

Summary: Wavelet Scattering Net

- ▶ Architecture:
 - ▶ Convolutional filters: band-limited wavelets
 - ▶ Nonlinear activation: modulus (Lipschitz)
 - ▶ Pooling: L1 norm as averaging

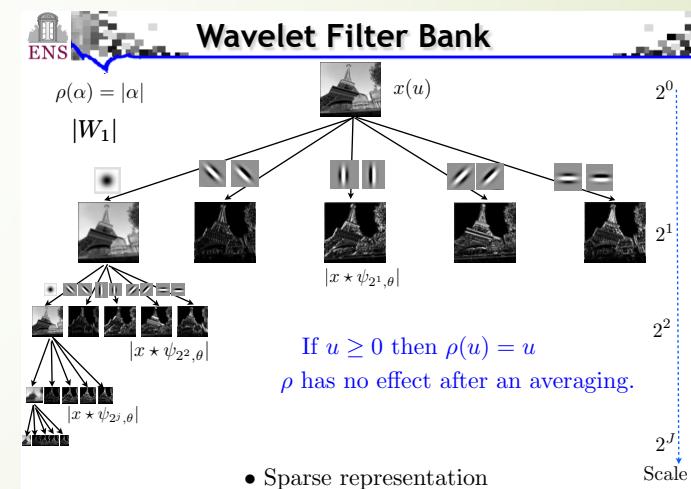
- ▶ Properties:
 - ▶ A Multiscale Sparse Representation
 - ▶ Norm Preservation (Parseval's identity):

$$\|Sx\| = \|x\|$$

- ▶ Contraction:

$$\|Sx - Sy\| \leq \|x - y\|$$

$$Sx = \begin{pmatrix} x * \phi(u) \\ |x * \psi_{\lambda_1}| * \phi(u) \\ ||x * \psi_{\lambda_1}| * \psi_{\lambda_2}| * \phi(u) \\ |||x * \psi_{\lambda_2}| * \psi_{\lambda_3}| * \phi(u) \\ \dots \\ u, \lambda_1, \lambda_2, \lambda_3, \dots \end{pmatrix}$$



Invariants/Stability of Scattering Net

► Translation Invariance:

- The average $|x \star \psi_{\lambda_1}| \star \phi(t)$ is invariant to small translations relatively to the support of ϕ .
- Full translation invariance at the limit:

$$\lim_{\phi \rightarrow 1} |x \star \psi_{\lambda_1}| \star \phi(t) = \int |x \star \psi_{\lambda_1}(u)| du = \|x \star \psi_{\lambda_1}\|_1$$

► Stable Small Deformations:

stable to deformations $x_\tau(t) = x(t - \tau(t))$

$$\|Sx - Sx_\tau\| \leq C \sup_t |\nabla \tau(t)| \|x\|$$

Feature Extraction

Linearized Classification

Joan Bruna

- Each class X_k is represented by a scattering centroid $E(SX_k)$
Affine space model $\mathbf{A}_k = E(SX_k) + \mathbf{V}_k$. computed with PCA.

MNIST data basis:

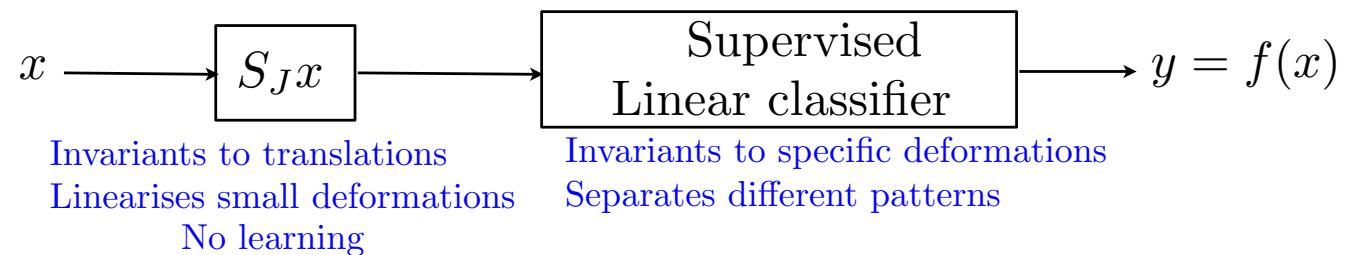
3	6	8	1	7	9	6	6	9	1
6	7	5	7	8	6	3	4	8	5
2	1	7	9	7	1	2	8	4	6
4	8	1	9	0	1	8	8	9	4



Digit Classification: MNIST

3 6 8 1 7 9 6 6 9 1
6 7 5 7 8 6 3 4 8 5
2 1 7 9 7 1 2 8 4 5
4 8 1 9 0 1 8 8 9 4

Joan Bruna



Classification Errors

Training size	Conv. Net.	Scattering
50000	0.4%	0.4%

LeCun et. al.



