```
Burrows-
Wheeler
Trans-
form
       \begin{array}{l} \textit{mata} \\ \textit{re-} \\ \textit{versibile} \\ \textit{pres-} \\ \textit{sione} \\ \textit{loss-} \\ \textit{less} \\ \textit{f} \\ \textit{s} \\ |T| = \\ \textit{gurrows-} \\ \textit{Wheeler} \\ \textit{Trans-} \\ \textit{form} \\ \textit{form} \\ \textit{f} \\ \textit{f} \\ \textit{T} \\ \textit{T} \\ \textit{form} \\ \textit{f} \\ \textit{

\stackrel{T}{\underset{n}{\mathbb{R}}} WT_{T}

           i
T
0 ≤
in <
           BWT_T[i] = \{\,T\;[SA_T[i] - 1]SA_T[i] \neq 1\$
   \begin{array}{c} BWT \\ \text{tazioni} \\ \text{fo-tazione} \\ \text{esima} \\ h \\ rot_T(i) \\ 0 \leq \\ i < \\ X \\ Y \\ Y \end{array}
           rot_T(i) = T[i, n-1] \cdot T[0, i-1]
   IndiceS\mathbf{A_TF_T}RotazioneB\mathbf{WT_T}
   F_T = \$BWT_T = \$
re-
versibile
BWT_T
T
LF-
terpoints
```