Assignment 6 (Writeup)



Created By:

Group: Chengyin Liu(cl93), Ran Jin(Oliver)(rj23)

April 20, 2018 COMP 540 – Statistical Machine Learning Rice University

Problem 1)

a) $O=\{low,medium,high\}$, $S=\{healthy,unhealthy\}$, $\lambda=\{\pi,a,b\}$, $\pi=[0.5,0.5]$

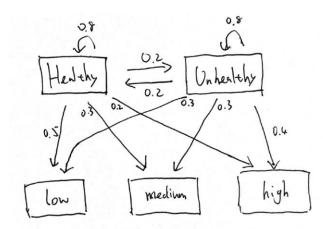
a:
$$\underset{unhealthy}{healthy} \begin{pmatrix} 0.8 & 0.2 \\ 0.2 & 0.8 \end{pmatrix}$$

healthy unhealthy

b:
$$\frac{healthy}{unhealthy} \begin{pmatrix} 0.5 & 0.3 & 0.2 \\ 0.3 & 0.3 & 0.4 \end{pmatrix}$$

low medium high

Observations: e_1 e_2 e



b) S_1 : healthy, S_2 : unhealthy, $e_1 = e_2 = low$

$$\alpha_t(i) = P(e_1, \dots, e_t, x_t = S_i)$$

$$\alpha_0(1) = \pi_1 = 0.5$$

$$\alpha_0(2) = \pi_2 = 0.5$$

$$\alpha_1(1) = 0.5 * (0.5 * 0.8 + 0.5 * 0.2) = 0.25$$

$$\alpha_1(2) = 0.3 * (0.5 * 0.2 + 0.5 * 0.8) = 0.15$$

$$\alpha_2(1) = 0.5 * (0.25 * 0.8 + 0.15 * 0.2) = 0.115$$

$$\alpha_2(2) = 0.3 * (0.25 * 0.2 + 0.15 * 0.8) = 0.051$$

Thus, $P(x_2 = S_1 | e_1, e_2) = \frac{0.115}{0.115 + 0.051} = 0.693$

c)
$$\delta_t(i) = max_{x_1,...,x_{t-1}} P(x_1,...,x_{t-1},x_t = S_i,e_1,...,e_t)$$

$$\delta_0(1) = 0.5$$

 $\delta_0(2) = 0.5$

For $\delta_1(1)$, for i = 1, it equals 0.5 * 0.8 * 0.5 = 0.2, for i = 2, it equals to 0.5 * 0.2 * 0.5 = 0.05. Thus, by taking the max, $\delta_1(1) = 0.2$

For
$$\delta_1(2)$$
, for $i=1$, it equals $0.5*0.2*0.3=0.03$, for $i=2$, it equals to $0.5*0.8*0.3=0.12$.

Thus, by taking the max, $\delta_1(1)=0.12$

For $\delta_2(1)$, for $i=1$, it equals $0.2*0.8*0.5=0.08$, for $i=2$, it equals to $0.12*0.2*0.5=0.012$.

Thus, by taking the max, $\delta_1(1)=0.08$

For $\delta_2(2)$, for $i=1$, it equals $0.2*0.2*0.3=0.012$, for $i=2$, it equals to $0.12*0.8*0.3=0.0288$.

Thus, $\delta_2(2) = 0.0288 < \delta_2(1)$. Therefore, $x_2 = S_1$.

Since
$$\delta_1(1)a_{11} > \delta_1(2)a_{21}, x_1 = S_1$$

Since $\delta_0(1)a_{11} > \delta_0(2)a_{21}$. Therefore, $x_0 = S_1$

Given that $e_1=e_2=low$, the most likely state sequence is $x_0\to x_1\to x_2$ which is healthy $\to healthy \to healthy$

Problem 2)

a) Likelihood:

$$L(D; \pi, \mu) = \prod_{i=1}^{m} \prod_{k=1}^{k} [P(z^{(i)} = k, \pi) P(x^{(i)} | z^{(i)} = k; \mu)]$$

$$= \prod_{i=1}^{m} \prod_{k=1}^{k} [\pi_k Bernoulli(x^{(i)}, \mu_k)]$$

Thus, the log likelihood:

$$l(D; \pi, \mu) = \sum_{i=1}^{m} \sum_{k=1}^{k} I(z^{(i)} = k) [\pi_k Bernoulli(x^{(i)}, \mu_k)]$$

