



# Use of Capella as Digital Twin to Perform Complex Systems Simulation

Prepared by Prof. Dr. Christopher Schneider Cerqueira

[chris@ita.br](mailto:chris@ita.br)



# Summary





# Context

Who we are....



INSTITUTO  
TECNOLÓGICO  
DE AERONÁUTICA

— 1950 —



<http://www.ita.br>





# Some info context

- We are a group of 2 professor (myself -> MBSE and prof. Jonas Fulindi -> STPA)
- We use Capella since 2018 and have the T4C / RAT.
  - Since 2019 we have a graduate course that has around of 30 students (OPM/Capella) per year.
  - Use in 3 undergraduate courses to teach: Verification & Validation, Space Mission Architecture and Space Ground Segment Architecture. Around 30 students per course.
  - Over 15 final works (undergrad/msc) using MBSE.
- Our lab is requested to do some help into strategic projects so we already applied Capella into 6 government acquisition processes.
- We have a funded project to interconnect MBSE with Modelling & Simulation as well as architecture optimization to create a Model based Mission Engineering Framework

# Our group



## PhD students



Jeanne Samara Lima  
(UTM Business Plans /  
Systems Eng.)



Priscila Renata  
Cardoso (Operational  
Research and Systems  
Engineering)



Emerson Oliveira  
(Verification and  
Validation)



Maj. Daniel Pleffken  
(Certification)



Maj Leonan Falqueto  
(Mission Optimization)



Lt. Col. Guilherme  
Moreira (Scenarios and  
Formal Methods)

## Master's Students



Matheus Cogo  
(Architecture  
Consistency Check)



Ariane Novais  
(Interaction with Digital  
Twins)



Cap Bruno Avelino  
(Route Optimization)



Ângelo Florentino  
(Interaction with  
simulation)



Maj Thiago Melo  
(Cyber Simulation  
Sandbox)



Rebeca Suede Cap  
(Requirements)

## Collaborators



Ariele Ferraz (Sensor Fusion)



Guilherme Matos (FullStack – VR)



João Cioffi (Machine Learning)



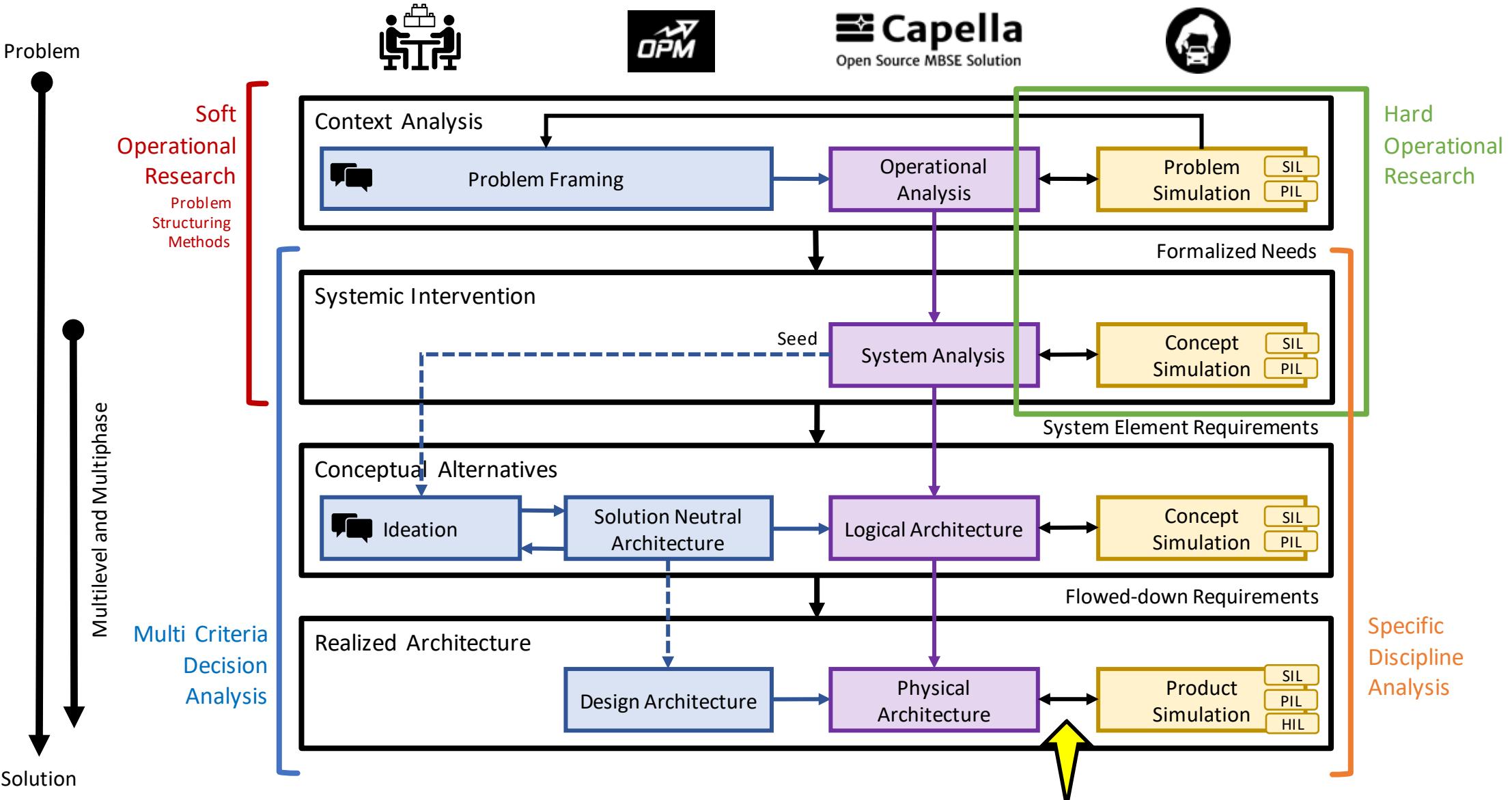
Moara Oliveira (Embedded Design)



Arthur Assis Alves (Simulated UTM  
Dev)

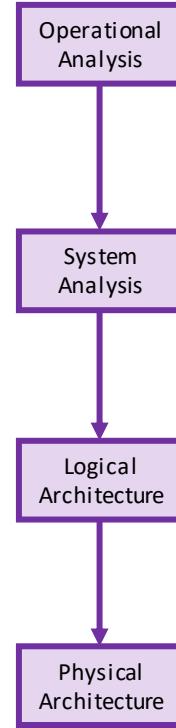
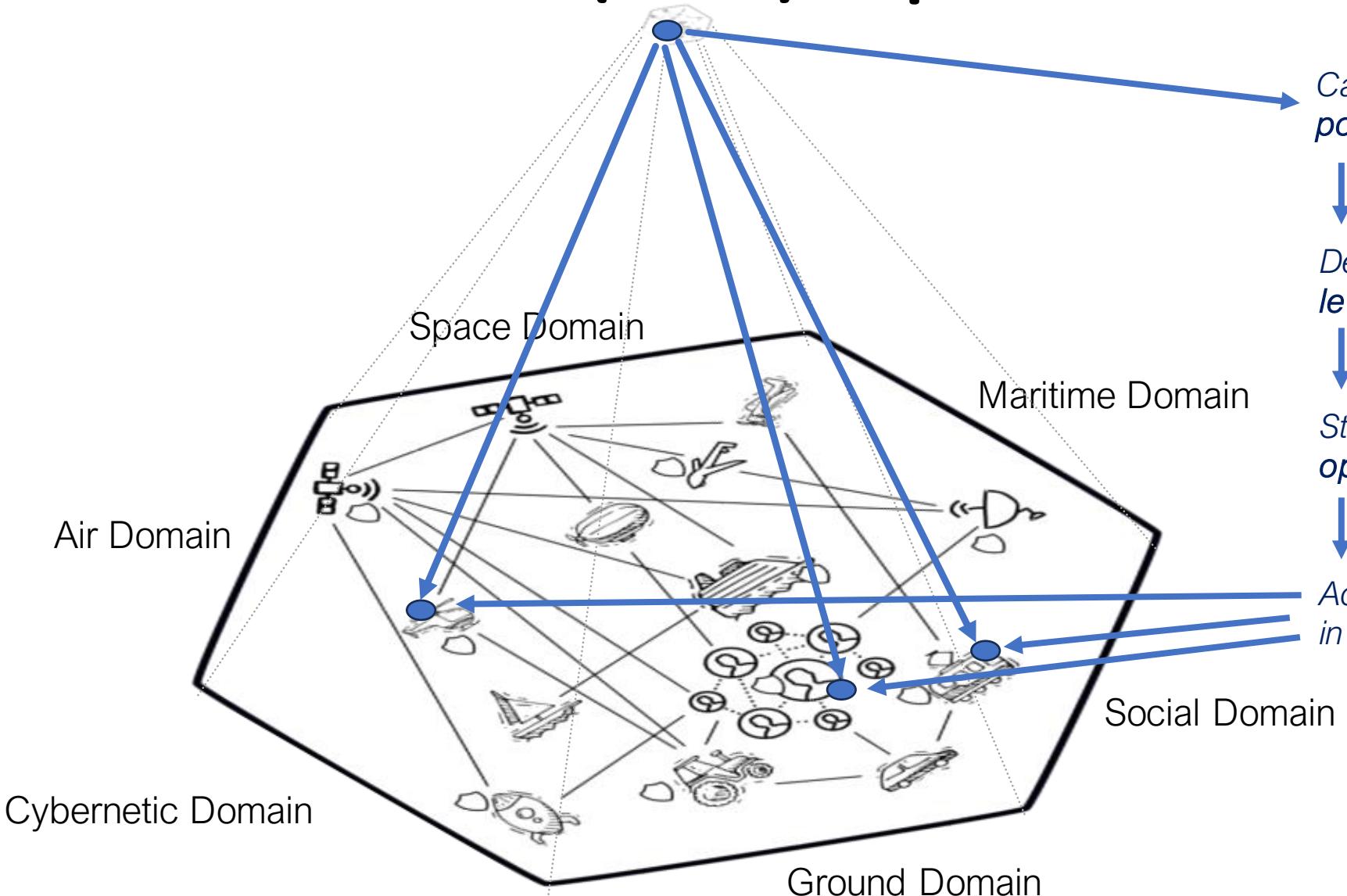


