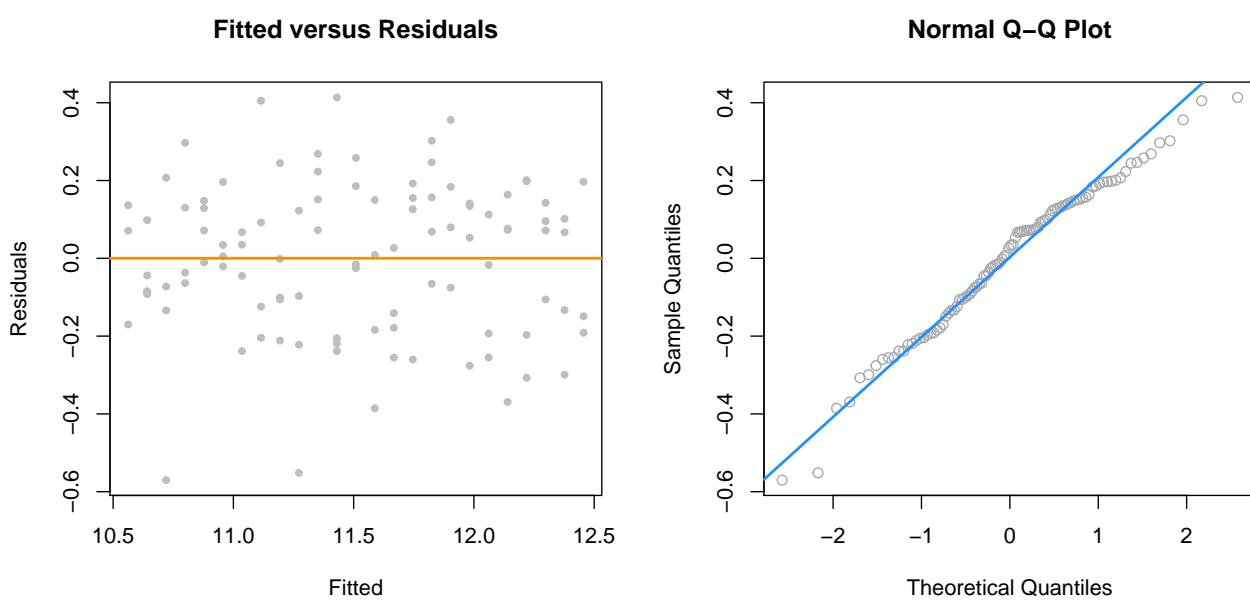
Salaries at Initech, By Seniority



```
par(mfrow = c(1, 2))

plot(fitted(initech_fit_log), resid(initech_fit_log), col = "grey", pch = 20,
      xlab = "Fitted", ylab = "Residuals", main = "Fitted versus Residuals")
abline(h = 0, col = "darkorange", lwd = 2)

qqnorm(resid(initech_fit_log), main = "Normal Q-Q Plot", col = "darkgrey")
qqline(resid(initech_fit_log), col = "dodgerblue", lwd = 2)
```



```

sqrt(mean(resid(initech_fit) ^ 2))

## [1] 27080.16

sqrt(mean(resid(initech_fit_log) ^ 2))

## [1] 0.1934907

sqrt(mean((initech$salary - fitted(initech_fit)) ^ 2))

## [1] 27080.16

sqrt(mean((initech$salary - exp(fitted(initech_fit_log)))) ^ 2))

## [1] 24280.36

```

17.2 Predictor Transformations

17.2.1 A Quadratic Model

```

sim_quad = function(sample_size = 500) {
  x = runif(n = sample_size) * 5
  y = 3 + 5 * x ^ 2 + rnorm(n = sample_size, mean = 0, sd = 5)
  data.frame(x, y)
}

set.seed(314)
quad_data = sim_quad(sample_size = 200)

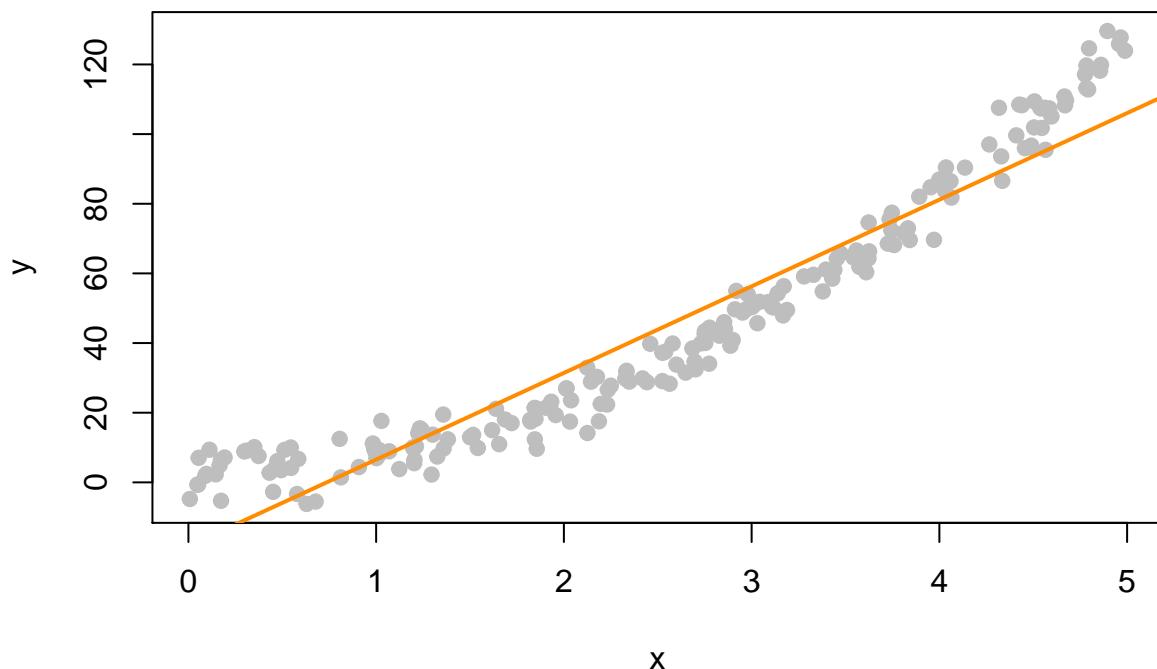
lin_fit = lm(y ~ x, data = quad_data)
summary(lin_fit)

##
## Call:
## lm(formula = y ~ x, data = quad_data)
##
## Residuals:
##      Min       1Q   Median       3Q      Max 
## -20.363  -7.550  -3.416   8.472  26.181 
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)    
## (Intercept) -18.3271    1.5494  -11.83   <2e-16 ***
## x            24.8716    0.5343   46.55   <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 10.79 on 198 degrees of freedom
## Multiple R-squared:  0.9163, Adjusted R-squared:  0.9158 
## F-statistic: 2167 on 1 and 198 DF,  p-value: < 2.2e-16

```

```
plot(y ~ x, data = quad_data, col = "grey", pch = 20, cex = 1.5,
      main = "Simulated Quadratic Data")
abline(lin_fit, col = "darkorange", lwd = 2)
```

