Lax-Friedrichs

$$u_{j}^{n+1} - \frac{1}{2}(u_{j+1}^n + u_{j-1}^n) + \frac{A}{2} \frac{u_{j+1}^n - u_{j-1}^n}{ax} = 0$$

Substitute $u_j^n = e^{at}e^{ik_mx}$
 $e^{at+at}e^{ik_mx} - \frac{1}{2}(e^{at}e^{ik_m(x+ax)} + e^{at}e^{ik_m(x-ax)})$

At

 $\frac{A}{2ax}(e^{at}e^{ik_mx} - e^{at}e^{ik_m(x-ax)}) = 0$

Divide by $e^{at}e^{ik_mx}$
 $e^{ant} = \frac{1}{2}(e^{ik_max} + e^{-ik_max}) - \frac{1}{2} \frac{Aat}{ax}(e^{ik_max} - e^{-ik_max})$
 $G = \cos(k_max) - i \nu \sin(k_max)$
 $G = \cos(k_max) + (-\nu \sin(k_max))^2 \le 1$
 $\cos^2(\beta) + \nu^2 \sin^2(\beta) \le 1$
 $1 + (\nu^2 - 1) \sin^2(\beta) \le 0$
 $\nu^2 \le 1$
 $\nu \le 1$

A Dt SI

Lax - Wendroff

$$u_j^{n+1} = u_j^n - \frac{A \cdot ot}{2 \cdot ax} (u_{j+1}^n - u_{j+1}^n)$$
 $+ \frac{1}{2} \frac{(\alpha_j t)^2}{(\alpha_j x)^2} (u_{j+1}^n - 2u_j^n + u_{j+1}^n)$
 $e^{a(t+ot)} e^{it_m x} = e^{at} e^{it_m x} - \frac{1}{2} \nu \left(e^{at} e^{it_m (x+ax)} - e^{at} e^{it_m (x-ax)} \right)$
 $+ \frac{1}{2} \nu^2 e^{at} \left(e^{it_m (x+ax)} - Z e^{it_m x} + e^{it_m (x-ax)} \right)$
 $e^{aot} = 1 - \frac{1}{2} \nu \left(e^{it_m ax} - e^{-it_m ax} \right)$
 $e^{aot} = 1 - i \nu \sin \left(t_m ax \right) - \nu^2 + \nu^2 \cos \left(t_m ax \right)$
 $G = 1 - i \nu \sin \left(t_m ax \right) - \nu^2 + \nu^2 \cos \left(t_m ax \right)$
 $G = 1 - i \nu \sin \left(t_m ax \right) - \nu^2 + \nu^2 \cos \left(t_m ax \right)$
 $G = 1 - i \nu \sin \left(t_m ax \right) - \nu^2 + \nu^2 \cos \left(t_m ax \right)$
 $G = 1 - i \nu \sin \left(t_m ax \right) - \nu^2 + \nu^2 \sin^2 \beta$
 $= \left[1 - \nu^2 \left(1 - \cos \beta \right) \right]^2 + \nu^2 \sin^2 \beta$
 $= \left[1 - \nu^2 \sin^2 \left(\frac{\beta}{2} \right) \right]^2 + \nu^2 \sin^2 \beta$
 $= \left[1 + 4\nu^4 \sin^4 \left(\frac{\beta}{2} \right) - 4\nu^2 \sin^4 \left(\frac{\beta}{2} \right) + \nu^2 \sin^2 \beta$
 $= 1 + 4\nu^4 \sin^4 \left(\frac{\beta}{2} \right) - 4\nu^2 \sin^4 \left(\frac{\beta}{2} \right)$
 $= 1 - (1 - \nu^2) 4\nu^2 \sin^4 \left(\frac{\beta}{2} \right) = 1$
 $1 - \nu^2 > 0$
 $\nu^2 \leq 1$
 $\nu \leq 1$
 $\lambda \leq 1$
 $\lambda \leq 1$

Upwind Consistency

Uses Forward-Time, Backword-Space finite differences $u(x,t+at) = u(x,t) + \frac{\partial u(x,t)}{\partial t} + \frac{1}{2} \frac{\partial^2 u(x,t)}{\partial t^2} + \frac{1}{6} \frac{\partial^3 u(x,t)}{\partial t^3} + \frac{1}{6}$

 $= \frac{1}{2} \frac{d^{3}u(x,t)}{dx^{2}} dx + \frac{1}{6} \frac{d^{3}u(x,t)}{dx^{3}} (dx)^{2} + \dots + \frac{1}{6} \frac{d^{3}u(x,t)}{dx^{3$

The truncation error obviously goes to 0 as. at end ax goes to B.