

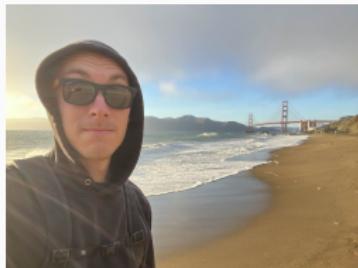
Structure of braid graphs for reduced words in Coxeter groups

NAU DoMS Colloquium

Dana C. Ernst
Northern Arizona University
September 9, 2025

Joint work with A. Attilio, J. Breland, A. Patrick, R. Perry, V. Wilmer

My collaborators



Coxeter systems

Definition

A **Coxeter system** consists of a **Coxeter group** W generated by a set of involutions S together with a function $m : S \times S \rightarrow \mathbb{N} \cup \{\infty\}$ such that for $s \neq t$:

$$m(s, t) = 2 \iff st = ts \quad \left. \right\} \text{ commutation relation}$$

$$\begin{aligned} m(s, t) = 3 &\iff sts = tst \\ m(s, t) = 4 &\iff stst = tstst \\ &\vdots \end{aligned} \quad \left. \right\} \text{ braid relations}$$

Reduced expressions & Matsumoto's Theorem

Definition

A word $\alpha = s_{x_1} s_{x_2} \cdots s_{x_\ell} \in S^*$ is called an **expression** for $w \in W$ if it is equal to w when considered as a group element. If ℓ is minimal among all expressions for w , α is called a **reduced expression**.

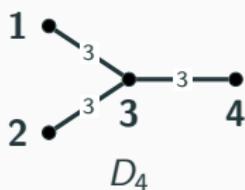
Matsumoto's Theorem

Any two reduced expressions for $w \in W$ differ by a sequence of commutation & braid moves.

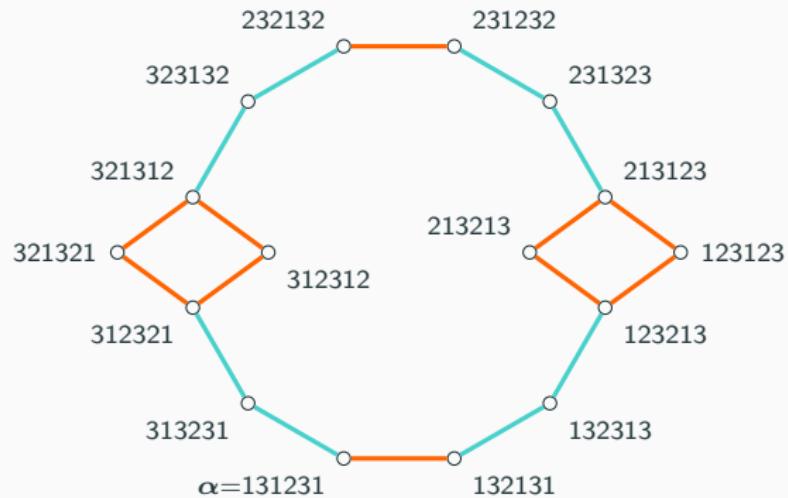
Matsumoto graphs

Example

Consider the reduced expression $\alpha = 131231$ in the Coxeter system of type D_4 .



Coxeter graph



Matsumoto graph

Braid equivalence & braid graphs

Definition

Reduced expressions α and β are **braid equivalent** iff they are related by a sequence of braid moves. The corresponding equivalence classes are called **braid classes**, denoted $[\alpha]$.

Definition

We can encode a braid class $[\alpha]$ in a **braid graph**, denoted $\mathcal{B}(\alpha)$:

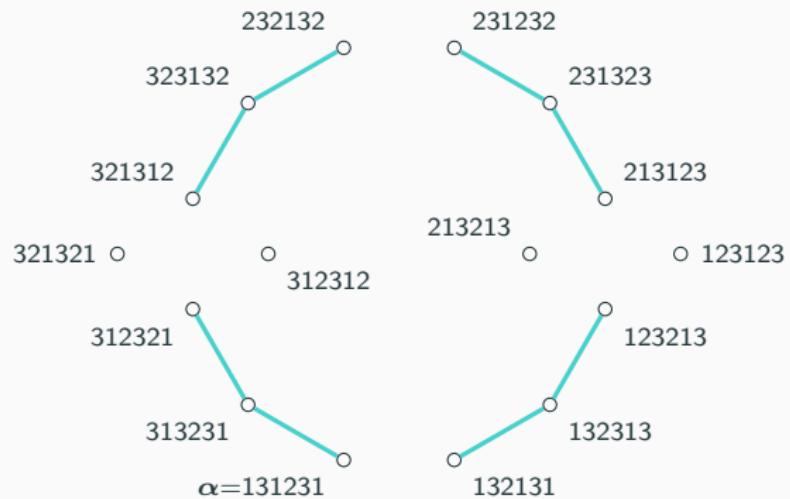
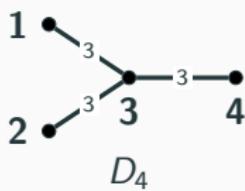
- Vertex set = $[\alpha]$
- $\{\gamma, \beta\}$ is an edge iff γ and β are related via a single **braid move**

Braid graphs are the maximal **blue** connected components in the Matsumoto graph.

