

Music 320  
Autumn 2011–2012  
**Homework #9**  
Filters & Turkey Analysis  
135 points  
Due next FRIDAY (12/09/2011) by 11:59pm - no late submissions!

## Theory Problems

1. (15 pts) [Symmetric Filter Chain]

Given a filter of the form  $y(n) = x(n) + 2x(n-1) + 3x(n-2) + 2x(n-3) + x(n-4)$

- (a) (5 pts) Find an expression for the group delay
- (b) (5 pts) Find an expression for the phase delay
- (c) (5 pts) Find an expression for the phase and group delay for a chain of  $N$  of these filters

2. (25 pts) [Butterworth filter]

A continuous time second-order high-pass Butterworth filter with normalized cutoff frequency  $\omega_c = 0.5$  has the following frequency response in the  $S$ -domain:

$$H(s) = \frac{s^2}{s^2 + \frac{1}{\sqrt{2}}s + \frac{1}{4}}$$

- (a) (10 pts) Sketch the bode plots of the filter (magnitude and phase). Use a log scale for the frequency axis, dB for the magnitude axis and degree for the phase axis.
- (b) (10 pts) One common method for discretizing a continuous-time filter is by using the Bilinear Transform  $s = \frac{2}{T} \frac{1-z^{-1}}{1+z^{-1}}$

Find the discrete-time frequency response  $H(z)$  of the filter  $H(s)$  and its corresponding difference equation, assuming  $T = 1$

- (c) (5 pts) Plot the poles and zeros of the filter in the  $Z$ -plane

3. (45 points) [Thanksgiving Turkey] You wake up on Thanksgiving, put your turkey into a 350 degree oven ( $T_{oven} = 350$ ), go back to sleep, wake up again, and...oh no! You forgot to write down what time you put the Turkey in the oven! You must figure out when ( $t_{cooked}$ ) the turkey will reach the desired temperature  $T_{cooked} = 160$ . To do so, you measure the temperature  $T_1 = 100$  at  $t_1 = 0$  and  $T_2 = 110$  at  $t_2 = 30$  where  $T$  is in degrees fahrenheit and  $t$  is in minutes.

Using these measurements can now solve for  $t_{cooked}$  by approximating the system as a leaky integrator (one-pole) filter  $y[n] = (1 - \lambda)x[n] + \lambda y[n-1]$ . The input  $x[n]$  is the

oven temperature over time (assumed constant), while the output  $y[n]$  is the turkey temperature over time.

Using this information, solve for the following:

- (a) (5 points) Draw the signal flow diagram of the turkey/oven system.
- (b) (5 points) Write the transfer function of the turkey/oven system.
- (c) (5 points) Plot the poles and zeros of the turkey/oven system.
- (d) (15 points) Write the turkey temperature trajectory (step response with the input at 350 instead of 1).
- (e) (5 points) Solve for the forgetting factor  $\lambda$
- (f) (5 points) Solve for the turkey time constant  $\tau$ .
- (g) (5 points) Solve for the time  $t_{cooked}$  when the turkey will reach  $T_{cooked}$ .

## Lab Assignments

Follow the same file naming convention of the previous lab.

1. (30 pts) The purpose of this problem is to introduce you to a couple of useful Matlab commands for filter design.
  - (a) (10 pts) (5 points) Use `butter` to design a digital second order low-pass filter that cuts off at  $f_s/3$ . Design a filter with the same cutoff frequency using `cheby1`. Turn in the coefficients for both filters.
  - (b) (10 pts) Use `freqz` to display the amplitude and phase response of both filters designed in part 1a (plot at least 2048 points). Plot both filters in the same figure using `hold` and comment briefly on the spectral differences between the filters.
  - (c) (5 pts) Repeat parts 1a and 1b for a high-pass filter with cutoff frequency of  $f_s/6$ .
  - (d) (5 pts) Repeat parts 1a and 1b for a band-pass filter with a low cutoff frequency of  $f_s/6$  and high cutoff frequency of  $f_s/3$ .

Turn in your Matlab code

2. (20 pts) [Allpass Filter Group Delay]

Form the allpass filters  $\mathbf{b} = [\rho \ 1]$ ;  $\mathbf{a} = [1 \ \rho]$ ; for different values of  $\rho = [-0.5, 0, 0.5]$ ; . For each filter, compute the group delay by using `diff()` on `angle()` of the transfer function formed by `freqz(b, a, 0:1/(nbins-1):pi)` (you probably don't have to do `unwrap()`, but verify if you need to). Compare that group delay to the output of `grpdelay()`. Plot the poles and zeros of the system using `zplane()` (note the different way `zplane()` treats row and column vectors).

Turn in your Matlab code.