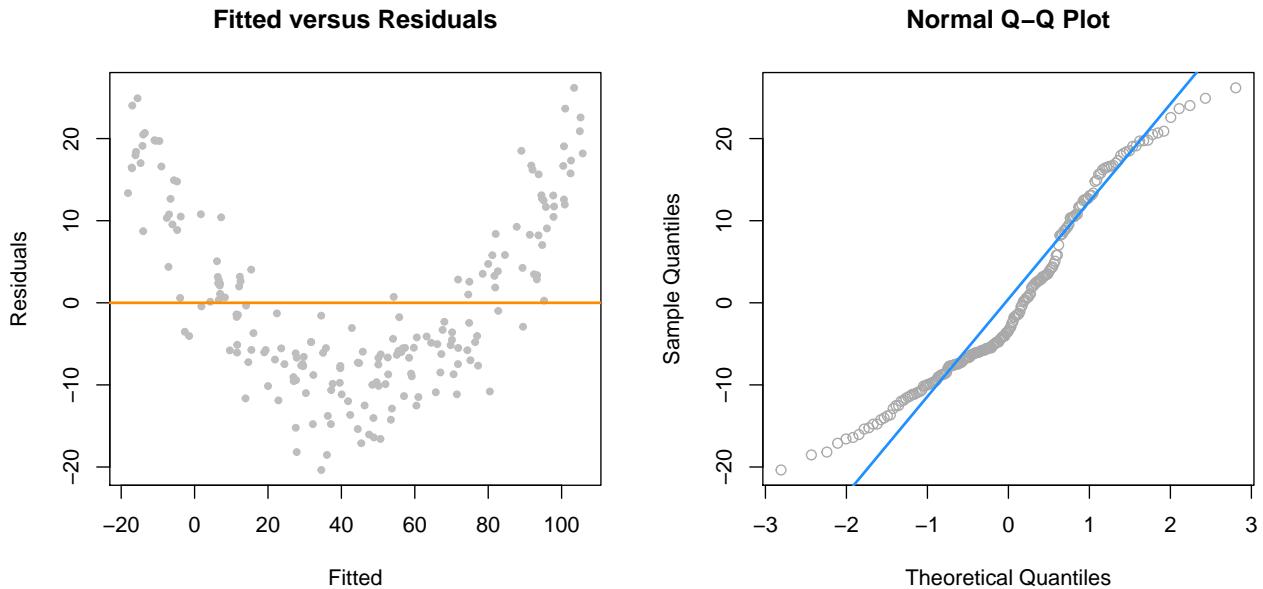
Simulated Quadratic Data



```
par(mfrow = c(1, 2))

plot(fitted(lin_fit), resid(lin_fit), col = "grey", pch = 20,
      xlab = "Fitted", ylab = "Residuals", main = "Fitted versus Residuals")
abline(h = 0, col = "darkorange", lwd = 2)

qqnorm(resid(lin_fit), main = "Normal Q-Q Plot", col = "darkgrey")
qqline(resid(lin_fit), col = "dodgerblue", lwd = 2)
```



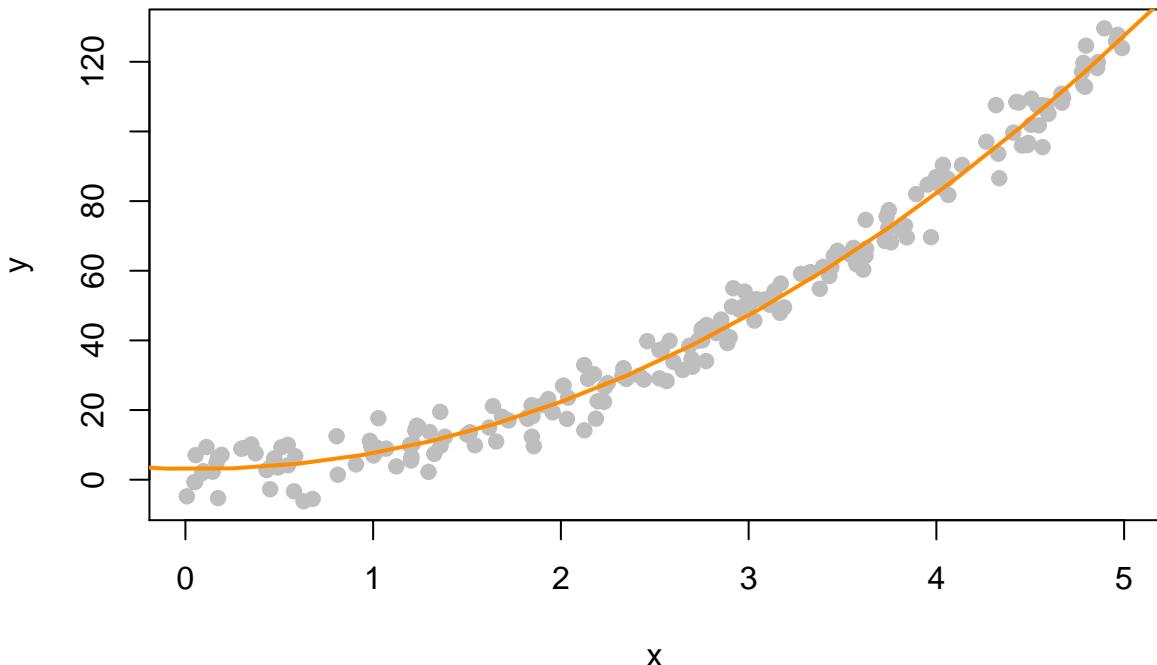
$$Y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \epsilon_i$$

```
quad_fit = lm(y ~ x + I(x^2), data = quad_data)
summary(quad_fit)
```

```
##
## Call:
## lm(formula = y ~ x + I(x^2), data = quad_data)
##
## Residuals:
##      Min       1Q   Median       3Q      Max 
## -11.4167  -3.0581   0.2297   3.1024  12.1256 
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)    
## (Intercept) 3.0649    0.9577   3.200   0.0016 ***
## x          -0.5108    0.8637  -0.591   0.5549    
## I(x^2)      5.0740    0.1667  30.433  <2e-16 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 4.531 on 197 degrees of freedom
## Multiple R-squared:  0.9853, Adjusted R-squared:  0.9852 
## F-statistic:  6608 on 2 and 197 DF,  p-value: < 2.2e-16
```

```
plot(y ~ x, data = quad_data, col = "grey", pch = 20, cex = 1.5,
     main = "Simulated Quadratic Data")
curve(quad_fit$coef[1] + quad_fit$coef[2] * x + quad_fit$coef[3] * x ^ 2,
      from = -5, to = 30, add = TRUE, col = "darkorange", lwd = 2)
```

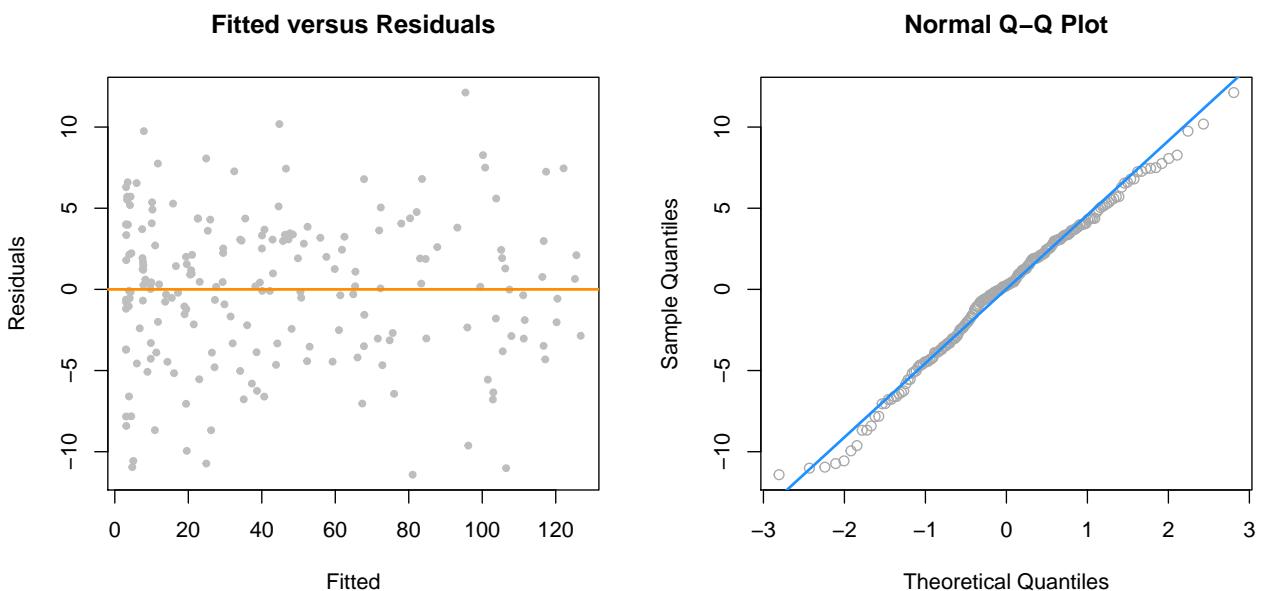
Simulated Quadratic Data



```
par(mfrow = c(1, 2))

plot(fitted(quad_fit), resid(quad_fit), col = "grey", pch = 20,
      xlab = "Fitted", ylab = "Residuals", main = "Fitted versus Residuals")
abline(h = 0, col = "darkorange", lwd = 2)

qqnorm(resid(quad_fit), main = "Normal Q-Q Plot", col = "darkgrey")
qqline(resid(quad_fit), col = "dodgerblue", lwd = 2)
```



