



# Chapter 15 : Concurrency Control

CSR IS TOO COSTLY FOR  
PRACTICAL USE - HERE, WE  
ARE GOING TO DISCUSS SOME  
ALTERNATIVES BASED ON LOCKS

Database System Concepts, 6<sup>th</sup> Ed.

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# Lock-Based Protocols

- A lock is a mechanism to control concurrent access to a data item  
*AN ENTIRE TABLE, A SET OF ITS COLUMNS, ...*
- Data items can be locked in two modes :
  1. *exclusive (X) mode*. Data item can be both read as well as written. X-lock is requested using **lock-X** instruction.
  2. *shared (S) mode*. Data item can only be read. S-lock is requested using **lock-S** instruction.
- Lock requests are made to the concurrency-control manager by the programmer. Transaction can proceed only after request is granted.



# Lock-Based Protocols (Cont.)

## ■ Lock-compatibility matrix

	S	X
S	true	false
X	false	false

- A transaction may be granted a lock on an item if the requested lock is compatible with locks already held on the item by other transactions
- Any number of transactions can hold shared locks on an item,
  - But if any transaction holds an exclusive on the item no other transaction may hold any lock on the item.
- If a lock cannot be granted, the requesting transaction is made to wait till all incompatible locks held by other transactions have been released. The lock is then granted.



# Lock-Based Protocols (Cont.)

- Example of a transaction performing locking:

```
 $T_2$ : lock-S(A);  
read (A);  
unlock(A);  
lock-S(B);  
read (B);  
unlock(B);  
display(A+B)
```

- Locking as above is not sufficient to guarantee serializability
  - if  $A$  and  $B$  get updated in-between the read of  $A$  and  $B$ , the displayed sum would be wrong.
- A **locking protocol** is a set of rules followed by all transactions while requesting and releasing locks. Locking protocols restrict the set of possible schedules.



# The Two-Phase Locking Protocol

- This protocol ensures conflict-serializable schedules.

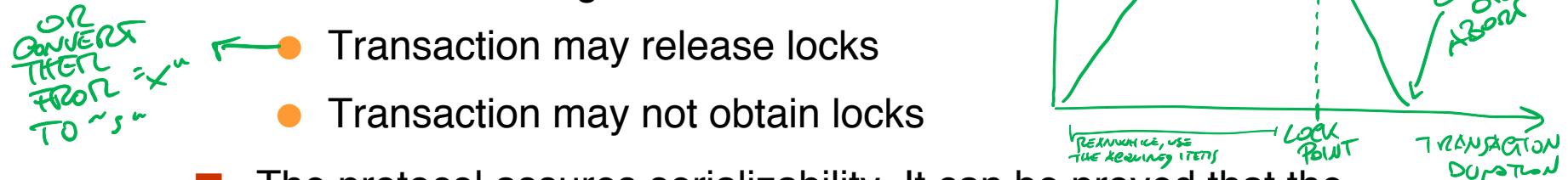
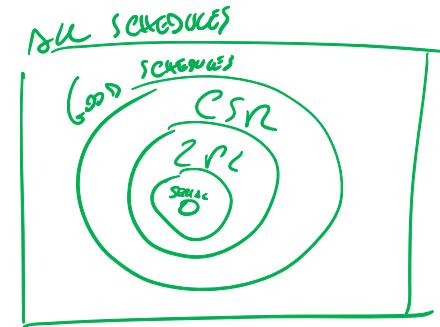
- Phase 1: Growing Phase

- Transaction may obtain locks
- Transaction may not release locks

- Phase 2: Shrinking Phase

- Transaction may release locks
- Transaction may not obtain locks

- The protocol assures serializability. It can be proved that the transactions can be serialized in the order of their **lock points** (i.e., the point where a transaction acquired its final lock).



