COMP4418

Assignment2

Chunnan Sheng

Student Code: 5100764

1. Answer Set Programming

(a)

```
% COMP4418 Assignment 2
% Question 1
\#const k = 3.
% encoding
k\{c(X) : v(X)\}k.
:- not e(X, Y), c(X), c(Y), X != Y.
% Vertices
v(1..6).
% Edges
e(1,2). e(2,1).
e(1,4). e(4,1).
e(1,3). e(3,1).
e(2,4). e(4,2).
e(2,6). e(6,2).
e(2,5). e(5,2).
e(3,4). e(4,3).
e(3,5). e(5,3).
e(3,6). e(6,3).
e(4,5). e(5,4).
e(5,6). e(6,5).
% Display
#show c/1.
```

(b) Outputs for $K \in \{3,4,5,6\}$

```
E:\UNSW_semester_3\COMP4418\clingo>clingo.exe --const k=3 -n 0 E:/COMP4418/assn2/clique.lp
clingo version 5.2.1
Reading from E:/COMP4418/assn2/clique.lp
Solving...
Answer: 1
c(5) c(2) c(4)
Answer: 2
c(5) c(3) c(4)
Answer: 3
c(5) c(6) c(2)
Answer: 4
c(5) c(6) c(3)
Answer: 5
c(1) c(2) c(4)
Answer: 6
c(1) c(3) c(4)
SATISFIABLE
Models
Calls
           : 0.035s (Solving: 0.03s 1st Model: 0.00s Unsat: 0.00s)
Time
CPU Time
            : 0.016s
E:\UNSW_semester_3\COMP4418\clingo>clingo.exe --const k=4 -n 0 E:/COMP4418/assn2/clique.lp
clingo version 5.2.1
Reading from E:/COMP4418/assn2/clique.lp
Solving...
UNSATISFIABLE
Models
           : 0
Calls
           : 1
Time
           : 0.000s (Solving: 0.00s 1st Model: 0.00s Unsat: 0.00s)
           : 0.000s
E:\UNSW_semester_3\COMP4418\clingo>clingo.exe --const k=5 -n 0 E:/COMP4418/assn2/clique.lp
clingo version 5.2.1
Reading from E:/COMP4418/assn2/clique.lp
Solving...
UNSATISFIABLE
Models
            : 0
Calls
           : 1
           : 0.000s (Solving: 0.00s 1st Model: 0.00s Unsat: 0.00s)
Time
           : 0.000s
CPU Time
E:\UNSW_semester_3\COMP4418\clingo>clingo.exe --const k=6 -n 0 E:/COMP4418/assn2/clique.lp
clingo version 5.2.1
Reading from E:/COMP4418/assn2/clique.lp
Solving...
UNSATISFIABLE
Models
           : 0
Calls
           : 1
Time
           : 0.000s (Solving: 0.00s 1st Model: 0.00s Unsat: 0.00s)
           : 0.000s
E:\UNSW_semester_3\COMP4418\clingo>
```

2. Answer Set Programming

Output of the logic:

```
E:\UNSW_semester_3\COMP4418\clingo>clingo.exe -n 0 E:/COMP4418/assn2/Question2.m
clingo version 5.2.1
Reading from E:/COMP4418/assn2/Question2.m
Solving...
Answer: 1
a d
Answer: 2
b d
Answer: 3
c d
SATISFIABLE

Models : 3
Calls : 1
Time : 0.026s (Solving: 0.02s 1st Model: 0.00s Unsat: 0.02s)
CPU Time : 0.000s
```

Candidate S	Reduct P ^s	Stable model
$\{a,b,c,d\}$	d :- a. d :- b. d :- c.	NO
$\{a,b,c\}$	d :- a. d :- b. d :- c.	NO
$\{a,b,d\}$	d :- a. d :- b. d :- c.	NO
$\{a,c,d\}$	d :- a. d :- b. d :- c.	NO
$\{b,c,d\}$	d :- a. d :- b. d :- c.	NO
{ <i>a</i> , <i>b</i> }	d :- a. d :- b. d :- c.	NO
{a, c}	d :- a. d :- b. d :- c.	NO
$\{a,d\}$	a. d:-a. d:-b. d:-c.	YES
{b, c}	d :- a. d :- b. d :- c.	NO
{b, d}	b. d:-a. d:-b. d:-c.	YES
$\{c,d\}$	c. d:-a. d:-b. d:-c.	YES
<i>{a}</i>	a. d:-a. d:-b. d:-c.	NO
<i>{b}</i>	b. d:-a. d:-b. d:-c.	NO
{c}	c. d:-a. d:-b. d:-c.	NO
{d}	a. b. c. d:-a. d:-b. d:-c.	NO
{}	a. b. c. d:-a. d:-b. d:-c.	NO

