

# Using multidimensional scaling with Duchon splines for reliable finite area smoothing

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Recent advances in spatial statistics in ecology  
5 May 2011  
St Andrews

# Outline

## Smoothing over complex regions

The problem

Smoothing with splines

Solutions

## Multidimensional Scaling

Details

Finding the within-area distances

Simulation Results

## High dimensional smoothing with Duchon splines

Nullspaces

Duchon splines

Results

## General distance smoothing

Conclusions

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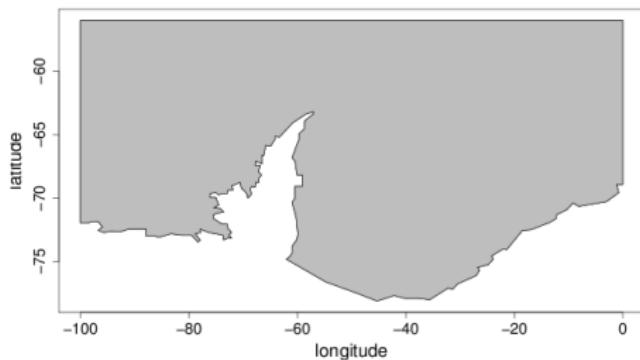
- Results

## General distance smoothing

- Conclusions

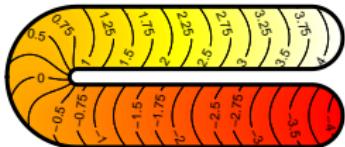
## Smoothing in 2 dimensions

- ▶ Have some geographical region and wish to find out something about the biological population in it.
- ▶ Response is eg. animal distribution, wish to predict based on  $(x, y)$  and other covariates eg. habitat, size, sex, etc.
- ▶ This problem is relatively easy if the domain is simple.

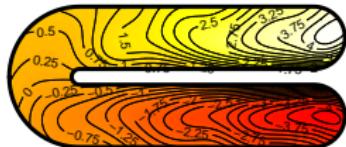


# Leakage (or, “whales don’t live in glaciers”)

- ▶ Smoothing of complex domains makes this a lot more difficult.
- ▶ Problem of leakage.
- ▶ Wrong metric.
- ▶ Euclidean distance doesn’t always make sense.



(modified) Ramsay test function



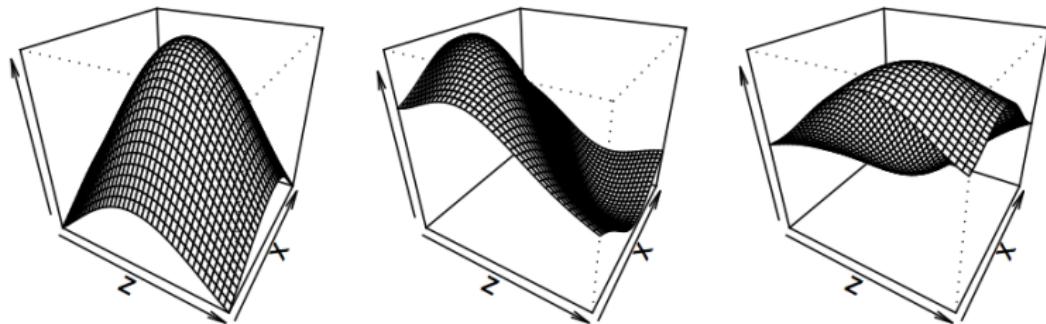
Thin plate spline fit

## Smoothing with penalties

- ▶ Do smoothing with splines in an additive model framework.
- ▶ Take some linear combination of (known) basis functions.
- ▶ Penalize based on integral of second squared derivative:

$$\int \int_{\mathbf{R}^2} \left( \left( \frac{\partial^2 f(x_1, x_2)}{\partial x_1^2} \right)^2 + \left( \frac{\partial^2 f(x_1, x_2)}{\partial x_1 \partial x_2} \right)^2 + \left( \frac{\partial^2 f(x_1, x_2)}{\partial x_2^2} \right)^2 \right) dx_1 dx_2.$$

- ▶ Using thin plate regression splines (eg Wood (2003)).



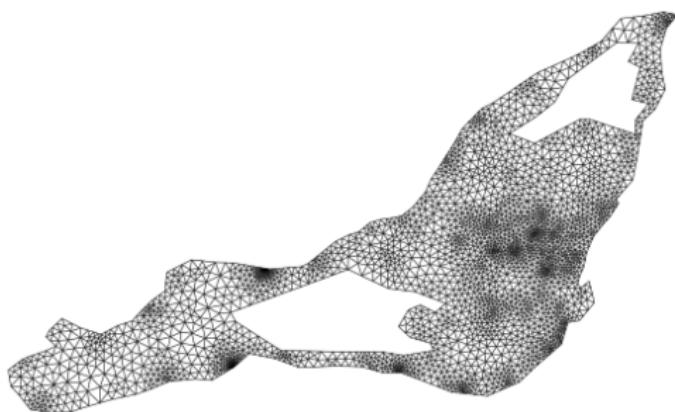
# Proposed solutions to leakage problems

Two classes:

- ▶ PDEs:
  - ▶ FELSPINE (Ramsay, 2002).
  - ▶ Soap film smoothers (Wood *et al*, 2008).
- ▶ Within-area distance
  - ▶ Geodesic Low-Rank Thin Plate Splines (GLTPS) (Wang and Ranalli, 2007).

