



Department of Computer Science and Engineering

ASSIGNMENT SUBMISSION

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Submitted By:

Name : Nayeem Mahmood
Matric No : C161026
Section : 6AM
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Submitted To:

Mohammed Shamsul Alam
Asst. Professor,
Dept. of CSE, IIUC

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Problem

- 1-1:** Write a program to count number of significant figures in a given number.

Theory

The digits that are used to express a number are called significant digits (or figures). A significant digit/figure is one of the digits 1, 2, … , 9 and 0 is a significant figure except when it is used to fix the decimal point or to fill the places of unknown or disorder digits.

Algorithm

1. All non-zero digits are significant.
2. All zeros occurring between non-zero digits are significant digits.
3. Trailing zeros following a decimal point are significant. For example, 3.50, 65.0 and 0.230 have three significant digits each.
4. Zeros between the decimal point and preceding a non-zero digit are non-significant. For example, the following numbers have four significant digits: 0.0001234, 0.001234, 0.01234

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4
5 int main()
6 {
7     string number, temp;
8     int i, _count;
9     bool decimalPoint;
10
11    while (true) {
12        cout << "Enter a number: ";
13        cin >> number;
14
15        if (!number.size()) {
16            break;
17        }
18
19        temp = number;
20
21        // removing all preceding 0s
22        while (temp[0] == '0') {
23            temp.erase(0, 1);
24        }
25
26        // looking for decimal point
27        decimalPoint = false;
28        for (i = 0; i < temp.size(); i++) {
29            if (temp[i] == '.') {
30                decimalPoint = true;
31                break;
32            }
33        }
34
35        if (!decimalPoint) {
36            // if decimal point is not found,
37            // remove all trailing 0s
38            i = temp.size() - 1;
39            while (temp[i] == '0') {
40                temp.erase(i, 1);
41                i--;
42            }
43            _count = temp.size();
44        }
45        else {
46            if (temp[0] == '.') {
47                // if there are no non-zero digits to the left of the
decimal point,
48                // then remove all 0s between decimal point and the
next non-zero digit
49                while (temp[1] == '0') {
50                    temp.erase(1, 1);
51                }
52            }
53
54            _count = temp.size() - 1; // decimal point is not a digit
55        }
56
57        cout << number << " has " << _count << " significant
digits.\n";
58        number = "";
59    }
60
61    return 0;
62 }
63

```

Sample I/O

Enter a number: 120
120 has 2 significant digits.

Enter a number: 3.50
3.50 has 3 significant digits.

Enter a number: 65.0
65.0 has 3 significant digits.

Enter a number: 0.230
0.230 has 3 significant digits.

Enter a number: 0.001234
0.001234 has 4 significant digits.

Enter a number: 7.56
7.56 has 3 significant digits.

Problem

1-3: Write a program to evaluate a polynomial by using Horner's rule.

Theory

We can write the polynomial $f(x)$ using *Horner's rule* (also known as *nested multiplication*) as follows:

$$f(x) = ((\dots ((a_n x + a_{n-1})x + a_{n-2})x + \dots + a_1)x + a_0)$$

Here the innermost expression $a_n x + a_{n-1}$ is evaluated first. The resulting value constitutes a multiplicand for the expression at the next level. The number of levels equals n , the degree of polynomial. This approach needs a total of n additions and n multiplications.

Algorithm

$$p_n = a_n$$

$$p_{n-1} = p_{n-2} x + a_{n-1}$$

...

...

...

$$p_j = p_{j+1} x + a_j$$

...

...

$$p_1 = p_2 x + a_1$$

$$f(x) = p_0 = p_1 x + a_0$$

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4
5 #define MAX 100
6
7 int allA[MAX];
8 int allP[MAX];
9
10 int main()
11 {
12     int n, i, x, a;
13
14     while (true) {
15         cout << "Degree of polynomial: ";
16         cin >> n;
17
18         if (!n) {
19             break;
20         }
21
22         cout << "Enter the co-efficients: ";
23         for (i = n; i >= 0; i--) {
24             cin >> allA[i];
25         }
26
27         cout << "Enter value for x: ";
28         cin >> x;
29
30         allP[n] = allA[n];
31         for (i = n - 1; i >= 0; i--) {
32             allP[i] = allP[i + 1] * x + allA[i];
33         }
34
35         cout << "f(" << x << ") = " << allP[0] << "\n";
36     }
37
38     return 0;
39 }
```

Sample I/O

Degree of polynomial: 3

Enter the co-efficients: 1 -4 1 6

Enter value for x: 2

$f(2) = 0$

Degree of polynomial: 3

Enter the co-efficients: 1 -2 5 10

Enter value for x: 3

$f(3) = 34$

Problem

- 1-4:** Write a program to find the root of the equation $x^3 - 9x + 1 = 0$, correct to 3 decimal places by using the Bisection method.

Theory

If $f(x)$ is a continuous function in some interval $[a, b]$ and $f(a)$ and $f(b)$ are of opposite signs, then the equation $f(x) = 0$ has at least one real root or an odd number of real roots in (a, b) .

Algorithm

1. Decide initial values for x_1 and x_2 and stopping criterion E .
2. Compute $f_1 = f(x_1)$ and $f_2 = f(x_2)$.
3. If $f_1 * f_2 > 0$, x_1 and x_2 do not bracket any root and go to step 1.
4. Compute $x_0 = (x_1 + x_2) / 2$ and compute $f_0 = f(x_0)$.
5. If $f_1 * f_0 < 0$ then set $x_2 = x_0$ else set $x_1 = x_0$.
6. If absolute value of $(x_2 - x_1)$ is less than E , then $\text{root} = (x_1 + x_2) / 2$ and go to step 7
Else go to step 4
7. Stop.

