

On a Nonlocal Finite Element Model for Mode-III Brittle Fracture with Surface-Tension Excess Property

S. M. Mallikarjunaiah

Department of Mathematics
Texas A&M University
College Station, TX



Overview

- 1 Notation and Preliminaries
- 2 Mode-III Fracture Model with Surface-Tension Excess Property
- 3 Reformulation of Jump Momentum Balance Boundary Condition
- 4 Nonlocal Finite Element Method
- 5 Numerical Results
- 6 References

Notation and preliminaries

- Let \mathbf{X} be any arbitrary point in the reference configuration and \mathbf{x} denotes the corresponding point in the deformed configuration.

Notation and preliminaries

- Let \mathbf{X} be any arbitrary point in the reference configuration and \mathbf{x} denotes the corresponding point in the deformed configuration.
- Then the mapping $\mathbf{x} = \mathbf{f}(\mathbf{X})$ represents the motion of the body.

Notation and preliminaries

- Let \mathbf{X} be any arbitrary point in the reference configuration and \mathbf{x} denotes the corresponding point in the deformed configuration.
- Then the mapping $\mathbf{x} = \mathbf{f}(\mathbf{X})$ represents the motion of the body.
- $\mathbf{u} := \mathbf{x} - \mathbf{X}$

Notation and preliminaries

- Let \mathbf{X} be any arbitrary point in the reference configuration and \mathbf{x} denotes the corresponding point in the deformed configuration.
- Then the mapping $\mathbf{x} = \mathbf{f}(\mathbf{X})$ represents the motion of the body.
- $\mathbf{u} := \mathbf{x} - \mathbf{X}$
- $\mathbf{F} := \frac{\partial \mathbf{f}}{\partial \mathbf{X}} = \mathbf{I} + \nabla \mathbf{u}$

Notation and preliminaries

- Let \mathbf{X} be any arbitrary point in the reference configuration and \mathbf{x} denotes the corresponding point in the deformed configuration.
- Then the mapping $\mathbf{x} = \mathbf{f}(\mathbf{X})$ represents the motion of the body.
- $\mathbf{u} := \mathbf{x} - \mathbf{X}$
- $\mathbf{F} := \frac{\partial \mathbf{f}}{\partial \mathbf{X}} = \mathbf{I} + \nabla \mathbf{u}$
- $\mathbf{B} := \mathbf{F}\mathbf{F}^T$, and $\mathbf{C} := \mathbf{F}^T\mathbf{F}$

Notation and preliminaries

- Let \mathbf{X} be any arbitrary point in the reference configuration and \mathbf{x} denotes the corresponding point in the deformed configuration.
- Then the mapping $\mathbf{x} = \mathbf{f}(\mathbf{X})$ represents the motion of the body.
- $\mathbf{u} := \mathbf{x} - \mathbf{X}$
- $\mathbf{F} := \frac{\partial \mathbf{f}}{\partial \mathbf{X}} = \mathbf{I} + \nabla \mathbf{u}$
- $\mathbf{B} := \mathbf{F}\mathbf{F}^T$, and $\mathbf{C} := \mathbf{F}^T\mathbf{F}$
- $\mathbf{E} = \frac{1}{2}(\mathbf{C} - \mathbf{I})$

Notation and preliminaries

- Let \mathbf{X} be any arbitrary point in the reference configuration and \mathbf{x} denotes the corresponding point in the deformed configuration.
- Then the mapping $\mathbf{x} = \mathbf{f}(\mathbf{X})$ represents the motion of the body.
- $\mathbf{u} := \mathbf{x} - \mathbf{X}$
- $\mathbf{F} := \frac{\partial \mathbf{f}}{\partial \mathbf{X}} = \mathbf{I} + \nabla \mathbf{u}$
- $\mathbf{B} := \mathbf{F}\mathbf{F}^T$, and $\mathbf{C} := \mathbf{F}^T\mathbf{F}$
- $\mathbf{E} = \frac{1}{2}(\mathbf{C} - \mathbf{I})$
- $\boldsymbol{\epsilon} = \frac{1}{2}(\nabla \mathbf{u} + \nabla \mathbf{u}^T)$