Then the expected log likelihood:

$$E[l(D; \pi, \mu)] = \sum_{i=1}^{m} \sum_{k=1}^{K} \gamma_k^{(i)} \{ log \pi_k + \log[\mu_k^{x^{(i)}} (1 - \mu_k)^{1 - x^{(i)}}] \}$$

$$= \sum_{i=1}^{m} \sum_{k=1}^{K} \gamma_k^{(i)} \{ log \pi_k + x^{(i)} \log \mu_k + (1 - x^{(i)}) \log(1 - \mu_k) \}$$

For MLE, for each μ_{ki}

We let
$$\frac{\partial E[l(D;\pi,\mu)]}{\partial \mu_{kj}} = 0$$

Then
$$\sum_{i=1}^{m} \gamma_k^{(i)} \left(\frac{x_j^{(i)}}{\mu_{kj}} - \frac{1 - x_j^{(i)}}{1 - \mu_{kj}} \right) = 0$$

Then
$$\mu_{kj} = \frac{\sum_{i=1}^{m} \gamma_k^{(i)} x_j^{(i)}}{\sum_{i=1}^{m} \gamma_k^{(i)}}$$

b)
$$P(\mu|D) \propto P(D|\mu)P(\mu)$$
 where $\mu \sim beta(\alpha, \beta)$

Thus,
$$P(\mu|D) \propto \prod_{i=1}^{m} \prod_{k=1}^{k} \left[\pi_k Bernoulli(x^{(i)}, \mu_k) \right]^{I(z^{(i)} = k)} \times \prod_{k=1}^{K} beta(\mu_k; \alpha, \beta)$$

Thus, the operation is:

$$E = \sum_{i=1}^{m} \sum_{k=1}^{K} I(z^{(i)} = k) [log \pi_k + log Bernoulli(x^{(i)}, \mu_k)] + \sum_{k=1}^{K} log \ beta(\mu_k; \alpha, \beta)$$

$$= \sum_{i=1}^{m} \sum_{k=1}^{K} \gamma_k^{(i)} \{ log \pi_k + x^{(i)} \log \mu_k + (1 - x^{(i)}) \log(1 - \mu_k) \}$$

$$+ \sum_{k=1}^{K} [(\alpha - 1) log \mu_k + (\beta - 1) log (1 - \mu_k)]$$

For each μ_{ki} , do MAP estimation,

Let
$$\frac{\partial E}{\partial \mu_{ki}} = 0$$
,

Then
$$\sum_{i=1}^{m} \gamma_k^{(i)} \left(\frac{x_j^{(i)}}{\mu_{kj}} - \frac{1 - x_j^{(i)}}{1 - \mu_{kj}} \right) + (\alpha - 1)/\log \mu_k - (\beta - 1)/\log (1 - \mu_k) = 0$$

Then
$$\mu_{kj} = \frac{\sum_{i=1}^{m} \gamma_k^{(i)} x_j^{(i)} + \alpha - 1}{\sum_{i=1}^{m} \gamma_k^{(i)} + \alpha + \beta - 2}$$

Problem 3)

$$V = \{au: a \in R\}$$

then $f_u(x) = argmin_{v \in V} ||x - v||^2 = \left(argmin_a ||x - au||^2\right) * u$

$$= [argmin_a(x^Tx + 2au^Tx + a^2u^Tu)] * u$$

since u s a unit vector, then $u^T u = 1$

let
$$\frac{\partial (x^T x + 2au^T x + a^2 u^T u)}{\partial a} = 0$$
,

we get
$$a = \frac{-2u^{T}x}{-2u^{T}u} = u^{T}x$$

Then
$$f_u(x) = u^T x u$$

Then

$$argmin_{u=u^{T}u=1} \sum_{i=1}^{m} \left| \left| x^{(i)} - f_{u}(x^{(i)}) \right| \right|^{2}$$

$$= argmin_{u} \sum_{i=1}^{m} \left| \left| x^{(i)} - u^{T}x^{(i)}u \right| \right|^{2}$$

$$= argmin_{u} \sum_{i=1}^{m} (x^{(i)} - u^{T} x^{(i)} u)^{T} (x^{(i)} - u^{T} x^{(i)} u)$$

$$= argmin_{u} \sum_{i=1}^{m} (x^{(i)^{T}} x^{(i)} - 2(u^{T} x^{(i)})^{2} + u^{T} u(u^{T} x^{(i)})^{2})$$

$$= argmin_{u} \sum_{i=1}^{m} -(u^{T} x^{(i)})^{2}$$

$$= argmin_{u} u^{T} \sum_{i=1}^{m} (x^{(i)^{T}} x^{(i)}) u$$

Thus, we say that $x^{(i)}$ have zero mean and unit variance. So, this is the first principal component.