ACTUAL SYSTEMS  
USE ZPL

→ EFFICIENCY

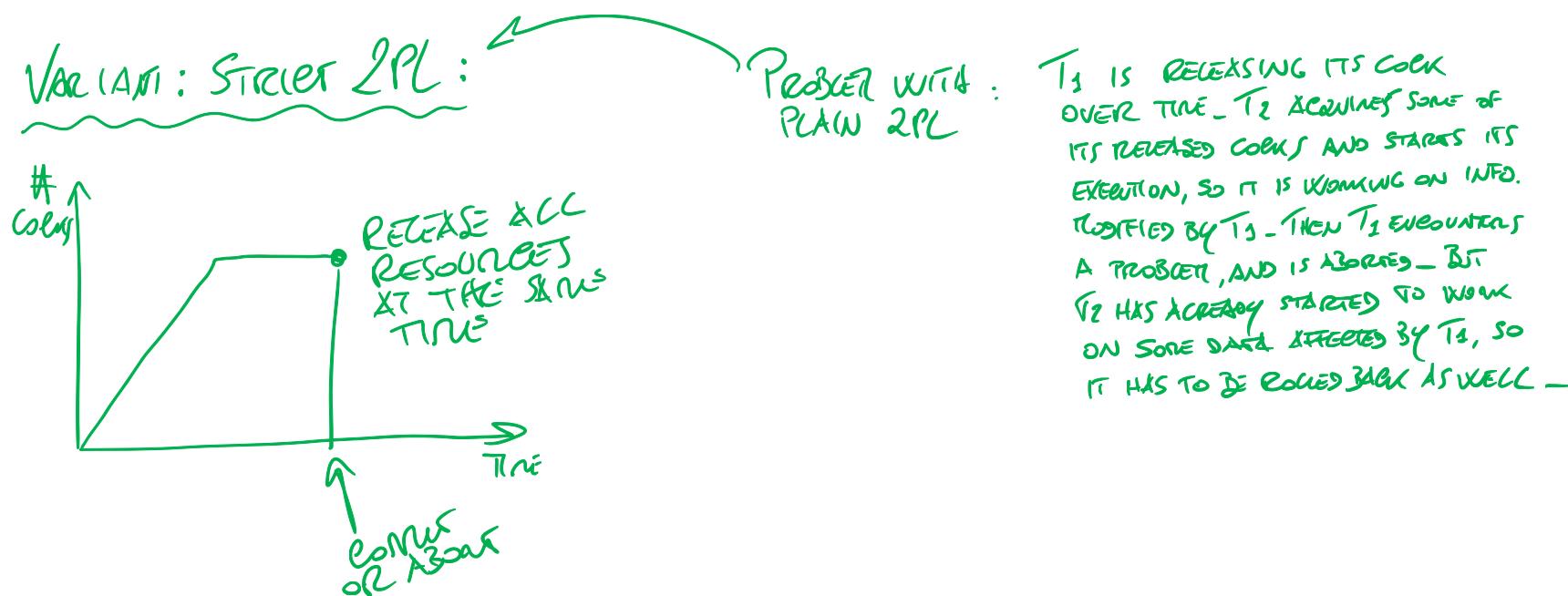
WE NEED AN "ENQUE" CRITERION TO DECIDE WHETHER TO ACCEPT AN OPERATION REQUESTED BY A TRANSACTION (ESE AND VSE WORK IN A POST-HOC WAY INSTEAD)

SO, YOU CANNOT INTERCAVE A CONVERSION AND RELEASE OF RESOURCES



# The Two-Phase Locking Protocol (Cont.)

- There can be conflict serializable schedules that cannot be obtained if two-phase locking is used.





# Lock Conversions

- Two-phase locking with lock conversions:
  - First Phase:
    - can acquire a lock-S on item
    - can acquire a lock-X on item
    - can convert a lock-S to a lock-X (upgrade)
  - Second Phase:
    - can release a lock-S
    - can release a lock-X
    - can convert a lock-X to a lock-S (downgrade)
- This protocol assures serializability. But still relies on the programmer to insert the various locking instructions.



