MAMMA: a 1-D steady state model of volcanic conduits

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MAMMA (Magma Ascent Mathematical Modeling and Analysis) is a FORTRAN code designed to solve a conservative model for steady magma ascent in a volcanic conduit, described as a compressible multicomponent two-phase flow. It is an open-source code mainly developed by Mattia de'Michieli Vitturi.

1 System of equations

The system of conservation equations is derived from the theory of thermodynamically compatible systems [1], considering the effects of the main processes that magmas experience during ascent, such as crystallization, rheological changes, fragmentation, injection of external water, physical interaction with conduit walls, vertical outgassing and lateral degassing. The system is described as a mixture of two phases ($i = 1, 2$), each one characterized by a volume fraction (α_i), density (ρ_i), velocity (u_i) and specific entropy (s_i). Below the fragmentation level, phase 1 is a mixture of crystals, dissolved volatiles and melt (continuous phase); while phase 2 is composed by the exsolved gas bubbles (dispersed phase). Above magma fragmentation, phase 1 is constituted by magma fragments (dispersed phase) and phase 2 is the exsolved gas mixture (continuous phase). Magma fragmentation occurs when the exsolved gas volume fraction reaches a critical value ($\alpha_g = \alpha_2 = \alpha_{cr}$) [2] (Fig. 1).

The components of the system are characterized by an equation of state; while pressure (p_i) and temperature (T_i) of both phases are derived from the internal energy (e_i):

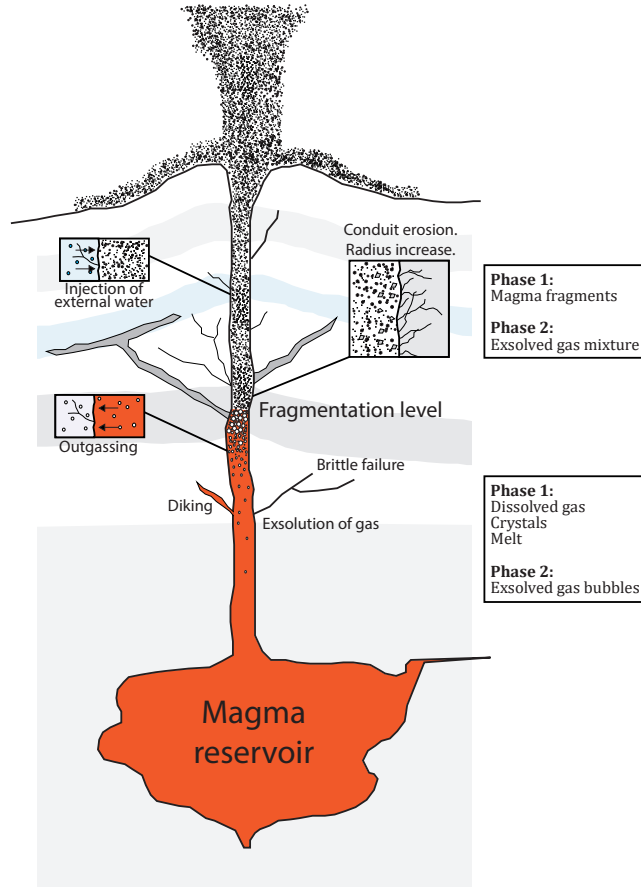$$p_i = \rho_i^2 \frac{\partial e_i}{\partial \rho_i} \tag{1}$$

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Figure 1: Schematic illustration of volcanic conduits.

$$T_i = \frac{\partial e_i}{\partial s_i} \tag{2}$$

The model is capable of describing conduits with elliptical cross section and depth-dependent dimensions, and it includes the conservation laws of total mass (Eq. 3), momentum (Eq. 4) and energy (Eq. 5).

$$\frac{\partial}{\partial z}\left(\rho u R_{eq}^2\right) = 2J_{ex}f_{\epsilon_1}R_{eq} - 2J_{lat}f_{\epsilon_1}R_{eq} \tag{3}$$

$$\frac{\partial}{\partial z}\left(\left(\alpha_1(\rho_1 u_1^2 + p_1) + \alpha_2(\rho_2 u_2^2 + p_2)\right)R_{eq}^2\right)$$
$$= -\rho g R_{eq}^2 - 2J_{lat}f_{\epsilon_1}u_2 R_{eq} - \frac{8\chi_1\mu u_1}{f_{\epsilon_2}^2} - \frac{\chi_2\lambda_w\rho_2 u_2^2 R_{eq}}{4f_{\epsilon_2}^2} + (\chi_1 p_1 + \chi_2 p_2)\frac{\partial(R_{eq}^2)}{\partial z} \tag{4}$$