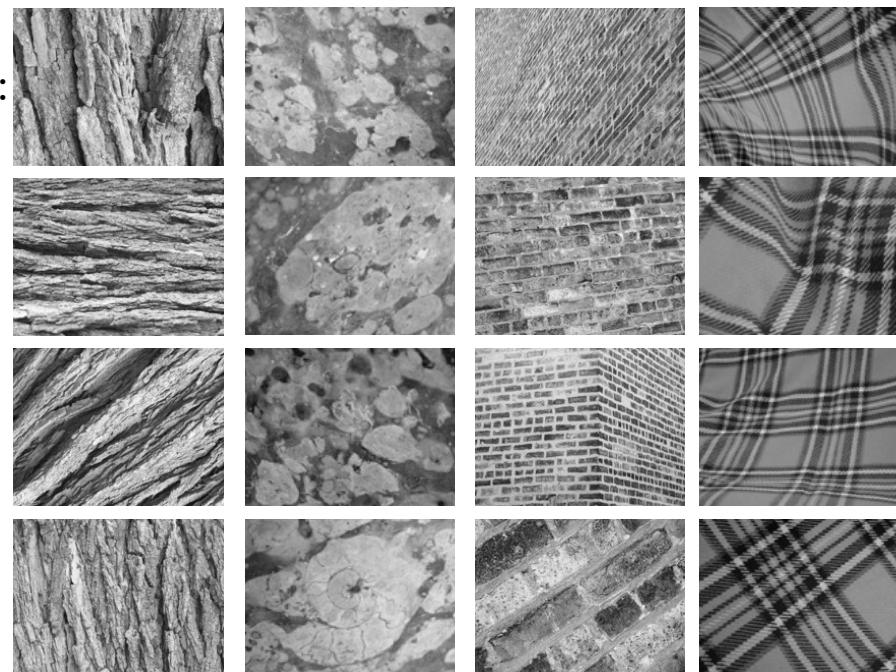
*Other Invariants?
General Convolutional
Neural Networks?*



