

“You must be at least this tall”:

Threads, fork(), Deadlocks and Tests



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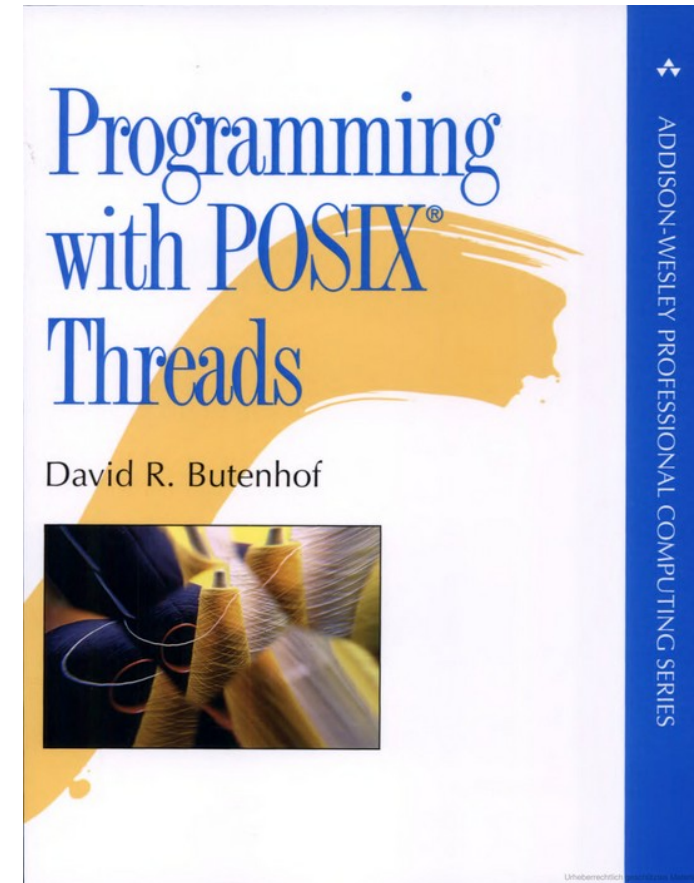
- Threads and Processes
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Must be
this tall to
write multi-
threaded
code.

Threads and Processes

- Threads implicitly share their memory (except stack), processes don't
- Threads arrived late in Unix/POSIX (pthreads: late nineties)
- Implicit memory sharing is dangerous & difficult → lots of locking required
- Java: **synchronized {}** block protection
- Python: threads honour the GIL → no CPU gain



multiprocessing v. threading

- Interface of multiprocessing.Process and threading.Thread look identical:

```
def print_val(val):  
    print(val)
```

```
import threading  
t = threading.Thread(target=print_val, args=("Hello",))  
t.start()  
t.join()
```

```
import multiprocessing as mp  
p = mp.Process(target=print_val, args=("Hello",))  
p.start()  
p.join()
```

multiprocessing v. threading

- Behaviour may differ, though:

```
def append_val(lst, val):  
    lst.append(val)
```

```
l = []  
t = threading.Thread(target=append_val,  
                     args=(l, "Hello",))
```

```
t.start()  
t.join()  
print(l)
```

```
l = []  
p = mp.Process(target=append_val, args=(l, "Hello",))  
p.start()  
p.join()  
print(l)
```

Unix Interface to Processes I

- Also used in the intestines of multiprocessing
- `fork(2)` is a syscall that is *called once* but **returns twice**:
 - In the original process, returns new process id
 - In the new process, returns 0
- `waitpid(2)` is a syscall that waits for a process to terminate (blocking or non-blocking)
- What does it look like?

Unix Interface to Processes II

```
pid = os.fork()
if pid == 0:
    # child process ...
    os._exit(exitcode) # not sys.exit()!
else:
    # parent process ...
    child_pid, exitstatus = os.waitpid(pid, 0)
    exitcode = os.WEXITSTATUS(exitstatus)
```

- New process is a copy on write (COW) memory image of original process
- Python: ref counting makes COW virtually useless
- File handles are duplicated, sockets inherited

Example – SOLR Index Updater

- Task: feed updates from spool dir into SOLRCloud cluster
- Digests linewise JSON delta file (0..1 lines per doc)
- Lots of converting → lots of CPU
- HTTP POST to SOLR already in its own thread (I/O bound so GIL is no issue)
- (Many) more updates → updater is CPU bound
- Thus, processes not threads
- Nagios bright red → we need a solution, now!