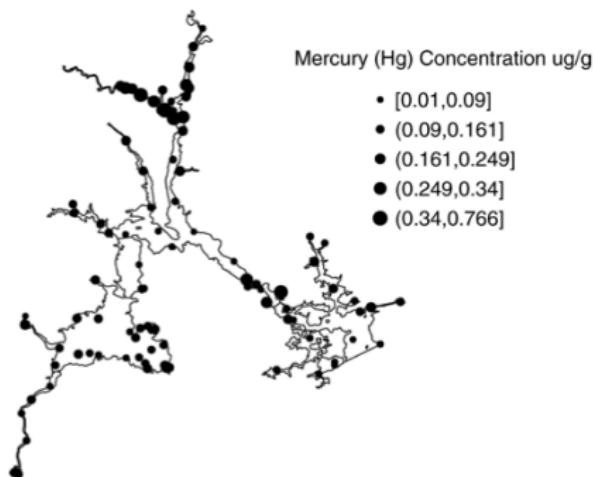
## FELSPLINE (Ramsay, 2002)

- ▶ Triangulate domain.
- ▶ Setup PDEs on triangles.
- ▶ Solve PDE system  $\Rightarrow$  solve smoothing problem.
- ▶ BAD: unrealistic boundary condition.



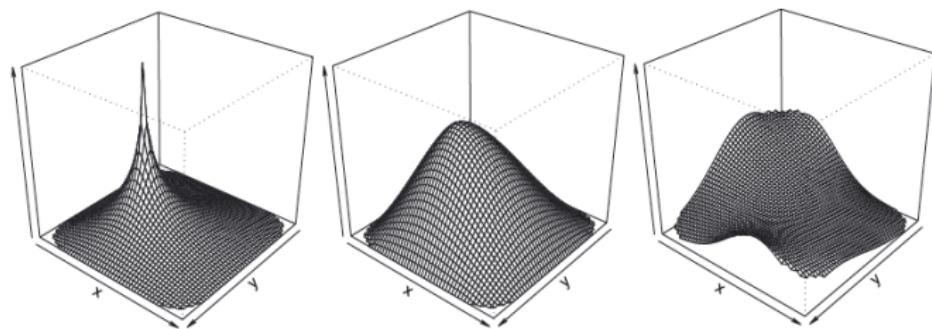
# Geodesic Low-Rank Thin Plate Splines (GLTPS) (Wang and Ranalli, 2007).

- ▶ Form the complete graph ( $G$ ) on the data.
- ▶ Run  $k$ -NN, to create the reduced graph ( $G_k$ ).
- ▶ Use Floyd's algorithm to find distances ( $O(n^3)$ ).
- ▶ BAD: few data  $\Rightarrow$  inaccurate distances.
- ▶ BAD: many data  $\Rightarrow$  slow!



## Soap film smoothers (Wood *et al*, 2008)

- ▶ Coat hangers, soapy water, PDEs.
- ▶ Solve PDEs (Laplace + Poisson)  $\Rightarrow$  basis functions.
- ▶ Cyclic spline gives boundary conditions.
- ▶ BAD: mathematically complex.

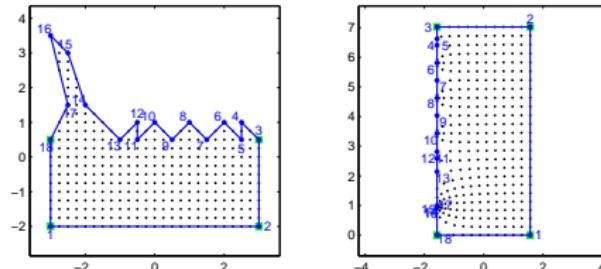


# Domain morphing

- ▶ Domain morphing - think of domain as silly putty.
- ▶ Takes into account within-area distance.
- ▶ Potentially less computationally intensive.
- ▶ Eilers (2006) proposes Schwarz-Christoffel transform.
- ▶ Gives a known domain - easier to smooth over.

**However:**

- ▶ Crowding - numerical singularities.
- ▶ Not clear what this does to the smoothness penalty - artefacts, penalty issues - but NOT GOOD!



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# Multidimensional scaling and within-area distances

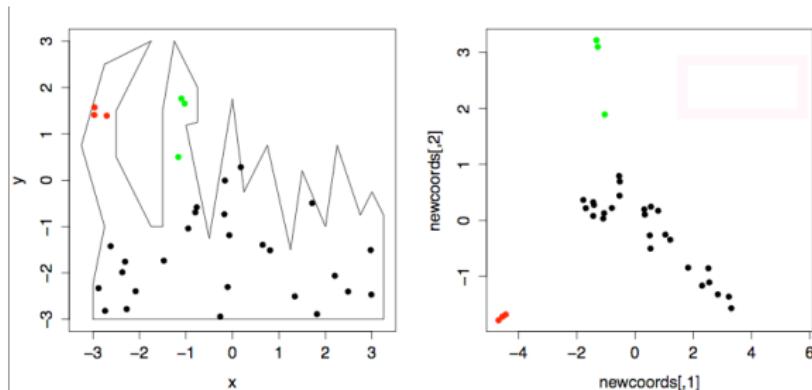
- ▶ Idea: use MDS to arrange points in the domain according to their distance within the domain.