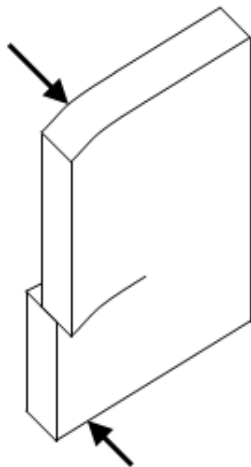
Notation and preliminaries

- Let \mathbf{X} be any arbitrary point in the reference configuration and \mathbf{x} denotes the corresponding point in the deformed configuration.
- Then the mapping $\mathbf{x} = \mathbf{f}(\mathbf{X})$ represents the motion of the body.
- $\mathbf{u} := \mathbf{x} - \mathbf{X}$
- $\mathbf{F} := \frac{\partial \mathbf{f}}{\partial \mathbf{X}} = \mathbf{I} + \nabla \mathbf{u}$
- $\mathbf{B} := \mathbf{F}\mathbf{F}^T$, and $\mathbf{C} := \mathbf{F}^T\mathbf{F}$
- $\mathbf{E} = \frac{1}{2}(\mathbf{C} - \mathbf{I})$
- $\boldsymbol{\epsilon} = \frac{1}{2}(\nabla \mathbf{u} + \nabla \mathbf{u}^T)$
- If we linearize using the assumption of displacement gradients are small, we can approximate \mathbf{E} and $\boldsymbol{\epsilon}$. Then there is no distinction between reference and deformed configuration.

Mode-III Fracture

The Mode-III fracture (or anti-plane shear fracture):

- The fracture surfaces slide relative to each other skew-symmetrically with shear stress acting as shown in the figure.
- Displacement:
 - $u_1 = 0$ and $u_2 = 0$
 - $u_3 = u_3(x_1, x_2)$



Classical LEFM model

The classical Linearized Elastic Fracture Mechanics (LEFM) model has two well known inconsistencies:

Classical LEFM model

The classical Linearized Elastic Fracture Mechanics (LEFM) model has two well known inconsistencies:

- It predict singular crack-tip strains and stresses.

Classical LEFM model

The classical Linearized Elastic Fracture Mechanics (LEFM) model has two well known inconsistencies:

- It predict singular crack-tip strains and stresses.
- Also it predicts an elliptical crack-surface opening displacement with a blunt crack-tip.

Classical LEFM model

The classical Linearized Elastic Fracture Mechanics (LEFM) model has two well known inconsistencies:

- It predict singular crack-tip strains and stresses.
- Also it predicts an elliptical crack-surface opening displacement with a blunt crack-tip.

Thus, several remedies have been attempted: appealing to a non-linear theory of elasticity, the introduction of a cohesive zone around the crack tip and non-local theories.

Mode-III Brittle Fracture Problem Formulation

The problem studied here is the straight, static, anti-plane shear crack, lying on $|x_1| < a$, $x_2 = 0$ in an infinite, isotropic, linear elastic body subjected to uniform far-field anti-plane shear loading (σ_{23}^∞). The stress-strain relations are:

$$\tau_{23} = \mu \frac{\partial u_3}{\partial x_2} \quad \text{and} \quad \tau_{13} = \mu \frac{\partial u_3}{\partial x_1},$$

where τ_{23} and τ_{13} are the relevant stress components, and u_3 denotes the z -displacement.

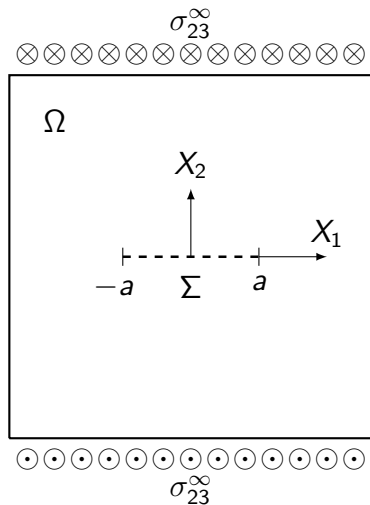


Figure: Physical description of the problem.

Mode-III fracture problem formulation

To derive the governing equations for this problem, we follow the study of Sendova and Walton¹.