# Automatic Acquisition of Locks

- A transaction  $T_i$  issues the standard read/write instruction, without explicit locking calls.
- The operation **read( $D$ )** is processed as:

```
if  $T_i$  has a lock on  $D$ 
  then
    read( $D$ )
  else begin
    if necessary wait until no other
      transaction has a lock-X on  $D$ 
    grant  $T_i$  a lock-S on  $D$ ;
    read( $D$ )
  end
```



# Automatic Acquisition of Locks (Cont.)

- **write( $D$ )** is processed as:

- if  $T_i$  has a **lock-X** on  $D$

- then**

- write( $D$ )**

- else begin**

- if necessary wait until no other transaction has any lock on  $D$ ,

- if  $T_i$  has a **lock-S** on  $D$

- then**

- upgrade lock on  $D$  to lock-X**

- else**

- grant  $T_i$  a **lock-X** on  $D$

Does somebody of you  
spot a problem with this  
policy of waiting/granting/releasing locks?

- write( $D$ )**

- end;**

- All locks are released after commit or abort

(If we consider strict 2-P L)



NOW CONSIDER  
THIS SITUATION

# Deadlocks

- Consider the partial schedule

$T_3$	$T_4$
lock-x ( $B$ ) read ( $B$ ) $B := B - 50$ write ( $B$ )    <i>lock-x (A)</i>	lock-s ( $A$ ) read ( $A$ ) lock-s ( $B$ )  <i>wait</i> ↘ ↗ <i>wait</i>

- Neither  $T_3$  nor  $T_4$  can make progress — executing **lock-S( $B$ )** causes  $T_4$  to wait for  $T_3$  to release its lock on  $B$ , while executing **lock-X( $A$ )** causes  $T_3$  to wait for  $T_4$  to release its lock on  $A$ .
- Such a situation is called a **deadlock**.
  - To handle a deadlock one of  $T_3$  or  $T_4$  must be rolled back and its locks released.



# Deadlocks (Cont.)

- Two-phase locking *does not* ensure freedom from deadlocks.
- In addition to deadlocks, there is a possibility of **starvation**.
- **Starvation** occurs if the concurrency control manager is badly designed. For example:
  - A transaction may be waiting for an X-lock on an item, while a sequence of other transactions request and are granted an S-lock on the same item.
  - The same transaction is repeatedly rolled back due to deadlocks.
- Concurrency control manager can be designed to prevent starvation.

↓  
**AGEING**

FOR INSTANCE, IT MIGHT  
PREFER TO GRANT  
SHARED LOCKS SINCE  
THEY ARE LESS "COSTLY"



Strategies to deal  
with deadlocks:  
- deadlock prevention  
- deadlock detection

# Deadlock Handling

- System is deadlocked if there is a set of transactions such that every transaction in the set is waiting for another transaction in the set.
- **Deadlock prevention** protocols ensure that the system will never enter into a deadlock state. Some prevention strategies :
  - Require that each transaction locks all its data items before it begins execution (predeclaration). *→ TOO RESTRICTIVE, RAY NEVER FIND ALL OF THEM AVAILABLE*
  - Impose partial ordering of all data items and require that a transaction can lock data items only in the order specified by the partial order.

THEN  
WE  
BREAK  
CYCLES

A TRANSACTION RAY  
PREFER IS DIFFERENT  
ORDER . . .



# More Deadlock Prevention Strategies

- Following schemes use transaction timestamps for the sake of deadlock prevention alone.
- **wait-die** scheme — non-preemptive
  - older transaction may wait for younger one to release data item.  
(older means smaller timestamp)  
Younger transactions never wait for older ones; they are rolled back instead.
  - a transaction may die several times before acquiring needed data item
- **wound-wait** scheme — preemptive
  - older transaction *wounds* (forces rollback ~~of~~) younger transaction instead of waiting for it. Younger transactions may wait for older ones.