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$$\frac{\partial}{\partial z}\left(\left(\left(\alpha_1\rho_1 u_1\left(e_1+\frac{p_1}{\rho_1}+\frac{u_1^2}{2}\right)+\alpha_2\rho_2 u_2\left(e_2+\frac{p_2}{\rho_2}+\frac{u_2^2}{2}\right)\right.\right.\right.$$

$$\left.\left.\left.-\,\rho x_1 x_2(u_1-u_2)(s_1-s_2)T\right)R_{eq}^2\right)=-\rho g u R_{eq}^2-(\chi_1 p_1 u_1+\chi_2 p_2 u_2)\frac{\partial(R_{eq}^2)}{\partial z}\right. \tag{5}$$

$$+\,2J_{ex}f_{\epsilon_1}c_w T_w R_{eq}-2J_{lat}f_{\epsilon_1}\left(c_g T+\frac{u_2^2}{2}\right)R_{eq}$$

where z is the vertical coordinate, ρ is mixture density, u is mixture velocity, R_{eq} is the equivalent conduit radius (Eq. 6), J_{ex} is the mass flux of external water, f_{ϵ_1} is a conduit eccentricity-derived factor (Eq. 7), J_{lat} is the lateral gas flux through conduit walls, g is the acceleration of gravity, χ_i controls the inclusion of wall friction (1 or 0, function of the continuous phase index), μ is mixture viscosity, f_{ϵ_2} is an additional conduit eccentricity-derived factor (Eq. 8), λ_w is a drag coefficient [3], x_i is the mass fraction of phase i, T is mixture temperature, c_w is the isochoric specific heat of external water, T_w is the external water temperature and c_g is the isochoric specific heat of exsolved gas.

$$R_{eq}=\sqrt{R_a\cdot R_b} \tag{6}$$

$$f_{\epsilon_1}=\frac{3(1+\sqrt{1-\epsilon^2})-\sqrt{(3+\sqrt{1-\epsilon^2})\cdot(1+3\sqrt{1-\epsilon^2})}}{2\cdot\sqrt[4]{1-\epsilon^2}} \tag{7}$$

$$f_{\epsilon_2}=\sqrt{\frac{2\sqrt{1-\epsilon^2}}{2-\epsilon^2}} \tag{8}$$

where R_a is the maximum semi-axis, R_b is the minimum semi-axis and ϵ is conduit eccentricity (Eq. 9).

$$\epsilon=\sqrt{1-\frac{R_b^2}{R_a^2}} \tag{9}$$

Phase 1 volume fraction is governed by the following equation:

$$\frac{\partial}{\partial z}\left(\rho u\alpha_1 R_{eq}^2\right)=-\frac{1}{\tau^{(p)}}(p_2-p_1)R_{eq}^2 \tag{10}$$

where $\tau^{(p)}$ is the relaxation parameter which controls the pressure difference between both phases ($[\mathrm{m}^2/\mathrm{s}]$).

Furthermore, the model includes an additional equation for controlling the relative veloc-

ity between the phases:

$$\frac{\partial}{\partial z}\left(\left(\frac{u_1^2}{2} - \frac{u_2^2}{2} + e_1 - e_2 + \frac{p_1}{\rho_1} - \frac{p_2}{\rho_2} - (s_1 - s_2)T\right)R_{eq}^2\right)$$
$$= -\frac{8\chi_1\mu u_1}{\alpha_1\rho_1 f_{\epsilon_2}^2} + \frac{\chi_2\lambda_w u_2^2 R_{eq}}{4\alpha_2 f_{\epsilon_2}^2} - \frac{\rho}{\rho_1\rho_2}\delta_f(u_1 - u_2)R_{eq}^2 \tag{11}$$

where δ_f is the drag factor ($[\mathrm{kg/m^3 s}]$).

Finally, the system of equations presents the mass conservation laws of crystals (Eq. 12), dissolved gas (Eq. 13) and exsolved gas (Eq. 14), and it allows to consider different crystalline and gas phases (n_{cry} and n_{gas}, respectively).