## Scheme:

- ▶ First need to find the within-area distances.
- ▶ Perform MDS on the matrix of within-area distances.
- ▶ Find the new configuration of the points.
- ▶ Smooth over the new points.

## Multidimensional scaling refresher

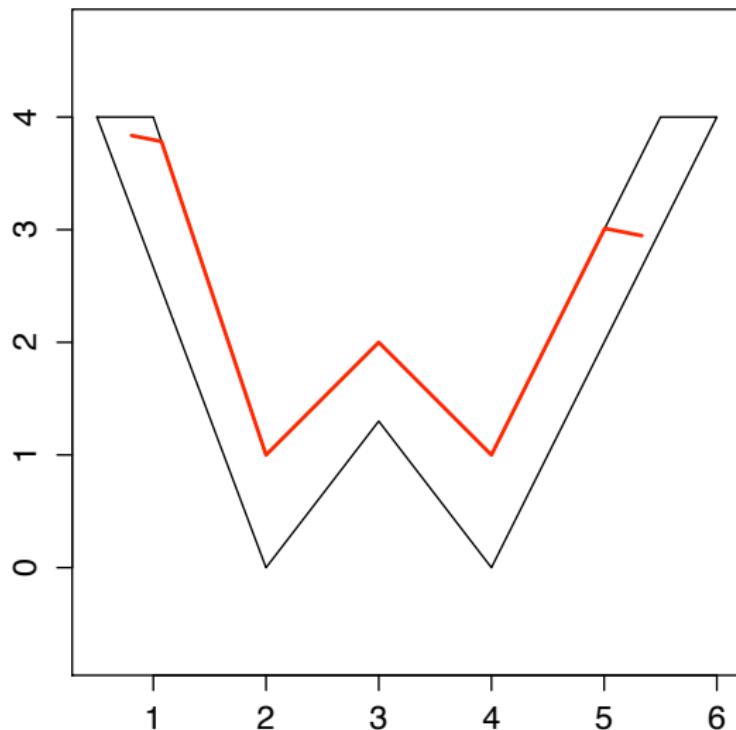
- ▶ Use double centred matrix of between point distances,  $D$ , using the eigen-decomposition of  $DD^T$  we can find new points.
- ▶ Finds a projection of points such that Euclidean distance between points in new arrangement is approximately the same as the distances in  $D$ .
- ▶ New points can be added into the MDS configuration via Gower's interpolation (Gower, 1968)



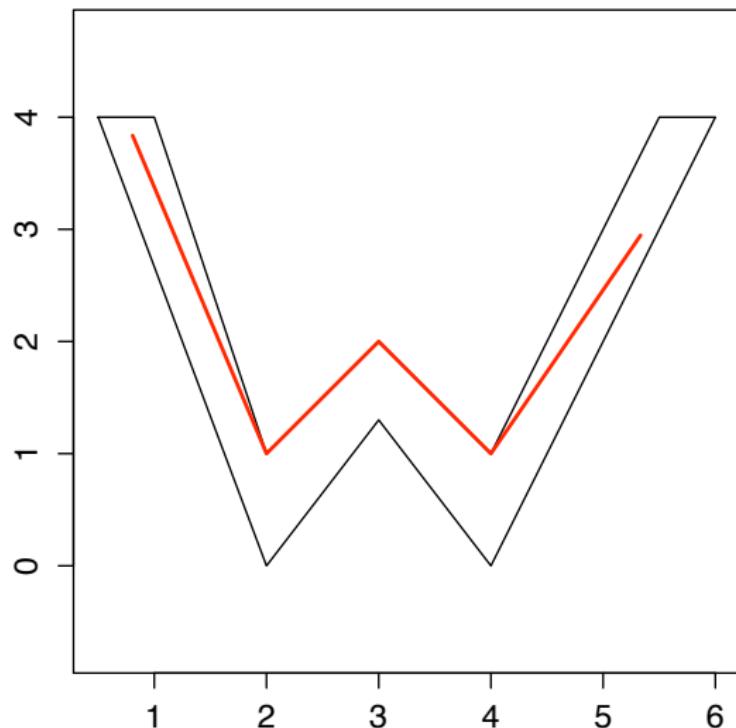
## A “new” algorithm for finding within-area distances

