# DiffEqFlux.jl 介紹

## **Outline**

- Introduction to DiffEqFlux.jl
- · Ordinal differential equations
- · ODE in Flux framework
- Demo Neural ODE

## Introduction to DiffEqFlux.jl

DiffEqFlux.jl 是由 DifferentialEquations.jl 的作者 Chris Rackauckas 以及 Flux.jl 的作者 Mike Innes 聯手合作的作品。

All the following materials comes from this blog (https://julialang.org/blog/2019/01/fluxdiffeq).

## **Ordinal differential equations**

```
using DifferentialEquations
In [ ]:
In [ ]: | function lotka_volterra(du,u,p,t)
            x, y = u
            \alpha, \beta, \delta, \gamma = p
            du[1] = dx = \alpha^*x - \beta^*x^*y
            du[2] = dy = -\delta * y + y * x * y
         end
In []: u0 = [1.0, 1.0]
         tspan = (0.0, 10.0)
         p = [1.5, 1.0, 3.0, 1.0];
         prob = ODEProblem(lotka_volterra, u0, tspan, p)
In [ ]:
         sol = solve(prob)
In [ ]:
         using Plots
In [ ]: plot(sol)
```

#### make u0 and tspans to be functions of p

```
In []: u0_f(p, t0) = [p[2], p[4]]

tspan_f(p) = (0.0, 10*p[4])

p = [1.5, 1.0, 3.0, 1.0]

prob = ODEProblem(lotka\_volterra, u0_f, tspan_f, p)
```

## **ODE** in Flux framework

#### **Solving problem by Flux**

```
In [ ]: using Flux, DiffEqFlux
In [ ]: p = [1.5, 1.0, 3.0, 1.0]
    prob = ODEProblem(lotka_volterra, u0, tspan, p)
In [ ]: diffeq_rd(p, prob, Tsit5(), saveat=0.1)
```

#### **Use ODE in Flux**

#### **Initial Parameters**

```
In [ ]: p = param([2.2, 1.0, 2.0, 0.4])
params = Flux.Params([p])
```

#### Wrap problem as 1-layer network

```
In [ ]: predict_rd() = diffeq_rd(p, prob, Tsit5(), saveat=0.1)[1, :]
```

#### **Loss function**

```
In [ ]: sin_data = [sin(2x) for x = 1:101];
In [ ]: loss_rd() = sum(abs2, predict_rd() .- sin_data)
```

#### Prepare dummy data

```
In [ ]: data = Iterators.repeated((), 100)
```

#### **Optimizer**

```
In [ ]: opt = ADAM(0.1)
```

#### **Callback function**

#### **Training**

```
In [ ]: Flux.train!(loss_rd, params, data, opt, cb=cb)
```

#### Flux layer

```
m = Chain(
  Dense(28^2, 32, relu),
  Dense(32, 10),
  softmax)
```

#### Stick ODE layer into MLP

```
m = Chain(
  Dense(28^2, 32, relu),
  # this would require an ODE of 32 parameters
  p -> diffeq_rd(p, prob, Tsit5(), saveat=0.1)[1, :],
  Dense(32, 10),
  softmax)
```

#### Stick ODE layer into CNN

```
m = Chain(
   Conv((2,2), 1=>16, relu),
   x -> maxpool(x, (2,2)),
   Conv((2,2), 16=>8, relu),
   x -> maxpool(x, (2,2)),
   x -> reshape(x, :, size(x, 4)),
   x -> diffeq_rd(p, prob, Tsit5(), saveat=0.1, u0=x)[1, :],
   Dense(288, 10), softmax) |> gpu
```

## **Neural ODE layer**

#### Generate some data

## Approximate derivative dudt with neural ODE layer

#### **Model and loss function**

```
In [ ]: predict_n_ode() = n_ode(u0)
  loss_n_ode() = sum(abs2, ode_data .- predict_n_ode())
```

#### **Optimizer and callback**

```
In [ ]: data = Iterators.repeated((), 1000)
    opt = ADAM(0.1)
    function cb2()
        display(loss_n_ode())
        # plot current prediction against data
        cur_pred = Flux.data(predict_n_ode())
        pl = scatter(t, ode_data[1, :], label="data")
        scatter!(pl, t, cur_pred[1, :], label="prediction")
        display(plot(pl))
    end

In [ ]: cb2()
In [ ]: Flux.train!(loss_n_ode, ps, data, opt, cb=cb2)
```

For example, if your data is unevenly spaced at time points t, just pass in saveat=t and the ODE solver takes care of it.

# <u>DiffEqFlux API (https://github.com/JuliaDiffEq/DiffEqFlux.jl#apidocumentation)</u>

# Thank you for attention