IF  $T_i$  WAITS ON A RESOURCE HELD BY  $T_j$ , WHICH IS YOUNGER THAN  $T_i$ , THEN  $T_i$  KILLS  $T_j$  —

KILLING A TRANSACTION IS NOT A TRAGEDY, SINCE ALL OPERATIONS IT HAS DONE UP TO THAT POINT ARE UNDONE, AND THE ENTIRE TRANSACTION IS THEN RESTARTED —



# Deadlock prevention (Cont.)

- Both in *wait-die* and in *wound-wait* schemes, a rolled back transaction is restarted with its original timestamp. Older transactions thus have precedence over newer ones, and starvation is hence avoided.

## Timeout-Based Schemes:

- a transaction waits for a lock only for a specified amount of time. If the lock has not been granted within that time, the transaction is rolled back and restarted,
- Thus, deadlocks are not possible
- simple to implement; but starvation is possible. Also difficult to determine good value of the timeout interval.

→ *ROST USED ALONG DEADLOCK PREVENTION STRATEGIES - KIND OF SUICIDE BY THE TRANSACTION -*

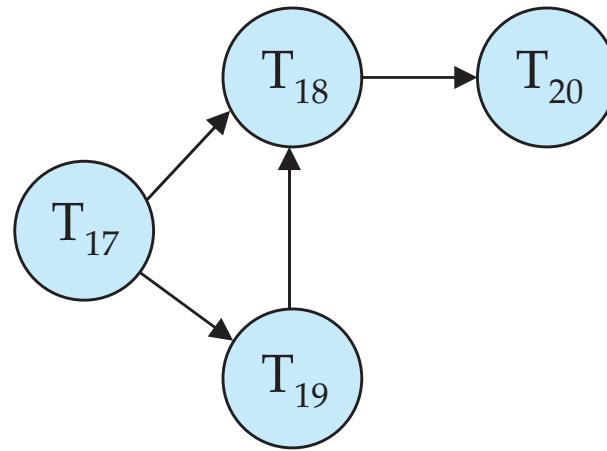


# Deadlock Detection

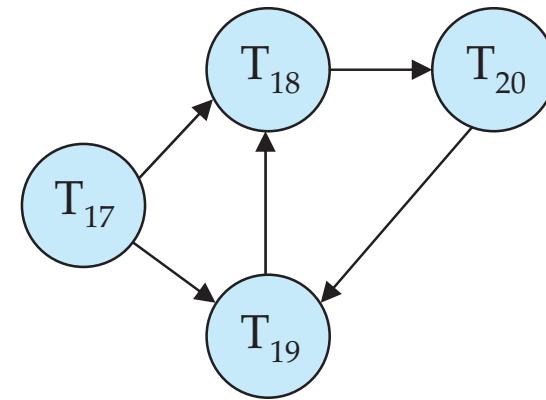
- Deadlocks can be described as a *wait-for graph*, which consists of a pair  $G = (V, E)$ ,
  - $V$  is a set of vertices (all the transactions in the system)
  - $E$  is a set of edges; each element is an ordered pair  $T_i \rightarrow T_j$ .
- If  $T_i \rightarrow T_j$  is in  $E$ , then there is a directed edge from  $T_i$  to  $T_j$ , implying that  $T_i$  is waiting for  $T_j$  to release a data item.
- When  $T_i$  requests a data item currently being held by  $T_j$ , then the edge  $T_i \rightarrow T_j$  is inserted in the wait-for graph. This edge is removed only when  $T_j$  is no longer holding a data item needed by  $T_i$ .
- The system is in a deadlock state if and only if the wait-for graph has a cycle. Must invoke a deadlock-detection algorithm periodically to look for cycles.



# Deadlock Detection (Cont.)



Wait-for graph without a cycle



Wait-for graph with a cycle

ROST USED  
SOLUTIONS

→ Thread-based deadlock prevention  
→ Deadlock detection with graphs