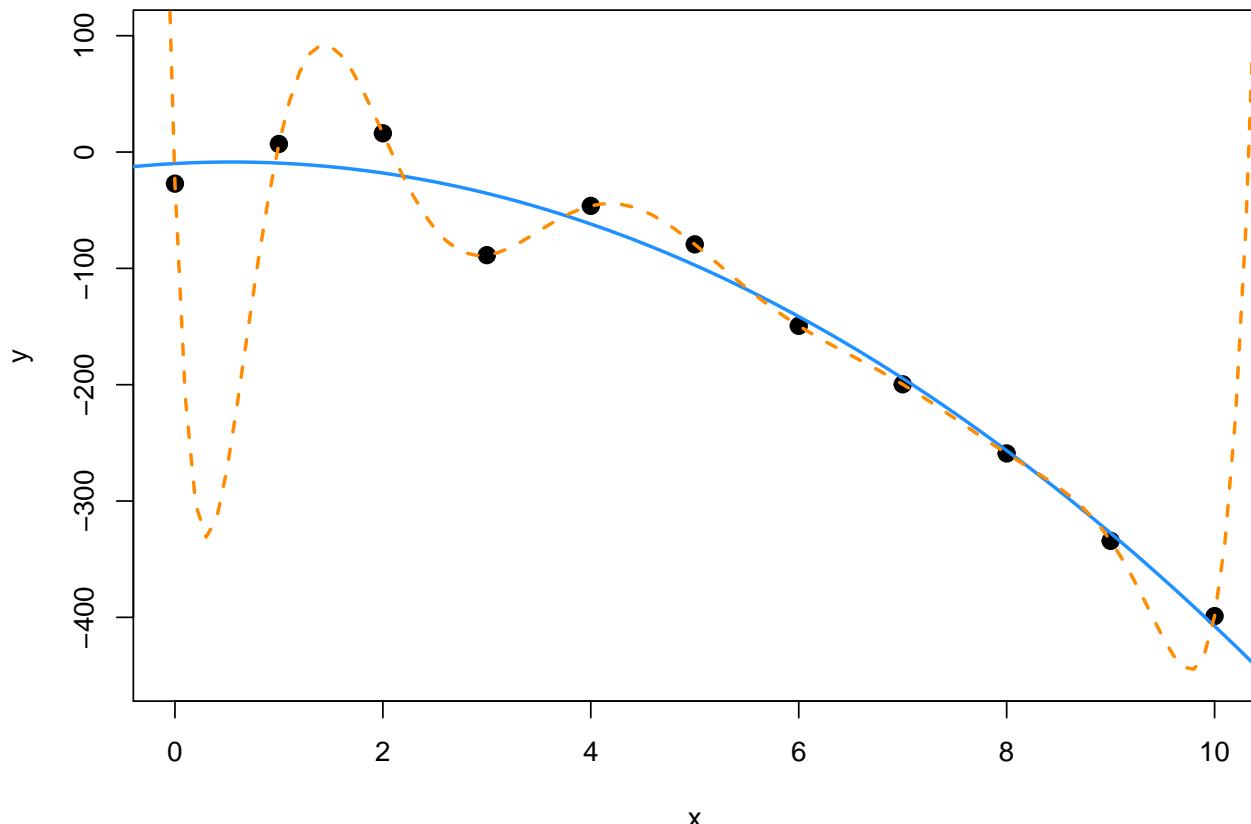
17.2.2 Overfitting and Extrapolation

```
sim_for_perf = function() {
  x = seq(0, 10)
  y = 3 + x - 4 * x ^ 2 + rnorm(n = 11, mean = 0, sd = 25)
  data.frame(x, y)
}
```

```
set.seed(1234)
data_for_perf = sim_for_perf()
```

```
fit_correct = lm(y ~ x + I(x ^ 2), data = data_for_perf)
fit_perfect = lm(y ~ x + I(x ^ 2) + I(x ^ 3) + I(x ^ 4) + I(x ^ 5) + I(x ^ 6) +
  I(x ^ 7) + I(x ^ 8) + I(x ^ 9) + I(x ^ 10),
  data = data_for_perf)
```

```
x_plot = seq(-5, 15, by = 0.1)
plot(y ~ x, data = data_for_perf, ylim = c(-450, 100), cex = 2, pch = 20)
lines(x_plot, predict(fit_correct, newdata = data.frame(x = x_plot)),
  col = "dodgerblue", lwd = 2, lty = 1)
lines(x_plot, predict(fit_perfect, newdata = data.frame(x = x_plot)),
  col = "darkorange", lwd = 2, lty = 2)
```



17.2.3 Comparing Polynomial Models

```
sim_higher = function(sample_size = 250) {
  x = runif(n = sample_size, min = -1, max = 1) * 2
  y = 3 + -6 * x ^ 2 + 1 * x ^ 4 + rnorm(n = sample_size, mean = 0, sd = 3)
  data.frame(x, y)
}
```

$$Y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \epsilon_i$$

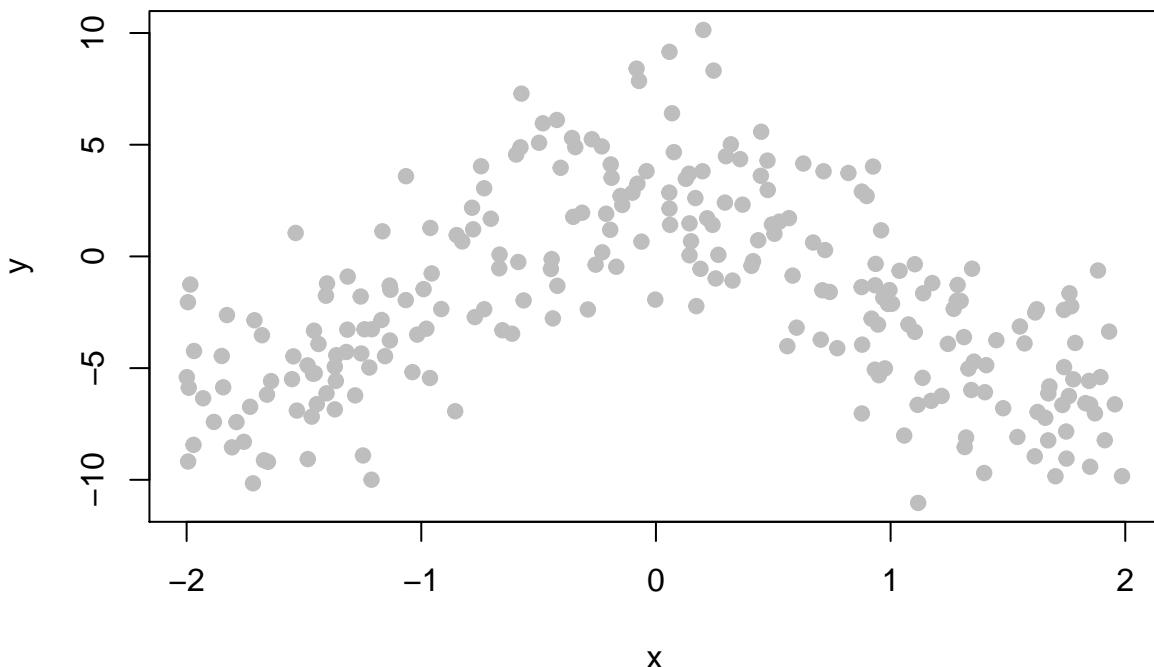
$$Y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \beta_3 x_i^3 + \beta_4 x_i^4 + \epsilon_i$$

