

Metric/Nonmetric Sammon Mapping

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TBD

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1 Introduction

In engineering and computer science *Sammon Mapping* is a popular multidimensional scaling (MDS) method. The technique was introduced in Sammon Jr (1969). It was originally intended to map points from a higher-dimensional Euclidean space into points in a lower-dimensional Euclidean space by approximating the given higher dimensional distances by best-fitting lower dimensional ones. The *MASS* package for R implemented the *sammon()* function, which generalizes the original idea by allowing the higher-dimensional distances to be replaced by any positive symmetric matrix of dissimilarities. This was again generalized in the packages *staps* (Rusch, Mair, and Hornik (2023)) and *smacofx* (Rusch et al. (2025)) where optimization is over low-dimensional configurations and over power transforms of the dissimilarities.

The Sammon loss function is

$$\sigma(X, \Delta) = \frac{1}{\sum \sum_{1 \leq i < j \leq n} w_{ij} \delta_{ij}} \sum \sum_{1 \leq i < j \leq n} w_{ij} \frac{(\delta_{ij} - d_{ij}(X))^2}{\delta_{ij}}. \quad (1)$$

The metric MDS problem we address in this paper is minimizing (1) over the $n \times p$ configurations X . In the non-metric case we minimize in addition over the symmetric non-negative and hollow matrices $\Delta := \{\delta_{ij}\}$, where the δ_{ij} are monotone with the given dissimilarities.

2 Properties

The usual stress loss function in *smacof*, due originally to Kruskal (1964a) and Kruskal (1964b), is

$$\sigma(X, \Delta) = \frac{\sum \sum_{1 \leq i < j \leq n} w_{ij} (\delta_{ij} - d_{ij}(X))^2}{\sum \sum_{1 \leq i < j \leq n} w_{ij} \delta_{ij}^2}. \quad (2)$$

If we compare (1) and (2) we see that in Kruskal's stress the sum of the squared residuals is normalized by dividing by the sum of the squared dissimilarities. This means minimum stress is between zero and one, and it also prevents us from considering the trivial zero-residual solution $X = 0$ and $\Delta = 0$. In Sammon loss each residual is normalized separately, based on the idea that large dissimilarities are somehow less reliable or stable and should be downweighted.

If δ_{ij} and $d_{ij}(X)$ are close then

$$\sqrt{d_{ij}(X)} - \sqrt{\delta_{ij}} \approx \frac{1}{2} \frac{1}{\sqrt{\delta_{ij}}} (d_{ij}(X) - \delta_{ij}), \quad (3)$$

and thus

$$\sum w_{ij} \frac{(\delta_{ij} - d_{ij}(X))^2}{\delta_{ij}} \approx 4 \sum w_{ij} (\sqrt{\delta_{ij}} - \sqrt{d_{ij}(X)})^2 \quad (4)$$

The loss function on the right-hand side of (4), which we will informally call *sqr-stress*, is the special case of *rStress* with $r = \frac{1}{4}$ (De Leeuw, Groenen, and Mair (2016)).

3 Algorithm

In metric (ratio) MDS we minimize over X for fixed Δ . This is a standard metric scaling problem with weights $w_{ij}\delta_{ij}^{-1}$. We use majorization steps to decrease loss. This is identical to the ratio sammon option in *smacofx*. In the non-metric case we use alternating least squares, i.e. we alternate majorization steps with minimizing over Δ , satisfying the ordinal constraints, for fixed X . As far as I know this has not been implemented before, and is somewhat non-standard. First, use the fact that $\sigma(\lambda X, \lambda \Delta) = \sigma(X, \Delta)$

$$\min_X \sigma(X, \Delta) = \min_X \sigma(X, \lambda \Delta), \quad (5)$$

i.e. the problem is homogeneous of degree zero in Δ . Thus we can require without loss of generality that

$$\sum \sum_{1 \leq i < j \leq n} w_{ij} \delta_{ij} = 1. \quad (6)$$

With this normalization we have

$$\sigma(X, \Delta) = 1 - 2 \sum \sum_{1 \leq i < j \leq n} w_{ij} d_{ij}(X) + \sum \sum_{1 \leq i < j \leq n} w_{ij} \frac{d_{ij}^2(X)}{\delta_{ij}} \quad (7)$$

Thus minimizing ω for fixed X over non-negative, isotone and normalized Δ means minimizing the third term on the right. And this means minimizing a separable, differentiable, and strictly convex function over a polyhedral convex set.

