

SSY080

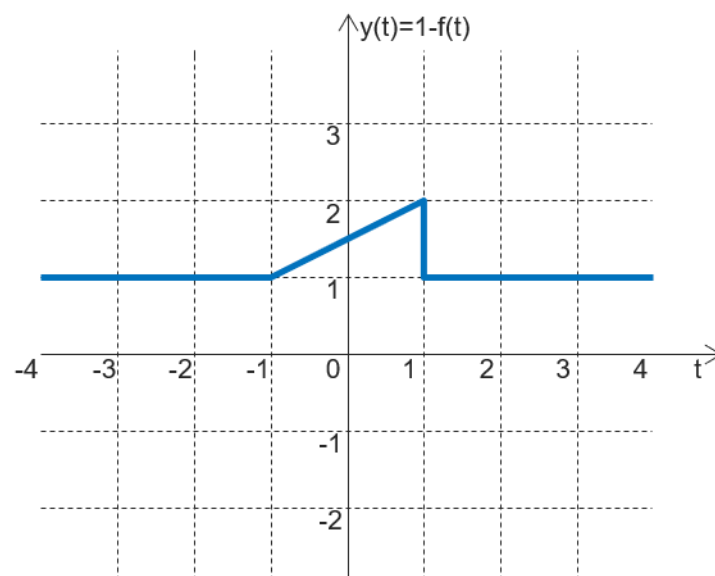
Transformer, Signaler och System

Examiner: Silvia Muceli muceli@chalmers.se

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Solution

A1.



- $f(t)$: flip about the t axis

1: DC

A2. B is the correct solution.

D cannot be correct, because the convolution of two positive sequences yields a positive output.

A, B, and C differ for the sample $x[3]$, which is obtained in case of maximal overlap between $x_1[n]$ and $x_2[n]$ ($\sum_{n=0}^3 x_1[n]x_2[n] = 6$).

A3. The system is instantaneous. Therefore $y[n]$ depends only on $x[n]$. Comparing input and output, it can be observed that

$$y[n] = \begin{cases} x[n] & \text{if } x[n] \geq 0 \\ -x[n] & \text{if } x[n] < 0 \end{cases}$$

Therefore $y[n] = |x[n]|$

The system is not invertible. For instance, given $y[5] = 3$, we cannot conclude if $x[5] = 3$ or $x[5] = -3$.

A4. $Y(\omega) = H(\omega)X(\omega)$

$\sin(t)$ contributes to $X(\omega)$ with terms proportional to δ centered at $\omega = \pm 1$ radians/seconds, and we want to filter them out

$\cos(3t)$ contributes to $X(\omega)$ with terms proportional to δ centered at $\omega = \pm 3$ radians/seconds, and we want to maintain them

Therefore, $0 < \omega_1 < 3$, and $3 < \omega_2 < \infty$

A5. The terms \cos and \sin are oscillatory and do not contribute to DC. Therefore, $c_0 = 0$.

A6.

$$f(t) = \mathcal{L}^{-1} \{ F(s) \} = \mathcal{L}^{-1} \left\{ \frac{1}{s} \right\} - \frac{3}{2} \mathcal{L}^{-1} \left\{ \frac{1}{s+2} \right\} = u(t) - \frac{3}{2} e^{-2t} u(t) = \left(1 - \frac{3}{2} e^{-2t} \right) u(t)$$

A7. Transfer function: ratio of the system output to input in the Laplace domain, assuming zero initial conditions

$$s^2 Y(s) + 10 s Y(s) + 16 Y(s) = X(s)$$

$$H(s) = \frac{Y(s)}{X(s)} = \frac{1}{s^2 + 10 s + 16}$$

A8. The system has poles in $p = \frac{-2 \pm \sqrt{4-20}}{2} = -1 \pm j2$, i.e. in the LHP. Therefore, the system is stable.

A9.

$$\sum_{n=0}^{+\infty} 0.4^n = \sum_{n=0}^{+\infty} 0.4^n z^{-n} \Big|_{z=1} = \mathcal{Z} \{ 0.4^n u[n] \} \Big|_{z=1} = \frac{z}{z-0.4} \Big|_{z=1} = \frac{1}{0.6} = \frac{10}{6} = \frac{5}{3}$$

A10.

$$f[k] = \mathcal{Z}^{-1} \{ F[z] \} = 4 \mathcal{Z}^{-1} \left\{ \frac{1}{z-3} \right\} + 5 \mathcal{Z}^{-1} \left\{ \frac{1}{z-2} \right\} = [4 (3)^{k-1} + 5 (2)^{k-1}] u[k-1]$$