# Our Multi Methodology MBSE Framework





# Multidomain (SoS) Operations



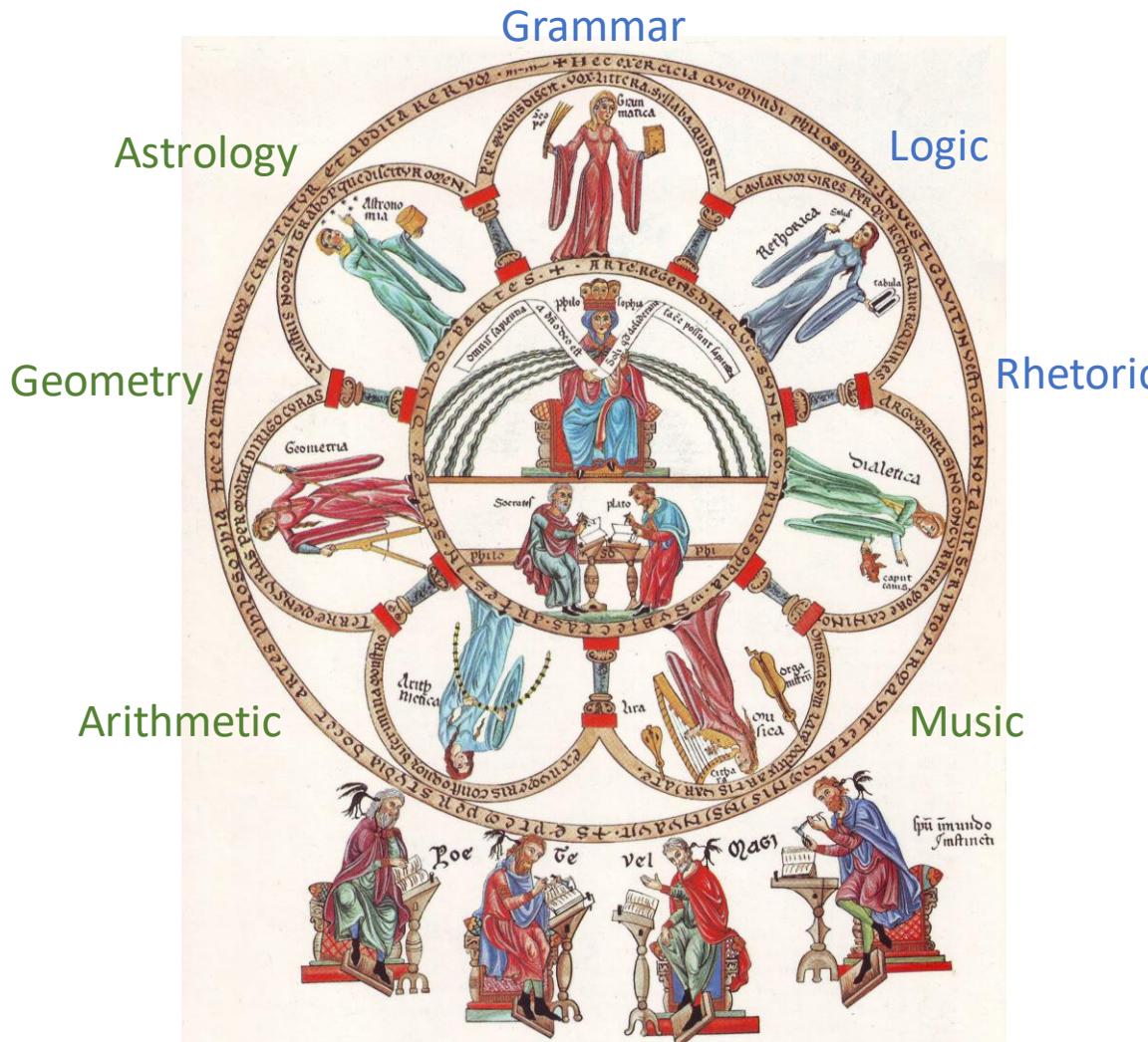


# Concepts

What you are going to find (more or less) in the literature

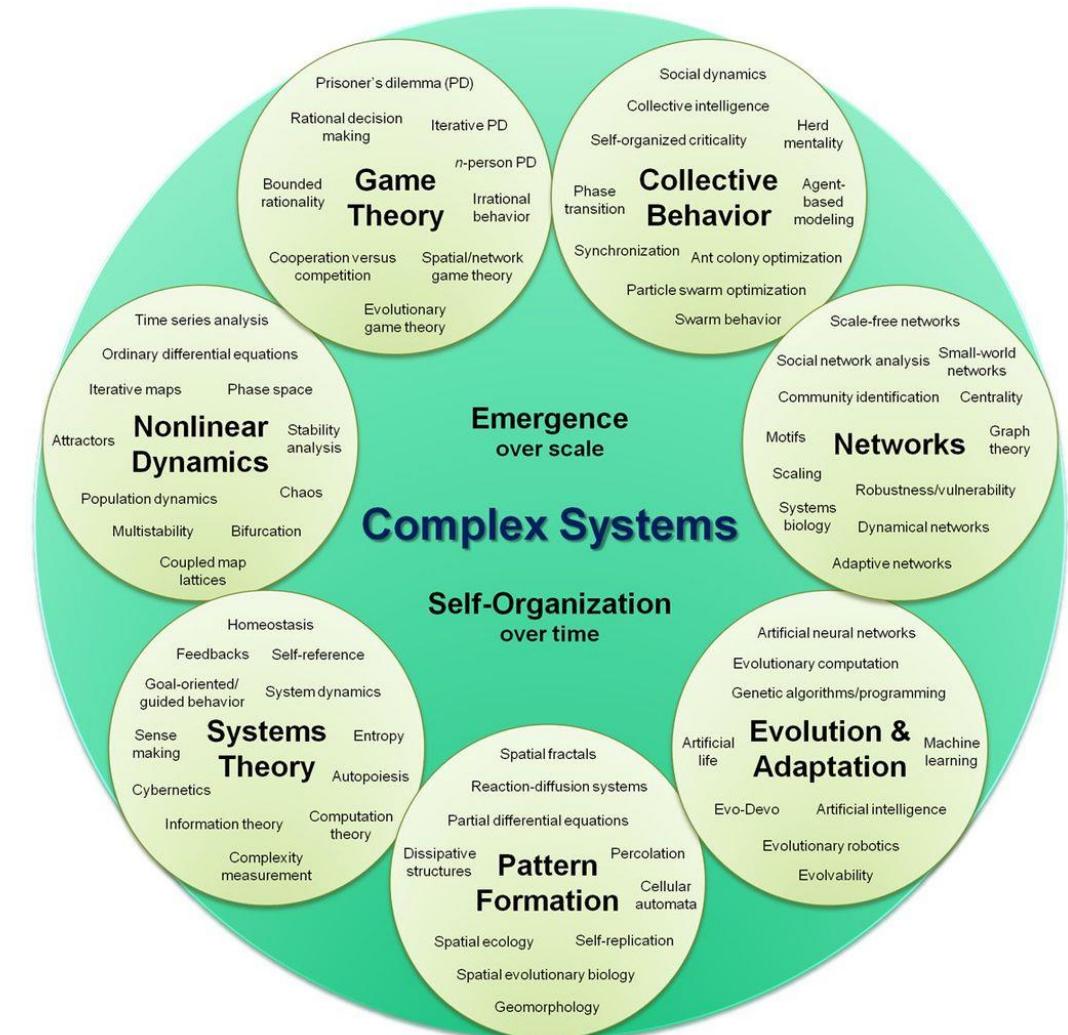


# Complex Systems



The Hortus Deliciarum of Herrad of Hohenbourg (Landsberg, 1176-96)

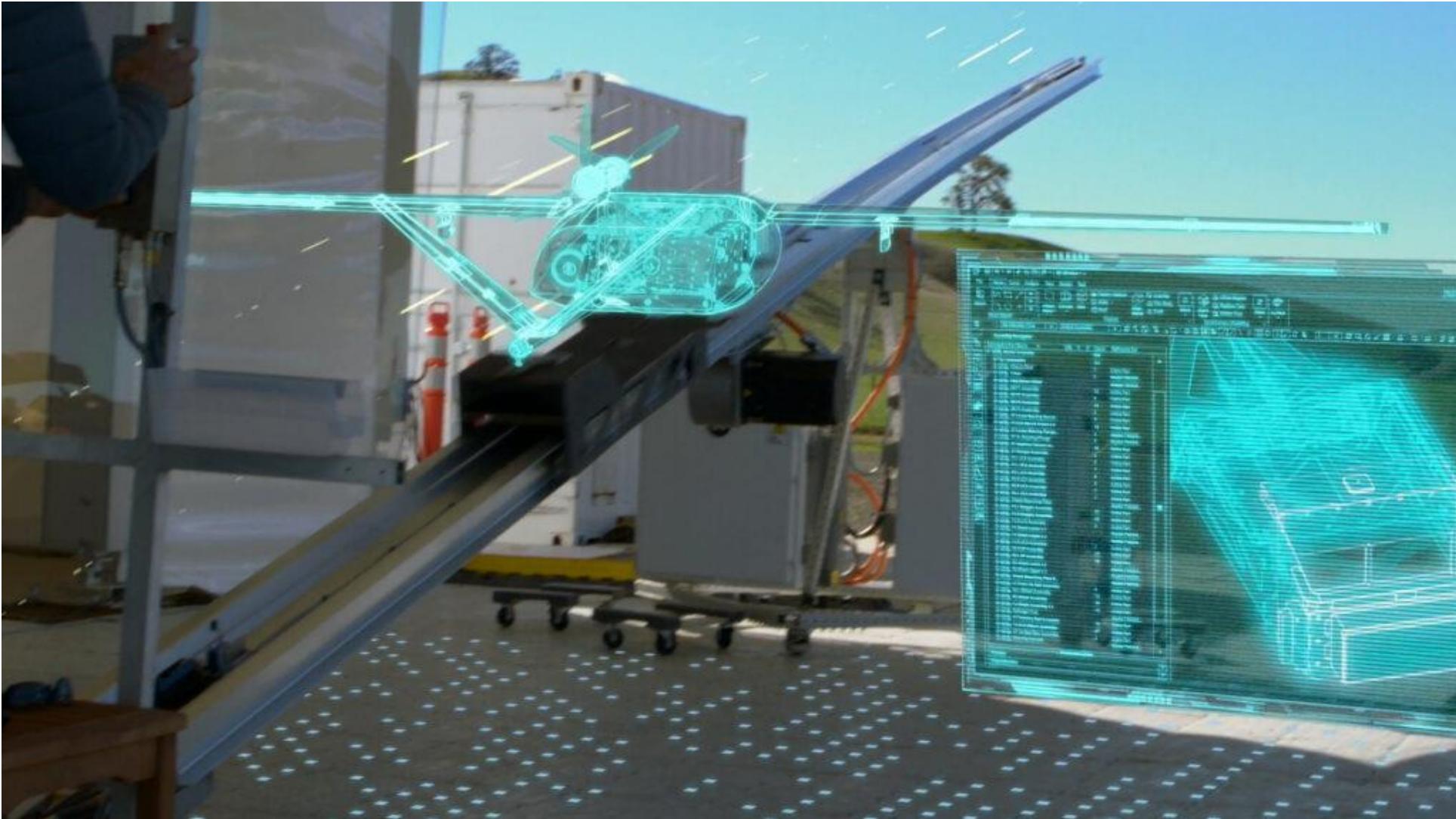
<https://liberalarts.online/trivium-and-quadrivium/>



[Introduction to the Modeling and Analysis of Complex Systems - Milne Open Textbooks \(opensuny.org\)](https://www.milneopen.com/textbooks)



# Digital Twin



<https://blogs.sw.siemens.com/xcelerator/2020/07/07/drones-deliver-critical-supplies-to-communities-in-need/>