Rotation and Scaling Invariance

Laurent Sifre

UIUC database:
25 classes

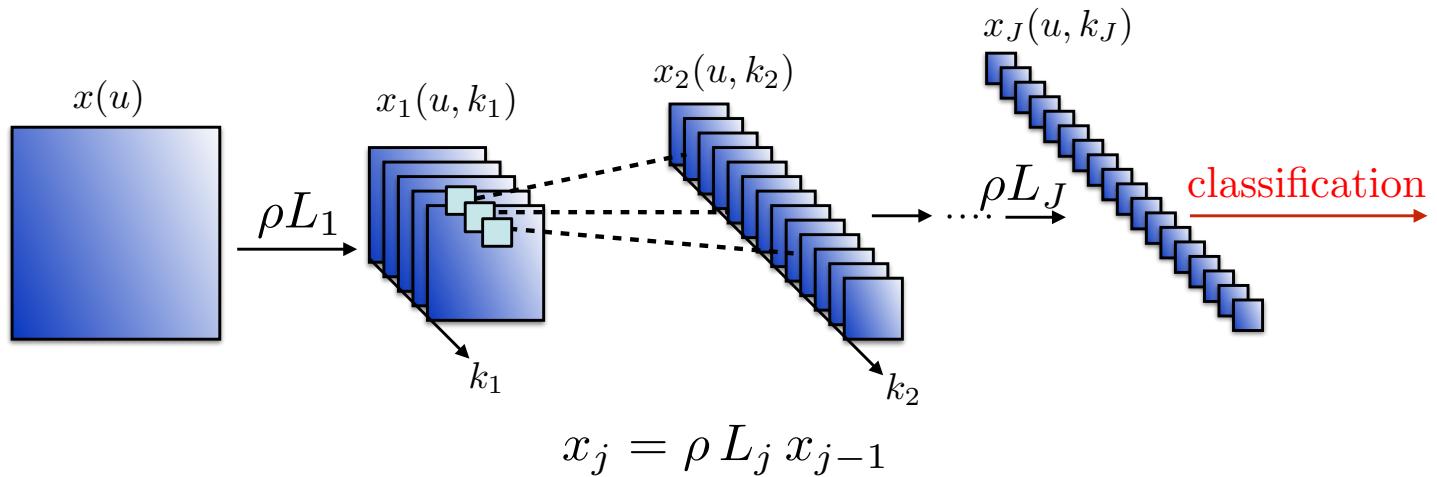


Scattering classification errors

Training	Scat. Translation
20	20 %



Deep Convolutional Trees



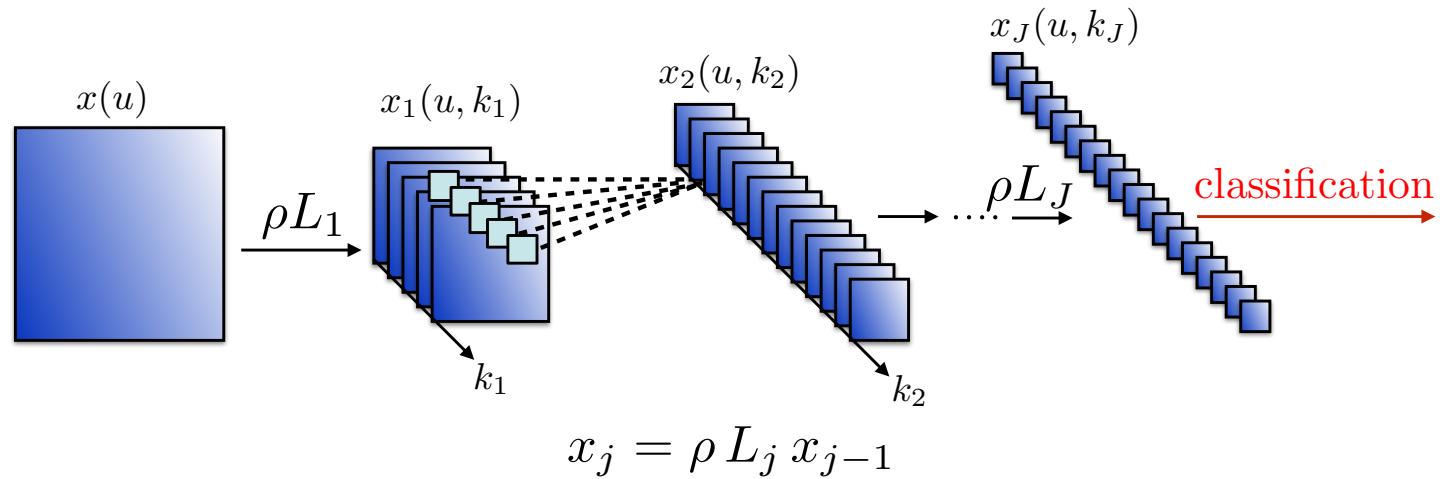
L_j is composed of convolutions and subs samplings:

$$x_j(u, k_j) = \rho(x_{j-1}(\cdot, k) \star h_{k_j, k}(u))$$

No channel communication: what limitations ?



Deep Convolutional Networks



- L_j is a linear combination of convolutions and subsampling:

$$x_j(u, k_j) = \rho \left(\sum_k x_{j-1}(\cdot, k) \star h_{k_j, k}(u) \right)$$

sum across channels

What is the role of channel connections ?

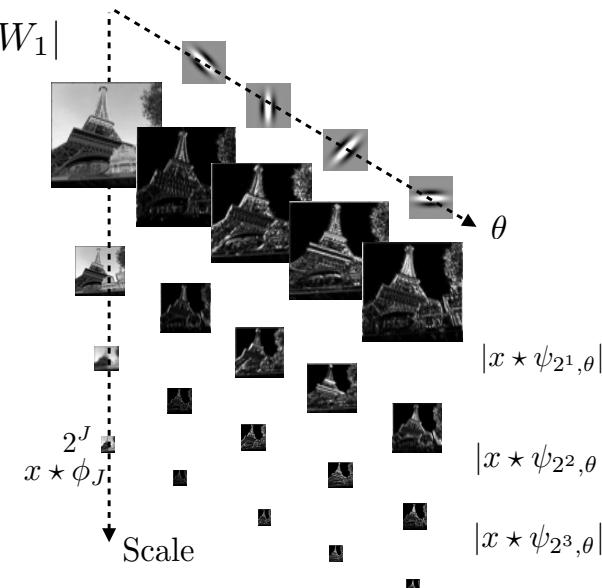
Linearize other symmetries beyond translations.



ENS

Rotation Invariance

- Channel connections linearize other symmetries.



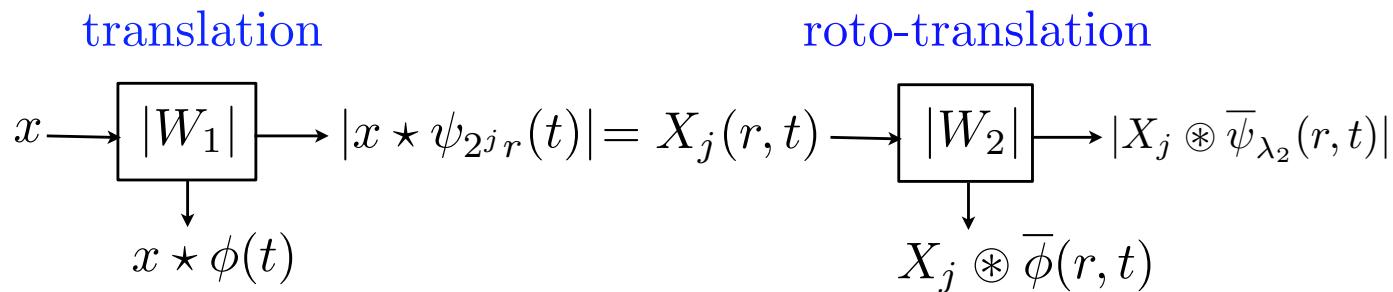
- Invariance to rotations are computed by convolutions along the rotation variable θ with wavelet filters.
⇒ invariance to rigid movements.

