

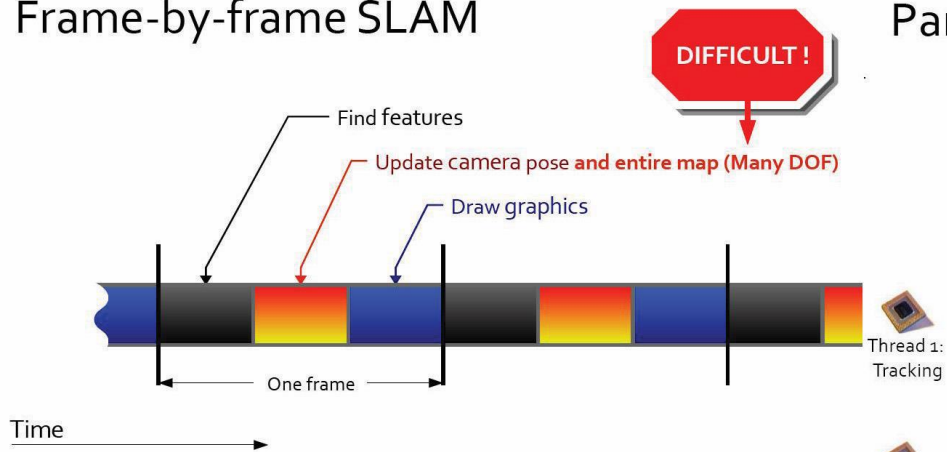
Parallel Tracking And Multiplo Mapping

Student: Daniel Palomino

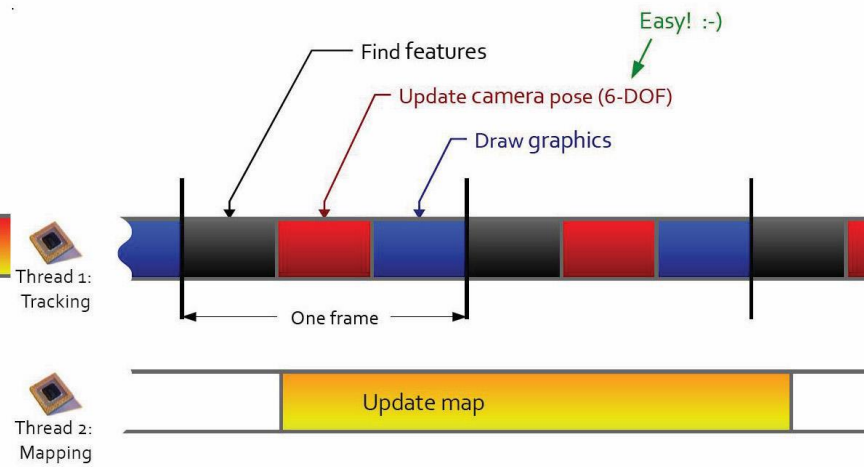


PTAMM

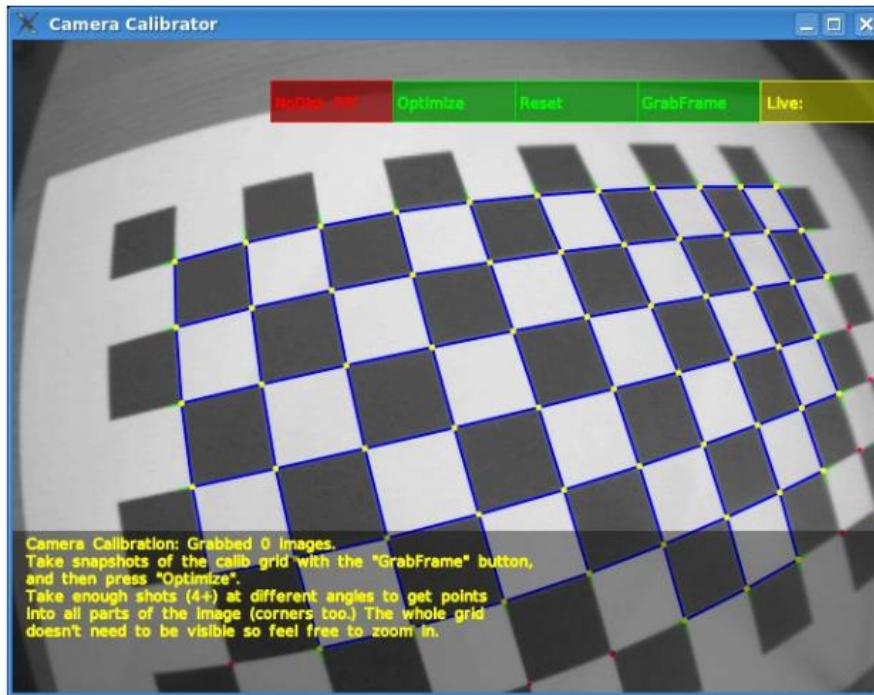
Frame-by-frame SLAM



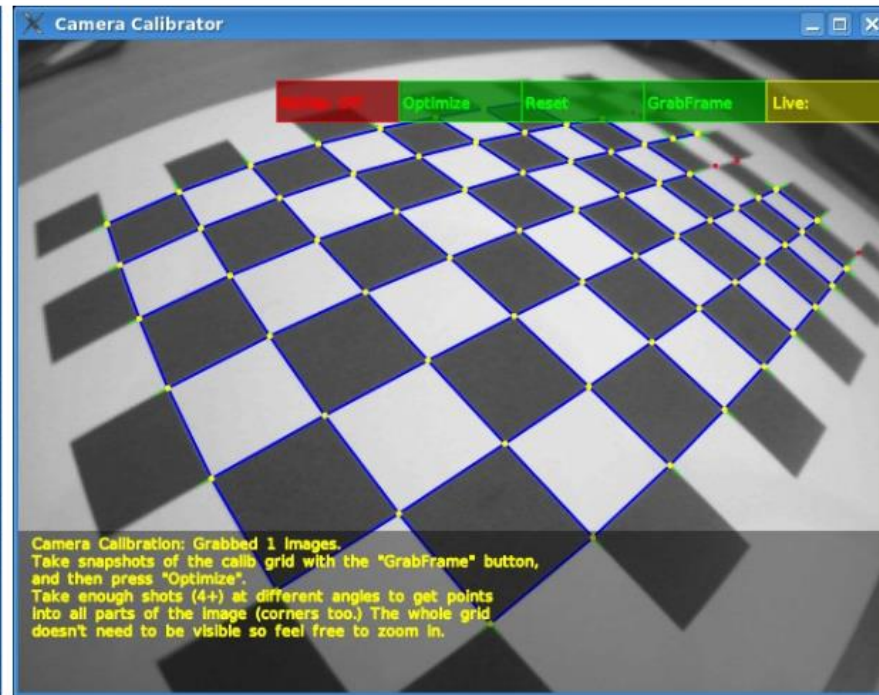
Parallel Tracking and Mapping



Calibración

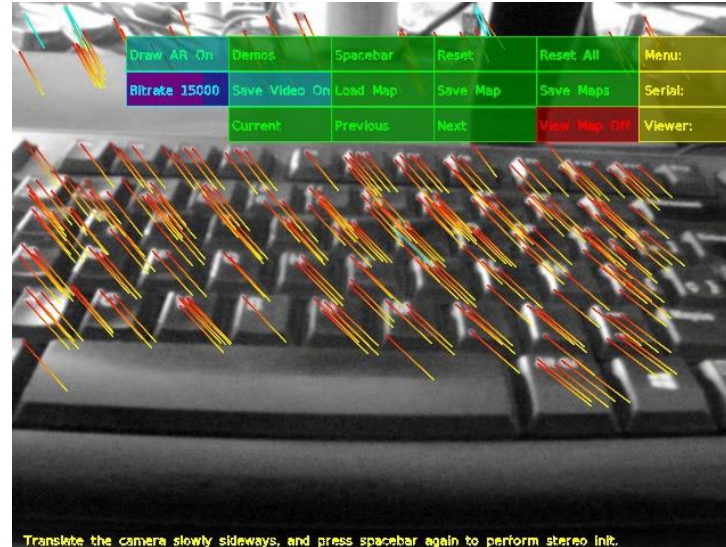


