	<pre>import numpy as np import matplotlib.pyplot as plt %matplotlib inline fig = plt.figure(figsize=(20,5)) for i in range(40): ax = fig.add_subplot(4, 10, i + 1, xticks=[], yticks=[]) ax.imshow(np.squeeze(x_train[i]))</pre>
7]:[]	3. Rescale the Images by Dividing Every Pixel in Every Image by 255 • Let's see how a datapoint looks like: print (x_train[1]) [[[154 177 187] [126 137 136]
	[105 104 95] [91 95 71] [87 90 71] [79 81 70]] [[140 160 169] [145 153 154] [125 125 118] [96 99 78] [77 80 62] [71 73 61]]
	[[140 155 164] [139 146 149] [115 115 112] [79 82 64] [68 70 55] [67 69 55]] [[175 167 166] [156 154 160] [154 160 170]
	[42 34 36] [61 53 57] [93 83 91]] [[165 154 128] [156 152 130] [159 161 142] [103 93 96] [123 114 120] [131 121 131]] [[163 148 120] [158 148 122] [163 156 133]
	 [143 133 139] [143 134 142] [143 133 144]]] Let's normalize each cell value [0,255], so that each cell value lies within the same distribution [0,1]. That is values change from [0,255]> [0,1]. We normalize using the formula: \$\$ \frac{X-X_{min}}{X_{max}-X_{min}}\$\$ Here, X_min=0 and X_max=255. Hence, \$\$ \frac{X-X_{min}}{X_{max}-X_{min}} = \frac{x^2}{255}\$\$
	<pre>x_train = x_train.astype('float32')/255 x_test = x_test.astype('float32')/255 4. Break Dataset into Training, Testing, and Validation Sets • A datapoint in the dataset could belong to any one of the 10 classes mentioned earlier. • Let's convert the output into one-hot encoded vector of size 10. • This will be helpful for our CNN to recognize a given image datapoint into one of the 10 classes. from keras.utils import np_utils</pre>
0]:	<pre># one-hot encoding num_classes = len(np.unique(y_train)) y_train = keras.utils.to_categorical(y_train, num_classes) y_test = keras.utils.to_categorical(y_test, num_classes) # break training set into training and validation sets (x_train, x_valid) = x_train[5000:], x_train[:5000] (y_train, y_valid) = y_train[5000:], y_train[:5000] # print shape of training set print('x_train shape:', x_train.shape)</pre>
3	<pre># print number of training, validation, and test images print(x_train.shape[0], 'train samples') print(x_test.shape[0], 'test samples') print(x_valid.shape[0], 'validation samples') x_train shape: (45000, 32, 32, 3) 45000 train samples 10000 test samples 5000 validation samples</pre> 5. Data Augmentation • Data augmentation helps in creating invariance in the data, especially in image data.
	<pre>Invariance in data could be for:</pre>
2]:	horizontal_flip=True) # randomly flip images horizontally # fit augmented image generator on data datagen_train.fit(x_train) 6. Visualize Original and Augmented Images import matplotlib.pyplot as plt # take subset of training data x_train_subset = x_train[:12]
	<pre># visualize subset of training data fig = plt.figure(figsize=(20,2)) for i in range(0, len(x_train_subset)): ax = fig.add_subplot(1, 12, i+1) ax.imshow(x_train_subset[i]) fig.suptitle('Subset of Original Training Images', fontsize=20) plt.show() # visualize augmented images fig = plt.figure(figsize=(20,2)) for x_batch in datagen_train.flow(x_train_subset, batch_size=12): for i in range(0, 12): ax = fig.add_subplot(1, 12, i+1) ax.imshow(x_batch[i])</pre>
	fig.suptitle('Augmented Images', fontsize=20) plt.show() break; Subset of Original Training Images Augmented Images Augmented Images