Wavelet Transform on a Group

Laurent Sifre

- Roto-translation group $G = \{g = (r, t) \in SO(2) \times \mathbb{R}^2\}$

$$(r, t) \cdot x(u) = x(r^{-1}(u - t))$$
 - Averaging on G :
$$X \circledast \bar{\phi}(g) = \int_G X(g') \bar{\phi}(g'^{-1}g) dg'$$
 - Wavelet transform on G :
$$W_2 X = \begin{pmatrix} X \circledast \bar{\phi}(g) \\ X \circledast \bar{\psi}_{\lambda_2}(g) \end{pmatrix}_{\lambda_2, g}.$$





Wavelet Transform on a Group

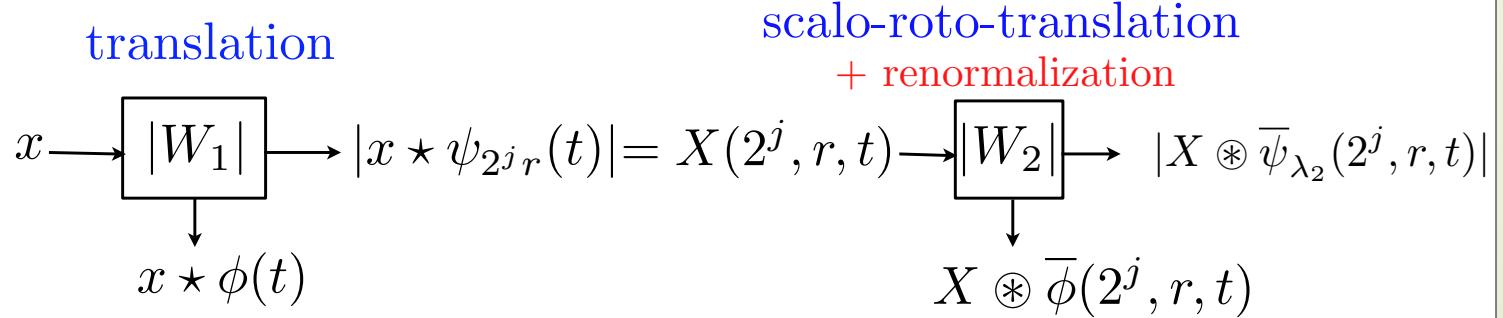
Laurent Sifre

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$$(r, t) \cdot x(u) = x(r^{-1}(u - t))$$

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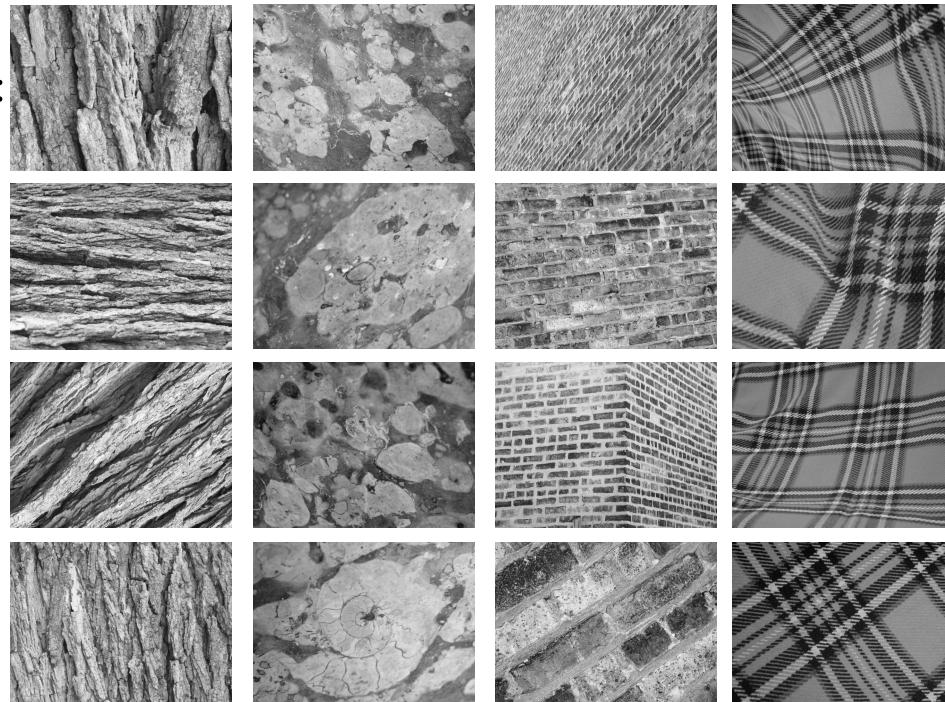
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Rotation and Scaling Invariance