# Simulation



Scenery from Florianópolis City at Brazil, from OpenStreetMap seen at MAK's VR-Forces

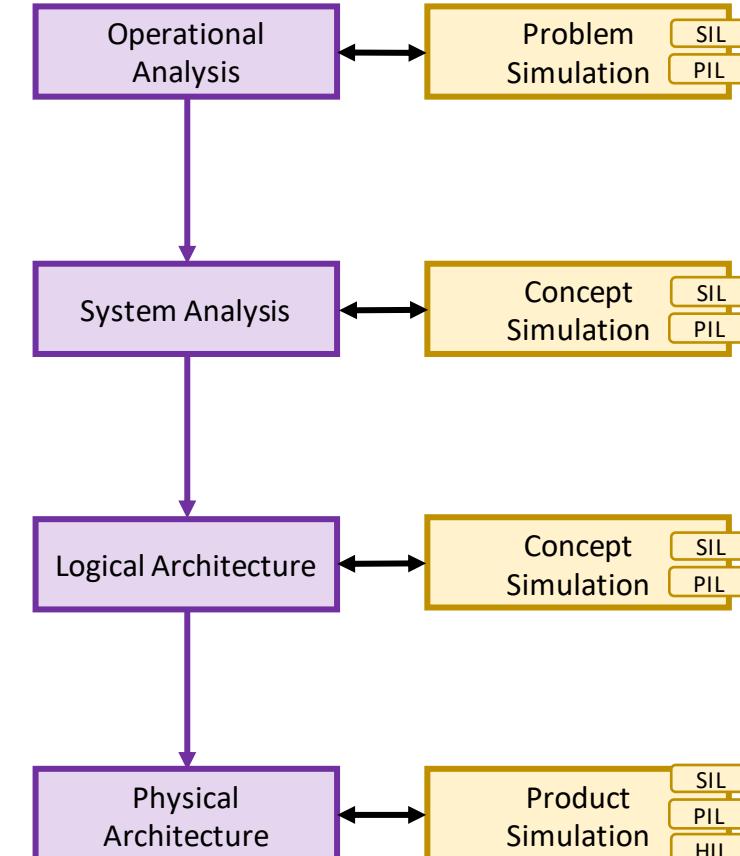


# Our assumptions and characteristics



# On how could we add simulation into Capella? And if we should do that...

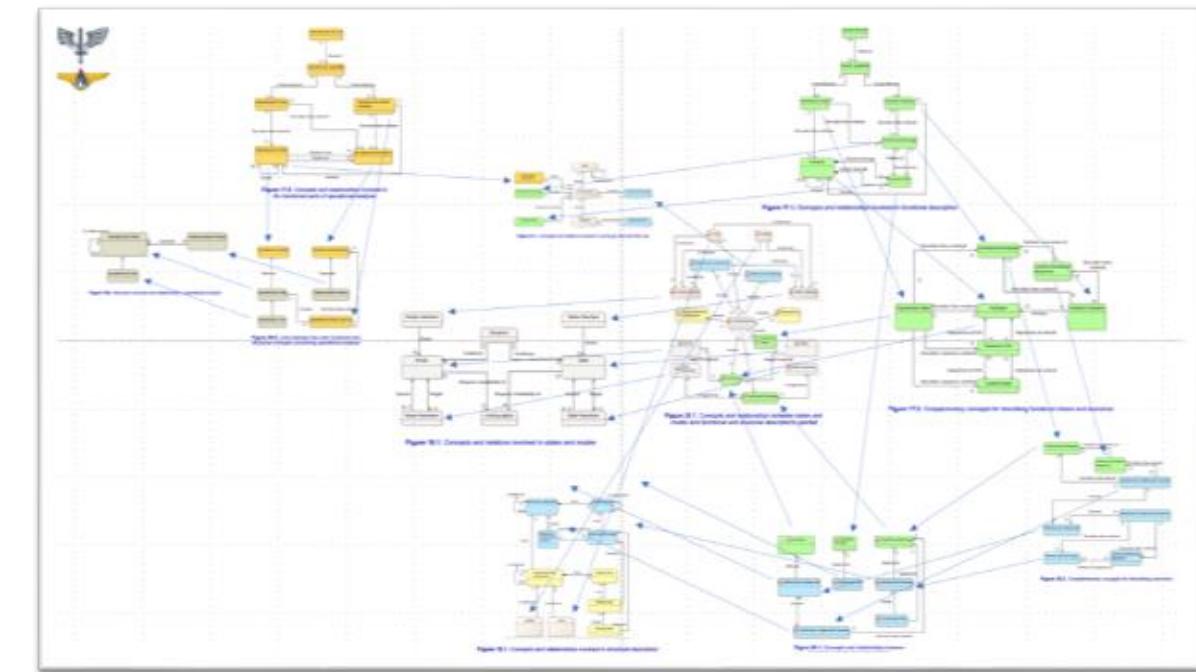
- Decide on the approach:
  - **Read the model** and moves the parameters: [RCE](#)
  - The simulation tool **imports and parse the model**: Python / OpenModellica / Scilab
  - Create a addon that **exports the model** and maintain it sync: Python / OpenModellica / Scilab
  - **Embed into Capella.**
- Why do we simulate?
  - Verify/Validate... the architecture (behavior or structure) / the model / concepts / CONOPs





# On how does the Capella Model needs to be? And the amount of changes...

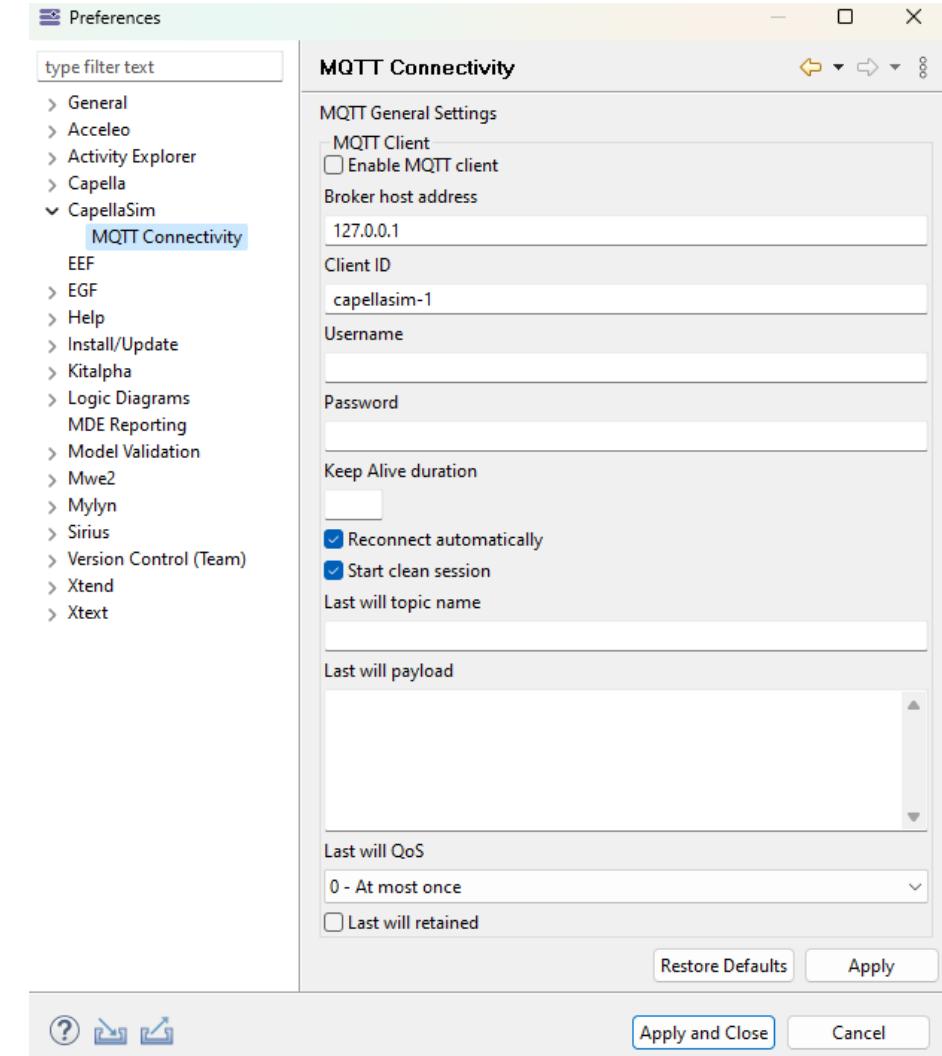
- Regarding the metamodel:
  - There has to be about **zero changes**.  
*I would not like to change it into our T4C server.*
  - Capella has **behavioral diagrams** (static / reactive).
- To the users?
  - There has to be no change unless it **eases the use**.
  - As new things will appear/be controlled, the **UI design has to follow to the same type of navigation**.





# On how to open a running Capella to the rest of world? And interface with it...

- Well... Capella is simulating, executing the reactive model.
- Can we interconnect **simulating Capellas** and integrate it, without actually sharing the model.
  - (the use of S2SS or the T4C are more to the model integration / sharing).
- Distributed Simulation:
  - Hard runtimes: HLA / DIS
  - “Soft” runtime: **ROS**
  - “Even softier” runtime: **MQTT**



