



# INTRODUCTION TO DATA-CENTRIC AI

---

Learn how to systematically engineer  
data to build better AI systems.

<https://dcai.csail.mit.edu>

Third lecture on 1/18 at 12:00p ET in Room 2-190

# Today's lecture: **Advanced Confident Learning**

Focus: Theory + Applications

# How does confident learning work?

To estimate  $p(\tilde{y}, y^*)$  and find label errors, confident learning requires two inputs:

- Noisy labels,  $\tilde{y}$
- Predicted probabilities,  $\hat{p}(\tilde{y}=i; \mathbf{x}, \boldsymbol{\theta})$

Note: CL is scale-invariant w.r.t. outputs, i.e. raw logits work as well

# How does confident learning work?

Key idea: First we find thresholds as a proxy for the machine's self-confidence, on average, for each task/class  $j$

$$t_j = \frac{1}{|\mathbf{X}_{\tilde{y}=j}|} \sum_{\mathbf{x} \in \mathbf{X}_{\tilde{y}=j}} \hat{p}(\tilde{y} = j; \mathbf{x}, \boldsymbol{\theta})$$

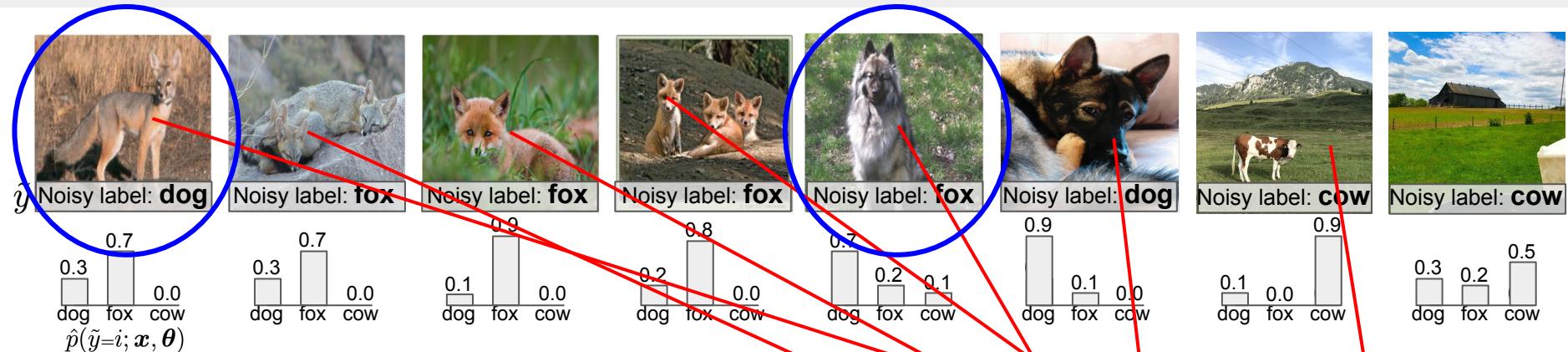
# How does confident learning work?

For each example,

estimate if its an error, correctly labeled, or an outlier based on:

$$\hat{\mathbf{X}}_{\tilde{y}=i, y^*=j} = \{x \in \mathbf{X}_{\tilde{y}=i} : \hat{p}(\tilde{y} = j; x, \theta) \geq t_j\}$$

# How does confident learning work? (in 10 seconds)



$$\begin{aligned} t_j &= \frac{t_j}{t_{\text{dog}} = 0.7} & \hat{X}_{\tilde{y}=i, y^*=j} = \\ t_{\text{fox}} &= 0.7 & \{x \in X_{\tilde{y}=i} : \hat{p}(\tilde{y}=j; x, \boldsymbol{\theta}) \geq t_j\} \\ t_{\text{cow}} &= 0.9 \end{aligned}$$

Off diagonals  
are CL-guessed  
label errors

$\tilde{y}, y^*$	$y^* = \text{dog}$	$y^* = \text{fox}$	$y^* = \text{cow}$
$\tilde{y} = \text{dog}$	1	1	0
$\tilde{y} = \text{fox}$	1	3	0
$\tilde{y} = \text{cow}$	0	0	1

$C_{\tilde{y}, y^*}[i][j] = |\hat{X}_{\tilde{y}=i, y^*=j}|$

After looking through the entire dataset, we have:

$C_{\tilde{y}, y^*}$	$y^* = \text{dog}$	$y^* = \text{fox}$	$y^* = \text{cow}$
$\tilde{y} = \text{dog}$	100	40	20
$\tilde{y} = \text{fox}$	56	60	0
$\tilde{y} = \text{cow}$	32	12	80

From  $C_{\tilde{y}, y^*}$  we obtain the joint distribution of label noise

$\hat{p}(\tilde{y}, y^*)$	$y^* = \text{dog}$	$y^* = \text{fox}$	$y^* = \text{cow}$
Estimated $\tilde{y} = \text{dog}$	0.25	0.1	0.05
$\tilde{y} = \text{fox}$	0.14	0.15	0
$\tilde{y} = \text{cow}$	0.08	0.03	0.2

# You can do this in 1 import and 1 line of code

```
from cleanlab.filter import find_label_issues

# Option 2 - works with ANY ML model - just input the model's predicted probabilities
ordered_label_issues = find_label_issues(
    labels=labels,
    pred_probs=pred_probs, # out-of-sample predicted probabilities from any model
    return_indices_ranked_by='self_confidence',
)
```

<https://github.com/cleanlab/cleanlab>

# Ranking label errors

- self-confidence (chalk board)
- Normalized margin (chalk board)

Organization for this part of the talk:

- ✓ 1. What is confident learning?
- ✓ 2. Situate confident learning
  - a. Noise + related work
- ✓ 3. How does CL work? (methods)
- 4. Comparison with other methods
- 5. Why does CL work? (theory)
  - a. Intuitions
  - b. Principles
- 6. Label errors on ML benchmarks

# Compare Accuracy: Learning with 40% label noise in CIFAR-10

		Fraction of zeros in the off-diagonals of $p(\tilde{y} y^*)$	
		0	0.6 ← More realistic (e.g. ImageNet)
Confident learning methods	Baseline (remove prediction $\neq$ label)	83.9	84.2
	INCV (Chen et al., 2019) Mixup (Zhang et al., 2018)	84.8 86.7 <b>87.1</b> <b>87.1</b>	86.2 86.9 <b>87.2</b> <b>87.2</b>
SCE-loss (Wang et al., 2019) MentorNet (Jiang et al., 2018) Co-Teaching (Han et al., 2018) S-Model (Goldberger et al., 2017) Reed (Reed et al., 2015) Baseline	Data-centric Train with errors removed <i>"Change the dataset"</i>	84.4 76.1	73.6 59.8
	Model-centric Train with errors <i>"adjust the loss"</i>	76.3 64.4 62.9 58.6 60.5 60.2	58.3 61.5 58.1 57.5 58.6 57.3

Organization for this part of the talk:

- ✓ 1. What is confident learning?
- ✓ 2. Situate confident learning
  - a. Noise + related work
- ✓ 3. How does CL work? (methods)
- ✓ 4. Comparison with other methods
- 5. Why does CL work? (theory)
  - a. Intuitions
  - b. Principles
- 6. Label errors on ML benchmarks

# Theory of Confident Learning

To understand CL performance, we studied conditions where CL exactly finds label errors, culminating in the following Theorem:

*As long as examples in class  $i$  are labeled  $i$  more than any other class, then...*

*We prove realistic sufficient conditions (allowing significant error in all model outputs)*

Such that CL still exactly finds label errors.  $\hat{\mathbf{X}}_{\tilde{y}=i, y^*=j} \approx \mathbf{X}_{\tilde{y}=i, y^*=j}$

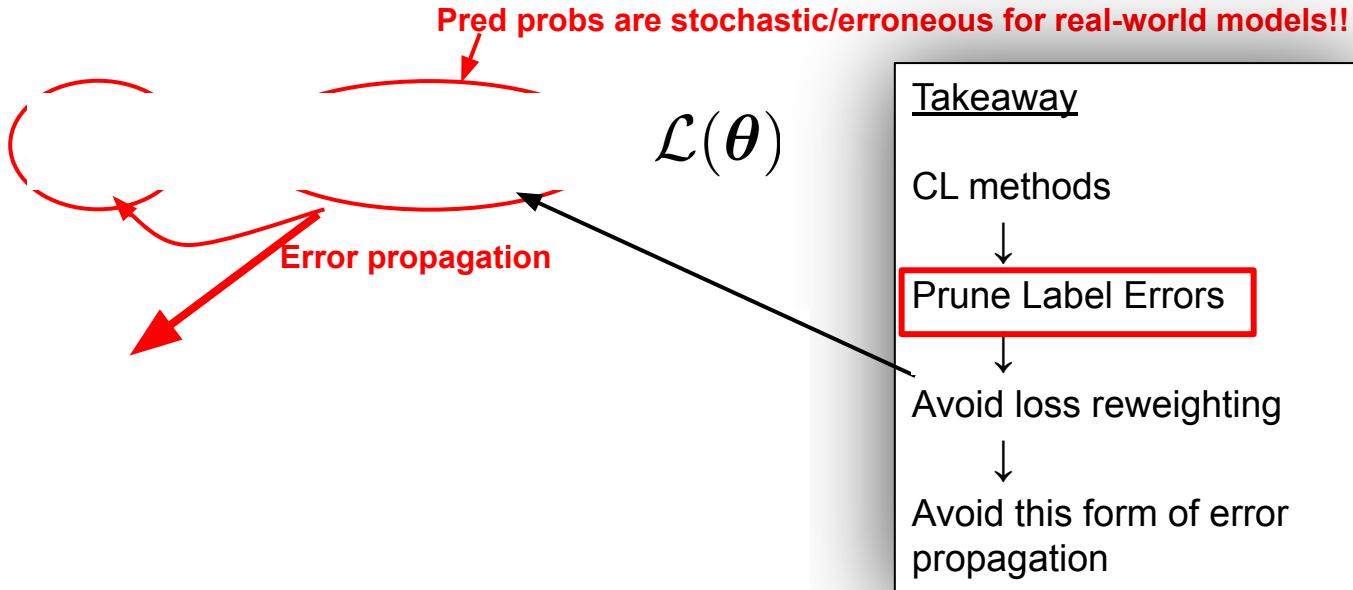
# Intuition: CL theory builds on three principles

- The **Prune** Principle
  - remove errors, then train
  - Chen et al. (2019), Patrini et al. (2017), Van Rooyen et al. (2015)
- The **Count** Principle
  - use ratios of counts, not noisy model outputs
  - Page et al. (1997), Jiang et al. (2018)
- The **Rank** Principle
  - use rank of model outputs, not the noisy values
  - Natarajan et al. (2017), Forman (2005, 2008), Lipton et al. (2018)

# CL Robustness Intuition 1: Prune

Key Idea:

Pruning enables robustness to stochastic/imperfect predicted probabilities  $\hat{p}(\tilde{y}=i; \mathbf{x}, \boldsymbol{\theta})$



SGD weights update:

## CL Robustness Intuition 2: Count & Rank

Same idea: **Counting** and **Ranking** enable robustness to errors

But this time: Let's look at noise transition estimation

Other methods:

(Elkan & Noto, 2008;  
Sukhbaatar et al., 2015)

$$p(y^* = j | \tilde{y} = i) \approx \mathbb{E}[p(\hat{y} = j | \mathbf{x})]$$

### Takeaway

CL methods



Robust statistics to estimate  
with counts based on rank



Robust to imperfect  
probabilities from model

# What do “ideal” (non-erroneous) predicted probs look like?

$$\boldsymbol{x} \in X_{\tilde{y}=i, y^*=j}$$

Equipped with this understanding of ideal probabilities

And the prune, count, and rank principles of CL

We can see the intuition for our theorem (exact error finding with noisy probs)

# Theorem Intuition

Let “ideal”  $\hat{p} = 0.9$ .

$$\hat{X}_{\tilde{y}=i, y^*=j} = \{\boldsymbol{x} \in X_{\tilde{y}=i} : \hat{p}(\tilde{y} = j; \boldsymbol{x}, \boldsymbol{\theta}) \geq 0.6\}$$

The model can be up to  $(0.9 - 0.6) / 0.9 = 33\%$  wrong in its estimate of  $\hat{p}$

And  $\boldsymbol{x}$  will be correctly counted.