3]:	7. Define the Model Architecture from keras.models import Sequential from keras.layers import Conv2D, MaxPooling2D, Flatten, Dense, Dropout input_shape = x_train[1].shape model = Sequential() model.add(Conv2D(filters=32, kernel size=3, padding='same', kernel initializer='glorot uniform',
	<pre>activation='relu', input_shape=input_shape)) model.add(MaxPooling2D(pool_size=2)) model.add(Conv2D(filters=32, kernel_size=2, padding='same', kernel_initializer='glorot_uniform',</pre>
I	model.add(Dense(10, activation='softmax')) model.summary() Model: "sequential_5" Layer (type) Output Shape Param # conv2d_13 (Conv2D) (None, 32, 32, 32) 896 max_pooling2d_13 (MaxPooling (None, 16, 16, 32) 0 conv2d_14 (Conv2D) (None, 16, 16, 32) 4128
- (((((((((((((((((((max_pooling2d_14 (MaxPooling (None, 8, 8, 32) 0 dropout_11 (Dropout) (None, 8, 8, 32) 0 conv2d_15 (Conv2D) (None, 8, 8, 64) 8256 max_pooling2d_15 (MaxPooling (None, 4, 4, 64) 0 dropout_12 (Dropout) (None, 4, 4, 64) 0 flatten_5 (Flatten) (None, 1024) 0 dense_9 (Dense) (None, 512) 524800
- - - - -	dropout_13 (Dropout) (None, 512) 0 dense_10 (Dense) (None, 10) 5130 Total params: 543,210 Trainable params: 543,210 Non-trainable params: 0 8. Compile the Model
	Epoch 3/50 - 11s - loss: 1.2383 - accuracy: 0.5564 - val_loss: 1.1120 - val_accuracy: 0.6148 Epoch 00003: val_loss improved from 1.22526 to 1.11199, saving model to model.weights.best.hdf5 Epoch 4/50 - 13s - loss: 1.1399 - accuracy: 0.5939 - val_loss: 1.0113 - val_accuracy: 0.6498 Epoch 00004: val_loss improved from 1.11199 to 1.01130, saving model to model.weights.best.hdf5 Epoch 5/50 - 12s - loss: 1.0773 - accuracy: 0.6150 - val_loss: 0.9489 - val_accuracy: 0.6730 Epoch 00005: val_loss improved from 1.01130 to 0.94893, saving model to model.weights.best.hdf5 Epoch 6/50 - 11s - loss: 1.0180 - accuracy: 0.6368 - val_loss: 0.9235 - val_accuracy: 0.6824 Epoch 00006: val_loss improved from 0.94893 to 0.92349, saving model to model.weights.best.hdf5 Epoch 7/50 - 12s - loss: 0.9618 - accuracy: 0.6578 - val_loss: 0.8814 - val_accuracy: 0.6976 Epoch 00007: val_loss improved from 0.92349 to 0.88143, saving model to model.weights.best.hdf5 Epoch 8/50 - 12s - loss: 0.9188 - accuracy: 0.6748 - val_loss: 0.8303 - val_accuracy: 0.7166 Epoch 00008: val_loss improved from 0.88143 to 0.83028, saving model to model.weights.best.hdf5 Epoch 00008: val_loss improved from 0.88143 to 0.83028, saving model to model.weights.best.hdf5 Epoch 9/50 - 12s - loss: 0.8825 - accuracy: 0.6869 - val_loss: 0.7856 - val_accuracy: 0.7230
	This - loss: 1.2383 - accuracy: 0.5564 - val_loss: 1.1120 - val_accuracy: 0.6148 Espech 00003: val_loss improved from 1.22526 to 1.11199, saving model to model.weights.best.hdf5 Espech 00004: val_loss improved from 1.11199 to 1.01130, saving model to model.weights.best.hdf5 Espech 00004: val_loss improved from 1.11199 to 1.01130, saving model to model.weights.best.hdf5 Espech 05/50 - 12s - loss: 1.0773 - accuracy: 0.6150 - val_loss: 0.9489 - val_accuracy: 0.6730 Espech 00005: val_loss improved from 1.01130 to 0.94893, saving model to model.weights.best.hdf5 Espech 06/50 - 11s - loss: 1.0180 - accuracy: 0.6368 - val_loss: 0.9235 - val_accuracy: 0.6824 Espech 00006: val_loss improved from 0.94893 to 0.92349, saving model to model.weights.best.hdf5 Espech 00006: val_loss improved from 0.94893 to 0.92349, saving model to model.weights.best.hdf5 Espech 00007: val_loss