To simplify notation we define the extended real valued function f equal to

$$f(x) := \sum_{i=1}^n w_i \frac{y_i}{x_i} \quad (8)$$

if $x_i > 0$ for all i , and to $+\infty$ otherwise. Thus the effective domain $\text{dom}(f)$ is the interior of the positive orthant. In the context of Sammon Mapping the y_i are squared distances and the x_i are the transformed dissimilarities.

The *Sammon Monotone Regression* or SMR problem is defined as minimization of f over the intersection of the polyhedral convex cone \mathcal{K} defined by $0 < x_1 \leq \dots \leq x_n$ and the affine set

\mathcal{A} defined by $w'x = 1$. We assume that all w_i and all y_i are positive, and that the w_i add up to one.

The first and second partials of f are

$$\mathcal{D}_i f(x) = -w_i \frac{y_i}{x_i^2}, \quad (9)$$

$$\mathcal{D}_{ii} f(x) = 2w_i \frac{y_i}{x_i^3}, \quad (10)$$

and $\mathcal{D}_{ik} f(x) = 0$ if $i \neq k$. This shows f is convex and twice differentiable on $\text{dom}(f)$, and thus on the intersection with $\mathcal{K} \cap \mathcal{A}$.

First some preliminary results.

Lemma 3.1.

$$\min_{x \in \mathcal{K} \cap \mathcal{A}} f(x) \leq w'y \quad (11)$$

Proof. The vector x with $x_i = 1$ for all i is in $\mathcal{K} \cap \mathcal{A}$. □

It follows from Lemma 3.1 that we can add the constraint $f(x) \leq w'y$ to the minimization problem and still have the same minimum and minimizer.

Lemma 3.2. *Suppose $y_1 \leq \dots \leq y_n$. Then*

$$\bar{x}_i = \frac{\sqrt{y_i}}{\sum_{k=1}^n w_k \sqrt{y_k}}. \quad (12)$$

Proof. The necessary conditions for a minimum of f on \mathcal{A} are

$$-w_i \frac{y_i}{x_i^2} = \lambda w_i, \quad (13)$$

for all i , together with the side condition $w'x = 1$. From (13) it follows that the solution \bar{x} must be proportional to \sqrt{y} , where the square root can have either sign. Of the 2^n solutions only one is in the effective domain of f , the one for which all square roots are taken with a positive sign. This solution is also in \mathcal{K} . Applying the side condition gives (12). □

The next rather trivial lemma deals with the case $n = 1$, in which w, x and y are one-element vectors, which identify with the corresponding scalars.

Lemma 3.3. *If $n = 1$ then the minimizer \bar{x} is equal to one and the minimum is y .*

Proof. w adds up to one, so $w = 1$. Also wx must be one, so $\bar{x} = 1$. \square

The following theorem is of prime importance, because it shows the SMR problem can be solved with a variation of the Pool Adjacent Violaters Algorithm (PAVA). For the details on PAVA, see for example De Leeuw, Hornik, and Mair (2009).

Theorem 3.1. *Suppose \bar{x} is the optimum solution. If $y_i \geq y_{i+1}$ then $\bar{x}_i = \bar{x}_{i+1}$.*

Proof. We show that $y_i \geq y_{i+1}$ and $\bar{x}_i < \bar{x}_{i+1}$ leads to a contradiction. A necessary and sufficient condition for \bar{x} to be the optimum solution is

$$(x - \bar{x})' \mathcal{D}f(\bar{x}) = - \sum_{i=1}^n w_i \frac{y_i}{\bar{x}_i^2} (x_i - \bar{x}_i) = f(\bar{x}) - \sum_{i=1}^n w_i \frac{y_i}{\bar{x}_i^2} x_i \geq 0 \quad (14)$$

for all $x \in \mathcal{K} \cap \mathcal{A}$ (Hiriart-Urruty and Lemaréchal (1993), Theorem 1.1.1, page 293).