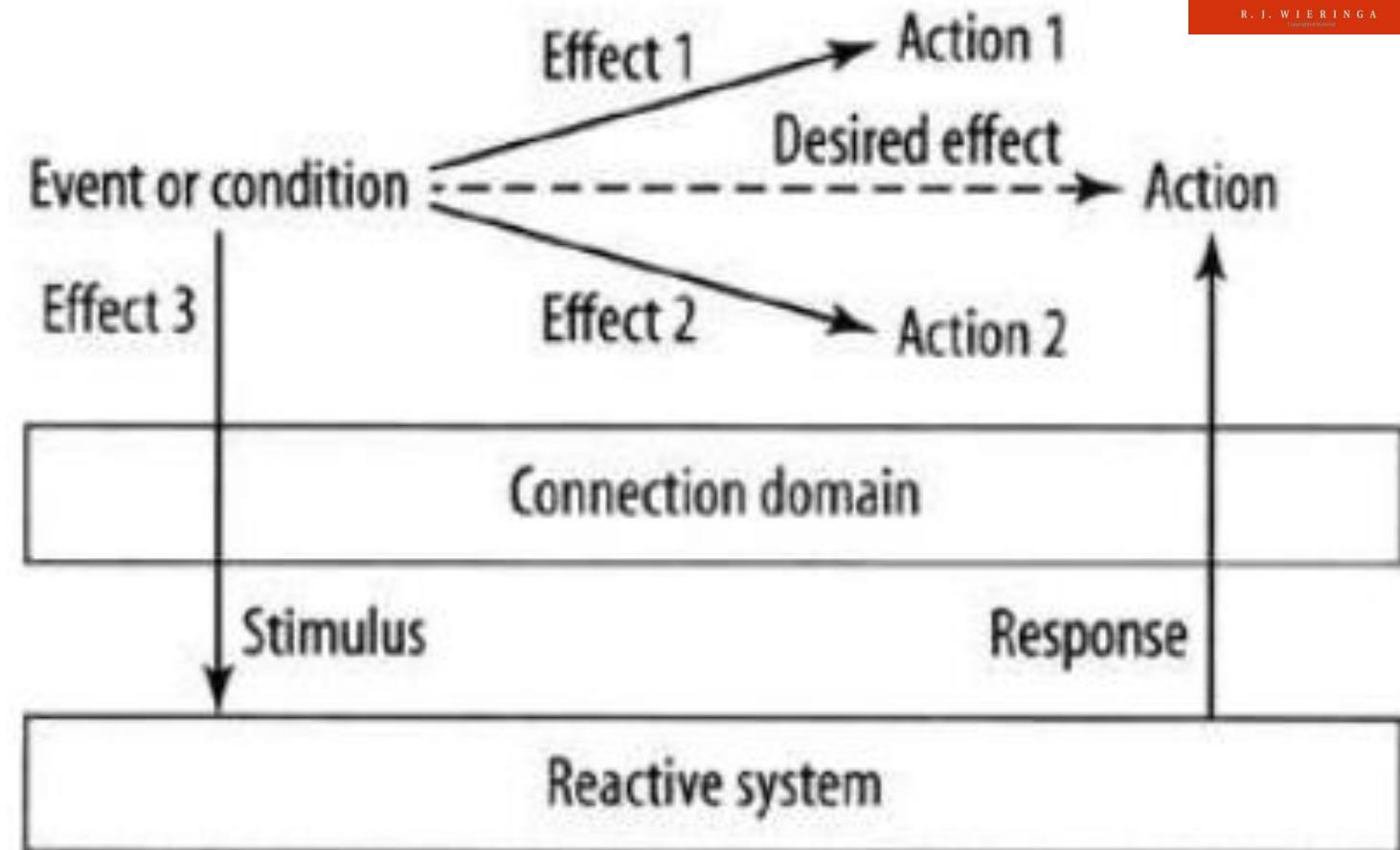
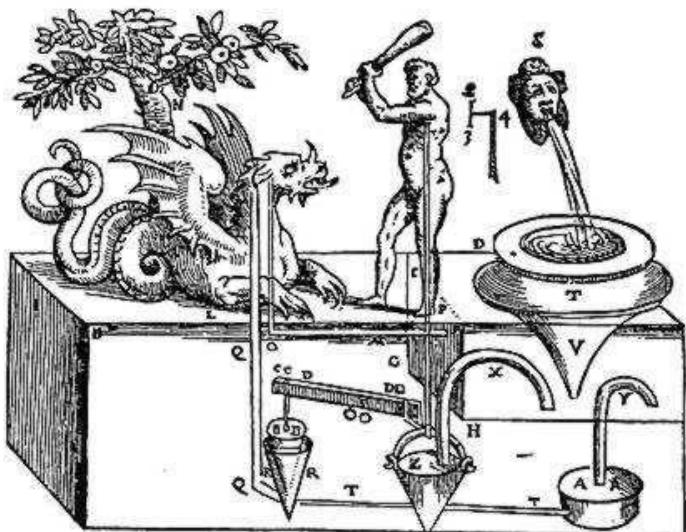
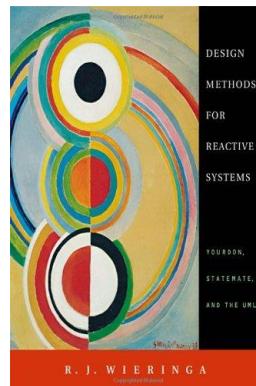


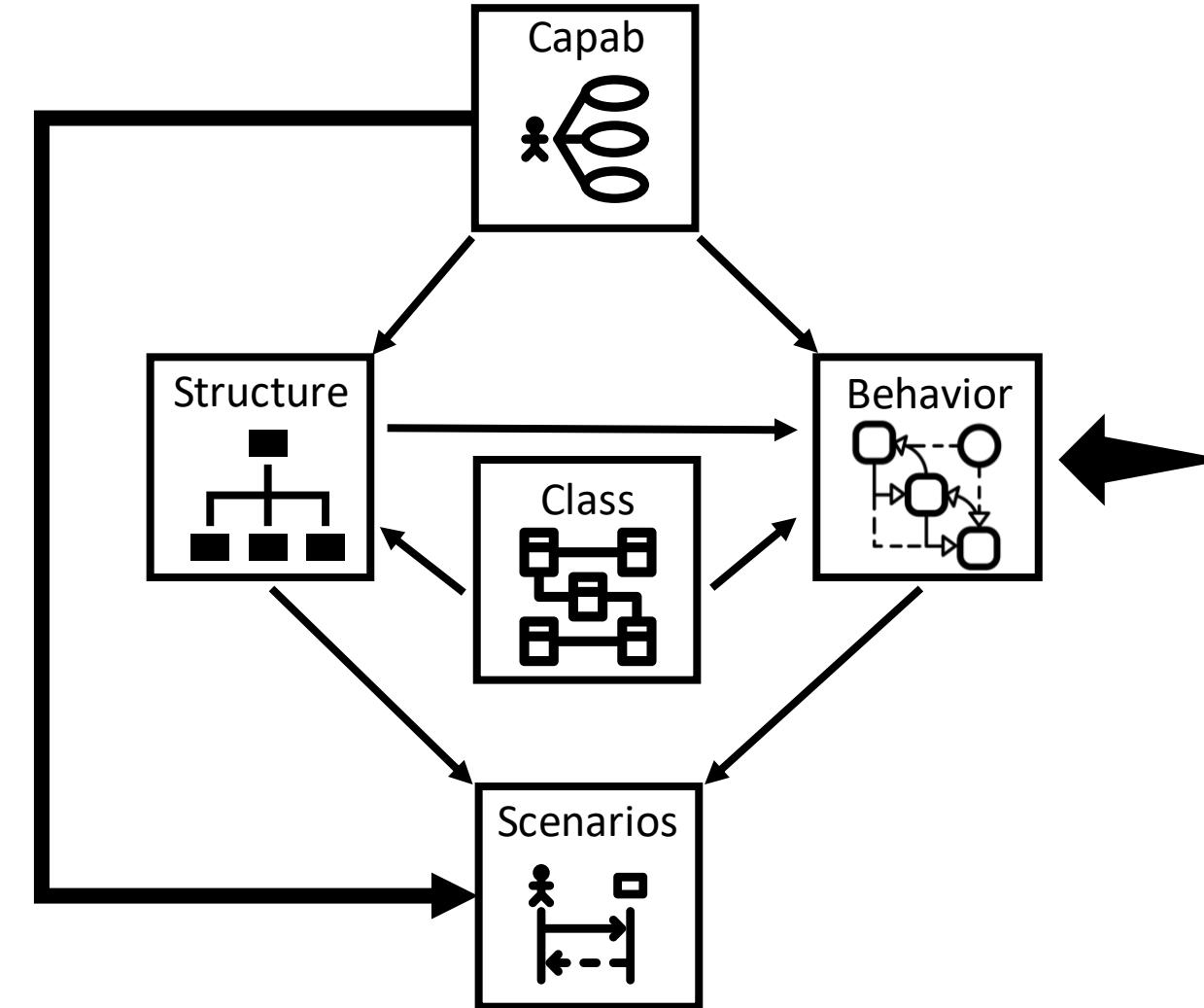
# CapellaSim Add-on

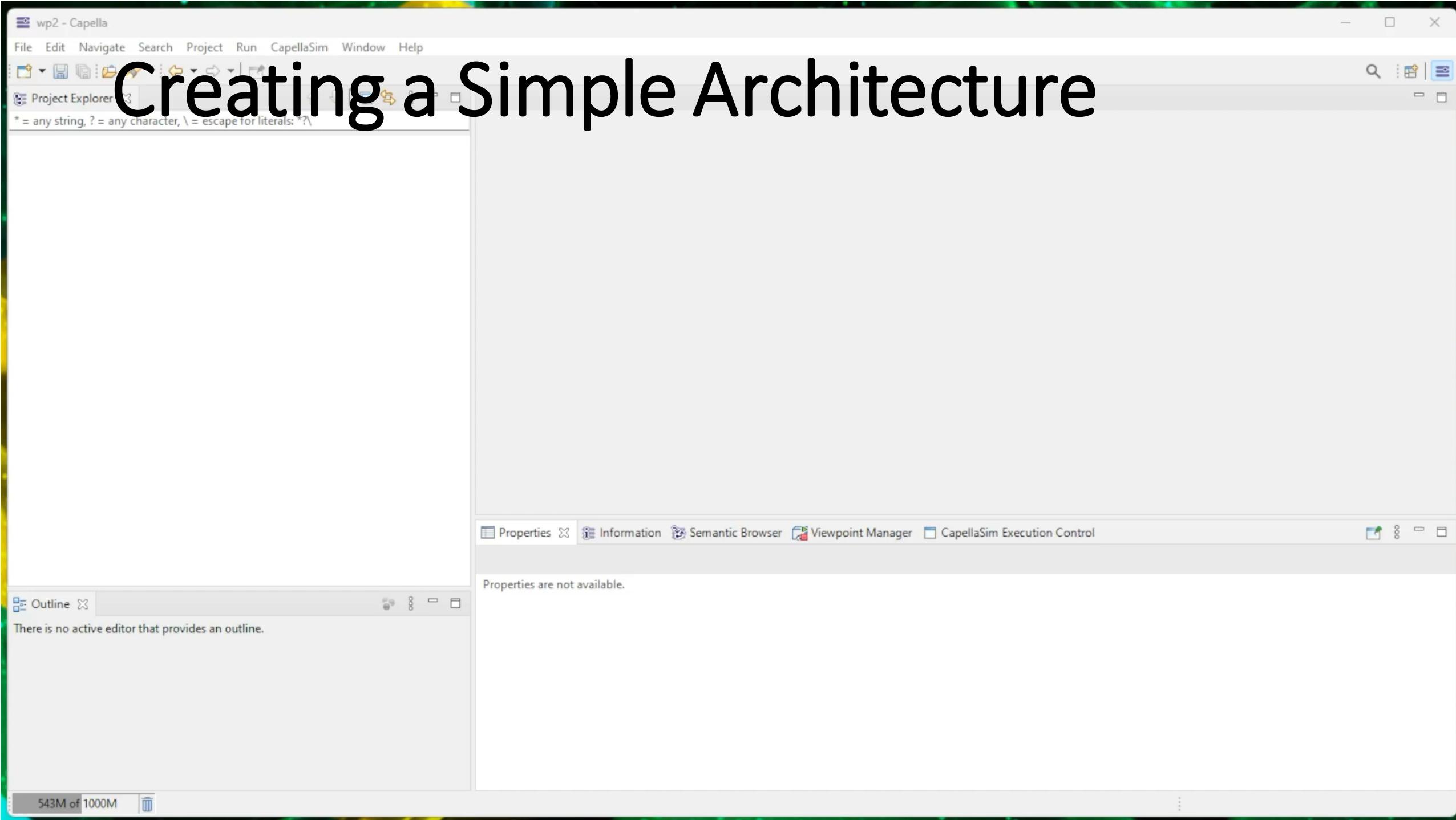
It is on github but the final final real final version release will be made available with the student master thesis.