$$Y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \beta_3 x_i^3 + \beta_4 x_i^4 + \beta_5 x_i^5 + \beta_6 x_i^6 + \epsilon_i$$

```
set.seed(42)
data_higher = sim_higher()
```

```
plot(y ~ x, data = data_higher, col = "grey", pch = 20, cex = 1.5,
     main = "Simulated Quartic Data")
```

Simulated Quartic Data



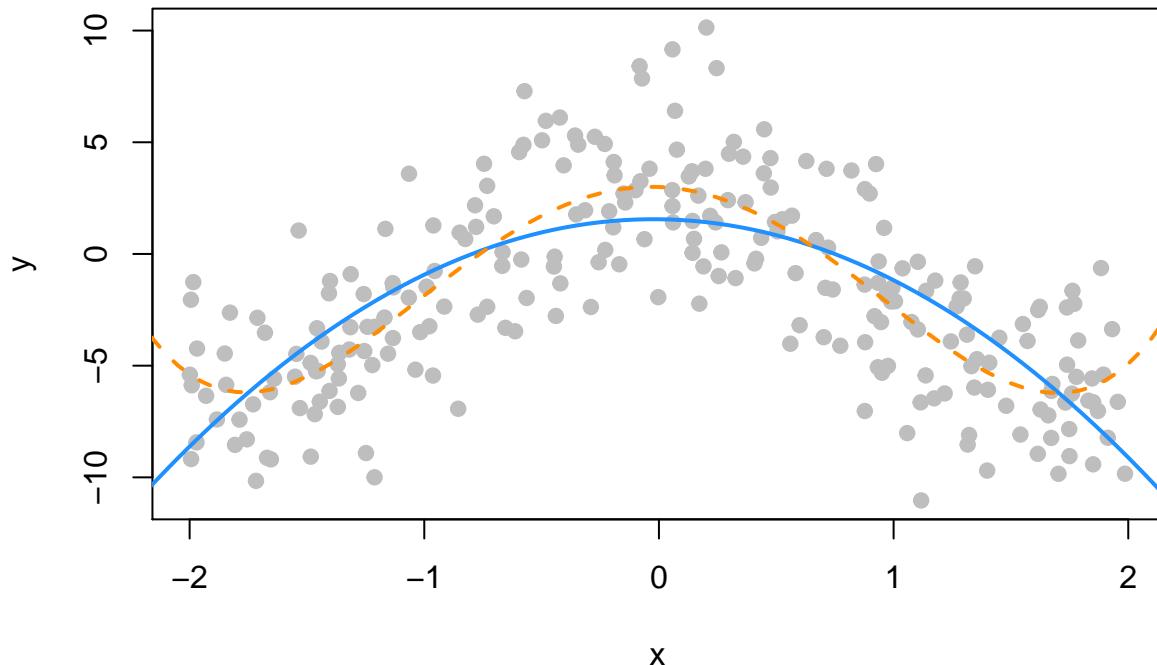
```
fit_2 = lm(y ~ poly(x, 2), data = data_higher)
fit_4 = lm(y ~ poly(x, 4), data = data_higher)
```

```

plot(y ~ x, data = data_higher, col = "grey", pch = 20, cex = 1.5,
      main = "Simulated Quartic Data")
x_plot = seq(-5, 5, by = 0.05)
lines(x_plot, predict(fit_2, newdata = data.frame(x = x_plot)),
      col = "dodgerblue", lwd = 2, lty = 1)
lines(x_plot, predict(fit_4, newdata = data.frame(x = x_plot)),
      col = "darkorange", lwd = 2, lty = 2)

