Table 1: Main table

	(1)	(2)	(3)	(4)	(5)
$\Delta \ln \underline{w}_{it}$	0.0259*	0.0233*	0.0238*	0.0266**	0.0243*
	(0.0129)	(0.0115)	(0.0124)	(0.0127)	(0.0126)
Wage controls	No	Yes	No	No	Yes
Employment controls	No	No	Yes	No	Yes
Establishment-count controls	No	No	No	Yes	Yes
R-squared	0.022	0.024	0.022	0.022	0.022
Observations	$112,\!232$	106,699	106,699	$108,\!511$	106,699

Table 2: Polynomial trends

	(1)	(2)	(3)
$\Delta \ln \underline{w}_{it}$	0.0259*	0.0256**	0.0254^*
	(0.0129)	(0.0121)	(0.0117)
Zipcode-specifc linear trend	No	Yes	Yes
Zipcode-specific quadratic trend	No	No	Yes
R-squared	0.022	0.024	0.026
Observations	112,232	112,232	112,233

 ${\bf Table~3:~Dynamic~models}$

$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		(1)	(2)	(3)	(4)	(5)
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\Delta \ln w_{i,t-5}$	-0.0146	-0.0123	-0.0123	-0.0143	-0.0122
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		(0.00910)	(0.00787)	(0.00787)	(0.00904)	(0.00787)
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$,	,	,	,	,
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\Delta \ln \underline{w}_{i,t-4}$		0.000688			
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		(0.0116)	(0.00998)	(0.00995)	(0.0116)	(0.00994)
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	A 1	0.00127	0.000566	0.000400	0.000000	0.0000717
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\Delta \ln \underline{w}_{i,t-3}$					
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		(0.00931)	(0.00966)	(0.00967)	(0.00921)	(0.00953)
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\Delta \ln w_{i,t-2}$	0.00608	0.00537	0.00547	0.00603	0.00565
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	i,t-2					
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		()	()	()	()	()
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\Delta \ln \underline{w}_{i,t-1}$	-0.000280	-0.00213	-0.00231	-0.0000542	-0.00229
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		(0.0123)	(0.0125)	(0.0126)	(0.0122)	(0.0126)
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	A 1	0.00=0**	0.00.40*	0.0040*	0.0000**	0.0045*
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\Delta \ln \underline{w}_{i,t}$					
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		(0.0127)	(0.0124)	(0.0125)	(0.0127)	(0.0127)
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\ln m$	0.0136*	0.0128*	0.0130*	0.0136*	0.0127*
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$m \underline{\underline{\omega}} i, t+1$					
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		(0.00110)	(0.00110)	(0.00110)	(0.00110)	(0.00121)
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\Delta \ln \underline{w}_{i,t+2}$	-0.00702	-0.00608	-0.00596	-0.00682	-0.00598
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	-,- 1 -	(0.0133)	(0.0136)	(0.0136)	(0.0133)	(0.0136)
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$						
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\Delta \ln \underline{w}_{i,t+3}$					
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		(0.00808)	(0.00784)	(0.00769)	(0.00789)	(0.00767)
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\Delta \ln m$	0.0108	0.0110	0.0110*	0.0108	0.0113*
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	$\Delta \prod \underline{w}_{i,t+4}$					
P-value no pretrends (0.00686) (0.00660) (0.00656) (0.00672) (0.00655) Wage controls 0.579 0.714 0.716 0.608 0.727 Wage controls No Yes No No Yes Employment controls No No Yes No Yes Establishment-count controls No No No Yes Yes R-squared 0.022 0.022 0.022 0.022 0.022 0.022		(0.00093)	(0.00038)	(0.00000)	(0.0004)	(0.00049)
P-value no pretrends (0.00686) (0.00660) (0.00656) (0.00672) (0.00655) Wage controls 0.579 0.714 0.716 0.608 0.727 Wage controls No Yes No No Yes Employment controls No No Yes No Yes Establishment-count controls No No No Yes Yes R-squared 0.022 0.022 0.022 0.022 0.022 0.022	$\Delta \ln w_{i t + 5}$	0.00862	0.00952	0.00970	0.00882	0.00967
P-value no pretrends 0.579 0.714 0.716 0.608 0.727 Wage controls No Yes No No Yes Employment controls No No Yes No Yes Establishment-count controls No No No Yes Yes R-squared 0.022 0.022 0.022 0.022 0.022 0.022		(0.00686)	(0.00660)	(0.00656)	(0.00672)	
Wage controlsNoYesNoNoYesEmployment controlsNoNoYesNoYesEstablishment-count controlsNoNoNoYesYesR-squared0.0220.0220.0220.0220.022	P-value no pretrends	. ,	,	` /	, ,	
Employment controls No No Yes No Yes Establishment-count controls No No No Yes Yes R-squared 0.022 0.022 0.022 0.022 0.022	-	No	Yes	No	No	Yes
R-squared 0.022 0.022 0.022 0.022 0.022	Employment controls	No	No	Yes	No	Yes
•	Establishment-count controls	No	No	No	Yes	Yes
Observations 106,446 104,360 104,360 106,160 104,360	R-squared	0.022	0.022	0.022	0.022	0.022
	Observations	106,446	104,360	104,360	106,160	104,360