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4
5 #define EPS 1e-4
6 #define MAX 100
7
8 int degree;
9 int allA[MAX];
10
11 double fX(double x)
12 {
13     double ans = 0;
14     for (int i = degree; i >= 0; i--) {
15         ans += allA[i] * pow(x, i);
16     }
17     return ans;
18 }
19
20 int main()
21 {
22     int i;
23     double x, x1, x2;
24
25     while (true) {
26         cout << "Degree of polynomial equation: ";
27         cin >> degree;
28
29         if (!degree) {
30             break;
31         }
32
33         cout << "Enter the co-efficients: ";
34         for (i = degree; i >= 0; i--) {
35             cin >> allA[i];
36         }
37
38         do {
39             cout << "Initial guess for x1: ";
40             cin >> x1;
41             cout << "Initial guess for x2: ";
42             cin >> x2;
43         } while (fX(x1) * fX(x2) > 0.0);
44
45         while (fabs(x2 - x1) > EPS) {
46             x = (x1 + x2) / 2.0;
47
48             if (fX(x) * fX(x1) < 0.0) {
49                 x2 = x;
50             }
51             else {
52                 x1 = x;
53             }
54         }
55
56         cout << "root = " << setprecision(3) << fixed << x1 << "\n";
57     }
58
59     return 0;
60 }
```

Sample I/O

Degree of polynomial equation: 3

Enter the co-efficients: 1 0 -1 -1

Initial guess for x1: 1

Initial guess for x2: 2

root = 1.325

Degree of polynomial equation: 3

Enter the co-efficients: 1 0 -9 1

Initial guess for x1: 1

Initial guess for x2: 3

root = 2.943

Problem

- 1-6:** Write a program to find the root of the equation $x^4 - 12x + 7 = 0$, correct to 3 decimal places by using the Newton-Raphson method.

Theory

Let x_0 be an approximate root of $f(x) = 0$ and let $x_1 = x_0 + h$ be the correct root so that $f(x_1) = 0$.

Expanding $f(x_0 + h)$ by Taylor's series, we obtain

$$f(x_0) + h f'(x_0) + h^2/2! f''(x_0) + \dots = 0$$

Neglecting the second and higher order derivatives, we have

$$f(x_0) + h f'(x_0) = 0$$

which gives $h = -f(x_0) / f'(x_0)$

A better approximation than x_0 is therefore given by x_1 , where

$$x_1 = x_0 - f(x_0) / f'(x_0)$$

Successive approximations are given by $x_2, x_3, x_4, \dots, x_{n+1}$, where

$$X_{n+1} = x_n - f(x_n) / f'(x_n)$$

which is called the *Newton-Raphson formula*.

The process will be continued till the absolute difference between two successive approximations is less than the specified error E i.e, $|x_{n+1} - x_n| < E$.

Algorithm

1. Assign an initial value for x , say x_0 and stopping criterion E .
2. Compute $f(x_0)$ and $f'(x_0)$.
3. Find the improved estimate of x_0
4. $x_1 = x_0 - f(x_0) / f'(x_0)$
5. Check for accuracy of the latest estimate.
6. If $|x_1 - x_0| < E$ then stop; otherwise continue.
7. Replace x_0 by x_1 and repeat steps 3 and 4.

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4
5 #define EPS 1e-4
6 #define MAX 100
7
8 int degree;
9 int allA[MAX];
10 int allD[MAX]; // derivative
11
12 double fX(double x)
13 {
14     double ans;
15     for (int i = degree; i >= 0; i--) {
16         ans += allA[i] * pow(x, i);
17     }
18     return ans;
19 }
20
21 double dX(double x)
22 {
23     double ans;
24     for (int i = degree - 1; i >= 0; i--) {
25         ans += allD[i] * pow(x, i);
26     }
27     return ans;
28 }
29 int main()
30 {
31     int i;
32     double x, x0;
33
34     while (true) {
35         cout << "Degree of polynomial equation: ";
36         cin >> degree;
37         if (!degree) {
38             break;
39         }
40         cout << "Co-efficients of the equation: ";
41         for (i = degree; i >= 0; i--) {
42             cin >> allA[i];
43         }
44         cout << "Co-efficients of the derivative equation: ";
45         for (i = degree - 1; i >= 0; i--) {
46             cin >> allD[i];
47         }
48         cout << "Initial guess for x: ";
49         cin >> x0;
50
51         while (true) {
52             x = x0 - fX(x0) / dX(x0);
53             if (fabs(x - x0) < EPS) {
54                 //cout << "# x : " << x << "\n# x0 : " << x0 <<
55                 //break;
56             }
57             else {
58                 //cout << "x: " << x << "\n";
59                 x0 = x;
60             }
61         }
62     }
63     cout << "root: " << setprecision(3) << fixed << x << "\n";
64 }
65 }
```

Sample I/O

Degree of polynomial equation: 4

Co-efficients of the equation: 1 0 0 -12 7

Co-efficients of the derivative equation: 4 0 0 -12

Initial guess for x: 0

root: 0.594

Degree of polynomial equation: 3

Co-efficients of the equation: 1 0 -6 4

Co-efficients of the derivative equation: 3 0 -6

Initial guess for x: 0

root: 2.000

Problem

1-7: Write a program to find the root of the equation $x^3 + x - 1 = 0$, correct to 3 decimal places by using the False Position method.