```

Simulated Quartic Data



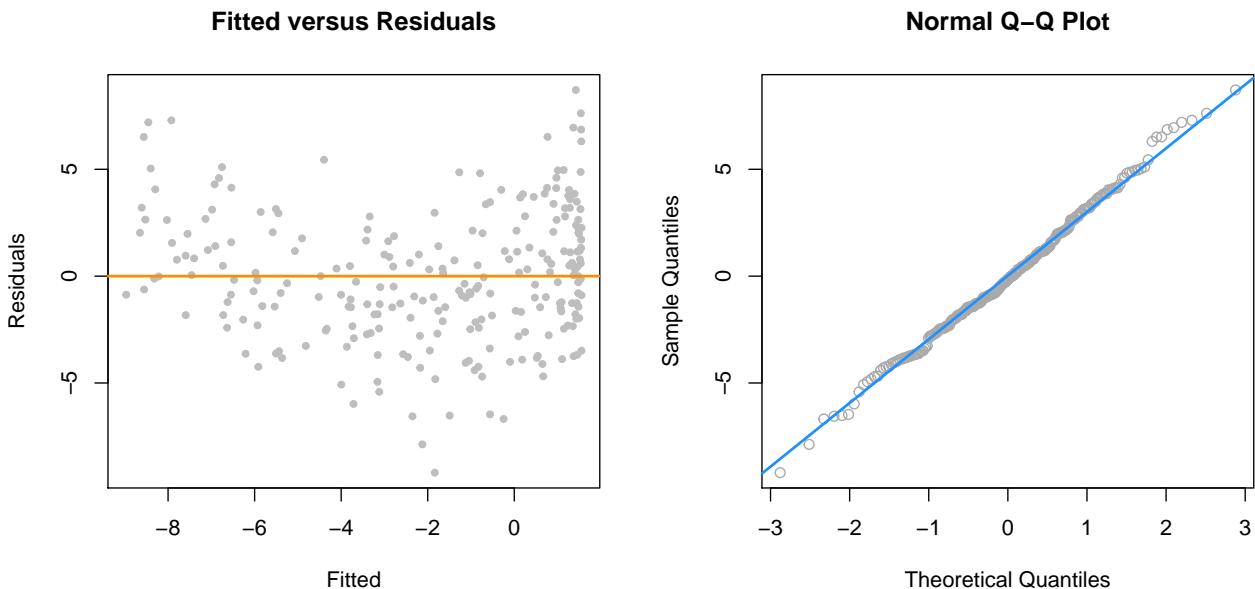
```

par(mfrow = c(1, 2))

plot(fitted(fit_2), resid(fit_2), col = "grey", pch = 20,
      xlab = "Fitted", ylab = "Residuals", main = "Fitted versus Residuals")
abline(h = 0, col = "darkorange", lwd = 2)

qqnorm(resid(fit_2), main = "Normal Q-Q Plot", col = "darkgrey")
qqline(resid(fit_2), col = "dodgerblue", lwd = 2)

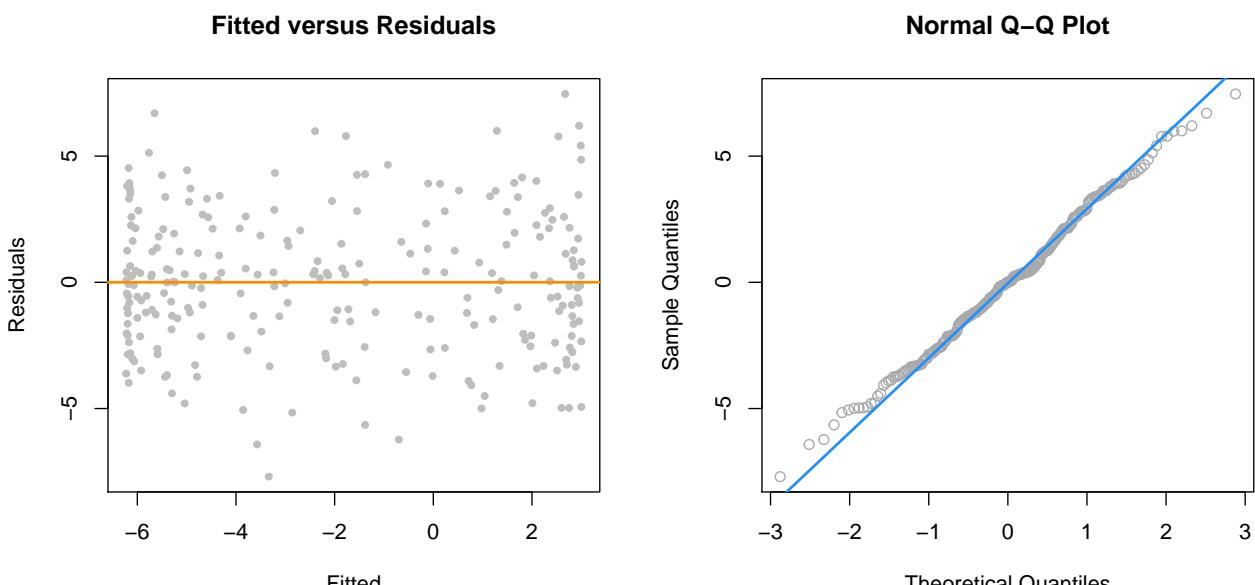
```



```
par(mfrow = c(1, 2))

plot(fitted(fit_4), resid(fit_4), col = "grey", pch = 20,
      xlab = "Fitted", ylab = "Residuals", main = "Fitted versus Residuals")
abline(h = 0, col = "darkorange", lwd = 2)

qqnorm(resid(fit_4), main = "Normal Q-Q Plot", col = "darkgrey")
qqline(resid(fit_4), col = "dodgerblue", lwd = 2)
```



```
anova(fit_2, fit_4)
```

```
## Analysis of Variance Table
##
## Model 1: y ~ poly(x, 2)
```

```

## Model 2: y ~ poly(x, 4)
##   Res.Df   RSS Df Sum of Sq    F    Pr(>F)
## 1     247 2334.1
## 2     245 1912.6  2      421.51 26.997 2.536e-11 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

fit_6 = lm(y ~ poly(x, 6), data = data_higher)

anova(fit_4, fit_6)

## Analysis of Variance Table
##
## Model 1: y ~ poly(x, 4)
## Model 2: y ~ poly(x, 6)
##   Res.Df   RSS Df Sum of Sq    F    Pr(>F)
## 1     245 1912.6
## 2     243 1904.4  2      8.1889 0.5224 0.5937

```

17.2.4 poly() Function and Orthogonal Polynomials

$$Y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \beta_3 x_i^3 + \beta_4 x_i^4 + \epsilon_i$$

```

fit_4a = lm(y ~ poly(x, degree = 4), data = data_higher)
fit_4b = lm(y ~ poly(x, degree = 4, raw = TRUE), data = data_higher)
fit_4c = lm(y ~ x + I(x^2) + I(x^3) + I(x^4), data = data_higher)

```

```
coef(fit_4a)
```

```

##             (Intercept) poly(x, degree = 4)1 poly(x, degree = 4)2
##             -1.980036          -2.053929          -49.344752
## poly(x, degree = 4)3 poly(x, degree = 4)4
##             0.669874          20.519759

```

```
coef(fit_4b)
```

```

##             (Intercept) poly(x, degree = 4, raw = TRUE)1
##             2.9996256          -0.3880250
## poly(x, degree = 4, raw = TRUE)2 poly(x, degree = 4, raw = TRUE)3
##             -6.1511166          0.1269046
## poly(x, degree = 4, raw = TRUE)4
##             1.0282139

```

```
coef(fit_4c)
```

```

## (Intercept)           x       I(x^2)       I(x^3)       I(x^4)
## 2.9996256 -0.3880250 -6.1511166  0.1269046  1.0282139

```

```
unnname(coef(fit_4a))

## [1] -1.980036 -2.053929 -49.344752  0.669874 20.519759

unnname(coef(fit_4b))

## [1] 2.9996256 -0.3880250 -6.1511166  0.1269046 1.0282139

unnname(coef(fit_4c))

## [1] 2.9996256 -0.3880250 -6.1511166  0.1269046 1.0282139

all.equal(fitted(fit_4a),
         fitted(fit_4b))

## [1] TRUE

all.equal(resid(fit_4a),
         resid(fit_4b))

## [1] TRUE

summary(fit_4a)

##
## Call:
## lm(formula = y ~ poly(x, degree = 4), data = data_higher)
##
## Residuals:
##     Min      1Q  Median      3Q     Max 
## -7.6982 -2.0334  0.0042  1.9532  7.4626 
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)    
## (Intercept) -1.9800    0.1767 -11.205 < 2e-16 ***
## poly(x, degree = 4)1 -2.0539    2.7940  -0.735   0.463  
## poly(x, degree = 4)2 -49.3448    2.7940 -17.661 < 2e-16 ***
## poly(x, degree = 4)3   0.6699    2.7940   0.240   0.811  
## poly(x, degree = 4)4  20.5198    2.7940   7.344 3.06e-12 ***
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 2.794 on 245 degrees of freedom
## Multiple R-squared:  0.5993, Adjusted R-squared:  0.5928 
## F-statistic: 91.61 on 4 and 245 DF,  p-value: < 2.2e-16

summary(fit_4c)
```

```

## 
## Call:
## lm(formula = y ~ x + I(x^2) + I(x^3) + I(x^4), data = data_higher)
## 
## Residuals:
##      Min      1Q  Median      3Q     Max 
## -7.6982 -2.0334  0.0042  1.9532  7.4626 
## 
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)    
## (Intercept)  2.9996    0.3315   9.048 < 2e-16 ***
## x           -0.3880    0.3828  -1.014   0.312    
## I(x^2)       -6.1511    0.5049 -12.183 < 2e-16 ***
## I(x^3)        0.1269    0.1456   0.871   0.384    
## I(x^4)        1.0282    0.1400   7.344 3.06e-12 ***
## --- 
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
## 
## Residual standard error: 2.794 on 245 degrees of freedom
## Multiple R-squared:  0.5993, Adjusted R-squared:  0.5928 
## F-statistic: 91.61 on 4 and 245 DF,  p-value: < 2.2e-16

```

17.2.5 Inhibit Function

```
coef(lm(y ~ x + x ^ 2, data = quad_data))
```

```

## (Intercept)          x
## -18.32715     24.87163

```

```
coef(lm(y ~ x + I(x ^ 2), data = quad_data))
```

```

## (Intercept)          x      I(x^2)
##  3.0649446  -0.5108131  5.0739805

```

```
coef(lm(y ~ x + x:x, data = quad_data))
```

```

## (Intercept)          x
## -18.32715     24.87163

