

Zero-Jitter Task Chains via Algebraic Rings

Enrico Bini, Paolo Pazzaglia, Martina Maggio

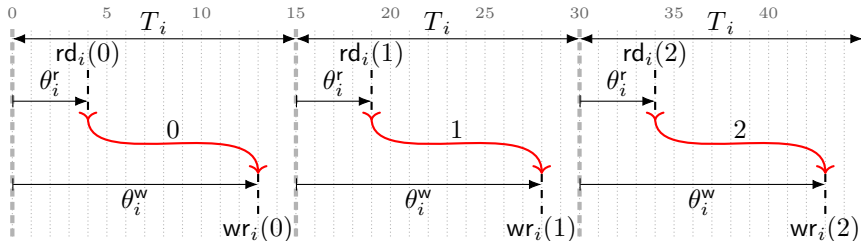
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Model of a LET task τ_i



- A LET task τ_i is composed by *periodic jobs* (curvy arrows)
 - in LET, we only care of the read and write instants

$$\theta_i^r$$

read phasing of τ_i , relative to the *period* T_i

$$\theta_i^w$$

write phasing of τ_i , relative to the *period* T_i

$$rd_i(j) = j T_i + \theta_i^r$$

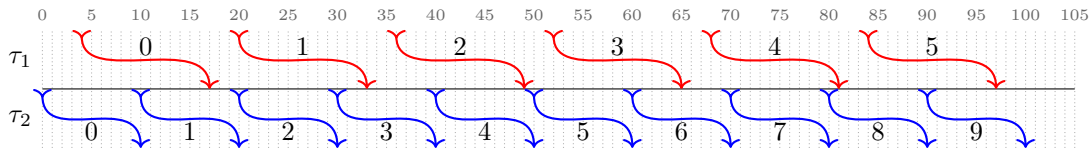
read instant of job j of τ_i

$$wr_i(j) = j T_i + \theta_i^w$$

write instant of job j of τ_i



Chain of 2 LET tasks

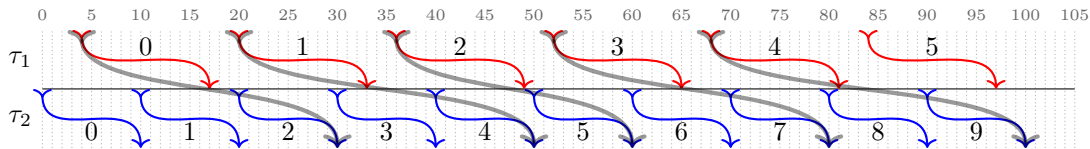


- Chain of LET tasks

- each task reads data written by the previous one
- data is on **shared memory**
 - ★ τ_1 may over-write data before τ_2 reads (if $T_1 < T_2$)
 - ★ τ_2 may read again the same data (if $T_2 < T_1$)



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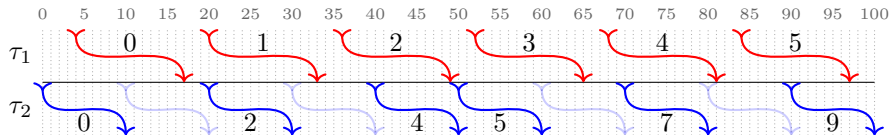
(j_1, j_2)	$rd_1(j_1)$	$wr_2(j_2)$	$wr_2(j_2) - rd_1(j_1)$
(0, 2)	4	30	26
(1, 4)	20	50	30
(2, 5)	36	60	24
(3, 7)	52	80	28
(4, 9)	68	100	32
...

- Chains of jobs have **variable** read-to-write delay



Variability of the input-output delay

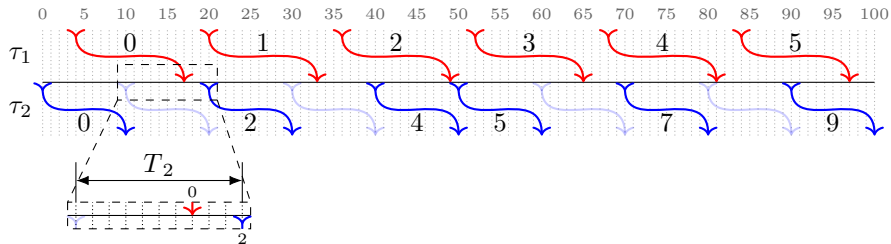
- The source of variability is $rd_2(j_2) - wr_1(j_1)$. In the example: 3, 7, 1, 5, 9, 3, 7, ...





