

README.TXT

request_firmware() hotplug interface:

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Why:

Today, the most extended way to use firmware in the Linux kernel is linking it statically in a header file. Which has political and technical issues:

- 1) Some firmware is not legal to redistribute.
- 2) The firmware occupies memory permanently, even though it often is just used once.
- 3) Some people, like the Debian crowd, don't consider some firmware free enough and remove entire drivers (e.g.: keyspan).

High level behavior (mixed):

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kernel(driver): calls request_firmware(&fw_entry, \$FIRMWARE, device)

userspace:

- /sys/class/firmware/xxx/{loading,data} appear.
- hotplug gets called with a firmware identifier in \$FIRMWARE and the usual hotplug environment.
 - hotplug: echo 1 > /sys/class/firmware/xxx/loading

kernel: Discard any previous partial load.

userspace:

- hotplug: cat appropriate_firmware_image > \
/sys/class/firmware/xxx/data

kernel: grows a buffer in PAGE_SIZE increments to hold the image as it comes in.

userspace:

- hotplug: echo 0 > /sys/class/firmware/xxx/loading

kernel: request_firmware() returns and the driver has the firmware image in fw_entry->{data,size}. If something went wrong request_firmware() returns non-zero and fw_entry is set to NULL.

kernel(driver): Driver code calls release_firmware(fw_entry) releasing the firmware image and any related resource.

High level behavior (driver code):

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```
if(request_firmware(&fw_entry, $FIRMWARE, device) == 0)
    copy_fw_to_device(fw_entry->data, fw_entry->size);
release(fw_entry);
```

Sample/simple hotplug script:

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Both \$DEVPATH and \$FIRMWARE are already provided in the environment.

HOTPLUG_FW_DIR=/usr/lib/hotplug/firmware/

```
echo 1 > /sys/$DEVPATH/loading
cat $HOTPLUG_FW_DIR/$FIRMWARE > /sysfs/$DEVPATH/data
echo 0 > /sys/$DEVPATH/loading
```

Random notes:

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- "echo -1 > /sys/class/firmware/xxx/loading" will cancel the load at once and make request_firmware() return with error.
- firmware_data_read() and firmware_loading_show() are just provided for testing and completeness, they are not called in normal use.
- There is also /sys/class/firmware/timeout which holds a timeout in seconds for the whole load operation.
- request_firmware_nowait() is also provided for convenience in user contexts to request firmware asynchronously, but can't be called in atomic contexts.

about in-kernel persistence:

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Under some circumstances, as explained below, it would be interesting to keep firmware images in non-swappable kernel memory or even in the kernel image (probably within initramfs).

Note that this functionality has not been implemented.

- Why OPTIONAL in-kernel persistence may be a good idea sometimes:
 - If the device that needs the firmware is needed to access the filesystem. When upon some error the device has to be reset and the firmware reloaded, it won't be possible to get it from userspace.
e.g.:
 - A diskless client with a network card that needs firmware.
 - The filesystem is stored in a disk behind an scsi device that needs firmware.
 - Replacing buggy DSDT/SSDT ACPI tables on boot.
Note: this would require the persistent objects to be included within the kernel image, probably within initramfs.

And the same device can be needed to access the filesystem or not depending on the setup, so I think that the choice on what firmware to make persistent should be left to userspace.