¹T. Sendova and J. R. Walton, A New Approach to the Modeling & Analysis of Fracture through an Extension of Continuum Mechanics to the Nanoscale. *Math. Mech. Solids*, 15(3), 368-413, 2010.

Mode-III fracture problem formulation

To derive the governing equations for this problem, we follow the study of Sendova and Walton¹.

The equilibrium equation, without the body force term, is the Laplace equation for u_3

$$-\Delta u_3 = 0.$$

¹T. Sendova and J. R. Walton, A New Approach to the Modeling & Analysis of Fracture through an Extension of Continuum Mechanics to the Nanoscale. *Math. Mech. Solids*, 15(3), 368-413, 2010.

Mode-III fracture problem formulation

To derive the governing equations for this problem, we follow the study of Sendova and Walton¹.

The equilibrium equation, without the body force term, is the Laplace equation for u_3

$$-\Delta u_3 = 0.$$

Then we consider a surface tension model which depend on (linearized) curvature of the out-of-plane displacement by:

$$\gamma = \gamma_0 + \gamma_1 u_{3,11}(x_1, 0),$$

where γ_0 and γ_1 are surface tension parameters.

¹T. Sendova and J. R. Walton, A New Approach to the Modeling & Analysis of Fracture through an Extension of Continuum Mechanics to the Nanoscale. *Math. Mech. Solids*, 15(3), 368-413, 2010.

Mode-III fracture problem formulation

To derive the governing equations for this problem, we follow the study of Sendova and Walton¹.

The equilibrium equation, without the body force term, is the Laplace equation for u_3

$$-\Delta u_3 = 0.$$

Then we consider a surface tension model which depend on (linearized) curvature of the out-of-plane displacement by:

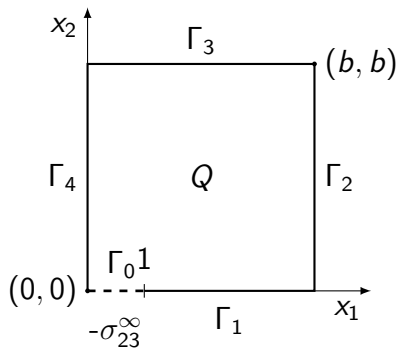
$$\gamma = \gamma_0 + \gamma_1 u_{3,11}(x_1, 0),$$

where γ_0 and γ_1 are surface tension parameters. Then the resulting boundary condition on the upper crack-surface is give by:

$$u_{3,2}(x_1, 0) = -\gamma_1 u_{3,111}(x_1, 0)$$

¹T. Sendova and J. R. Walton, A New Approach to the Modeling & Analysis of Fracture through an Extension of Continuum Mechanics to the Nanoscale. *Math. Mech. Solids*, 15(3), 368-413, 2010.

Mode-III fracture BVP



$$-\Delta u_3(x_1, x_2) = 0, \quad \text{in } Q$$

Boundary conditions:

$$\text{on } \Gamma_0 \quad u_{3,2}(x_1, 0) = -\sigma_{23}^{\infty} - \gamma_1 u_{3,111},$$

$$\text{on } \Gamma_1 \quad u_3 = 0,$$

$$\text{on } \Gamma_2 \quad \vec{n} \cdot \nabla u_3 = 0,$$

$$\text{on } \Gamma_3 \quad \vec{n} \cdot \nabla u_3 = 0,$$

$$\text{on } \Gamma_4 \quad \vec{n} \cdot \nabla u_3 = 0.$$

Figure: Finite computational domain Q .

Weak Formulation and Numerical Strategy

Appealing to the BVP, the weak formulation for the problem on hand is found by integrating the PDE against a test function v over Ω . This yields

$$\int_Q \nabla v \cdot \nabla u_3 \, dQ - \int_{\partial Q} v (\vec{n} \cdot \nabla u_3) \, d\partial Q = 0.$$

Weak Formulation and Numerical Strategy

Appealing to the BVP, the weak formulation for the problem on hand is found by integrating the PDE against a test function v over Ω . This yields

$$\int_Q \nabla v \cdot \nabla u_3 \, dQ - \int_{\partial Q} v (\vec{n} \cdot \nabla u_3) \, d\partial Q = 0.$$

There is no contribution from the second term on the left-hand side of the above equation except over the crack-surface Γ_0 .

