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                                libs.tmpl.txt
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<book id="Reed-Solomon-Library-Guide">
  <bookinfo>
    <title>Reed-Solomon Library Programming Interface</title>

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  <toc></toc>

  <chapter id="intro">

```

<title>Introduction</title>

<para>

The generic Reed-Solomon Library provides encoding, decoding and error correction functions.

</para>

<para>

Reed-Solomon codes are used in communication and storage applications to ensure data integrity.

</para>

<para>

This documentation is provided for developers who want to utilize the functions provided by the library.

</para>

</chapter>

<chapter id="bugs">

<title>Known Bugs And Assumptions</title>

<para>

None.

</para>

</chapter>

<chapter id="usage">

<title>Usage</title>

<para>

This chapter provides examples of how to use the library.

</para>

<sect1>

<title>Initializing</title>

<para>

The init function `init_rs` returns a pointer to an rs decoder structure, which holds the necessary information for encoding, decoding and error correction with the given polynomial. It either uses an existing matching decoder or creates a new one. On creation all the lookup tables for fast en/decoding are created. The function may take a while, so make sure not to call it in critical code paths.

</para>

<programlisting>

/* the Reed Solomon control structure */

static struct rs_control *rs_decoder;

/* Symbolsize is 10 (bits)

* Primitive polynomial is $x^{10}+x^3+1$

* first consecutive root is 0

* primitive element to generate roots = 1

* generator polynomial degree (number of roots) = 6

*/

rs_decoder = init_rs (10, 0x409, 0, 1, 6);

</programlisting>

</sect1>

<sect1>

<title>Encoding</title>

<para>

The encoder calculates the Reed-Solomon code over

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                                librs.tmpl.txt
                                the given data length and stores the result in
                                the parity buffer. Note that the parity buffer must
                                be initialized before calling the encoder.
</para>
<para>
is
                                The expanded data can be inverted on the fly by
                                providing a non-zero inversion mask. The expanded data
                                XOR'ed with the mask. This is used e.g. for FLASH
                                ECC, where the all 0xFF is inverted to an all 0x00.
                                The Reed-Solomon code for all 0x00 is all 0x00. The
                                code is inverted before storing to FLASH so it is 0xFF
                                too. This prevents that reading from an erased FLASH
                                results in ECC errors.
</para>
<para>
                                The databytes are expanded to the given symbol size
                                on the fly. There is no support for encoding continuous
                                bitstreams with a symbol size != 8 at the moment. If
                                it is necessary it should be not a big deal to implement
                                such functionality.
</para>
<programlisting>
/* Parity buffer. Size = number of roots */
uint16_t par[6];
/* Initialize the parity buffer */
memset(par, 0, sizeof(par));
/* Encode 512 byte in data8. Store parity in buffer par */
encode_rs8 (rs_decoder, data8, 512, par, 0);
</programlisting>
</sect1>
<sect1>
<title>Decoding</title>
<para>
                                The decoder calculates the syndrome over
                                the given data length and the received parity symbols
                                and corrects errors in the data.
</para>
<para>
                                If a syndrome is available from a hardware decoder
                                then the syndrome calculation is skipped.
</para>
<para>
                                The correction of the data buffer can be suppressed
                                by providing a correction pattern buffer and an error
                                location buffer to the decoder. The decoder stores the
                                calculated error location and the correction bitmask
                                in the given buffers. This is useful for hardware
                                decoders which use a weird bit ordering scheme.
</para>
<para>
                                The databytes are expanded to the given symbol size
                                on the fly. There is no support for decoding continuous
                                bitstreams with a symbolsize != 8 at the moment. If
                                it is necessary it should be not a big deal to implement
                                such functionality.

```

</para>

<sect2>

<title>

Decoding with syndrome calculation, direct data

correction

</title>

<programlisting>

/* Parity buffer. Size = number of roots */

uint16_t par[6];

uint8_t data[512];

int numerr;

/* Receive data */

.....

/* Receive parity */

.....

/* Decode 512 byte in data8.*/

numerr = decode_rs8(rs_decoder, data8, par, 512, NULL, 0, NULL, 0, NULL);

</programlisting>

</sect2>

<sect2>

<title>

Decoding with syndrome given by hardware decoder, direct

data correction

</title>

<programlisting>

/* Parity buffer. Size = number of roots */

uint16_t par[6], syn[6];

uint8_t data[512];

int numerr;

/* Receive data */

.....

/* Receive parity */

.....

/* Get syndrome from hardware decoder */

.....

/* Decode 512 byte in data8.*/

numerr = decode_rs8(rs_decoder, data8, par, 512, syn, 0, NULL, 0, NULL);

</programlisting>

</sect2>

<sect2>

<title>

Decoding with syndrome given by hardware decoder, no

direct data correction.

</title>

<para>

Note: It's not necessary to give data and received parity to the decoder.

</para>

<programlisting>

/* Parity buffer. Size = number of roots */

uint16_t par[6], syn[6], corr[8];

uint8_t data[512];

int numerr, errpos[8];

```

/* Receive data */
.....
/* Receive parity */
.....
/* Get syndrome from hardware decoder */
.....
/* Decode 512 byte in data8.*/
numerr = decode_rs8 (rs_decoder, NULL, NULL, 512, syn, 0, errpos, 0, corr);
for (i = 0; i &lt; numerr; i++) {
    do_error_correction_in_your_buffer(errpos[i], corr[i]);
}

```

</programlisting>

</sect2>

</sect1>

<sect1>

<title>Cleanup</title>

<para>

The function free_rs frees the allocated resources,
if the caller is the last user of the decoder.

</para>

<programlisting>

```

/* Release resources */
free_rs(rs_decoder);

```

</programlisting>

</sect1>

</chapter>

<chapter id="structs">

<title>Structures</title>

<para>

This chapter contains the autogenerated documentation of the structures
which are

used in the Reed-Solomon Library and are relevant for a developer.

</para>

!Iinclude/linux/rslib.h

</chapter>

<chapter id="pubfunctions">

<title>Public Functions Provided</title>

<para>

This chapter contains the autogenerated documentation of the Reed-Solomon
functions

which are exported.

</para>

!Elib/reed_solomon/reed_solomon.c

</chapter>

<chapter id="credits">

<title>Credits</title>

<para>

The library code for encoding and decoding was written by Phil
Karn.

</para>

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(GPL)

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<para>

The wrapper functions and interfaces are written by Thomas

Gleixner.

</para>

<para>

Many users have provided bugfixes, improvements and helping hands for testing.

Thanks a lot.

</para>

<para>

The following people have contributed to this document:

</para>

<para>

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</para>

</chapter>

</book>