Braid graphs

Example

Consider the reduced expression $\alpha = 131231$ in type D_4 from earlier.



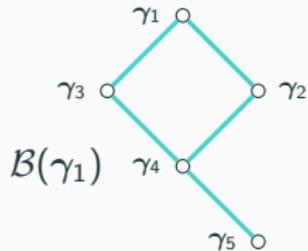
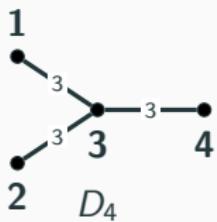
Eight braid graphs

Braid graphs (continued)

Example

In the Coxeter system of type D_4 , the expression $\gamma_1 = 2321434$ is reduced and its braid class consists of the following reduced expressions:

$$\gamma_1 = \underline{2321434}, \gamma_2 = \underline{3231434}, \gamma_3 = \underline{2321343}, \gamma_4 = \underline{32\overline{3}1343}, \gamma_5 = 32\underline{13143}.$$



Example of Fibonacci cube

Braid shadows

Notation

For $i \leq j$, we define the interval

$$\llbracket i, j \rrbracket := \{i, i+1, \dots, j-1, j\}.$$

Definition

Let α be a reduced expression.

- $\llbracket i, j \rrbracket$ is a braid shadow for α if $\alpha_{\llbracket i, j \rrbracket} = \underbrace{st \cdots}_{m(s,t) \geq 3}$
- $\mathcal{S}(\alpha) :=$ set of braid shadows for α
- Collection of braid shadows for braid class $[\alpha]$:

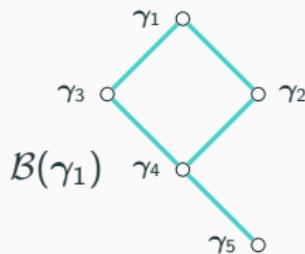
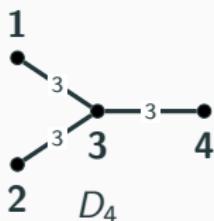
$$\mathcal{S}([\alpha]) := \bigcup_{\beta \in [\alpha]} \mathcal{S}(\beta)$$

- $\text{rank}(\alpha) := |\mathcal{S}([\alpha])|$

Example

Recall the reduced expression $\gamma_1 = 2321434$ in the Coxeter system of type D_4 with braid class:

$$\gamma_1 = \underline{2} \underline{3} \underline{2} \underline{1} \underline{4} \underline{3} \underline{4}, \quad \gamma_2 = \underline{3} \underline{2} \underline{3} \underline{1} \underline{4} \underline{3} \underline{4}, \quad \gamma_3 = \underline{2} \underline{3} \underline{2} \underline{1} \underline{3} \underline{4} \underline{3}, \quad \gamma_4 = \underline{3} \underline{2} \underline{3} \underline{1} \underline{\overline{3}} \underline{4} \underline{3}, \quad \gamma_5 = 321\underline{3}143.$$



We see that

$$\mathcal{S}(\gamma_1) = \{[\![1, 3]\!], [\![5, 7]\!]\} \text{ and } \mathcal{S}([\gamma_1]) = \{[\![1, 3]\!], [\![3, 5]\!], [\![5, 7]\!]\}.$$

Links (continued)

Theorem

Braid shadows are either disjoint or overlap by a single position.

Definition

If α is a reduced expression, then α is a [link](#) provided it either consists of a single generator or

$$\mathcal{S}([\alpha]) = \{\llbracket 1, \ell_1 \rrbracket, \llbracket \ell_1, \ell_2 \rrbracket, \dots, \llbracket \ell_{d-1}, \ell_d \rrbracket\}$$

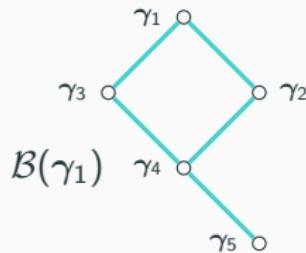
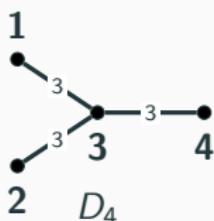
with $1 < \ell_1 < \ell_2 < \dots < \ell_d$.