Theory

The equation of the line joining the points $(x_1, f(x_1))$ and $(x_2, f(x_2))$ is given by

$$(f(x_2) - f(x_1)) / (x_2 - x_1) = (y - f(x_1)) / (x - x_1)$$

Since the line intersects the x-axis at x_0 , when $x = x_0$, $y = 0$, we have,

$$(f(x_2) - f(x_1)) / (x_2 - x_1) = (-f(x_1)) / (x_0 - x_1)$$

$$\text{or } x_0 - x_1 = -f(x_1) (x_2 - x_1) / (f(x_2) - f(x_1))$$

Then we have,

$$x_0 = x_1 - (f(x_1) (x_2 - x_1)) / (f(x_2) - f(x_1))$$

This equation is known as the *false position formula*.

Algorithm

1. Decide initial values for x_1 and x_2 and stopping criterion E.
2. Compute $x_0 = x_1 - (f(x_1) (x_2 - x_1)) / (f(x_2) - f(x_1))$
3. If $f(x_0) * f(x_1) < 0$ set $x_2 = x_0$ otherwise set $x_1 = x_0$
4. If the absolute difference of two successive x_0 is less than E, then root = x_0 and stop.
5. Else go to step 2.

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4
5 #define EPS 1e-4
6 #define MAX 100
7
8 int degree;
9 int allA[MAX];
10
11 double fX(double x)
12 {
13     double ans = 0;
14     for (int i = degree; i >= 0; i--) {
15         ans += allA[i] * pow(x, i);
16     }
17     return ans;
18 }
19
20 int main()
21 {
22     int i;
23     double x, previousX, x1, x2;
24
25     while (true) {
26
27         cout << "Degree of polynomial equation: ";
28         cin >> degree;
29
30         if (!degree) {
31             break;
32         }
33
34         cout << "Enter the co-efficients: ";
35         for (i = degree; i >= 0; i--) {
36             cin >> allA[i];
37         }
38
39         cout << "Initial guess for x1: ";
40         cin >> x1;
41         cout << "Initial guess for x2: ";
42         cin >> x2;
43
44         previousX = DBL_MIN;
45         while (true) {
46             x = x1 - (fX(x1) * (x2 - x1)) / (fX(x2) - fX(x1));
47
48             if (fabs(x - previousX) < EPS) {
49                 break;
50             }
51             else {
52                 previousX = x;
53             }
54
55             if (fX(x) * fX(x1) < 0.0) {
56                 x2 = x;
57             }
58             else {
59                 x1 = x;
60             }
61         }
62         cout << "root = " << setprecision(3) << fixed << x << "\n";
63     }
64     return 0;
65 }
```

Sample I/O

Degree of polynomial equation: 3

Enter the co-efficients: 1 0 1 -1

Initial guess for x1: 0

Initial guess for x2: 1

root = 0.682

Degree of polynomial equation: 2

Enter the co-efficients: 1 -1 -2

Initial guess for x1: 1

Initial guess for x2: 3

root = 2.000

Problem

- 1-8:** Write a program to find the root of the equation $x^3 - 9x + 1 = 0$, correct to 3 decimal places by using the Secant method.

Theory

Secant method, like the False Position & Bisection methods, uses two initial estimates but does not require that they must bracket the root.

Let us consider two points x_1 and x_2 as starting values. Slope of the secant line passing through x_1 and x_2 is given by,

$$\frac{f(x_1)}{x_1 - x_3} = \frac{f(x_2)}{x_2 - x_3}$$

$$f(x_1)(x_2 - x_3) = f(x_2)(x_1 - x_3)$$

$$x_3[f(x_2) - f(x_1)] = f(x_2).x_1 - f(x_1).x_2$$

$$\therefore x_3 = \frac{f(x_2).x_1 - f(x_1).x_2}{f(x_2) - f(x_1)}$$

By adding and subtracting $f(x_2).x_2$ to the numerator and remaining the terms we have,

$$x_3 = x_2 - \frac{f(x_2)(x_2 - x_1)}{f(x_2) - f(x_1)}$$

which is called the *secant formula*.

Algorithm

1. Decide two initial points x_1 and x_2 and required accuracy level E.
2. Compute $f_1 = f(x_1)$ and $f_2 = f(x_2)$
3. Compute $x_3 = (f_2 x_1 - f_1 x_2) / (f_2 - f_1)$
4. If $|x_3 - x_2| > E$, then
 - Set $x_1 = x_2$ and $f_1 = f_2$
 - Set $x_2 = x_3$ and $f_2 = f(x_3)$
 - Go to step 3
- Else
 - Set root = x_3
 - Print root
5. Stop.

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4
5 #define EPS 1e-4
6 #define MAX 100
7
8 int degree;
9 int allA[MAX];
10
11 double fX(double x)
12 {
13     double ans = 0;
14     for (int i = degree; i >= 0; i--) {
15         ans += allA[i] * pow(x, i);
16     }
17     return ans;
18 }
19
20 int main()
21 {
22     int i;
23     double x, x1, x2;
24
25     while (true) {
26         cout << "Degree of polynomial equation: ";
27         cin >> degree;
28
29         if (!degree) {
30             break;
31         }
32
33         cout << "Enter the co-efficients: ";
34         for (i = degree; i >= 0; i--) {
35             cin >> allA[i];
36         }
37
38         cout << "Initial guess for x1: ";
39         cin >> x1;
40         cout << "Initial guess for x2: ";
41         cin >> x2;
42
43         while (true) {
44             x = x2 - (fX(x2) * (x2 - x1)) / (fX(x2) - fX(x1));
45
46             if (fabs(x - x2) > EPS) {
47                 x1 = x2;
48                 x2 = x;
49             }
50             else {
51                 break;
52             }
53         }
54
55         cout << "root = " << setprecision(3) << fixed << x << "\n";
56     }
57
58     return 0;
59 }
```