$$\frac{\partial}{\partial z}\left(\alpha_1\rho_{c_j}\alpha_{c_j}u_1 R_{eq}^2\right) = -\frac{1}{\tau^{(c_j)}}\alpha_1\rho_{c_j}(\alpha_{c_j} - \alpha_{c_j}^{eq})R_{eq}^2 \tag{12}$$

$$\frac{\partial}{\partial z}\left(x_{d_k}\alpha_1\left(\rho_1 - \sum_{j=1}^{n_{cry}}(\alpha_{c_j}\rho_{c_j})\right)u_1 R_{eq}^2\right)$$
$$= 2J_{ex}f_{\epsilon_1}\psi_k R_{eq} - \frac{(x_{d_k} - x_{d_k}^{eq})}{\tau^{(d_k)}}\alpha_1\left(\rho_1 - \sum_{j=1}^{n_{cry}}(\alpha_{c_j}\rho_{c_j})\right)R_{eq}^2 \tag{13}$$

$$\frac{\partial}{\partial z}\left(\alpha_{g_k}\rho_{g_k}u_2 R_{eq}^2\right)$$
$$= -2J_{lat}x_{g_k}f_{\epsilon_1}R_{eq} + \frac{(x_{d_k} - x_{d_k}^{eq})}{\tau^{(d_k)}}\alpha_1\left(\rho_1 - \sum_{j=1}^{n_{cry}}(\alpha_{c_j}\rho_{c_j})\right)R_{eq}^2 \tag{14}$$

where ρ_{c_j} is density of the j-th crystalline phase ($j = 1, ..., n_{cry}$), α_{c_j} is the volume fraction of the j-th crystalline phase in phase 1, $\tau^{(c_j)}$ is the crystallization relaxation parameter of the j-th crystalline phase ($[\mathrm{s}]$), $\alpha_{c_j}^{eq}$ is the equilibrium value of α_{c_j}, x_{d_k} is the dissolved mass fraction of the k-th volatile specie ($k = 1, ..., n_{gas}$) in the phase composed by melt and dissolved gas, ψ_k controls the inclusion of external water in the conservation equations ($\psi_k = 1$ for $k = 1$ and $\psi_k = 0$ for $k > 1$), $\tau^{(d_k)}$ is the relaxation parameter which controls the exsolution rate of the k-th volatile specie ($[\mathrm{s}]$), $x_{d_k}^{eq}$ is the equilibrium value of x_{d_k}, α_{g_k} and ρ_{g_k} are volume fraction and density of exsolved gas of the k-th volatile specie, and x_{g_k} is the mass fraction of the k-th volatile specie in phase 2. Please note that water is represented by the first volatile specie ($k = 1$).

For the model solution, it employs a numerical shooting technique: for a given inlet pres-

sure, the model adjusts the inlet flow rate until the appropriate boundary condition (choked flow or atmospheric pressure) is reached. For the spatial integration of the equations, a well-established PI step-size control technique is adopted, with the relaxation terms treated implicitly to guarantee the stability of the numerical scheme.

2 Constitutive equations

In order to offer the possibility of describing the behaviour of a wide range of magma compositions and volcanic phenomena, a complete set of constitutive equations has been implemented in the code.

2.1 Viscosity models

Since it has been suggested a strong effect of crystal content [4, 5, 6] and exsolved gas bubbles [5, 7] on the resulting mixture rheology, magma viscosity (μ) is evaluated using the following expression:

$$\mu = \mu_{melt} \cdot \theta_c(\alpha_c) \cdot \theta_g(\alpha_g) \tag{15}$$

where μ_{melt} is the crystal and bubble-free viscosity; whereas $\theta_c(\alpha_c)$ and $\theta_g(\alpha_g)$ account for the effect of crystals (Eq. 16) and bubbles on the resulting viscosity, respectively.

$$\alpha_c = \sum_{j=1}^{n_{cry}} \alpha_{c_j} \tag{16}$$

The following models are implemented for calculating μ_{melt}, while the available expressions for calculating θ_c and θ_g are shown in Tables 1 and 2 and Figs. 2 and 3.

2.1.1 Hess and Dingwell [24]

This model is based on a multiple non-linear regression of 111 measurements of viscosity, and is adapted for studying rhyolitic magmas:

$$\log_{10}(\mu_{melt}) = -3.545 + 0.833 \cdot \ln(w) + \frac{9601 - 2368 \cdot \ln(w)}{T - (195.7 + 32.25 \cdot \ln(w))} \tag{17}$$

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Table 1: Available models for calculating $\theta_c(\alpha_c)$ in MAMMA.