B1. a. Fundamental frequency

$$\omega_1 = 2 \left[\frac{\text{r}}{\text{s}} \right], T_1 = \frac{2\pi}{\omega_1} = \frac{2\pi}{2} = \pi \text{ [s]}$$

$$\omega_2 = 4 \left[\frac{\text{r}}{\text{s}} \right], T_2 = \frac{2\pi}{\omega_2} = \frac{2\pi}{4} = \frac{\pi}{2} \text{ [s]}$$

Common period $T = m_1 T_1 = m_2 T_2$, with $m_1, m_2 \in \mathbb{Z}$

$$T = \pi \text{ [s]}, m_1 = 1, m_2 = 2$$

$$\omega_0 = \frac{2\pi}{T} = 2 \left[\frac{\text{r}}{\text{s}} \right]$$

b. Coefficients

$$\begin{aligned} x(t) &= 7 + \sin(2t) + 5 \cos\left(4t + \frac{\pi}{3}\right) = 7 + \frac{e^{j2t} - e^{-j2t}}{2j} + 5 \frac{e^{j4t} e^{\frac{j\pi}{3}} + e^{-j4t} e^{-\frac{j\pi}{3}}}{2} = \\ &= 7e^{jk\omega_0 t} \Big|_{k=0} + \frac{1}{2j} e^{jk\omega_0 t} \Big|_{k=1} - \frac{1}{2j} e^{jk\omega_0 t} \Big|_{k=-1} + \frac{5}{2} e^{\frac{j\pi}{3}} e^{jk\omega_0 t} \Big|_{k=2} + \frac{5}{2} e^{-\frac{j\pi}{3}} e^{jk\omega_0 t} \Big|_{k=-2} \end{aligned}$$

$$c_k = \begin{cases} 7 & k=0 \\ \pm \frac{1}{2j} & k = \pm 1 \\ \frac{5}{2j} e^{\pm \frac{j\pi}{3}} & k = \pm 2 \\ 0 & \text{otherwise} \end{cases}$$

$$\mathbf{B2. a.} \ y_a(t) = x_1(t) * x_2(t) = \int_{-\infty}^{+\infty} x_1(\tau) x_2(t - \tau) d\tau$$

$$t \leq 0$$

$$y_a(t) = 0$$

$$0 \leq t \leq 1$$

$$y_a(t) = \int_0^t \tau d\tau = \frac{1}{2} \tau^2 \Big|_0^t = \frac{1}{2} t^2$$

$$1 \leq t \leq 2$$

$$y_a(t) = \int_{-1+t}^1 \tau d\tau = \frac{1}{2} \tau^2 \Big|_{t-1}^1 = \frac{1}{2} - \frac{1}{2} (t-1)^2 = t - \frac{1}{2} t^2$$

$$t \geq 2$$

$$y_a(t) = 0$$

b.

$$y_b(t) = x_2(t) * x_1(t) = \int_{-\infty}^{+\infty} x_2(\tau) x_1(t - \tau) d\tau$$

$$t \leq 0$$

$$y_b(t) = 0$$

$$0 \leq t \leq 1$$

$$y_b(t) = \int_0^t (t - \tau) d\tau = t \tau \Big|_0^t - \frac{1}{2} \tau^2 \Big|_0^t = t^2 - \frac{1}{2} t^2 = \frac{1}{2} t^2$$

$$1 \leq t \leq 2$$

$$y_b(t) = \int_{-1+t}^1 (t - \tau) d\tau = t \tau \Big|_{t-1}^1 - \frac{1}{2} \tau^2 \Big|_{t-1}^1 = t(1 - t + 1) - \frac{1}{2} + \frac{1}{2} (t-1)^2 = t - \frac{1}{2} t^2$$