Now suppose $\bar{x}_i < \bar{x}_{i+1}$. Then for $\epsilon > 0$ small enough

$$z = \bar{x} + \epsilon \left(\frac{e_i}{w_i} - \frac{e_{i+1}}{w_{i+1}} \right) \quad (15)$$

is also in $\mathcal{K} \cap \mathcal{A}$. In (15) we add a small amount to \bar{x}_i and subtract a small amount from \bar{x}_{i+1} , while leaving all other elements of \bar{x} unperturbed. Since

$$\sum_{i=1}^n w_i \frac{y_i}{\bar{x}_i^2} z_i = f(\bar{x}) + \epsilon \left(\frac{y_i}{\bar{x}_i^2} - \frac{y_{i+1}}{\bar{x}_{i+1}^2} \right) \quad (16)$$

we must have

$$\frac{y_i}{\bar{x}_i^2} \leq \frac{y_{i+1}}{\bar{x}_{i+1}^2} \quad (17)$$

But $y_i \geq y_{i+1}$ and $\bar{x}_i < \bar{x}_{i+1}$ implies

$$\frac{y_i}{\bar{x}_i^2} > \frac{y_{i+1}}{\bar{x}_{i+1}^2} \quad (18)$$

and thus \bar{x} cannot be the optimal solution. \square

Theorem 3.1 can be used to replace an SMR problem of size n with an SMR problem of size $n - 1$. If $y_i \geq y_{i+1}$ we remove these two y -values and put the single value

$$\tilde{y}_i := \frac{w_i y_i + w_{i+1} y_{i+1}}{w_i + w_{i+1}} \quad (19)$$

in their place. This new value gets the weight $\tilde{w}_i := w_i + w_{i+1}$.

Theorem 3.2. Suppose \hat{x} solves the monotone regression problem for the weighted least squares norm

$$\hat{x} := \underset{x_1 \leq \dots \leq x_n}{\operatorname{argmin}} (x - y)' W (x - y) \quad (20)$$

then

$$\bar{x}_i = \frac{\sqrt{\hat{x}_i}}{\sum_{k=1}^n w_k \sqrt{\hat{x}_k}} \quad (21)$$

solves the SMR problem.

Proof. We use Theorem 3.1 repeatedly until we have an SMR problem of size r for which $\tilde{y}_1 < \dots < \tilde{y}_r$. We can use the same sequence of pooling adjacent violators as in least squares monotone regression, and we find the same weighted average pooled values in each step. When we have reduced the problem to a strictly increasing \tilde{y} sequence we apply Lemma 3.2 (and if $r = 1$ we apply Lemma 3.3). We then expand each block again to a length equal to the number of averaged elements. \square

A small example illustrates our PAVA variation. Start with y equal to $(1, 2, 3, 1, 2, 3, 5, 1)$ and w equal to $(1, 1, 1, 1, 1, 1, 1, 1)$. Merge elements 3 and 4 to get $y = (1, 2, 2, 2, 3, 5, 1)$ and $w = (1, 1, 2, 1, 1, 1, 1)$. Now merge elements 2, 3, and 4 to get $y = (1, 2, 3, 5, 1)$ and $w = (1, 4, 1, 1, 1)$. Merge 4 and 5 to get $y = (1, 2, 3, 3)$ and $w = (1, 4, 1, 2)$ and finally merge 3 and 4 to get $y = (1, 2, 3)$ and $w = (1, 4, 3)$. Thus

$$\bar{x} = \frac{1}{1 + 4\sqrt{2} + 3\sqrt{3}} (1, \sqrt{2}, \sqrt{2}, \sqrt{2}, \sqrt{2}, \sqrt{3}, \sqrt{3}, \sqrt{3})$$

Remember that in the context of Sammon Mapping the least squares monotone regression has to be done on the squared distances.

4 Examples

4.1 Results

Numerical Sammon mapping takes 21 iterations to arrive at stress 0.0222606801. For ordinal we need 31 iterations for stress 0.0006660664. Since the ordinal fit is very good the sqrt-stress of (4) should be close to Sammon stress. It is 0.0006701850.

