HM58 P • HM58S P • HMC58 P



- Compact programmable encoder
- Singleturn resolution up to 18 bit, multiturn up to 14 bit
- SSI or Bit parallel output
- Programmable SSI protocol, clock rate and timing



HMx58x P

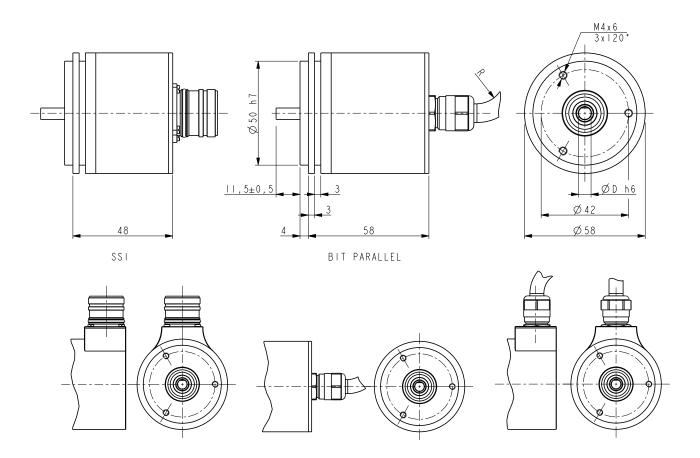
	ENVIRONMENTAL SPECIFICATIONS
Shock:	100 g, 6 ms (acc. to MIL STD 202F)
Vibrations:	10 g, 5-2000 Hz (acc. to MIL STD 202F)
Operating temperature range:	-40°C +85°C (-40°F +185°F)
Storage temperature range:	-40°C +100°C (-40°F +212°F)
	(98% R.H. without condensation)
Protection:	IP67, IP65 shaft side
Option:	• Operating temperature range: -40°C +100°C (-40°F +212°F)

MECHANICAL SPECIFICATIONS							
Dimensions:	see drawing						
Solid shaft:	Ø 6, 8, 9.52, 10, 12 mm						
Hollow shaft:	ø 14, 15 mm						
Reducing sleeves BR1-xx from ø15	5mm: to 6, 8, 9.52, 10, 11, 12 mm						
Shaft loading (axial and radial):	100 N max.						
Shaft rotational speed:	12000 rpm, 9000 rpm continuous operation						
Bearing life:	400x10 ⁶ rev. min. (10 ⁹ rev. min. with shaft loading of 20 N max.)						
Weight:	~ 0,3 kg (10,6 oz)						
Electrical connections:	SSI: M23 or M12 connector, cable 1 m, MIL pin inline connector Bit parallel: cable, MIL or DSub inline connector						
Option:	• additional cable						

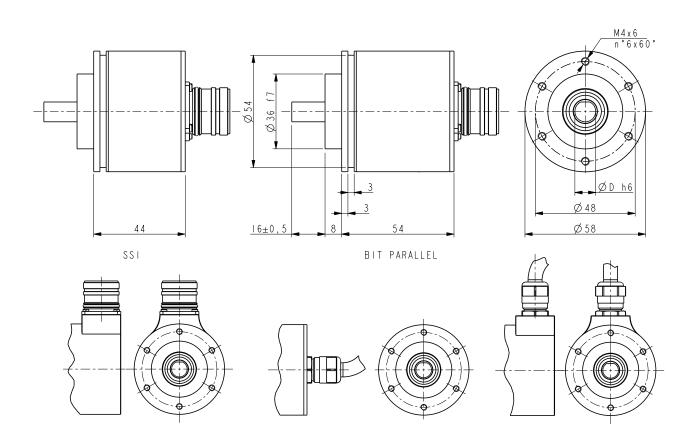
ELECTRICAL SPECIFICATIONS							
Resolution:	singleturn = programmable, 1-262144 cpr multiturn = programmable, 1-16384 turns						
Output code:	Gray, Binary, BCD						
Power supply:	$+10Vdc \div 30Vdc$						
Power consumption:	SSI: 1 W Bit parallel: 2,16 W						
Output circuits:	SSI (RS422), Bit parallel Push-Pull, NPN						
Output current:	40 mA (each channel)						
Counting frequency:	> 150 kHz						
Accuracy:	± 30% LSB						
Protection:	against inversion of polarity, short-circuit						
EMC:	according to: EN-61000-4-2/A1 EN-61000-4-4						
Optoelectronic life:	> 100.000 h						
Functions:	 Programmable resolution Teach-in of resolution Counting direction (programmable + input) Zero setting / Preset (programmable + input) Parity bit (even/odd) SSI protcol (alignment, clock, timing) 						
	 Latch, Tristate inputs 						

