

Zero-Jitter Task Chains via Algebraic Rings

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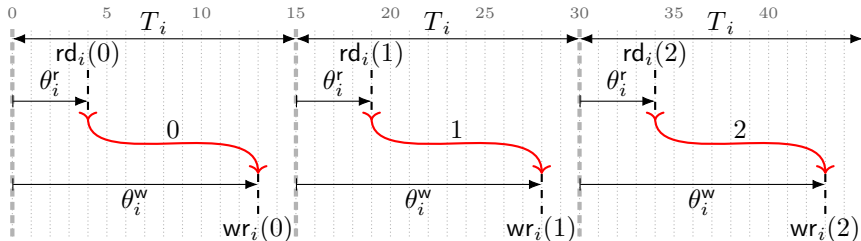
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Model of a LET task τ_i



- A LET task τ_i is composed by *periodic jobs* (curvy arrows)
 - in LET, we only care of the read and write instants

θ_i^r read phasing of τ_i , relative to the period T_i (aka the offset)

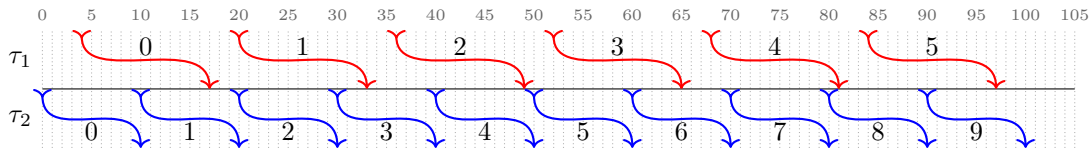
θ_i^w write phasing of τ_i , rel. to period T_i ($\theta_i^w - \theta_i^r$ is aka the deadline)

$rd_i(j) = j T_i + \theta_i^r$ read instant of job j of τ_i

$wr_i(j) = j T_i + \theta_i^w$ write instant of job j of τ_i



Chain of 2 LET tasks

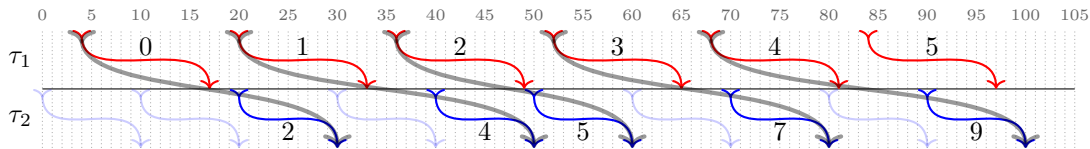


- Chain of LET tasks

- each task reads data written by the previous one
- data is on **shared memory**
 - ★ τ_1 may over-write data before τ_2 reads (if $T_1 < T_2$)
 - ★ τ_2 may read again the same data (if $T_2 < T_1$)



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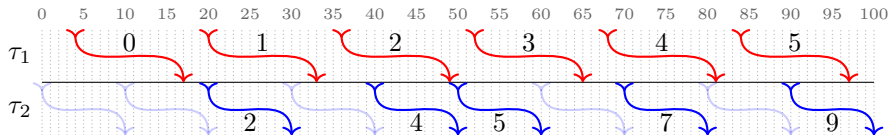
(j_1, j_2)	$rd_1(j_1)$	$wr_2(j_2)$	$wr_2(j_2) - rd_1(j_1)$
(0, 2)	4	30	$26 = 13 + \mathbf{3} + 10$
(1, 4)	20	50	$30 = 13 + \mathbf{7} + 10$
(2, 5)	36	60	$24 = 13 + \mathbf{1} + 10$
(3, 7)	52	80	$28 = 13 + \mathbf{5} + 10$
(4, 9)	68	100	$32 = 13 + \mathbf{9} + 10$
...

- Chains of jobs have **variable** read-to-write delay



Variability of the input-output delay

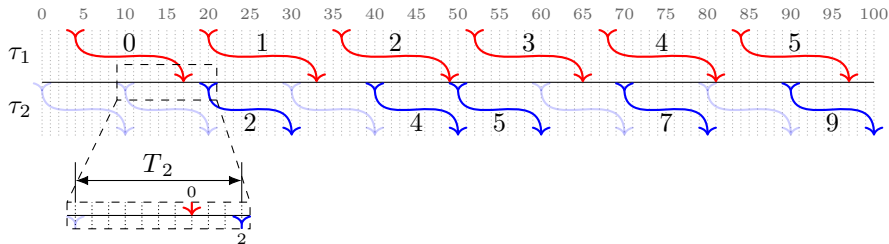
- The source of variability is $rd_2(j_2) - wr_1(j_1)$. In the example: 3, 7, 1, 5, 9, 3, 7, ...