**So, how do we find the distances to put in D?**

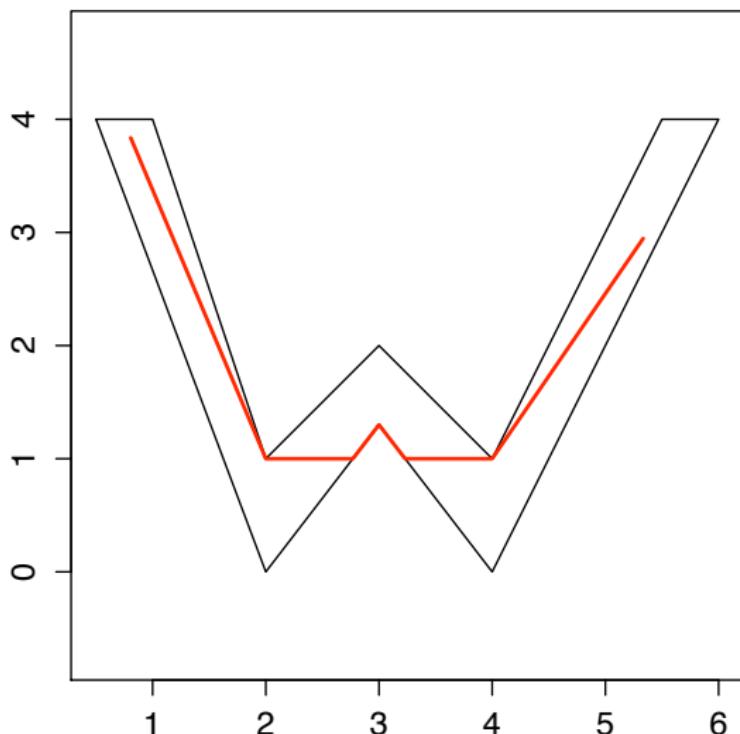
## Finding the path - 1



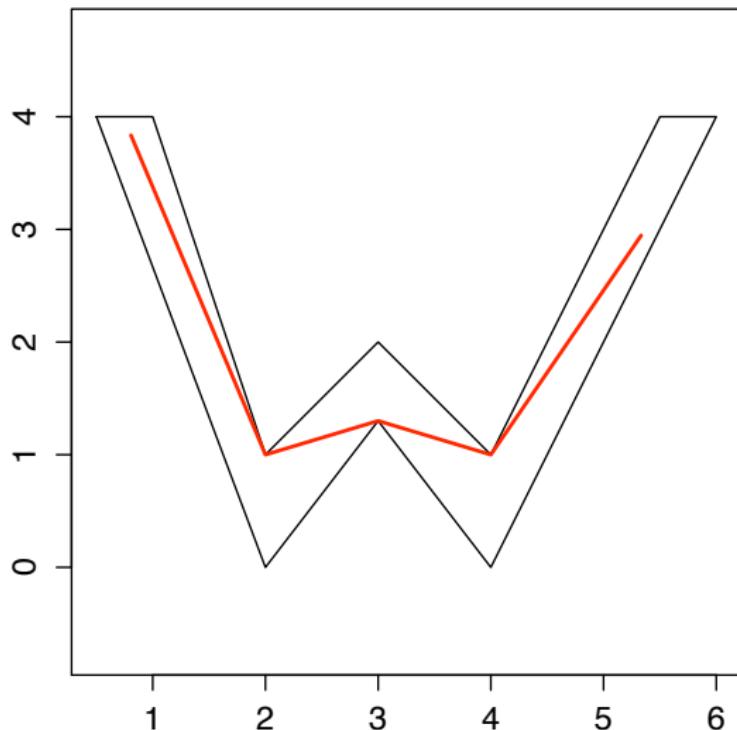
## Finding the path - 2



## Finding the path - 3



## Finding the path - 4

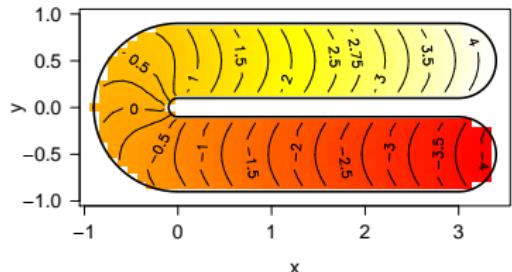


# Simulations

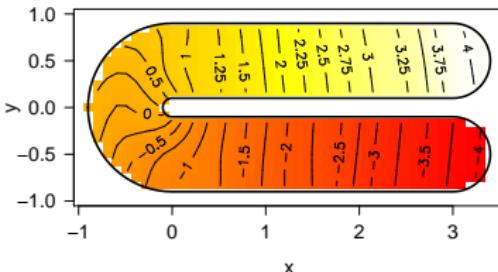
**But how does it perform?**

# Ramsay simulations

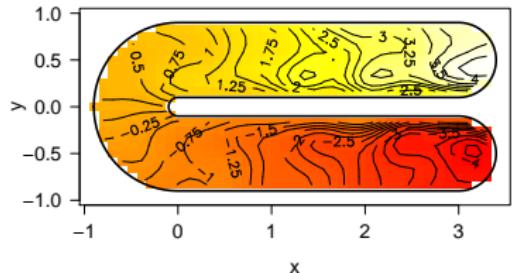
truth



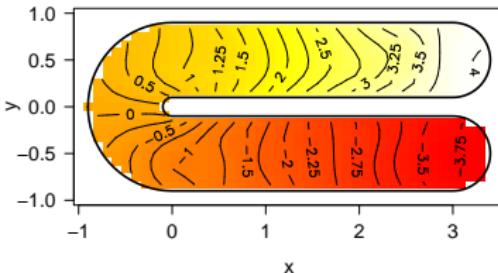
MDS



tprs

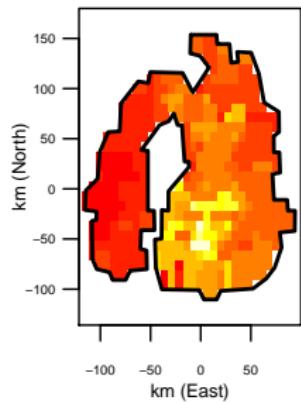


soap

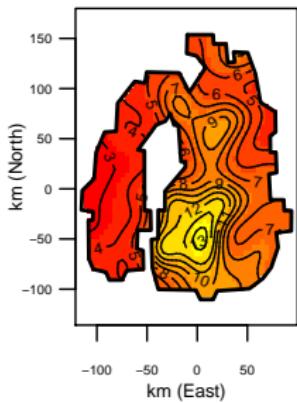


# The Aral sea

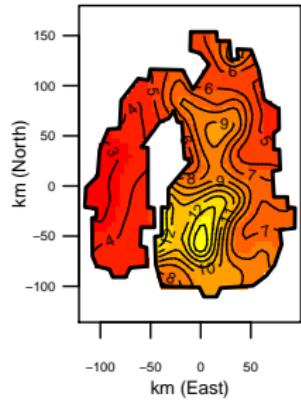
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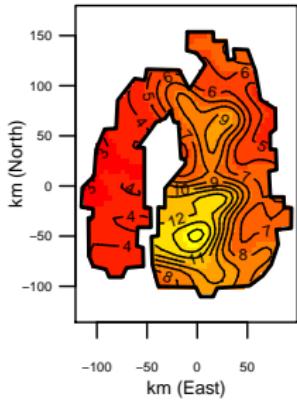
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soap



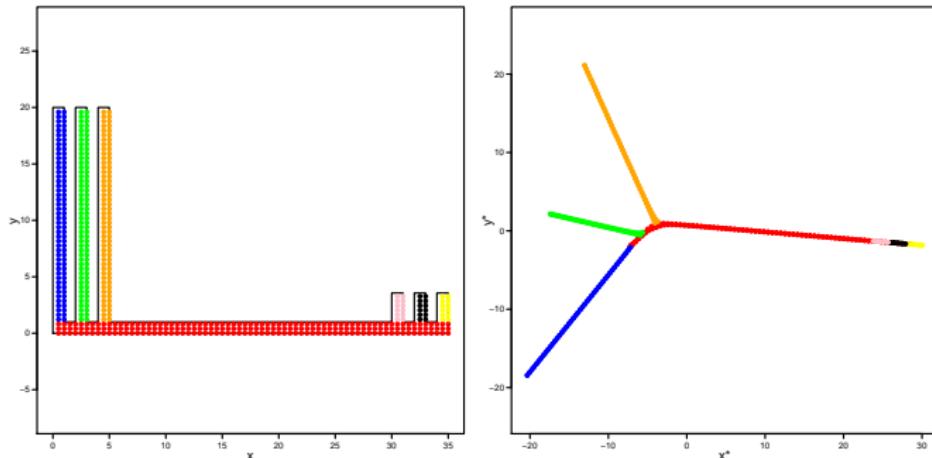
mds



But...

- ▶ Computationally costly to find the within-area distances.  
(Esp. prediction.)
- ▶ Comparative in MSE terms to the soap film smoother.