Does this result still hold for systematic miscalibration (common in neural networks)?

Guo, Pleiss, Sun, & Weinberger (2017) “On Calibration of Modern Neural Networks.” ICML

# Final Intuition: Robustness to miscalibration

Exactly finds label errors  
for “ideal” probabilities  
(Ch. 2, Thm 1, in thesis)

$$C_{\tilde{y}=i, y^*=j} := |\{\mathbf{x} : \mathbf{x} \in \mathbf{X}_{\tilde{y}=i}, \hat{p}(\tilde{y} = j | \mathbf{x}) \geq t_j\}|$$

$$t_j = \frac{1}{|\mathbf{X}_{\tilde{y}=j}|} \sum_{\mathbf{x} \in \mathbf{X}_{\tilde{y}=j}} \hat{p}(\tilde{y} = j; \mathbf{x}, \boldsymbol{\theta})$$

But neural networks have been shown (Guo et al., 2017) to be over-confident for some classes:

$$\begin{aligned} t_j^{\epsilon_j} &= \frac{1}{|\mathbf{X}_{\tilde{y}=j}|} \sum_{\mathbf{x} \in \mathbf{X}_{\tilde{y}=j}} \hat{p}(\tilde{y} = j; \mathbf{x}, \boldsymbol{\theta}) + \epsilon_j \\ &= t_j + \epsilon_j \end{aligned}$$

What happens to  $C_{\tilde{y}=i, y^*=j}$ ?

$$C_{\tilde{y}=i, y^*=j}^{\epsilon_j} = |\{\mathbf{x} : \mathbf{x} \in \mathbf{X}_{\tilde{y}=i}, \hat{p}(\tilde{y} = j | \mathbf{x}) + \epsilon_j \geq t_j + \epsilon_j\}|$$

exactly finds errors

# Enough intuition, let's see some results

First we'll look at examples for dataset curation in ImageNet.

Then we'll look at CL with various distributions/models

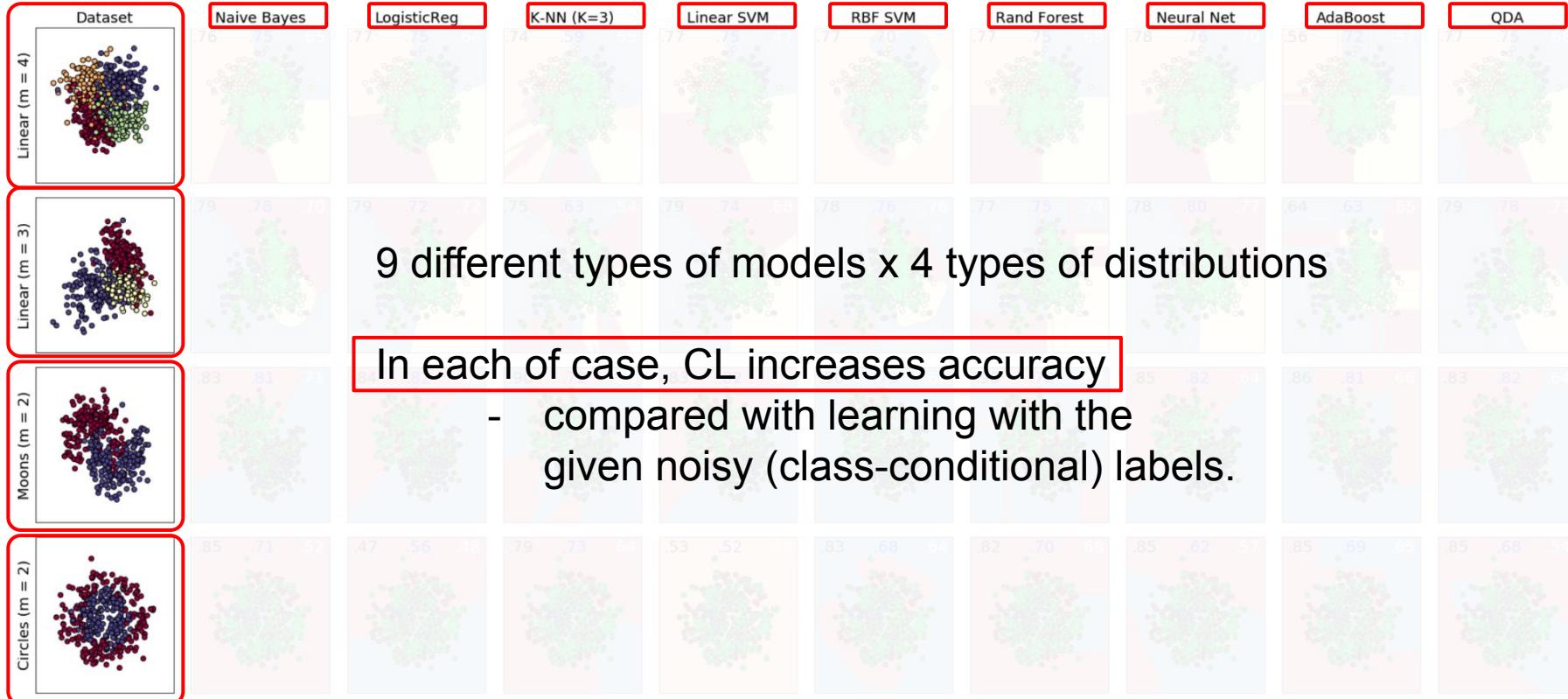
Then we'll look at failure modes

Finally, we're ready for part 3: "label errors"

Organization for this part of the talk:

- ✓ 1. What is confident learning?
- ✓ 2. Situate confident learning
  - a. Noise + related work
- ✓ 3. How does CL work? (methods)
- ✓ 4. Comparison with other methods
- ✓ 5. Why does CL work? (theory)
  - a. Intuitions
  - b. Principles
- 6. Label errors on ML benchmarks

# CL is model-agnostic



# Hard examples. Often there is no good ‘true’ label.



ImageNet given label:  
**sewing machine**

We guessed: **manhole cover**

MTurk consensus: **Neither sewing machine nor manhole cover**

ID: 00001127

(a)



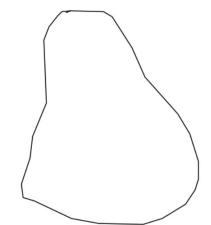
CIFAR-10 given label:  
**airplane**

We guessed: **automobile**

MTurk consensus: **Neither airplane nor automobile**

ID: 2532

(b)



QuickDraw given label:  
**potato**

We guessed: **pear**

MTurk consensus: **pear**

ID: 34728775

(c)



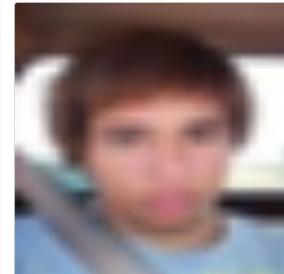
MNIST given label:  
**5**

We guessed: **3**

MTurk consensus: **3**

ID: 5937

(d)



CIFAR-100 given label:  
**man**

We guessed: **boy**

MTurk consensus: **boy**

ID: 2935

(e)



Caltech-256 given label:  
**drinking-straw**

We guessed: **ladder**

MTurk consensus: **Neither drinking-straw nor ladder**

ID: 059\_drinking-straw|059\_0037

(f)

# 3.4% of labels in popular ML test sets are erroneous

<https://labelerrors.com/>

Dataset		Test Set Errors				
		CL guessed	MTurk checked	validated	estimated	% error
Images →	MNIST	100	100 (100%)	15	-	0.15
	CIFAR-10	275	275 (100%)	54	-	0.54
	CIFAR-100	2235	2235 (100%)	585	-	5.85
	Caltech-256	4,643	400 (8.6%)	65	754	2.46
	ImageNet*	5,440	5,440 (100%)	2,916	-	5.83
Text →	QuickDraw	6,825,383	2,500 (0.04%)	1870	5,105,386	10.12
	20news	93	93 (100%)	82	-	1.11
	IMDB	1,310	1,310 (100%)	725	-	2.9
Audio →	Amazon	533,249	1,000 (0.2%)	732	390,338	3.9
	AudioSet	307	307 (100%)	275	-	1.35

There are pervasive label errors in test sets, but what are the implications for ML?

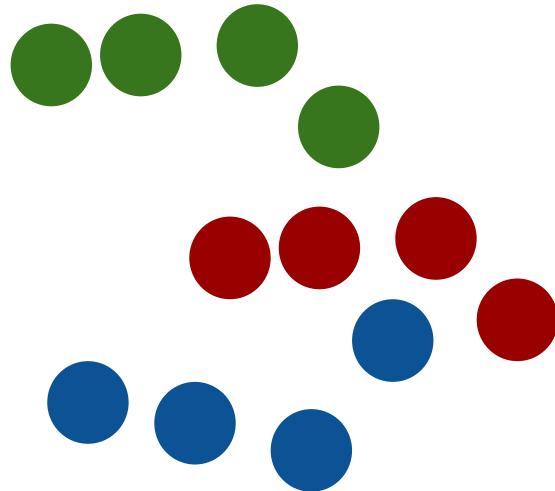
Are practitioners unknowingly benchmarking ML using erroneous test sets?

To answer this, let's consider how ML traditionally creates test sets...

and why it can lead to problems for real-world deployed AI models.