Model	Equation	Auxiliary variables
None	$\theta_c = 1.0$	
Costa [4]	$\theta_c = \left(1 - c_1 \cdot \mathrm{erf}\left(\frac{\sqrt{\pi}}{2}\alpha_c\left(1 + \frac{c_2}{(1-\alpha_c)^{c_3}}\right)\right)\right)^{\frac{c_4}{c_1}}$	$c_1 = 0.9995.$ $c_2 = 0.4.$ $c_3 = 1.0.$ $c_4 = -2.5.$
Dingwell [8]	$\theta_c = \left(1 + 0.75 \cdot \frac{\alpha_c}{c - \alpha_c}\right)^2$	$c = 0.84$
Lejeune-Richet [9]	$\theta_c = \left(1 - \frac{\alpha_c}{c_1}\right)^{-c_2}$	$c_1 = 0.7.$ $c_2 = 3.4.$
Melnik-Sparks v1 [10]	$\log_{10}\left(\frac{\theta_c}{c_1}\right) = \mathrm{atan}(c_2 \cdot (\alpha_c - c_3)) + \frac{\pi}{2}$	$c_1 = 0.84$ $(^1).$ $c_2 = 20.6.$ $c_3 = 0.62.$
Melnik-Sparks v2 [11]	$\log_{10}\left(\frac{\theta_c}{c_1}\right) = \mathrm{atan}(c_2 \cdot (\alpha_c - c_3)) + \frac{\pi}{2}$	$c_1 = 0.68$ $(^1).$ $c_2 = 8.6.$ $c_3 = 0.69.$
Vona v1 [12]	$\theta_c = \frac{1 + \phi^{c_2}}{\left(1 - (1-c_3)\mathrm{erf}\left(\frac{\sqrt{\pi}}{2(1-c_3)}\phi(1+\phi^{c_4})\right)\right)^{c_1 c_5}}$	$\phi = \sum_j \alpha_{c_j}\rho_{c_j}/\rho_1 c_1.$ $c_1 = 0.27.$ $c_2 = 12.16.$ $c_3 = 0.032.$ $c_4 = 0.84.$ $c_5 = 2.8.$
Vona v2 [12]	$\theta_c = \frac{1 + \phi^{c_2}}{\left(1 - (1-c_3)\mathrm{erf}\left(\frac{\sqrt{\pi}}{2(1-c_3)}\phi(1+\phi^{c_4})\right)\right)^{c_1 c_5}}$	$\phi = \sum_j \alpha_{c_j}\rho_{c_j}/\rho_1 c_1.$ $c_1 = 0.39.$ $c_2 = 1.16.$ $c_3 = 0.03.$ $c_4 = 0.84.$ $c_5 = 2.8.$

$(^1)$ Modified for producing $\theta_c(0) = 1.0$.

Table 2: Available models for calculating $\theta_g(\alpha_g)$ in MAMMA.

Model	Equation	Auxiliary variables
None	$\theta_g = 1.0$	
Bagdassarov-Dingwell [13]	$\theta_g = \frac{1}{1 + b \cdot \alpha_g}$	$b = 22.4$
Costa et al. [14]	$\theta_g = \frac{1 + 25 \cdot \mathrm{Ca}^2(1-\alpha_g)^{8/3}}{(1-\alpha_g)\cdot(1 + 25 \cdot \mathrm{Ca}^2)}$	Ca $(^1)$
Ducamp-Raj [15]	$\theta_g = \exp\left(\frac{b \cdot \alpha_g}{1 - \alpha_g}\right)$	$b = -3$
Eilers [16, 17]	$\theta_g = \left(1 + \frac{1.25\alpha_g}{1 - b \cdot \alpha_g}\right)^2$	$b = 1.29$
Mackenzie [18]	$\theta_g = 1 - \frac{5}{3}\alpha_g$	
Quane-Russel [19]	$\theta_g = \exp\left(\frac{b \cdot \alpha_g}{1 - \alpha_g}\right)$	$b = -0.63$ $(^2)$
Rahaman [20]	$\theta_g = \exp(-b \cdot \alpha_g)$	$b = 11.2$
Sibree [21]	$\theta_g = \frac{1}{1 - (b \cdot \alpha_g)^{1/3}}$	$b = 1.2$
Taylor [22]	$\theta_g = 1 + \alpha_g$	

$(^1)$ Capillarity number. Calculated following Llewellin and Manga [23].
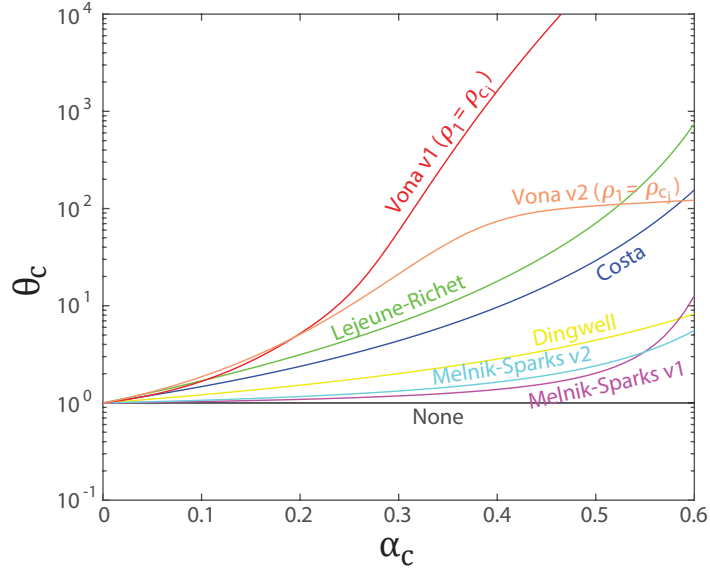$(^2)$ Adapted for Phlegrean Fields.