Index Updater Worker Processes

- New delta file arrives → we fork() worker processes
- Each worker knows its number and n_workers, i.e. knows which lines to process:

```
def updater_main(fname, n_workers, worker_num):  
    log.info("worker %i of %i", worker_num, n_workers)  
    #...  
    for i, line in enumerate(open(fname)):  
        if i % n_workers != worker_num:  
            continue  
        # actually process line
```

- Each worker gets its own POST thread

Index Updater Worker Processes

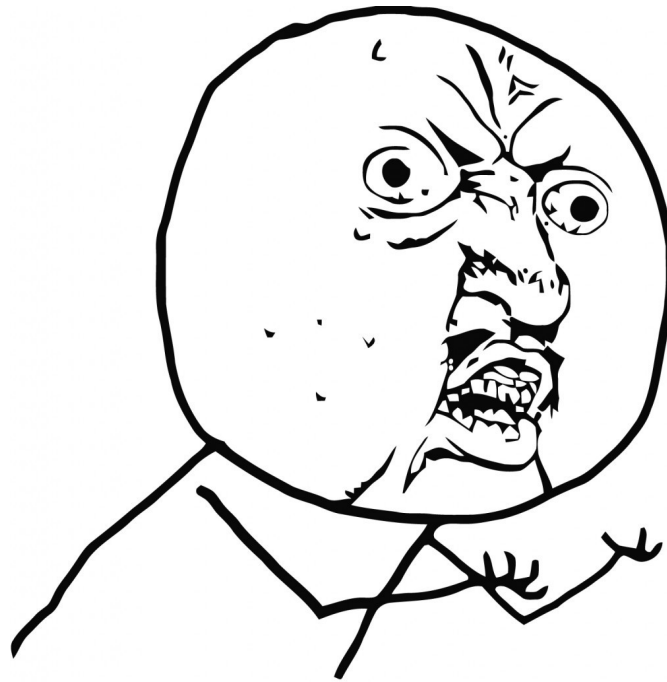
- Worked fine... most of the time
- Occasional deadlocks!
Child processes would lock up,
parent waits forever.



- Caused by...

Index Updater Worker Processes

- Worked fine... most of the time
- Occasional deadlocks!
Child processes would lock up,
parent waits forever.



- Caused by... **our monitoring thread!**

fork() and Threads

- Thread creation *after* fork() is fine, but...
- POSIX says: A process forked from a multithreaded process may basically just call `execv()`
- **CERN says:** “Mixing Python modules multiprocessing and threading along with logging error/debug messages with module logging is a very bad idea which leads to unexpected process stalling.”

fork() and Threads

- **Python Bugtracker says:** “The python logging module uses a lock to surround many operations, in particular. This causes deadlocks in programs that use logging, fork and threading simultaneously.”
- **What POSIX actually says:** “A process shall be created with a single thread. If a multi-threaded process calls fork(), the new process shall contain a replica of the calling thread and its entire address space, possibly including the states of mutexes and other resources. Consequently, to avoid errors, the child process may only execute async-signal-safe operations until such time as one of the exec functions is called. [THR]”

Processes and **py.test**

- **py.test** works well with multiprocessing:

```
def print_val(val):  
    print(val)  
  
def test_mp():  
    p = multiprocessing.Process(  
        target=print_val,  
        args=("unittest mp", ),  
    )  
    p.start()  
    p.join()  
    assert p.exitcode == 0
```

- But what about `os.fork()` style processes?

fork() and py.test

```
def print_val(val):  
    print(val)  
  
def test_fork():  
    pid = os.fork()  
    if pid == 0:  
        print_val("unittest fork")  
        os._exit(0)  
    else:  
        child_pid, exitcode = os.waitpid(pid, 0)  
        assert child_pid == pid  
        assert os.WEXITSTATUS(exitcode) == 0
```

- Use `os._exit()` instead of `sys.exit()` b/c `SystemExit`
- No coverage for child process!

Summary

- If you can, use multiprocessing instead of `os.fork()` and `os.waitpid()`
- Because multiprocessing plays nice with `py.test`
- No multiprocessing or `fork()` after thread creation
- Unless the child just `os.exec()`utes another program
- You're **NOT** Tall Enough.