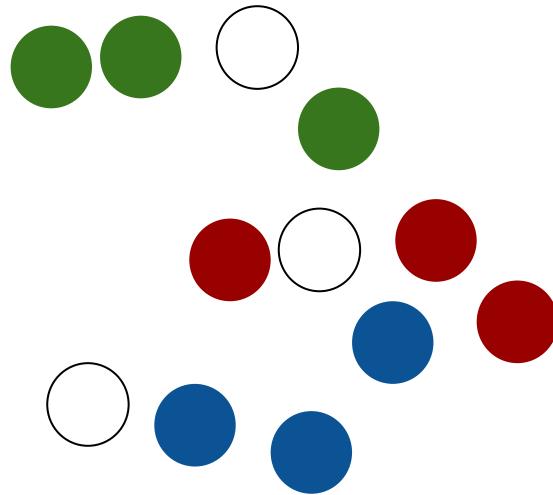
# A traditional view

Data Set

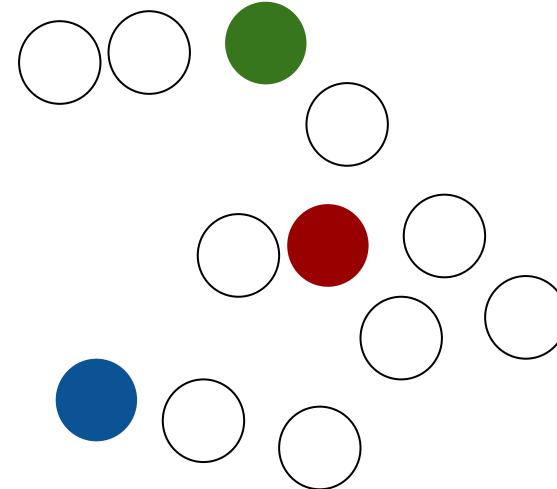


# A traditional view

Train Set

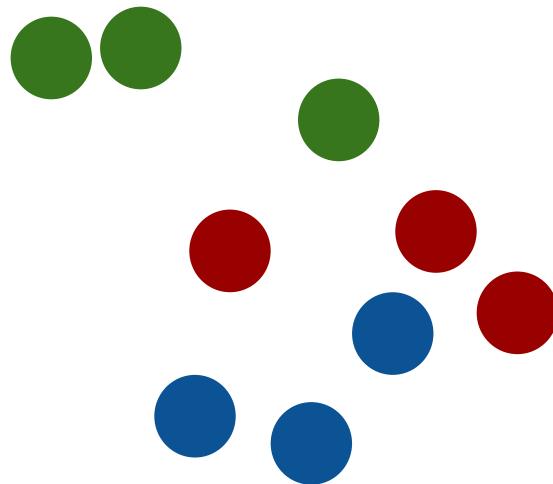


Test Set

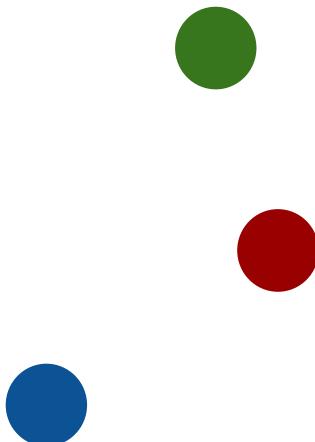


# A traditional view

Train Set

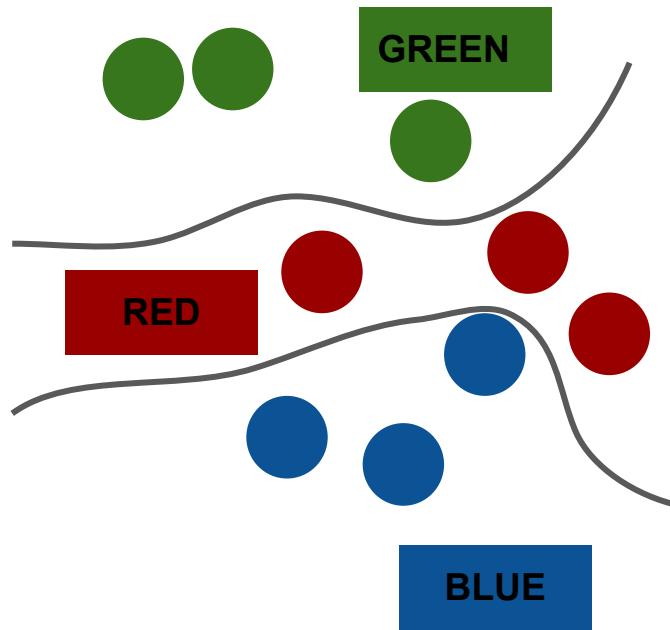


Test Set

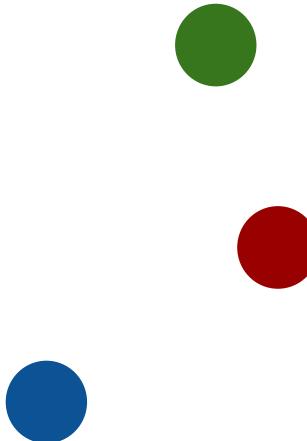


# A traditional view

Train Set

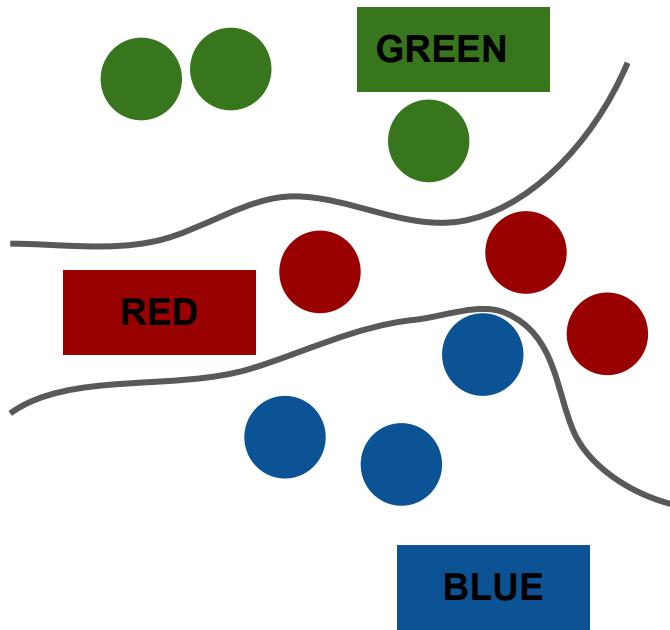


Test Set

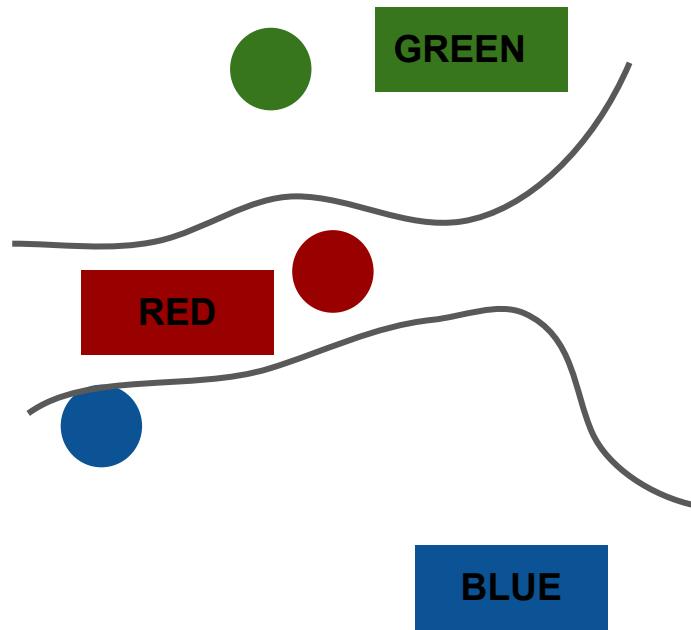


# A traditional view

Train Set

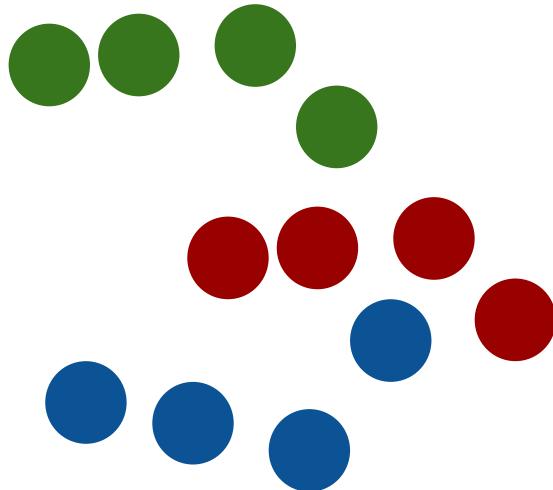


Test Set



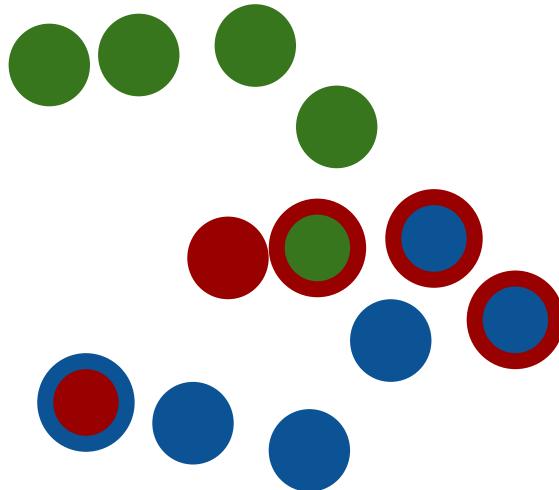
# A real-world view

Data Set



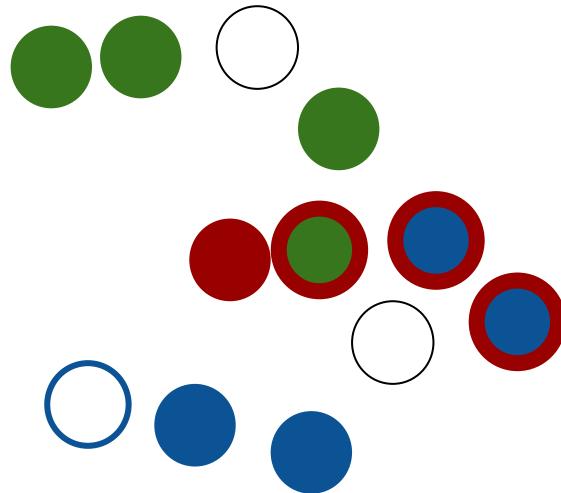