Links (continued)

Example

Recall the reduced expression $\gamma_1 = 2321434$ in the Coxeter system of type D_4 with braid class:

$$\gamma_1 = \underline{2} \underline{3} \underline{2} \underline{1} \underline{4} \underline{3} \underline{4}, \quad \gamma_2 = \underline{3} \underline{2} \underline{3} \underline{1} \underline{4} \underline{3} \underline{4}, \quad \gamma_3 = \underline{2} \underline{3} \underline{2} \underline{1} \underline{3} \underline{4} \underline{3}, \quad \gamma_4 = \underline{3} \underline{2} \underline{3} \underline{1} \underline{3} \underline{4} \underline{3}, \quad \gamma_5 = 32\underline{1}31\underline{4}3.$$



Recall

$$\mathcal{S}([\gamma_1]) = \{\llbracket 1, 3 \rrbracket, \llbracket 3, 5 \rrbracket, \llbracket 5, 7 \rrbracket\}.$$

So, γ_1 is a link of rank 3.

Link factorizations

Definition

If α is a reduced expression, then β is a link factor of α if:

- β is factor of α ,
- β is a link, and
- β is not a proper factor of a link that is a factor of α .

Theorem

Every reduced expression for a nonidentity group element can be written uniquely as a product of link factors.

For emphasis, we write the link factorization as:

$$\alpha = \beta_1 | \beta_2 | \cdots | \beta_m.$$

Braid graphs for link factorizations

Theorem

If α is reduced expression with link factorization

$$\alpha = \beta_1 | \beta_2 | \cdots | \beta_m,$$

then $\mathcal{B}(\alpha)$ is the box product of the braid graphs for each β_i .

Upshot

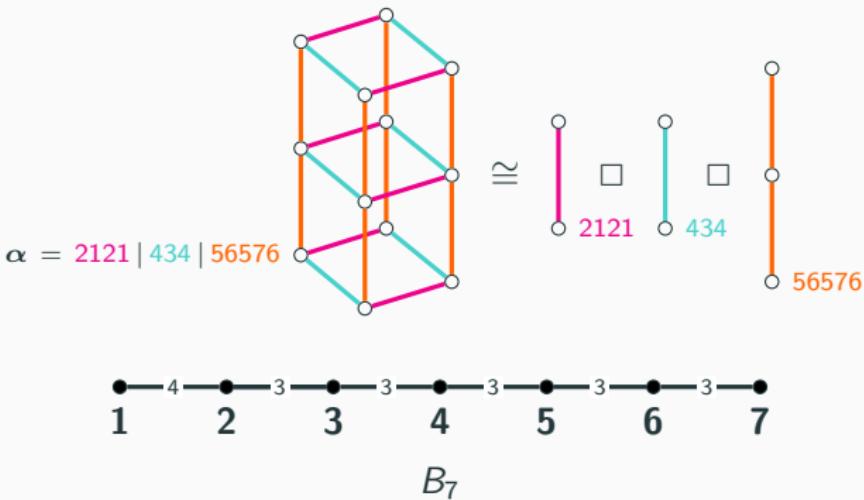
If you want to understand the structure of braid graphs, you can first characterize braid graphs for links.

Braid graphs for link factorizations (continued)

Example

Consider the reduced expression $\alpha = 212143456576$ in type B_7 with link factorization:

$$2121 \mid 434 \mid 56576.$$

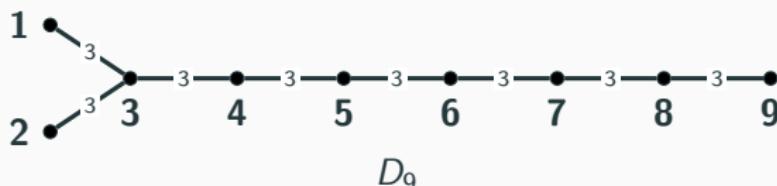
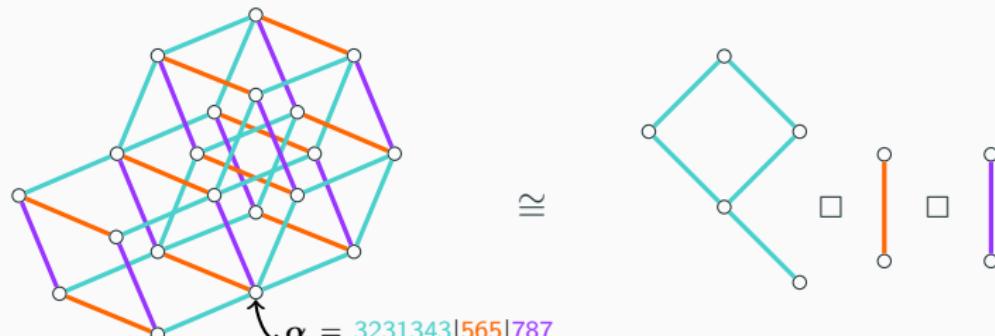