Figure 2: Available models for calculating $\theta_c(\alpha_c)$ in MAMMA.

where μ_{melt} is expressed in $\mathrm{Pa} \cdot \mathrm{s}$, w is dissolved gas concentration (Eq. 18) in $\mathrm{wt.\%}$ and T is temperature in K.

$$\mathrm{w} = \sum_{k=1}^{n_{gas}} x_{d_k} \tag{18}$$

2.1.2 Romano et al. [25]

This model has been calibrated using samples from Vesuvius and Phlegrean Fields. For trachytic magmas, melt viscosity is calculated using:

$$\log_{10}(\mu_{melt}) = -3.5405 + 0.14467 \cdot \ln(\mathrm{w}) + \frac{9618.9 - 498.79 \cdot \ln(\mathrm{w})}{T - (191.78 - 35.518 \cdot \ln(\mathrm{w}))} \tag{19}$$

On the other hand, the following equation is adapted for studying phonolitic magmas:

$$\log_{10}(\mu_{melt}) = -5.8996 - 0.2857 \cdot \ln(\mathrm{w}) + \frac{10775 - 394.83 \cdot \ln(\mathrm{w})}{T - (148.71 - 21.65 \cdot \ln(\mathrm{w}))} \tag{20}$$
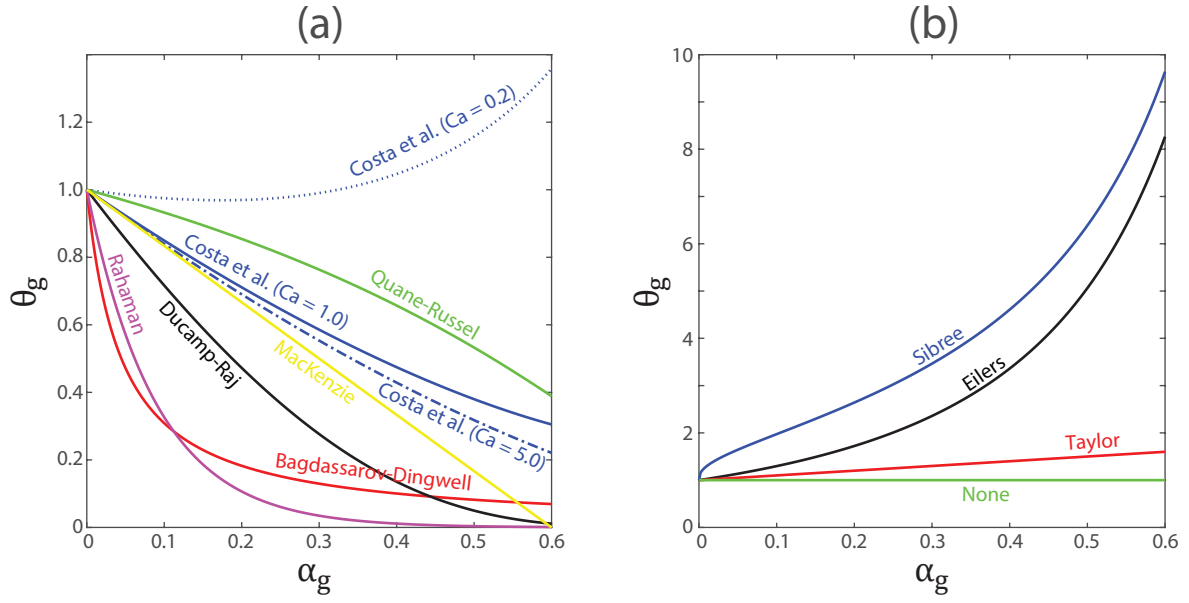
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Figure 3: Available models for calculating $\theta_g(\alpha_g)$ in MAMMA.