Sample I/O

Degree of polynomial equation: 3

Enter the co-efficients: 1 -5 0 -29

Initial guess for x1: 0

Initial guess for x2: 3

root = 5.848

Degree of polynomial equation: 3

Enter the co-efficients: 1 0 1 -1

Initial guess for x1: 0

Initial guess for x2: 1

root = 0.682

Degree of polynomial equation: 2

Enter the co-efficients: 1 -1 -2

Initial guess for x1: 1

Initial guess for x2: 3

root = 2.000

Problem

1-9: Write a program to find the Quotient Polynomial $q(x)$ such that $p(x) = (x - 2) q(x)$ where $p(x) = x^3 - 6x^2 + 11x - 6 = 0$ has a root at $x = 2$.

Theory

A polynomial of degree n can be expressed as

$$p(x) = (x - x_r) q(x)$$

where x_r is a root of the polynomial $p(x)$ and $q(x)$ is the *quotient. Polynomial* of degree $n-1$. Once a root is found, we can use this fact to obtain a lower degree polynomial $q(x)$ by dividing $p(x)$ by $(x - x_r)$ using a process known as *Synthetic division*. The name “Synthetic” is used because the quotient polynomial $q(x)$ is obtained without actually performing the division. The activity of reducing the degree of a polynomial is referred to as *deflation*.

Algorithm

If $p(x) = (x - x_r) q(x)$, then

$$a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0 = (x - x_r) (b_{n-1} x^{n-1} + b_{n-2} x^{n-2} + \dots + b_1 x + b_0)$$

By comparing the coefficients of like powers of x on both the sides of equation, we get the following relation between them:

$$a_n = b_{n-1}$$

$$a_{n-1} = b_{n-2} - x_r b_{n-1}$$

...

...

$$a_1 = b_0 - x_r b_1$$

$$a_0 = -x_r b_0$$

That is $a_i = b_{i-1} - x_r b_i$ where, $b_n = 0$ and $i = n, n-1, \dots, 0$

Then $b_{i-1} = a_i + x_r b_i$ where, $b_n = 0$ and $i = n, n-1, \dots, 1$

The above Equation suggests that we can determine the co-efficient of $q(x)$ [i.e, $b_{n-1}, b_{n-2}, \dots, b_0$] from the co-efficient of $p(x)$ [i.e a_n, a_{n-1}, \dots, a_1] recursively. Thus we have obtained the polynomial $q(x)$ without performing any division operation.

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4
5 #define MAX 100
6
7 int allP[MAX];
8 int allQ[MAX];
9
10 int main()
11 {
12     int degree, i, x;
13
14     while (true) {
15         cout << "Degree of polynomial: ";
16         cin >> degree;
17
18         if (!degree) {
19             break;
20         }
21
22         cout << "Co-efficients: ";
23         for (i = degree; i >= 0; i--) {
24             cin >> allP[i];
25         }
26
27         cout << "Root, x: ";
28         cin >> x;
29
30         allQ[degree] = 0;
31         for (i = degree - 1; i >= 0; i--) {
32             allQ[i] = allP[i + 1] + x * allQ[i + 1];
33         }
34
35         cout << "Co-efficients of q(x): ";
36         for (i = degree - 1; i >= 0; i--) {
37             cout << allQ[i] << " ";
38         }
39         cout << "\n";
40     }
41
42     return 0;
43 }
```

Sample I/O

Degree of polynomial: 3

Co-efficients: 1 -6 11 -6

Root, x: 2

Co-efficients of $q(x)$: 1 -4 3

Degree of polynomial: 3

Co-efficients: 1 -7 15 -9

Root, x: 3

Co-efficients of $q(x)$: 1 -4 3

Problem

2-1: The following values of $f(x)$ are given:

x	1	2	3	4	5
$y = f(x)$	1	8	27	64	125

Write a program to find difference table for above values.

Theory

If $y_0, y_1, y_2, \dots, y_n$ denote a set of values of y , then $y_1 - y_0, y_2 - y_1, \dots, \dots, y_n - y_{n-1}$ are called the *differences* of y . Denoting these differences by $\Delta y_0, \Delta y_1, \Delta y_2, \dots, \dots, \Delta y_{n-1}$ respectively, we have,

$$\Delta y_0 = y_1 - y_0, \Delta y_1 = y_2 - y_1, \dots, \dots, \Delta y_{n-1} = y_n - y_{n-1}$$

General form: $\Delta y_i = y_{i+1} - y_i$, where $i = 0, 1, 2, 3, \dots, n-1$

where Δ is called the *forward difference operator* and $\Delta y_0, \Delta y_1, \Delta y_2, \dots, \Delta y_{n-1}$ are called *first forward differences*.

The difference of the first forward differences are called *second forward differences* and denoted by $\Delta^2 y_0, \Delta^2 y_1, \Delta^2 y_2, \dots$. Similarly, one can define *third forward differences*, *fourth forward differences*, etc.

$$\Delta^2 y_0 = \Delta y_1 - \Delta y_0 = (y_2 - y_1) - (y_1 - y_0) = y_2 - 2y_1 + y_0$$

$$\Delta^3 y_0 = \Delta^2 y_1 - \Delta^2 y_0 = (y_3 - 2y_2 + y_1) - (y_2 - 2y_1 + y_0) = y_3 - 3y_2 + 3y_1 - y_0$$

- Any higher order difference can easily be expressed in terms of the ordinates, since the coefficients occurring on the right side are the binomial coefficients.

- $\Delta^r y_i = \Delta^{r-1} y_{i+1} - \Delta^{r-1} y_i$

-

$$\Delta^n y_0 = \sum_{k=0}^n (-1)^k c_k y_{n-k}$$

$$\Delta^n y_0 = y_n - {}^n c_1 y_{n-1} + {}^n c_2 y_{n-2} - {}^n c_3 y_{n-3} \dots \dots + (-1)^n y_0$$

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4
5 int main()
6 {
7     int n, i, j;
8     double x, y;
9     vector<double> allX;
10    vector<vector<double>> allY;
11
12    while (true) {
13        cout << "Number of points in the table: ";
14        cin >> n;
15
16        if (!n) {
17            break;
18        }
19
20        allX.assign(n, 0);
21        allY.assign(n, vector<double>());
22        for (i = 0; i < n; i++) {
23            cout << "Enter x" << i << " y" << i << "\n";
24            cin >> allX[i] >> y;
25            allY[0].push_back(y);
26        }
27
28        for (i = 1; i < n; i++) {
29            for (j = 1; j < allY[i - 1].size(); j++) {
30                y = allY[i - 1][j] - allY[i - 1][j - 1];
31                allY[i].push_back(y);
32            }
33        }
34
35        for (i = 1; i < n; i++) {
36            cout << "del^" << i << "y:" ;
37            for (j = 0; j < allY[i].size(); j++) {
38                cout << " " << allY[i][j];
39            }
40            cout << "\n";
41        }
42    }
43
44    return 0;
45 }
```