```

```
coef(lm(y ~ x * x, data = quad_data))
```

```

## (Intercept)          x
## -18.32715     24.87163

```

```
coef(lm(y ~ x ^ 2, data = quad_data))
```

```

## (Intercept)          x
## -18.32715     24.87163

```

```
coef(lm(y ~ x + x ^ 2, data = quad_data))
```

```
## (Intercept)           x  
## -18.32715    24.87163
```

```
coef(lm(y ~ I(x + x), data = quad_data))
```

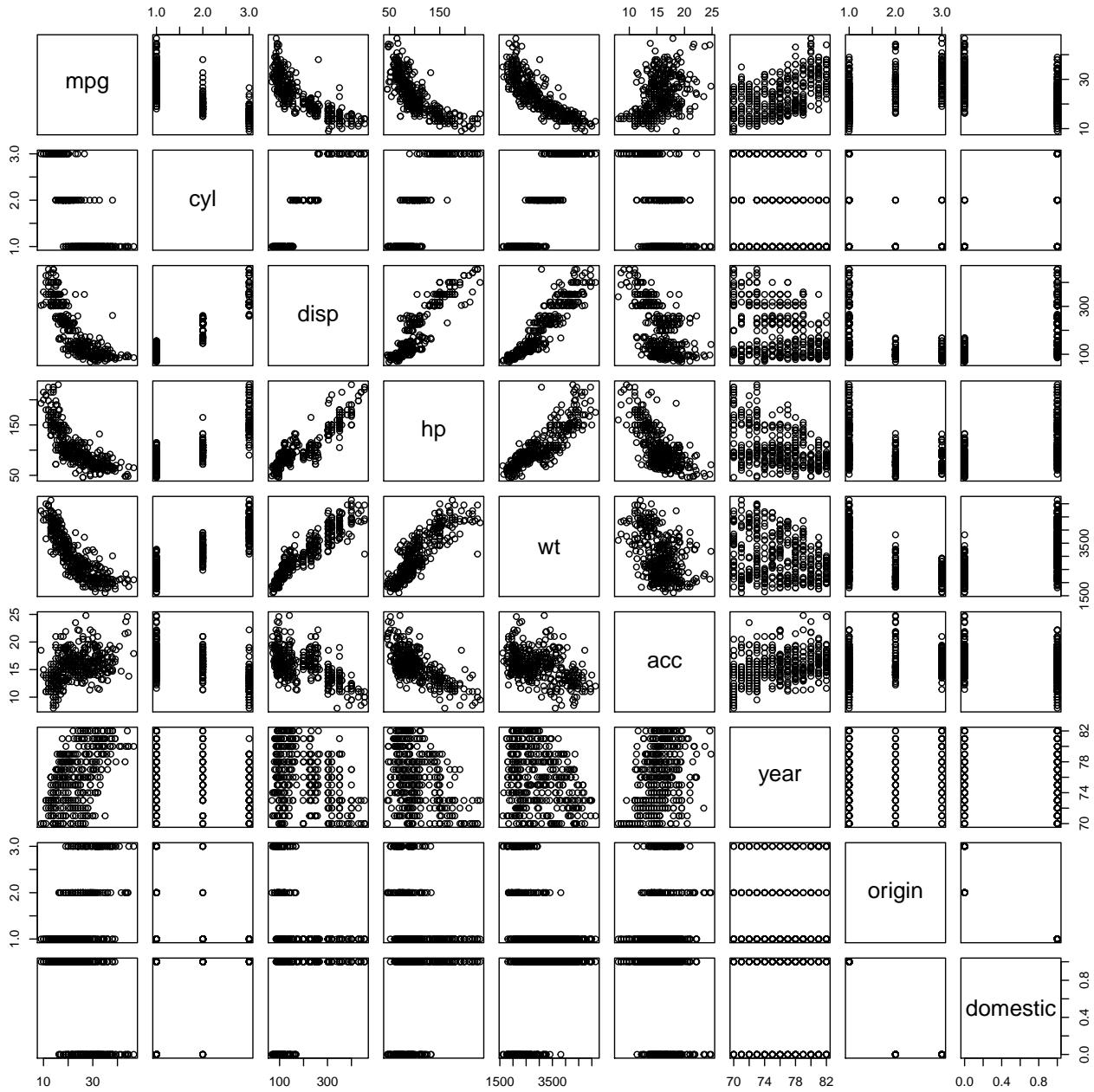
```
## (Intercept)   I(x + x)  
## -18.32715    12.43582
```

```
coef(lm(y ~ x + x, data = quad_data))
```

```
## (Intercept)           x  
## -18.32715    24.87163
```

17.2.6 Data Example

```
pairs(autompg)
```



```

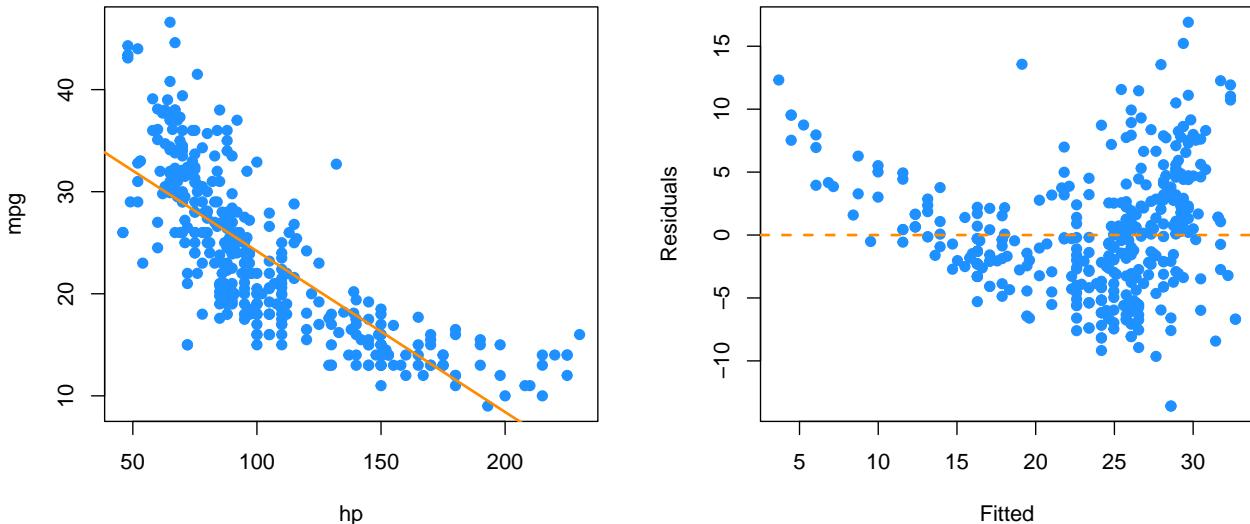
mpg_hp = lm(mpg ~ hp, data = autompg)

par(mfrow = c(1, 2))

plot(mpg ~ hp, data = autompg, col = "dodgerblue", pch = 20, cex = 1.5)
abline(mpg_hp, col = "darkorange", lwd = 2)

plot(fitted(mpg_hp), resid(mpg_hp), col = "dodgerblue",
      pch = 20, cex = 1.5, xlab = "Fitted", ylab = "Residuals")
abline(h = 0, lty = 2, col = "darkorange", lwd = 2)