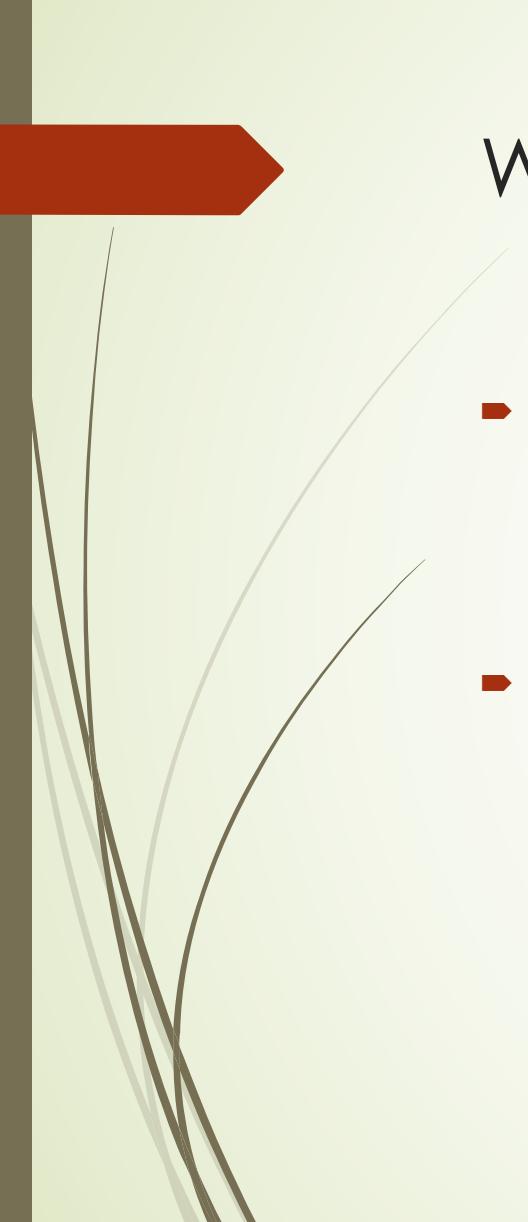
Laurent Sifre

UIUC database:
25 classes



Scattering classification errors

Training	Translation	Transl + Rotation	+ Scaling
20	20 %	2%	0.6%

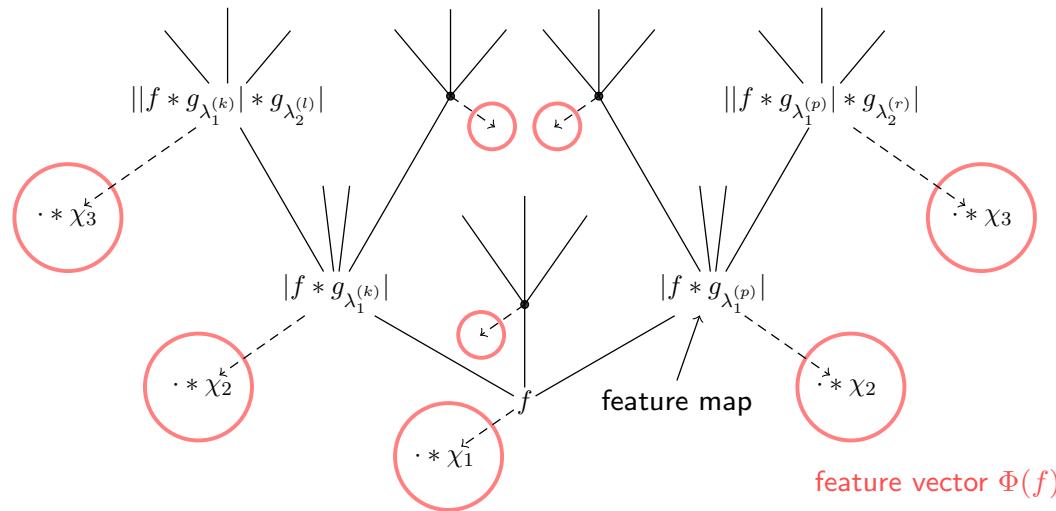


Wiatowski-Bolcskei'15

- ▶ Scattering Net by Mallat et al. so far
 - ▶ Wavelet Linear filter
 - ▶ Nonlinear activation by modulus
 - ▶ Average pooling
- ▶ Generalization by Wiatowski-Bolcskei'15
 - ▶ Filters as frames
 - ▶ Lipschitz continuous Nonlinearities
 - ▶ General Pooling: Max/Average/Nonlinear, etc.

Generalization of Wiatowski-Bolcskei'15

Scattering networks ([Mallat, 2012], [Wiatowski and HB, 2015])



General scattering networks guarantee [Wiatowski & HB, 2015]

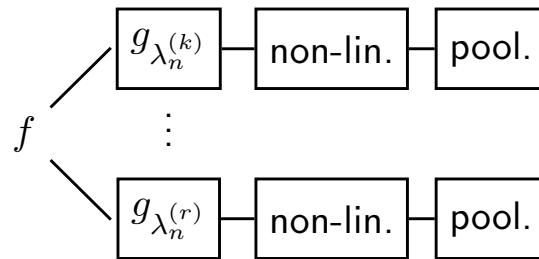
- (vertical) **translation invariance**
- **small deformation sensitivity**

essentially irrespective of filters, non-linearities, and poolings!

Wavelet basis -> filter frame

Building blocks

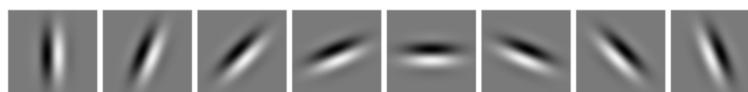
Basic operations in the n -th network layer



Filters: Semi-discrete frame $\Psi_n := \{\chi_n\} \cup \{g_{\lambda_n}\}_{\lambda_n \in \Lambda_n}$

$$A_n \|f\|_2^2 \leq \|f * \chi_n\|_2^2 + \sum_{\lambda_n \in \Lambda_n} \|f * g_{\lambda_n}\|^2 \leq B_n \|f\|_2^2, \quad \forall f \in L^2(\mathbb{R}^d)$$

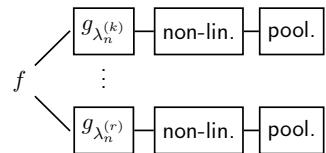
e.g.: Structured filters



Frames: random or learned filters

Building blocks

Basic operations in the n -th network layer



Filters: Semi-discrete frame $\Psi_n := \{\chi_n\} \cup \{g_{\lambda_n}\}_{\lambda_n \in \Lambda_n}$