# A real-world view

Data Set

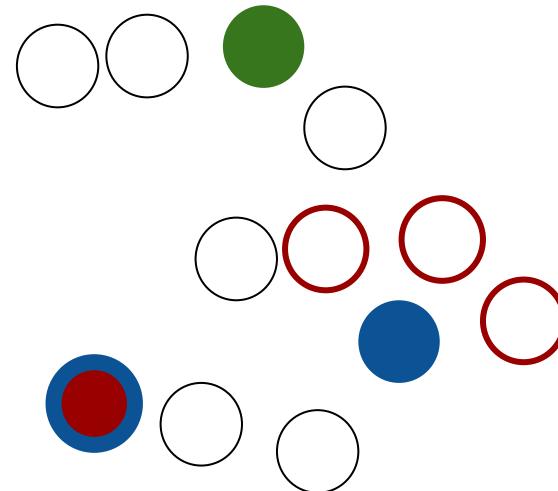


# A real-world view

Train Set

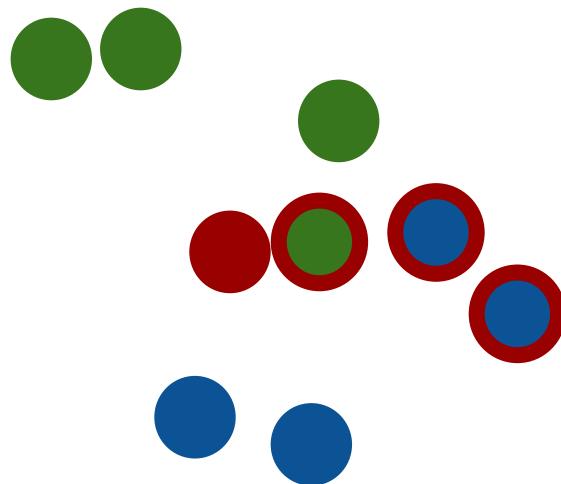


Test Set

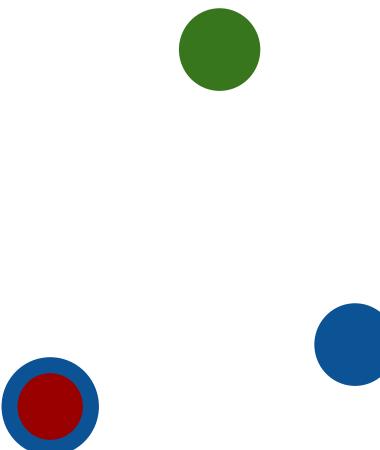


# A real-world view

Train Set

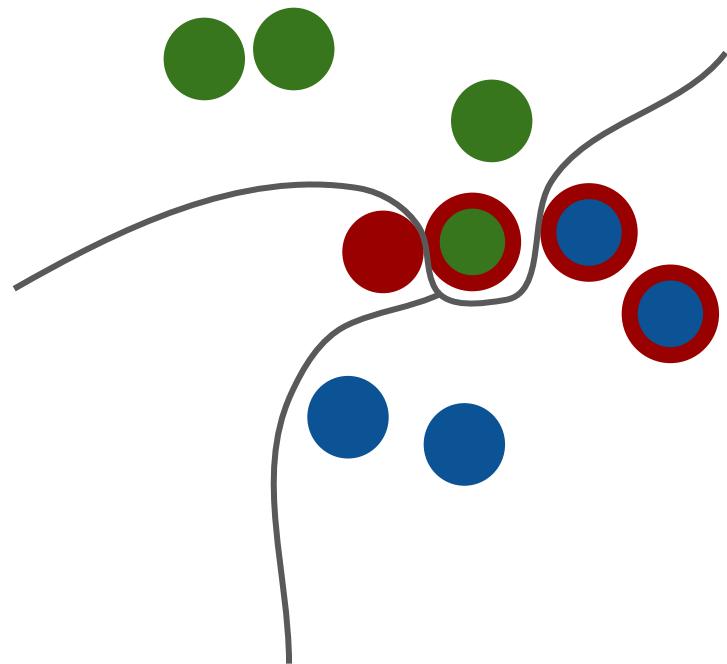


Test Set

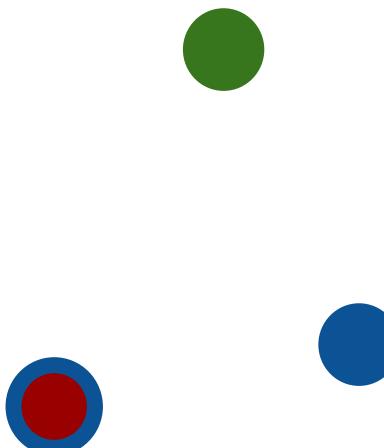


# A real-world view

Train Set

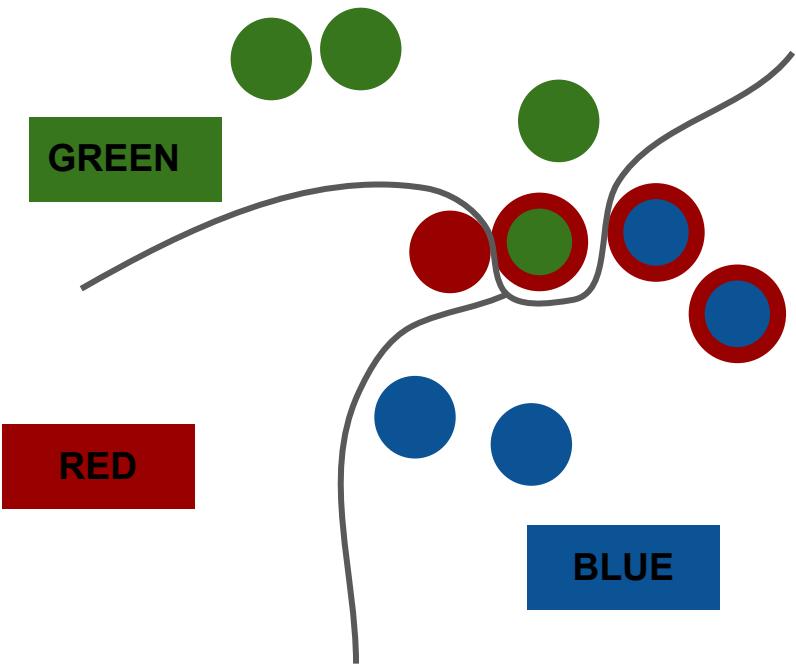


Test Set

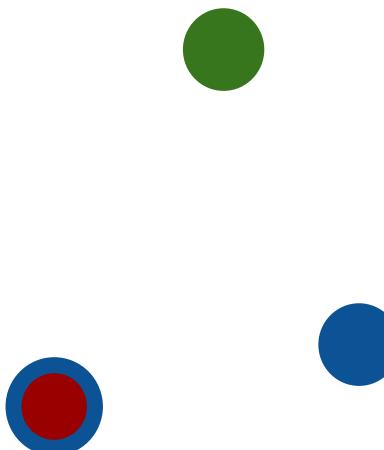


# A real-world view

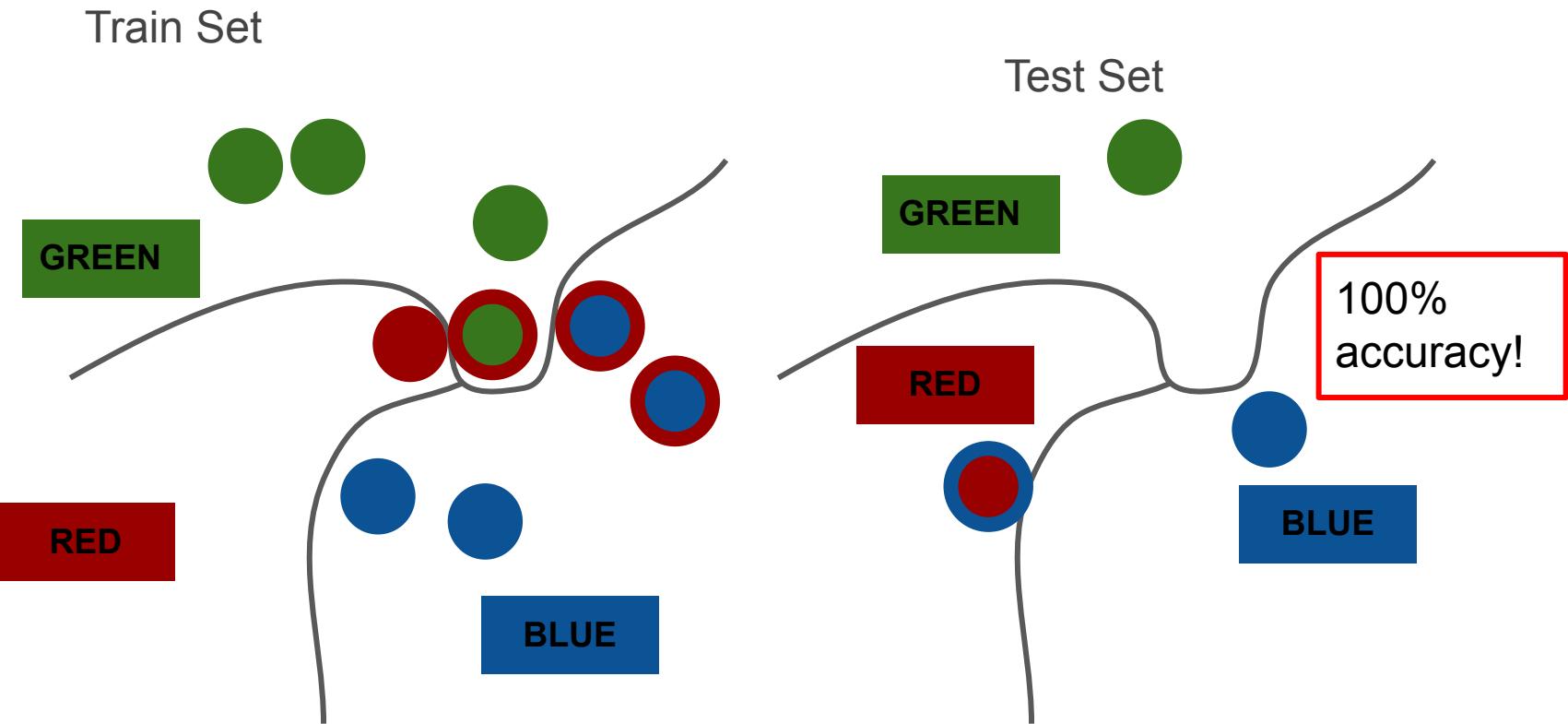
Train Set



Test Set

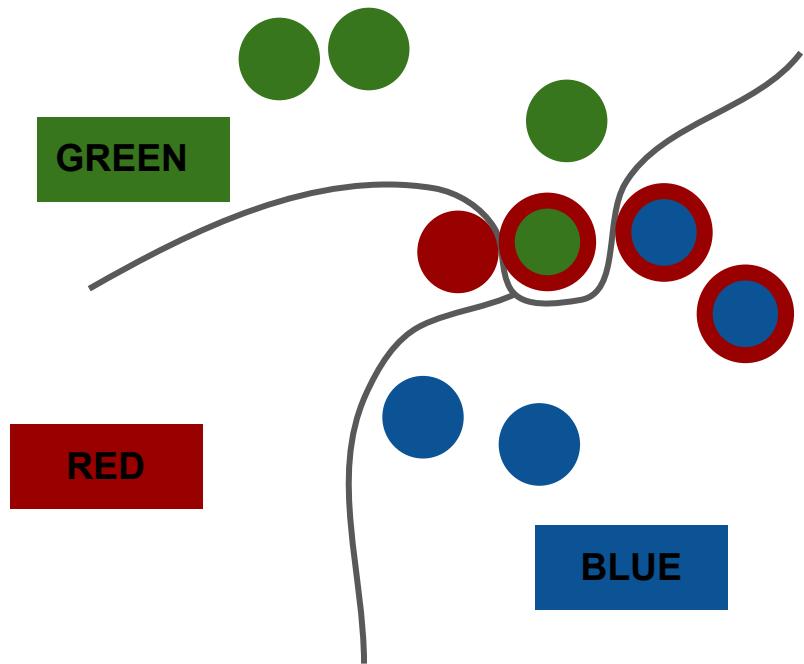


# A real-world view



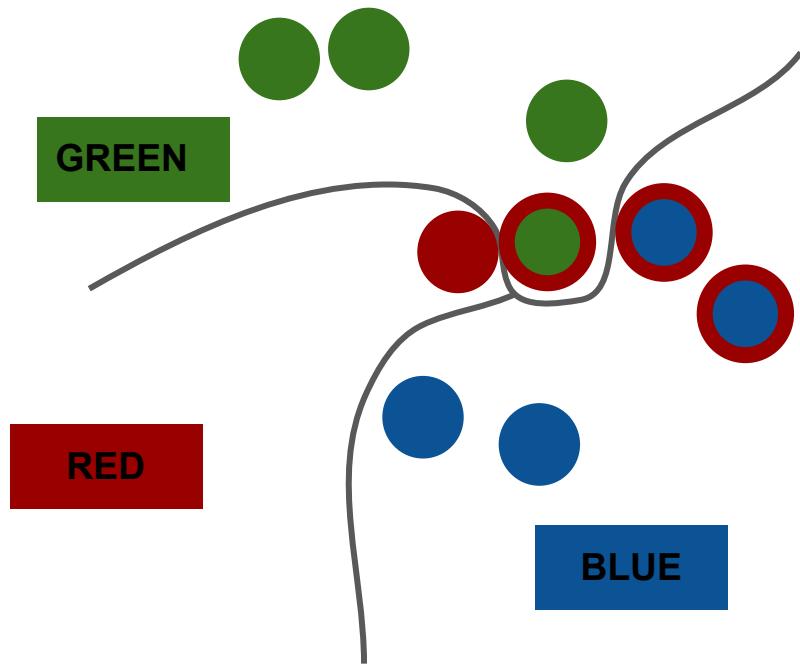
# A real-world view

Trained Model with 100% test accuracy.

