

# gdbmacros.txt

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# This file contains a few gdb macros (user defined commands) to extract
# useful information from kernel crashdump (kdump) like stack traces of
# all the processes or a particular process and trapinfo.
#
# These macros can be used by copying this file in .gdbinit (put in home
# directory or current directory) or by invoking gdb command with
# --command=<command-file-name> option
#
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#

define bttnobp
    set $tasks_off=((size_t)&((struct task_struct *)0)->tasks)
    set $pid_off=((size_t)&((struct task_struct *)0)->pids[1].pid_list.next)
    set $init_t=&init_task
    set $next_t=((char *)($init_t->tasks).next) - $tasks_off
    while ($next_t != $init_t)
        set $next_t=(struct task_struct *)$next_t
        printf "\npid %d; comm %s:\n", $next_t.pid, $next_t.comm
        printf "=====\n"
        set var $stackp = $next_t.thread.esp
        set var $stack_top = ($stackp & ~4095) + 4096

        while ($stackp < $stack_top)
            if (*($stackp) > _stext && *($stackp) < _sinittext)
                info symbol *($stackp)
            end
            set $stackp += 4
        end
        set $next_th=((char *)$next_t->pids[1].pid_list.next) -
$pid_off)
        while ($next_th != $next_t)
            set $next_th=(struct task_struct *)$next_th
            printf "\npid %d; comm %s:\n", $next_t.pid, $next_t.comm
            printf "=====\n"
            set var $stackp = $next_t.thread.esp
            set var $stack_top = ($stackp & ~4095) + 4096

            while ($stackp < $stack_top)
                if (*($stackp) > _stext && *($stackp) <
_sinittext)
                    info symbol *($stackp)
                end
                set $stackp += 4
            end
            set $next_th=((char *)$next_th->pids[1].pid_list.next)
- $pid_off)
        end
        set $next_t=(char *)($next_t->tasks.next) - $tasks_off
    end
end
document bttnobp
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                                gdbmacros.txt
    dump all thread stack traces on a kernel compiled with
!CONFIG_FRAME_POINTER
end

define btt
    set $tasks_off=((size_t)&((struct task_struct *)0)->tasks)
    set $pid_off=((size_t)&((struct task_struct *)0)->pids[1].pid_list.next)
    set $init_t=&init_task
    set $next_t=((char *)($init_t->tasks).next) - $tasks_off
    while ($next_t != $init_t)
        set $next_t=(struct task_struct *)$next_t
        printf "\npid %d; comm %s:\n", $next_t.pid, $next_t.comm
        printf "===== \n"
        set var $stackp = $next_t.thread.esp
        set var $stack_top = ($stackp & ~4095) + 4096
        set var $stack_bot = ($stackp & ~4095)

        set $stackp = *($stackp)
        while (($stackp < $stack_top) && ($stackp > $stack_bot))
            set var $addr = *($stackp + 4)
            info symbol $addr
            set $stackp = *($stackp)
        end

        set $next_th=((char *)$next_t->pids[1].pid_list.next) -
$pid_off)
        while ($next_th != $next_t)
            set $next_th=(struct task_struct *)$next_th
            printf "\npid %d; comm %s:\n", $next_t.pid, $next_t.comm
            printf "===== \n"
            set var $stackp = $next_t.thread.esp
            set var $stack_top = ($stackp & ~4095) + 4096
            set var $stack_bot = ($stackp & ~4095)

            set $stackp = *($stackp)
            while (($stackp < $stack_top) && ($stackp > $stack_bot))
                set var $addr = *($stackp + 4)
                info symbol $addr
                set $stackp = *($stackp)
            end
            set $next_th=((char *)$next_th->pids[1].pid_list.next)
- $pid_off)
        end
        set $next_t=(char *)($next_t->tasks.next) - $tasks_off
    end
end
document btt
    dump all thread stack traces on a kernel compiled with
CONFIG_FRAME_POINTER
end

define btpid
    set var $pid = $arg0
    set $tasks_off=((size_t)&((struct task_struct *)0)->tasks)
    set $pid_off=((size_t)&((struct task_struct *)0)->pids[1].pid_list.next)
    set $init_t=&init_task

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                                gdbmacros.txt
set $next_t=((char *)($init_t->tasks).next) - $tasks_off)
set var $pid_task = 0

while ($next_t != $init_t)
    set $next_t=(struct task_struct *)$next_t

    if ($next_t.pid == $pid)
        set $pid_task = $next_t
    end

    set $next_th=((char *)$next_t->pids[1].pid_list.next) -
$pid_off)
    while ($next_th != $next_t)
        set $next_th=(struct task_struct *)$next_th
        if ($next_th.pid == $pid)
            set $pid_task = $next_th
        end
        set $next_th=((char *)$next_th->pids[1].pid_list.next)
- $pid_off)
    end
    set $next_t=(char *)($next_t->tasks.next) - $tasks_off
end

printf "\npid %d; comm %s:\n", $pid_task.pid, $pid_task.comm
printf "===== \n"
set var $stackp = $pid_task.thread.esp
set var $stack_top = ($stackp & ~4095) + 4096
set var $stack_bot = ($stackp & ~4095)

set $stackp = *($stackp)
while (($stackp < $stack_top) && ($stackp > $stack_bot))
    set var $addr = *($stackp + 4)
    info symbol $addr
    set $stackp = *($stackp)
end

end
document btpid
    backtrace of pid
end

define trapinfo
    set var $pid = $arg0
    set $tasks_off=((size_t)&((struct task_struct *)0)->tasks)
    set $pid_off=((size_t)&((struct task_struct *)0)->pids[1].pid_list.next)
    set $init_t=&init_task
    set $next_t=((char *)($init_t->tasks).next) - $tasks_off)
    set var $pid_task = 0

    while ($next_t != $init_t)
        set $next_t=(struct task_struct *)$next_t

        if ($next_t.pid == $pid)
            set $pid_task = $next_t
        end
    end
end

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                                gdbmacros.txt
                                set $next_th=((char *)$next_t->pids[1].pid_list.next) -
$pid_off)
                                while ($next_th != $next_t)
                                    set $next_th=(struct task_struct *)$next_th
                                    if ($next_th.pid == $pid)
                                        set $pid_task = $next_th
                                    end
                                    set $next_th=((char *)$next_th->pids[1].pid_list.next)
- $pid_off)
                                end
                                set $next_t=(char *)($next_t->tasks.next) - $tasks_off
                                end

                                printf "Trapno %ld, cr2 0x%lx, error_code %ld\n",
$pid_task.thread.trap_no, \
                                $pid_task.thread.cr2,
$pid_task.thread.error_code

                                end
                                document trapinfo
                                    Run info threads and lookup pid of thread #1
                                    'trapinfo <pid>' will tell you by which trap & possibly
                                    address the kernel panicked.
                                end

                                define dmesg
                                    set $i = 0
                                    set $end_idx = (log_end - 1) & (log_buf_len - 1)

                                    while ($i < logged_chars)
                                        set $idx = (log_end - 1 - logged_chars + $i) & (log_buf_len - 1)

                                        if ($idx + 100 <= $end_idx) || \
                                            ($end_idx <= $idx && $idx + 100 < log_buf_len)
                                            printf "%.100s", &log_buf[$idx]
                                            set $i = $i + 100
                                        else
                                            printf "%c", log_buf[$idx]
                                            set $i = $i + 1
                                        end
                                    end
                                end

                                end
                                document dmesg
                                    print the kernel ring buffer
                                end

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