Problem 4)

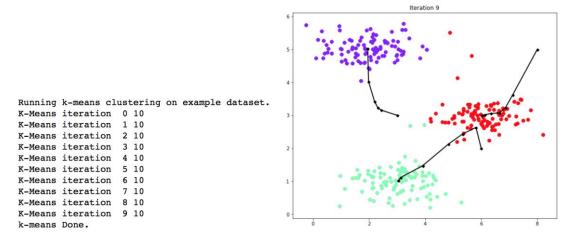
Problem 4.1: Finding closest centroids

```
Finding closest centroids.

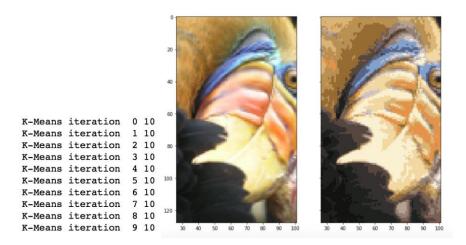
Closest centroids for the first 3 examples: (should be [0 2 1]): [0 2 1]
```

Problem 4.2: Computing centroid means

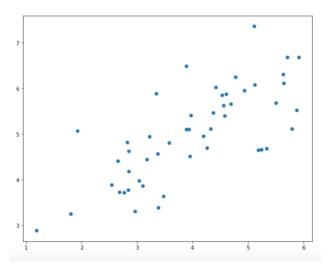
K-means on example dataset



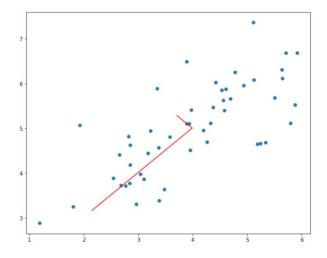
Problem 4.3: Random initialization Image compression with k-means



Problem 5) PCA on a simple 2D example



Problem 5.1: Implementing PCA



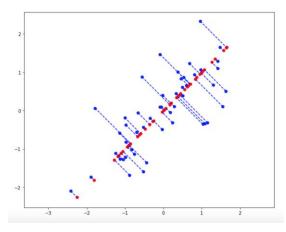
Dimensionality reduction with PCA

Problem 5.2: Projecting the data onto the principal components

Problem: 5.3 Reconstructing an approximation of the data

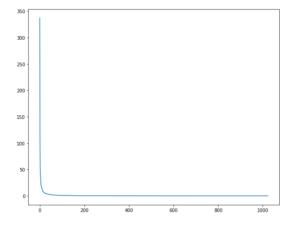
The projection of the first example (should be about 1.496) [1.49631261] Approximation of the first example (should be about [-1.058 -1.058]) [-1.05805279 -1.05805279]

Visualizing the projections



Face image dataset PCA on faces

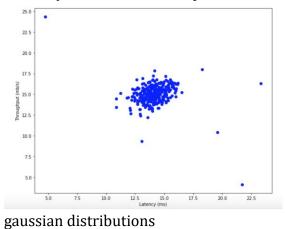




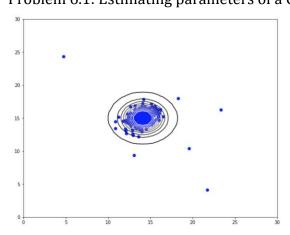
dimensionality reduction



Problem 6) Anomaly detection on a simple 2D data set

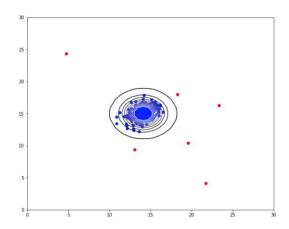


Problem 6.1: Estimating parameters of a Gaussian distribution



Problem 6.2: Selecting the threshold ϵ

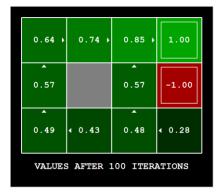
8.99085277927e-05 1.5555555556



High dimensional dataset
1.37722889076e-18 0.615384615385
(117L,)

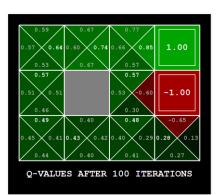
Problem 7)

7.1 Value Iteration



EPISODE 10 COMPLETE: RETURN WAS 0.531441

AVERAGE RETURNS FROM START STATE: 0.4847450508



	0.51 ▶	0.72 ▶	0.84 ▶	1.00
	^		^	
	0.27		0.55	-1.00
ı	_		_	
	0.00	0.22 ▶	0.37	∢ 0.13
VALUES AFTER 5 ITERATIONS				

```
Question q1

*** PASS: test_cases\q1\1-tinygrid test

*** PASS: test_cases\q1\2-tinygrid-moisy test

*** PASS: test_cases\q1\2-tinygrid-moisy test

*** PASS: test_cases\q1\4-discountgrid test

### Question q1: 6/6 ###

Finished at 1:35:21

Provisional grades

Question q1: 6/6

Total: 6/6

Your grades are NOT yet registered. To register your grades, make sure to follow your instructor's guidelines to receive credit on your project.
```