MATERIALS						
Flange:	non corroding, UNI EN AW-6082					
Housing:	non corroding, UNI EN AW-6082					
Bearings:	ABEC 5					
Shaft:	stainless steel, non magnetic, UNI EN 4305					

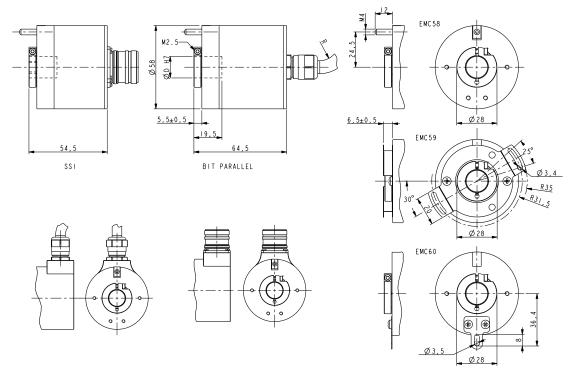
ACCESSORIES							
E41MLS:	MIL 41 pin connector						
E32MLS:	MIL 32 pin connector						
E19MLS:	MIL 19 pin connector						
E10MLS:	MIL 10 pin connector						
E7MLS:	MIL 7pin connector						
EDA 15S:	DSub 15 pin connector						
EDB 25S:	DSub 25 pin connector						
PAN/PGF:	flexible couplings						
BR1:	reducing sleeves						
LKM-386:	fixing clamps						



HM58 P



HM58S P



HMC58 - HMC59 - HMC60

Order code - Bit parallel

Additional code (optional)

HM58	XX	/	XXXXX	Х	Х	XX	Х	XXX	Х	/Sxxx - /Pxxx
HM58S	a		b	©	(d)	e	(f)	9	h	(i)
HMC58										
HMC59										
HMC60										

ⓐ RESOLUTION

(b) REVOLUTIONS

16384 = 16384 turns

© P = programmable

18 = 18 bit

© SHAFT DIAMETER

6 = 6 mm

8 = 8 mm

P9 = 9.52mm / 3/8"

10 = 10 mm

12 = 12 mm

14 = 14 mm (HMCxx)

15 = 15 mm (HMCxx)

@ OUTPUT

 $\mathbf{Y} = \mathsf{Push}\text{-}\mathsf{Pull}$

(f) CONNECTION POSITION

N = PUSN-PU

- = axialR = radial

CONNECTIONS

Lx = cable output x m

Z1 = 1 m cable + DSub 15 pin inline plug

W1 = 1 m cable + DSub 25 pin inline plug

Y1 = 1 m cable + MIL 41 pin inline plug

V1 = 1 m cable + MIL 32 pin inline plug

X1 = 1 m cable + MIL 19 pin inline plug

(h) OPERATING TEMPERATURE RANGE

K = -40°C +100°C (-40°F +212°F)

(i)

/Sxxx: Custom version

/Pxxx: Factory programmed encoder

on customers request

Order code - SSI output

Additional code (optional)

HM58	XX	1	XXXXX	Х	Х	XX	Х	XXX	X	/Sxxx - /Pxxx
HM58S	a		(b)	©	(d)	e	f	g	h	(i)
HMC58										
HMC59										
HMC60										

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① CONNECTION POSITION

- = axial

R = radial

(9) CONNECTIONS

Lx = cable output x m

M2 = M23 connector P1 = 1 m cable + MIL 7 pin inline plug

P1 = 1 m cable + MIL 7 pin inline plug D1 = 1 m cable + MIL 10 pin inline plug (h) OPERATING TEMPERATURE RANGE

K = -40°C +100°C (-40°F +212°F)

(i)

/Sxxx: Custom version

/Pxxx: Factory programmed encoder on customers request

(d) OUTPUT S = SSI