Weak Formulation and Numerical Strategy

Appealing to the BVP, the weak formulation for the problem on hand is found by integrating the PDE against a test function v over Ω . This yields

$$\int_Q \nabla v \cdot \nabla u_3 dQ - \int_{\partial Q} v (\vec{n} \cdot \nabla u_3) d\partial Q = 0.$$

There is no contribution from the second term on the left-hand side of the above equation except over the crack-surface Γ_0 . Therefore the resulting weak formulation takes the form

$$\int_Q \nabla u_3 \cdot \nabla v dQ - \int_{\Gamma_0} v u_{3,2}(x_1, 0) dx_1 = 0 ,$$

Reformulation of the Crack-Face Boundary Condition

We consider the crack-surface boundary condition and rearrange the equation to obtain

$$-u_{3,111}(x_1, 0) = \frac{1}{\gamma_1} [u_{3,2}(x_1, 0) + \sigma_{23}^{\infty}] \quad \text{on } \Gamma_0 .$$

Reformulation of the Crack-Face Boundary Condition

We consider the crack-surface boundary condition and rearrange the equation to obtain

$$-u_{3,111}(x_1, 0) = \frac{1}{\gamma_1} [u_{3,2}(x_1, 0) + \sigma_{23}^{\infty}] \quad \text{on } \Gamma_0 .$$

$$\mathcal{L}\{u_{3,1}\} = \frac{1}{\gamma_1} [u_{3,2}(x_1, 0) + \sigma_{23}^{\infty}] ,$$

Reformulation of the Crack-Face Boundary Condition

We consider the crack-surface boundary condition and rearrange the equation to obtain

$$-u_{3,111}(x_1, 0) = \frac{1}{\gamma_1} [u_{3,2}(x_1, 0) + \sigma_{23}^{\infty}] \quad \text{on } \Gamma_0 .$$

$$\mathcal{L}\{u_{3,1}\} = \frac{1}{\gamma_1} [u_{3,2}(x_1, 0) + \sigma_{23}^{\infty}] ,$$

- $u_3(x_1, x_2)$ is an odd function in x_2 , therefore $u_{3,1}(0, 0) = 0$.

Reformulation of the Crack-Face Boundary Condition

We consider the crack-surface boundary condition and rearrange the equation to obtain

$$-u_{3,111}(x_1, 0) = \frac{1}{\gamma_1} [u_{3,2}(x_1, 0) + \sigma_{23}^{\infty}] \quad \text{on } \Gamma_0 .$$

$$\mathcal{L}\{u_{3,1}\} = \frac{1}{\gamma_1} [u_{3,2}(x_1, 0) + \sigma_{23}^{\infty}] ,$$

- $u_3(x_1, x_2)$ is an odd function in x_2 , therefore $u_{3,1}(0, 0) = 0$.
- Also regularization on $\Gamma_0 \cup \Gamma_1$ requires $u_{3,1}(1, 0) = 0$.

Reformulation of the Crack-Face Boundary Condition

Then the solution to the two point boundary value problem is given by

$$u_{3,1}(x, 0) = \mathcal{G}\{f\}(x) := \int_0^1 G(x, q)f(q)dq.$$

Reformulation of the Crack-Face Boundary Condition

Then the solution to the two point boundary value problem is given by

$$u_{3,1}(x, 0) = \mathcal{G}\{f\}(x) := \int_0^1 G(x, q)f(q)dq.$$

$$\begin{aligned} u_{3,1}(x, 0) &= \frac{1}{\gamma_1} \int_0^1 G(x, q)[u_{3,2}(q, 0) + \sigma_{23}^\infty] dq \\ &= \frac{1}{\gamma_1} \int_0^1 G(x, q) u_{3,2}(q, 0) dq - \frac{\sigma_{23}^\infty}{2\gamma_1} x(1 - x). \end{aligned}$$