For the Morse code data numerical Sammon mapping takes 99 iterations to arrive at stress 0.0977737, for ordinal we need 92 iterations for stress 0.0398178. Because the fit is much worse than in the Ekman case we do not expect sqrt-stress to be close to Sammon stress. For the ordinal case final sqrt-stress is 0.0445148.

4.2 Timing

The results of a comparison of the R and C implementations of Sammon mapping with microbenchmark (Mersmann (2024)) yields the times in microseconds in the following table.

Unit: microseconds

	expr	min	lq	mean
	smacofSSSammonR(ekmanData, ordinal = FALSE)	1624.584	1694.4685	1958.5417
	smacofSSSammonC(ekmanData, ordinal = FALSE)	298.193	318.1600	338.2229
	smacofSSSammonR(ekmanData, ordinal = TRUE)	10767.953	11144.2510	12111.8748
	smacofSSSammonC(ekmanData, ordinal = TRUE)	525.989	567.1325	672.8375
	smacofSS(ekmanData, ordinal = FALSE)	259.940	276.7295	289.6978
	smacofSS(ekmanData, ordinal = TRUE)	967.764	1037.9355	1142.9222
median	uq	max	neval	
1733.8490	1765.2140	20538.007	100	
332.2025	352.7230	433.083	100	
11342.2810	11505.2150	22628.966	100	
575.9680	590.6050	5144.065	100	
286.2620	298.7055	357.479	100	
1055.1760	1074.0155	9417.905	100	

Unit: milliseconds

	expr	min	lq	mean
	smacofSSSammonR(morseData, ordinal = FALSE)	38.153288	40.545412	44.831142
	smacofSSSammonC(morseData, ordinal = FALSE)	3.619603	3.844590	3.914574
	smacofSSSammonR(morseData, ordinal = TRUE)	425.866549	447.049281	463.749984
	smacofSSSammonC(morseData, ordinal = TRUE)	4.882649	5.214195	5.317852
	smacofSS(morseData, ordinal = FALSE)	1.564027	1.660111	1.742756
	smacofSS(morseData, ordinal = TRUE)	2.579187	2.700527	2.865947
median	uq	max	neval	
42.262861	43.966227	109.556059	100	
3.901888	3.954204	5.391992	100	
455.434867	467.828306	577.709598	100	
5.331250	5.386026	6.830272	100	
1.683194	1.754390	5.064894	100	
2.770821	2.851673	6.140857	100	

Unit: microseconds

	expr	min	lq	mean
	smacofSSSammonR(wishData, ordinal = FALSE)	5568.415	5754.2680	6031.8761

smacofSSSammonC(wishData, ordinal = FALSE)	357.110	386.2405	441.1522
smacofSSSammonR(wishData, ordinal = TRUE)	15313.254	15889.4475	16975.3760
smacofSSSammonC(wishData, ordinal = TRUE)	591.302	617.8700	633.4627
smacofSS(wishData, ordinal = FALSE)	216.275	233.2285	288.7671
smacofSS(wishData, ordinal = TRUE)	1000.769	1090.3950	1138.7574
median	uq	max	neval
5875.1360	5975.7500	9804.535	100
394.5225	423.2020	3961.461	100
16095.9235	18080.9180	27165.411	100
626.8080	643.2900	743.822	100
240.2190	255.9425	4485.113	100
1106.9180	1123.3795	4550.016	100