- ▶ Artefacts – ordering?
- ▶ Taking a  $m$ -D projection of  $n$ -D space – higher dimensions == better?

### [[3D PLOT]]



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# High dimensional smoothing with Duchon splines

**How can we fix this?**

## Nullspaces

- ▶ TPRS functions of the form:

$$f(\mathbf{x}) = \sum_{i=1}^n \delta_i \eta_{md}(\mathbf{x} - \mathbf{x}_i) + \sum_{j=1}^M \alpha_j \phi_j(\mathbf{x})$$

= radial basis functions + “planes”

Where

$m$  = the derivative order in the penalty

$d$  = smoothing dimension

$n$  = # data

$M$  = nullspace dimension

- ▶  $\phi_j(\mathbf{x})$  are linearly independent polynomials of degree  $< m$ .

## When nullspaces get big...(I)

- ▶ For TPRS, nullspace size is

$$M = \binom{m+d-1}{d}$$

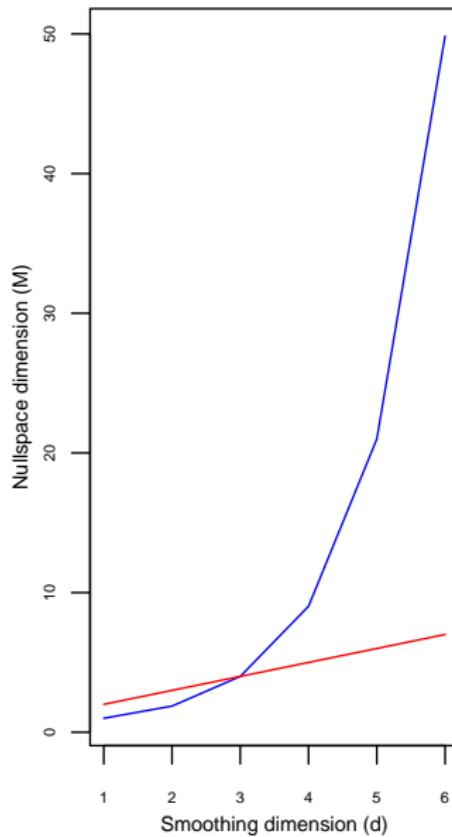
Where

$m$  = the derivative order in the penalty

$d$  = smoothing dimension

- ▶ **AND** must obey  $2m > d$   
smoothing dimension++  $\Rightarrow$  derivative order++++.
- ▶  $M$  gets very big, very fast.