Reformulation of the Crack-Face Boundary Condition

Then the solution to the two point boundary value problem is given by

$$u_{3,1}(x, 0) = \mathcal{G}\{f\}(x) := \int_0^1 G(x, q)f(q)dq.$$

$$\begin{aligned} u_{3,1}(x, 0) &= \frac{1}{\gamma_1} \int_0^1 G(x, q)[u_{3,2}(q, 0) + \sigma_{23}^\infty] dq \\ &= \frac{1}{\gamma_1} \int_0^1 G(x, q) u_{3,2}(q, 0) dq - \frac{\sigma_{23}^\infty}{2\gamma_1} x(1 - x). \end{aligned}$$

Now, we know that the Hilbert transform gives the Dirichlet-to-Neumann map, ie

$$\begin{aligned} u_{3,2}(x, 0^+) &= \mathcal{H}\{u_{3,1}\} \\ &= \frac{1}{\pi} \int_{-\infty}^{\infty} u_{3,1}(q, 0^+) \frac{dq}{q - x} \\ &= \frac{1}{\pi} \int_0^1 u_{3,1}(q, 0^+) \frac{2q}{q^2 - x^2} dq, \end{aligned}$$

Reformulation of the Crack-Face Boundary Condition

$$u_{3,2}(x, 0) = \frac{1}{\pi\gamma_1} \int_0^1 k(x, q) u_{3,2}(q, 0) dq - \frac{\sigma_{23}^\infty}{2\pi\gamma_1} g(x), \quad \text{on } \Gamma_0,$$

Reformulation of the Crack-Face Boundary Condition

$$u_{3,2}(x, 0) = \frac{1}{\pi\gamma_1} \int_0^1 k(x, q) u_{3,2}(q, 0) dq - \frac{\sigma_{23}^\infty}{2\pi\gamma_1} g(x), \quad \text{on } \Gamma_0,$$

where $k(x, q)$ and $g(x)$ are given by:

$$\begin{aligned} k(x, q) = & (q + x) \ln(q + x) + (q - x) \ln|q - x| \\ & - q(1 + x) \ln(1 + x) - q(1 - x) \ln|1 - x| \end{aligned}$$

$$g(x) = 1 - x(1 + x) \ln\left(\frac{1 + x}{x}\right) + x(1 - x) \ln\left|\frac{1 - x}{x}\right|$$

Reformulation of the Crack-Face Boundary Condition

Applying this result to the earlier *Weak-Form* yields the final weak form

$$\begin{aligned} \int_Q \nabla u_3 \cdot \nabla v + \frac{1}{\pi \gamma_1} \int_0^1 v(x, 0) \int_0^1 k(x, q) u_{3,2}(q, 0) dq dx \\ = \frac{\sigma_{23}^\infty}{2\pi \gamma_1} \int_0^1 v(x, 0) g(x) dx. \end{aligned}$$

Note that this weak form has no higher-order derivatives, thus the standard FEM can now be applied.

Theorem

The Fredholm integral equation

$$\gamma_1 u(x) - \mathcal{K}[u](x) = -\frac{\sigma_{23}^{\infty}}{2\pi} g(x), \quad \text{for } 0 \leq x \leq 1,$$

where \mathcal{K} is the integral operator

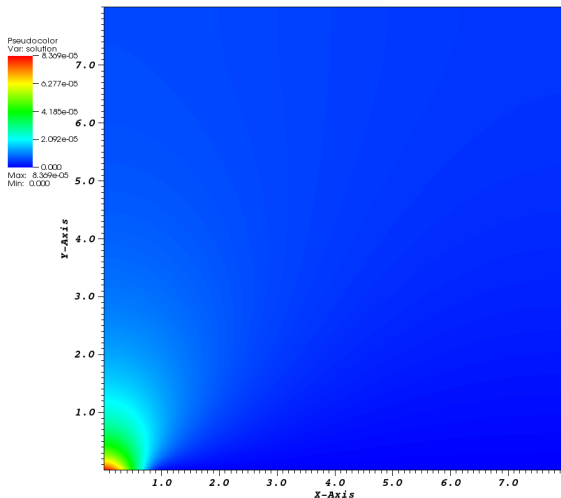
$$\mathcal{K}[\psi](x) = \frac{1}{\pi} \int_0^1 k(x, q) \psi(q) dq,$$

has a unique, continuous solution for all but countably many values of γ_1 .