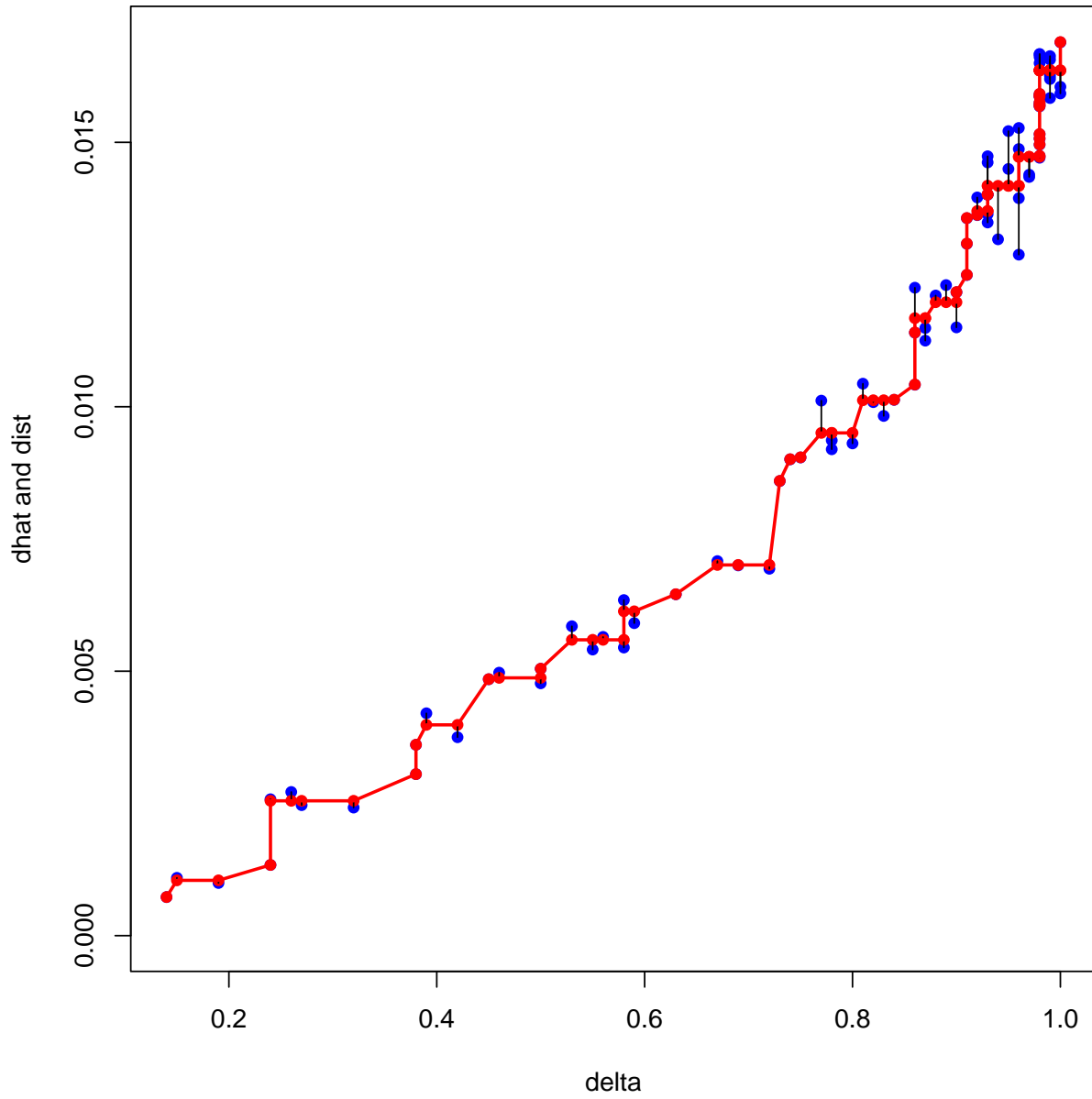
Unit: microseconds

	expr	min	lq	mean
smacofSSSammonR(gruijterData, ordinal = FALSE)	8908.193	9296.1760	9823.1437	
smacofSSSammonC(gruijterData, ordinal = FALSE)	334.314	359.2830	369.9188	
smacofSSSammonR(gruijterData, ordinal = TRUE)	8032.146	8218.4295	8853.6597	
smacofSSSammonC(gruijterData, ordinal = TRUE)	412.255	428.9830	448.2731	
smacofSS(gruijterData, ordinal = FALSE)	157.645	166.8290	179.2746	
smacofSS(gruijterData, ordinal = TRUE)	474.616	508.4205	523.1342	
median	uq	max	neval	
9493.6525	9695.5160	13150.176	100	
366.7245	378.4505	423.448	100	
8371.9745	8537.5325	21884.611	100	
437.9415	459.9585	583.266	100	
171.9950	185.2380	279.866	100	
517.0715	532.7335	649.317	100	