Braid graphs for link factorizations (continued)

Example

Consider the reduced expression $\alpha = 3231343565787$ in type D_9 with link factorization:

$$3231343 \mid 565 \mid 787.$$



Core of a braid shadow

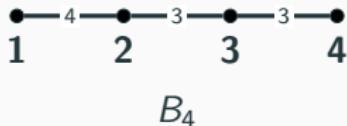
Definition

If $\llbracket i, j \rrbracket$ is the k th braid shadow of $[\alpha]$, then the k th core of α is the factor of α at $\llbracket i+1, j-1 \rrbracket$, denoted $\Theta_k(\alpha)$.

Example

Consider the reduced expression $\beta_1 = 21213243$ in the Coxeter system of type B_4 with braid class:

$$\beta_1 = \underline{2}121\underline{3}243, \quad \beta_2 = 1\underline{2}1\underline{2}\overline{3}243, \quad \beta_3 = 1213\underline{2}\overline{3}\overline{4}3, \quad \beta_4 = 12132\overline{4}\overline{3}4.$$



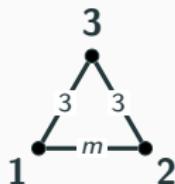
Then for example:

$$\Theta_1(\beta_1) = 12, \quad \Theta_2(\beta_1) = 3, \quad \Theta_3(\beta_1) = 4.$$

Δ_m -avoiding Coxeter systems

Definition

For $m \geq 3$, a Coxeter system (W, S) is $(3, 3, m)$ -avoiding, written Δ_m -avoiding, if its Coxeter graph avoids the following subgraph:



Theorem

If (W, S) is Δ_m -avoiding and α is a link of rank at least one, then $\Theta_k(\beta)$ is an st -string or ts -string for a unique pair s and t for every $\beta \in [\alpha]$.

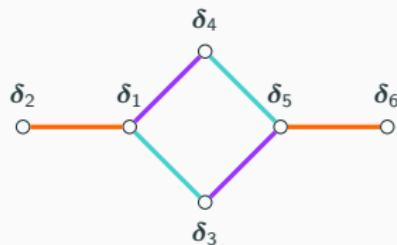
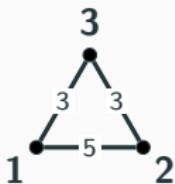
Why Δ_m -avoiding?

Example

Consider the link $\delta_1 = 12121312121$ in the Coxeter system given below with braid class:

$$\delta_1 = \underline{1} \textcolor{teal}{2} \textcolor{teal}{1} \textcolor{teal}{2} \overline{1} \textcolor{orange}{3} \overline{1} \textcolor{purple}{2} \textcolor{purple}{1} \textcolor{purple}{2} \overline{1}, \quad \delta_2 = 1 \textcolor{teal}{2} \textcolor{teal}{1} \textcolor{teal}{2} \overline{3} \overline{1} \textcolor{orange}{3} \textcolor{purple}{2} \textcolor{purple}{1} \textcolor{purple}{2} \overline{1}, \quad \delta_3 = 2 \textcolor{teal}{1} \textcolor{teal}{2} \textcolor{teal}{1} \textcolor{teal}{2} \textcolor{orange}{3} \overline{1} \textcolor{purple}{2} \textcolor{purple}{1} \textcolor{purple}{2} \overline{1}$$

$$\delta_4 = \underline{1} \textcolor{teal}{2} \textcolor{teal}{1} \textcolor{teal}{2} \overline{1} \textcolor{orange}{3} \textcolor{purple}{2} \textcolor{purple}{1} \textcolor{purple}{2}, \quad \delta_5 = 2 \textcolor{teal}{1} \textcolor{teal}{2} \overline{1} \textcolor{orange}{2} \overline{3} \textcolor{purple}{2} \textcolor{purple}{1} \textcolor{purple}{2}, \quad \delta_6 = 2 \textcolor{teal}{1} \textcolor{teal}{2} \textcolor{teal}{1} \textcolor{orange}{3} \overline{2} \overline{3} \textcolor{purple}{1} \textcolor{purple}{2} \textcolor{purple}{1} \textcolor{purple}{2}$$



Links are uniquely determined by cores

Theorem

Suppose (W, S) is Δ_m -avoiding and let α and β be braid equivalent links.
Then $\alpha = \beta$ iff $\Theta_k(\alpha) = \Theta_k(\beta)$ for all k .