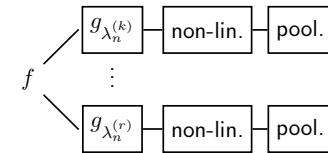
$$A_n \|f\|_2^2 \leq \|f * \chi_n\|_2^2 + \sum_{\lambda_n \in \Lambda_n} \|f * g_{\lambda_n}\|^2 \leq B_n \|f\|_2^2, \quad \forall f \in L^2(\mathbb{R}^d)$$

e.g.: Unstructured filters



Building blocks

Basic operations in the n -th network layer



Filters: Semi-discrete frame $\Psi_n := \{\chi_n\} \cup \{g_{\lambda_n}\}_{\lambda_n \in \Lambda_n}$

$$A_n \|f\|_2^2 \leq \|f * \chi_n\|_2^2 + \sum_{\lambda_n \in \Lambda_n} \|f * g_{\lambda_n}\|^2 \leq B_n \|f\|_2^2, \quad \forall f \in L^2(\mathbb{R}^d)$$

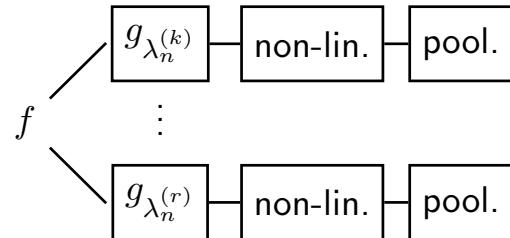
e.g.: Learned filters



Nonlinear activations

Building blocks

Basic operations in the n -th network layer



Non-linearities: Point-wise and Lipschitz-continuous

$$\|M_n(f) - M_n(h)\|_2 \leq L_n \|f - h\|_2, \quad \forall f, h \in L^2(\mathbb{R}^d)$$

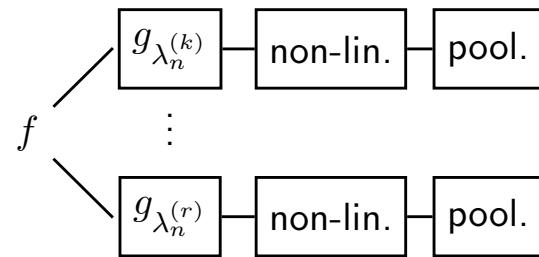
⇒ Satisfied by virtually **all** non-linearities used
in the **deep learning literature!**

ReLU: $L_n = 1$; modulus: $L_n = 1$; logistic sigmoid: $L_n = \frac{1}{4}$; ...

Pooling

Building blocks

Basic operations in the n -th network layer



Pooling: In continuous-time according to

$$f \mapsto S_n^{d/2} P_n(f)(S_n \cdot),$$

where $S_n \geq 1$ is the **pooling factor** and $P_n : L^2(\mathbb{R}^d) \rightarrow L^2(\mathbb{R}^d)$ is R_n -Lipschitz-continuous

⇒ Emulates most **poolings** used in the **deep learning literature!**

e.g.: Pooling by **sub-sampling** $P_n(f) = f$ with $R_n = 1$

e.g.: Pooling by **averaging** $P_n(f) = f * \phi_n$ with $R_n = \|\phi_n\|_1$



Vertical translation invariance

Theorem (Wiatowski and HB, 2015)

Assume that the filters, non-linearities, and poolings satisfy

$$B_n \leq \min\{1, L_n^{-2} R_n^{-2}\}, \quad \forall n \in \mathbb{N}.$$

Let the pooling factors be $S_n \geq 1$, $n \in \mathbb{N}$. Then,

$$|||\Phi^n(T_t f) - \Phi^n(f)||| = \mathcal{O}\left(\frac{\|t\|}{S_1 \dots S_n}\right),$$

for all $f \in L^2(\mathbb{R}^d)$, $t \in \mathbb{R}^d$, $n \in \mathbb{N}$.

The condition

$$B_n \leq \min\{1, L_n^{-2} R_n^{-2}\}, \quad \forall n \in \mathbb{N},$$

is **easily satisfied** by **normalizing** the filters $\{g_{\lambda_n}\}_{\lambda_n \in \Lambda_n}$.



Vertical translation invariance

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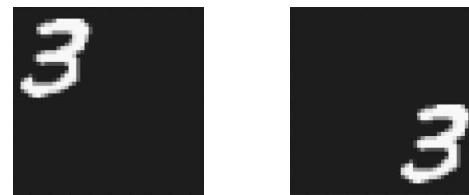
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⇒ Features become **more invariant** with **increasing** network **depth**!





Vertical translation invariance

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for all $f \in L^2(\mathbb{R}^d)$, $t \in \mathbb{R}^d$, $n \in \mathbb{N}$.

