

view_frames Result
Recorded at time: 4412.190

map

Broadcaster: /odom_map_broadcaster_robot2
Average rate: 10.211 Hz
Most recent transform: 4412.230 (-0.040 sec old)
Buffer length: 4.309 sec

Broadcaster: /odom_map_broadcaster_robot1
Average rate: 10.218 Hz
Most recent transform: 4412.200 (-0.010 sec old)
Buffer length: 4.306 sec

robot2_tf/odom

robot1_tf/odom

Broadcaster: /gazebo
Average rate: 100.227 Hz
Most recent transform: 4412.185 (0.005 sec old)
Buffer length: 4.410 sec

Broadcaster: /gazebo
Average rate: 100.227 Hz
Most recent transform: 4412.184 (0.006 sec old)
Buffer length: 4.410 sec

robot2_tf/base_footprint

robot1_tf/base_footprint

Broadcaster: /robot2/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

robot2_tf/base_link

robot1_tf/base_link

Broadcaster: /robot2/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

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Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 25.285 Hz
Most recent transform: 4412.166 (0.024 sec old)
Buffer length: 4.390 sec

Broadcaster: /robot2/robot_state_publisher
Average rate: 25.285 Hz
Most recent transform: 4412.166 (0.024 sec old)
Buffer length: 4.390 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 25.285 Hz
Most recent transform: 4412.175 (0.015 sec old)
Buffer length: 4.390 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 25.285 Hz
Most recent transform: 4412.175 (0.015 sec old)
Buffer length: 4.390 sec

robot2_tf/laser

robot2_tf/camera_link

robot2_tf/caster_back_left_link

robot2_tf/caster_back_right_link

robot2_tf/imu_link

robot2_tf/wheel_left_link

robot2_tf/wheel_right_link

robot1_tf/laser

robot1_tf/camera_link

robot1_tf/caster_back_left_link

robot1_tf/caster_back_right_link

robot1_tf/imu_link

robot1_tf/wheel_left_link

robot1_tf/wheel_right_link

Broadcaster: /robot2/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot1/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (4412.190 sec old)
Buffer length: 0.000 sec

robot2_tf/camera_lens_link

robot1_tf/camera_lens_link