## When nullspaces get big... (II)



# Enter Jean Duchon...

## SPLINES MINIMIZING ROTATION-INVARIANT SEMI-NORMS IN SOBOLEV SPACES

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### ABSTRACT

We define a family of semi-norms  $\|u\|_{m,s} = \left( \int_{\mathbb{R}^n} |\tau|^{2s} |\mathcal{F} D^m u(\tau)|^2 d\tau \right)^{1/2}$ .

Minimizing such semi-norms, subject to some interpolating conditions, leads to functions of very simple forms, providing interpolation methods that :

1°) preserve polynomials of degree  $\leq m-1$  ; 2°) commute with similarities as well as translations and rotations of  $\mathbb{R}^n$  ; and 3°) converge in Sobolev spaces  $H^{m+s}(\Omega)$ .

# High dimensional smoothing with Duchon splines

**TPRS to Duchon splines.**

# High dimensional smoothing with Duchon splines

Wood (2003) type penalty in 2D, order 2 derivatives:

$$\int \int_{\mathbf{R}^2} \left( \left( \frac{\partial^2 f(x_1, x_2)}{\partial x_1^2} \right)^2 + \left( \frac{\partial^2 f(x_1, x_2)}{\partial x_1 \partial x_2} \right)^2 + \left( \frac{\partial^2 f(x_1, x_2)}{\partial x_2^2} \right)^2 \right) dx_1 dx_2.$$

More generally:

$$J_{m,d} = \int \dots \int_{\mathbb{R}^d} \sum_{\nu_1 + \dots + \nu_d = m} \frac{m!}{\nu_1! \dots \nu_d!} \left( \frac{\partial^m f(x_1, \dots, x_d)}{\partial x_1^{\nu_1} \dots \partial x_d^{\nu_d}} \right)^2 dx_1 \dots dx_d$$

# High dimensional smoothing with Duchon splines

$$J_{m,d} = \int \cdots \int_{\mathbb{R}^d} \sum_{\nu_1 + \cdots + \nu_d = m} \frac{m!}{\nu_1! \cdots \nu_d!} \left( \frac{\partial^m f(x_1, \dots, x_d)}{\partial x_1^{\nu_1} \cdots \partial x_d^{\nu_d}} \right)^2 dx_1 \cdots dx_d$$

Why not take the Fourier transform?

$$J_{m,d} = \int \cdots \int_{\mathbb{R}^d} \sum_{\nu_1 + \cdots + \nu_d = m} \frac{m!}{\nu_1! \cdots \nu_d!} \left( \mathfrak{F} \frac{\partial^m f}{\partial x_1^{\nu_1} \cdots \partial x_d^{\nu_d}}(\boldsymbol{\tau}) \right)^2 d\boldsymbol{\tau}$$

(Equivalent by Plancherel theorem)

## Duchon splines penalty

Putting in some arbitrary weighting,  $w(\boldsymbol{\tau})$ :

$$\check{J}_{m,d} = \int \dots \int_{\mathbb{R}^d} w(\boldsymbol{\tau}) \sum_{\nu_1 + \dots + \nu_d = m} \frac{m!}{\nu_1! \dots \nu_d!} \left( \mathfrak{F} \frac{\partial^m f}{\partial x_1^{\nu_1} \dots \partial x_d^{\nu_d}} (\boldsymbol{\tau}) \right)^2 d\boldsymbol{\tau}$$

Let  $w(\boldsymbol{\tau}) = |\boldsymbol{\tau}|^{2s}$  (Duchon 1977)

$$\check{J}_{m,d} = \int \dots \int_{\mathbb{R}^n} |\boldsymbol{\tau}|^{2s} \sum_{\nu_1 + \dots + \nu_d = m} \frac{m!}{\nu_1! \dots \nu_d!} \left( \mathfrak{F} \frac{\partial^m f}{\partial x_1^{\nu_1} \dots \partial x_d^{\nu_d}} (\boldsymbol{\tau}) \right)^2 d\boldsymbol{\tau}$$

## Duchon splines penalty

$$\check{J}_{m,d} = \int \dots \int_{\mathbb{R}^n} |\boldsymbol{\tau}|^{2s} \sum_{\nu_1 + \dots + \nu_d = m} \frac{m!}{\nu_1! \dots \nu_d!} \left( \mathfrak{F} \frac{\partial^m f}{\partial x_1^{\nu_1} \dots \partial x_d^{\nu_d}} (\boldsymbol{\tau}) \right)^2 d\boldsymbol{\tau}$$