Full translation invariance: If $\lim_{n \rightarrow \infty} S_1 \cdot S_2 \cdot \dots \cdot S_n = \infty$, then

$$\lim_{n \rightarrow \infty} |||\Phi^n(T_t f) - \Phi^n(f)||| = 0$$



Philosophy behind invariance results

Mallat's "horizontal" translation invariance [[Mallat, 2012](#)]:

$$\lim_{J \rightarrow \infty} |||\Phi_W(T_t f) - \Phi_W(f)||| = 0, \quad \forall f \in L^2(\mathbb{R}^d), \forall t \in \mathbb{R}^d$$

- features become invariant in every network layer, but needs $J \rightarrow \infty$
- applies to wavelet transform and modulus non-linearity without pooling

"Vertical" translation invariance:

$$\lim_{n \rightarrow \infty} |||\Phi^n(T_t f) - \Phi^n(f)||| = 0, \quad \forall f \in L^2(\mathbb{R}^d), \forall t \in \mathbb{R}^d$$

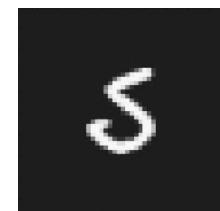
- features become more invariant with increasing network depth
- applies to general filters, general non-linearities, and general poolings



Non-linear deformations

Non-linear deformation $(F_\tau f)(x) = f(x - \tau(x))$, where $\tau : \mathbb{R}^d \rightarrow \mathbb{R}^d$

For “small” τ :

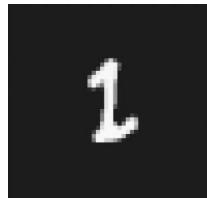




Non-linear deformations

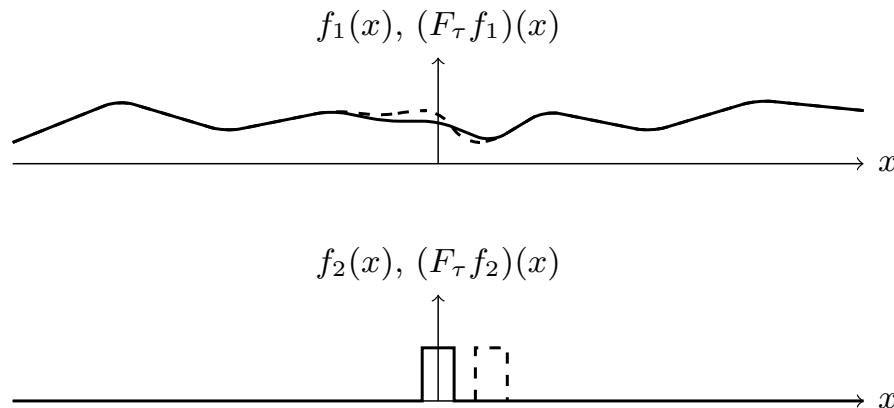
Non-linear deformation $(F_\tau f)(x) = f(x - \tau(x))$, where $\tau : \mathbb{R}^d \rightarrow \mathbb{R}^d$

For “large” τ :



Deformation sensitivity for signal classes

Consider $(F_\tau f)(x) = f(x - \tau(x)) = f(x - e^{-x^2})$



For given τ the amount of deformation induced
can depend drastically on $f \in L^2(\mathbb{R}^d)$



Wiatowski-Bolcskei'15 Deformation Stability Bounds

Philosophy behind deformation stability/sensitivity bounds

Mallat's deformation stability bound [[Mallat, 2012](#)]:

$$|||\Phi_W(F_\tau f) - \Phi_W(f)||| \leq C(2^{-J}\|\tau\|_\infty + J\|D\tau\|_\infty + \|D^2\tau\|_\infty)\|f\|_W,$$

for all $f \in H_W \subseteq L^2(\mathbb{R}^d)$

- The signal class H_W and the corresponding norm $\|\cdot\|_W$ depend on the mother wavelet (and hence the network)

Our deformation sensitivity bound:

$$|||\Phi(F_\tau f) - \Phi(f)||| \leq C_{\mathcal{C}}\|\tau\|_\infty^\alpha, \quad \forall f \in \mathcal{C} \subseteq L^2(\mathbb{R}^d)$$

- The signal class \mathcal{C} (band-limited functions, cartoon functions, or Lipschitz functions) is independent of the network

Wiatowski-Bolcskei'15 Deformation Stability Bounds

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for all $f \in H_W \subseteq L^2(\mathbb{R}^d)$

- Signal class description complexity implicit via norm $\|\cdot\|_W$

Our deformation sensitivity bound:

$$|||\Phi(F_\tau f) - \Phi(f)||| \leq C_{\mathcal{C}}\|\tau\|_\infty^\alpha, \quad \forall f \in \mathcal{C} \subseteq L^2(\mathbb{R}^d)$$

- Signal class description complexity explicit via $C_{\mathcal{C}}$
 - L -band-limited functions: $C_{\mathcal{C}} = \mathcal{O}(L)$
 - cartoon functions of size K : $C_{\mathcal{C}} = \mathcal{O}(K^{3/2})$
 - M -Lipschitz functions $C_{\mathcal{C}} = \mathcal{O}(M)$



Philosophy behind deformation stability/sensitivity bounds

Mallat's deformation stability bound [[Mallat, 2012](#)]:

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for all $f \in H_W \subseteq L^2(\mathbb{R}^d)$

- The bound depends explicitly on higher order derivatives of τ

Our deformation sensitivity bound:

$$\|\Phi(F_\tau f) - \Phi(f)\| \leq C_c \|\tau\|_\infty^\alpha, \quad \forall f \in \mathcal{C} \subseteq L^2(\mathbb{R}^d)$$