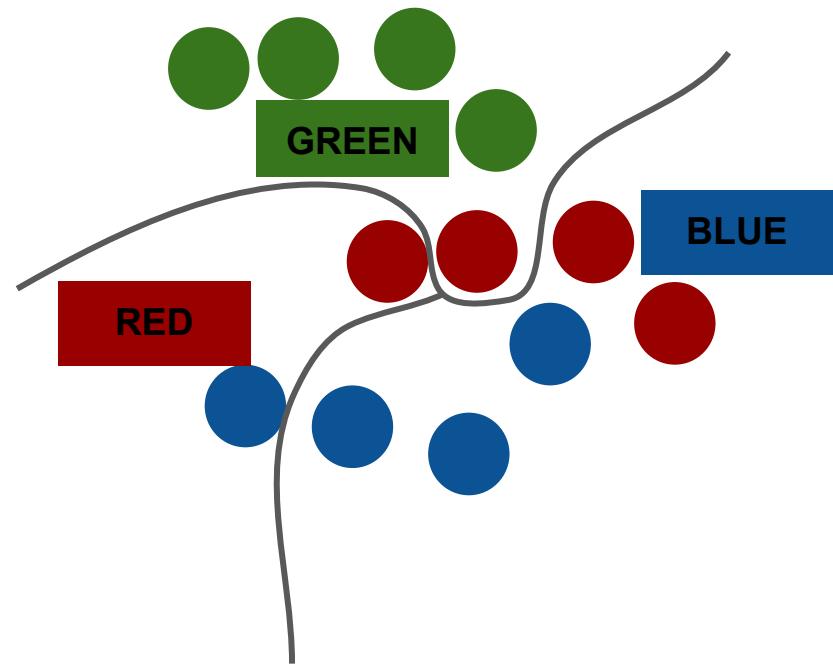


# A real-world view

Trained Model with 100% test accuracy.



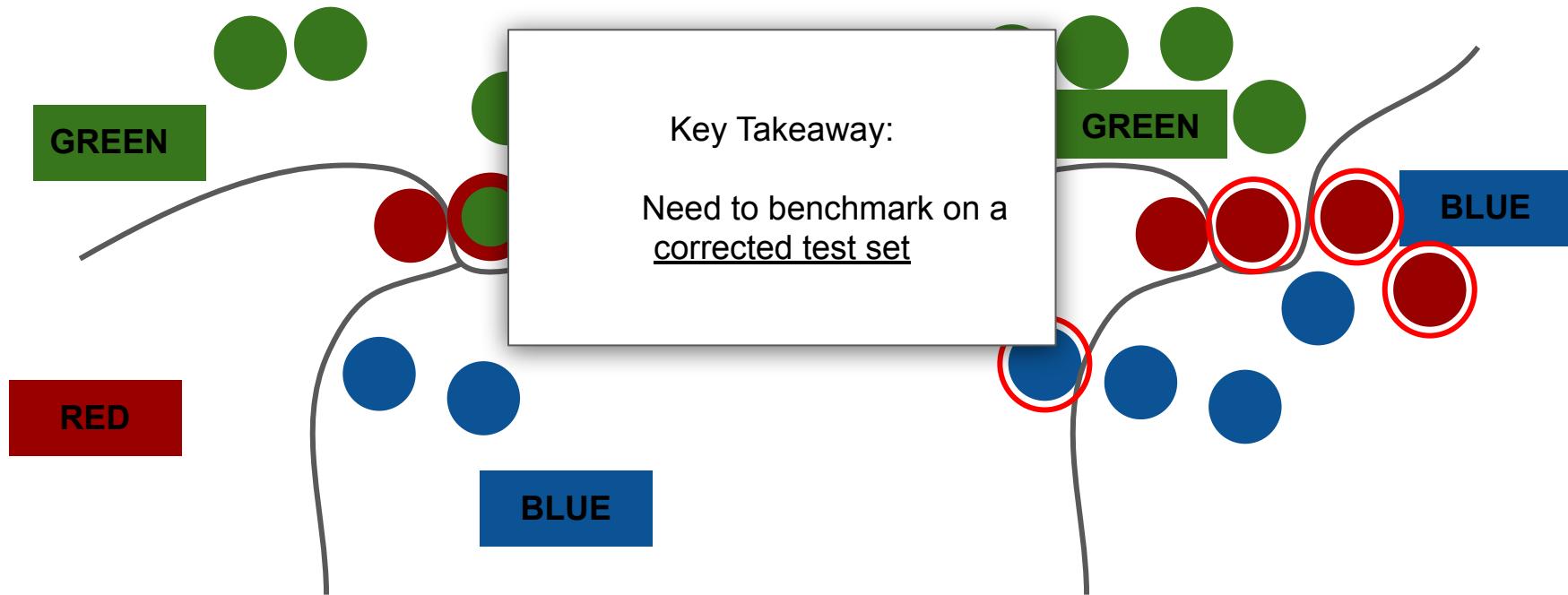
Real-world distribution  
(the test set you actually care about)



# A real-world view

Trained Model with 100% test accuracy.

Real-world accuracy ~ 67%



# Correcting the test set

**Instructions**  
Choose the category that appears in the image. Examples of each category are given below. If the image contains both categories, select "Both". If neither appears, select "Neither".

**Examples of frog**



**Which do you see?**  
(images are supposed to be blurry)



**Click image to expand.**

**Examples of cat**



**Select an option**

- (a) frog 1
- (b) cat 2
- both (a) and (b) 3
- neither 2

correctable



given: 5  
corrected: 3



given: cat  
corrected: frog



given: lobster  
corrected: crab



given: ewer  
corrected: teapot



given: white stork  
corrected: black stork



given: tiger  
corrected: eye

multi-label



given: 6  
alt: 1



given: deer  
alt: bird



given: rose  
alt: apple



given: porcupine  
alt: hot tub



given: polar bear  
alt: elephant



given: pineapple  
alt: raccoon

neither



given: 4  
alt: 9



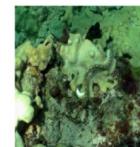
given: deer  
alt: frog



given: spider  
alt: cockroach



given: minotaur  
alt: coin



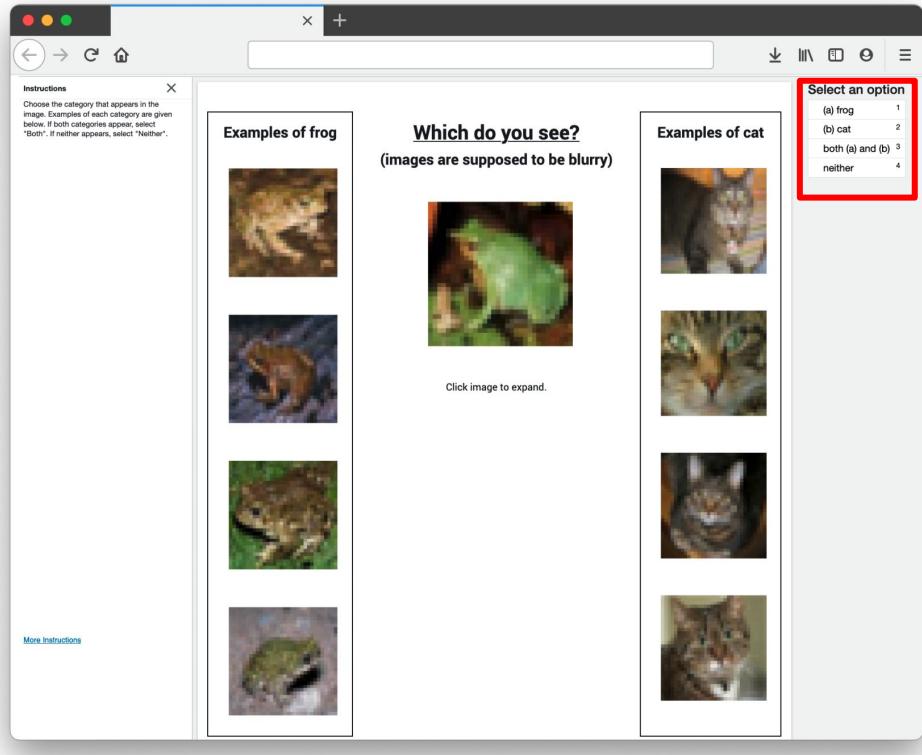
given: eel  
alt: flatworm



given: bandage  
alt: roller coaster

non-agreement

# Correcting the test sets



**Correct the label** if a majority of reviewers:

- agree on our proposed label

**Do nothing** if a majority of reviewers:

- agree on the original label

**Prune the example** from the test set if the consensus is:

- Neither
- Both (multi-label)
- Reviewers cannot agree

## To support this claim, this talk addresses two questions

1. In noisy, realistic settings, can we assemble a principled framework for quantifying, finding, and learning with label errors using a machine's confidence?
  - a. Traditionally, ML has focused on "Which model best learns with noisy labels?"
  - b. In this talk I ask, "Which data is mislabeled?"

If Q1 works out, and there are label errors in datasets... does it matter? This leads us to Q2...

2. Are we unknowingly benchmarking the progress of ML models, based on erroneous test sets? If so, can we quantify how much noise destabilizes benchmarks?

