

AMBARTI models for agricultural experiments

Prado, E. B., Lemos, A. A.

Hamilton Institute & Dept. of Mathematics and Statistics



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Agenda

- ▶ Additive Main Effect interaction (AMMI) models
- ▶ $\text{AMMI} + \text{BART} = \text{AMBARTI}$
- ▶ Some preliminary results

Additive Main effects and Multiplicative Interactions (AMMI)

- ▶ Linear–bilinear models are frequently used to analyse two-way data such as genotype-by-environment data;
- ▶ An example of this class of models is the AMMI model.

$$y_{ij} = \mu + g_i + e_j + \sum_{q=1}^Q \lambda_q \gamma_{iq} \delta_{jq} + \epsilon_{ij}, \quad \epsilon_{ij} \sim \mathcal{N}(0, \tau^{-1}),$$

where

- ▶ y - response
- ▶ g - genotype
- ▶ e - environment
- ▶ λ - singular value of the multiplicative component
- ▶ γ - genotype singular value
- ▶ δ - environment singular value

Additive Main effects and Multiplicative Interactions (AMMI)

The following priors are assumed in its Bayesian version (Josse et al, JABES, 2014):

$$\mu \sim \mathcal{N}(m, s_{\mu}^2)$$

$$g_i \sim \mathcal{N}(0, s_g^2)$$

$$e_j \sim \mathcal{N}(0, s_e^2)$$

$$(\lambda_q)_{q=1,\dots,Q} \sim \text{ordered sample of } Q \text{ independent } \mathcal{N}^+(0, s_{\lambda}^2)$$

$$\gamma_{1q} \sim \mathcal{N}^+(0, 1) \quad \text{for } q = 1, \dots, Q$$

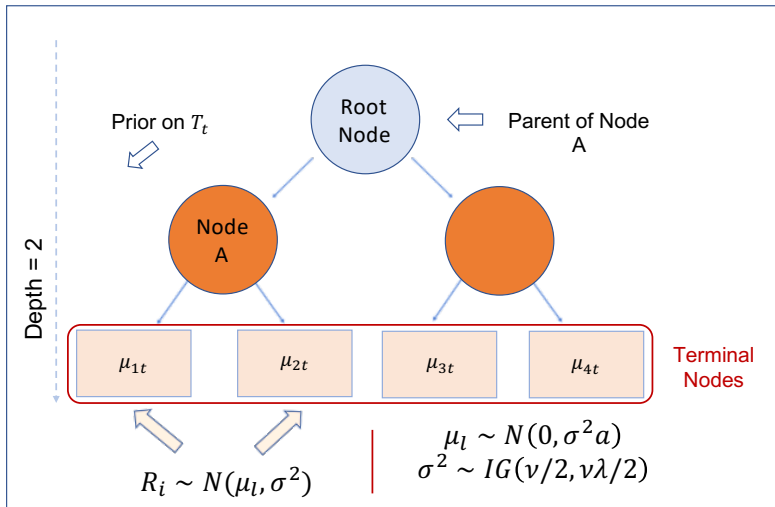
$$\gamma_{iq} \sim \mathcal{N}(0, 1) \quad \text{for } i > 1 \text{ and } q = 1, \dots, Q$$

$$\delta_{jq} \sim \mathcal{N}(0, 1) \quad \text{for } j \geq 1 \text{ and } q = 1, \dots, Q$$

$$\sigma_E \sim \mathcal{U}(0, S_{\text{ME}})$$

Additive Main Effect Bayesian Additive
Regression Tree interaction models (AMBARTI)

BART



AMMI + BART

BART is a flexible tree-based method that can be used for predicting when there are interactions and non-linear relationships.

$$y_{ij}|\mathbf{x}_{ij}, \mathcal{T}, \mathcal{M}, \Theta, \sigma^2 \sim \text{N} \left(g_i + e_j + \sum_{t=1}^T h(\mathbf{x}_{ij}, \mathcal{M}_t, \mathcal{T}_t), \sigma^2 \right),$$

where y_{ij} is the yield for genotype i and environment j , and g_i and e_j are the genotype and environment effects, respectively.