Table 4: Dynamic models: cumulative sum of coefficients

	(1)	(2)	(3)	(4)	(5)
Sum of MW effects	0.0566	0.0554	0.0562	0.0563	0.0556
	(0.0347)	(0.0345)	(0.0343)	(0.0343)	(0.0342)
Wage controls	No	Yes	Yes	No	Yes
Employment controls	No	No	No	No	Yes
Establishment-count controls	No	No	No	Yes	Yes
Observations	$106,\!446$	$104,\!360$	$104,\!360$	$106,\!160$	$104,\!360$

Table 5: Horse race models

	(1)	(2) Distributed	(3) Distributed	(4) AB Distributed	(5) AB Distributed	(6) MW Distributed	(7) MW Distributed
	DiD	leads and lags	Lags	leads and lags	Lags	leads and lags	Lags
$\Delta \ln \underline{w}_{i,t-5}$		-0.0146		-0.0134		-0.0167	
-,-		(0.00910)		(0.00910)		(0.0155)	
$\Delta \ln \underline{w}_{i,t-4}$		-0.00232		0.00494		-0.00886	
		(0.0116)		(0.0105)		(0.0347)	
$\Delta \ln \underline{w}_{i,t-3}$		0.00137		0.00222		0.000503	
		(0.00931)		(0.00918)		(0.0152)	
$\Delta \ln \underline{w}_{i,t-2}$		0.00608		0.00581		0.00647	
-,-		(0.0115)		(0.0139)		(0.0102)	
$\Delta \ln \underline{w}_{i,t-1}$		-0.000280		-0.00531		-0.000132	
-,-		(0.0123)		(0.0151)		(0.0154)	
$\Delta \ln \underline{w}_{i,t}$	0.0259*	0.0270**	0.0261*	0.0294*	0.0288*	0.0267**	0.0256**
-,-	(0.0129)	(0.0127)	(0.0129)	(0.0157)	(0.0160)	(0.0104)	(0.0106)
$\ln \underline{w}_{i,t+1}$		0.0136*	0.0161**	0.000887	0.00401	0.0267	0.0304
-,-,-		(0.00715)	(0.00750)	(0.00733)	(0.00788)	(0.0514)	(0.0536)
$\Delta \ln \underline{w}_{i,t+2}$		-0.00702	-0.00673	-0.0131	-0.0142	-0.00102	0.00170
-,- , -		(0.0133)	(0.0125)	(0.0128)	(0.0120)	(0.0286)	(0.0354)
$\Delta \ln \underline{w}_{i,t+3}$		0.00364	0.00392	0.00651	0.00692	0.000616	0.000316
, .		(0.00808)	(0.00799)	(0.00798)	(0.00764)	(0.0158)	(0.0173)
$\Delta \ln \underline{w}_{i,t+4}$		0.0108	0.0105	0.00897	0.00850	0.0120	0.0122
, .		(0.00693)	(0.00684)	(0.00736)	(0.00737)	(0.0108)	(0.0119)
$\Delta \ln \underline{w}_{i,t+5}$		0.00862	0.00637	0.00384	0.00163	0.0124	0.0112
-,- 1		(0.00686)	(0.00675)	(0.00878)	(0.00870)	(0.0160)	(0.0174)
$\Delta \ln y_{i,t-1}$				0.421***	0.436***	-0.451	-0.531
0-,				(0.0238)	(0.0231)	(1.634)	(1.812)
Observations	112,232	106,446	112,161	104,208	109923	105,303	111,018

Figure 1: Dynamic model

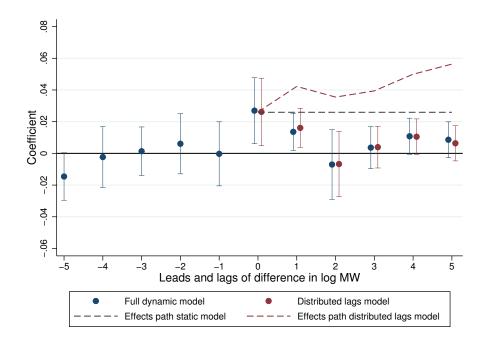


Figure 2: Dynamic model: varying controls