2.1.3 Giordano et al. [26]

This model predicts the non-Arrhenian Newtonian viscosity of silicate melts as a function of T and melt composition (major elements). Melt viscosity (μ_{melt}) is calculated using:

$$\log_{10}(\mu_{melt}) = -4.55 + \frac{B_G}{T - C_G} \tag{21}$$

where B_G and C_G are composition-dependent constants (Eq. 22 and Eq. 23, respectively).

$$B_G = \sum_{i=1}^{7}(b_i M_i) + \sum_{j=1}^{3} b_{1j} M_{1j} \tag{22}$$

$$C_G = \sum_{i=1}^{6}(c_i N_i) + c_{11} N_{11} \tag{23}$$

where M_i, M_{1j}, N_i and N_{11} refer to the combinations of $\mathrm{mol\%}$ oxides reported in Table 3, and b_i, b_{1j}, c_i and c_{11} are constant values (Table 3).

Table 3: Coefficients for calculation of B_G and C_G from melt composition (mol% oxide) [26].

Coefficient	Value	Oxides
b_1	159.6	$M_1 = SiO_2 + TiO_2$
b_2	-173.3	$M_2 = Al_2O_3$
b_3	72.1	$M_3 = FeO(T) + MnO + P_2O_5$
b_4	75.7	$M_4 = MgO$
b_5	-39.0	$M_5 = CaO$
b_6	-84.1	$M_6 = Na_2O + V(^1)$
b_7	141.5	$M_7 = V + \ln(1 + H_2O)$
b_{11}	-2.43	$M_{11} = (SiO_2+TiO_2) \cdot (FM(^2))$
b_{12}	-0.91	$M_{12} = (SiO_2+TA(^3) + P_2O_5) \cdot (NK(^4) + H_2O)$
b_{13}	17.6	$M_{13} = (Al_2O_3) \cdot (NK)$
c_1	2.75	$N_1 = SiO_2$
c_2	15.7	$N_2 = TA$
c_3	8.3	$N_3 = FM$
c_4	10.2	$N_4 = CaO$
c_5	-12.3	$N_5 = NK$
c_6	-99.5	$N_6 = \ln(1 + V)$
c_{11}	0.30	$N_{11} = (Al_2O_3+FM + CaO - P_2O_5) \cdot (NK + V)$

(^{1}) $V = H_2O + F_2O_{-1}$.
(^{2}) $FM = FeO(T) + MnO + MgO$.
(^{3}) $TA = TiO_2+Al_2O_3$.
(^{4}) $NK = Na_2O + K_2O$.

2.1.4 Giordano et al. [27]

This model was calibrated using data derived from Stromboli samples, thus it is adapted for studying basaltic magmas. Melt viscosity (μ_{melt}) is determined using the following equation:

$$\log_{10}(\mu_{melt}) = -4.55 + \frac{6101 - 63.66 \cdot w^*}{T - (567 - 160.3 \cdot \log_{10}(1 + w^*))} \tag{24}$$

where w^* is dissolved gas concentration in mol%.

2.1.5 Whittington et al. [28]

In this case, the viscosity model is adapted to dacitic magmas and uses the following formulation:

$$\log_{10}(\mu_{melt}) = -4.43 + \frac{7618.3 - 17.25 \cdot \log_{10}(\text{w} + 0.26)}{T - (406.1 - 292.6 \cdot \log_{10}(\text{w} + 0.26))} \tag{25}$$

2.1.6 Di Genova et al. [29]

This work includes two viscosity models, adapted for studying the pantelleritic melts from the Khaggiar lava flow. The first formulation (Di Genova v1) uses the parametrization proposed by Giordano et al. [27]:

$$\log_{10}(\mu_{melt}) = -4.55 + \frac{4278.17 + 8.6 \cdot \text{w}^*}{T - (513 - 245.3 \cdot \log_{10}(1 + \text{w}^*))} \tag{26}$$

The second model (Di Genova v2) uses the following parametrization:

$$\log_{10}(\mu_{melt}) = -4.55 + \frac{10528.64 - 4672.21 \cdot \log_{10}(1 + \text{w}^*)}{T - (172.27 + 89.75 \cdot \log_{10}(1 + \text{w}^*))} \tag{27}$$

2.2 Solubility models

2.2.1 Henry's law

For each volatile specie, the equilibrium value of dissolved gas is calculated using the following expression:

$$x_{d_k}^{eq} = \sigma_k \left(\frac{p_{g_k}}{p_r}\right)^{\epsilon_k} \tag{28}$$

where σ_k is the solubility coefficient of the k-th volatile specie, p_{g_k} is pressure of the k-th gas component, p_r is a reference value of pressure (equal to 1 [Pa]) and ϵ_k is the solubility exponent of the k-th volatile specie.