7.2 Bridge Crossing Analysis

```
def question2():
    answerDiscount = 0.9
    #answerNoise = 0.2
    answerNoise = 0
    return answerDiscount, answerNoise
```



```
Question q2

*** PASS: test_cases\q2\1-bridge-grid.test

### Question q2: 1/1 ###

Finished at 1:34:14

Provisional grades

Question q2: 1/1

Total: 1/1

Your grades are NOT yet registered. To register your grades, make sure to follow your instructor's guidelines to receive credit on your project.
```

7.3 Policies

```
#** PASS: test_cases\q3\1-question-3.1.test

*** PASS: test_cases\q3\2-question-3.2.test

*** PASS: test_cases\q3\2-question-3.3.test

*** PASS: test_cases\q3\4-question-3.4.test

*** PASS: test_cases\q3\5-question-3.5.test

### Question q3: 5/5 ###

Finished at 1:48:59

Provisional grades

Question q3: 5/5

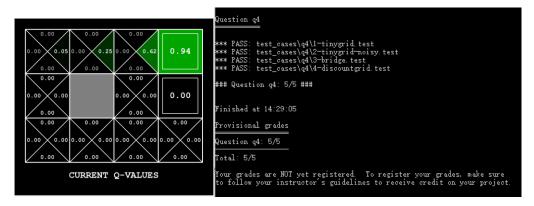
Total: 5/5

Total: 5/5

Your grades are NOT yet registered. To register your grades, make sure to follow your instructor's guidelines to receive credit on your project.
```

7.4 Q-learning

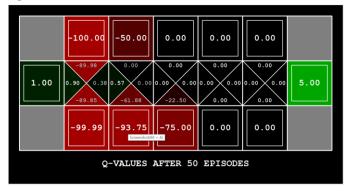
Steer Pacman north and then east along the optimal path for four episodes:



7.5 Epsilon-greedy policies

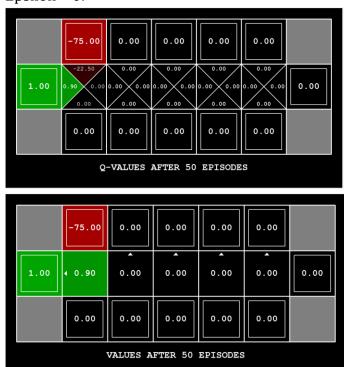


7.6 Bridge Crossing Revisited Epsilon = 1:





Epsilon = 0:



```
Question q6

*** PASS: test_cases\q6\grade=agent.test

### Question q6: 1/1 ###

Finished at 14:59:52

Provisional grades

Question q6: 1/1

Total: 1/1

Your grades are NOT yet registered. To register your grades, make sure to follow your instructor's guidelines to receive credit on your project.
```

7.7 Q-learning and Pacman

```
Reinforcement Learning Status:

Completed 2000 out of 2000 training episodes
Average Rewards over all training: -05.07
Average Rewards for last 100 episodes: 196.43
Episode took 1.76 seconds

Training Done (turning off epislon and alpha)

Paoman emerges victorious! Score: 502
Paoman emerges victorious! Score: 502
Paoman emerges victorious! Score: 496
Paoman emerges victorious! Score: 496
Paoman emerges victorious! Score: 503
Paoman emerges victorious! Score: 503
Paoman emerges victorious! Score: 504
Paoman emerges victorious! Score: 505
Paoman emerges victorious! Score: 496
Paoman emerges victorious! Score: 502
Paoman emerges victor
```

7.8 Approximate Q-learning smallGrid:

mediumGrid:

mediumClassic:

```
#** PASS: test_cases\q8\1-tinygrid.test

*** PASS: test_cases\q8\2-tinygrid-noisy.test

*** PASS: test_cases\q8\3-bridge.test

*** PASS: test_cases\q8\4-discountgrid.test

*** PASS: test_cases\q8\5-coord-extractor.test

### Question q8: 3/3 ###

Finished at 16:11:16

Provisional grades

Question q8: 3/3

Total: 3/3

Your grades are NOT yet registered. To register your grades, make sure to follow your instructor's guidelines to receive credit on your project.
```

Reference:

http://ai.berkeley.edu/reinforcement.html

https://github.com/shiro873/pacman-projects