Lipschitz-Certifiable Training with a Tight Outer Bound

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Background and Motivation

- Deep neural networks are vulnerable to small but adversarially designed perturbations in the input which can mislead a network to predict wrong label.
- There are two different defense approaches:
 - Heuristic Defense: be designed to defend against specific predefined adversarial attacks → can be defeated by unseen stronger adaptive adversaries [Tra+20].
 - Certified Defense: minimize an upper bound on the worst-case logit over all possible perturbations within a given noise level [TSS18, Won+18, Gow+18].
- We build a robust model through certifiable training method.

Problem

 Certified Defenses minimize the following upper bound on the worst-case loss:

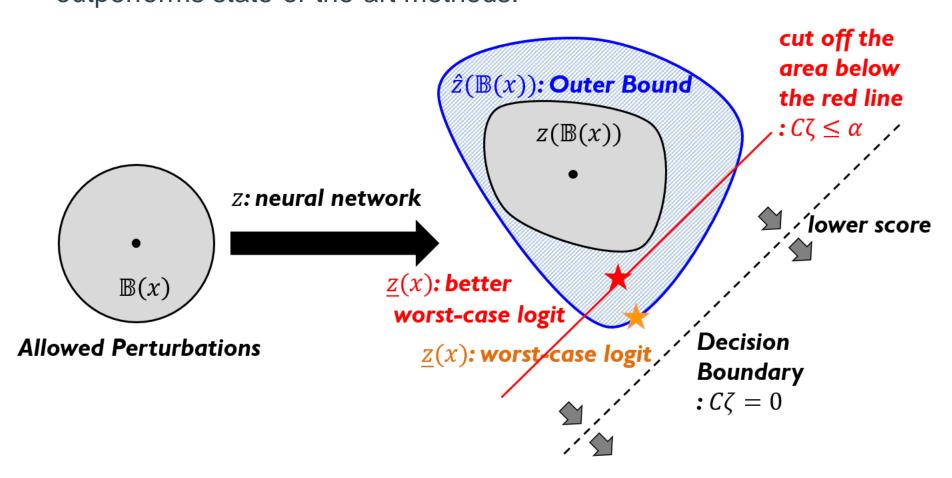
$$\max_{\mathbf{x}' \in \mathbb{B}(\mathbf{x})} \mathcal{L}(z(\mathbf{x}'), y) \le \mathcal{L}(\underline{z}(\mathbf{x}), y)$$

with a worst-case logit $\underline{z}(x) = \arg\min_{\zeta \in \hat{z}(\mathbb{B})} C\zeta$ where $C = 1e^{(y)T} - I$ over an outer bound $\hat{z}(\mathbb{B})$ in the logit space.

- Certified Defenses with worst-case logit consists of two stages:
 - Propagate the input perturbation through the network and obtain an outer bound of the image → the tightness of the outer bound
 - Solve an optimization problem to compute the worst-cae logit over the outer bound → the efficient computation
- We need an efficient certifiable training method with the tight outer bound.

Main Contribution

- **Efficiency**: We propose a fast certified defense method called Box Constraint Propagation (BCP).
- **Tightness**: By introducing an additional box constraint, we can obtain a tighter upper bound to be minimized.
- Expressiveness/Robustness: We can build a certifiably robust model outperforms state-of-the-art methods.



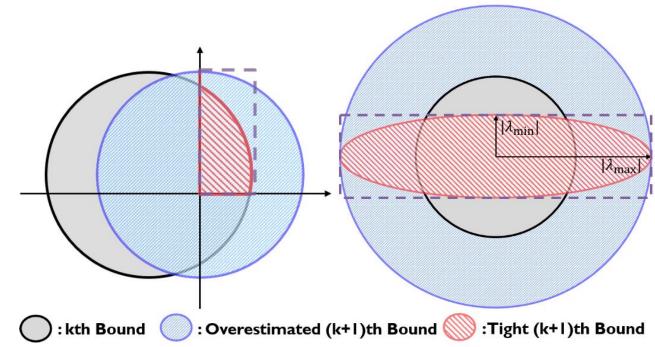
Proposed Method

Intuition Behind the Design

• LMT [TSS18]: Lipchitz outer bound is simple and efficient but **overestimates** the true image of the allowed perturbations:

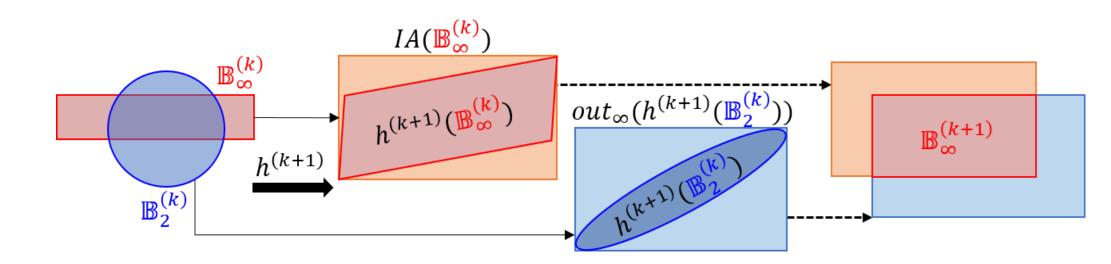
$$\hat{z}(\mathbb{B}(x)) = \mathbb{B}_2(z(x), \epsilon L)$$
 with the Lipschitz constant L .

- ▶ Our proposed method aims to obtain a tighter outer bound.
- Our proposed method is effective in both nonlinear (ReLU) and linear operations.
 k-th Bound → (k+1)-th Bound (Tight bound ⊂ Overestimated bound)
 - ► Consider **element-wise bound (=Box Constraint)** propagation
 - Nonlinear operation (ReLU): $L_i = 1 \ge \frac{u^+}{u^+ l^-}$
 - Linear operation: $L_i = |\lambda_{max}(\mathbf{W}^{(i)})|$ (spectral norm)



Box Constraint Propagation (BCP)

- We introduce additional "Box Constraints" to further tighten the outer bound:
 - ① Circumscribing box of the propagated ℓ_2 ball $h^{(k+1)}\left(\mathbb{B}_2^{(k)}\right)$: $out_{\infty}(h^{(k+1)}\left(\mathbb{B}_2^{(k)}\right))$
 - \circ ② Circumscribing box of the propagated ℓ_{∞} box $h^{(k+1)}\left(\mathbb{B}_{\infty}^{(k)}\right)$: $IA\left(\mathbb{B}_{\infty}^{(k)}\right)$
 - ► The (k+1)th box outer bound: $\mathbb{B}_{\infty}^{(k+1)} = \mathbb{Q} \cap \mathbb{Q} = out_{\infty}(h^{(k+1)}(\mathbb{B}_{2}^{(k)})) \cap IA(\mathbb{B}_{\infty}^{(k)})$



- Our certifiable training algorithm minimizes the following objective:
 - Training objective: $\mathcal{J}(f,\mathcal{D}) = \mathbb{E}_{(x,y)\sim\mathcal{D}}[\mathcal{L}(\underline{z}(x),y)]$
 - o The worst-case logit: $\min_{\zeta'} c^T \zeta'$ s.t. $\|\zeta' \mathbf{z}^{(K-1)}\|_2 \le \rho^{(K-1)}$,

$$|\zeta'-m^{(K-1)}|\leq r^{K-1}.$$

- To compute the worst-case logit, we propose an efficient algorithm (**Algorithm 1**) that terminates in finite iterations.
- Theorem (Efficient Computation) The while loop in Algorithm 1 finds the optimal solution ζ^* of the optimization problem $\min_{\zeta \in \mathbb{B}_2 \cap \mathbb{B}_\infty} c^T \zeta$ in a finite number of iterative steps less than the number of elements in c.

Algorithm 1 Box Constraint Propagation (BCP) Certifiable Training

Input: training data $(x, y) \sim \mathcal{D}$, target perturbation size ϵ_{target} , network parameterized by θ **Output:** Robust network f_{θ} **repeat**

Read mini-batch B from $\mathcal D$ and adjust ϵ and λ according to the schedule.