Cartoon-250

ImageNet

QuickDraw

**Remember our two questions? Now we have the tools (corrected test sets) to answer Q2:**

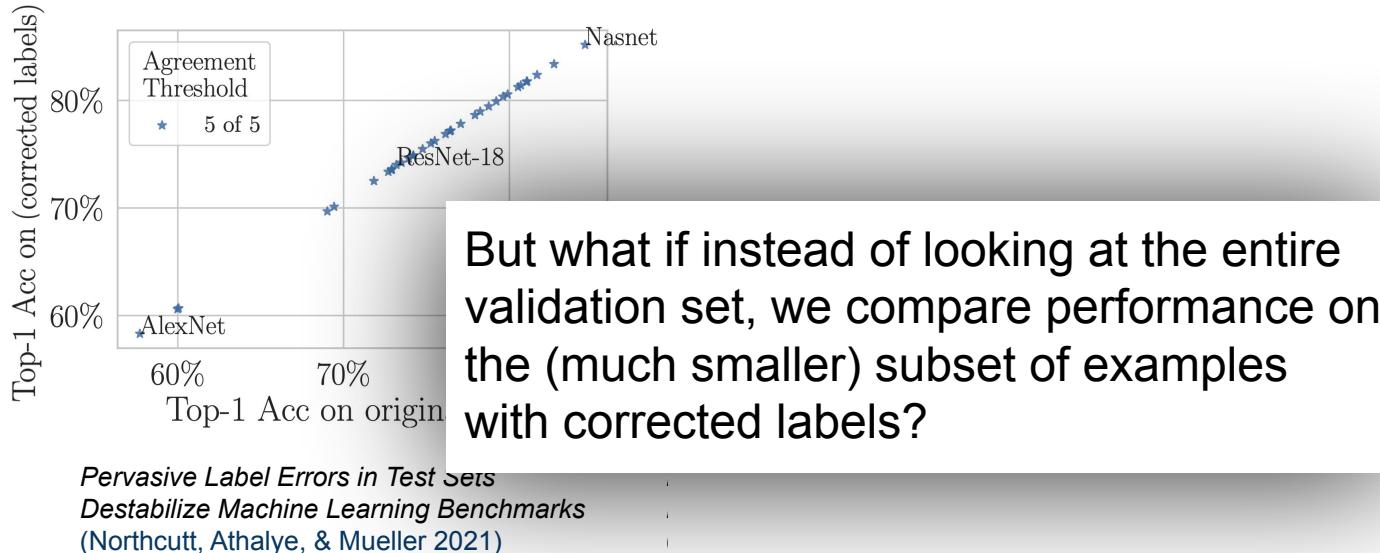
AudioSet

### Categorization

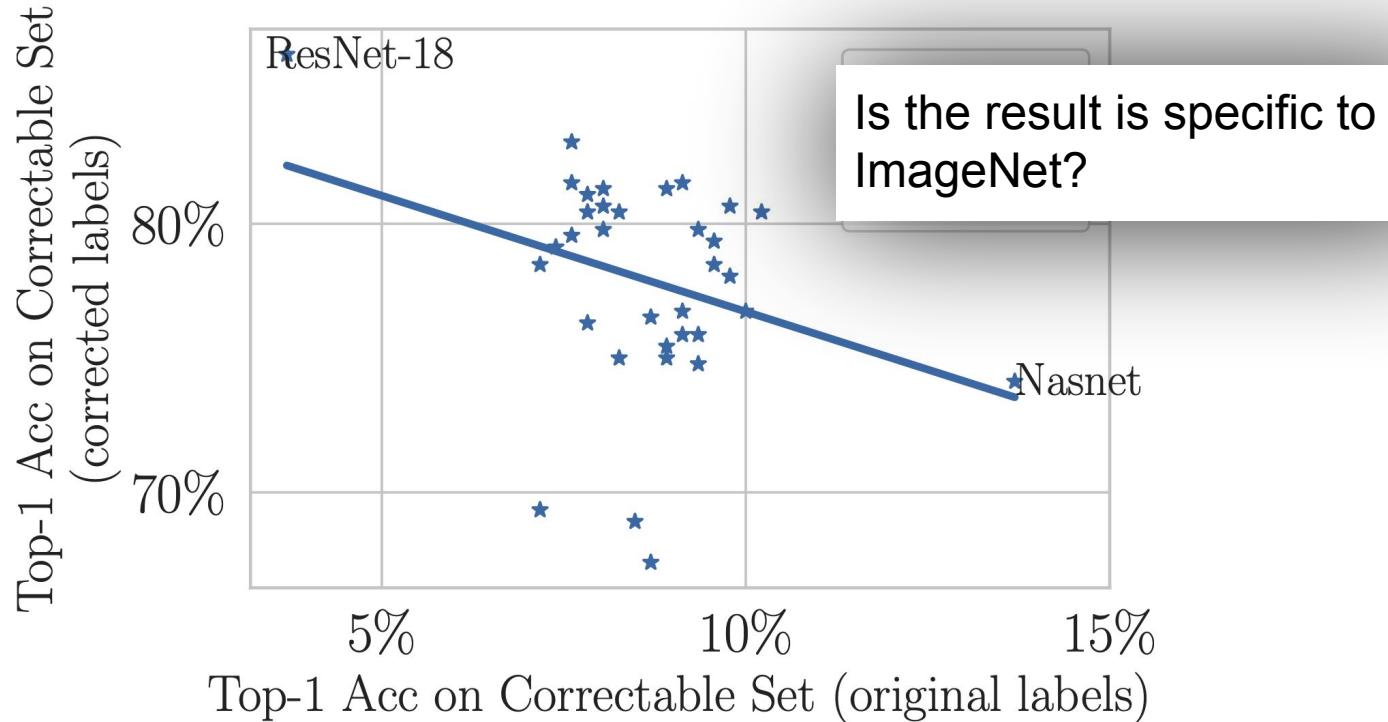
#### correctable

10
18
318
22
1428
1047
22
173
302
-

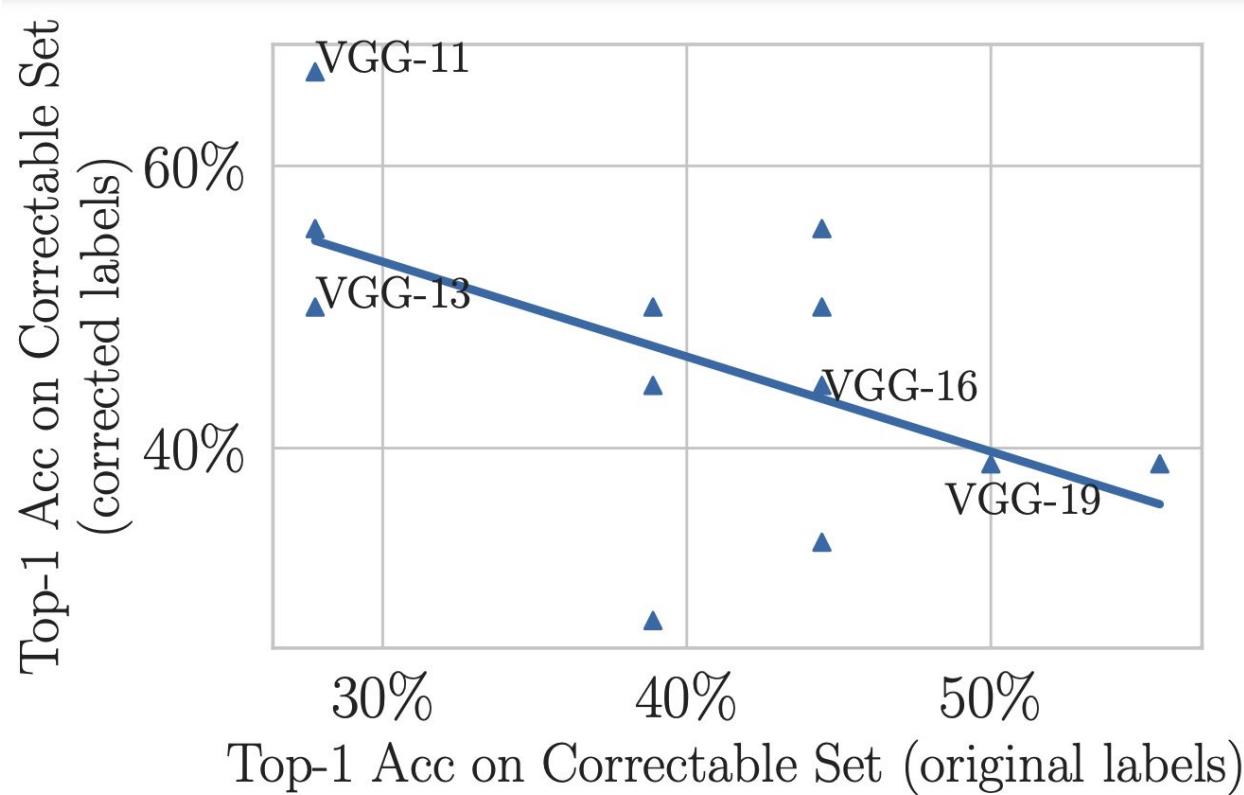
# 34 pre-trained black-box models on ImageNet