```

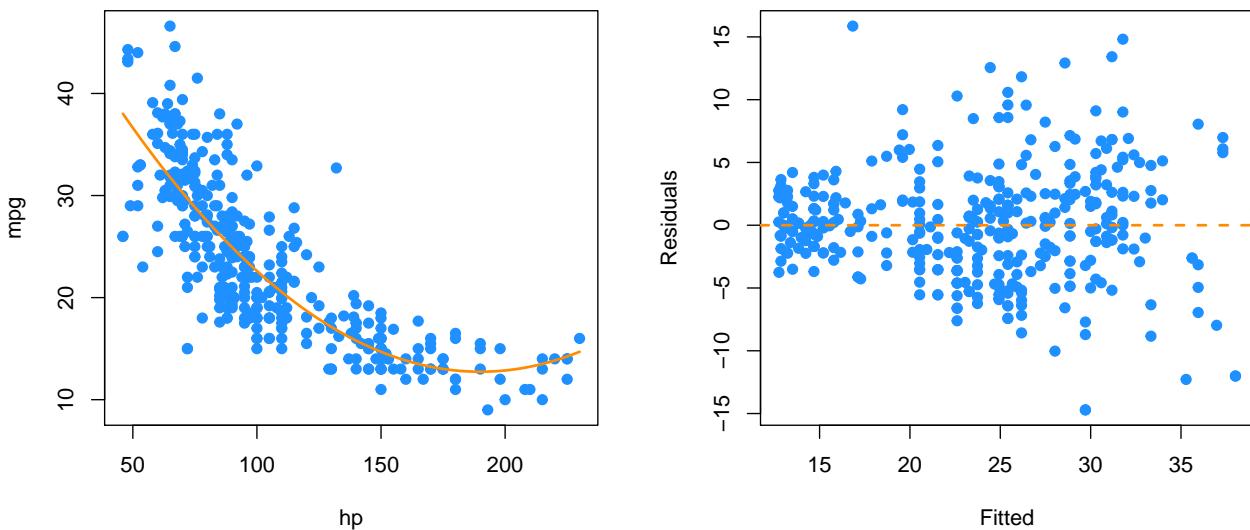


```
mpg_hp_log = lm(mpg ~ hp + I(hp ^ 2), data = autompg)

par(mfrow = c(1, 2))

plot(mpg ~ hp, data = autompg, col = "dodgerblue", pch = 20, cex = 1.5)
xplot = seq(min(autompg$hp), max(autompg$hp), by = 0.1)
lines(xplot, predict(mpg_hp_log, newdata = data.frame(hp = xplot)),
      col = "darkorange", lwd = 2, lty = 1)

plot(fitted(mpg_hp_log), resid(mpg_hp_log), col = "dodgerblue",
      pch = 20, cex = 1.5, xlab = "Fitted", ylab = "Residuals")
abline(h = 0, lty = 2, col = "darkorange", lwd = 2)
```



```
mpg_hp_log = lm(log(mpg) ~ hp + I(hp ^ 2), data = autompg)

par(mfrow = c(1, 2))

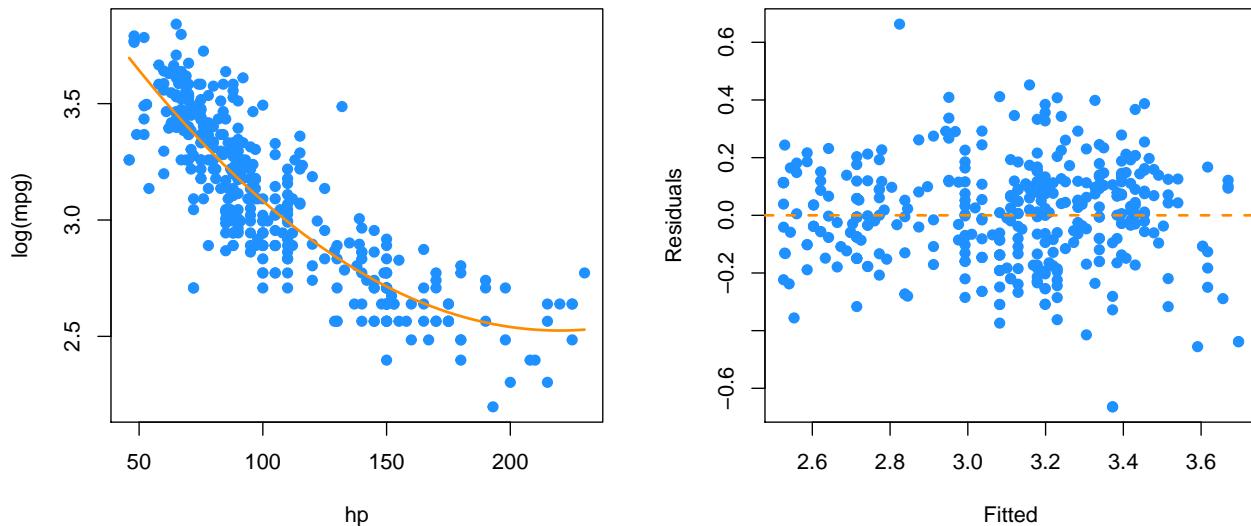
plot(log(mpg) ~ hp, data = autompg, col = "dodgerblue", pch = 20, cex = 1.5)
xplot = seq(min(autompg$hp), max(autompg$hp), by = 0.1)
```

```

lines(xplot, predict(mpg_hp_log, newdata = data.frame(hp = xplot)),
      col = "darkorange", lwd = 2, lty = 1)

plot(fitted(mpg_hp_log), resid(mpg_hp_log), col = "dodgerblue",
      pch = 20, cex = 1.5, xlab = "Fitted", ylab = "Residuals")
abline(h = 0, lty = 2, col = "darkorange", lwd = 2)