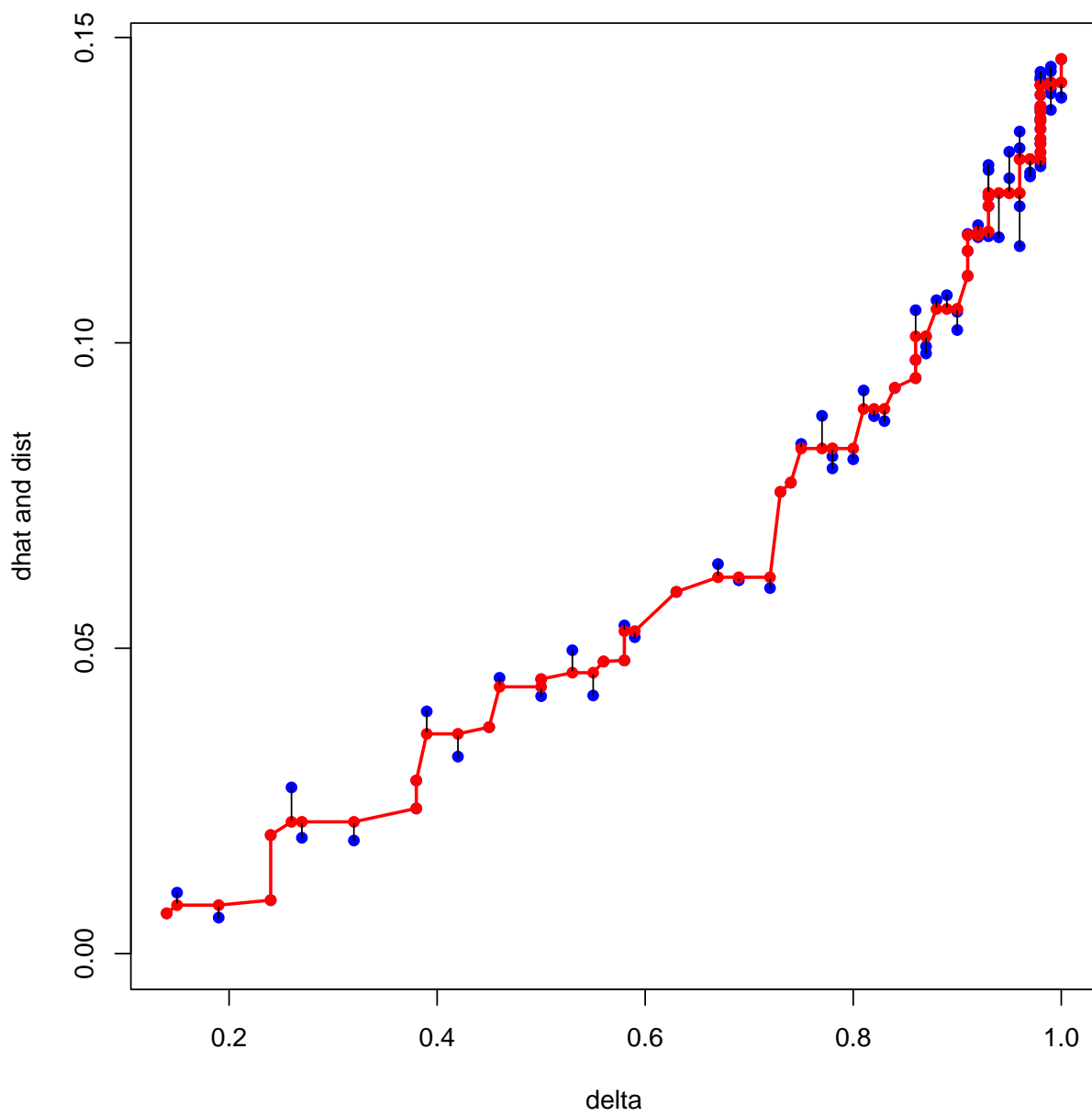
Of course these microbenchmark results depend on the default parameters of the programs (same in R and C), on the speed of my computer (Mac Mini with Apple M4 Pro, 64 GB of RAM, Tahoe 26.2, Apple clang 17.0.0), and on my programming habits (same in R and C).