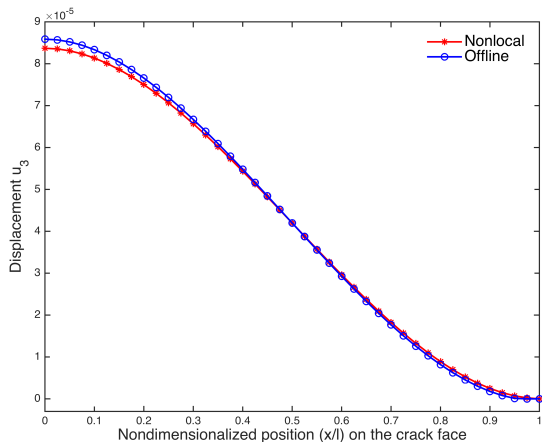
Where $k(x, q)$ is given by:

$$\begin{aligned} k(x, q) = & (q + x) \ln(q + x) + (q - x) \ln|q - x| \\ & - q(1 + x) \ln(1 + x) - q(1 - x) \ln|1 - x| \end{aligned}$$

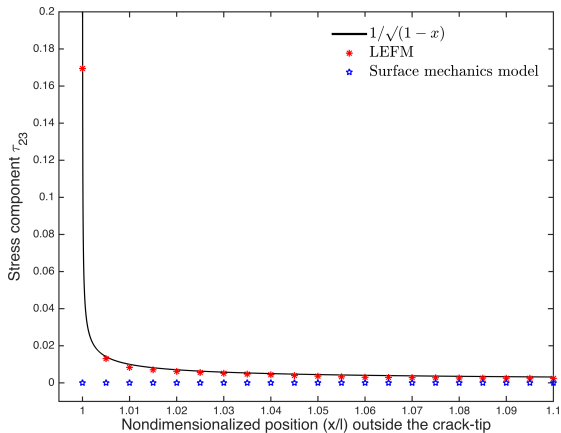
Numerical Results: Displacement



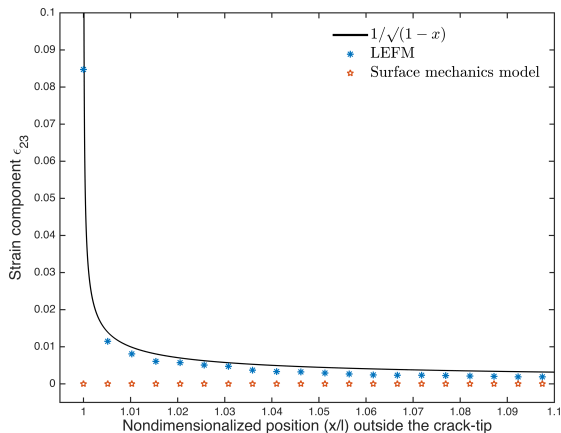
Numerical Results: Crack-Face Displacement



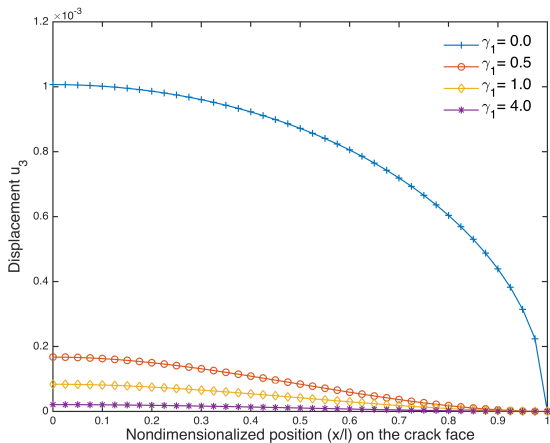
Numerical Results: Near-Tip Stress τ_{23}



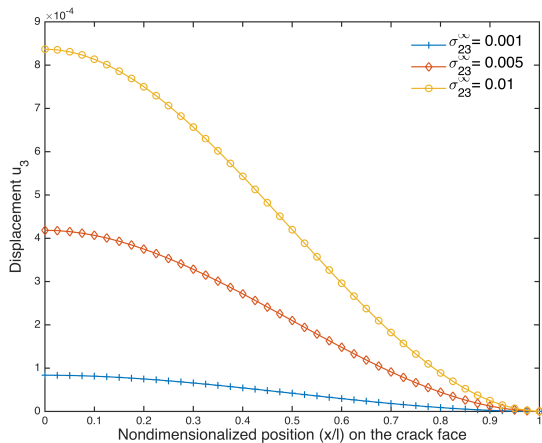
Numerical Results: Near-Tip Strain ϵ_{23}