- The bound implicitly depends on derivative of τ via the condition $\|D\tau\|_\infty \leq \frac{1}{2d}$



Philosophy behind deformation stability/sensitivity bounds

Mallat's deformation stability bound [Mallat, 2012]:

$$|||\Phi_W(F_\tau f) - \Phi_W(f)||| \leq C(2^{-J}\|\tau\|_\infty + J\|D\tau\|_\infty + \|D^2\tau\|_\infty)\|f\|_W,$$

for all $f \in H_W \subseteq L^2(\mathbb{R}^d)$

- The bound is *coupled* to horizontal translation invariance

$$\lim_{J \rightarrow \infty} |||\Phi_W(T_t f) - \Phi_W(f)||| = 0, \quad \forall f \in L^2(\mathbb{R}^d), \forall t \in \mathbb{R}^d$$

Our deformation sensitivity bound:

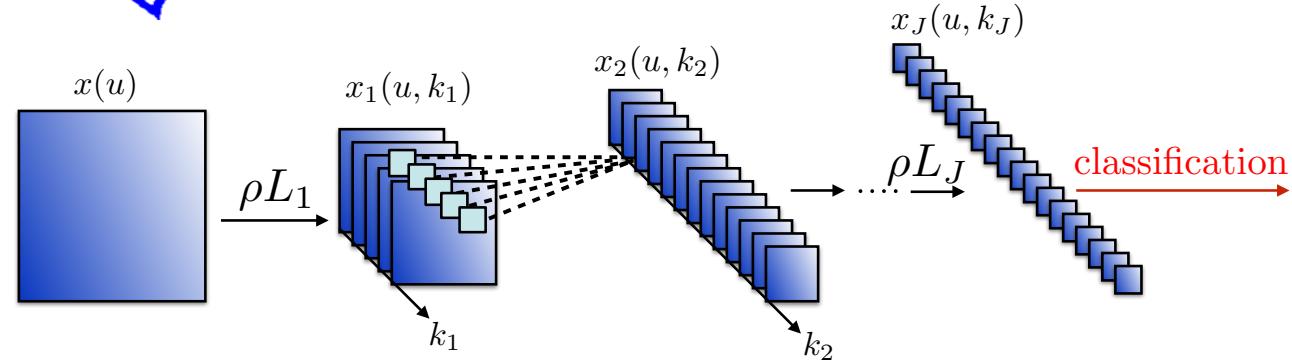
$$|||\Phi(F_\tau f) - \Phi(f)||| \leq C_C \|\tau\|_\infty^\alpha, \quad \forall f \in \mathcal{C} \subseteq L^2(\mathbb{R}^d)$$

- The bound is *decoupled* from vertical translation invariance

$$\lim_{n \rightarrow \infty} |||\Phi^n(T_t f) - \Phi^n(f)||| = 0, \quad \forall f \in L^2(\mathbb{R}^d), \forall t \in \mathbb{R}^d$$



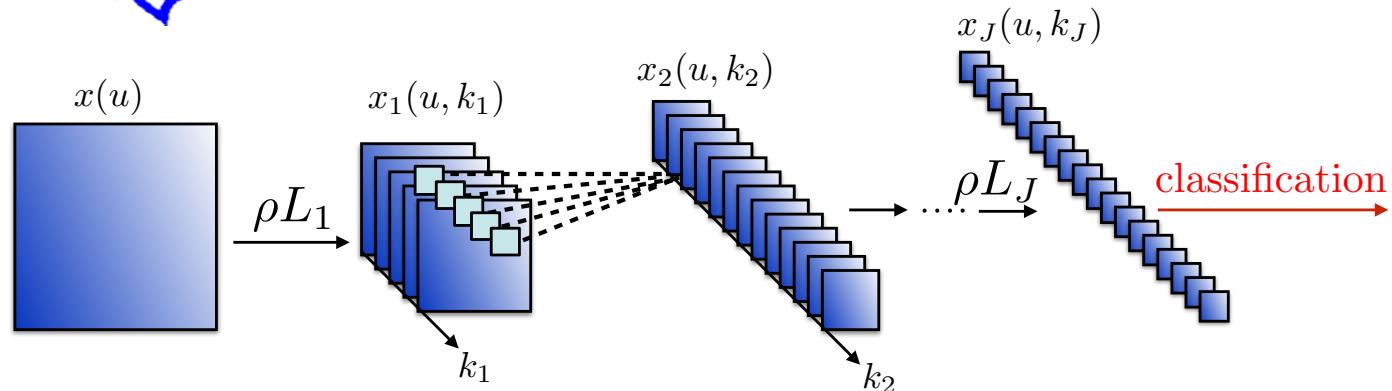
Deep Convolutional Networks



- The convolution network operators L_j have many roles:
 - Linearize non-linear transformations (symmetries)
 - Reduce dimension with projections
 - Memory storage of « characteristic » structures
- Difficult to separate these roles when analyzing learned networks



Open Problems



- Can we recover symmetry groups from the matrices L_j ?
- What kind of groups ?
- Can we characterise the regularity of $f(x)$ from these groups ?
- Can we define classes of high-dimensional « regular » functions that are well approximated by deep neural networks ?
- Can we get approximation theorems giving errors depending on number of training examples, with a fast decay ?