2.2.2 Polynomial fit

When the polynomial fit is employed, $x_{d_k}^{eq}$ is computed with the following expression:

$$x_{d_k}^{eq} = c_{1_k} \cdot \left(\frac{p_{g_k}}{p_r}\right)^2 + c_{2_k} \cdot \left(\frac{p_{g_k}}{p_r}\right) \tag{29}$$

where c_{1_k} and c_{2_k} are fitting parameters for the k-th volatile specie.

2.2.3 Zhang model [30]

In this case, $x_{d_k}^{eq}$ is calculated using the following equations:

$$x_{d_k}^{eq} = 0.01 \cdot \left(d_1(T) \cdot \sqrt{p_{g_k}} + d_2(T) \cdot p_{g_k} + d_3(T) \cdot \sqrt{p_{g_k}^3} \right) \tag{30}$$

$$d_1(T) = 0.4874 - \frac{608}{T} + \frac{489530}{T^2} \tag{31}$$

$$d_2(T) = -0.060602 + \frac{135.6}{T} - \frac{69200}{T^2} \tag{32}$$

$$d_3(T) = 0.00253 - \frac{4.154}{T} + \frac{1509}{T^2} \tag{33}$$

where p_{g_k} and T are expressed in MPa and K, respectively.

2.3 Crystallization models

2.3.1 de'Michieli Vitturi et al. [31]

The equilibrium volume fraction of the j-th crystalline phase ($\alpha_{c_j}^{eq}$) is calculated using Eq. 34.

$$\alpha_{c_j}^{eq} = \min \left(\alpha_{c_j,max}, \alpha_{c_j,0} + 0.55 \cdot (0.58815 \cdot p_1^{-0.5226}) \right) \tag{34}$$

where $\alpha_{c_j,max}$ is the maximum crystallinity of the j-th crystalline phase, $\alpha_{c_j,0}$ is the initial volume fraction of the j-th crystalline phase, p_1 is measured in MPa and $\min()$ is the minimum function.

2.4 Outgassing models

2.4.1 Forchheimer's law [3]

The model is dependent on the relative position of the fragmentation level. Below magma fragmentation, since a non-linear relationship between pressure gradient and gas flow rate has been recognized, Degruyter et al. [3] describe the outgassing process using the Forchheimer's law, which includes the influence of viscous (linear term) and inertial forces (quadratic term) (Eq. 35). Above magma fragmentation, the model presented by Yoshida and Koyaguchi [32] is considered; and the presence of a transitional domain is also assumed

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(Eq. 35). Please note that $|dp/dz| = \delta_f \cdot \triangle u$, where $\triangle u$ is the velocity difference between both phases.

$$\left|\frac{dp}{dz}\right| = \begin{cases} \frac{\mu_g}{k_D}(\triangle u) + \frac{\rho_g}{k_I}(\triangle u)^2 & \text{if } \alpha_g \leq \alpha_{cr} \\ \left(\frac{\mu_g}{k_D}(\triangle u) + \frac{\rho_g}{k_I}(\triangle u)^2\right)^{1-t} \cdot \left(\frac{3C_D}{8r_a}\rho_g(\triangle u)^2\right)^t & \text{if } \alpha_{cr} < \alpha_g < \alpha_t \\ \frac{3C_D}{8r_a}\rho_g(\triangle u)^2 & \text{if } \alpha_g \geq \alpha_t \end{cases} \tag{35}$$

where μ_g and ρ_g are viscosity and density of the exsolved gas phase, k_D and k_I are the Darcian and inertial permeabilities, respectively (Eq. 36 and Eq. 37), C_D is a drag coefficient, r_a is the average size of the fragmented magma particles, $t = (\alpha_g - \alpha_{cr})/(\alpha_t - \alpha_{cr})$ and α_t controls the range of the transitional domain.

$$k_D = \frac{(f_{rb}r_b)^2}{8}\alpha_g^m \tag{36}$$

$$k_I = \frac{f_{rb}r_b}{f}\alpha_g^{(1+3m)/2} \tag{37}$$

$$r_b = \left(\frac{\alpha_g}{\frac{4\pi}{3}N_{bd}\alpha_1}\right)^{1/3} \tag{38}$$

where f_{rb} is the throat-bubble size ratio (0.1 - 1), r_b is the average bubble size, N_{bd} is the bubble density number (10^8 - 10^{16} m^{-3}) and f and m are fitting parameters.