```



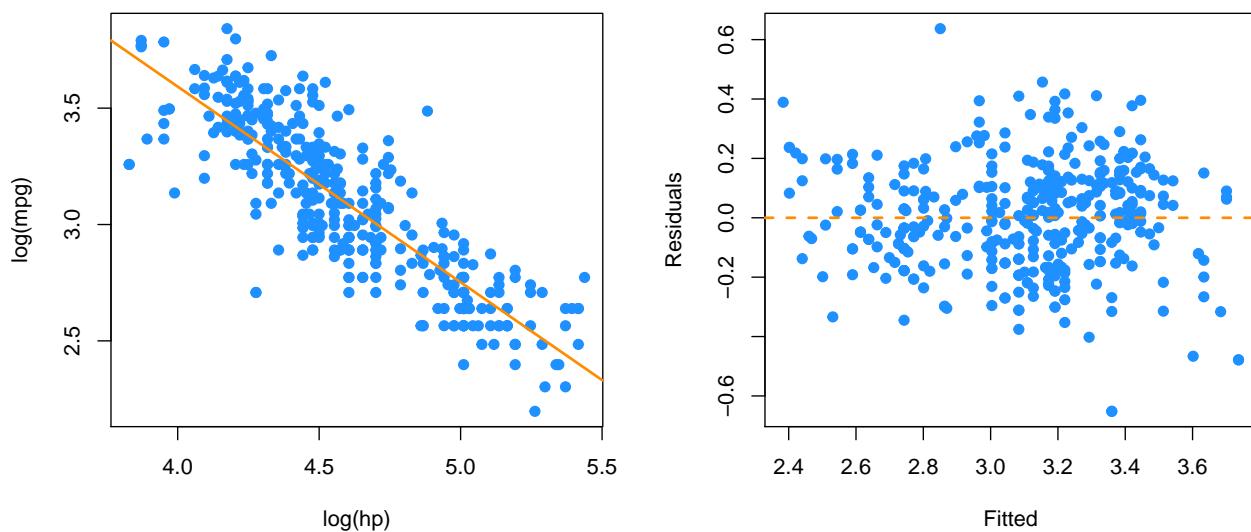
```

mpg_hp_loglog = lm(log(mpg) ~ log(hp), data = autompg)

par(mfrow = c(1, 2))
plot(log(mpg) ~ log(hp), data = autompg, col = "dodgerblue", pch = 20, cex = 1.5)
abline(mpg_hp_loglog, col = "darkorange", lwd = 2)

plot(fitted(mpg_hp_loglog), resid(mpg_hp_loglog), col = "dodgerblue",
      pch = 20, cex = 1.5, xlab = "Fitted", ylab = "Residuals")
abline(h = 0, lty = 2, col = "darkorange", lwd = 2)

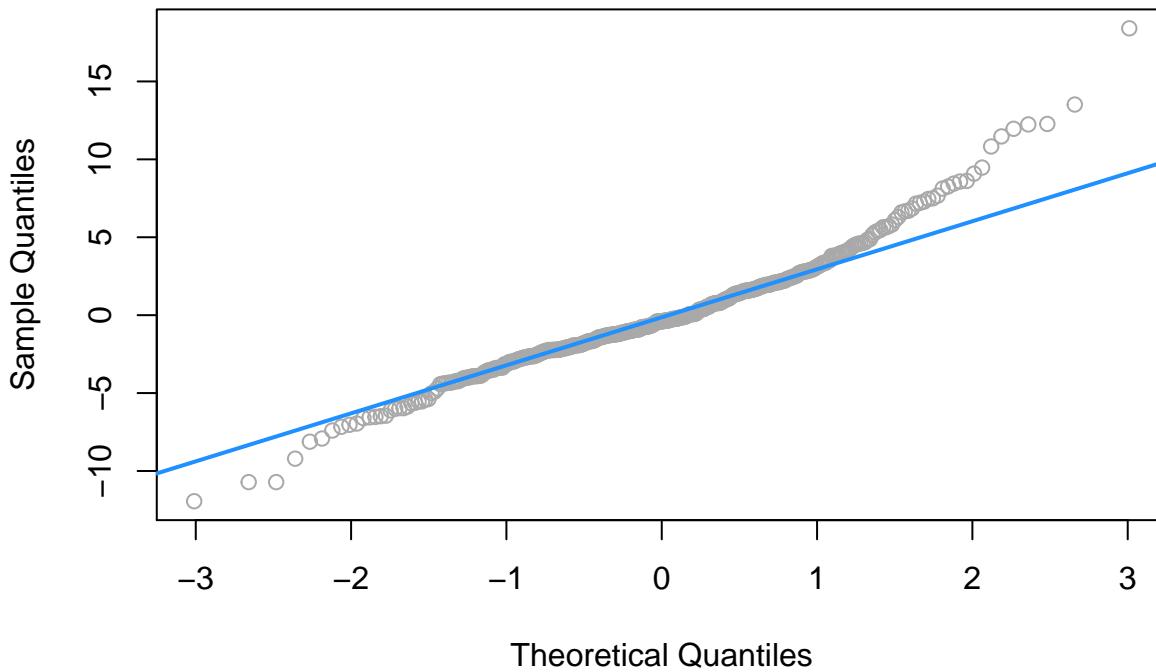
```



```
big_model = lm(mpg ~ disp * hp * domestic, data = autompg)
```

```
qqnorm(resid(big_model), col = "darkgrey")
qqline(resid(big_model), col = "dodgerblue", lwd = 2)
```

Normal Q-Q Plot

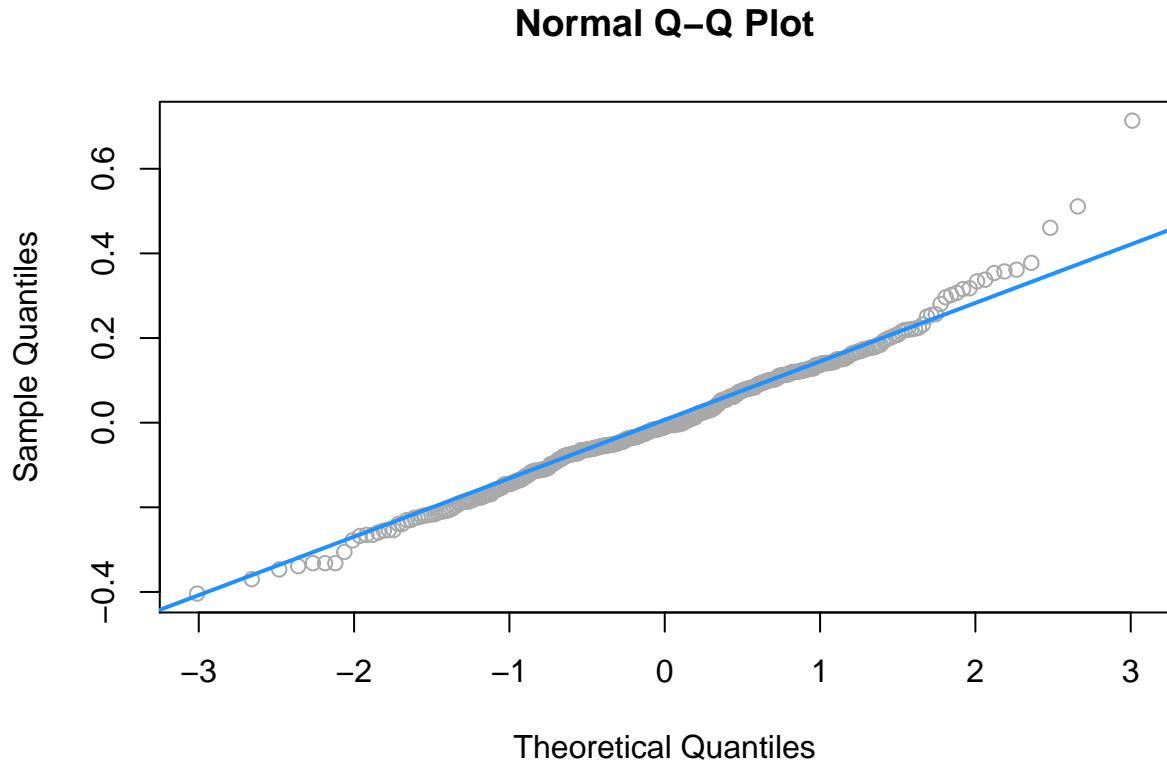


```
bigger_model = lm(log(mpg) ~ disp * hp * domestic +
                   I(disp^2) + I(hp^2), data = autompg)
summary(bigger_model)
```

```
##
## Call:
## lm(formula = log(mpg) ~ disp * hp * domestic + I(disp^2) + I(hp^2),
##      data = autompg)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -0.40381 -0.08635 -0.01040  0.09995  0.71365
##
## Coefficients:
##             Estimate Std. Error t value Pr(>|t|)
## (Intercept) 4.275696041 0.256435432 16.674 <2e-16 ***
## disp        -0.005289110 0.002564979 -2.062 0.0399 *
## hp         -0.007386162 0.003309347 -2.232 0.0262 *
## domestic    -0.249599488 0.278672623 -0.896 0.3710
## I(disp^2)    0.000008552 0.000004141  2.065 0.0396 *
## I(hp^2)     -0.000015649 0.000016791 -0.932 0.3519
## disp:hp     0.000026855 0.000030822  0.871 0.3842
```

```
## disp:domestic -0.001101296 0.002526207 -0.436 0.6631
## hp:domestic      0.007559531 0.003688787  2.049 0.0411 *
## disp:hp:domestic -0.000023110 0.000026620 -0.868 0.3859
## ---
## Signif. codes:  0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1
##
## Residual standard error: 0.1507 on 373 degrees of freedom
## Multiple R-squared:  0.8107, Adjusted R-squared:  0.8062
## F-statistic: 177.5 on 9 and 373 DF,  p-value: < 2.2e-16

qqnorm(resid(bigger_model), col = "darkgrey")
qqline(resid(bigger_model), col = "dodgerblue", lwd = 2)
```



Bibliography