Example

Recall the reduced expression $\beta_1 = 21213243$ in the Coxeter system of type B_4 with braid class:

$$\beta_1 = \underline{2} \underline{1} \underline{2} \underline{1} \underline{3} \underline{2} \underline{4} \underline{3}, \quad \beta_2 = \underline{1} \underline{2} \underline{1} \overline{2} \overline{3} \overline{2} \underline{4} \underline{3}, \quad \beta_3 = \underline{1} \underline{2} \underline{1} \underline{3} \underline{2} \overline{3} \overline{4} \underline{3}, \quad \beta_4 = \underline{1} \underline{2} \underline{1} \underline{3} \underline{2} \underline{4} \overline{3} \overline{4}$$

$$\overbrace{(12, 3, 4)} \qquad \overbrace{(21, 3, 4)} \qquad \overbrace{(21, 2, 4)} \qquad \overbrace{(21, 2, 3)}$$



B_4

Observation

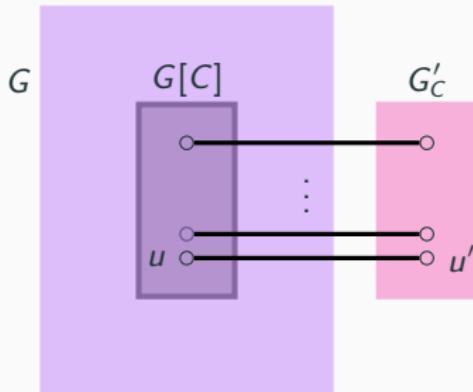
In Δ_m -avoiding Coxeter systems, $|\mathcal{B}(\alpha)| \leq 2^{\text{rank}(\alpha)}$.

Convex expansions

Definition

Given a graph G and a convex set $C \subseteq V(G)$, we define the **expanded graph relative to C** :

- Start with a graph G ;
- Make an isomorphic copy of $G[C]$, denoted G'_C , where each $u \in C$ corresponds to $u' \in C' := V(G'_C)$;
- For each $u \in C$, join u and u' with an edge.



Median graphs

Definition

A graph is **median** if every three vertices x, y, z have a unique median: a vertex $\text{med}(x, y, z)$ that belongs to geodesics between each pair.

Proposition (Mulder)

A graph is **median** iff it can be obtained from a single vertex by a sequence of convex expansions.

Example

o

Median graphs

Definition

A graph is **median** if every three vertices x, y, z have a unique median: a vertex $\text{med}(x, y, z)$ that belongs to geodesics between each pair.

Proposition (Mulder)

A graph is **median** iff it can be obtained from a single vertex by a sequence of convex expansions.

Example



Median graphs

Definition

A graph is **median** if every three vertices x, y, z have a unique median: a vertex $\text{med}(x, y, z)$ that belongs to geodesics between each pair.

Proposition (Mulder)

A graph is **median** iff it can be obtained from a single vertex by a sequence of convex expansions.

Example



Median graphs

Definition

A graph is **median** if every three vertices x, y, z have a unique median: a vertex $\text{med}(x, y, z)$ that belongs to geodesics between each pair.

Proposition (Mulder)

A graph is **median** iff it can be obtained from a single vertex by a sequence of convex expansions.

Example



Median graphs

Definition

A graph is **median** if every three vertices x, y, z have a unique median: a vertex $\text{med}(x, y, z)$ that belongs to geodesics between each pair.

Proposition (Mulder)

A graph is **median** iff it can be obtained from a single vertex by a sequence of convex expansions.

Example



Median graphs

Definition

A graph is **median** if every three vertices x, y, z have a unique median: a vertex $\text{med}(x, y, z)$ that belongs to geodesics between each pair.

Proposition (Mulder)

A graph is **median** iff it can be obtained from a single vertex by a sequence of convex expansions.

Example



Median graphs

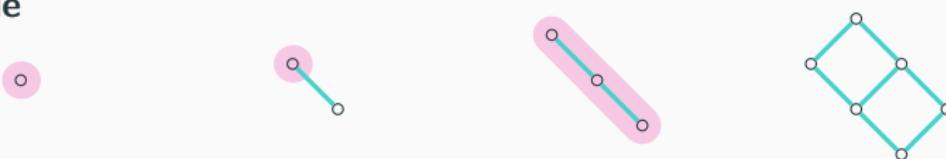
Definition

A graph is **median** if every three vertices x, y, z have a unique median: a vertex $\text{med}(x, y, z)$ that belongs to geodesics between each pair.