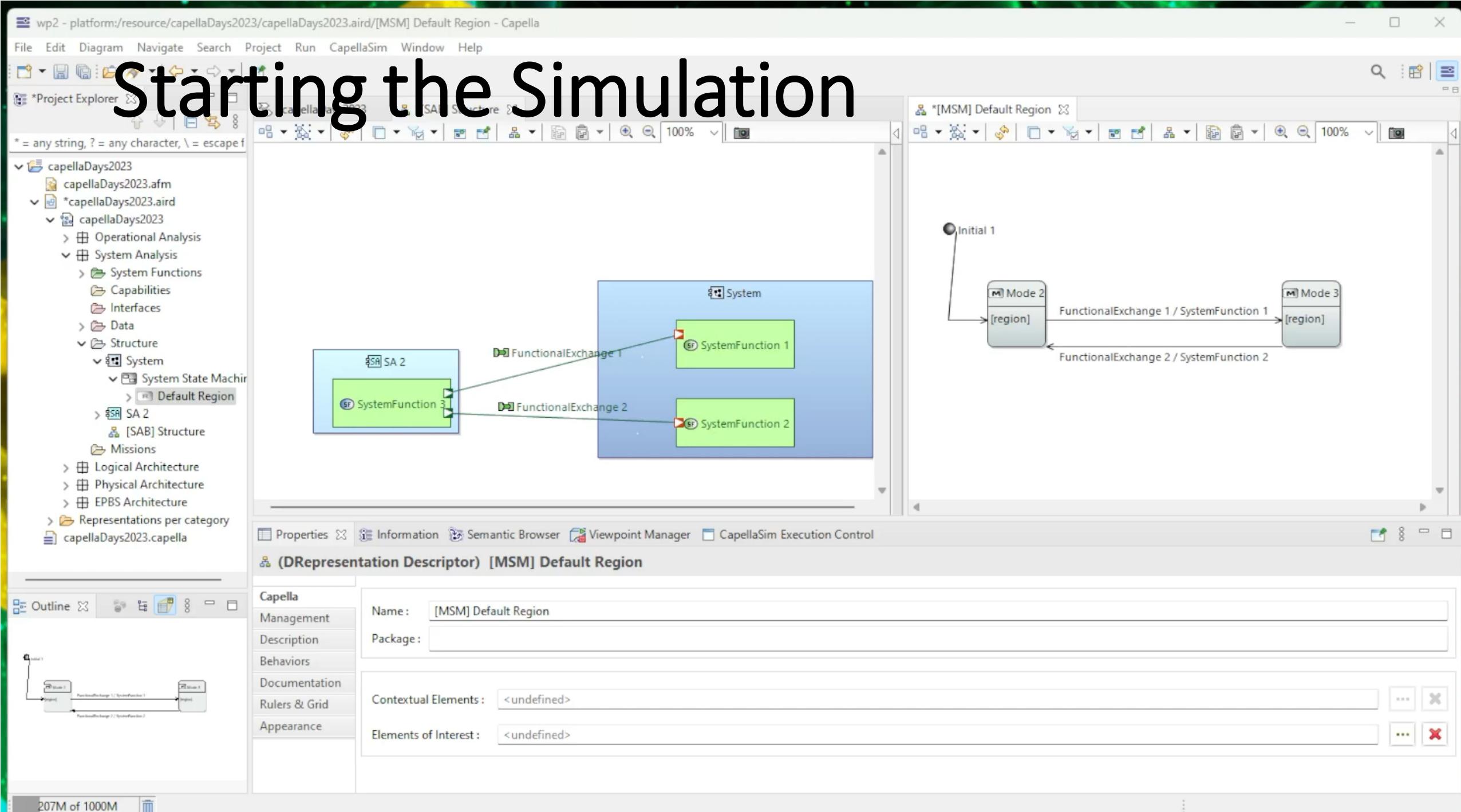
# Statechart - Reactive Simulation



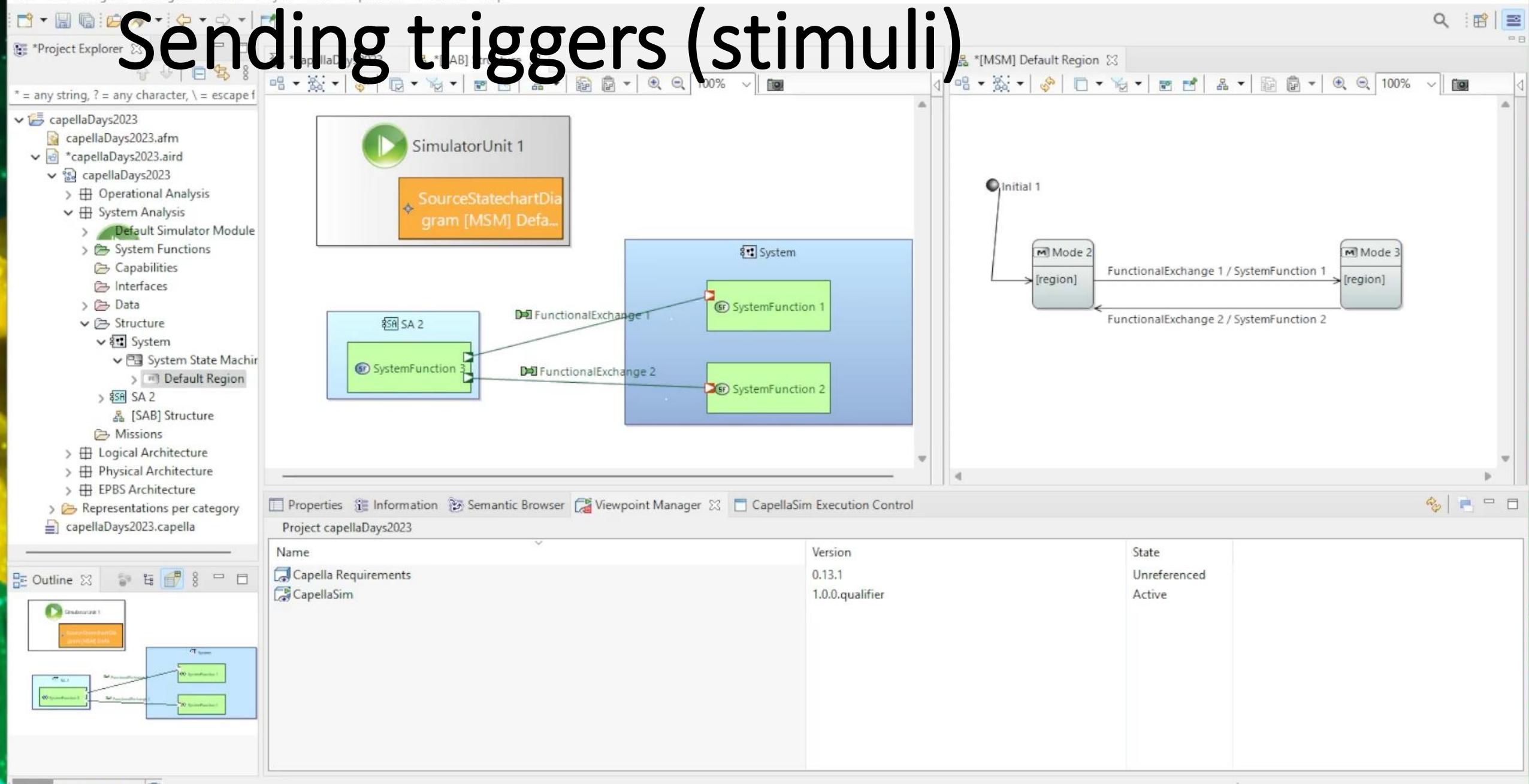


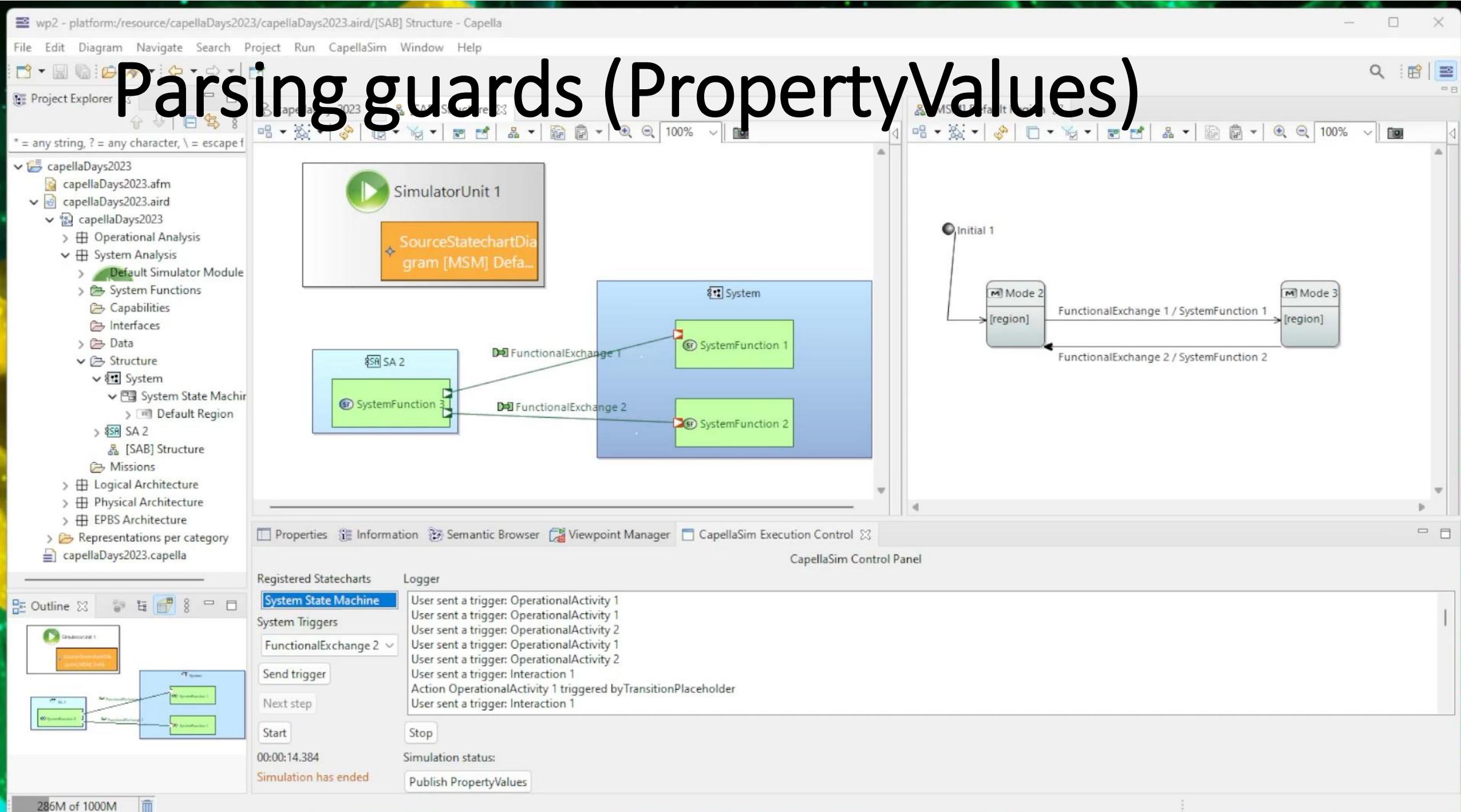


# Creating a Simple Architecture



# Sending triggers (stimuli)





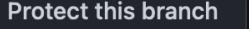


# Soon will be public at Github

 **CapellaSim** Private

 Edit Pins  Watch 2  Fork 0  Star 0

 main  3 branches  4 tags  Go to file  Add file  Code

**Your main branch isn't protected**  Protect this branch 

Protect this branch from force pushing or deletion, or require status checks before merging. [Learn more](#)

Author	Commit Message	Date	Commits
 mvccogo	Change wizard message	2d69dc7 yesterday	142 commits
	Repo restructuring	2 days ago	
 mvccogo	Change wizard message	yesterday	
 mvccogo	Repo restructuring	2 days ago	
 mvccogo	Ignore .class files	8 months ago	
 mvccogo	Initial commit	last year	
 mvccogo	Update README (UNDER PROGRESS)	2 days ago	
 mvccogo	New view prototyping (.txt)	3 months ago	

 README.md 

**CapellaSim** 

**About** 

No description, website, or topics provided.