Sample I/O

Number of points in the table: 5

Enter x0 y0: 1 1

Enter x1 y1: 2 8

Enter x2 y2: 3 27

Enter x3 y3: 4 64

Enter x4 y4: 5 125

del^1y: 7 19 37 61

del^2y: 12 18 24

del^3y: 6 6

del^4y: 0

Number of points in the table: 5

Enter x0 y0: 1 11.022

Enter x1 y1: 3 12.023

Enter x2 y2: 5 15.134

Enter x3 y3: 7 16.723

Enter x4 y4: 9 22.442

del^1y: 1.001 3.111 1.589 5.719

del^2y: 2.11 -1.522 4.13

del^3y: -3.632 5.652

del^4y: 9.284

Problem

2-2: The following values of $f(x)$ are given:

x	1	2	3	4	5
$y = f(x)$	1	8	27	64	125

Write a program to find $f(1.7)$ by using Newton's Forward Interpolation.

Theory

Let $y = f(x)$ be a function which takes the values $y_0, y_1, y_2, \dots, y_n$ corresponding to the $(n+1)$ values $x_0, x_1, x_2, \dots, x_n$ of the independent variables. Let the values of x be equally spaced i.e. $x_i = x_0 + ih$ where $i = 0, 1, 2, \dots, n$ and h is the interval of differencing. Let $\varphi(x)$ be a polynomial of the n^{th} degree such that y and $\varphi(x)$ agree at the tabulated points i.e. $f(x_i) = \varphi(x_i)$, $i = 0, 1, 2, \dots, n$ and at all other points $f(x) = \varphi(x) + R(x)$ where $R(x)$ is called *error term* of the interpolation formula. Ignoring the error term let us assume

$$f(x) \approx \varphi(x) = a_0 + a_1(x-x_0) + a_2(x-x_0)(x-x_1) + \dots + a_n(x-x_0)(x-x_1)\dots(x-x_{n-1})$$

The constants a_0, a_1, \dots, a_n can be determined as follows:

putting $x = x_0$ we get

$$f(x_0) \approx \varphi(x_0) = a_0$$

$$\therefore a_0 = y_0$$

putting $x = x_1$ we get

$$f(x_1) \approx \varphi(x_1) = a_0 + a_1(x_1 - x_0) = y_0 + a_1h$$

$$\therefore a_1 = (y_1 - y_0) / h = \Delta y_0 / h$$

putting $x = x_2$ we get

$$f(x_2) \approx \varphi(x_2) = a_0 + a_1(x_2 - x_0) + a_1(x_2 - x_0)(x_2 - x_1)$$

$$y_2 = y_0 + \Delta y_0/h(2h) + a_2(2h)(h)$$

$$y_2 = y_0 + 2(y_1 - y_0) + a_2(2h^2)$$

$$y_2 = 2y_1 + y_0$$

$$a_2 = \frac{2h^2}{\Delta^2 y_0}$$

$$\therefore a_2 = \frac{2! h^2}{\Delta^2 y_0}$$

Similarly by putting $x = x_3, x = x_4, \dots, x = x_n$ we get,

$$a_3 = \frac{\Delta^3 y_0}{3! h^3}, \quad a_4 = \frac{\Delta^4 y_0}{4! h^4}, \dots, \dots, \dots, a_n = \frac{\Delta^n y_0}{n! h^n}$$

putting the values of a_0, a_1, \dots, a_n we get

$$f(x) \approx \varphi(x) = y_0 + (\Delta y_0/h)(x-x_0) + (\Delta^2 y_0 / (2! h^2))(x-x_0)(x-x_1) + \dots + (\Delta^n y_0 / (n! h^n))(x-x_0)(x-x_1) \dots (x-x_{n-1})$$

writing $u = ((x-x_0) / h)$, we get

$$x-x_0 = uh$$

$$x-x_1 = (x-x_0) + (x_0-x_1) = (x-x_0) - (x_1-x_0) = uh - h = (u-1)h$$

Similarly, $x-x_2 = (u-2)h$

$$x-x_3 = (u-3)h$$

.....