improved from 0.92349 to 0.88143, saving model to model.weights.best.hdf5 Espech 00007: val_loss improved from 0.92349 to 0.88143, saving model to model.weights.best.hdf5 Espech 00008: val_loss improved from 0.88143 to 0.83028, saving model to model.weights.best.hdf5 Espech 00008: val_loss improved from 0.88143 to 0.83028, saving model to model.weights.best.hdf5 Espech 00008: val_loss improved from 0.88143 to 0.83028, saving model to model.weights.best.hdf5 Espech 00009: val_loss improved from 0.88143 to 0.76576, saving model to model.weights.best.hdf5 Espech 00009: val_loss improved from 0.78556 to 0.76577 val_accuracy: 0.7316 Espech 00010: val_loss improved from 0.78556 to 0.76572, saving model to model.weights.best.hdf5 Espech 10/50 - 12s - loss: 0.8154 - accuracy: 0.7127 - val_loss: 0.7552 - val_accuracy: 0.7266 Espech 10011: val_loss did not improve from 0.76572 Espech 10012: val_loss improved from 0.76572 to 0.75524, saving model to model.weights.best.hdf5 Espech 13/50 - 12s - loss: 0.7475 - accuracy: 0.7300 - val_loss: 0.7012 - val_accuracy: 0.7470 Espech 13/50 - 12s - loss: 0.7475 - accuracy: 0.7300 - val_loss: 0.7012 - val
	Espech 00003; valloss improved from 1.22526 to 1.11199, saving model to model.weights.best.hdf5 peoch 4/50 - 13s - loss: 1.1399 - accuracy: 0.5939 - valloss: 1.0135 - vallaccuracy: 0.6498 Booch 00004; valloss improved from 1.11199 to 1.0130, saving model to model.weights.best.hdf5 peoch 3/50 - 12s - loss: 1.0773 - accuracy: 0.6180 - valloss: 0.9489 - vallaccuracy: 0.6730 Booch 00005; valloss improved from 1.0130 to 0.94893, saving model to model.weights.best.hdf5 peoch 6/50 - 12s - loss: 1.0180 - accuracy: 0.6368 - valloss: 0.9233 - vallaccuracy: 0.6824 Booch 00006; valloss improved from 0.94893 to 0.92349, saving model to model.weights.best.hdf5 peoch 7/50 - 12s - loss: 0.9518 - accuracy: 0.6578 - valloss: 0.8814 - vallaccuracy: 0.6976 Booch 00006; valloss improved from 0.94893 to 0.98143, saving model to model.weights.best.hdf5 peoch 6/50 - 12s - loss: 0.95188 - accuracy: 0.6748 - valloss: 0.8303 - vallaccuracy: 0.77166 Booch 00006; valloss improved from 0.88143 to 0.83028, saving model to model.weights.best.hdf5 peoch 9/50 - 12s - loss: 0.8825 - accuracy: 0.6869 - valloss: 0.7856 - vallaccuracy: 0.7336 Booch 00008; valloss improved from 0.83028 to 0.78556, saving model to model.weights.best.hdf5 peoch 9/50 - 12s - loss: 0.8825 - accuracy: 0.6889 - valloss: 0.7657 - vallaccuracy: 0.7336 Booch 00009; valloss improved from 0.83028 to 0.78556, saving model to model.weights.best.hdf5 peoch 00010: valloss improved from 0.83028 to 0.78556, saving model to model.weights.best.hdf5 peoch 00011: valloss improved from 0.78556 to 0.76572, saving model to model.weights.best.hdf5 peoch 00012: valloss: 0.8154 - accuracy: 0.7127 - valloss: 0.7748 - vallaccuracy: 0.7366 Booch 00012: valloss improved from 0.78556 to 0.76572 saving model to model.weights.best.hdf5 peoch 10/50 - 12s - loss: 0.7475 - accuracy: 0.7370 - valloss: 0.7524, saving model to model.weights.best.hdf5 peoch 10/50 - 12s - loss: 0.7666 - accuracy: 0.7370 - valloss: 0.6869 - vallaccuracy: 0.7592 Booch 00016: valloss improved from 0.75524 to