 Readme

 GPL-3.0 license

 Activity

 0 stars

 2 watching

 0 forks

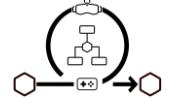
**Releases** 4 

 CapellaSim v0.1.1-beta2 Latest 2 days ago

+ 3 releases

**Packages**

No packages published  
Publish your first package

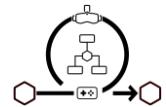


# Quick Example



# Appling into a UAV context

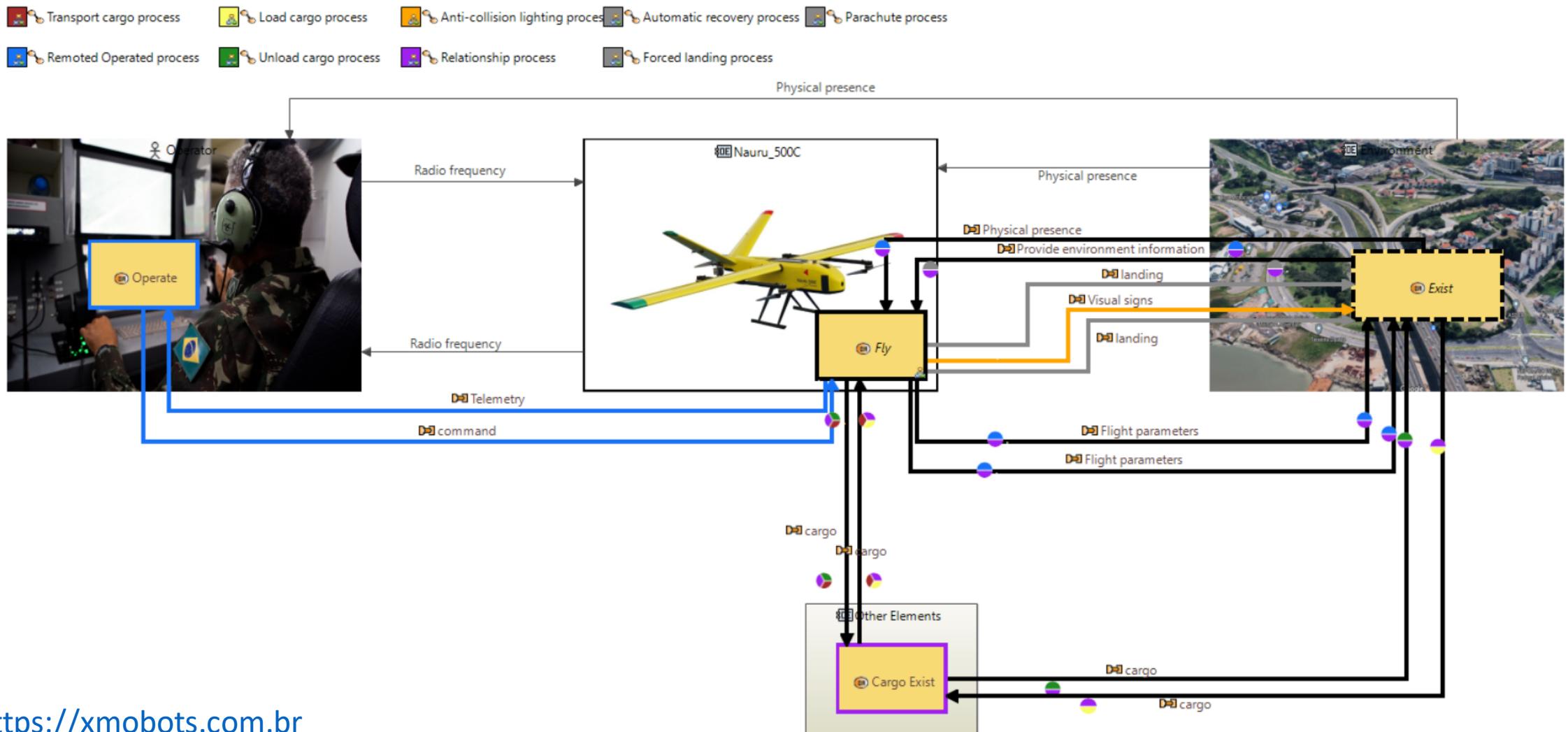




# Modelling the Aircraft functions

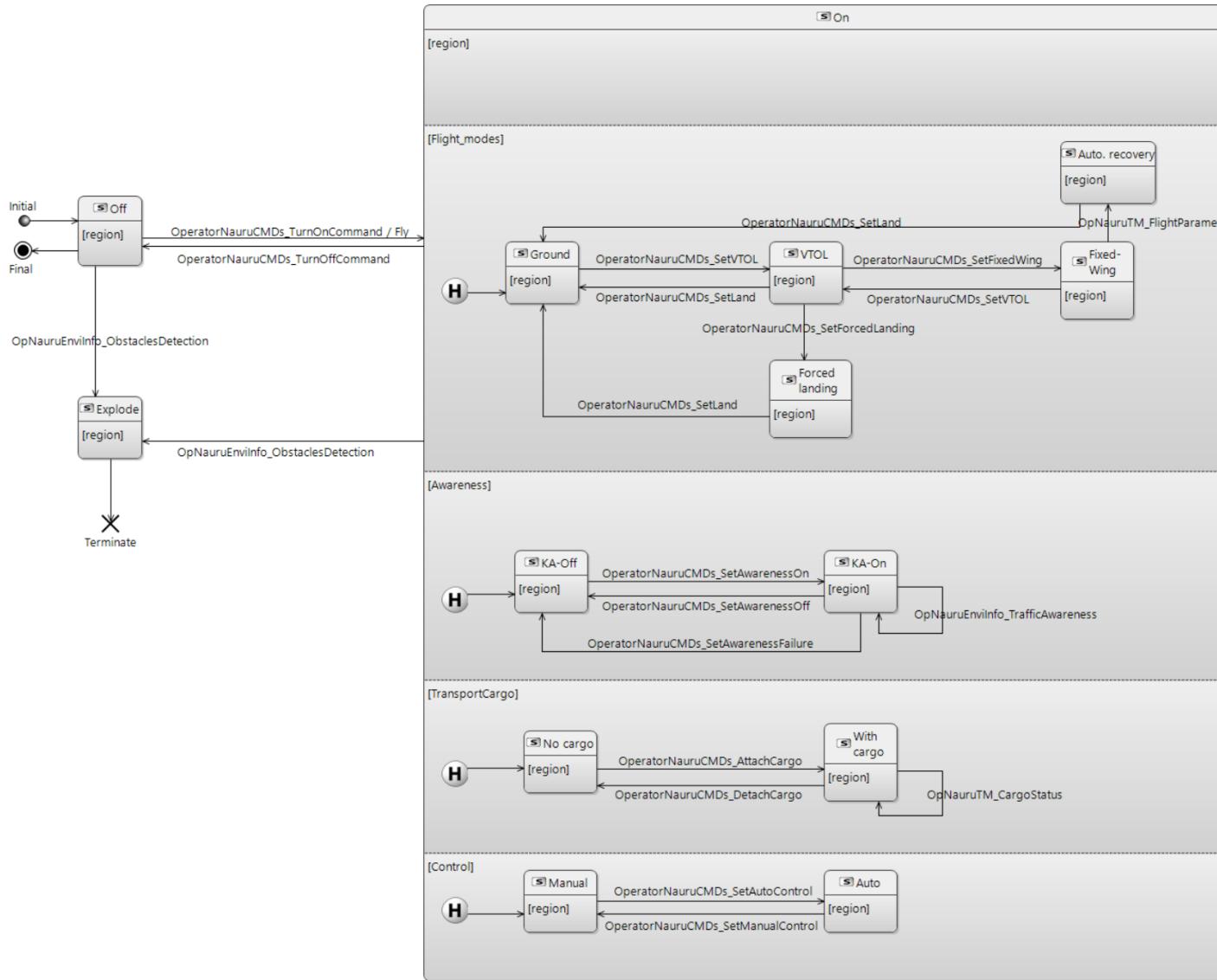


(same approach to all layers)