$$x-x_{n-1} = (u-n+1)h$$

$$f(x) \approx \varphi(x) = y_0 + u(\Delta y_0/1!) + u(u-1)(\Delta^2 y_0)/2! + \dots + u(u-1)(u-2) \dots (u-n+1)(\Delta^n y_0)/n!$$

The above formula is called *Newton's forward interpolation formula*.

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4
5 int main()
6 {
7     int n, i, j, fact;
8     double x, y, h, u, ans, tempU;
9     vector<double> allX;
10    vector<vector<double>> allY;
11
12    while (true) {
13        cout << "Number of points in the table: ";
14        cin >> n;
15
16        if (!n) {
17            break;
18        }
19
20        allX.assign(n, 0);
21        allY.assign(n, vector<double>());
22        for (i = 0; i < n; i++) {
23            cout << "Enter x" << i << " y" << i << "\n";
24            cin >> allX[i] >> y;
25            allY[0].push_back(y);
26        }
27
28        cout << "Value for x: ";
29        cin >> x;
30
31        for (i = 1; i < n; i++) {
32            for (j = 1; j < allY[i - 1].size(); j++) {
33                y = allY[i - 1][j] - allY[i - 1][j - 1];
34                allY[i].push_back(y);
35            }
36        }
37
38        h = allX[1] - allX[0];
39        u = (x - allX[0]) / h;
40
41        ans = allY[0][0];
42        for (i = 1, fact = 1; i < n; i++) {
43            tempU = u;
44            for (j = 1; j < i; j++) {
45                tempU *= (u - j);
46            }
47            fact *= i;
48            ans += (tempU * allY[i][0]) / (fact * 1.0);
49        }
50
51        cout << "f( " << x << " ) = " << ans << "\n";
52    }
53
54    return 0;
55 }
```

Sample I/O

Number of points in the table: 5

Enter x0 y0: 1 1

Enter x1 y1: 2 8

Enter x2 y2: 3 27

Enter x3 y3: 4 64

Enter x4 y4: 5 125

Value for x: 1.7

$f(1.7) = 13.573$

Number of points in the table: 5

Enter x0 y0: 1 11.022

Enter x1 y1: 3 12.023

Enter x2 y2: 5 15.134

Enter x3 y3: 7 16.723

Enter x4 y4: 9 22.442

Value for x: 7.2

$f(7.2) = 10.0057$

Problem

2-3: The following values of $f(x)$ are given:

x	1	2	3	4	5
$y = f(x)$	1	8	27	64	125

Write a program to find $f(4.7)$ by using Newton's Backward Interpolation.

Theory

Newton forward interpolation formula cannot be used for interpolating a value of y near the end of a table of values. For this purpose, we use another formula known as Newton-Gregory interpolation formula.

Let $y = f(x)$ be a function which takes the values $y_0, y_1, y_2, \dots, y_n$ corresponding to the $(n+1)$ values $x_0, x_1, x_2, \dots, x_n$ of the independent variables. Let the values of x be equally spaced i.e. $x_i = x_0 + ih$ where $i = 0, 1, 2, \dots, n$ and h is the interval of differencing. Let $\varphi(x)$ be a polynomial of the n^{th} degree such that y and $\varphi(x)$ agree at the tabulated points i.e. $f(x_i) = \varphi(x_i)$, $i = 0, 1, 2, \dots, n$ and at all other points $f(x) = \varphi(x) + R(x)$ where $R(x)$ is called *error term* of the interpolation formula. Ignoring the error term let us assume

$$f(x) \approx \varphi(x) = a_0 + a_1(x - x_n) + a_2(x - x_n)(x - x_{n-1}) + \dots + a_n(x - x_n)(x - x_{n-1}) \dots (x - x_1)$$

putting $x = x_n$ we get

$$f(x_n) \approx \varphi(x_n) = a_0$$

$$\therefore a_0 = y_n$$

putting $x = x_{n-1}$ we get

$$f(x_{n-1}) \approx \varphi(x_{n-1}) = a_0 + a_1(x_{n-1} - x_n) = y_n + a_1(-h)$$

putting $x = x_{n-2}$ we get

$$f(x_{n-2}) \approx \varphi(x_{n-2}) = a_0 + a_1(x_{n-2} - x_n) + a_2(x_{n-2} - x_n)(x_{n-2} - x_{n-1})$$

$$y_{n-2} = y_n + \nabla y_n/h (-2h) + a_2(-2h)(-h)$$

$$y_{n-2} = y_n - 2y_n + 2y_{n-1} + a_2(2h^2)$$

$$y_n - 2y_{n-1} + y_{n-2}$$

$$a_2 = \frac{2h^2}{\nabla^2 y_n}$$

$$\therefore a_2 = \frac{-}{2! h^2}$$

Similarly,

$$a_3 = \frac{\nabla^3 y_n}{3! h^3}, \quad a_4 = \frac{\nabla^4 y_n}{4! h^4}, \quad \dots, \quad a_n = \frac{\nabla^n y_n}{n! h^n}$$

putting the values of a_0, a_1, \dots, a_n we get

$$f(x) \approx \varphi(x) = y_n + (\nabla y_n/h)(x-x_n) + (\nabla^2 y_n / (2! h^2)) (x-x_n)(x-x_{n-1}) + \dots \dots \\ \dots \dots + (\nabla^n y_n / (n! h^n)) (x-x_n)(x-x_{n-1}) \dots \dots (x-x_1)$$

writing $u = ((x-x_n)/h)$, we get

$$x-x_n = uh$$

$$x-x_{n-1} = (x-x_n) + (x_n - x_{n-1}) = (u+1)h$$

Similarly,

$$x-x_{n-2} = (u+2)h$$

$$x-x_{n-3} = (u+3)h$$

.....

$$x-x_1 = (u+n-1)h$$

$$f(x) \approx \varphi(x) = y_n + u (\nabla y_n / 1!) + u (u+1) (\nabla^2 y_n) / 2! + \dots \dots \\ \dots \dots + u (u+1) (u+2) \dots \dots (u+n-1) (\nabla^n y_n) / n!$$

The above formula is called *Newton's backward interpolation formula*.

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4
5 int main()
6 {
7     int n, i, j, fact;
8     double x, y, h, u, ans, tempU;
9     vector<double> allX;
10    vector<vector<double>> allY;
11
12    while (true) {
13        cout << "Number of points in the table: ";
14        cin >> n;
15
16        if (!n) {
17            break;
18        }
19
20        allX.assign(n, 0);
21        allY.assign(n, vector<double>());
22        for (i = 0; i < n; i++) {
23            cout << "Enter x" << i << " y" << i << "\n";
24            cin >> allX[i] >> y;
25            allY[0].push_back(y);
26        }
27
28        cout << "Value for x: ";
29        cin >> x;
30
31        for (i = 1; i < n; i++) {
32            for (j = 1; j < allY[i - 1].size(); j++) {
33                y = allY[i - 1][j] - allY[i - 1][j - 1];
34                allY[i].push_back(y);
35            }
36        }
37
38        h = allX[1] - allX[0];
39        u = (x - allX[n - 1]) / h;
40
41        ans = allY[0][n - 1];
42        for (i = 1, fact = 1; i < n; i++) {
43            tempU = u;
44            for (j = 1; j < i; j++) {
45                tempU *= (u + j);
46            }
47            fact *= i;
48            ans += (tempU * allY[i][allY[i].size() - 1]) / (fact * 1.0
49        );
50    }
51    cout << "f(" << x << ") = " << ans << "\n";
52}
53
54 return 0;
55 }
```

