

Example 1, Example 2

Stability Limit

Example 3

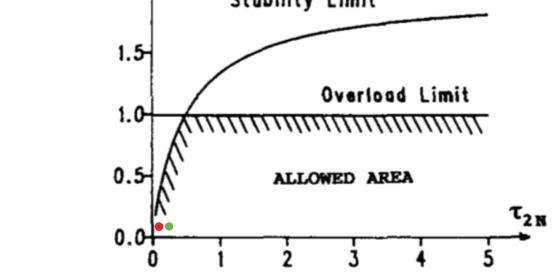


Fig. 18. Stability and overload limits for the PLL normalized loop gain  $K_N$  as function of the normalized loop filter time constant  $\tau_{2N}$ .