$$\mu_{t\ell}|\mathcal{T}_t \sim \text{N}(\mu_\mu = 0, \sigma_\mu^2),$$

$$g_i|\mathcal{T}_t \sim \text{N}(\mu_g, \sigma_g^2),$$

$$e_j|\mathcal{T}_t \sim \text{N}(\mu_e, \sigma_e^2),$$

$$\sigma_g^2 \sim \text{IG}(a_g, b_g),$$

$$\sigma_e^2 \sim \text{IG}(a_e, b_e),$$

$$\sigma^2 \sim \text{IG}(a, b).$$

Some preliminary results

Simulated example

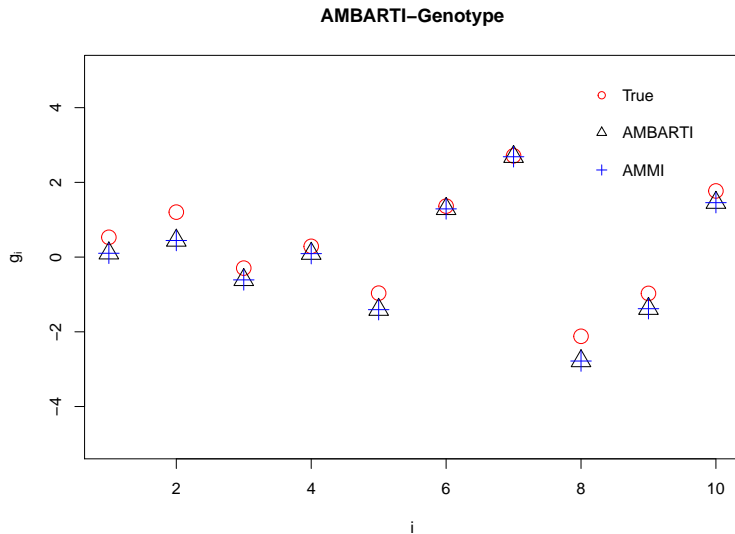
We consider the following setting to generate a simulated data set.

$$y_{ij} = \mu + g_i + e_j + \sum_{q=1}^Q \lambda_q \gamma_{iq} \delta_{jq} + \epsilon_{ij}, \quad \epsilon_{ij} \sim \mathcal{N}(0, \tau^{-1}),$$

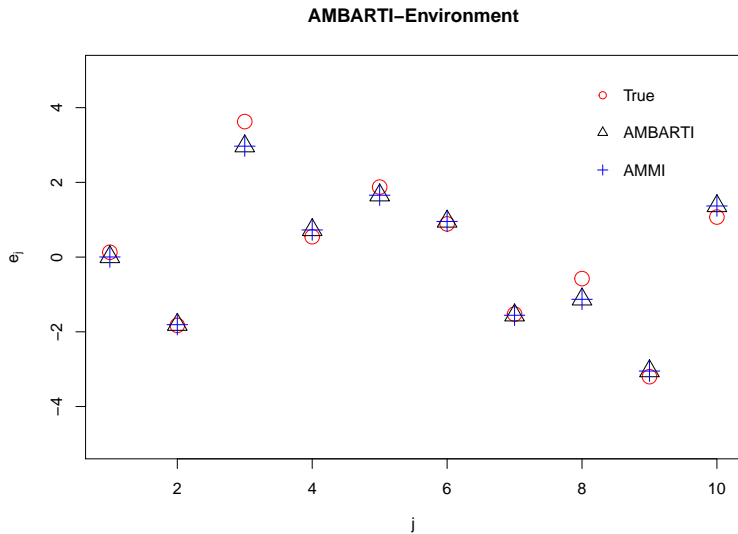
where

- ▶ $Q = 1$
- ▶ $I = J = 10$
- ▶ $\mu = 10$
- ▶ $g = \mathcal{N}(0, s_g)$
- ▶ $e = \mathcal{N}(0, s_e)$
- ▶ $s_g = 2, s_e = 2$
- ▶ $\lambda = 12$
- ▶ $\tau = 1$

Preliminary results



Preliminary results



Some remarks and next steps

- ▶ Interestingly, BART is doing a good job. . .

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cor(y, y_hat_AMBARTI) = 0.98  
cor(y, y_hat_AMMI) = 0.93
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- ▶ More simulations
- ▶ Calculate the interactions
- ▶ Real datasets

That's all, folks! Thank you!

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References