Variability of the input-output delay

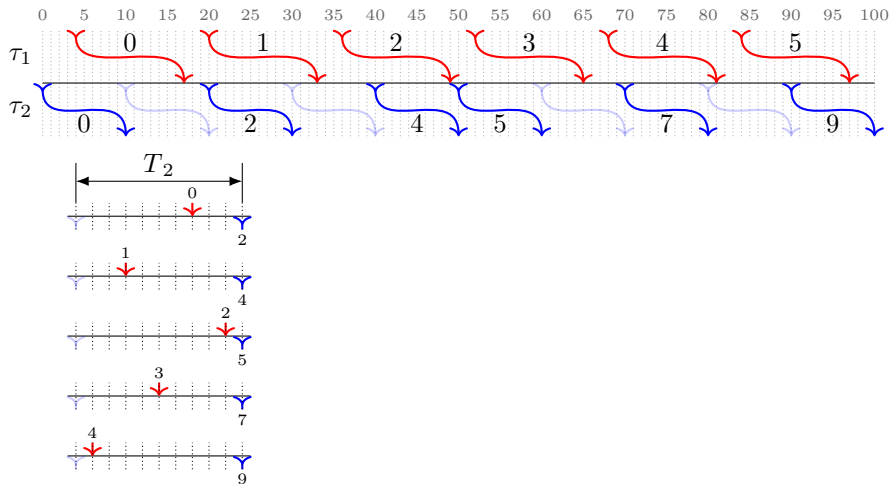
- $rd_2(j_2) - wr_1(j_1) < T_2$, always. Let's zoom in ...





Variability of the input-output delay

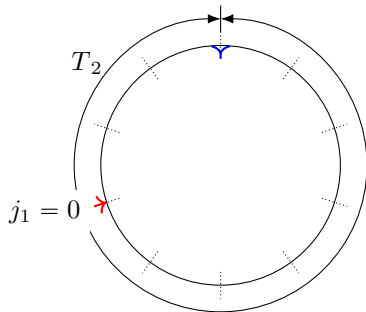
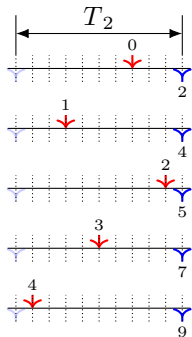
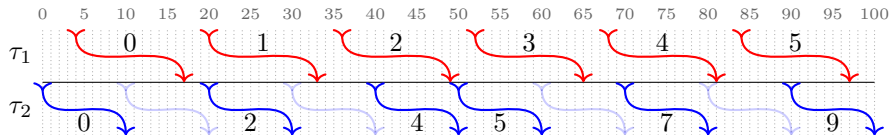
- ... and align the read instants of consecutive τ_2 jobs.





Variability of the input-output delay

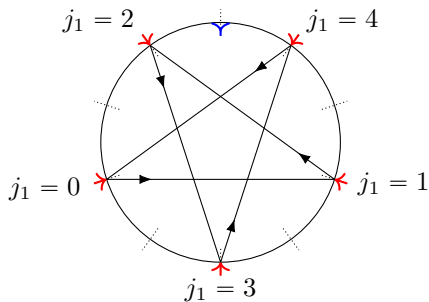
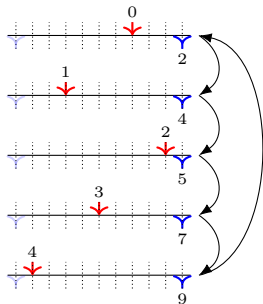
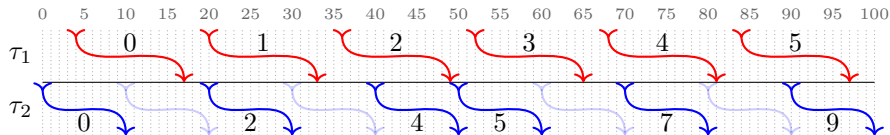
- A repetitive sequence...mmhhh... better to visualize over the (algebraic) ring $\mathbb{Z}/T_2\mathbb{Z}$.





Variability of the input-output delay

- By inverting over the ring $\mathbb{Z}/T_2\mathbb{Z}$, max/min delay is found **without** unrolling the schedule.





Variability of the input-output delay

- Exploited to **eliminate the jitter** of a 2-tasks chain.