- ▶ This penalises high frequency components of the derivatives.
- ▶ For continuity now just need:

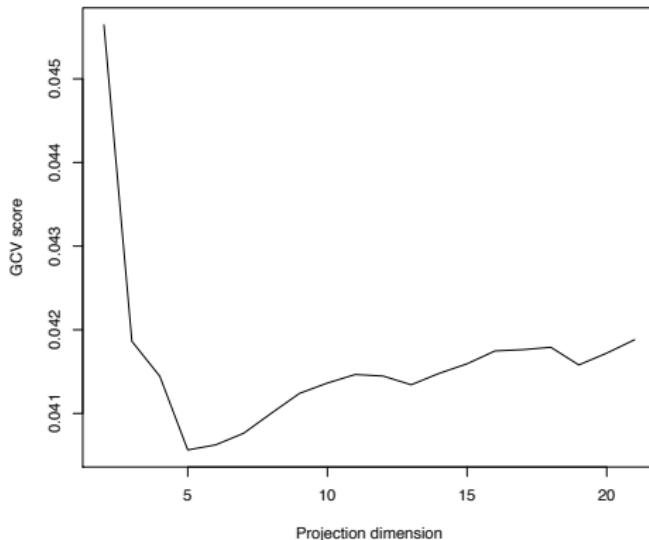
$$d/2 - m \leq s$$

- ▶ Can now always use  $m = 2$  (some pseudo-theoretical reasons for that) and we have a set  $d$ , determine  $s$  by

$$s = d/2 - 2$$

## Using ML/GCV score to select projection dimension

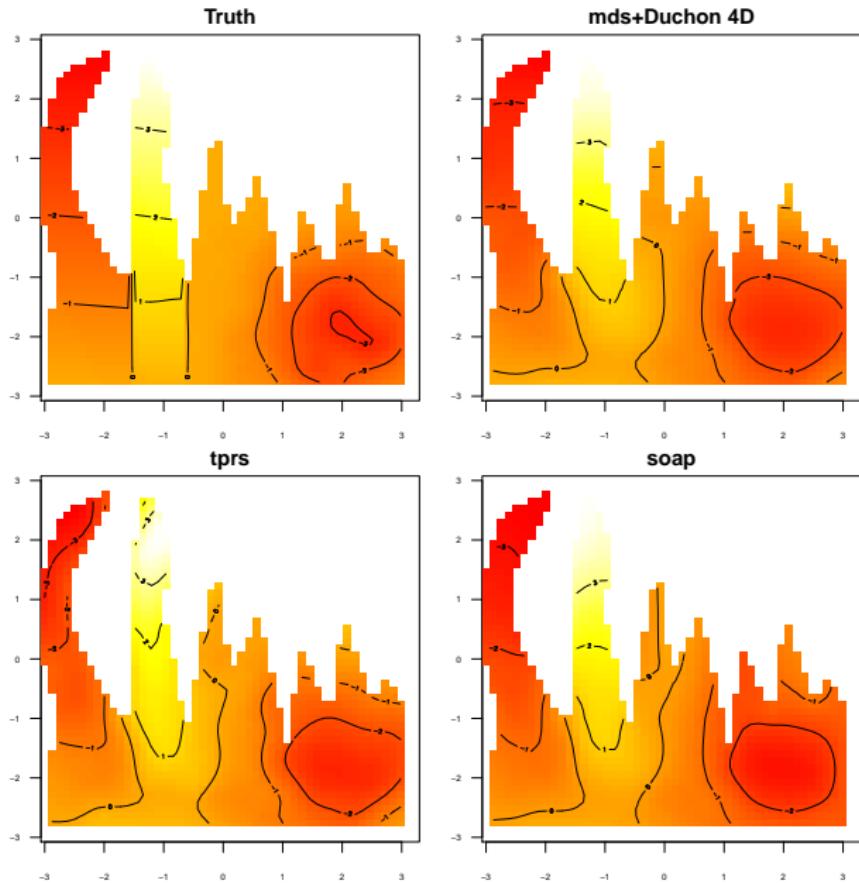
- ▶ So, we can now smooth in higher dimensions, **but how many?**
- ▶ Select MDS dimension using GCV or ML score.
- ▶ Fit model in a range of dimensions, pick best score.
- ▶ No guarantee of having a “nice” function to optimise.



