

# Mathematical thoughts on statistics

Daniel Miller

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## 1 General definitions

Let  $\mathbf{R}$  be the set of real numbers,  $R = R(\mathbf{R})$  the space of Radon measures on  $\mathbf{R}$ . Then  $R$  has a “positive subspace”  $R^+$  consisting of all non-negative Radon measures, and if we put  $R^- = -R^+$ , then  $R = R^+ + R^-$ . Any  $\nu \in R$  has a unique decomposition  $\nu = \nu^+ + \nu^-$ . There is a natural norm on the vector space  $R$  given by  $|\nu| = \nu^+(1) + \nu^-(1)$ .

Let  $P = R^{+, |\cdot|=1}$  be the space of probability measure on  $\mathbf{R}$ . We can also interpret  $P$  as the positive subset of  $R^{(1)=1}$ , so its tangent space is  $R^{(1)=0}$ , the space of Radon measures  $\nu$  with  $\nu(1) = 0$ .

## 2 Statistics and test statistics

**Definition 1.** A *statistic* is a function  $T: P \rightarrow \mathbf{R}$ .

In practice, we are never actually given the true probability distribution underlying data, so the best we can do is estimate it.

**Definition 2.** An *estimate* is a family  $T_\bullet = (T_n)_{n \geq 1}$ , where  $T_n: \mathbf{R}^n \rightarrow \mathbf{R}$ .

Given  $n$  points  $x_1, \dots, x_n$  drawn from  $\nu \in P$ , we estimate  $T(\nu)$  by  $T_n(x_1, \dots, x_n)$ . The distribution of the  $T_n(x_1, \dots, x_n)$  is  $T_{n*}\nu^{\times n}$ . We also call  $T_n(x_1, \dots, x_n)$  the *test statistic*.

**Definition 3.** The estimate  $T_\bullet$  is *consistent* if  $T_{n*}\nu^{\times n}$  converges to  $\delta_{T(\nu)}$  in probability for any  $\nu$ .

Write  $t$  for the identity function  $\mathbf{R} \rightarrow \mathbf{R}$ . Our first example of a statistic is the *mean*,  $E: P \rightarrow \mathbf{R}$ , given by  $E(\nu) = \nu(t)$ . Another example is the *variance*, given by  $V(\nu) = \nu((t - E(\nu))^2) = \nu(t^2) - \nu(t)^2$ .

**Definition 4.** The estimate  $T_\bullet$  is *unbiased* if  $E(T_{n*}\nu^{\times n}) = T(\nu)$  for all  $\nu \in P$  and for all  $n \geq 1$ .

Ideally, there will be some kind of theoretical “best unbiased estimate.”

We will also generally assume our estimates are *permutation invariant*, that is  $T_n(x_1, \dots, x_n) = T_n(x_{\sigma(1)}, \dots, x_{\sigma(n)})$  for all permutations  $\sigma$ .

Try  $\nu = \delta_x$ ; then  $T_{n*} \delta_x^{\times n} = \delta_{T_n(x, \dots, x)}$ . Unbiasedness tells us that at the very least,  $T_n(x, \dots, x) = T(\delta_x)$ . This is our first example of the “plug-in estimate.”

Now try  $\nu = \frac{1}{2}(\delta_{x_1} + \delta_{x_2})$ . Then

$$T_{n*} \nu^{\times n} = 2^{-n} \sum_{\sigma: [n] \rightarrow [2]} \delta_{T_n(x_{\sigma(1)}, \dots, x_{\sigma(n)})},$$

which has expected value (mean)

$$2^{-n} \sum_{\sigma: [n] \rightarrow [2]} T_n(x_{\sigma(1)}, \dots, x_{\sigma(n)}) = 2^{-n} \sum_{k=0}^n \binom{n}{k} T_n(\overbrace{x_1, \dots, x_1}^k, \overbrace{x_2, \dots, x_2}^{n-k})$$

which we want to equal  $\frac{1}{2}(x_1 + x_2)$ .

What can we say: one should have  $T_1(x) = T(\delta_x)$ .

### 3 Linear statistics

A statistic  $T$  is *linear* if it extends to a linear map  $T: R \rightarrow \mathbf{R}$ . Equivalently, whenever  $a_1, \dots, a_n \geq 0$  and  $\sum a_i = 1$  and  $\nu_i \in P$ , then  $T(\sum a_i \nu_i) = \sum a_i T(\nu_i)$ .

Any reasonable linear statistic will be of the form  $T(\nu) = \nu(f)$  for some  $f$  a function on  $\mathbf{R}$ .

Let’s see if there is a “best unbiased estimate” for linear statistics of this form.