Proposition (Mulder)

A graph is **median** iff it can be obtained from a single vertex by a sequence of convex expansions.

Example



Median graphs

Definition

A graph is **median** if every three vertices x, y, z have a unique median: a vertex $\text{med}(x, y, z)$ that belongs to geodesics between each pair.

Proposition (Mulder)

A graph is **median** iff it can be obtained from a single vertex by a sequence of convex expansions.

Example



Median graphs

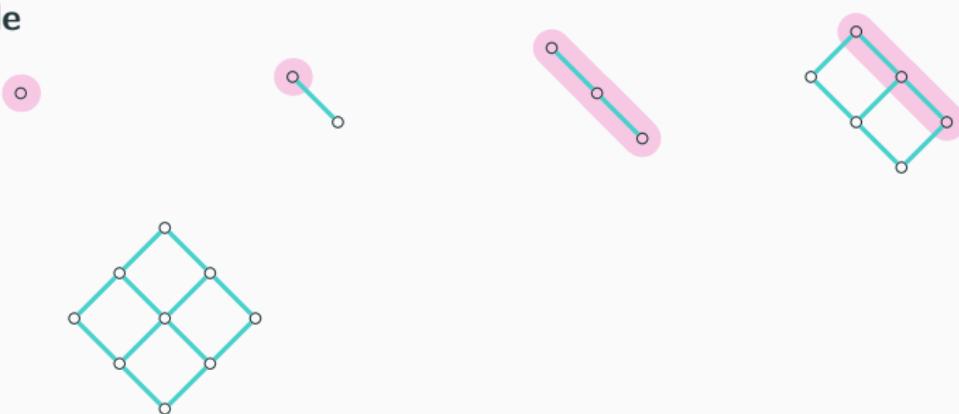
Definition

A graph is **median** if every three vertices x, y, z have a unique median: a vertex $\text{med}(x, y, z)$ that belongs to geodesics between each pair.

Proposition (Mulder)

A graph is **median** iff it can be obtained from a single vertex by a sequence of convex expansions.

Example



Median graphs

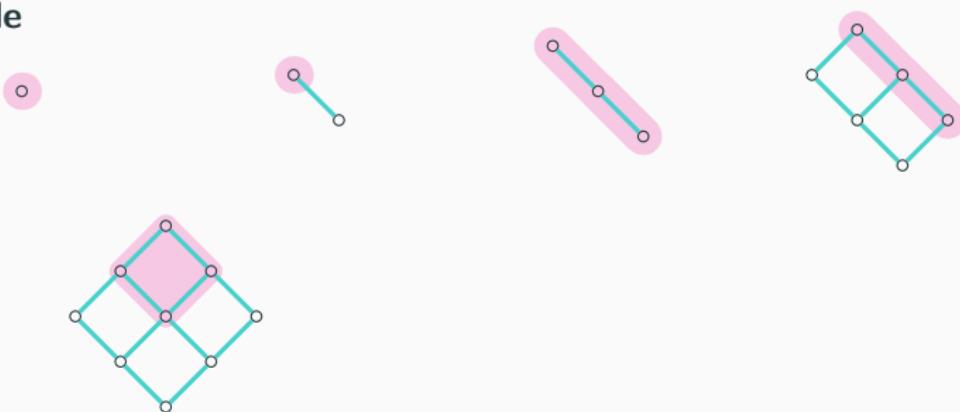
Definition

A graph is **median** if every three vertices x, y, z have a unique median: a vertex $\text{med}(x, y, z)$ that belongs to geodesics between each pair.

Proposition (Mulder)

A graph is **median** iff it can be obtained from a single vertex by a sequence of convex expansions.