Sample I/O

Number of points in the table: 5

Enter x0 y0: 1 1

Enter x1 y1: 2 8

Enter x2 y2: 3 27

Enter x3 y3: 4 64

Enter x4 y4: 5 125

Value for x: 4.7

$f(4.7) = 103.823$

Number of points in the table: 6

Enter x0 y0: 1961 20

Enter x1 y1: 1971 27

Enter x2 y2: 1981 39

Enter x3 y3: 1991 52

Enter x4 y4: 2001 70

Enter x5 y5: 2011 90

Value for x: 2006

$f(2006) = 80.6211$

Problem

2-4: The following values of $f(x)$ are given:

x	1	2	3	4	5
$y = f(x)$	1	8	27	64	125

Write a program to find value of x for which $f(x) = 85$ by using Lagrange's Inverse Interpolation formula.

Theory

We know, the Lagrange interpolation formula is

$$y = f(x) = \frac{(x-x_1)(x-x_2)\dots(x-x_n)}{(x_0-x_1)(x_0-x_2)\dots(x_0-x_n)}f(x_0) + \frac{(x-x_0)(x-x_2)\dots(x-x_n)}{(x_1-x_0)(x_1-x_2)\dots(x_1-x_n)}f(x_1) \\ + \dots + \frac{(x-x_0)(x-x_2)\dots(x-x_{n-1})}{(x_n-x_0)(x_n-x_2)\dots(x_n-x_{n-1})}f(x_n)$$

By interchanging x and y we can express x as a function of y as follows:

$$x = \frac{(y-y_1)(y-y_2)\dots(y-y_n)}{(y_0-y_1)(y_0-y_2)\dots(y_0-y_n)}x_0 + \frac{(y-y_0)(y-y_2)\dots(y-y_n)}{(y_1-y_0)(y_1-y_2)\dots(y_1-y_n)}x_1 \\ + \dots + \frac{(y-y_0)(y-y_2)\dots(y-y_{n-1})}{(y_n-y_0)(y_n-y_2)\dots(y_n-y_{n-1})}x_n$$

This is called *Lagrange's inverse interpolation formula*.