// Compute the box outer bound and the ball outer bound //
$$\mathbb{B}_{\infty}^{(K-1)} = \operatorname{midrad}(\boldsymbol{m}^{(K-1)}, \boldsymbol{r}^{(K-1)}) \text{ where } \boldsymbol{m}^{(K-1)}, \boldsymbol{r}^{(K-1)} = \operatorname{BCP}(\boldsymbol{x}, \epsilon; \theta) \text{ ((6)-(8))}.$$

$$\mathbb{B}_{2}^{(K-1)} = \mathbb{B}_{2}(\mathbf{z}^{(K-1)}, \rho^{(K-1)}) \text{ where } \mathbf{z}^{(K-1)} = h^{(K-1)} \circ \cdots \circ h^{(1)}(\boldsymbol{x}) \text{ and } \rho^{(K-1)} = \epsilon \prod_{i=1}^{K-1} L^{(i)}$$
 // Solve the optimization in (11) for each $m \neq y$ in parallel //

Initialize
$$p = \mathbf{z}^{(K-1)} - \rho^{(K-1)} \frac{\mathbf{c}}{\|\mathbf{c}\|}$$
.
while not $|p - m^{(K-1)}| \le r^{(K-1)}$ do

Decompose \boldsymbol{p} into two parts: $\boldsymbol{p} = \boldsymbol{p}[I] + \boldsymbol{p}[I^c]$, where $I \equiv \{l : |p_l - m_l^{(K-1)}| \ge r_l^{(K-1)}\}$. First phase Project $\boldsymbol{p}[I]$ onto $\mathbb{B}_{\infty}^{(K-1)}$.

Second phase With the scaling parameter η in (12), update $\boldsymbol{p} \leftarrow \prod_{\mathbb{B}_{\infty}^{(K-1)}} \boldsymbol{p}[I] + \eta \boldsymbol{p}[I^c]$.

Calculate the worst-translated logit $\underline{z}(x) = z(x) + t(x)$ with (2) and (10):

 $t_m(\boldsymbol{x}) = \mathbf{c}^T (\mathbf{z}^{(K-1)} - \boldsymbol{p}).$

// Update Parameters //
Update the parameter θ with the objective (13):

 $\theta \leftarrow \theta - \alpha \nabla_{\theta} \mathcal{J}(f_{\theta}, B; \lambda).$

until training phase ends

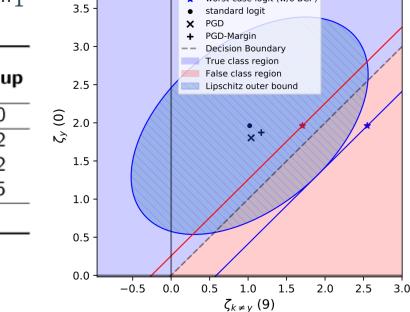
Experiments

Efficnecy & Tightness

- Our proposed method is over 12 times faster than CAP [Won+18].
- The additional box constraint makes 'wost-case translations' **25-55%**Logit space tighter in terms of translation $\propto \|\underline{z}(x) z(x)\|_1$.

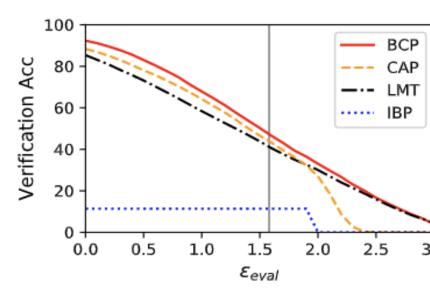
 * worst-case logit (BC worst-case logit (W/C worst-case

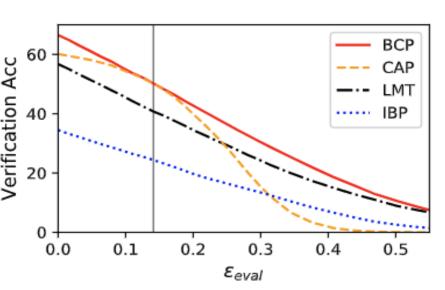
Computation time (sec/epoch) Speed up Structure ×12.0 MNIS⁻ 57.5 ×12.2 53.0 645 56.5 CIFAR-10 $\times 24.2$ 1,369 $\times 12.5$ 1,121 (2 GPUs) 89.5 3,268 Tiny ImageNet



Expressiveness/Robustness

Our proposed method outperforms state-of-the-art methods (CAP [Won+18], LMT [TSS18], IBP [Gow+18]).





(a) MNIST

(b) CIFAR-10 (36/255)

References

[Gow+18] S. Gowal, K. et al. (2018). "On the effectiveness of interval bound propagation for training verifiably robust models." In: arXivpreprint arXiv:1810.12715

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[Won+18] Eric Wong et al. (2018). "Scaling provable adversarial defenses". In: Advances in Neural Information Processing Systems 31. pp. 8400–8409