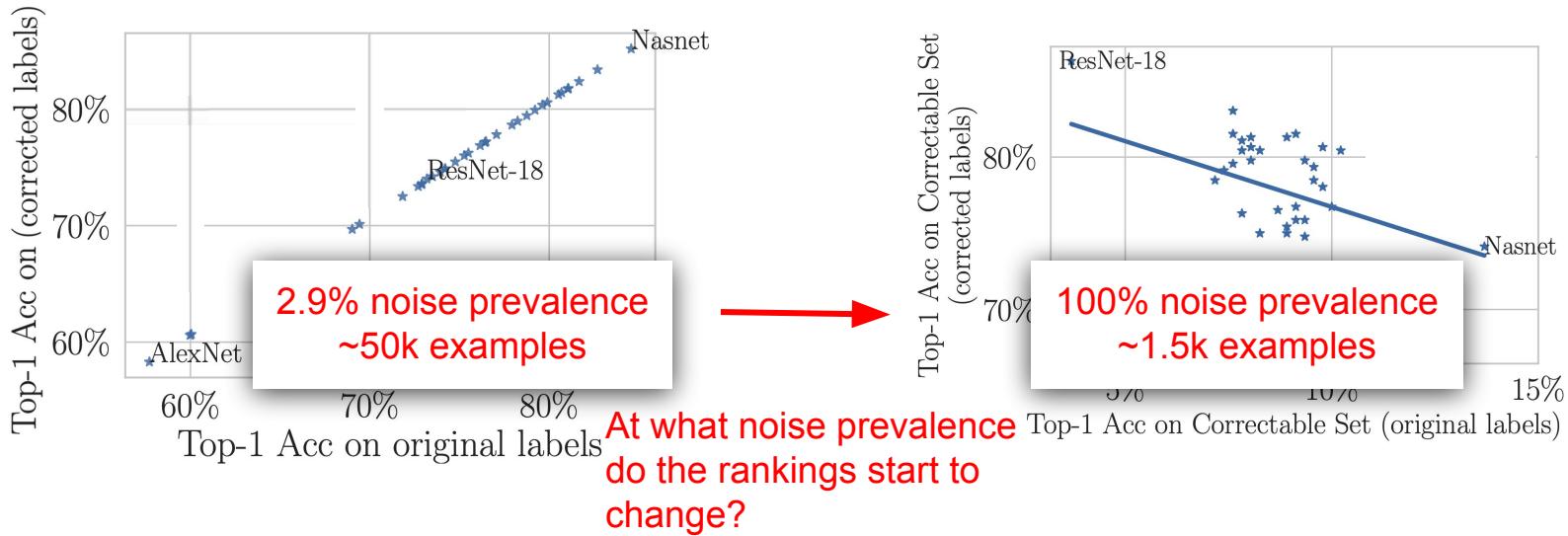


# 34 pre-trained black-box models on ImageNet

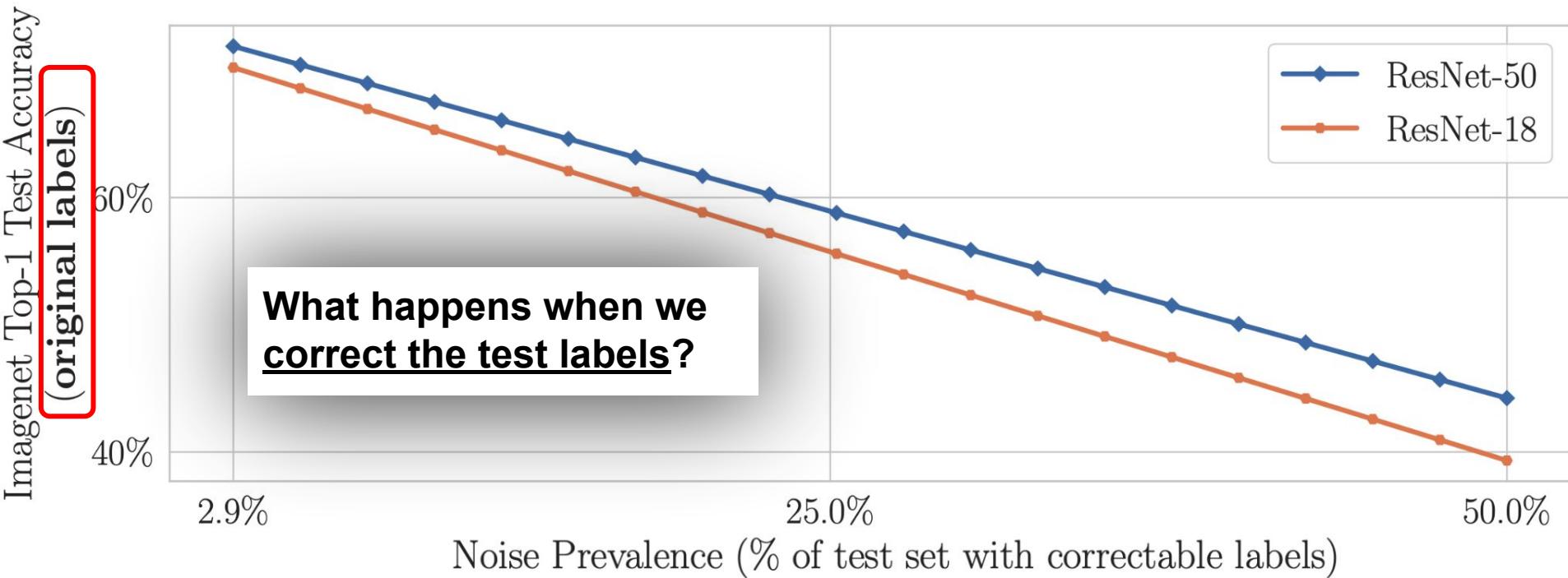


# The same finding, this time on CIFAR-10

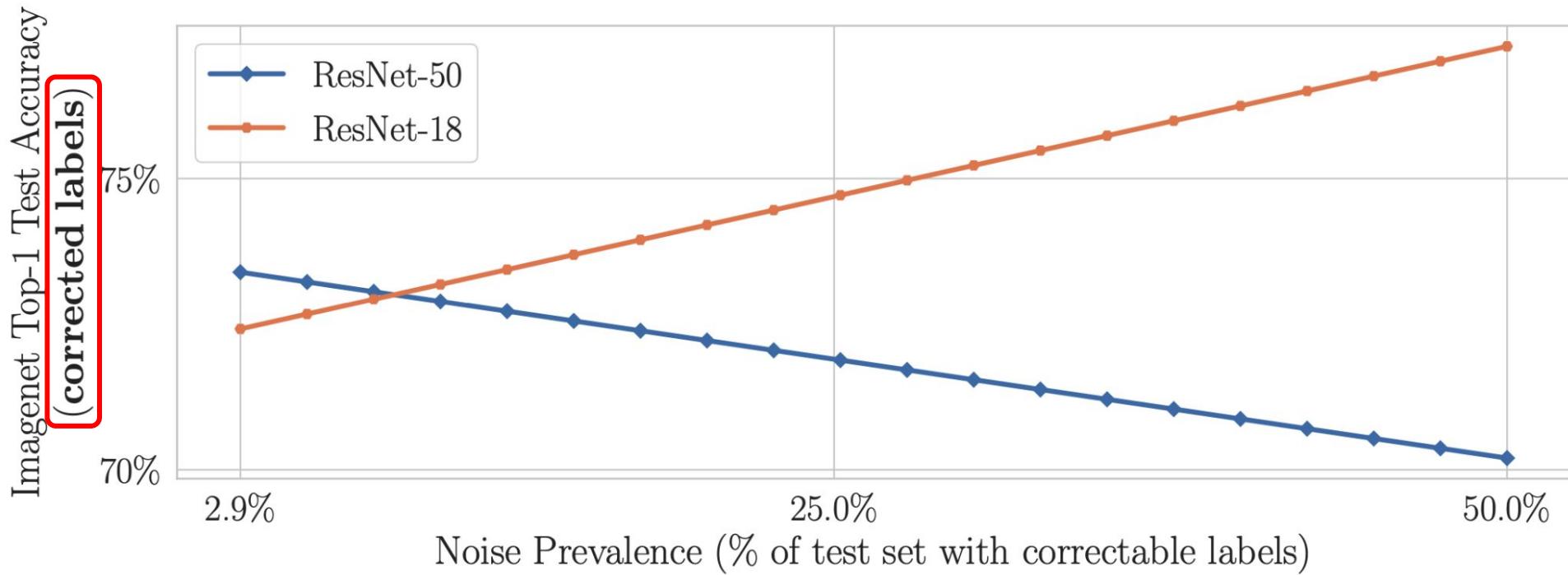




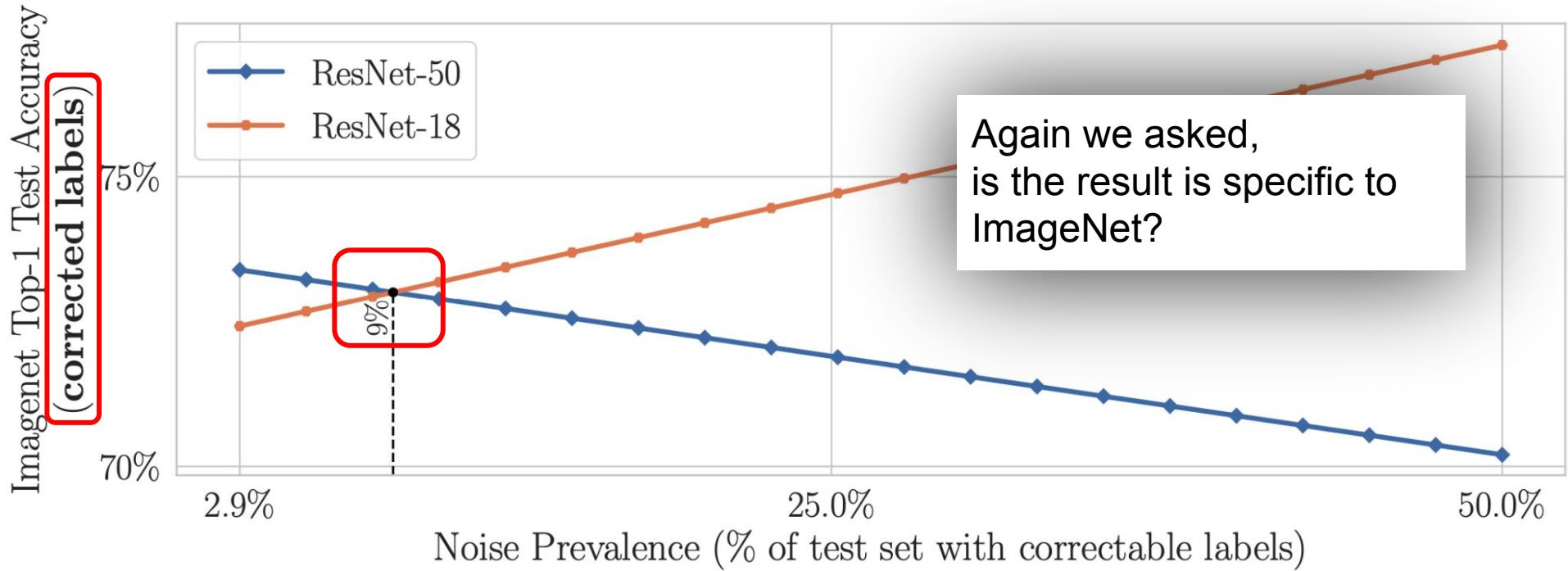
## Two pre-trained ImageNet models tested on original (noisy) labels



## But when we correct the test set, benchmark rankings destabilize



## But when we correct the test set, benchmark rankings destabilize



# *Are practitioners unknowingly benchmarking ML using erroneous test sets?*

## Conclusions

- Model rankings can change with just 6% increase in noise prevalence (even in these highly-curated test sets)
  - ML practitioners cannot know this unless they benchmark with corrected test set labels.
- The fact that simple models regularize (reduce overfitting to label noise) is not surprising. (Li, Socher, & Hoi, 2020)
  - The surprise -- test sets are far noisier than the ML community thought ([labelerrors.com](http://labelerrors.com))
  - An ML practitioner's "best model" may underperform other models in real-world deployment.
- For humans to deploy ML models with confidence -- noise in the test set must be quantified
  - confident learning addresses this problem with realistic sufficient conditions for finding label errors -- and we have shown its efficacy for ten of the most popular ML benchmark test sets.

# Take a break for questions

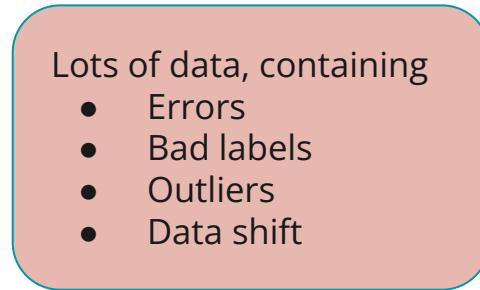
# Confident Learning + Generative AI

We'll consider use cases for:

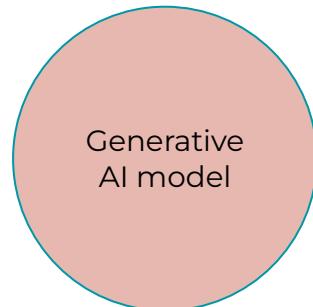
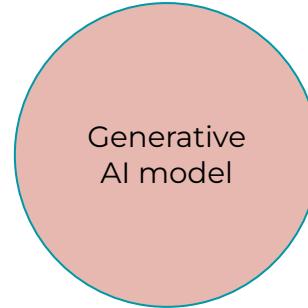
- Image
- Text

# The ‘ins’ and ‘outs’ of Generative AI models

The ‘ins’

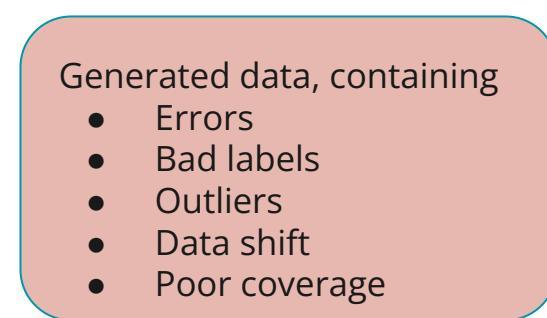


training



inference

The ‘outs’