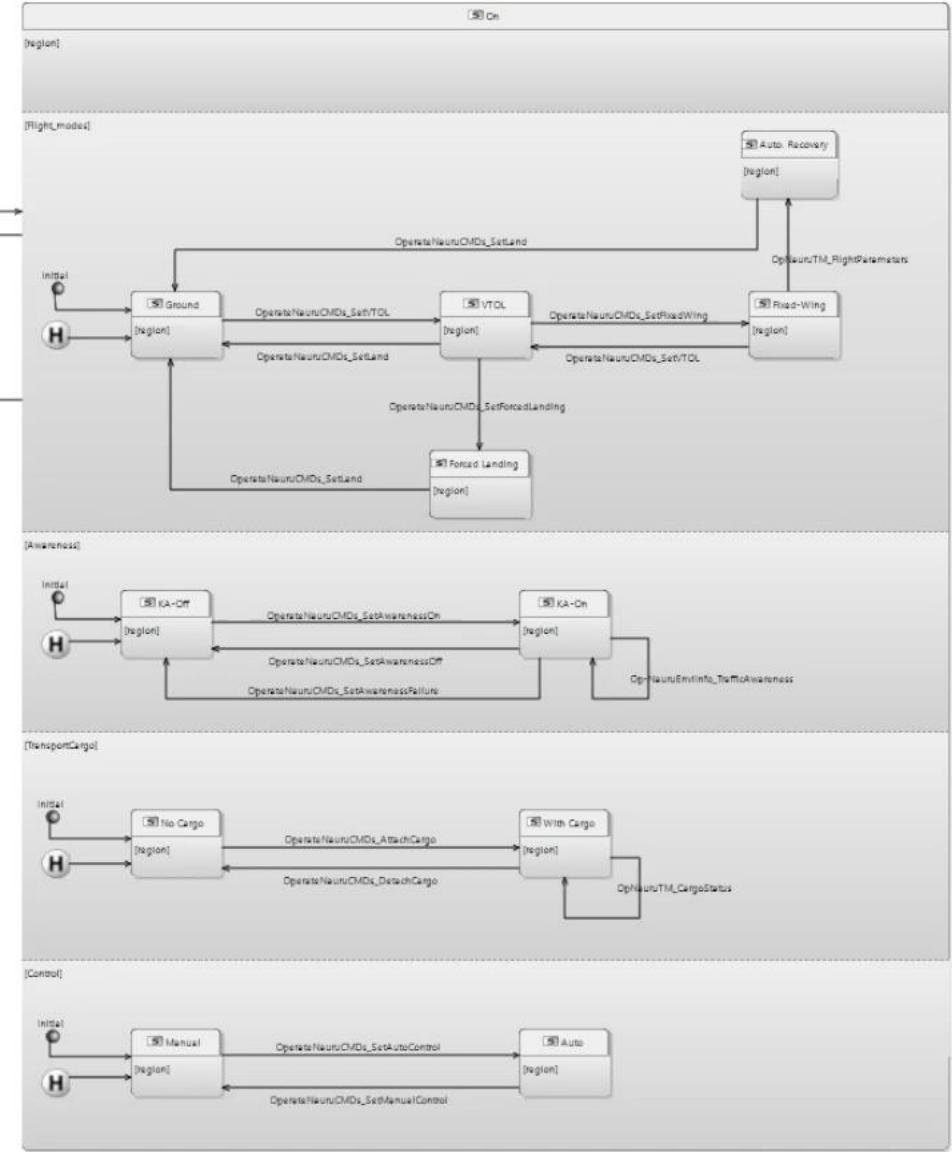
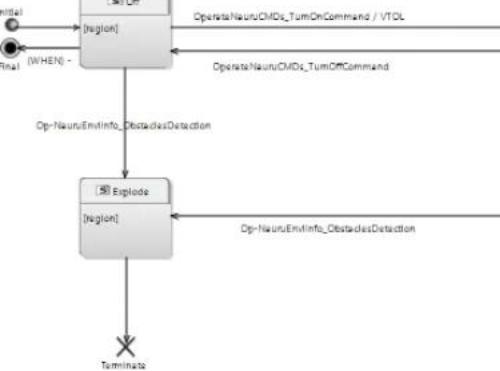
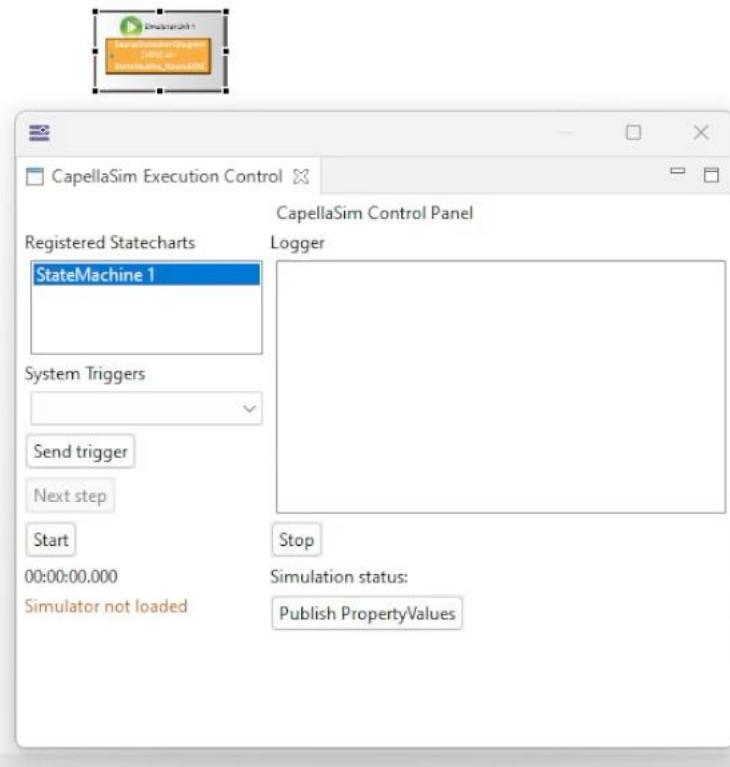
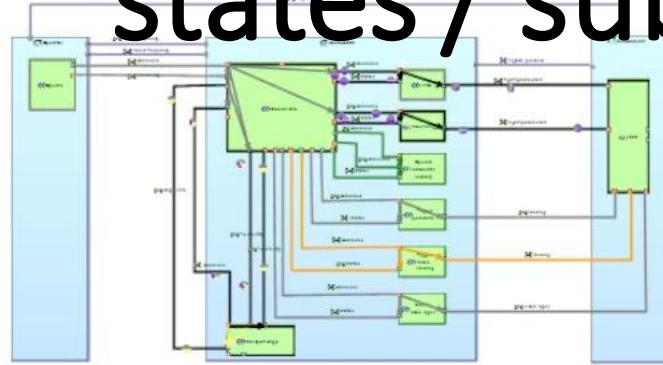




# Modelling the State Machine



# Simulating the commands and changing the states / substates





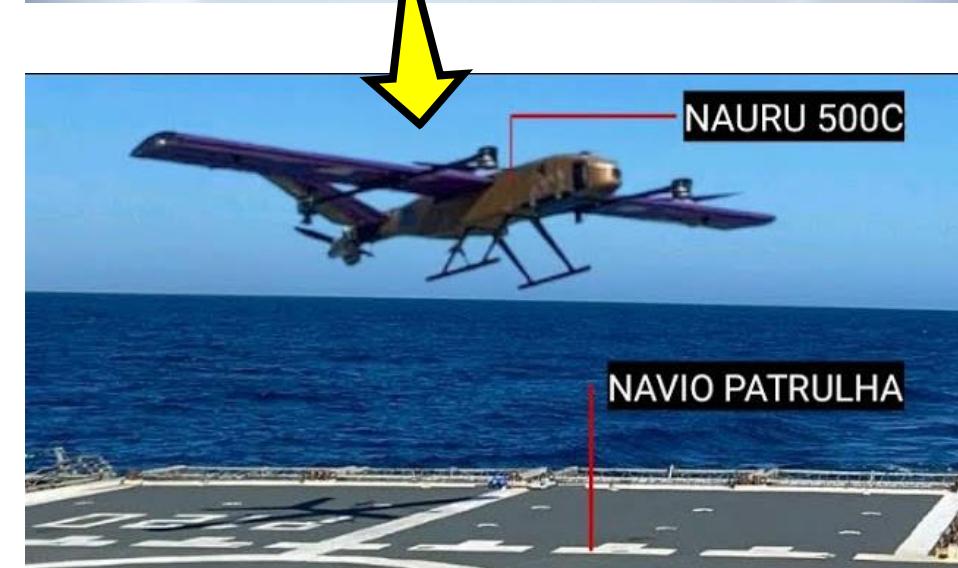
# Connecting Capella to Physical Things

It is not HIL (could be), the idea is to have a twin representation of the physical vehicle into the systemic view and track its behavior changes validating it.



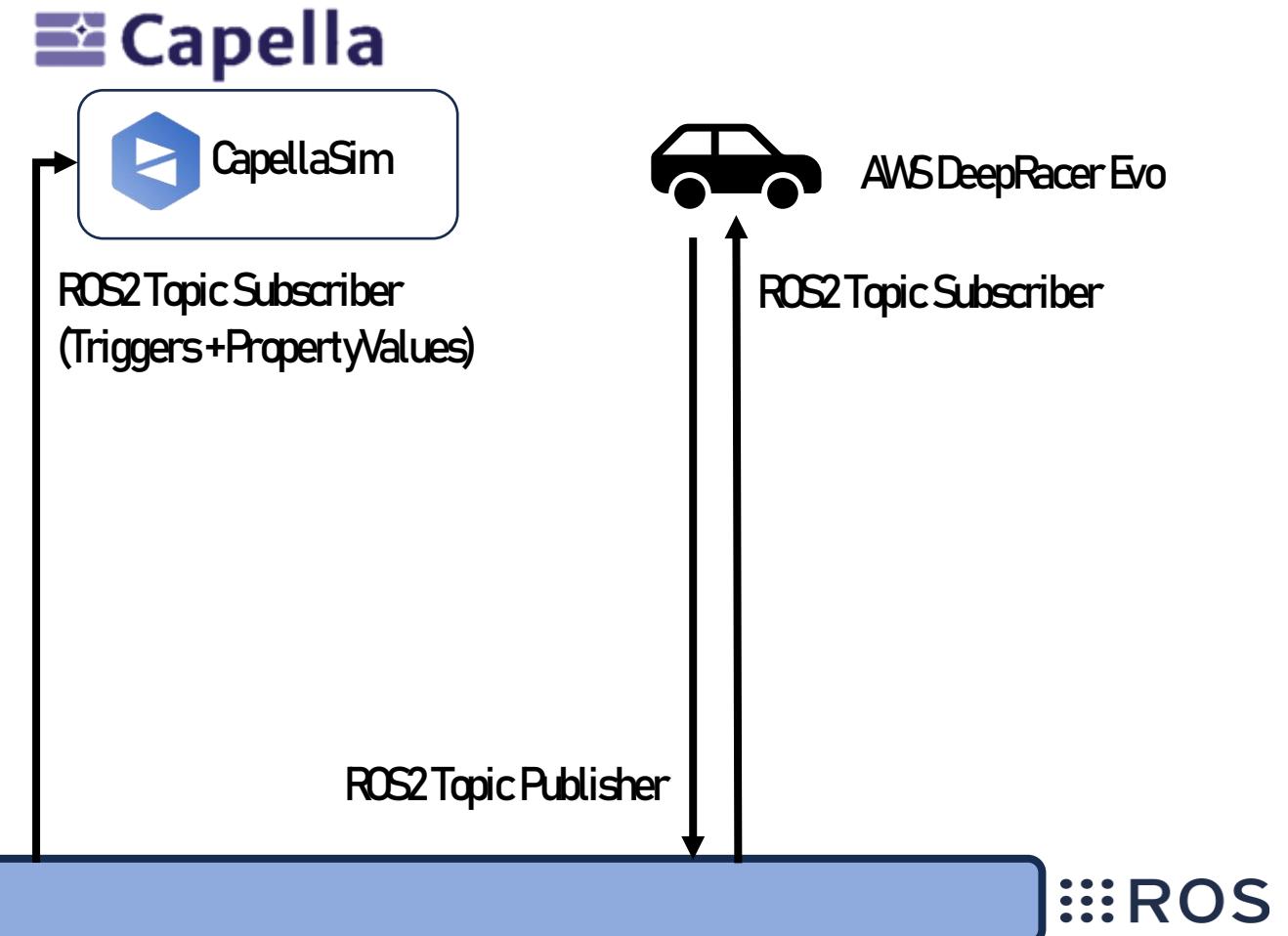
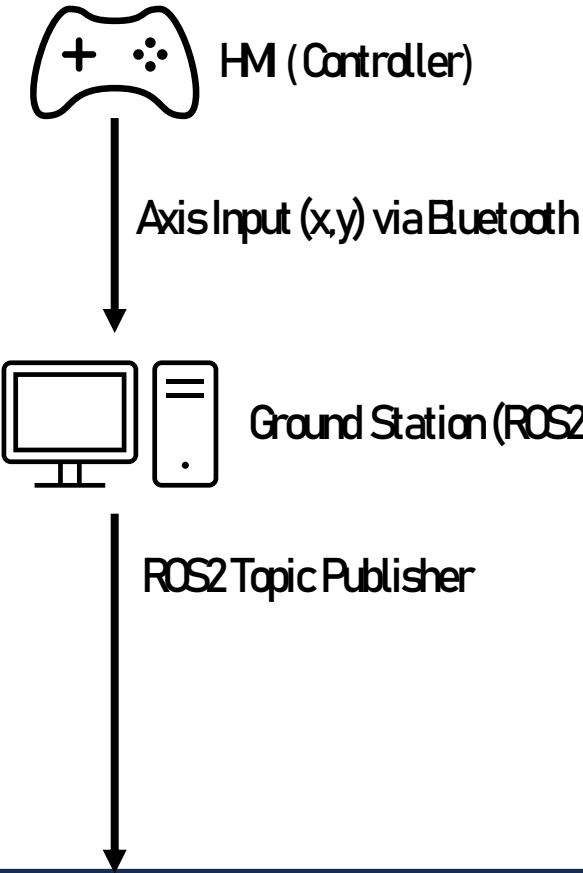
# Design of Experiments