(a)

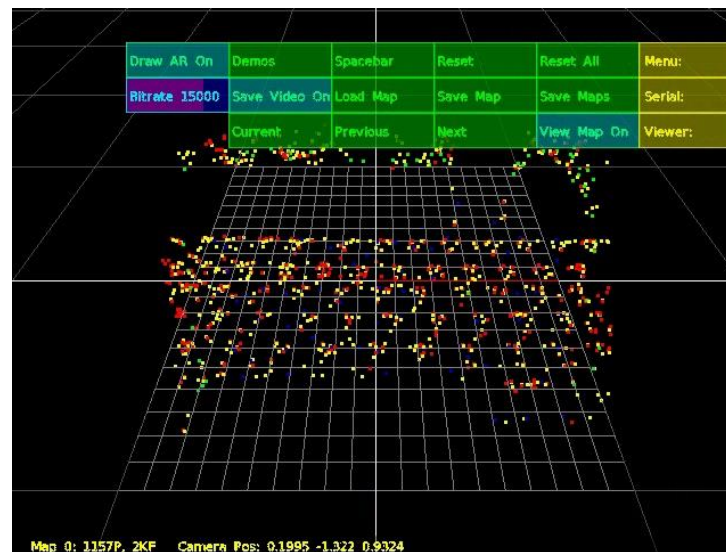


(b)

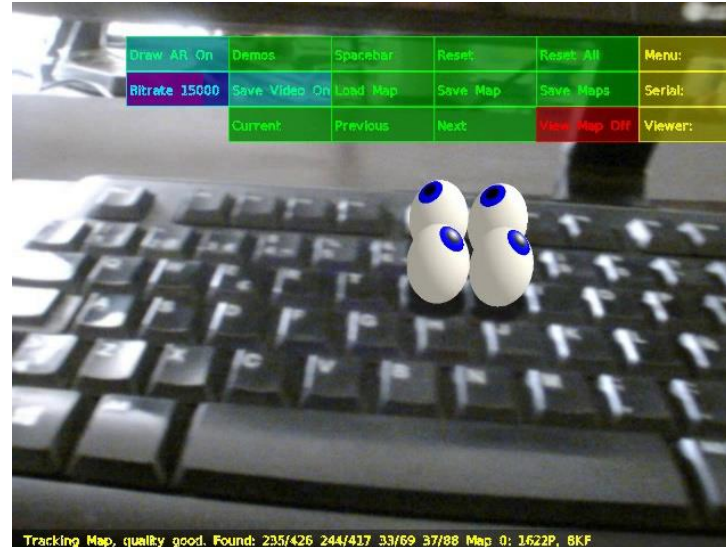
Point the
Camera at
planar scene and
press spacebar
to start for
initial map



Visualize the map created



Choose the AR model



Demo



Thanks

A thin, vertical green line is positioned to the right of the word "Thanks".