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4
5 int main()
6 {
7     int n, i, j;
8     double x, y, ans, numerator, denominator;
9     vector<double> allX;
10    vector<double> allY;
11
12    while (true) {
13        cout << "Number of points in the table: ";
14        cin >> n;
15
16        if (!n) {
17            break;
18        }
19
20        allX.assign(n, 0);
21        allY.assign(n, 0);
22        for (i = 0; i < n; i++) {
23            cout << "Enter x" << i << " y" << i << "\n";
24            cin >> allX[i] >> allY[i];
25        }
26
27        cout << "Value for x: ";
28        cin >> x;
29
30        ans = 0.0;
31        for (i = 0; i < n; i++) {
32            numerator = denominator = 1.0;
33            for (j = 0; j < n; j++) {
34                if (j == i) {
35                    continue;
36                }
37
38                numerator *= (x - allX[j]);
39                denominator *= (allX[i] - allX[j]);
40            }
41            ans += (numerator * allY[i]) / denominator;
42        }
43
44        cout << "f(" << x << ") = " << ans << "\n";
45    }
46
47    return 0;
48 }

```

Sample I/O

Number of points in the table: 5

Enter x0 y0: 1 1

Enter x1 y1: 8 2

Enter x2 y2: 27 3

Enter x3 y3: 64 4

Enter x4 y4: 125 5

Value for x: 85

$f(85) = 5.64691$

Number of points in the table: 5

Enter x0 y0: 2 10.0123

Enter x1 y1: 4 13.0234

Enter x2 y2: 6 16.045

Enter x3 y3: 7 20.123

Enter x4 y4: 8 25.234

Value for x: 5

$f(5) = 13.7645$

Problem

2-5: The following values of $f(x)$ are given:

x	1	3	4	6	10
$y = f(x)$	0	18	58	190	920

Write a program to find $f(2.7)$ by using Newton's Divided Difference formula.

Theory

Let $y = f(x)$ be a function which assumes the values $f(x_0), f(x_1), f(x_2), \dots, f(x_n)$ corresponding to the values $x = x_0, x_1, x_2, \dots, x_n$ where the values of x are not necessarily equispaced. From the definition of divided difference

$$f[x, x_0] = \frac{f(x) - f(x_0)}{x - x_0}$$
$$f(x) = f(x_0) + (x-x_0)f[x, x_0] \dots \dots \dots \dots (1)$$

Again,

$$f[x, x_0, x_1] = \frac{f[x, x_0] - f[x_0, x_1]}{x - x_1}$$

$$f[x, x_0] = f[x_0, x_1] + (x-x_1)f[x, x_0, x_1] \dots \dots \dots \dots (2)$$

Substituting in (1) we get,

$$f(x) = f(x_0) + (x-x_0)f[x_0, x_1] + (x-x_0)(x-x_1)f[x, x_0, x_1]$$

Proceeding in this way we get,

$$f(x) = f(x_0) + (x-x_0)f[x_0, x_1] + (x-x_0)(x-x_1)f[x_0, x_1, x_2] + \dots \dots \dots \dots$$
$$+ (x-x_0)(x-x_1) \dots \dots (x-x_{n-1})f[x_0, x_1, \dots, x_n]$$
$$+ (x-x_0)(x-x_1) \dots \dots (x-x_n)f[x, x_0, x_1, \dots, x_n]$$

If $f(x)$ is a polynomial of degree n then, the $(n+1)^{\text{th}}$ order divided differences of $f(x)$ will be zero.

$$\therefore f[x_0, x_1, \dots, x_n] = 0$$

Hence, $f(x) = f(x_0) + (x-x_0)f[x_0, x_1] + (x-x_0)(x-x_1)f[x_0, x_1, x_2] + \dots \dots \dots \dots$
$$+ (x-x_0)(x-x_1) \dots \dots (x-x_{n-1})f[x_0, x_1, \dots, x_n]$$

This is called *Newton's divided difference formula*.

```

1 #include <bits/stdc++.h>
2
3 using namespace std;
4
5 int main()
6 {
7     int n, i, j, k;
8     double x, y, ans, temp;
9     vector<vector<double>> allX, allY;
10
11    while (true) {
12        cout << "Number of points in the table: ";
13        cin >> n;
14
15        if (!n) {
16            break;
17        }
18
19        allX.assign(n, vector<double>());
20        allY.assign(n, vector<double>());
21        for (i = 0; i < n; i++) {
22            cout << "Enter x" << i << " y" << i << "\n";
23            cin >> x >> y;
24            allX[0].push_back(x);
25            allY[0].push_back(y);
26        }
27
28        // denominator table
29        for (i = 1; i < n; i++) {
30            for (j = 0, k = j + i; j < n && k < n; j++, k++) {
31                x = allX[0][k] - allX[0][j];
32                allX[i].push_back(x);
33            }
34        }
35
36        for (i = 1; i < n; i++) {
37            for (j = 1; j < allY[i - 1].size(); j++) {
38                y = (allY[i - 1][j] - allY[i - 1][j - 1]) / (allX[i][j - 1]);
39                allY[i].push_back(y);
40            }
41        }
42
43        cout << "Enter value for x: ";
44        cin >> x;
45
46        ans = allY[0][0];
47        for (i = 1; i < n; i++) {
48            temp = 1.0;
49            for (j = 0; j < i; j++) {
50                temp *= (x - allX[0][j]);
51            }
52            ans += (temp * allY[i][0]);
53        }
54
55        cout << f( " << x << " ) = " << ans << "\n";
56    }
57
58    return 0;
59
60

```

Sample I/O

Number of points in the table: 5

Enter x0 y0: 1 0

Enter x1 y1: 3 18

Enter x2 y2: 4 58

Enter x3 y3: 6 190

Enter x4 y4: 10 920

Value for x: 2.7

$f(2.7) = 9.35463$

Number of points in the table: 5

Enter x0 y0: 2 10.012

Enter x1 y1: 4 12.123

Enter x2 y2: 5 14.234

Enter x3 y3: 7 18.123

Enter x4 y4: 9 22.342

Value for x: 4.2

$f(4.2) = 12.5318$