- Use a representative of the vehicle to run 2D detect and avoid experiments. Flying crashes are more expensive 😊.
- Use of Capella to track the changes during the simulation.
  - Live Simulation: Commands sent to the vehicle by a HMI should be sent to the Capella, sending triggers to the state-machine should also be sent to the vehicle.





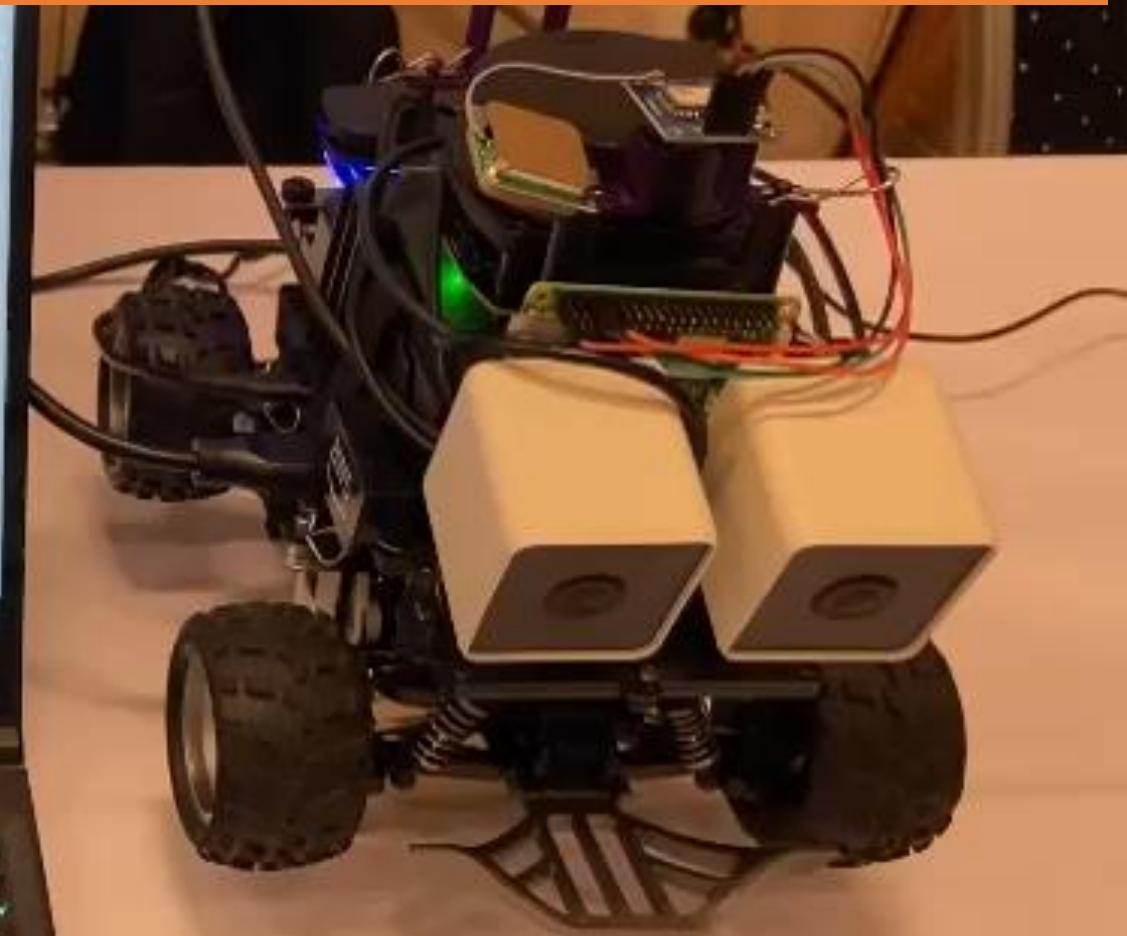
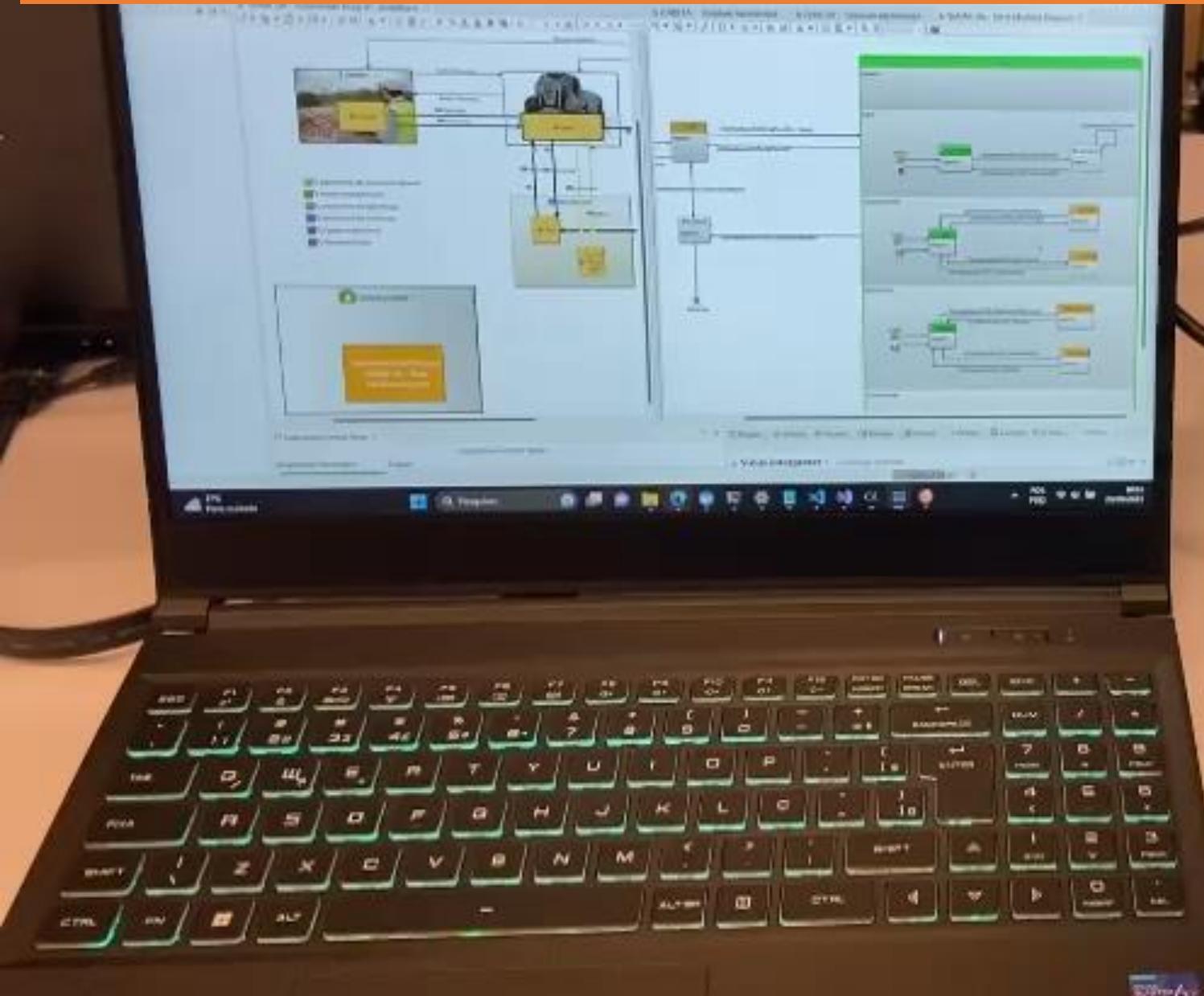
# ROS



<https://portal.waraps.org>



# Twin in Capella / Equipment





# Final Considerations



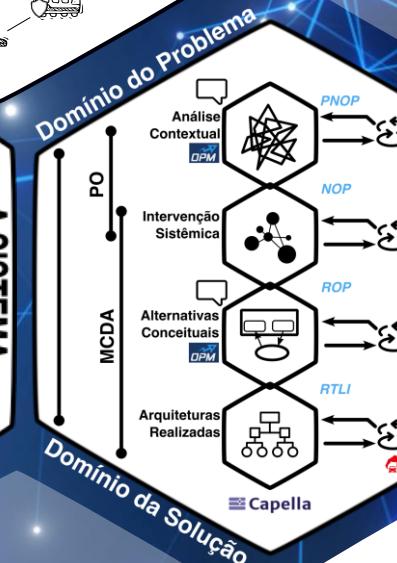
# Some on-going developments

- Our lab is working into **multidomain problems** and **Brazilian Air Force Life Cycle Framework**.
- We have a question: "**Is the current Systems Engineering UI Metaphor natural?**"
- In terms of development:
  - Library Management Add-On (ways to better filter elements of the library)
  - Architecture Optimization Add-On (ways to check interfaces and simulation results)
  - Distributed Simulation Add-On (what was presented)
  - Operational Research Add-On (we started with Soft Systems Methodology)
  - simple\_OPM Add-On (changes on the block-diagram to be able to show structure/behavior simultaneously)

conceptiolab.dev.br



Thank  
you!



 **Capella**  
Open Source MBSE Solution