$$t \geq 2$$

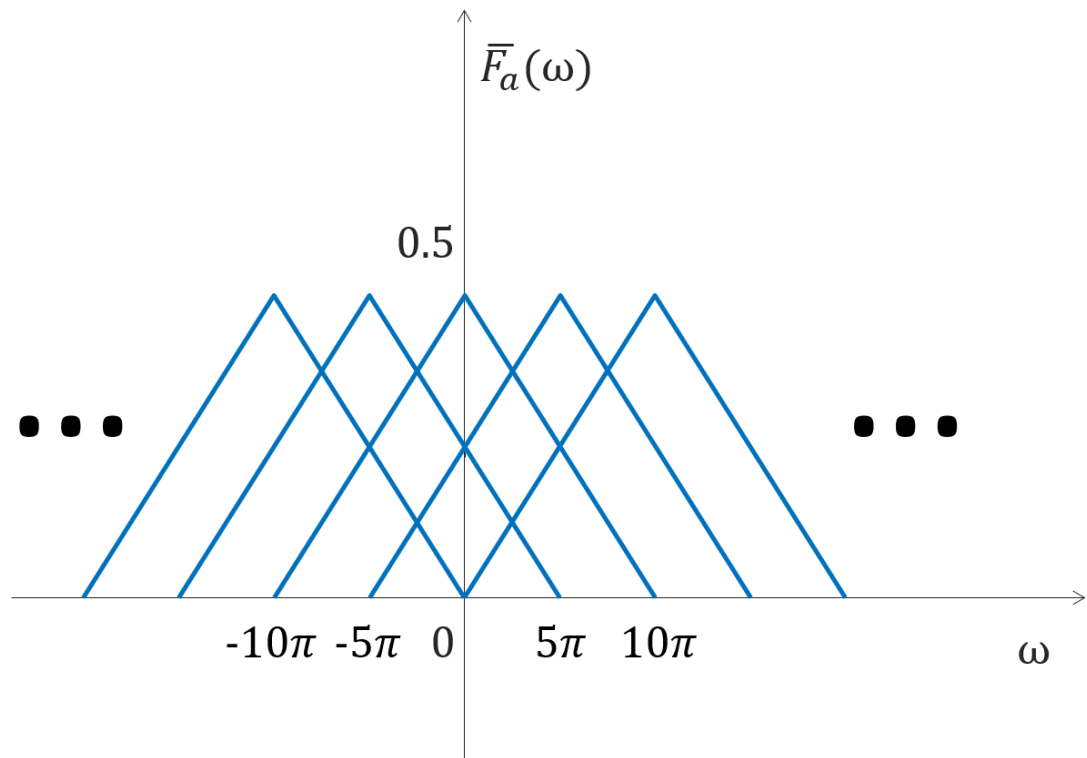
$$y_b(t) = 0$$

$$y_a(t) = y_b(t), \text{ as expected since the convolution is commutative}$$

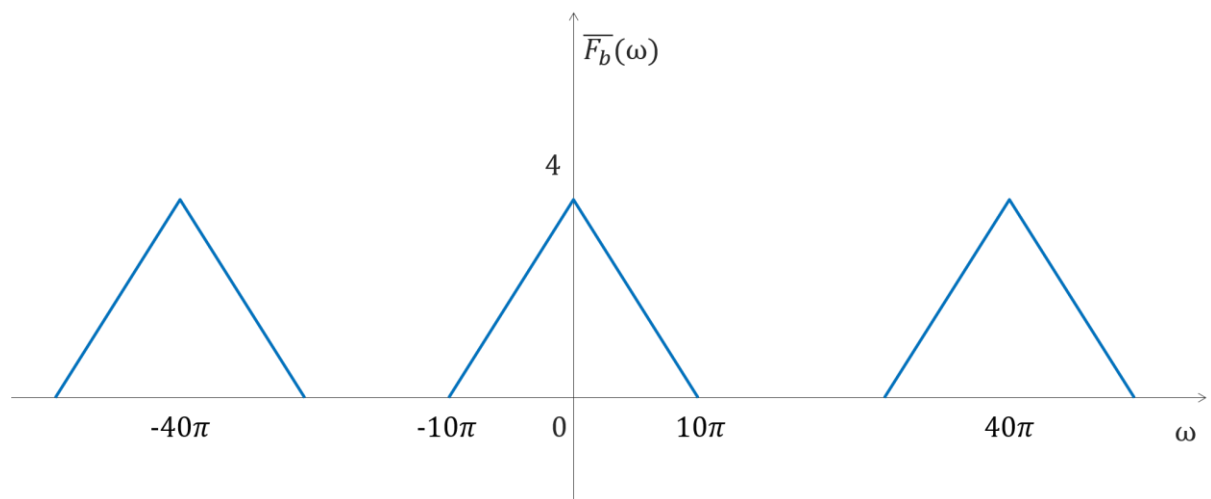
B3.

$$\bar{F}(\omega) = \frac{1}{T} \sum_{n=-\infty}^{+\infty} F(\omega - n \omega_s)$$

a. $\omega_{sA} = \frac{2\pi}{T_A} = \frac{2\pi}{0.4} = 5\pi \quad \left[\frac{\text{radian}}{\text{second}}\right]$



b. $\omega_{sB} = \frac{2\pi}{T_B} = \frac{2\pi}{0.05} = 40\pi \quad \left[\frac{\text{radian}}{\text{second}}\right]$



Note: this figure is not in scale.

Case a: aliasing

Case b: sampling higher than Nyquist rate, we can recover the original signal (even using a practical filter).