Example



Median graphs

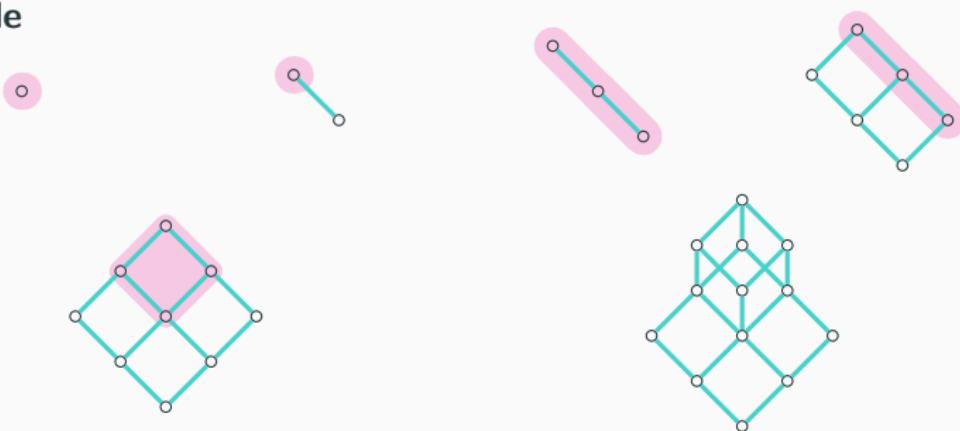
Definition

A graph is **median** if every three vertices x, y, z have a unique median: a vertex $\text{med}(x, y, z)$ that belongs to geodesics between each pair.

Proposition (Mulder)

A graph is **median** iff it can be obtained from a single vertex by a sequence of convex expansions.

Example



Convex expansions



Earth, Moon, & Shadow

Definition

Suppose (W, S) is Δ_m -avoiding and α is a link of rank $r \geq 2$, and let $\sigma \in [\alpha]$ such that the two rightmost braid shadows exist in σ . Define

$\hat{\sigma} :=$ “chop off at left edge of last core in σ ”.

For example: $\sigma = 212\overline{323}2 \Rightarrow \hat{\sigma} = 212$.

Earth := $\{\beta \in [\alpha] \mid \Theta_r(\beta) = \Theta_r(\sigma)\}$

$\hat{\text{Earth}} := [\hat{\sigma}]$

Moon := $\{\beta \in [\alpha] \mid \Theta_r(\beta) \neq \Theta_r(\sigma)\}$

Shadow := $\{\beta \in \text{Earth} \mid \text{rightmost braid shadow exists in } \beta\}$

For simplicity, we refer to the corresponding induced subgraphs using the same names.

Earth, Moon, & Shadow are convex

Theorem

Suppose (W, S) is Δ_m -avoiding and α is a link of rank at least two.

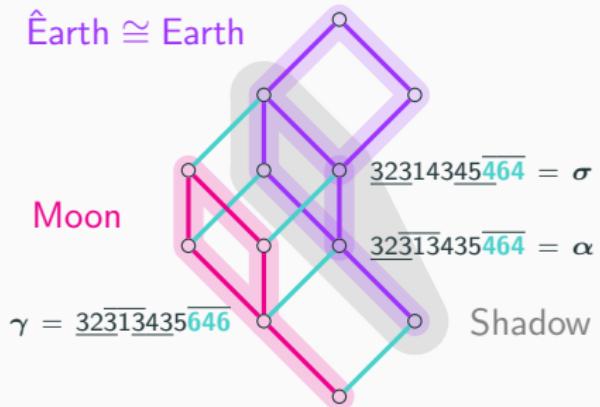
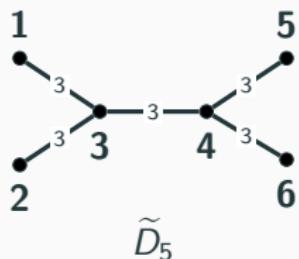
Choose $\sigma \in [\alpha]$ according to previous definition. Then

- Earth, Moon, and Shadow are convex.
- $\hat{\sigma}$ is a link with rank one less than σ .
- $\beta \in \text{Earth}$ iff $\hat{\beta} \in \hat{\text{Earth}} = [\hat{\sigma}]$.
- $\hat{\text{Earth}} \xrightarrow{\text{isometric}} \mathcal{B}(\alpha)$ with $\hat{\text{Earth}} \cong \text{Earth}$
- Shadow \cong Moon

Visualizing Earth, Moon, & Shadow

Example

Consider the link $\alpha = 32313435464$ in the Coxeter system of type \tilde{D}_5 .



Braid graphs for links are median

Theorem

If (W, S) is Δ_m -avoiding and α is a link, then $\mathcal{B}(\alpha)$ is median.

Outline of Proof

- We induct on rank. Base cases check out.
- Choose $\sigma \in [\alpha]$ with the last two braid shadows locally available.
- By induction, $\text{Earth} \cong \hat{\text{Earth}}$ is median.
- $\mathcal{B}(\alpha)$ is obtained from Earth via a convex expansion relative to Shadow .

Braid graphs for reduced expressions are median

Proposition

If graphs G_1 and G_2 are median, then $G_1 \square G_2$ is also median.

Theorem

If (W, S) is Δ_m -avoiding and α a reduced expression, then $\mathcal{B}(\alpha)$ is median. The median of any three reduced expressions is computed by taking majority across sequence of cores.