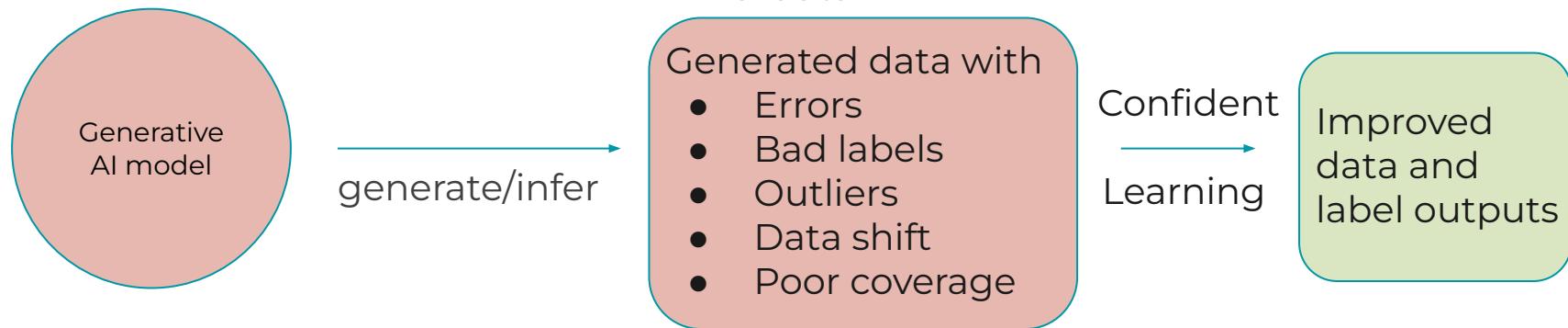


# The ‘ins’ and ‘outs’ of Generative AI models

The ‘ins’

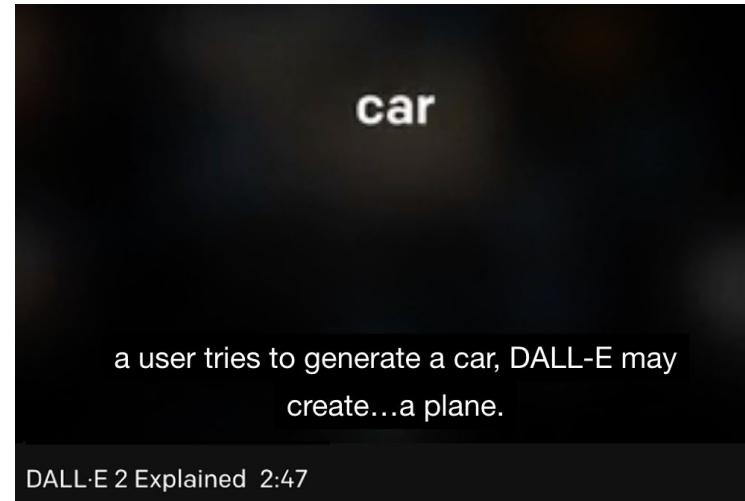
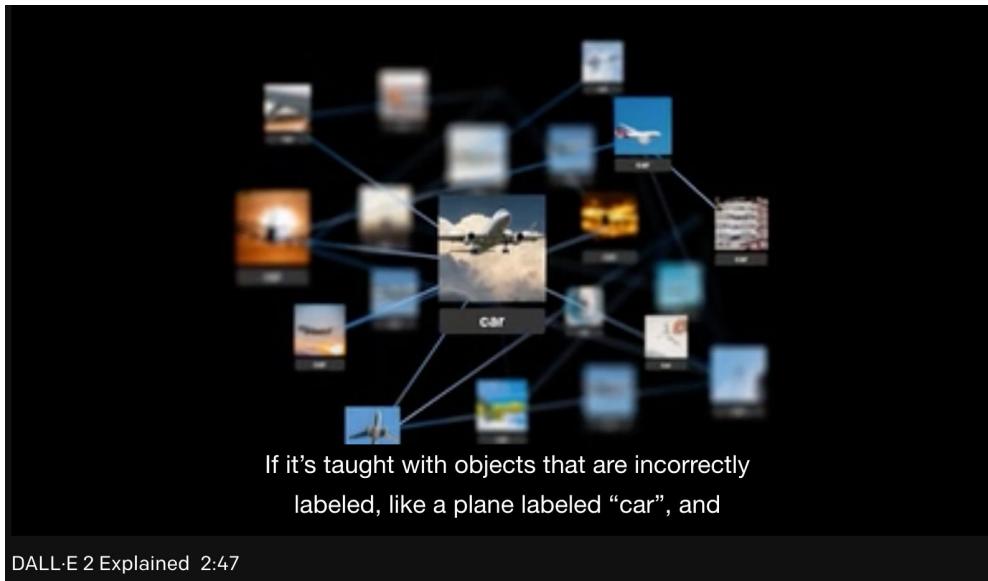


The ‘outs’



# Generative AI: Image (e.g. Dall-E, GPT-4)

For improving reliability in Image generation, ideally run confident learning on the data prior to training to avoid this issue we saw in the first lecture:



# Generative AI: Image (e.g. Dall-E, GPT-4)

If you need to improve outputs from generative AI models, the key is to **work backwards**.

Let's look at an example of a cat/dog generated dataset where we want to improve the reliability of our dataset, post generation.

# Generative AI: Image (e.g. Dall-E, GPT-4)

ChatGPT 4 ▾

You  
Draw me an image of a cat.

ChatGPT



Here's the image of a cute, fluffy cat sitting contentedly on a sunny windowsill.

# Generative AI: Image (e.g. Dall-E, GPT-4)

ChatGPT 4 ▾

You User  
Draw me an image of a dog.

ChatGPT



Here's the image of a dog as you requested.

# Improve dataset post generation

Steps:

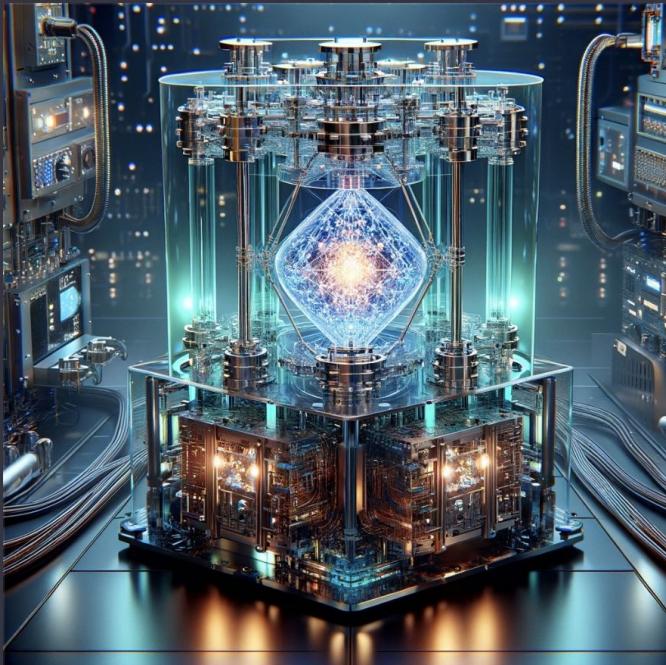
- Generate 1000 cats
- Generate 1000 dogs
- Run the 2000 images through confident learning with the labels (dog, cat) from generation time.
- Auto-remove/fix errors

**In practice, this doesn't matter a lot for cat/dog images, but it does for more challenging images... Let's look at one.**

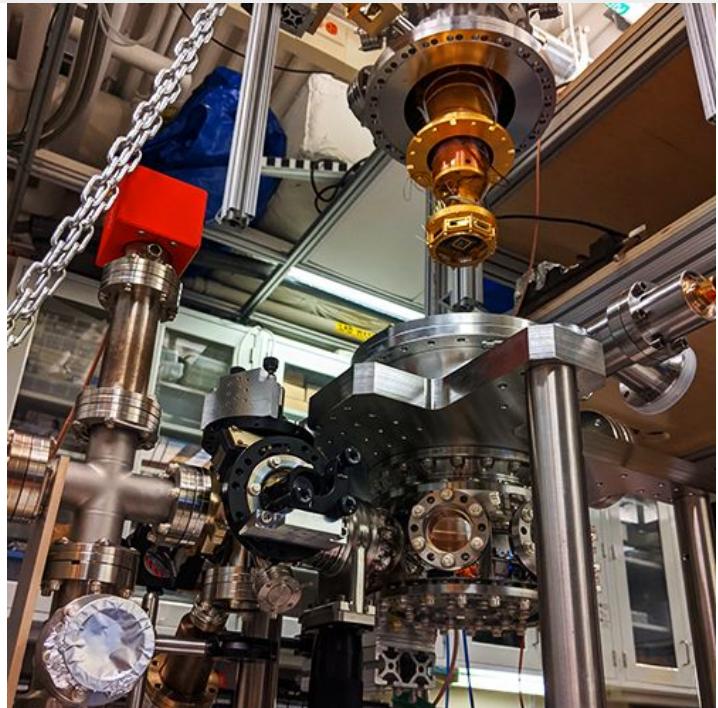
# Improve image dataset – post generation



ChatGPT



Here's the image of an ion trapping quantum computer in a high-tech laboratory setting.



Actual ion trapping quantum computer  
(Ike Chuang lab, MIT)

# Generative AI for Text (e.g. Large Language Models - LLMs)

The same concepts apply as with image. Preferably, improve the data with confident learning prior to training the language model.

In practice, you likely will download an open-source LLM from the internet with no way to retrain a massive 1B+ model yourself from scratch. So reliability/acc improvement will be on inference side.

We'll consider two use cases:

- LLM + RAG + CL
- TLM

# LLM + RAG + CL

What is RAG? Look up answers from a database using an LLM (retrieval augmented generation)

Steps:

1. Use LLM queries to find labels from an imperfect database (1000s of times)
2. Use CL to improve the resulting labels found

# TLM (Trustworthy Language Model)

Goal: Generate a quality/confidence score for every output from a LLM

Demo: (in lecture)

[Link](#).

Ref: (Chen & Mueller, 2023, arXiv)

THIS SLIDE  
INTENTIONALLY LEFT BLANK

# Find label errors in your own dataset (1 import + 1 line of code)

```
● ● ●

from cleanlab.classification import CleanLearning
from cleanlab.filter import find_label_issues

# Option 1 - works with sklearn-compatible models - just input the data and labels
cl = CleanLearning(clf=sklearn_compatible_model)
label_issues_info = cl.find_label_issues(data, labels)

# Option 2 - works with ANY ML model - just input the model's predicted probabilities
ordered_label_issues = find_label_issues(
    labels=labels,
    pred_probs=pred_probs, # out-of-sample predicted probabilities from any model
    return_indices_ranked_by='self_confidence',
)
```

<https://github.com/cleanlab/cleanlab>

# Find data errors in your own dataset (1 import + 1 line of code)

```
from cleanlab.outlier import OutOfDistribution  
  
ood = OutOfDistribution()  
  
# To get outlier scores for train_data using feature matrix train_feature_embeddings  
ood_train_feature_scores = ood.fit_score(features=train_feature_embeddings)  
  
# To get outlier scores for additional test_data using feature matrix test_feature_embeddings  
ood_test_feature_scores = ood.score(features=test_feature_embeddings)  
  
# To get outlier scores for train_data using predicted class probabilities (from a trained  
classifier) and given class labels  
ood_train_predictions_scores = ood.fit_score(pred_probs=train_pred_probs, labels=labels)  
  
# To get outlier scores for additional test_data using predicted class probabilities  
ood_test_predictions_scores = ood.score(pred_probs=test_pred_probs)
```

<https://github.com/cleanlab/cleanlab>

# Find consensus labels for your dataset (1 import + 1 line of code)

```
from cleanlab.multiannotator import get_label_quality_multiannotator  
get_label_quality_multiannotator(multiannotator_labels, pred_probs)
```

<https://github.com/cleanlab/cleanlab>