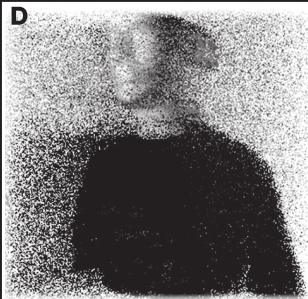
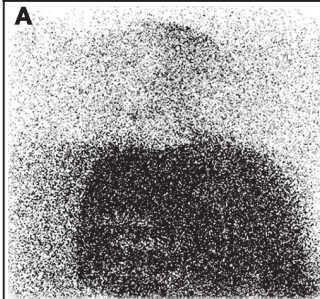
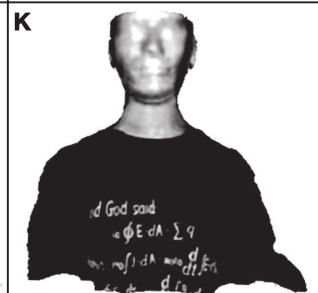
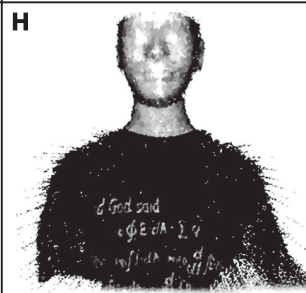
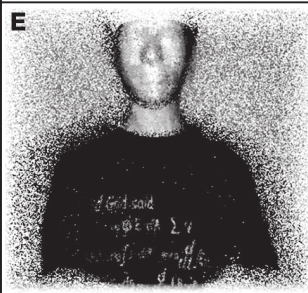
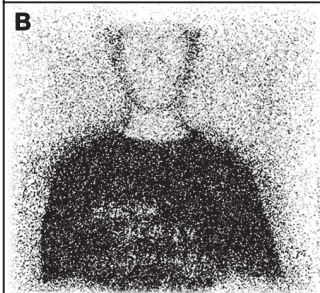


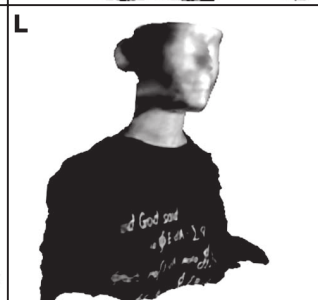
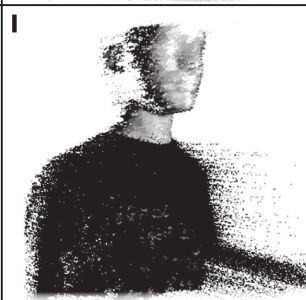
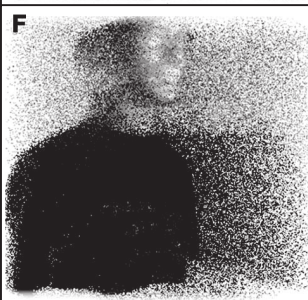
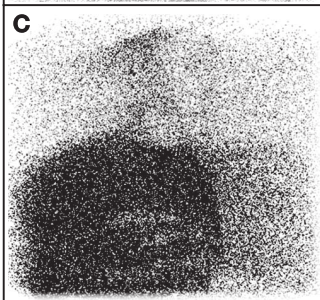
Right profile



Front view



Left profile



Pointwise maximum-likelihood processing

Step 1
reflectivity estimationStep 2:
ambient noise censoringStep 3:
3D estimation