```
**************
 1
  2
  3
     ***********************************
  4
     #include <bits/stdc++.h>
 5
    using namespace std;
 6
 7
     int main()
 8
         double allX[] = {1, 2, 3, 4, 5};
double allY[] = {1, 8, 27, 64, 125};
 9
10
         int tableSize = sizeof allY / sizeof allY[0];
11
         vector<double>delY[tableSize];
12
13
         double x = 1;
14
         double h = allX[1] - allX[0];
15
         double u = (x - allX[0]) / h;
16
17
         for (int i = 0; i < tableSize; i++) {
18
             delY[0].push_back(allY[i]);
19
20
         for (int i = 1; i < tableSize; i++) {</pre>
21
22
             for (int j = 1; j < delY[i - 1].size(); j++) {</pre>
                 delY[i].push_back(delY[i - 1][j] - delY[i - 1][j - 1]);
23
24
25
26
27
         double firstD = delY[1][0] + (2 * u - 1) * (delY[2][0] / 2) + (3
* u * u - 6 * u + 2) * (delY[3][0] / 6) + (4 * u * u * u - 18 * u * u + 22
* u - 6) * (delY[4][0] / 24);
28
         firstD /= h;
29
         double secondD = delY[2][0] + (6 * u - 6) * (delY[3][0] / 6) + (
30
12 * u * u - 36 * u + 22) * (delY[4][0] / 24);
31
         secondD /= (h * h);
32
33
         cout << "First Derivative = " << setprecision(3) << fixed <<</pre>
firstD << "\n";
         cout << "Second Derivative = " << setprecision(3) << fixed <<</pre>
34
secondD << "\n";
35
36
         return 0;
37
38
     /*********************
39
40
     *********************************
41
42
     #include <bits/stdc++.h>
43
    using namespace std;
44
45
     int main()
46
         double allX[] = {1, 2, 3, 4, 5};
double allY[] = {1, 8, 27, 64, 125};
47
48
         int tableSize = sizeof allY / sizeof allY[0];
49
50
         vector<double>delY[tableSize];
51
         double x = 1.5;
52
         double h = allX[1] - allX[0];
53
         double u = (x - allX[0]) / h;
54
55
         for (int i = 0; i < tableSize; i++) {
56
             delY[0].push_back(allY[i]);
57
58
59
         for (int i = 1; i < tableSize; i++) {
             for (int j = 1; j < delY[i - 1].size(); j++) {</pre>
60
61
                 delY[i].push_back(delY[i - 1][j] - delY[i - 1][j - 1]);
```

```
62
 63
 64
 65
        double firstD = delY[1][0] + (2 * u - 1) * (delY[2][0] / 2) + (3
* u * u - 6 * u + 2) * (delY[3][0] / 6) + (4 * u * u * u - 18 * u * u + 22
* u - 6) * (delY[4][0] / 24);
        firstD /= h;
 66
 67
         double secondD = delY[2][0] + (6 * u - 6) * (delY[3][0] / 6) + (
68
12 * u * u - 36 * u + 22) * (delY[4][0] / 24);
         secondD /= (h * h);
 69
 70
71
         cout << "First Derivative = " << setprecision(3) << fixed <<</pre>
firstD << "\n";
        cout << "Second Derivative = " << setprecision(3) << fixed <<</pre>
secondD << "\n";
 73
 74
        return 0;
 75
 76
     /*******************
 77
 78
     **********************************
 79
     #include <bits/stdc++.h>
 80
 81
     using namespace std;
 82
 83
    double fX(double x)
 84
 85
        return (5 * log10(x));
 86
 87
 88
     int main()
 89
 90
         double upperLimit = 7;
91
         double lowerLimit = 1;
 92
         int n = 6;
 93
         double h = (upperLimit - lowerLimit) / n;
 94
 95
         double x = lowerLimit;
 96
         double y[n + 1];
         for (int i = 0; i <= n; i++) {
 97
            y[i] = fX(x);

x += h;
 98
 99
100
101
102
         double I = y[0] + y[n];
         for (int i = 1; i < n; i++) {</pre>
103
104
             I += (2 * y[i]);
105
106
         I = I * (h / 2);
107
108
         cout << "Area = " << setprecision(3) << fixed << I << "\n";</pre>
109
110
        return 0;
111
112
113
114
     **********************
115
     #include <bits/stdc++.h>
116
117
     using namespace std;
118
119
     #define PI acos(-1.0)
120
     #define sinD(degree) sin((degree * PI) / 180.0)
121
122
     double fX(double x)
```

```
123
124
         return (PI * exp(sinD(x))) / 2;
125
126
127
     int main()
128
129
