

#### SOFTWARE ENGINEER · ROBOTICS ENGINEER

Jl. Tubagus Ismail II No. 10, Bandung, 40134, Indonesia

□ (+62) 813-3645-6789 | ■ dionesiusap@gmail.com | 回 dionesiusap | 🖬 dionesius-agung

# **Summary**

A student currently pursuing a bachelor's degree in computer science from Institut Teknologi Bandung with high interests in robotics and AI, mainly focused in state estimation, active perception, and computer vision. A proactive person who is eager to learn new things and has good communication skills. An aspiring engineer currently looking for opportunity as robotics software engineer.

## **Education**

#### **Institut Teknologi Bandung**

Bandung, Indonesia

BACHELOR OF ENGINEERING, COMPUTER SCIENCE (GPA 3.08/4.00)

Aug 2016 - Jul 2020 (expected)

- · Currently doing final project about autonomous navigation and control for simultaneous localization and mapping (SLAM) on mobile robots.
- · Is currently active in a robotics team focusing on mobile robots, doing research and software implementations.

# **Experiences**

#### **Shopee Internasional Indonesia**

Jakarta, Indonesia May 2019 - Aug 2019

SOFTWARE ENGINEER INTERN

- Implemented back end handler component that deals with high number of requests per second.
- · Created feature release manager to enable independent and individual releases of features for different countries.

Dagozilla ITB Robotics

Bandung, Indonesia

LEAD SOFTWARE ENGINEER Sept 2018 - Sept 2019

- · Generally directed the research and development on computer vision, robotic system controls, robot AI, and software UI/UX.
- Designed and implemented AI for goalkeeper robot behavior and decision making.
- · Researched and implemented algorithm for robot state (position) estimation using Monte Carlo Localization.

SOFTWARE ENGINEER Sept 2017 - Present

- · Designed architecture for computer vision system software for football-playing robots that compete in Indonesian MSL.
- Made object (ball, obstacle, and field) detection for MSL robots using OpenCV library.
- Did research on odometry and IMU sensor fusion using Extended Kalman Filter.

### Skills

**Programming** Python, C++, Golang, Javascript, Node.js

Systems and Tools ROS (Robot Operating System), Unix Operating Systems, OpenCV Library

**Human Languages** Indonesian (native), English (fluent/native proficiency)

# **Projects**

### **Vision-Based Vehicle License Plate Reader**

Image Processing

USING PURE IMAGE PROCESSING TECHNIQUES WITHOUT ANY LEARNING ALGORITHMS TO READ LICENSE PLATES

2019

- Built a custom image processing library for the recognition.
- Used pure image processing methods to recognize characters on license plates.
- Created a web-based graphical user interface for the application.
- Used C++, Javascript, and WebAssembly for this project.

### **Smart Home IoT Project**

Distributed System and Platforms

An IoT prototype for smart home using Arduino, Raspberry Pi, and Android

2019

- Created simple Android app to control lights and other home appliances via WiFi.
- Implemented ROS nodes to communicate with hardware controllers.

#### **Mobile Telepresence Robot**

Robotics

2018

A MOBILE TELEPRESENCE ROBOT THAT CAN BE CONTROLLED REMOTELY VIA THE INTERNET USED FOR TELECONFERENCE

- Developed the robot software including the middleware and control with Robot Operating System (ROS).
- Programmed the microcontroller (STM32 Nucleo F446RE).
- Created video chat software for the robot-mounted and user-facing applications using WebRTC.
- Used Python, C++, Node.js, socket.io, and WebRTC for this project.