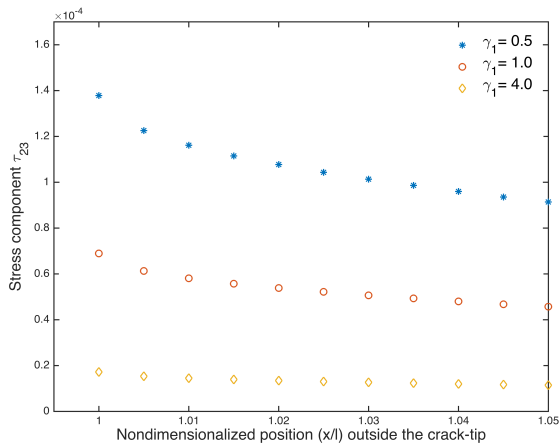
Numerical Results: Crack-Face Displacement



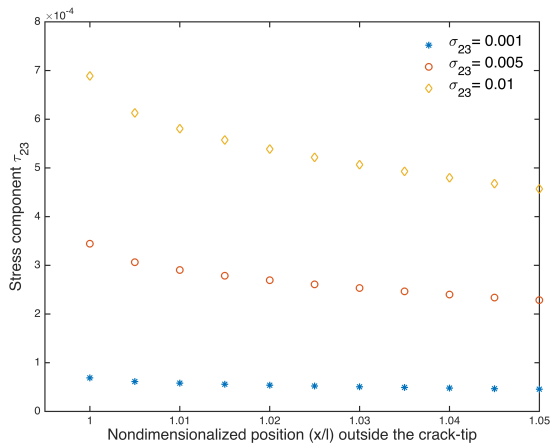
Numerical Results: Near-Tip Stress τ_{23}



Numerical Results: Near-Tip Stress τ_{23}



Numerical Results: Near-Tip Stress τ_{23}



Summary

- We have successfully demonstrated an approach for the direct numerical implementation of the surface tension class of continuum-surface methods using FEM in the case of mode-III fracture.

Summary

- We have successfully demonstrated an approach for the direct numerical implementation of the surface tension class of continuum-surface methods using FEM in the case of mode-III fracture.
- We showed that the two FEM implementations agree well with each other. In particular, the model predicts bounded crack-tip stresses (also strains) and a cusp-like crack opening profile with a sharp crack-tip.

- We have successfully demonstrated an approach for the direct numerical implementation of the surface tension class of continuum-surface methods using FEM in the case of mode-III fracture.
- We showed that the two FEM implementations agree well with each other. In particular, the model predicts bounded crack-tip stresses (also strains) and a cusp-like crack opening profile with a sharp crack-tip.
- We are currently developing a corresponding implementation of both pure mode-I and mixed-mode (combination of mode-I and mode-II) fracture.

References



W. Bangerth, R. Hartmann and G. Kanschat.
deal.II – a General Purpose Object Oriented Finite Element Library,
ACM Trans. Math. Softw., 33(4):24/1–24/27, 2007.



W. Bangerth, T. Heister, L. Heltai, G. Kanschat, M. Kronbichler, M. Maier, B. Turcksin, T. D. Young.
The deal.II Library, Version 8.1, arXiv preprint,
<http://arxiv.org/abs/1312.2266v4>.



T. Sendova and J. R. Walton.
A New Approach to the Modeling & Analysis of Fracture through an Extension of
Continuum Mechanics to the Nanoscale.
Math. Mech. Solids, 15(3), 368-413, 2010.



L. Ferguson, S. M. Mallikarjunaiah and J. R. Walton.
Numerical simulation of mode-III fracture incorporating interfacial mechanics.
International Journal of Fracture, 192, 47-56, 2015.



J. R. Walton.
A note on fracture models incorporating surface elasticity.
Journal of Elasticity, 109(1), 95-102, 2012.

THANK YOU