         double upperLimit = 7;
130
         double lowerLimit = 1;
131
         int n = 6;
         double h = (upperLimit - lowerLimit) / n;
132
133
134
         double x = lowerLimit;
135
         double y[n + 1];
         for (int i = 0; i <= n; i++) {
136
             y[i] = fX(x);
137
138
             x += h;
139
140
141
         double I = y[0] + y[n];
142
         for (int i = 1; i < n; i++) {
             if (i % 2 == 0) {
143
144
                 I += (2 * y[i]);
145
146
             else {
147
                 I += (4 * y[i]);
148
149
150
         I = I * (h / 3);
151
152
         cout << "Area = " << setprecision(3) << fixed << I << "\n";</pre>
153
154
         return 0;
155
156
     /*******************************
157
158
                              5
                           ************
159
160
     #include <bits/stdc++.h>
161
     using namespace std;
162
163
     double fX(double x)
164
         return (x / (1 + x * x));
165
166
167
168
     int main()
169
         double upperLimit = 7;
170
171
         double lowerLimit = 1;
172
         int n = 6;
173
         double h = (upperLimit - lowerLimit) / n;
174
175
         double x = lowerLimit;
176
         double y[n + 1];
         for (int i = 0; i <= n; i++) {</pre>
177
178
             y[i] = fX(x);
179
             x += h;
180
181
182
         double I = y[0] + y[n];
183
         for (int i = 1; i < n; i++) {</pre>
184
             if (i % 3 == 0) {
                 I += (2 * y[i]);
185
186
187
             else {
                 I += (3 * y[i]);
188
```

```
189
190
191
         I = I * ((3 * h) / 8);
192
193
         cout << "Area = " << setprecision(3) << fixed << I << "\n";</pre>
194
195
         return 0;
196
197
     /*******************************
198
199
     ***********************
200
201
     #include <bits/stdc++.h>
202
     using namespace std;
203
204
     int temp[4][4];
205
206
     int det3x3()
207
208
         int ans = 0;
209
         ans += temp[1][1] * (temp[2][2] * temp[3][3] - temp[2][3] * temp[
3][2]);
210
         ans -= temp[1][2] * (temp[2][1] * temp[3][3] - temp[2][3] * temp[
3][1]);
211
         ans += temp[1][3] * (temp[2][1] * temp[3][2] - temp[2][2] * temp[
3][1]);
212
         return ans;
213
214
215
     int main()
216
217
         int n = 4;
218
         int matrix[n + 1][n + 1];
219
220
         for (int i = 1; i <= n; i++) {</pre>
221
             for (int j = 1; j \le n; j++) {
222
                 cin >> matrix[i][j];
223
224
225
226
         int ans = 0;
         for (int i = 1; i <= n; i++) {</pre>
227
             for (int j = 2; j <= n; j++) {
228
229
                 int m = 1;
230
                 for (int k = 1; k <= n; k++) {
                      if (k == i) {
231
232
                          continue;
233
234
                     temp[j-1][m] = matrix[j][k];
235
                     m++;
236
237
238
239
             cout << det3x3() << "\n";</pre>
240
241
             int d = matrix[1][i] * det3x3();
             if (i % 2 == 1) {
242
243
                 ans += d;
244
245
             else {
246
                 ans -= d;
247
248
249
250
         cout << "Determinant = " << ans << "\n";</pre>
251
```

```
252
         return 0;
253
254
255
256
     ************************
257
258
     #include <bits/stdc++.h>
259
     using namespace std;
260
261
     const int n = 3;
262
263
     double A[n + 1][n + 1] = {
                       {0, 0, 0, 0, 0},
264
                       \{0, 1, 1, 1\},\
265
                       {0, 1, 2,
                                  3
266
267
268
269
     double B[n + 1] = \{0, 1, 6, 6\};
270
271
272
     double det3x3()
273
274
         double ans = 0;
         ans += A[1][1] *
275
                            (A[2][2] * A[3][3] - A[2][3] * A[3][2]);
         ans -= A[1][2] * (A[2][1] * A[3][3] - A[2][3] * A[3][1]);
276
277
         ans += A[1][3] * (A[2][1] * A[3][2] - A[2][2] * A[3][1]);
