
```

% *****
% Suppose f is a function of two design variables x1 and x2 as follows:
%           f = 3*x1^3+10*x2^2-4*x1*x2-6*x1
%
% Generate a response surface with all of the linear and quadratic terms
% using the least squares method. (number of sample points = 9)
% *****

clc
clear

% We want to approximate evaluations of our problem via the form:
% f_hat = d1 + d[2:n]*z
% where d is a coefficient vector and z is in this case, the linear and
% quadratic terms of x
%
% We solve for the d coefficients though the linear system of equations:
% A*d = b
% We Initialize A and b as empty vectors/matrices of proper size
% For a two variable linear and quadratic term approximation, we will have
% 6 terms in the b vector, and a 6x6 A matrix (yielding a vector of size 6
% for d)
A=zeros(6);
b=zeros(6,1);
% k: number of sample points
k=9;
% sample points X=(x1,x2)
x1=[-1.5,-1.5,-1.5,1.25,1.25,1.25,4,4,4];
x2=[-3,0,3,-3,0,3,-3,0,3];
X=[x1;x2];

% Define the linear and quadratic terms based on sampled points (x1, x2)
% z1 = x1, z2 = x2, z3 = x1^2, z4 = x2^2, z5 = x1*x2
z1=x1;
z2=x2;
z3=x1.^2;
z4=x2.^2;
z5=x1.*x2;
z=[z1;z2;z3;z4;z5]';
% Show all Linear and Quadratic Terms
z

%Calculate A
A(1,1)=k;
A(1,2:6)=sum(z);
A(2:6,1)=sum(z)';
for i=2:6
    for j=2:6
        A(i,j)=sum(z(:,i-1).*z(:,j-1));
    end
end
%Show A matrix

```

A

```
% Calculate b
%f = @(x) 3*x(1)^3+10*x(2)^2-4*x(1)*x(2)-6*x(1);

f = @(x) 3*x(1)^2-10*x(2)^2+2*x(1)*x(2)-6*x(1)+8; % Changed to solve problem
in lab

for i=1:k
    F(i)=f(X(:,i));
end
b(1)=sum(F);
for i=1:5
    b(i+1)=sum(F'.*z(:,i));
end
% Show b coefficients
b
% solve linear equation A*d=b
d = linsolve(A,b);
% Show d coefficients
d
%Response Surface Model is an approximation for f that uses d as the
%coefficients for the linear and quadratic order terms (z vector) above.
% You could use a cubic or higher order RSM could use higher order terms as
well
% NOTE: d1 is an intercept, not a coefficients

% Compare approximation for sample points with true values
approx = d(1) +z* d(2:6)
table(F',approx)
% With a limited number of points (such as in this case), the approximation
% should very closely or exactly fit the true values. However, in general
% we are using a least squares approximation, so this is not generally:

%%% ANSWER %%%
% As seen in the table the approximated values are almost spot in if not
% exact to the actual solution as stated in the comment above.

% Try varying x1 and x2 above, and then comparing the true and approximate
% values again

% Try with test points
x1_new = 8;
x2_new = 8;
z_test = [x1_new x2_new x1_new.^2 x2_new.^2 x1_new.*x2_new];
approx_check = d(1) +z_test*d(2:6);
% Evaluate the true function at this point. Is it the same

% the true value and the approximation are the same.
x = [x1_new,x2_new];
display('Test Point Value then Approx. Value:')
f(x)
approx_check
```

$z =$

-1.5000	-3.0000	2.2500	9.0000	4.5000
-1.5000	0	2.2500	0	0
-1.5000	3.0000	2.2500	9.0000	-4.5000
1.2500	-3.0000	1.5625	9.0000	-3.7500
1.2500	0	1.5625	0	0
1.2500	3.0000	1.5625	9.0000	3.7500
4.0000	-3.0000	16.0000	9.0000	-12.0000
4.0000	0	16.0000	0	0
4.0000	3.0000	16.0000	9.0000	12.0000

$A =$

9.0000	11.2500	0	59.4375	54.0000	0
11.2500	59.4375	0	187.7344	67.5000	0
0	0	54.0000	0	0	67.5000
59.4375	187.7344	0	790.5117	356.6250	0
54.0000	67.5000	0	356.6250	486.0000	0
0	0	67.5000	0	0	356.6250

$b =$

1.0e+03 *

-0.3572
-0.3784
0.1350
-1.8456
-3.7631
0.7133

$d =$

8.0000
-6.0000
0
3.0000
-10.0000
2.0000

$approx =$

-57.2500
23.7500
-75.2500
-92.3125
5.1875
-77.3125

```
-82.0000
 32.0000
-34.0000
```

```
ans =
```

```
9x2 table
```

Var1	approx
-57.25	-57.25
23.75	23.75
-75.25	-75.25
-92.312	-92.312
5.1875	5.1875
-77.312	-77.312
-82	-82
32	32
-34	-34

```
Test Point Value then Approx. Value:
```

```
ans =
```

```
-360
```

```
approx_check =
```

```
-360.0000
```

```
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