3. Reasoning about Knowledge

(a)

$$\begin{aligned} \mathbf{OKB} &\vDash \mathbf{K} \big(P(n_1) \land Q(n_2) \big) \Leftrightarrow \\ &\vDash \big\| \mathbf{K} \big(P(n_1) \land Q(n_2) \big) \big\|_{\mathbf{KB}} \Leftrightarrow \\ &\vDash \mathbf{RES} [\mathbf{KB}, \| P(n_1) \land Q(n_2) \|_{\mathbf{KB}}] \Leftrightarrow \\ &\vDash \mathbf{RES} [\mathbf{KB}, P(n_1) \land Q(n_2)] \stackrel{\text{def}}{=} \left\{ \begin{matrix} TRUE & \mathbf{KB} \vDash P(n_1) \land Q(n_2) \\ FALSE & Otherwise \end{matrix} \right. \end{aligned}$$

Since

$$\forall x (P(x) \Leftrightarrow x = \#1 \lor x = \#2) \land \forall x \big(P(x) \Leftrightarrow \neg Q(x)\big)$$

Then

$$P(x) \Leftrightarrow x \in \{\#1, \#2\}$$
$$Q(x) \Leftrightarrow x \in \{\#1, \#2\}^c = \{\#3, \#4, \#5 \dots\}$$

Therefore, if $\mathbf{OKB} \models \mathbf{K}(P(n_1) \land Q(n_2))$ should be true,

Then

$$n_1 \in \{\#1, \#2\}$$

$$n_2 \in \{\#3, \#4, \#5, \dots\}$$

Or equivalently:

$$(n_1, n_2) \in \{\#1, \#2\} \times \{\#3, \#4, \#5, \dots\}$$

(b)

$$\mathbf{RES}[\mathbf{KB}, P(x) \land \neg Q(y)] \stackrel{\text{def}}{=} \begin{cases} TRUE & \mathbf{KB} \vDash P(x) \land \neg Q(y) \\ FALSE & therwise \end{cases}$$

$$\Leftrightarrow$$

$$\mathbf{KB} \vDash P(x) \land \neg Q(y)$$

$$\Leftrightarrow$$

$$\mathbf{KB} \vDash P(x) \land P(y)$$

Since

$$P(x) \land P(y) = \begin{cases} TRUE & x \in \{\#1, \#2\} \land y \in \{\#1, \#2\} \\ FALSE & otherwise \end{cases}$$

Therefore,

$$\mathbf{KB} \vDash \neg \mathbf{K}(P(x) \land P(y))$$

Which means

RES[KB,
$$P(x) \land \neg Q(y)$$
]

Cannot be determined.

4. Limited Belief

(a)

Proper+ of KB:

$$(\neg F \lor C) \land (\neg C \lor \neg U) \land (C \lor U)$$
or
$$\mathbf{KB} = \{\neg F \lor C, \neg C \lor \neg U, C \lor U\}$$

(b)

КВ	$\{\neg F \lor C, \neg C \lor \neg U, C \lor U\}$	
UP ⁻ (KB)	$\{\neg F \lor C, \neg C \lor \neg U, C \lor U\}$	
UP(KB)	$\{\neg F \lor C, \neg C \lor \neg U, C \lor U\}$	
UP ⁺ (KB)	$\{\neg F \lor C, \neg C \lor \neg U, C \lor U\} \cup$ $\{c c \supseteq \neg F \lor C \ or \ c \supseteq \neg C \lor \neg U \ or \ c \supseteq C \lor U\}$	

According to the above table, KB is not obviously inconsistent.

However, $(F \lor U \lor C) \in UP^+(KB)$

Then **OKB** $| \approx \mathbf{K_0}(F \vee U \vee C)$ hold. The minimal k = 0

(c)

$$\neg(\neg F \land \neg U) \Leftrightarrow F \lor U$$
$$F \lor U \notin \mathsf{UP}^+(\mathbf{KB})$$

Then

A.
$$\neg(\neg F \land \neg U) \notin UP^+(KB)$$

In addition:

B. **KB** is not obviously inconsistent

According to A and B:

OKB
$$\mid \approx \neg K_0 \neg (\neg F \land \neg U)$$

5. Reasoning about Action

(a) Proved

$$(a) \Leftrightarrow \Sigma_{0} \vDash \forall x \mathbf{R}[\langle \rangle, [putInBox(x)]InBox(x)]$$

$$\Leftrightarrow \Sigma_{0} \vDash \forall x \mathbf{R}[putInBox(x), InBox(x)]$$

$$\Leftrightarrow \Sigma_{0} \vDash \forall x \mathbf{R}\Big[\langle \rangle, \gamma_{in} {a \atop putInBox(x)} {b \atop x}\Big]$$

$$\Leftrightarrow \Sigma_{0} \vDash \forall x \Big(\Big(putInBox(x) = putInBox(s)\Big) \lor InBox(s)\Big)$$
if $x = s$, then
$$\forall x \Big(\Big(putInBox(x) = putInBox(s)\Big) \lor InBox(s)\Big) = \mathbf{TRUE}$$

(b) Proved

(c) Proved

Proved
$$(b) \Leftrightarrow \Sigma_0 \vDash \mathbf{R}[\langle\rangle, \forall y [moveBox(y)] \forall x (lnBox(x) \Rightarrow localtion(x) = y)] \\ \Leftrightarrow \Sigma_0 \vDash \mathbf{R}[\forall y (moveBox(y)), \forall x (lnBox(x) \Rightarrow location(x) = y)] \\ \Leftrightarrow \Sigma_0 \vDash \forall y \forall x \mathbf{R}[moveBox(y), ([putlnBox(x)](localtion(x) = y))] \\ \lor (lnBox(x) \land (location(x) = y))] \\ \Leftrightarrow \Sigma_0 \vDash \forall y \forall x (\mathbf{R}[moveBox(y) \cdot putlnBox(x), localtion(x) = y] \lor \dots) \\ \Leftrightarrow \Sigma_0 \vDash \forall y \forall x \left(\mathbf{R}[putlnBox(x), \gamma_{pos}^{a}_{moveBox(y)}, \frac{p}{y}] \lor \dots\right) \\ \Leftrightarrow \Sigma_0 \vDash \forall y \forall x \left(\left((moveBox(y) = moveBox(t)) \land \mathbf{R}[putlnBox(x), lnBox(s)]) \lor \dots\right) \lor \dots\right) \\ \Leftrightarrow \Sigma_0 \vDash \forall y \forall x \left(\left((moveBox(y) = moveBox(t)) \land \mathbf{R}[putlnBox(x), lnBox(s)]) \lor \dots\right) \\ \Leftrightarrow \Sigma_0 \vDash \forall y \forall x \left(\left((moveBox(y) = moveBox(t)) \land \mathbf{R}[putlnBox(x), lnBox(s)]) \lor \dots\right) \\ \Leftrightarrow \nabla_0 \vDash \forall y \forall x \left(\left((moveBox(y) = moveBox(t)) \land \mathbf{R}[putlnBox(x), lnBox(x)] \lor \dots\right) \\ \Leftrightarrow \forall y \forall x \left(\mathbf{R}[putlnBox(x), lnBox(x)] \lor \dots\right) \\ \Leftrightarrow \forall y \forall x \left(\left((putlnBox(x) = putlnBox(s)) \lor lnBox(s) \lor \dots\right) \Leftrightarrow \mathbf{TRUE}$$

[shakeBox]**K** $\exists xInBox(x)$ $(\mathbf{SF}(shakeBox) \Rightarrow \mathbf{K}(\mathbf{SF}(shakeBox) \Rightarrow [shakeBox] \exists xInBox(x)))$ $\wedge \left(\neg \mathbf{SF}(shakeBox) \Rightarrow \mathbf{K}\left(\neg \mathbf{SF}(shakeBox) \Rightarrow [shakeBox] \exists xInBox(x)\right)\right)$



$$\mathbf{K}(\mathbf{SF}(shakeBox) \Rightarrow [shakeBox] \exists xInBox(x))$$

$$\vee \mathbf{K}(\neg \mathbf{SF}(shakeBox) \Rightarrow [shakeBox] \exists xInBox(x))$$

$$\Rightarrow$$

$$\mathbf{K}(\mathbf{SF}(shakeBox) \Rightarrow [shakeBox] \exists xInBox(x)) \quad \mathbf{P}$$
Since
$$\left(\Box \mathbf{SF}(a) \Leftrightarrow \left((a = shakeBox) \Rightarrow \exists xInBox(x)\right)\right) \in \Sigma_{dyn}$$
and
$$\left(\Box \mathbf{Poss}(a) \Leftrightarrow \mathbf{TRUE}\right) \in \Sigma_{dyn}$$
Therefore
$$\Sigma_0 \land \Sigma_{dyn} \land \mathbf{o}\Sigma_{dyn} \models \mathbf{P} \quad \checkmark$$

(d) Disproved