Universidad Nacional de San Agustín de Arequipa Estructuras de Datos Avanzadas

K-d tree

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Clase nodo del kd tree

```
:lass Node {
   constructor(point, axis) {
       this.point = point;
       this left = null;
       this.right = null;
       this axis = axis;
```

Construcción del kd tree

```
function build kdtree(points, depth = θ, father = null) {
   if (!points.length) return null;
   n = points.length;
   m = points[0].length;
   eje = depth % m;
   points.sort((a, b) => a[eje] - b[eje]);
   median = Math.ceil((points.length - 1) / 2);
   let izg = [];
   let der = [];
   for (let i = 0; i < median; i++) izq.push(points[i]);
   for (let i = median + 1; i < n; i++) der.push(points[i]);
   let node = new Node(points[median], eje);
    /***********************************/
   var width = 250;
   var height = 200;
   var c = color(255, 204, 0);
   stroke(r):
```

```
var c = color(255, 204, 0);
stroke(c);
if(eje == 1){
   var y = node.point[eje];
    if(node.point[father.axis] < father.point[father.axis]){
       line(0, 200-y, father.point[father.axis], 200-y);
    }else{
        line(father.point[father.axis], 200-y, width, 200-y);
}else if( eje == 0){
    var x = node.point[eje];
    if(!father){
       line(x, 0, x, height);
    }else{
        if(node.point[father.axis] < father.point[father.axis]){
           line(x, 200 - father.point[father.axis], x, height);
       }else{
            line(x, 0, x,200 - father.point[father.axis]);
node.left = build kdtree(izg, depth + 1, father);
node.right = build kdtree(der, depth + 1, father);
return node:
```

closest_point_brute_force()

```
function closest point brute force(points, point) {
   if (points.length < 1) return null;
   if (points.length == 1) return points[0];
   var min = distanceSquared(point, points[0]);
   var minPoint = points[0];
   for (let i = 1; i < points.length; i++) {
       var distance = distanceSquared(point, points[i]);
       if (distance < min) {
           min = distance;
           minPoint = points[i];
   return minPoint;
```

naive_closest_point()

```
function naive closest point(node, point, depth = 0, best = null) {
   if (!node) return best;
   if (!depth) {
       best = node.point;
   } else {
       if (distanceSquared(node.point, point) < distanceSquared(best, point)) {</pre>
           best = node.point;
   var axis = depth % node.point.length;
   if (point[axis] < node.point[axis]) {
        return naive closest point(node.left, point, depth + 1, best);
     else {
        return naive closest point(node.right, point, depth + 1, best);
```

closest_point()

```
function closest point(node, point, depth = 0, best = null) {
   if (!node) return best;
   if (!depth) {
       best = node.point;
   } else {
       if (distanceSquared(node.point, point) < distanceSquared(best, point)) {
           best = node.point;
   var axis = depth % node.point.length;
   if (point[axis] < node.point[axis]) {
       best = closest point(node.left, point, depth + 1, best);
           Math.abs(point[axis] - node.point[axis]) <
           distanceSquared(point, best)
           best = closest point(node.right, point, depth + 1, best);
   } else {
       best = closest point(node.right, point, depth + 1, best);
       if (
           Math.abs(point[axis] - node.point[axis]) <
           distanceSquared(point, best)
           best = closest point(node.left, point, depth + 1, best);
   return best;
```

KNN(k_nearest_neighbor)

```
function k nearest neighbor(node, point,arr, depth = 0, best = null) {
   if (!node) return best;
   if (!depth) {
       best = node.point;
   } else {
        if (distanceSquared(node.point, point) < distanceSquared(best, point)) {</pre>
            best = node.point;
   var axis = depth % node.point.length;
   arr.push(node.point);
   if (point[axis] < node.point[axis]) {
       best = k nearest neighbor(node.left, point,arr, depth + 1, best);
       if (
           Math.abs(point[axis] - node.point[axis]) <
           distanceSquared(point, best)
           best = k nearest neighbor(node.right, point,arr, depth + 1, best);
   } else {
       best = k nearest neighbor(node.right, point,arr, depth + 1, best);
       if (
           Math.abs(point[axis] - node.point[axis]) <
           distanceSquared(point, best)
           best = k nearest neighbor(node.left, point,arr, depth + 1, best);
   return best;
```

generate_dot()

```
function generate_dot(node) {
    string = "digraph G {\n";
    string = string + recursive_generate_dot(node);
    string = string + "}\n";
    return string;
}
```

```
function recursive generate dot(node) {
   let txt = "";
   if (node) {
       if (node.left) {
           txt = txt + '\t"';
           txt = txt + node.point;
           txt = txt + ' -> ";
           txt = txt + node.left.point;
           txt = txt + '";\n';
           txt = txt + recursive generate dot(node.left);
       if (node.right) {
           txt = txt + '\t"';
           txt = txt + node.point;
           txt = txt + ' ' ';
           txt = txt + node.right.point;
           txt = txt + '";\n';
           txt = txt + recursive generate dot(node.right);
   return txt;
function generate dot(node) {
   string = "digraph G {\n";
   string = string + recursive generate dot(node);
   string = string + "}\n";
   return string;
```

Resultados

```
var data = [
    [40, 70],
    [70, 130],
    [90, 40],
    [110, 100],
    [140, 110],
    [160, 100],
    [150, 30],
1:
var point = [140, 90];
```

```
digraph G {
    "110,100" -> "40,70";
    "40,70" -> "90,40";
    "40,70" -> "70,130";
    "110,100" -> "160,100";
    "160,100" -> "150,30";
    "160,100" -> "140,110";
}
```

Resultados



```
Queried point: 140,90

Brute force: 140,110

Naive closest point: 160,100

Closest point: 140,110

Más cercanos:

> Array [ 140, 110 ]

> Array [ 160, 100 ]

> Array [ 110, 100 ]
```

Resultados