## More results

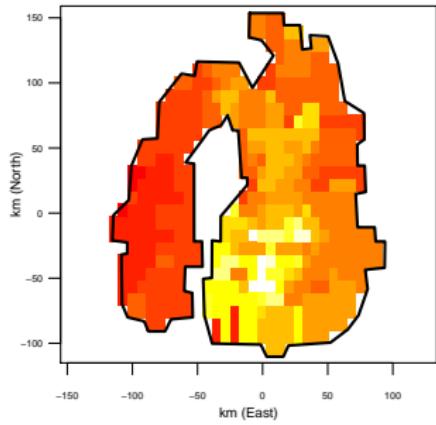
**How well do Duchon splines do?**

# Fake coastline simulation

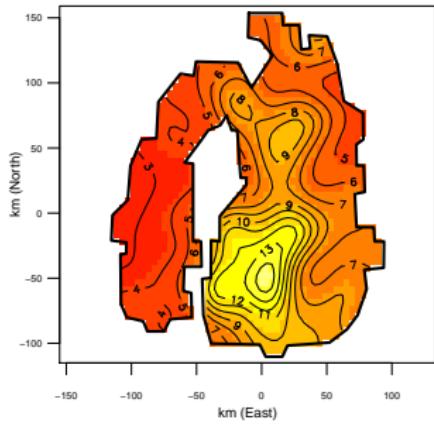


# Aral sea

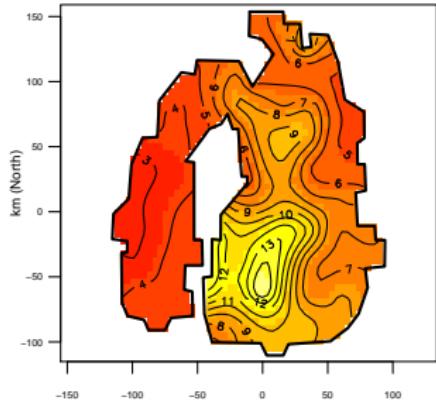
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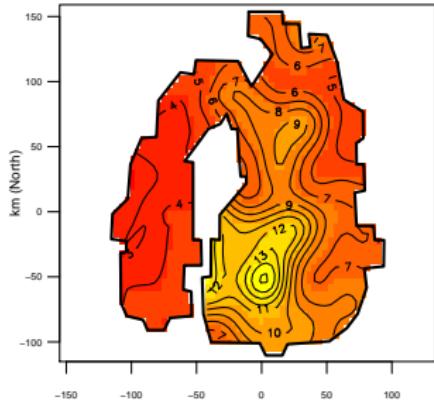
tprs



soap



mds 5D



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## General distance smoothing

- ▶ Given a general distance matrix,  $D$ .
- ▶ Project the points in  $D$  using MDS.
- ▶ Smooth over those points – full GAM framework available.

Examples:

- ▶ Other bio/ecol distances (?)
- ▶ MP voting data
- ▶ Microarrays
- ▶ Socio-economic data

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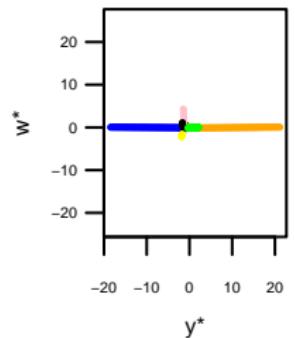
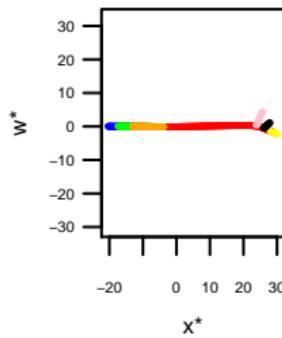
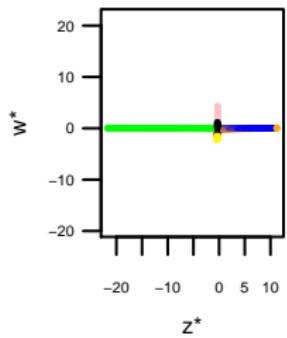
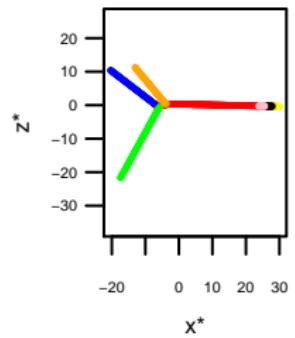
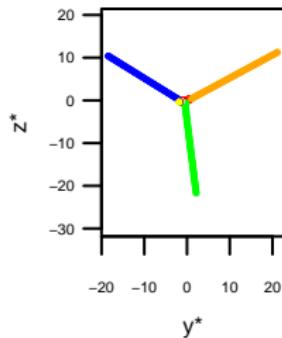
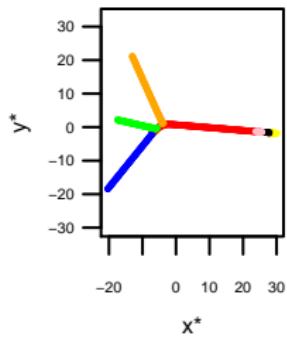
## Conclusions

## Conclusions

- ▶ Using Duchon splines gets around problems with high dimensional smoothing.
- ▶ MDS projections + Duchon splines + WAD useful for spatial smoothing.
- ▶ Perhaps applications in a broader set of problems involving distances.

Slides available at <http://people.bath.ac.uk/dlm27>

## Appendix - Ordering problems in 4-D



## Appendix - A “new” algorithm for finding within-area distances

- ▶ Algorithm “bounces” around inside the polygon.
- ▶ Initial path is just the path around the edge, then iterate over two steps: *delete* and *alter*.
- ▶ Delete (iterating over all nodes):
  - ▶ If we can shorten the path by simply deleting a node, do that.
- ▶ Alter (iterating over all nodes):
  - ▶ If we can find a shorter sub-path by bouncing off the other “side” of the polygon, do that.