Variability of the input-output delay

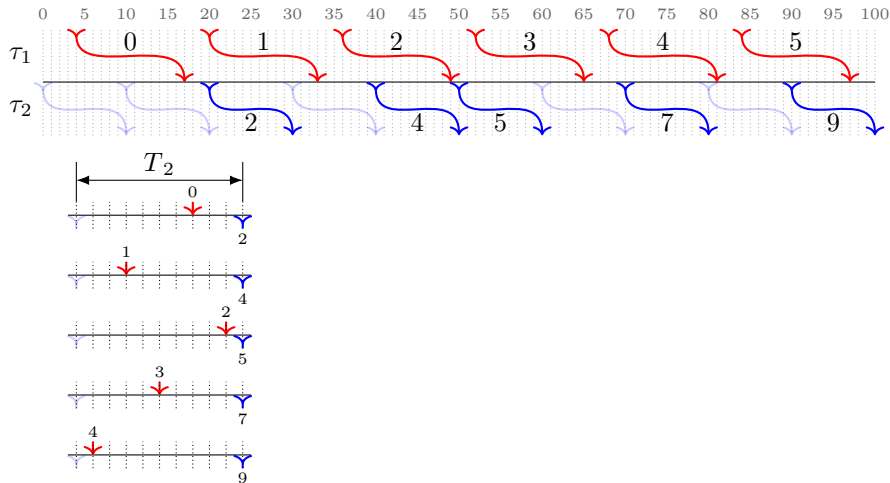
- $rd_2(j_2) - wr_1(j_1) < T_2$, always. Let's zoom in ...





Variability of the input-output delay

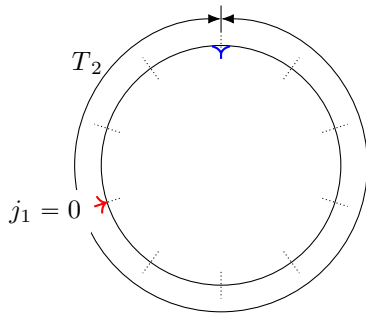
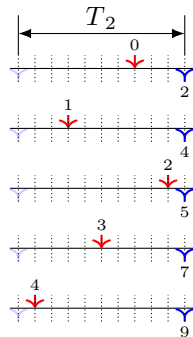
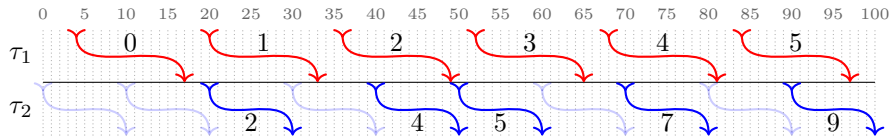
- ... and align the read instants of consecutive τ_2 jobs.





Variability of the input-output delay

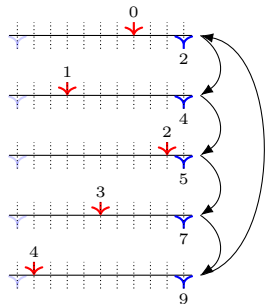
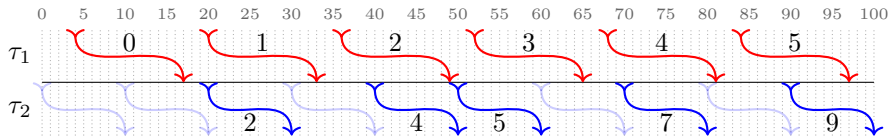
- A repetitive sequence...mmhhh... let's move over the (algebraic) ring $\mathbb{Z}/T_2\mathbb{Z}$.



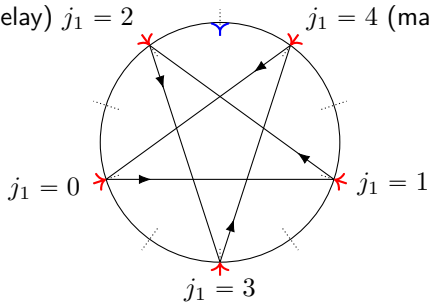


Variability of the input-output delay

- By inverting over the ring $\mathbb{Z}/T_2\mathbb{Z}$, max/min delay is found **without** unrolling the schedule.



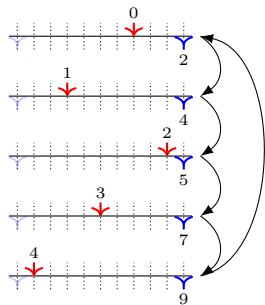
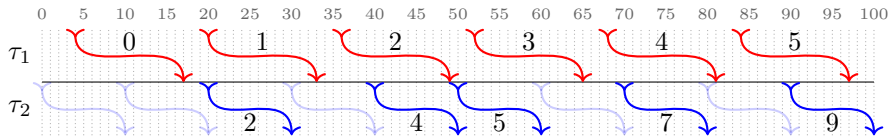
(min delay) $j_1 = 2$ (max delay) $j_1 = 4$





Variability of the input-output delay

- We can **eliminate the jitter** of a 2-tasks chain, by adding a copier task.



(min delay) $j_1 = 2$ $j_1 = 4$ (max delay)