278
         return ans;
279
280
281
     int main()
282
283
         double detA = det3x3();
         double cofactor[n + 1][n + 1];
284
285
286
         vector<double>data;
287
288
         data.clear();
         for (int i = 1; i <= n; i++) {</pre>
289
              for (int j = 1; j <= n; j++) {
    for (int row = 1; row <= n; row++) {</pre>
290
291
292
                       for (int col = 1; col <= n; col++) {</pre>
                           if (row == i || col == j) {
293
294
                               continue;
295
296
                           data.push_back(A[row][col]);
297
298
299
300
                  cofactor[i][j] = (data[0] * data[3]) - (data[1] * data[2]
]);
301
                  if ((i + j) % 2 == 1) {
                       cofactor[i][j] *= -1;
302
303
304
                  data.clear();
305
306
307
308
         double adjA[n + 1][n + 1];
309
         for (int i = 1; i <= n; i++) {
310
              for (int j = 1; j <= n; j++) {
                  adjA[i][j] = cofactor[j][i];
311
312
                  adjA[i][j] /= detA;
313
314
315
316
         double solution[n + 1];
```

```
for (int i = 1; i <= n; i++) {</pre>
317
318
             double x = 0;
319
             for (int j = 1; j <= n; j++) {
320
                 x += adjA[i][j] * B[j];
321
             solution[i] = x;
322
323
324
325
         cout << "x = " << setprecision(3) << fixed << solution[1] << "\n"</pre>
326
         cout << "y = " << setprecision(3) << fixed << solution[2] << "\n"</pre>
327
         cout << "z = " << setprecision(3) << fixed << solution[3] << "\n"</pre>
328
329
         return 0;
330
331
     /*******************
332
333
                              11
     ***********************************
334
335
     #include <bits/stdc++.h>
336
     using namespace std;
337
338
     double eqX(double y, double z)
339
         double x = (95 - 11 * y + 4 * z) / 83;
340
341
         return x;
342
343
344
     double eqY(double x, double z)
345
346
         double y = (71 - 3 * x - 29 * z) / 8;
347
         return y;
348
349
350
     double eqZ(double x, double y)
351
         double z = (104 - 7 * x - 52 * y) / 13;
352
353
         return z;
354
355
356
     int main()
357
         double x, y, z;
358
359
         int n = 5;
360
361
         x = y = z = 0;
362
363
         for (int i = 1; i <= n; i++) {</pre>
364
             double newX = eqX(y, z);
365
             double newY = eqY(x, z);
             double newZ = eqZ(x, y);
366
367
368
             x = newX;
369
             y = newY;
370
             z = newZ;
371
372
         cout << "x = " << setprecision(3) << fixed << x << "\n";</pre>
373
         cout << "y = " << setprecision(3) << fixed << y << "\n";</pre>
374
         cout << "z = " << setprecision(3) << fixed << z << "\n";</pre>
375
376
377
         return 0;
378
379
```

```
380
     /*******************
381
                                12
     ***********************
382
383
     #include <bits/stdc++.h>
384
     using namespace std;
385
386
     double eqX(double y, double z)
387
388
          double x = (12 - y - z) / 10;
389
          return x;
390
391
392
     double eqY(double x, double z)
393
          double y = (13 - 2 * x - z) / 10;
394
395
          return y;
396
397
398
     double eqZ(double x, double y)
399
          double z = (14 - 2 * x - 2 * y) / 10;
400
401
          return z;
402
403
404
     int main()
405
          double x, y, z;
406
          int n = 1000;
407
408
          x = y = z = 0;
409
410
          for (int i = 1; i <= n; i++) {</pre>
411
412
              x = eqX(y, z);
413
              y = eqY(x, z);
414
              z = eqZ(x, y);
415
416
          cout << "x = " << setprecision(3) << fixed << x << "\n";
cout << "y = " << setprecision(3) << fixed << y << "\n";
cout << "z = " << setprecision(3) << fixed << z << "\n";</pre>
417
418
419
420
421
          return 0;
422
```