2.4.2 Darcy's law

In this case, the inertial forces below magma fragmentation (quadratic term) and the transitional domain are not considered, and thus the resulting model is described by the following expression:

$$\left|\frac{dp}{dz}\right| = \begin{cases} \frac{\mu_g}{k_D}(\triangle u) & \text{if } \alpha_g \leq \alpha_{cr} \\ \frac{3C_D}{8r_a}\rho_g(\triangle u)^2 & \text{if } \alpha_g > \alpha_{cr} \end{cases} \tag{39}$$

2.5 Degassing model

If lateral degassing is considered, it follows Eq. 40.

$$J_{lat} = \frac{\rho_g \alpha_g k_{cr}}{\mu_g f_{\epsilon_2}} \frac{\partial p}{\partial r}\bigg|_{r=R_{eq}} \tag{40}$$

where k_{cr} is country rock permeability.

2.6 Injection of external water

When the injection of external water is considered, it is modelled using the following equation [2]:

$$J_{ex} = \frac{\rho_w k_a}{\mu_w f_{\epsilon_2}} \frac{\partial p}{\partial r}\bigg|_{r=R_{eq}} \tag{41}$$

where ρ_w is external water density, k_a is the aquifer permeability and μ_w is external water viscosity.

2.7 Equations of state

In order to define the specific internal energy and entropy of melt, crystals and dissolved gas, a linearized version of the Mie-Gruneisen equation of state [33] was adopted:

$$e_l(\rho_l, T) = \bar{e}_l + c_{v,l}T + \frac{\rho_{0,l}C_{0,l}^2 - \gamma_l p_{0,l}}{\gamma_l \rho_l} \tag{42}$$

$$s_l(\rho_l, T) = s_{0,l} + c_{v,l} \cdot \ln\left(\frac{T}{T_{0,l}}\left(\frac{\rho_{0,l}}{\rho_l}\right)^{\gamma_l - 1}\right) \tag{43}$$

where $\bar{e}_l$ is formation energy, $c_{v,l}$ is the specific heat capacity at constant volume, $\rho_{0,l}$ and $C_{0,l}$ are density and sound speed at a reference state, γ_l is the adiabatic exponent and $p_{0,l}$, $s_{0,l}$ and $T_{0,l}$ are pressure, specific entropy and temperature at a reference state. Subscript l refers to melt (m), the dissolved gas phases (d_k) or the crystalline phases (c_j).

For the equation of state of exsolved gas of the k-th volatile specie, two models are available:

2.7.1 Ideal gas

The internal energy and specific entropy are calculated using equations 44 and 45, respectively.

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$$e_{g_k}(\rho_{g_k}, T) = \bar{e}_{g_k} + c_{v,g_k} T \tag{44}$$

$$s_{g_k}(\rho_{g_k}, T) = s_{0,g_k} + c_{v,g_k} \cdot \ln\left(\frac{T}{T_{0,g_k}} \left(\frac{\rho_{0,g_k}}{\rho_{g_k}}\right)^{\gamma_{g_k}-1}\right) \tag{45}$$

where c_{v,g_k} is the specific heat capacity at constant volume, $\bar{e}_{g_k}$ is the formation energy, s_{0,g_k}, T_{0,g_k} and ρ_{0,g_k} are specific entropy, temperature and density at a reference state and γ_{g_k} is the adiabatic exponent.

2.7.2 Van der Waals

In this case, the following equations are employed:

$$e_{g_k}(\rho_{g_k}, T) = \bar{e}_{g_k} + c_{v,g_k} T - a_{g_k} \cdot \rho_{g_k} \tag{46}$$

$$s_{g_k}(\rho_{g_k}, T) = s_{0,g_k} + c_{v,g_k} \cdot \ln\left(\frac{T}{T_{0,g_k}} \left(\frac{\rho_{0,g_k}}{\rho_{g_k}} \cdot (1 - b_{g_k} \cdot \rho_{g_k})\right)^{\gamma_{g_k}-1}\right) \tag{47}$$

where:

$$a_{g_k} = \frac{27}{64} \cdot \frac{c_{v,g_k}^2 (\gamma_{g_k} - 1)^2 T_{cr,g_k}^2}{p_{cr,g_k}} \tag{48}$$

$$b_{g_k} = \frac{1}{8} \cdot \frac{c_{v,g_k}(\gamma_{g_k} - 1)T_{cr,g_k}}{p_{cr,g_k}} \tag{49}$$

where T_{cr,g_k} and p_{cr,g_k} are critical temperature and pressure of the k-th volatile component.

3   Outputs of the model

MAMMA provides the profiles along the conduit of the following parameters:

(a) Velocity of both phases.

(b) Density of both phases.

(c) Pressure of both phases.

(d) Temperature.

(e) Dissolved gas mass fraction and the equilibrium value.

(f) Exsolved gas volume fraction.

(g) Volume fraction of crystals.

(h) Mass discharge rate.

(i) Mixture viscosity.

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