	Figure 10001: valless improved from 1.22926 to 1.11199, saving model to model.weights.best.hdf5 peoch 4796 Figure 10001: valless improved from 1.22926 to 1.11199, saving model to model.weights.best.hdf5 peoch 5796 Figure 10001: valless improved from 1.11199 to 1.01130, saving model to model.weights.best.hdf5 spech 5790 Figure 10001: valless improved from 1.01190 to 0.9489, saving model to model.weights.best.hdf5 peoch 5790 Figure 10001: valless improved from 1.01190 to 0.9489, saving model to model.weights.best.hdf5 peoch 6790 Figure 10001: valless improved from 0.94893 to 0.92349, saving model to model.weights.best.hdf5 peoch 6790 Figure 10001: valless improved from 0.94893 to 0.92349, saving model to model.weights.best.hdf5 peoch 6790 Figure 10001: valless improved from 0.93499 to 0.88144 - vallescurscy: 0.6976 Figure 10001: valless improved from 0.93499 to 0.88143, saving model to model.weights.best.hdf5 peoch 6790 Figure 10001: valless improved from 0.88143 to 0.83028, saving model to model.weights.best.hdf5 peoch 6790 Figure 10001: valless improved from 0.88143 to 0.83028, saving model to model.weights.best.hdf5 peoch 6790 Figure 10001: valless improved from 0.88143 to 0.83028, saving model to model.weights.best.hdf5 peoch 6790 Figure 10001: valless improved from 0.88143 to 0.83028, saving model to model.weights.best.hdf5 peoch 6790; valless improved from 0.78596 to 0.76556, saving model to model.weights.best.hdf5 peoch 1790 Figure 1079 Figu
	Figure 1098: 1,2780 - accuracy: 0.5984 - val.lose: 1,1227 - val.accuracy: 0.548 Report 2003: val.cos improved from 1,2228 to 1,1219, avoing model to model.weights.best.hoff Report 2006: val.cos improved from 1,11193 to 1,01120, avoing model to model.weights.best.hoff Report 2006: val.cos improved from 1,11193 to 1,01120, avoing model to model.weights.best.hoff Report 2006: val.cos improved from 1,11193 to 1,01120, avoing model to model.weights.best.hoff Report 2006: val.cos improved from 1,11193 to 1,01120, avoing model to model.weights.best.hoff Report 2006: val.cos improved from 1,11193 to 0,9483, avoing model to model.weights.best.hoff Report 2006: val.cos improved from 0,14493 to 0,92349, avoing model to model.weights.best.hoff Report 2006: val.cos improved from 0,14493 to 0,92349, avoing model to model.weights.best.hoff Report 2006: val.cos improved from 0,14493 to 0,93249, avoing model to model.weights.best.hoff Report 2006: val.cos improved from 0,14493 to 0,93028; avoing model to model.weights.best.hoff Report 2006: val.cos improved from 0,14493 to 0,93028; avoing model to model.weights.best.hoff Report 2006: val.cos improved from 0,18493 to 0,93028; avoing model to model.weights.best.hoff Report 2009: val.cos improved from 0,18493 to 0,93028; avoing model to model.weights.best.hoff Report 2009: val.cos improved from 0,18493 to 0,93046, avoing model to model.weights.best.hoff Report 2009: val.cos improved from 0,18493 to 0,78506, avoing model to model.weights.best.hoff Report 2009: val.cos improved from 0,18493 to 0,78506, avoing model to model.weights.best.hoff Report 2009: val.cos improved from 0,18493 to 0,78504, avoing model to model.weights.best.hoff Report 2009: val.cos improved from 0,18493 to 0,78504, avoing model to model.weights.best.hoff Report 2009: val.cos improved from 0,78494 to 0,78504, avoing model to model.weights.best.hoff Report 2009: val.cos improved from 0,78494 to 0,78504, avoing model to model.weights.best.hoff Report 2009: val.cos improved from 0,78494 to 0,78604 to val.scourac
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