Corollary

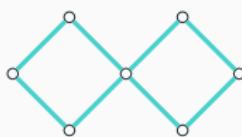
If (W, S) is Δ_m -avoiding and α a reduced expression, then $\mathcal{B}(\alpha)$ is

- a partial cube with isometric dimension equal to rank (also equal to diameter);
- the one-skeleton of a CAT(0) cube complex.

Not every median graph arises as a braid graph

Example

Not every median graph can be realized as the braid graph for a reduced expression!



Braid graphs are “special” median graphs. What is “special” ???

Geodesics between diametrical reduced expressions

Theorem

If (W, S) is Δ_m -avoiding and α is a link, then there exists a unique diametrical pair of reduced expressions in $[\alpha]$. Moreover, every reduced expression in $[\alpha]$ occurs on a geodesic between the diametrical pair.

Note

Not true for general reduced expressions!

Braid graphs as the Hasse diagram of a partial order

Suppose (W, S) is Δ_m -avoiding and α is a link of rank $r \geq 1$.

- Identify diametrical pair μ and γ and choose μ to be the designated smallest vertex
- Define $\beta < \sigma$ if there exists a unique i such that $\Theta_i(\beta) \neq \Theta_i(\sigma)$ and $d(\mu, \beta) + 1 = d(\mu, \sigma)$.
- Let $\mathcal{P}(\mu) := ([\alpha], \leq)$ be the partial order induced by these covering relations.

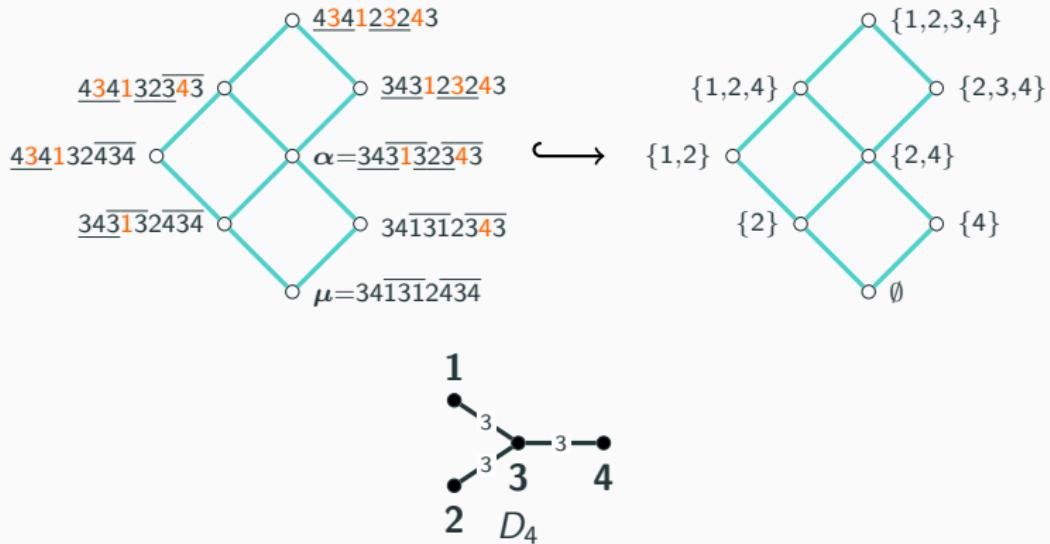
Theorem

If (W, S) is Δ_m -avoiding and α is a reduced expression, then $\mathcal{B}(\alpha)$ is the underlying graph for the Hasse diagram of $\mathcal{P}(\mu)$.

Braid graphs as the Hasse diagram of a partial order

Example

Consider the link $\alpha = 343132343$ in the Coxeter system of type D_4 .



Braid graphs as the Hasse diagram of a distributive lattice

Theorem

If (W, S) is Δ_m -avoiding and α is a reduced expression, then $\mathcal{B}(\alpha)$ is the underlying graph for the Hasse diagram of a distributive lattice.

Note

Not every distributive lattice arises in this way!

Future work & open problems

- Not every underlying graph for the Hasse diagram of a distributive lattice corresponds to a braid graph in a Δ_m -avoiding Coxeter system. What additional restrictions do these braid graphs have? Can we completely characterize them?
- Deal with the pesky Δ_m -avoiding obstruction! We conjecture that every braid graph is median and the underlying graph for the Hasse diagram of a distributive lattice.
- If α and β are commutation-related in a Δ_m -avoiding Coxeter system, then how are $\mathcal{B}(\alpha)$ and $\mathcal{B}(\beta)$ related? As a special case, what if α and β are related by a single commutation move?