4.3 Plots

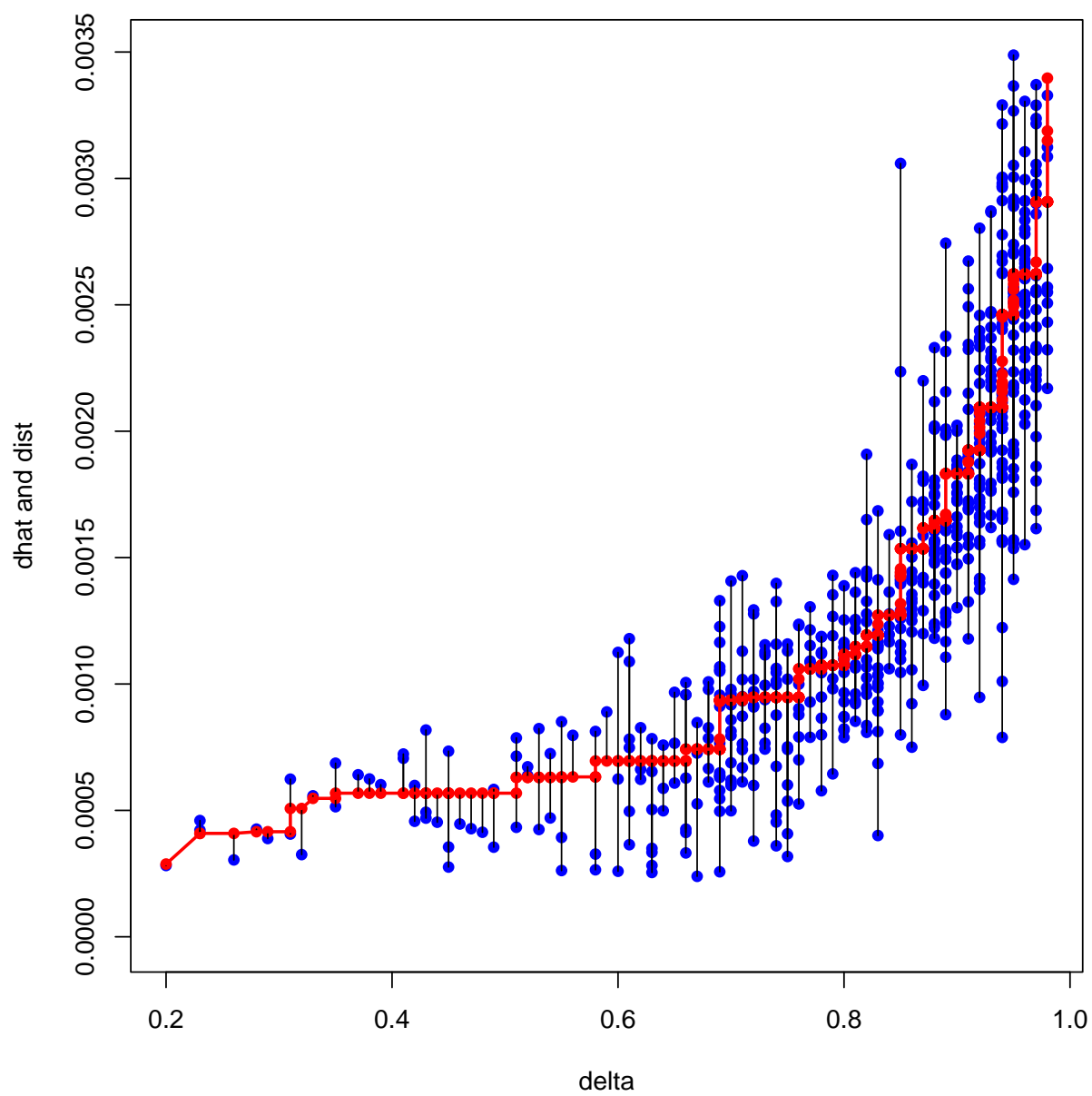
Shepard Plot Ekman, Sammon



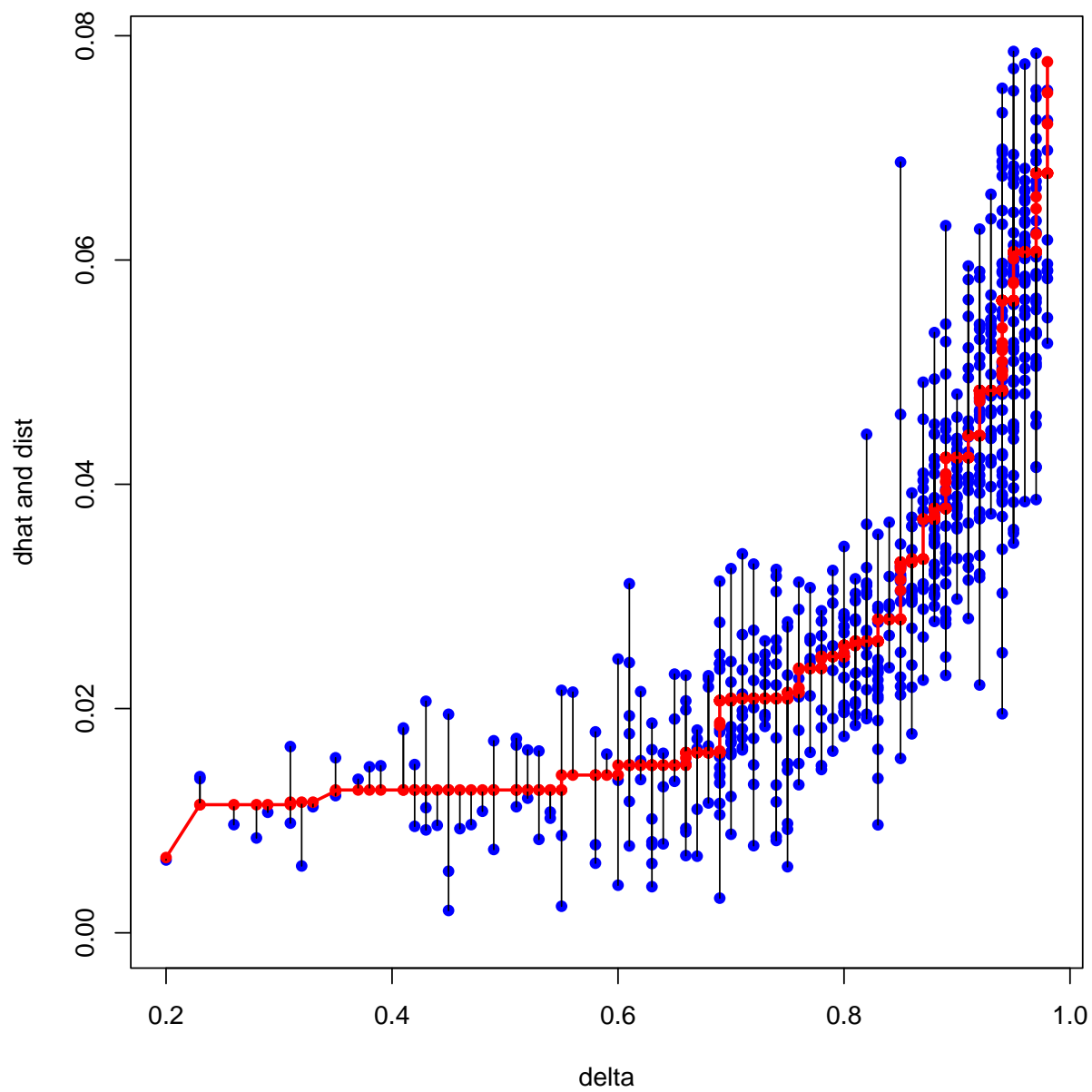
Shepard Plot Ekman, Kruskal



Shepard Plot Morse, Sammon



Shepard Plot Morse, Kruskal



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